

#### Outline

- The Particle-In-Cell simulation method
- Aspects of data Visualization and simulation scales
- Presentation of ongoing research
- Conclusions

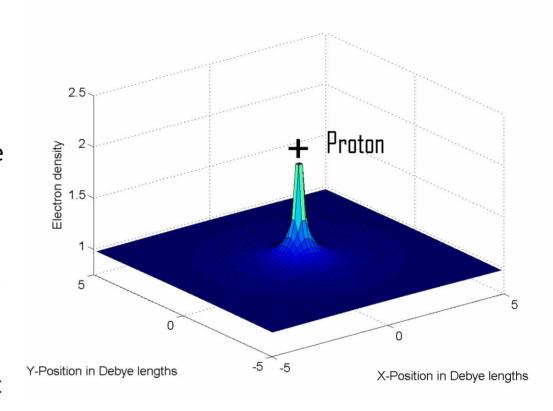
### Phase Space Fluid

#### Fluid: No individual particles

A charged particle brought into a plasma causes a redistribution of the charge  $\rho(x,t)$  (Fluid)

The particle is shielded over the distance  $v_t / \omega_p$  (Thermal speed over plasma frequency): Debye length  $\lambda_p$ 

No binary interactions are important for the plasma on scales  $\lambda > \lambda_D$ 



- Plasma interaction: macroscopic electromagnetic fields.
- Phase space Fluid: Charge density  $\rho(x,t) = q \int f(x,v,t) dv$

### The Vlasov Equation

Consider a single species of nonrelativistic electrons.

Many electrons per Debye sphere  $\Rightarrow f_{\epsilon}(\vec{x}, \vec{v}, t)$ .

The moments are  $\rho_e(\vec{x},t) = -e \int f_e(\vec{x},\vec{v},t) d\vec{v}$  (Charge)

$$\vec{J_e} = -e \int \vec{v} f_e(\vec{x}, \vec{v}, t) d\vec{v}$$
 (Current)

The (collision-less) electron plasma is then evolved in time through:

The Vlasov equation

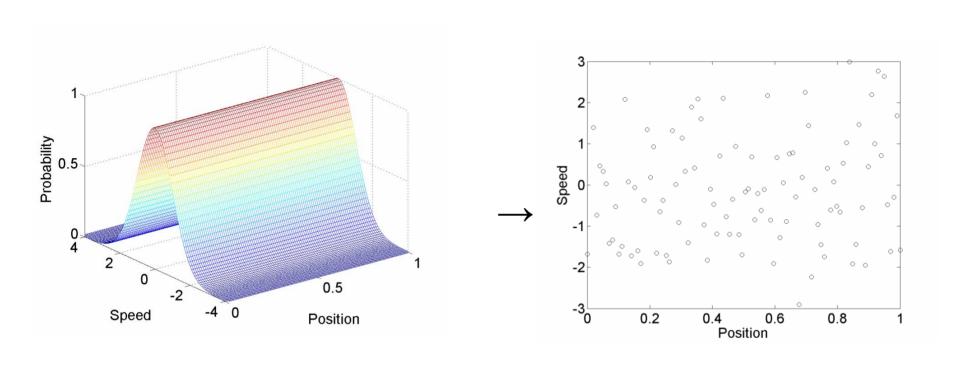
$$\frac{\partial f_e}{\partial t} + \vec{v} \frac{\partial f_e}{d\vec{x}} - \frac{e}{m_e} \left( \vec{E} + \vec{v} \times \vec{B} \right) \frac{\partial f_e}{d\vec{v}} = 0$$

The Maxwell's equations

$$\nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}, \ \nabla \cdot \vec{B} = 0,$$

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abla \cdot ec{E} = 
ho_e/\epsilon_0$$

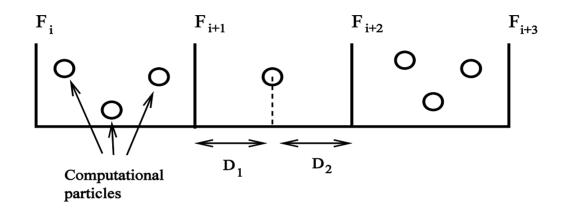
#### The Particle-In-Cell Method



The PIC method approximates  $f_e(x,v,t)$  by computational particles.

$$\frac{\partial f_e}{\partial t} + \vec{v} \frac{\partial f_e}{d\vec{x}} - \frac{e}{m_e} \left( \vec{E} + \vec{v} \times \vec{B} \right) \frac{\partial f_e}{d\vec{v}} = 0 \Rightarrow \frac{dv_j}{dt} = \frac{-e}{m_e} \left( \vec{E}[x_j] + \vec{v_j} \times \vec{B}[x_j] \right)$$

#### The Numerical Scheme



- •Each computational electron j carries a micro-current  $j_j \sim q_j v_j$
- •Distribute micro-current onto neighboring grid nodes using  $D_1, D_2$
- •Sum over all computational electrons j: Get macroscopic current J at grid nodes  $F_i$
- •Update E and B with Maxwell's equations on grid nodes  $F_i$
- •Interpolate E and B from grid nodes  $F_i$  to computational electrons and update their velocity and position.

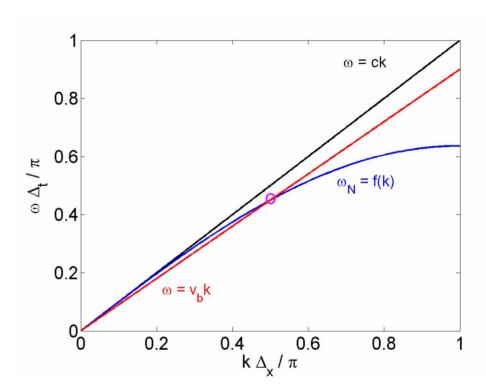
## Consequence of finite grid (1)

Light waves at high wavenumbers *k* move through the plasma with speed of light *c*.

However: Result is obtained from the differential equations.

PIC codes solve Maxwell's equations on a grid  $\rightarrow$  numerical effects close to scales comparable to the cell size  $\Delta x$  and to the time step  $\Delta t$ 

For illustration:  $\Delta x / \Delta t = c$ 



Black: True light mode.

Blue: Numerical light mode.

*Red:* Beam mode for  $v_h = 0.9c$ .

Purple circle: Plasma (finite grid) instability?

k > k(*purple circle*): Numerical Cherenkov?

## Consequence of finite grid (2)

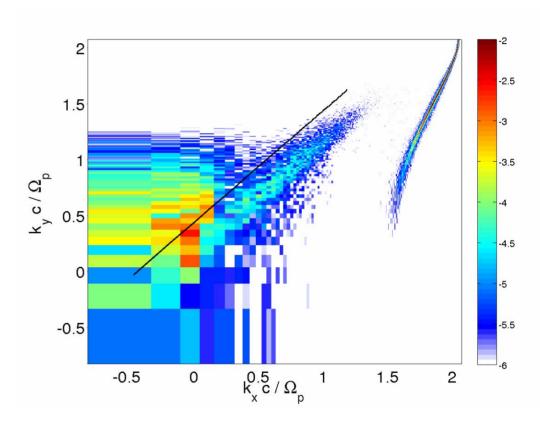
Simulation test: Beam instability in unmagnetized plasma

**Bulk plasma:** Protons and electrons, nonrelativistic temperature, no mean speed.

Beam plasma: Protons and electrons, nonrelativistic temperature, beam Lorentz factor 4, 0.1 times the bulk density, beam direction: x

Beam modes "superluminal" within a small angular interval around  $k_x$ -axis and at high wavenumbers.

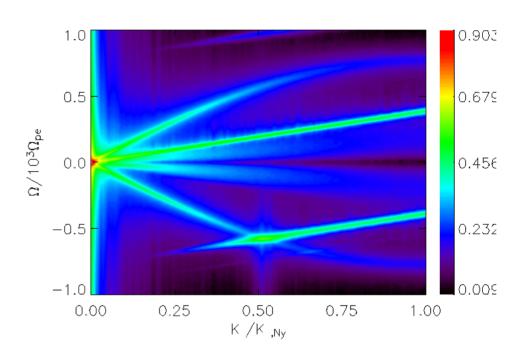
We expect finite grid instability (sharp resonance) at high  $k_x$  and low  $k_y$ 



(Note: k-axes are 10-logarithmic.)
Observation: "Unphysical wave modes" grow obliquely to beam velocity vector.

# Consequence of finite grid (3)

- 1D PIC simulation along x, beam moves with the speed  $v_b$  obliquely to the box in x,y plane. Projected speed  $v_{bx} < v_b$
- Oblique propagation: We excite the electromagnetic instability!
- Sample the  $E_v(x, t)$  for some time.
- Get power spectrum  $|E_v(k_x, \omega)|^2$



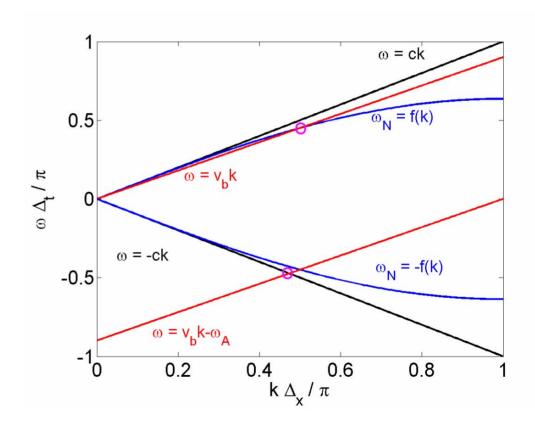
- We observe in the upper quadrant the beam dispersion relation  $\omega \approx v_{bx} k$
- We observe in both quadrants the numerical light mode with decreasing phase speed modulus above  $k \Delta x / \pi \approx 0.3$
- Two sidebands: The intersection of the lower with the O-mode is unstable.

## Consequence of the finite grid (4)

A cold beam with speed  $v_b$  moves across a grid cell during the time  $t_c = \Delta x / v_{bx}$ .

The periodicity of a simulation grid is experienced by the beam with the frequency  $\omega_A = 2\pi/t_c$ 

The beam motion across "periodic potentials" result in sidebands, separated by  $\omega_A$  from the beam dispersion  $\omega \approx v_{bx} k$ 



### Simulation constraints (1)

- We need to resolve the Debye length  $v_e / \omega_p$  (neglect ions for it)
- A temperature of 100 keV implies a thermal speed of  $v_e \approx 0.4c$  and we need 2.5 cells per electron skin depth  $c/\omega_p$
- The proton skin depth (equal proton and electron density) is then resolved by 100 cells.
- Proton filament size is initially ≈ proton skin depth, but the filaments merge. Minimize periodicity effects → resolve 20 proton skin depths in each direction orthogonal to the flow direction, giving 2000 \* 2000 cells.
- A full shock development may require 200 proton skin depths along the flow velocity vector: Grid size =  $20000*2000*2000 \approx 10^{11}$ cells

### Simulation constraints (2)

- We need 10<sup>11</sup> cells and 10<sup>13</sup> computational particles.
- Each particle: 3 doubles for X and 3 for P = 48 bytes
- Physical memory: 10<sup>2</sup>-10<sup>3</sup> Terabytes!
- Resolve well electron times:  $\Delta t = 2\pi / \omega_p / 10$
- Resolve well shock times:  $T_{sim} = 100 \ 1836^{1/2} \ 2\pi / \omega_p$  $\rightarrow 40000 \ time \ steps$
- My code does on one CPU a time step with 4 millions of CPs per second.
- A time step on 1 CPU needs  $10^6 10^7$  s and the simulation  $10^{11}$  s.
- Data write out: Sample electron and proton scales!
- $\rightarrow 10^3$  samples of phase space, each with  $10^3$  Terabytes

#### Simulation constraints (3)

- Let us assume the computer can do this:
- A phase space fluid has in general 3 spatial and 3 velocity dimensions and the time dimension: 6D + Time
- We cannot visualize and understand this!
- Consequence: We must reduce dimensions or spatio-temporal scales (no heavy ions)
- Both can alter the physics.
- "The purpose of computing is *insight* not numbers".
   (Hamming, 1972)

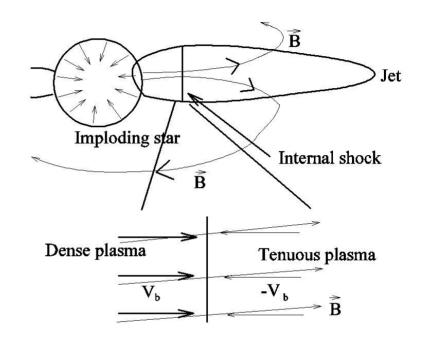
#### Gamma Ray Bursts

Radiation source: Accelerating charged particles

Particle acceleration: Macroscopic electromagnetic fields

Observed radiation requires: Extremely hot electrons and strong magnetic fields

**Provided by:** Fast shocks moving through the jet



Filamentation instability does not like:

- 1. Asymmetric plasma clouds
- 2. Guiding magnetic fields
- 3. High plasma temperatures

Let's use all of it.

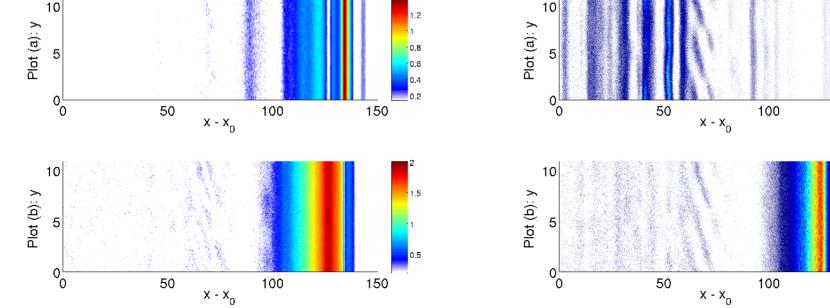
#### "Short" 2D simulations

- •Let the plasma collide at  $x=x_0$  The collision speed is 0.9c and points along x.
- •The dense cloud moving to the right is 10 times denser than the thin cloud moving to the left. The clouds move at equal velocity moduli.
- •We focus on the interval  $x>x_0$  where the dense cloud moves into the thin cloud.
- •Temperature = 100 keV, electron cyclotron frequency equals plasma frequency in dense cloud. Magnetic field tilted with 10 degrees relative to flow.

150

150

•/ $B_y$  /(a) and / $B_z$  / (b) in left column and  $E_x$  (a) and / $E_y$  +  $iE_z$ / (b) in right column. Simulation time  $\omega_n$  t = 209



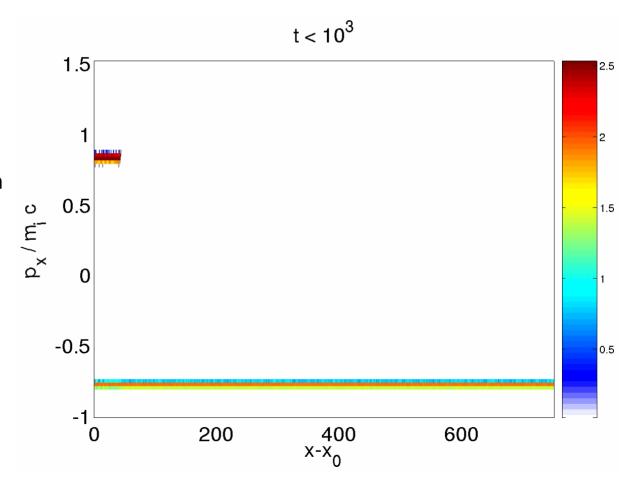
#### 1D Simulation (1)

Here we animate in time the ion  $(m_i / m_e = 400)$  phase space distribution along the collision direction.

X-unit: Box-averaged electron skin depth.

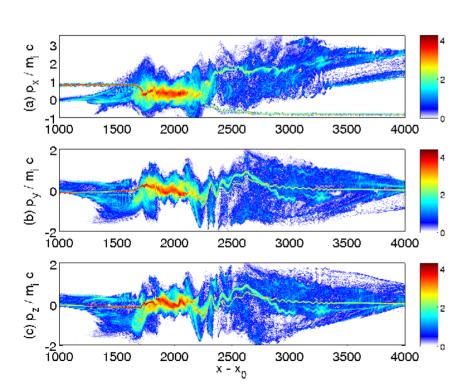
Time in inverse box-averaged electron plasma frequencies.

Colorbar: 10-logarithmic number of computational particles.

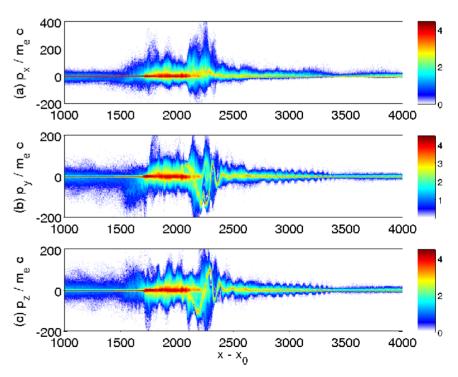


## 1D Simulation (2)

Left column: Projected phase space distributions of ions at simulation's end at  $t \omega_p \approx 5000$ 



Left column: Projected phase space distributions of electrons at simulation's end at  $t \omega_p \approx 5000$ 



#### Summary

- Brief outline of a phase space fluid and illustration of the Particle-In-Cell method.
- Aspects of the simulation: Need for reduced geometries
- Example simulation of an internal GRB shock.
- Future work: Vary parameters and assess their impact

Thank you for your attention!