

Spontaneous motion and deformation of a droplet

Natsuhiko Yoshinaga

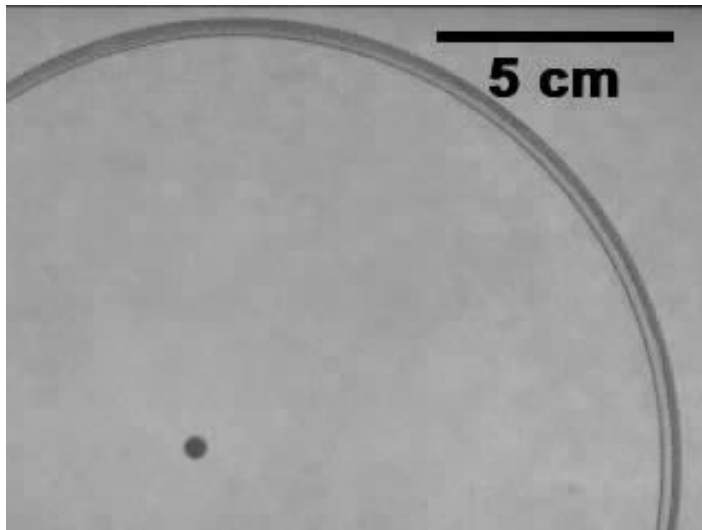
WPI - Advanced Institute for Materials Research,
Tohoku University



Motivation

- Motility and Shape -

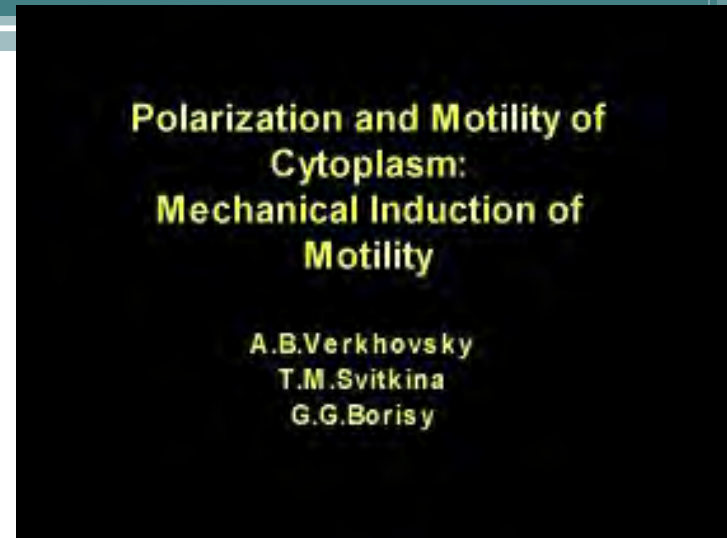
pentanol drop



K. Nagai (2005)

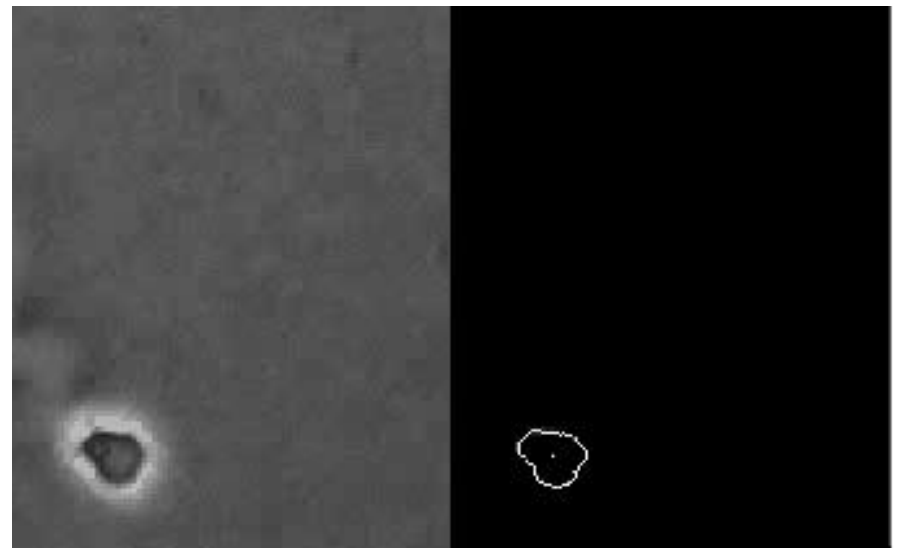
1. Force free
2. Symmetry breaking

keratocyte



A. Verkhovskiy (1999)

Dictyostelium

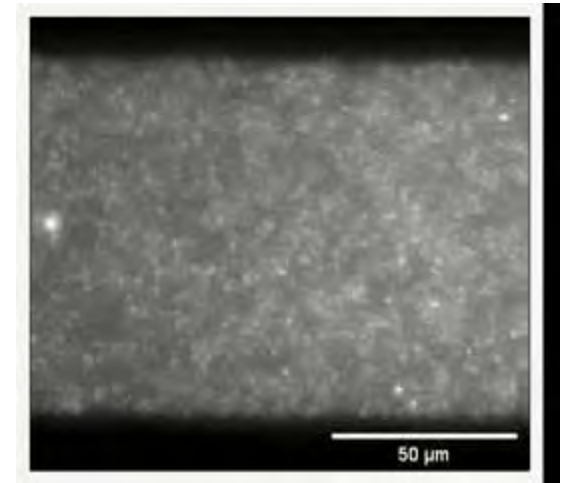


E. Cox, et al. (2008)

Y. Maeda and M. Sano (2008)

Motion “without” external force

- Phoresis
 - Electrophoresis
 - Diffusiophoresis
 - Soret Effect (thermophoresis)
- Marangoni Effect
 - liquid-liquid, gas-liquid interface



D. Braun et al. (2002)

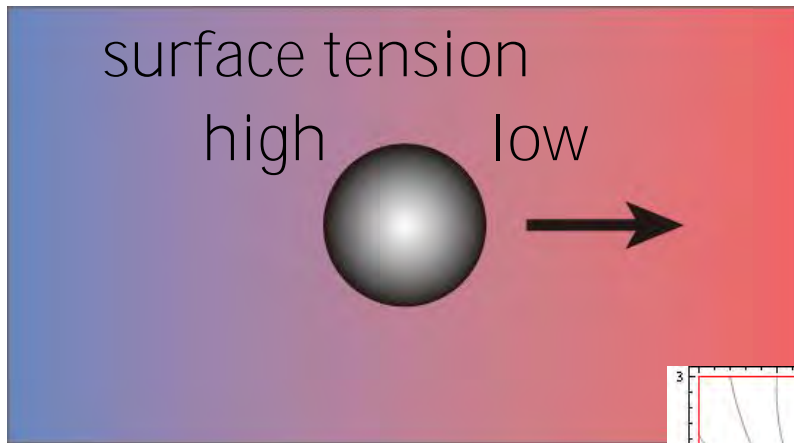
No mechanical force acting on the drop

$$f_z = \int \sigma \cdot \mathbf{n} dS = 0$$

J. L. Anderson, (1989)

Motion of a droplet in a linear temperature gradient

- Drops move toward a hotter place



drop velocity

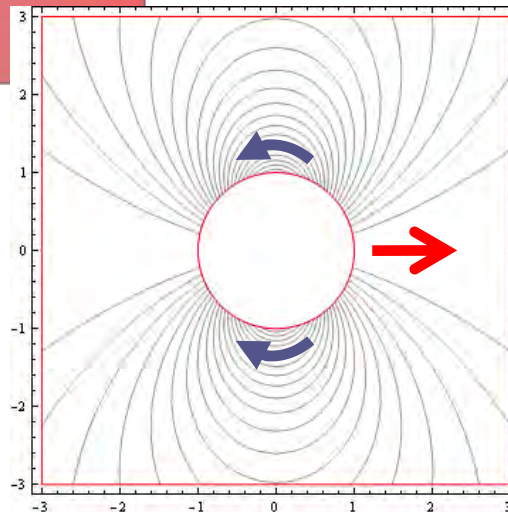
$$u = -\frac{2}{3(3\eta_i + 2\eta_o)} \gamma_T \nabla T$$

N. Young et al. (1959)

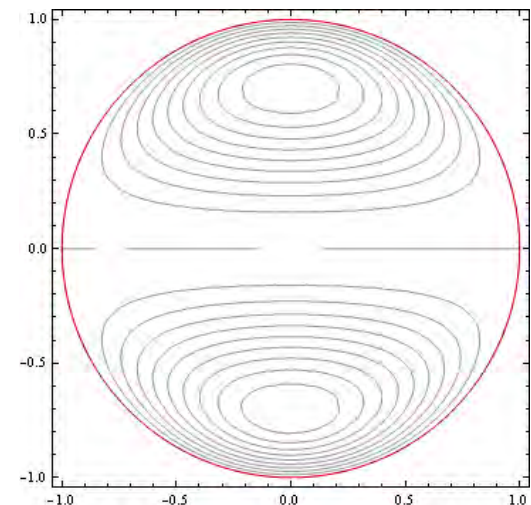
$$f_z = \int \sigma \cdot \mathbf{n} dS = 0$$

The drop is swimming in a fluid.

outer flow

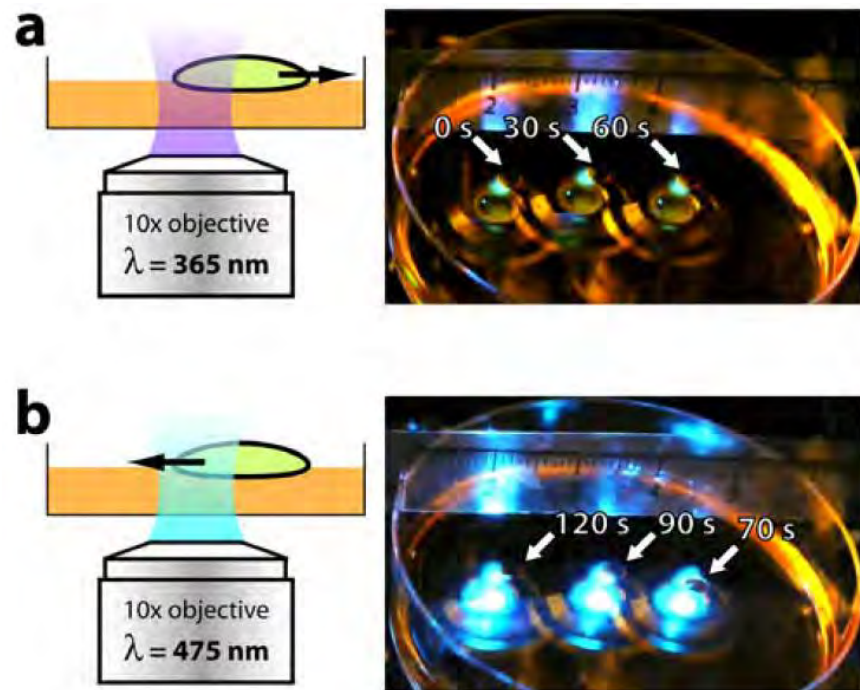


inner flow



Light-guided drop

Photo-sensitive surfactant

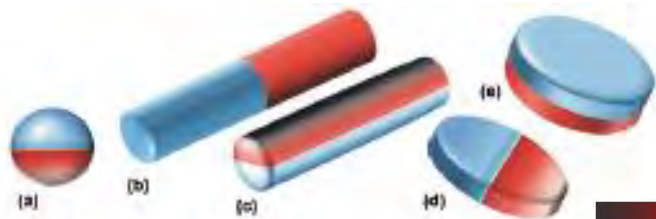


A. Diguët, et al. *Ang. Chim.* (2009)

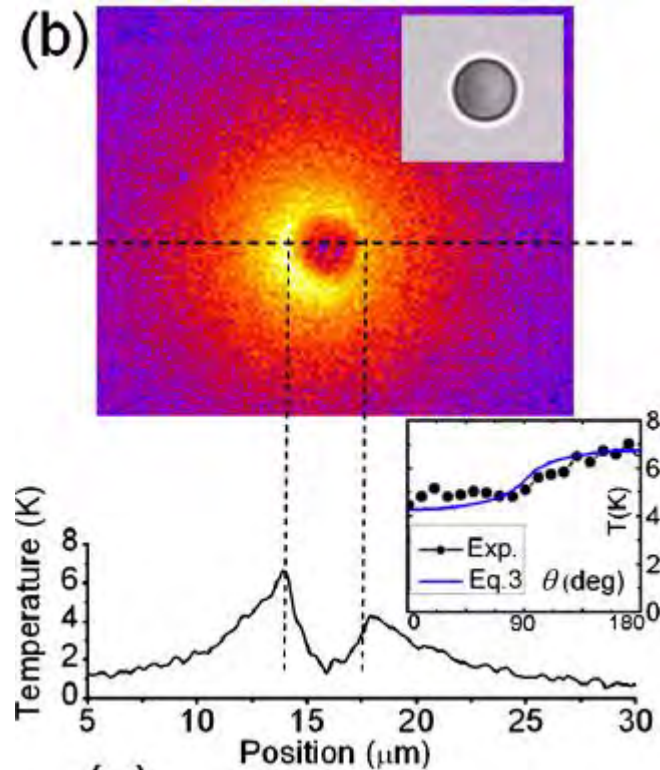
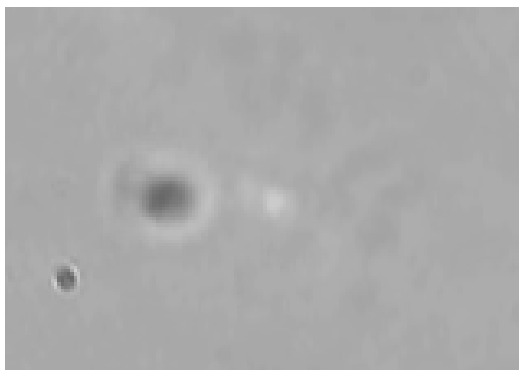
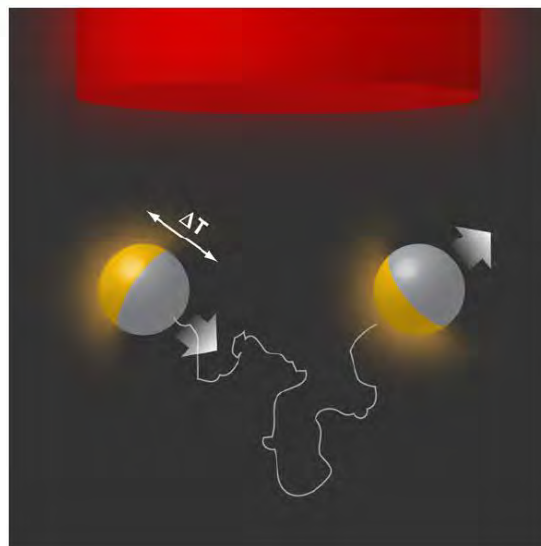
A drop partially illuminated by laser may have inhomogeneous distribution of surface tension due to photo-sensitive surfactants, which leads to motion.

Active motion of Janus particles

a particle with two faces



A. Walther,
Soft Matter (2008)



H.-R. Jiang, H. Wada, NY, and M. Sano. *PRL* (2009)

H.-R. Jiang, NY, and M. Sano. *PRL* (2010)

W. F. Paxton, *JACS* (2004)

J. R. Howse, *PRL* (2004)

$$u = -DS_T \frac{\Delta T}{3R}$$

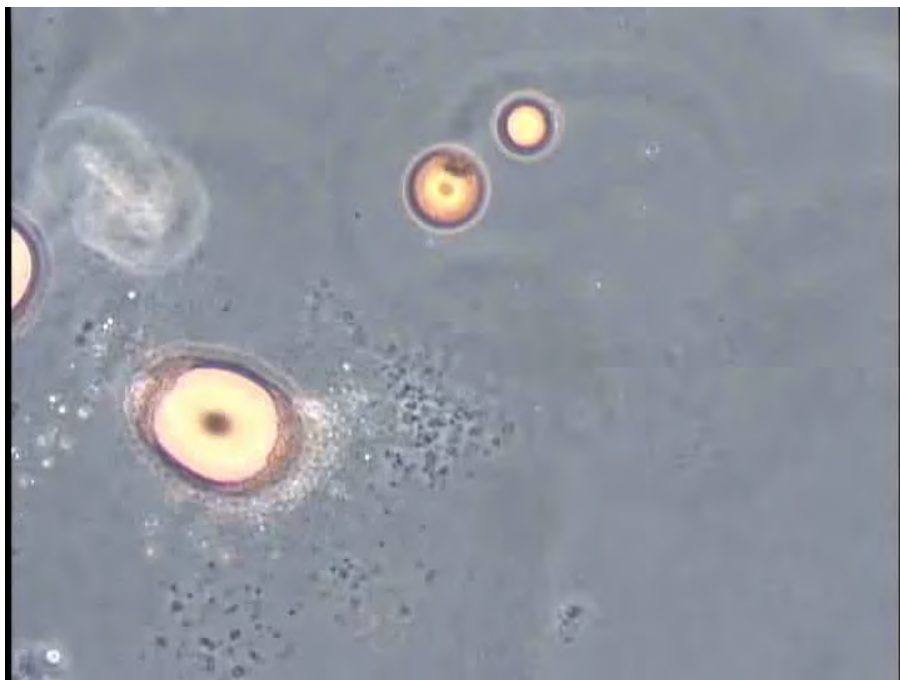
~ laser intensity

Spontaneous motion

- Motion under an external field (gradient)
- Motion of an asymmetric particle under a uniform (isotropic) field
- Spontaneous symmetry breaking
 - Motion itself breaks symmetry (two isotropic fields have different centers)
 - Internal nonlinear pattern formation breaks symmetry

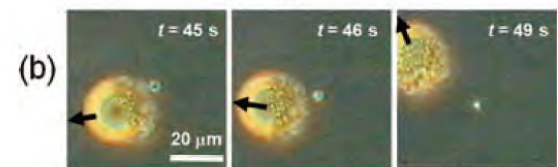
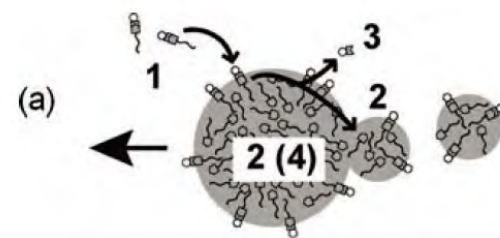
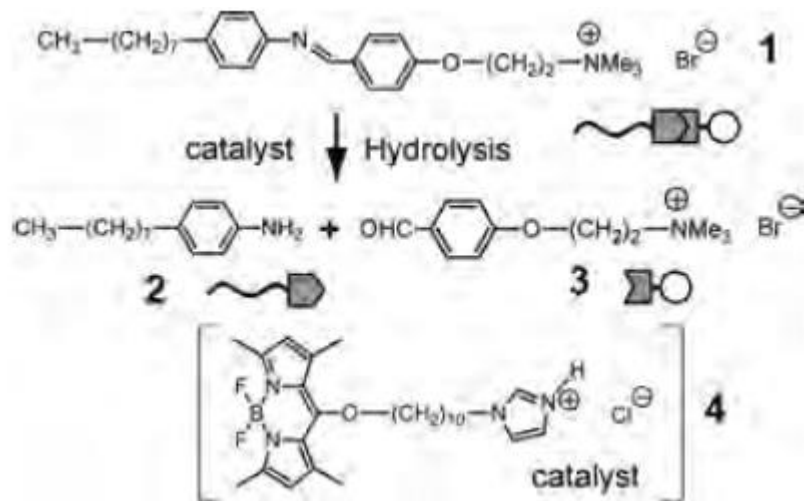
Spontaneous Symmetry Breaking

oil drop consuming surfactant



T. Toyota, *JACS* (2009)

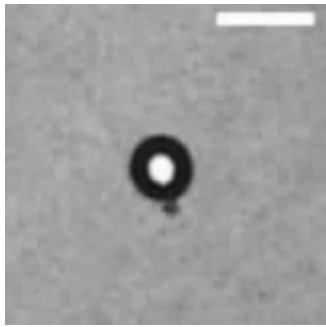
also S. Thutupalli *et al.*, *NJP* (2011)



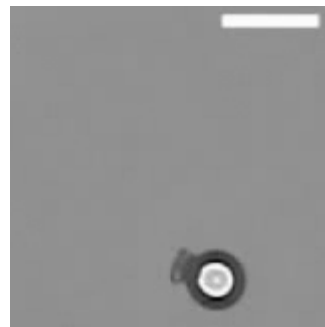
Spontaneous rotational motion

oil drop + solid soap

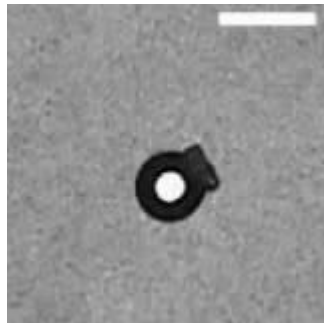
10 mm



spinning



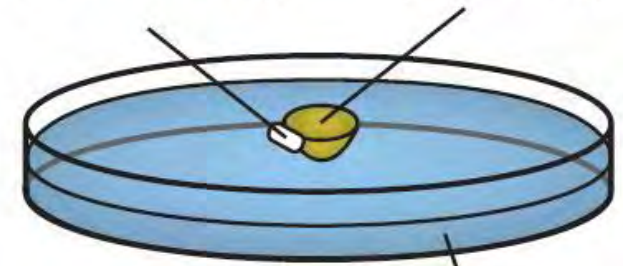
translation



rotation

Sodium Oleate
(Solid column)

Oleic Acid
(Oil droplet)



Aqueous Phase

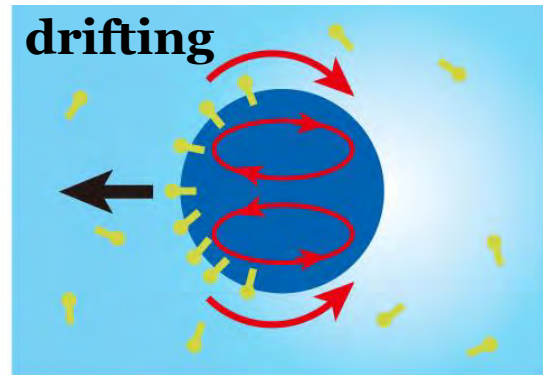
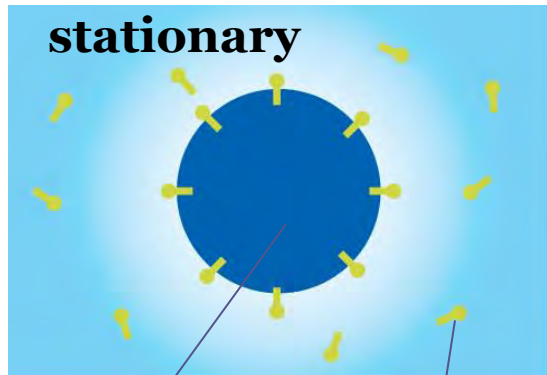
Experiments

F. Takabatake, *et al.*, *JCP* (2011)

Theory

K.H. Nagai, F. Takabatake, Y. Sumino,
H. Kitahata, M. Ichikawa, NY (2013)

“Reactive” droplet



droplet surfactant

self-propulsion of **uniform** systems

- reactive surfactant
- heating inside a drop
- production inside a drop

- Bulk Concentration Field

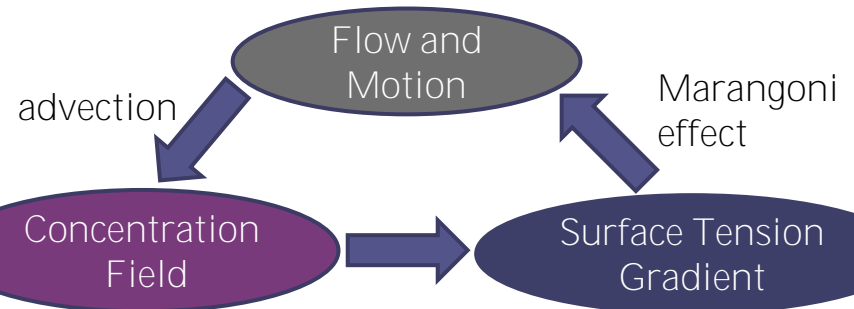
$$\frac{\partial c}{\partial t} + \mathbf{v} \cdot \nabla c = D \nabla^2 c - \kappa(c - c_\infty)$$

- Hydrodynamics

$$-\nabla p + \eta \nabla^2 \mathbf{v} + \mathbf{f} = 0$$

- Surface Concentration Field

$$\frac{\partial \Gamma}{\partial t} + v_s \nabla_s \Gamma = D_s \nabla_s^2 c - k_s \Gamma \pm \left. \frac{\partial c}{\partial r} \right|_{r=R}$$



Amplitude Equation of Droplet Velocity

$$\frac{du}{dt} = (-1 + \tau)u - gu^3$$

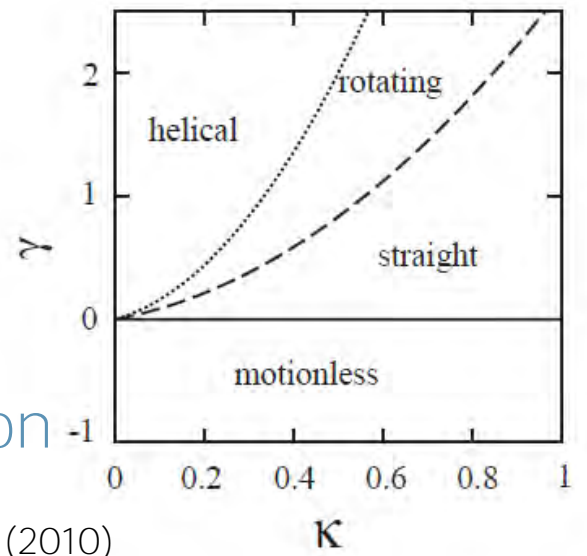
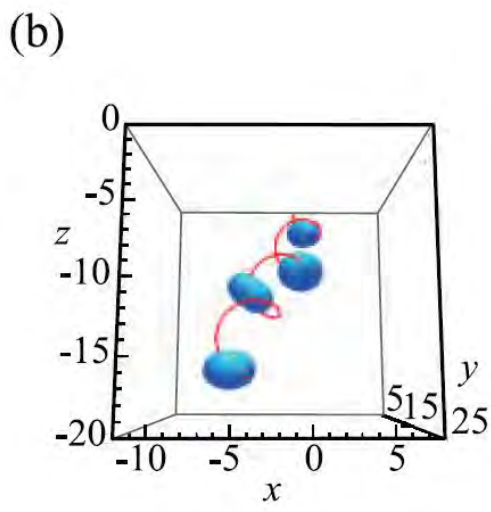
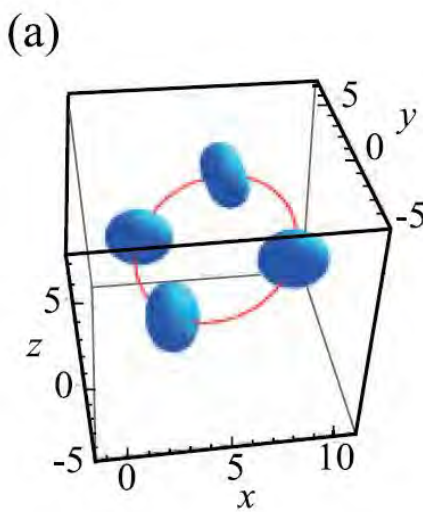
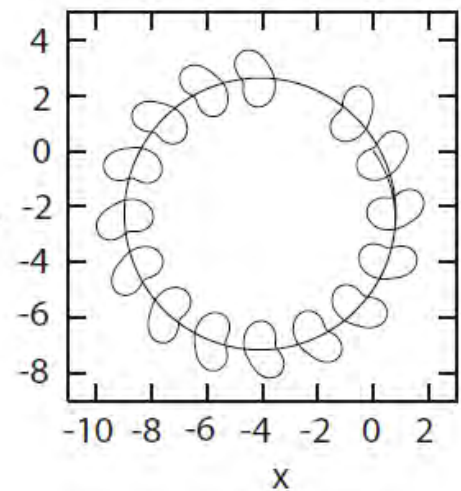
Phenomenological model for motion and deformation

Motion

$$m \frac{\partial u_i}{\partial t} = (-1 + \tau)u_i - gu^2u_i + bu_iS_{ij}$$

Deformation

$$\tau_2 \frac{\partial S_{ij}}{\partial t} = -\kappa S_{ij} - \lambda \left(u_i u_j - \frac{1}{3} \delta_{ij} u^2 \right)$$



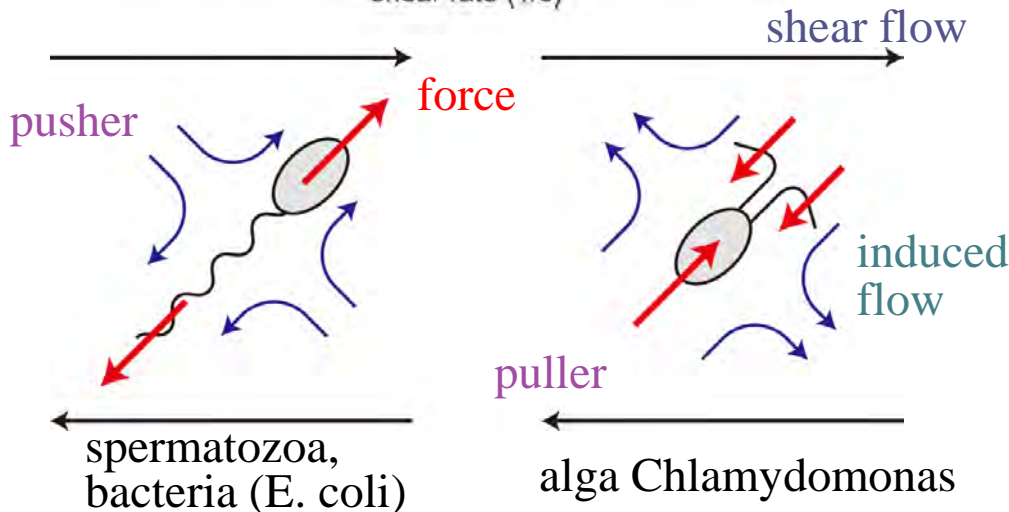
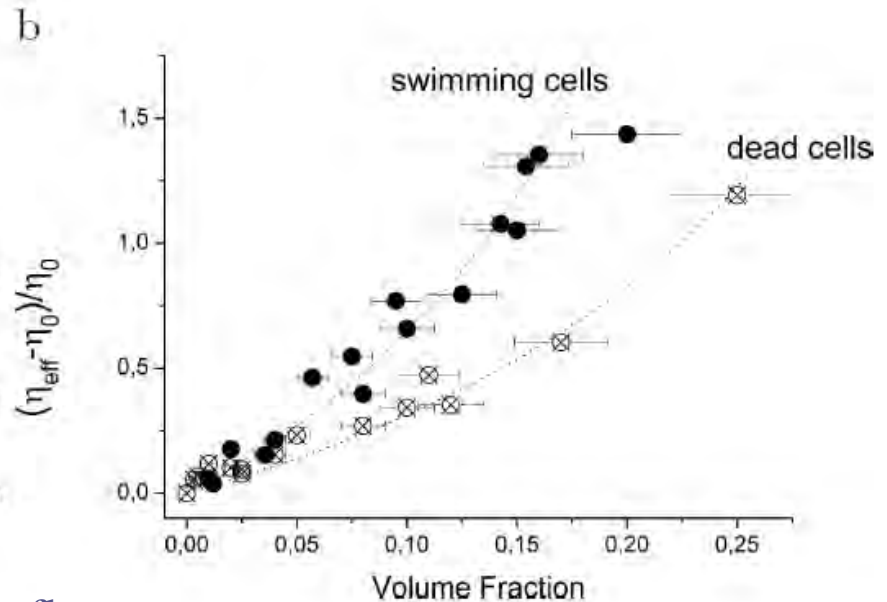
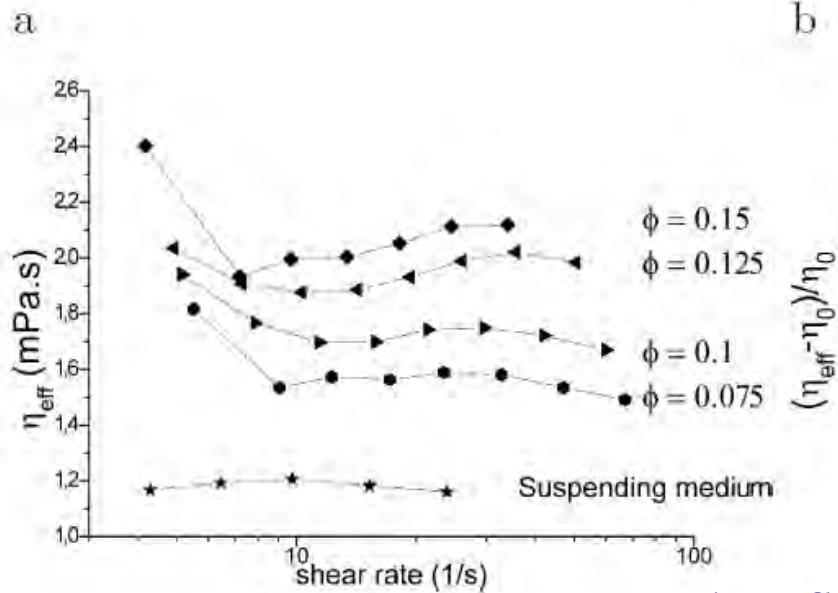
also derived from reaction-diffusion equation

Mechanics ??

T. Ohkuma, and T. Ohta (2009)
 T. Hiraiwa, K. Shitara, and T. Ohta (2010)
 K. Shitara, T. Hiraiwa, and T. Ohta (2011)

Pusher or Puller?

Viscosity of *Chlamydomonas* suspension



P. Peyla, et al., (2010)
Effective viscosity of microswimmer suspensions

S. Ramaswamy, et al., (2004)
Rheology of Active-Particle Suspensions

Phase-field model

Dynamics of phase , $\phi(\mathbf{r})$

$$\frac{\partial \phi}{\partial t} + \nabla \cdot (\mathbf{v} \phi) = \nabla^2 \frac{\delta F}{\delta \phi}$$

$$F[\phi(\mathbf{r}), c(\mathbf{r})] = \int d^3r \left[f_{GL}(\phi) + f_0(c) + \frac{1}{2} B(c) |\nabla \phi|^2 \right]$$

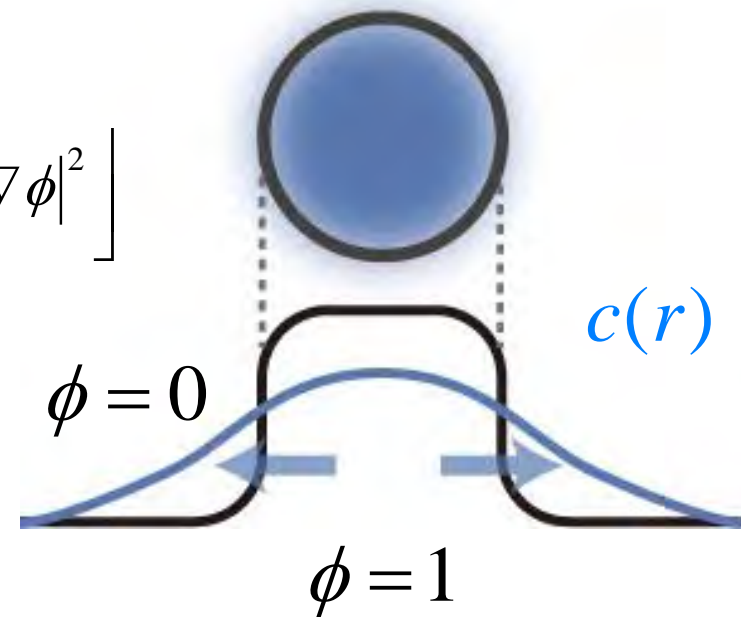
$$f_{GL}(\phi) = \frac{1}{4} \phi^2 (1 - \phi)^2$$

$$f_0(c) = c \ln c$$

$$B(c) = B_0 + B_1 c$$

surface tension

$$B[c(\mathbf{R}_s)] \approx \gamma(\theta, \phi)$$



Concentration Field

Dynamics of chemical

$$\frac{\partial c}{\partial t} + \nabla \cdot (\mathbf{v}c) = D\nabla^2 c - kc + \boxed{A\Theta(R - |\mathbf{r} - \mathbf{r}_G|)}$$

motion
production of chemicals

Velocity field, $\mathbf{v}(\mathbf{r})$

$$\eta\nabla^2 \mathbf{v} - \nabla p - \mathbf{f} = 0$$

Perturbation around drift bifurcation

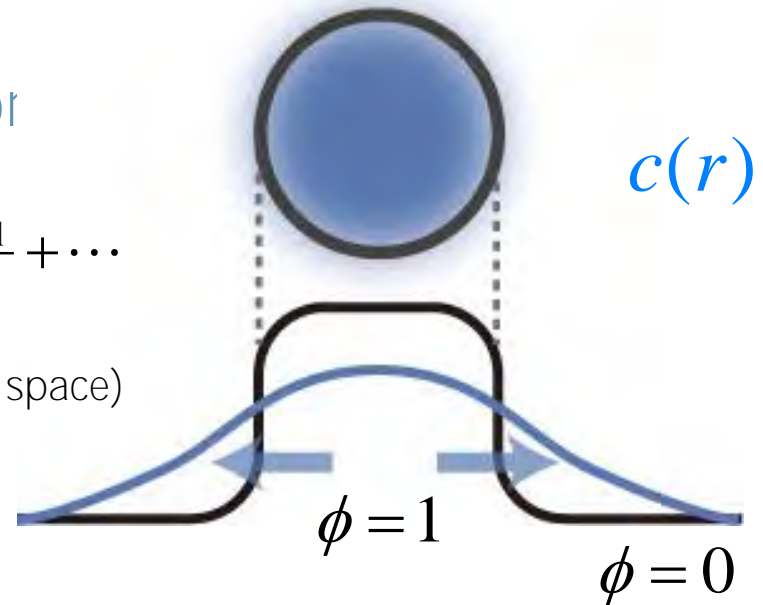
$$c_{\mathbf{q}} = \frac{G_{\mathbf{q}}}{D} H_{\mathbf{q}} - \frac{G_{\mathbf{q}}^2}{D^2} \frac{\partial H_{\mathbf{q}}}{\partial t} + \frac{G_{\mathbf{q}}^3}{D^3} \frac{\partial^2 H_{\mathbf{q}}}{\partial^2 t} - \frac{G_{\mathbf{q}}^4}{D^4} \frac{\partial^3 H_{\mathbf{q}}}{\partial^3 t} + \dots$$

$H_{\mathbf{q}}$: source (in Fourier space)

$G_{\mathbf{q}}$: Green's function

Expansion in terms of

$$\epsilon \sim u = \dot{r}_G$$



Hydrodynamics

low-Reynolds Stokes flow

$$\eta \nabla^2 \mathbf{v} - \nabla p - \nabla \cdot \Pi = 0$$

sharp-interface limit

$$\mathbf{f} = \mathbf{f}_s \delta(r - R)$$

Korteweg stress

$$\Pi_{ij} = -B(c) \nabla_i \phi \nabla_j \phi$$

$$B(c) = B_0 + B_1 c$$

$$B[c(\mathbf{R}_s)] \sim \gamma(\theta, \varphi)$$

surface tension

→ boundary-value problem

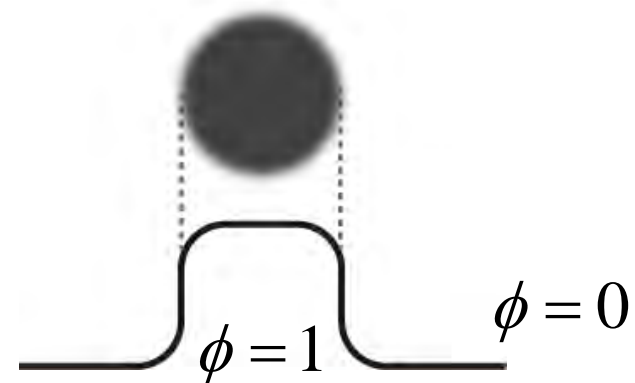
$$\eta \nabla^2 \mathbf{v} - \nabla p = 0$$

$$\mathbf{v}_{\text{in}}(R) = \mathbf{v}_{\text{out}}(R)$$

$$\mathbf{n} \cdot \boldsymbol{\sigma}_{\text{in}}(R) - \mathbf{n} \cdot \boldsymbol{\sigma}_{\text{out}}(R) = \partial_s [\gamma(\theta) \mathbf{t}]$$

conventional Marangoni effect

$$c(\mathbf{r}) = c_0 + c_1 z \quad \longrightarrow \quad u = -\frac{2\gamma_c c_1 R}{15\eta}$$



Interfacial force

Force acting on an interface

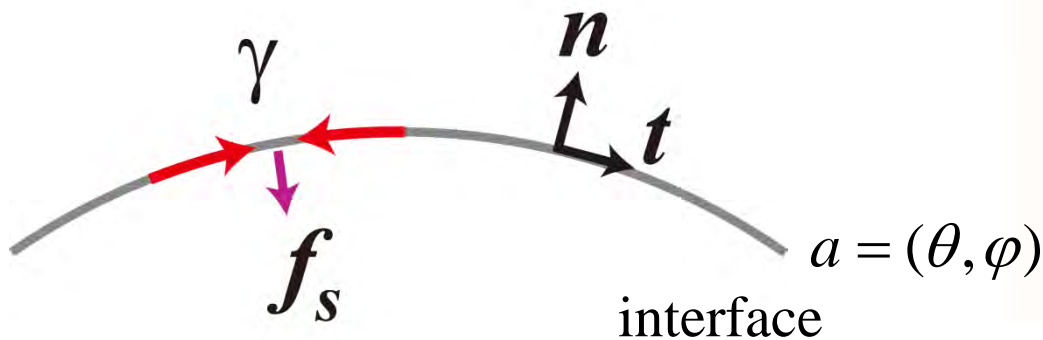
$$\mathbf{f} = \mathbf{f}_s \delta(r - R)$$

$$\mathbf{f}_s = -\kappa \gamma(a) \mathbf{n} + \nabla_s \gamma(a) \mathbf{t}$$

curvature

inhomogeneous surface tension

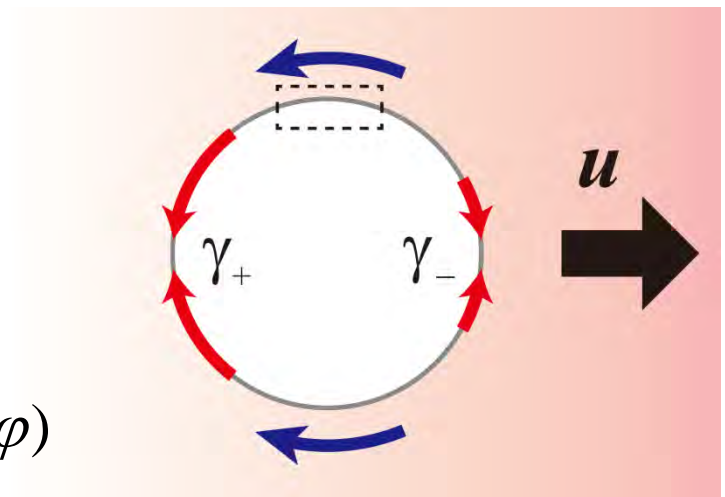
$$\gamma(a) = \sum_{l=0}^{\infty} \sum_{m=-l}^l \gamma_{lm} Y_l^m(a)$$



Laplace pressure



Marangoni force



Force moments

Multipole expansion of flow field

$$v_i = T_{ij} F_j - T_{ij,k} D_{jk} + \frac{1}{2} T_{ij,kl} G_{jkl} + \dots$$

monopole (Stokeslet)

$$F_i = \int f_i dV = 0 \quad \longrightarrow \quad \mathbf{v} \sim \frac{1}{r} \cos \theta$$

dipole (stresslet)

$$D_{ij} = \int f_i x_j dV = \gamma_2 \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \quad \longrightarrow \quad \mathbf{v} \sim \frac{\gamma_2}{r^2} P_2(\cos \theta)$$

deformation

$\gamma_2 < 0$: puller

$\gamma_2 > 0$: pusher

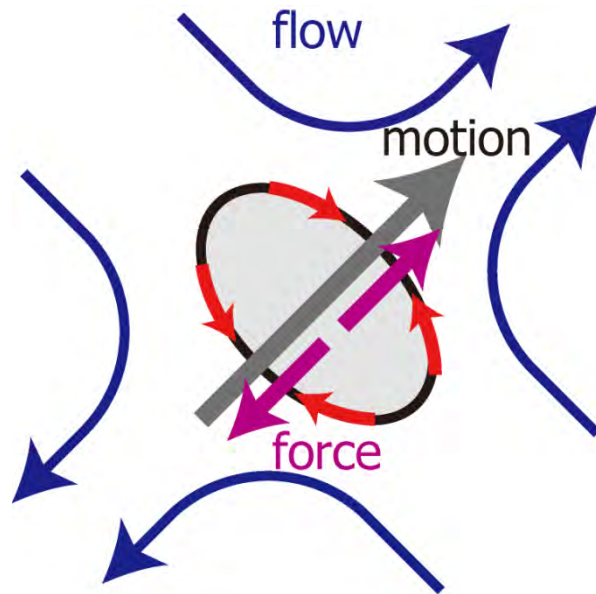
quadrupole

$$G_{ijk} = \int f_i x_j x_k dV \quad \longrightarrow \quad \mathbf{v} \sim \frac{\gamma_1}{r^3} \cos \theta + \mathcal{O}(P_3)$$

motion (F. Jülicher and J. Prost, 2009)

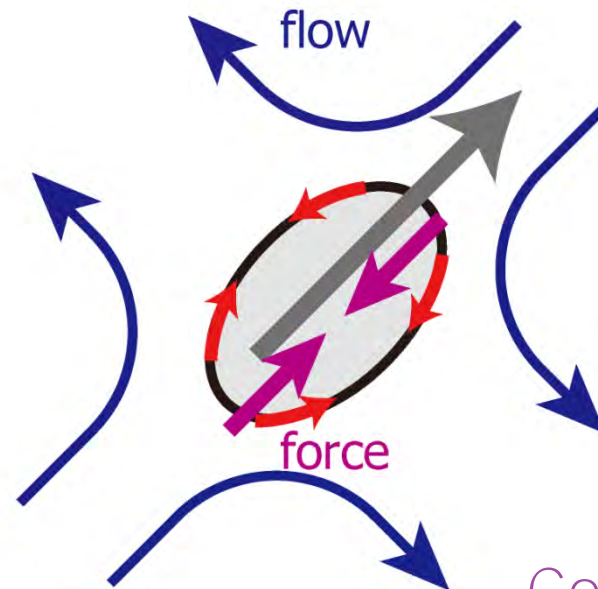
Shape and Force moment

pusher



$$\gamma_2 > 0$$

puller



$$\gamma_2 < 0$$

Concentration

$$\updownarrow \gamma = \gamma_c c$$

Surface tension

Motion

Velocity field

$$\mathbf{v}(\mathbf{r}) = \gamma_c \int dS \left[\underbrace{\mathbf{T}(\mathbf{r}, \mathbf{r}') \cdot \mathbf{n}(a') c(a') \kappa(a')}_{\text{Laplace pressure}} + \underbrace{\mathbf{T}(\mathbf{r}, \mathbf{r}') \cdot (\mathbf{I} - \mathbf{n}(a') \mathbf{n}(a')) \nabla c(a')}_{\text{tangential force}} \right]$$

Oseen Tensor

Velocity of a droplet

$$\mathbf{u} = \frac{1}{V} \int v_n \mathbf{R} dS$$

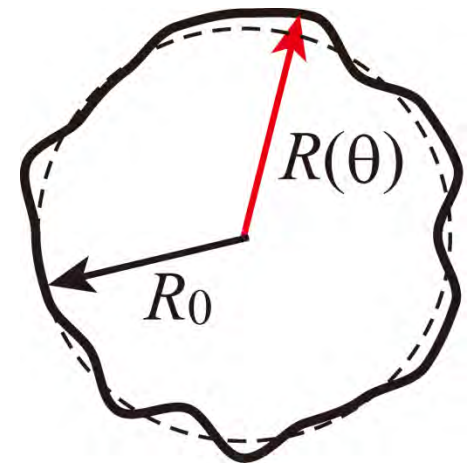
Kinematic condition

$$v_n = \mathbf{u} \cdot \mathbf{n} + \frac{d\delta R(a, t)}{dt}$$

Shape of the droplet

$$R(\theta, \varphi) = R_0 + \delta R(\theta, \varphi)$$

$$\delta R(\theta, \varphi) = \sum_{l=2}^{\infty} \sum_{m=-l}^l w_{l,m} Y_l^m(\theta, \varphi)$$



Deformation

Order parameter tensor

$$R_{ijkl\dots} = \int \delta R \left[n_i^{(0)} n_j^{(0)} n_k^{(0)} n_l^{(0)} \dots \right]_{\substack{\text{symm} \\ \text{traceless}}} dS$$

Kinematic condition

$$\frac{d\delta R(a, t)}{dt} = \mathbf{u} \cdot \mathbf{n} - v_n$$

$$\times \left(n_i n_j - \frac{1}{3} \delta_{ij} \right) \longrightarrow \frac{dS_{ij}}{dt} = \dots \quad \text{second mode}$$

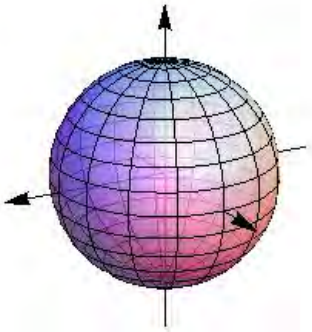
$$\times \left(n_i n_j n_k - \frac{1}{5} (\delta_{ij} n_k + \delta_{jk} n_i + \delta_{ik} n_j) \right) \longrightarrow \frac{dT_{ijk}}{dt} = \dots \quad \text{third mode}$$

Deformation

Second mode

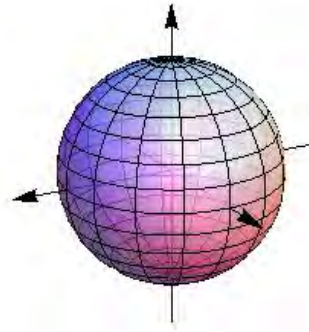
$$S_{xx} - S_{yy}$$

$$w_{2,2} + w_{2,-2}$$



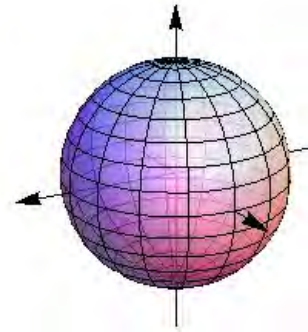
$$\frac{1}{2}(S_{xy} + S_{yx})$$

$$i(w_{2,2} - w_{2,-2})$$



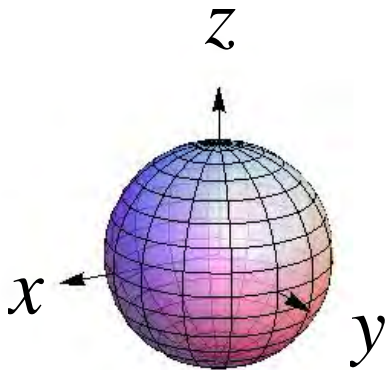
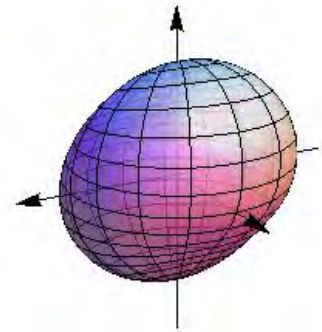
$$\frac{1}{2}(S_{xz} + S_{zx})$$

$$w_{2,1} - w_{2,-1}$$



$$\frac{1}{2}(S_{yz} + S_{zy})$$

$$i(w_{2,1} + w_{2,-1})$$



$$S_{zz}$$

$$w_{2,0}$$

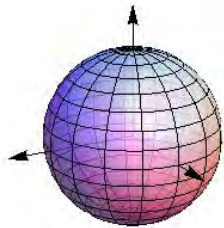
5 independent modes

Deformation

Third mode

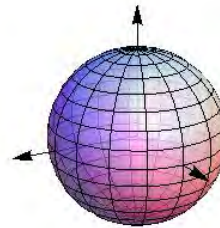
$$T_{zzz} - \frac{1}{3}(T_{xxz} + T_{xzx} + T_{zxx}) - \frac{1}{3}(T_{yyz} + T_{zyy} + T_{zyy})$$

$$w_{3,0}$$



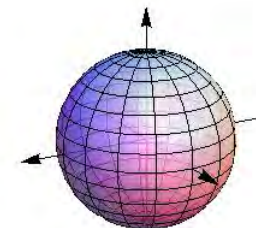
$$T_{xxx} - T_{xyy} - T_{yyx} - T_{yxx}$$

$$w_{3,3} - w_{3,-3}$$



$$T_{yyy} - T_{yyx} - T_{yxx} - T_{xyy}$$

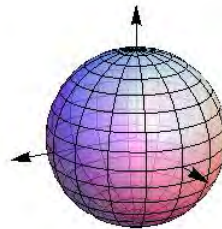
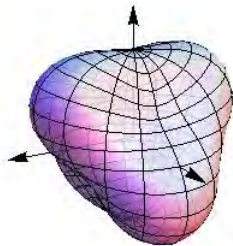
$$i(w_{3,3} + w_{3,-3})$$



7 independent modes

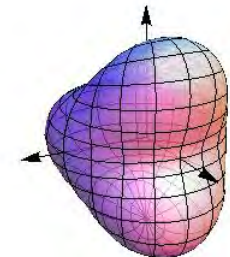
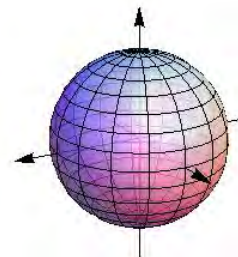
$$T_{xyz} + T_{xzy} + T_{yxz} + T_{yzx} + T_{zxy} + T_{zyx}$$

$$i(w_{3,2} - w_{3,-2})$$



$$\frac{1}{3}(T_{yzz} + T_{zyz} + T_{zzy}) - \frac{1}{4}T_{yyy} - \frac{1}{12}(T_{yxx} + T_{xyx} + T_{xxy})$$

$$i(w_{3,1} + w_{3,-1})$$



$$T_{zxx} - T_{zyy} + T_{xzx} - T_{yzy} + T_{xxz} - T_{yyz}$$

$$w_{3,2} + w_{3,-2}$$

$$\frac{1}{3}(T_{xzz} + T_{zxx} + T_{zzx}) - \frac{1}{4}T_{xxx} - \frac{1}{12}(T_{xyy} + T_{yyx} + T_{yxx})$$

$$w_{3,1} - w_{3,-1}$$

Motion and Deformation

First mode

$$m \frac{\partial u_i}{\partial t} = (-1 + \tau)u_i - gu^2u_i + bu_iS_{ij} + \mathcal{O}(\epsilon^4)$$

Second mode

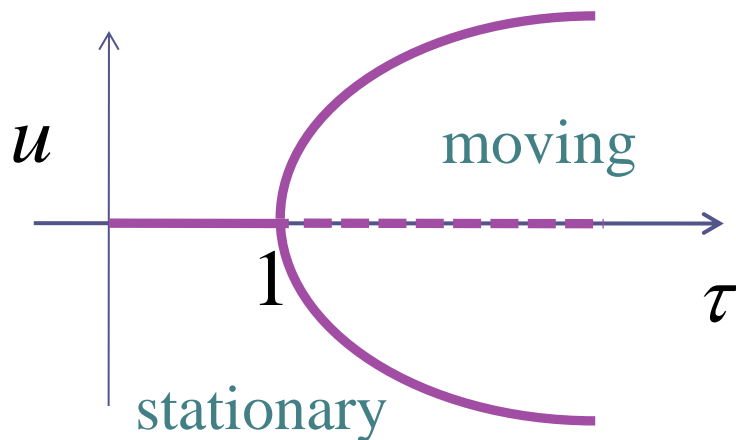
$$\tau_2 \frac{\partial S_{ij}}{\partial t} = -\kappa S_{ij} + \lambda \left(u_i u_j - \frac{1}{3} \delta_{ij} u^2 \right) + \mathcal{O}(\epsilon^4)$$

Third mode

$$\begin{aligned} \tau_3 \frac{\partial T_{ijk}}{\partial t} = & -\kappa_3 T_{ijk} + \lambda_3 \left[u_i u_j u_k - \frac{1}{5} u^2 (u_i \delta_{jk} + u_j \delta_{ik} + u_k \delta_{ij}) \right] \\ & + b_3 \left[(S_{jk} u_i + S_{ik} u_j + S_{ij} u_k) - \frac{2}{5} u_\alpha (S_{j\alpha} \delta_{ik} + S_{k\alpha} \delta_{ij} + S_{i\alpha} \delta_{jk}) \right] + \mathcal{O}(\epsilon^4) \end{aligned}$$

Drift bifurcation

pitchfork bifurcation



nondimensional activity

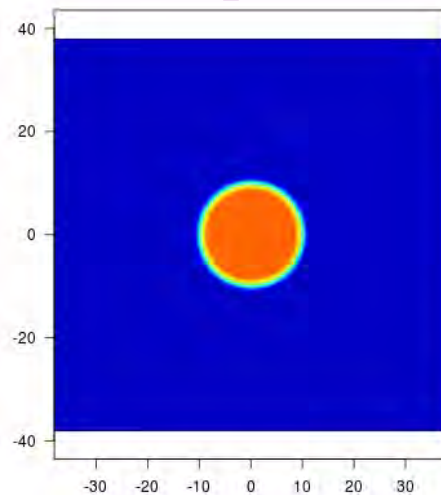
$$\frac{\tau}{\tau^*} = F_\tau(\beta R) \quad \tau^* = \frac{\gamma_c A}{\eta D^2 \beta^3}$$

stationary velocity

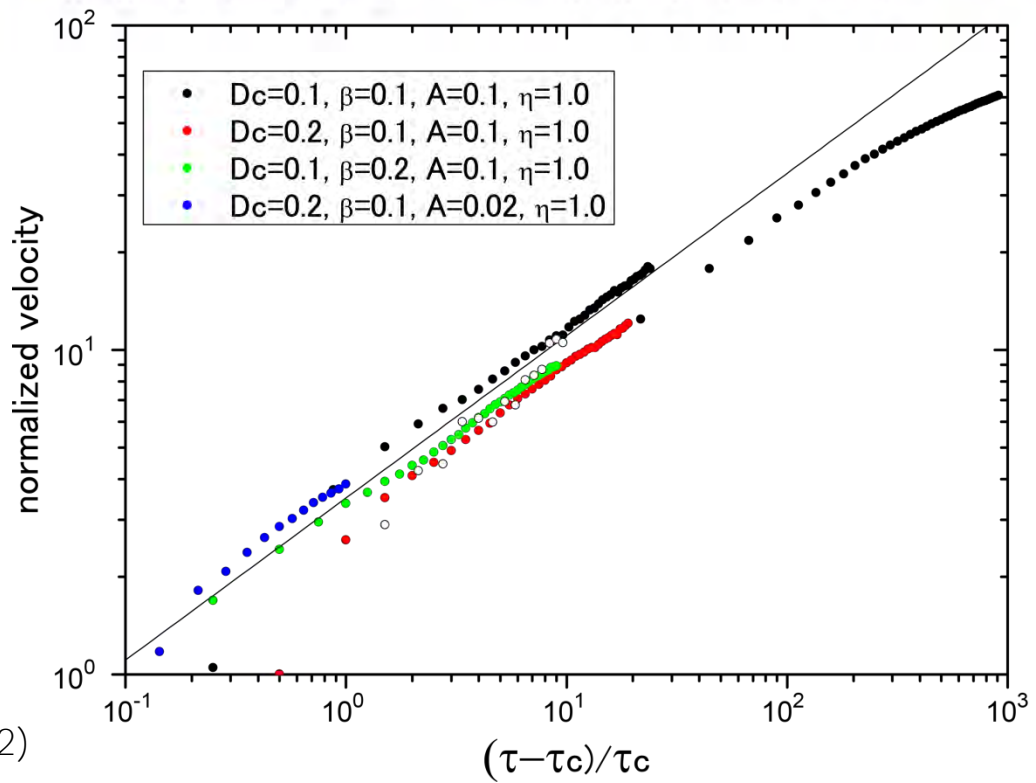
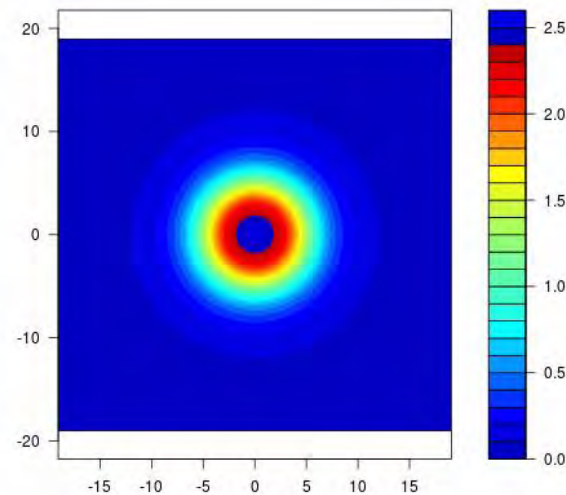
$$u \sim \sqrt{k D F_u(\beta R)}$$

$$\beta \sim \sqrt{\frac{k}{D}}$$

droplet



concentration

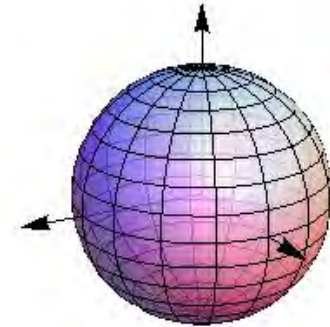


Deformation

First mode

$$S_{zz} > 0$$

$$m \frac{\partial u_i}{\partial t} = (-1 + \tau)u_i - gu^2 u_i + bu_i S_{ij}$$

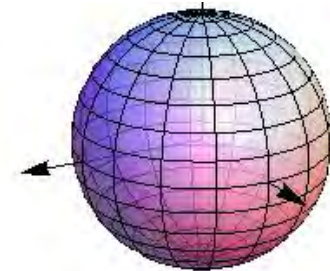


Second mode

↑ motion

$$\tau_2 \frac{\partial S_{ij}}{\partial t} = -\kappa S_{ij} + \lambda \left(u_i u_j - \frac{1}{3} \delta_{ij} u^2 \right)$$

$$S_{zz} < 0$$



T_{zzz}



le

$$+ \lambda_3 \left[u_i u_j u_k - \frac{1}{5} (u_i \delta_{jk} + u_j \delta_{ik} + u_k \delta_{ij}) \right]$$

$$- \frac{2}{5} u_\alpha (S_{j\alpha} \delta_{ik} + S_{k\alpha} \delta_{ij} + S_{i\alpha} \delta_{jk})$$

L

The drop is pusher

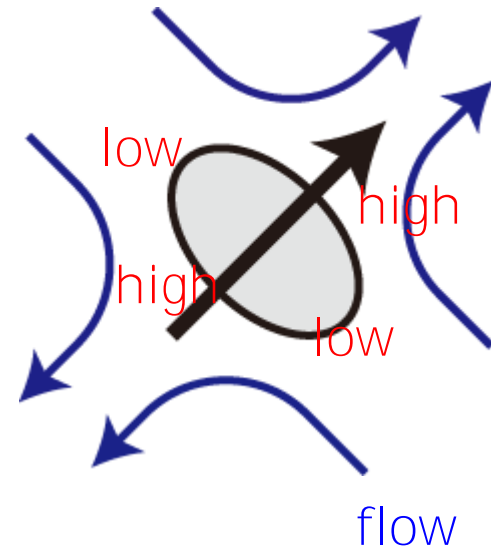
Second mode

$$\tau_2 \frac{\partial S_{ij}}{\partial t} = -\kappa S_{ij} - \lambda \left(u_i u_j - \frac{1}{3} \delta_{ij} u^2 \right)$$

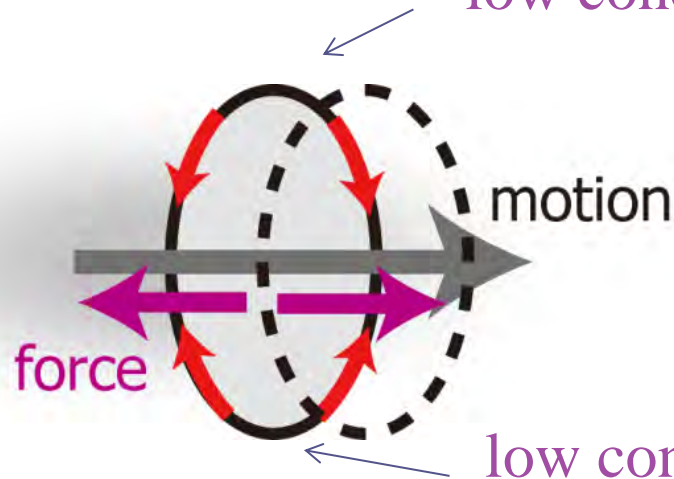
Stationary shape

$$S_{ij} = \frac{\lambda}{\kappa} \left(u_i u_j - \frac{1}{3} \delta_{ij} u^2 \right) \longrightarrow \gamma_2 > 0$$

surface tension



low conc.



Lyapunov function

$$E = (1 - \tau)u^2 + gu^4 + S_{ij} \left(u_i u_j - \frac{1}{3} u^2 \delta_{ij} \right)$$

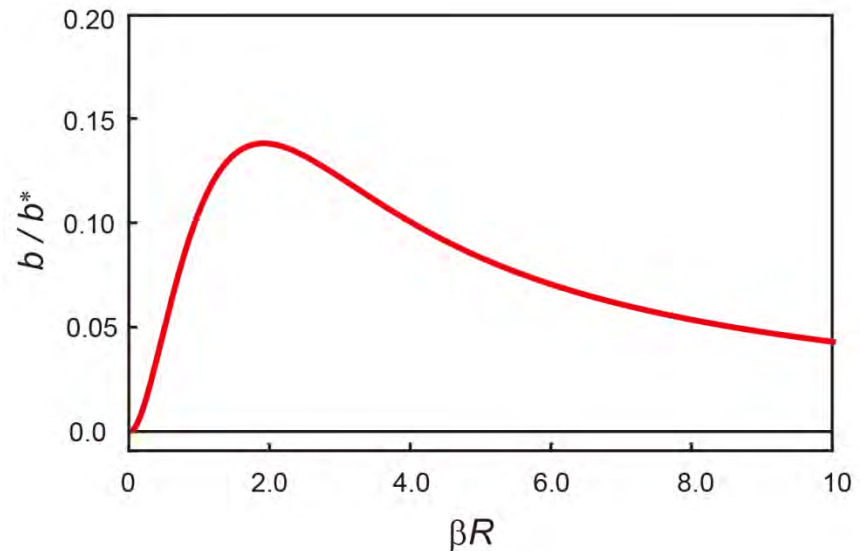
First mode

$$m \frac{\partial u_i}{\partial t} = - \frac{\partial E}{\partial u_i}$$

Second mode

$$\tau_2 \frac{\partial S_{ij}}{\partial t} = - \frac{\partial E}{\partial S_{ij}}$$

Lyapunov function exists when $b\lambda > 0$

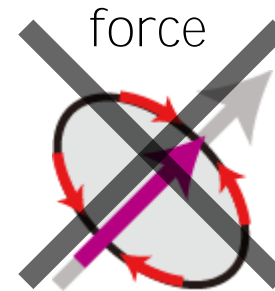


There is no Lyapunov function

Active Stress

Kortweg Stress

$$\Pi_{ij} = -B(c)\nabla_i\phi\nabla_j\phi$$



force dipole



Active Stress

$$\sigma_a = \frac{1}{R_0^3} \int_{\Omega} \Pi_a \approx -\frac{\gamma_c}{R_0} \int c(\mathbf{r}) n_i n_j dS$$

$$\longrightarrow \sigma_a \sim \lambda \left(u_i u_j - \frac{1}{3} \delta_{ij} u^2 \right)$$

$$D \sim 10^{-3} \text{ mm}^2 / \text{s}$$

$$R_0 \sim \beta^{-1} \sim 100 \mu\text{m}$$

$$\gamma_c A \sim 1 \text{ mN} / \text{m}\cdot\text{s}$$

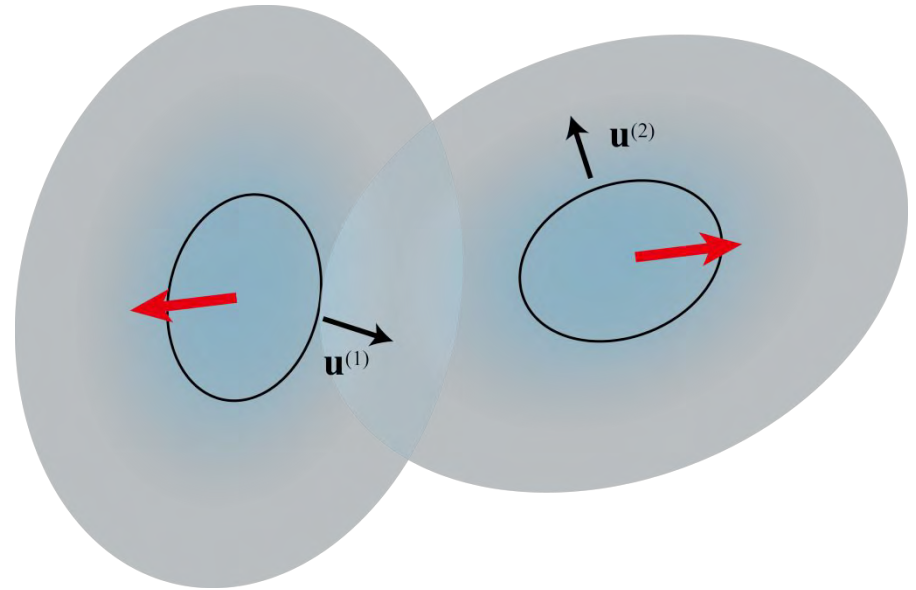
$$\sigma_a \sim 100 \text{ Pa}$$

Interaction

Shape of the droplet

$$R_i(\theta, \varphi) = R_0 + \delta R_i(\theta, \varphi)$$

$$\delta R_i(\theta, \varphi) = \sum_{l=2}^{\infty} \sum_{m=-l}^l w_{l,m}^{(i)} Y_l^m$$



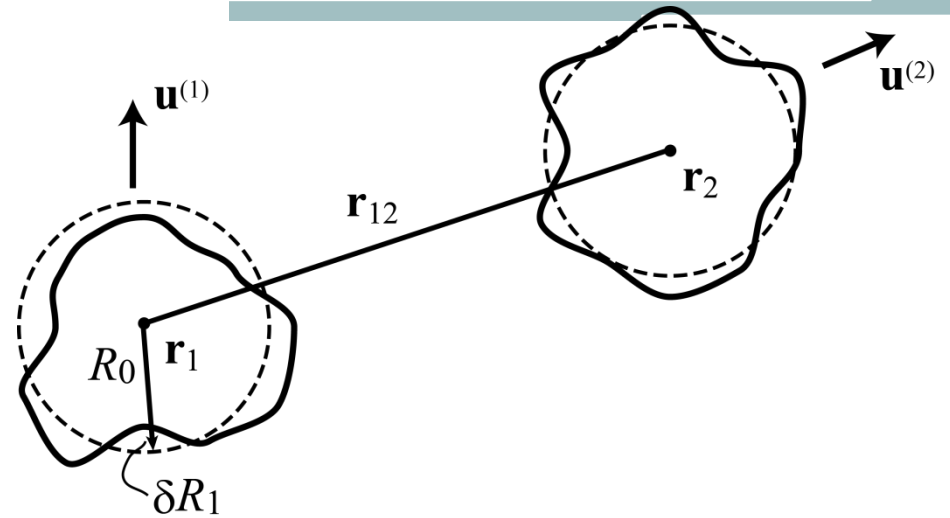
Dynamics of chemical

$$\frac{\partial c}{\partial t} = D \nabla^2 c - \kappa c + \sum_i A_i \Theta(R_i - |\mathbf{r} - \mathbf{r}_{G,i}|)$$

velocity of the droplet

$$m \frac{\partial \mathbf{u}_i^{(1)}}{\partial t} = (-1 + \tau) \mathbf{u}_i^{(1)} - g |\mathbf{u}^{(1)}|^2 \mathbf{u}_i^{(1)} + b u_j^{(1)} S_{ij}^{(1)} + \mathbf{u}_i^{\text{int}}$$

Interaction



velocity of the droplet

$$m \frac{\partial u_i^{(1)}}{\partial t} = (-1 + \tau) u_i^{(1)} - g |u^{(1)}|^2 u_i^{(1)} + b u_j^{(1)} S_{ij}^{(1)} + u_i^{\text{int}}$$

$$u_i^{\text{int}} = \nabla_{r_{i,1}} U(r_{12}) + \underbrace{F_1(r_{12}) N_j S_{ij}^{(2)} + F_3(r_{12}) N_{ijk} S_{jk}^{(2)} + \dots}_{\text{interaction between deformed droplets}}$$

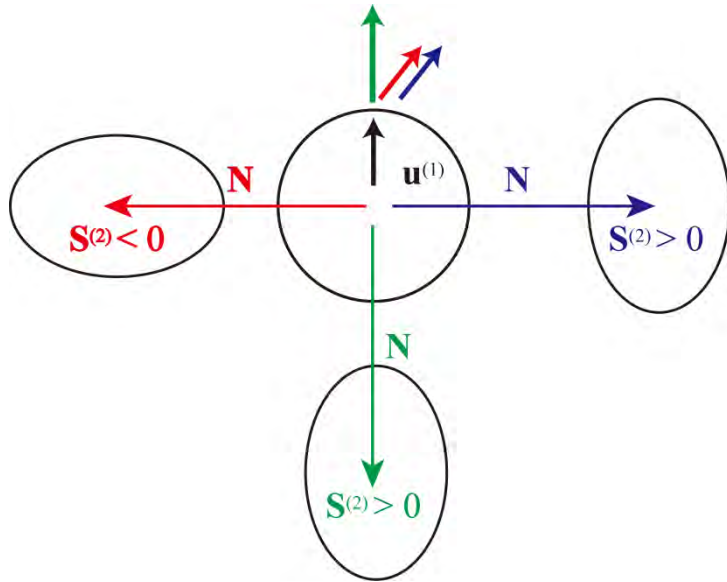
interaction between spherical droplets

interaction between deformed droplets

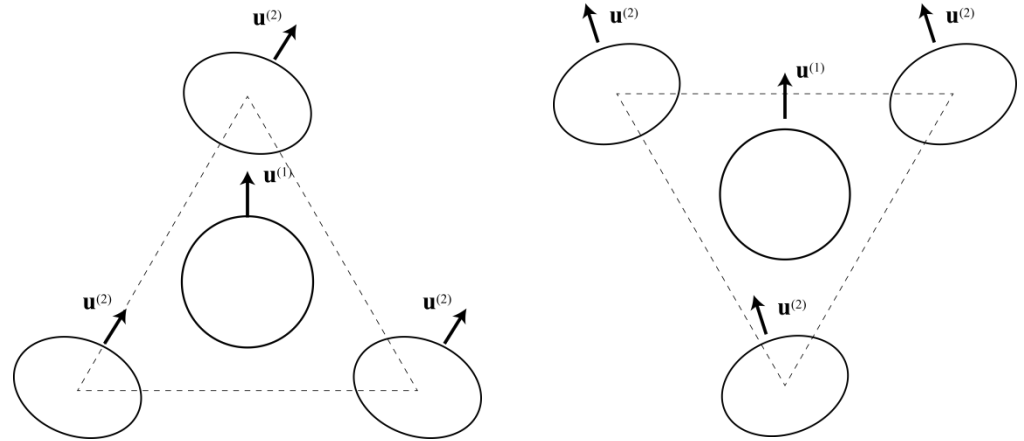
$$U(r_{12}) = \frac{A^{(2)} \gamma_c^{(1)}}{\eta D \beta^3} g(\beta R_0) k_0(\beta r_{12}) \sim \frac{e^{-\beta r_{12}}}{r_{12}} \quad \begin{cases} A^{(1)} A^{(2)} > 0 & \text{repulsive} \\ A^{(1)} A^{(2)} < 0 & \text{attractive} \end{cases}$$

Interaction

$$u_i^{\text{int}} \sim F_1(r_{12}) N_j S_{ij}^{(2)}$$



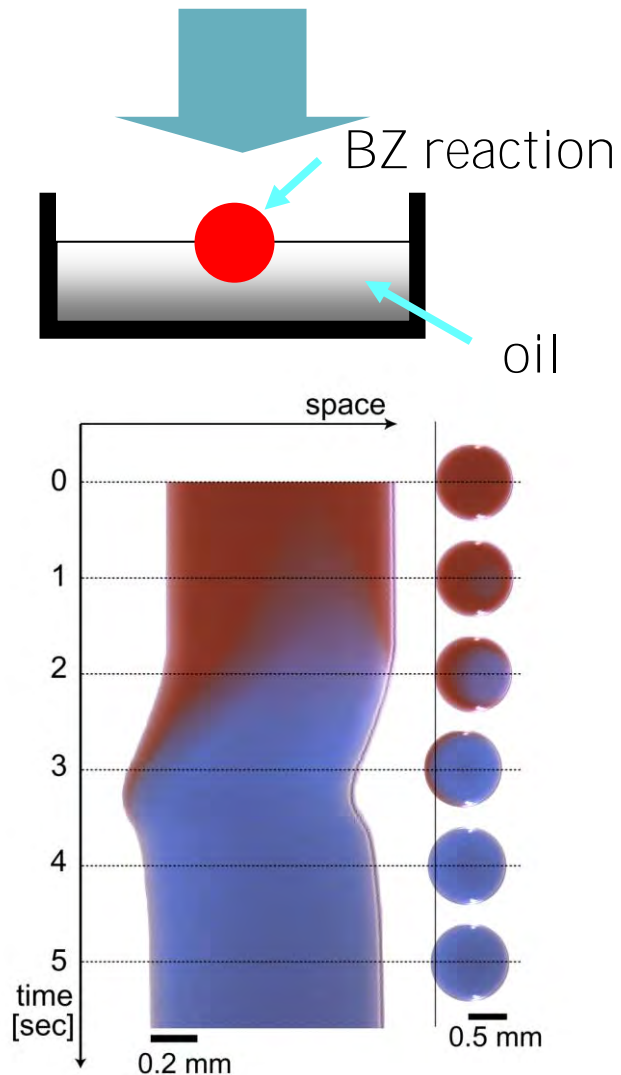
$$u_i^{\text{int}} \sim F_3(r_{12}) N_{ijk} S_{jk}^{(2)}$$



Tensor describing relative position

$$N_{ijk} = \hat{r}_{12,i} \hat{r}_{12,j} \hat{r}_{12,k} - \frac{1}{d+2} (\hat{r}_{12,i} \delta_{jk} + \hat{r}_{12,j} \delta_{ik} + \hat{r}_{12,k} \delta_{ij})$$

Self-propulsion of a BZ drop



BZ reaction medium on oil



Top view

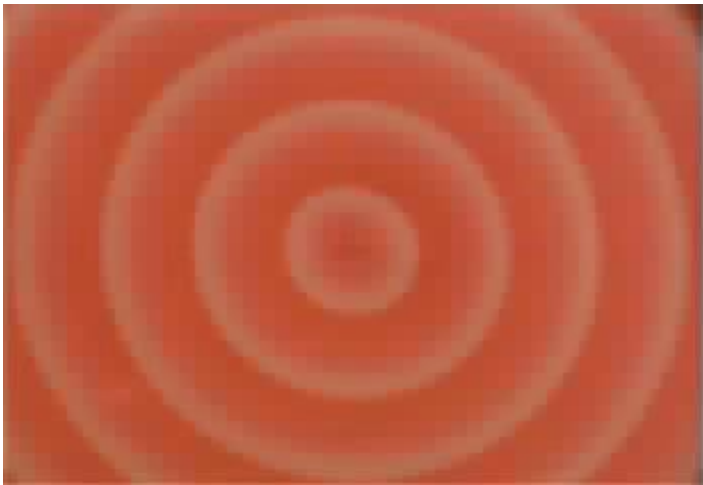
1 mm

H. Kitahata et al. (2002)

H. Kitahata, NY, K. H. Nagai and S. Yutaka, *PRE* **84** 015101 (2011)

Pattern in Chemical Reactions

Target Pattern



(x4 in time)

3 mm

Spiral Pattern



(x4 in time)

3 mm

Chemical reactions and flow field

• Chemical Reaction (Oregonator Model)

Activator:
$$\frac{\partial U}{\partial t} + \mathbf{v} \cdot \nabla U = \frac{1}{\varepsilon} \left[U(1-U) - fV \frac{U-q}{U+q} \right] + D_U \nabla^2 U$$

Inhibitor:
$$\frac{\partial V}{\partial t} + \mathbf{v} \cdot \nabla V = U - V + D_V \nabla^2 V$$

J. P. Keener and J. J. Tyson (1986)

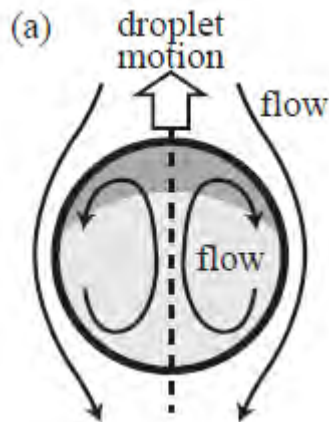
• Hydrodynamics

$$-\nabla p + \eta \nabla^2 \mathbf{v} = 0$$

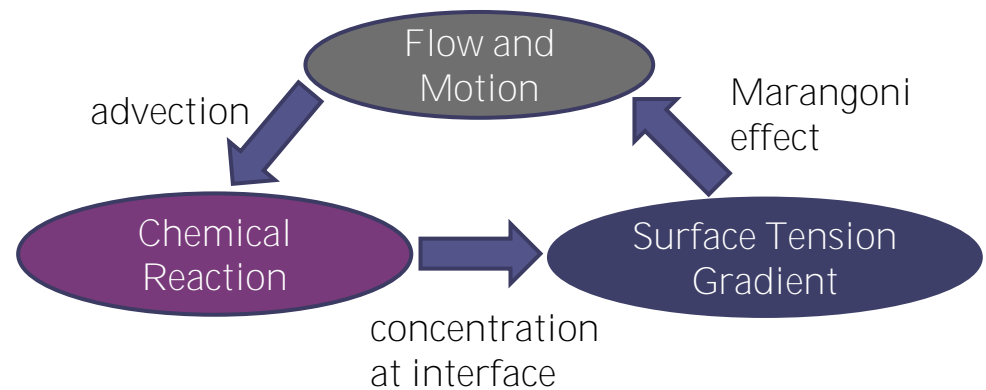
$$\nabla \cdot \mathbf{v} = 0$$

Surface tension

$$\gamma \propto V$$

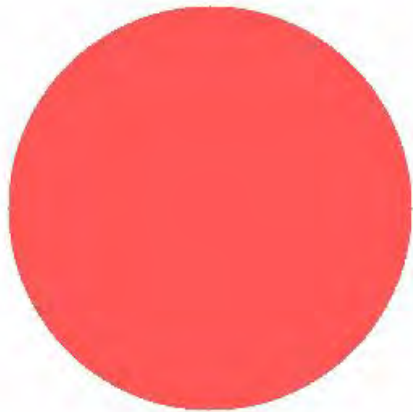


$$\mathbf{n} \cdot \boldsymbol{\sigma}^{(o)} - \mathbf{n} \cdot \boldsymbol{\sigma}^{(i)} = \partial_s (\gamma t)$$

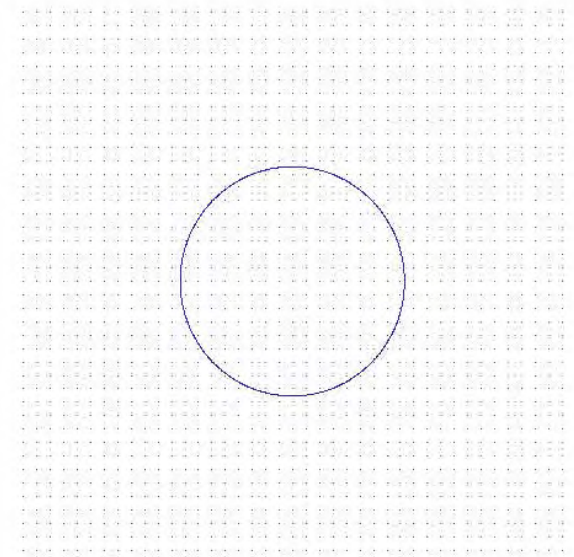
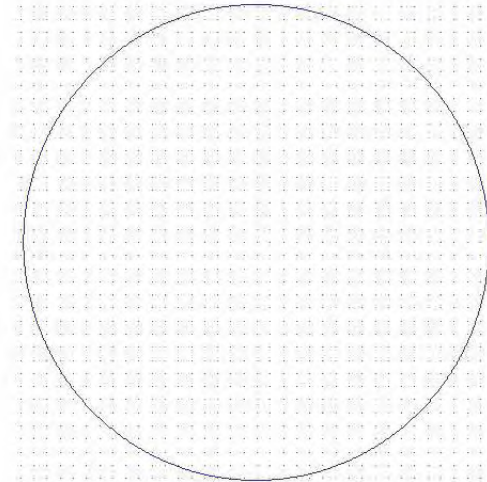


Target pattern and Motion

concentration



velocity field

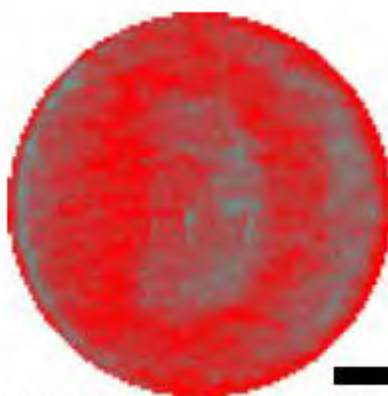


Pattern and motion

theory



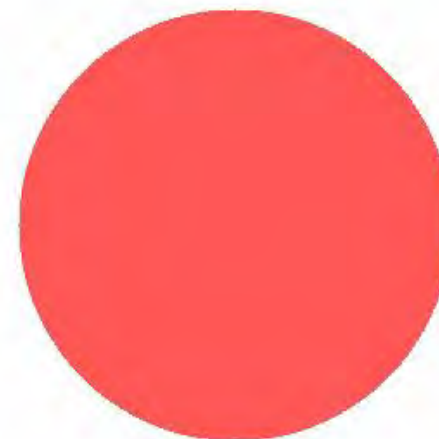
experiment



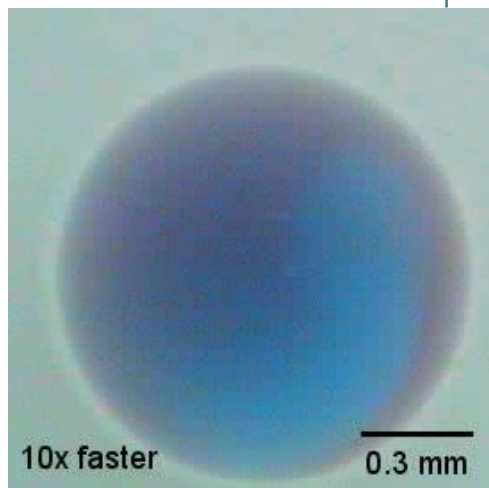
10x faster

0.3 mm

theory

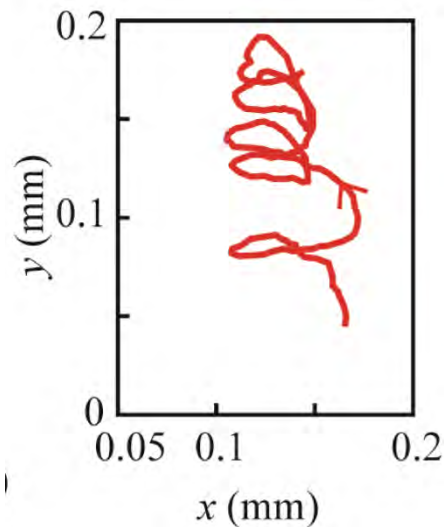


spiral pattern experiment



10x faster

0.3 mm



scrolling pattern

H. Kitahata, NY, K. H. Nagai and S. Yutaka, *Chem. Lett.* (2012)

Summary and Remarks

- Spontaneous motion and deformation
 - The amplitude equations for spontaneous symmetry breaking of self-propulsion is obtained.
 - Force moment and flow are characterized as a pusher.
- Motion and pattern formation
 - Pattern induced by chemical reaction makes a droplet motion.
- Future works
 - Collective phenomena, and hydrodynamic theory
 - Fluctuation (Langevin, stochastic PDE)
 - Complex fluid inside a droplet

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