

Conceptual “Progress” in Large Scale Dynamo Theory

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- Different styles and goals of dynamo research / analogies to accretion disk research
- Ask not: “Is mean field theory correct” BUT “Is it the correct mean field theory?”
- Classification of dynamos
- Magnetic helicity NOT kinetic helicity is the “unifying” helicity
- Seemingly different LSDs and their saturation can be unified by tracking magnetic helicity
- Textbook shortcomings vs. principles of nonlinear saturation
- Importance of time evolution, helicity fluxes, and shear
- Importance of subtle restrictions and differences between simulations
- Symbiosis between interior and coronal dynamos in astrophysics
- are key LSD properties sensitive to mechanism of reconnection?
- New “transient” dynamos for explosive astrophysics

I. Small Scale Dynamos

- flow driven
- no pseudo-scalar involved; EMF irrelevant
- field amplified at and below forcing scale; little amplification at $k < k_f$

2. Large Scale Dynamos (LSD)

- EMF essential; tracking properly defined magnetic helicity evolution potentially relevant for understanding saturation in ALL cases
- field sustained on time or spatial scales larger than turbulent forcing scales
- **Globally Reflection Asymmetric** sign of $\langle \bar{\mathcal{E}} \cdot \bar{B} \rangle$ fixed by initial conditions
- Saturation determined by coupling large scale B growth to small scale mag. helicity evolution
 - Flow Driven Helical Dynamo (FDHD): Inside Rotators
 - artificially forced or natural
 - sheared or unsheared
 - Magnetically Driven Helical Dynamo (MDHD)= Dynamical relaxation in Lab Plasmas and Coronae
- **Not GRA:** sign of $\bar{\mathcal{E}} \cdot \bar{B}$ can be finite in subaverage; helicity flux can be of fixed sign
 - stochastic large scale dynamos (e.g. Vishniac & Brandenburg 97)
 - turb+ shear w/out imposed helical forcing or pseudoscalar (Lesur & Ogilvie 08; Yousef et al 08)?
 - quasi-locally averaged finite pseudo scalars e.g. $\bar{\epsilon} \propto (\bar{\mathbf{W}} \cdot \nabla) \bar{B}^2$
 - absence of helical forcing but shear Brandenburg Sandin 04: Helicity fluxes sustain LSD

2A. Globally Helical LSDs

- Flow Driven (FDHD): flow energy initially exceeds mag. energy
 - FDHD: global pseudoscalar or pseudovector flux of mag. helicity
 - FDHD amplifies and pumps oppositely signed magnetic helicities to large and small scales **or** drives spatial flows of mag. helicity
 - nonhelical mean field can still dominate magn energy and
 - SSD often concurrent
- Magnetically Driven (MDHD): magnetic energy exceeds kinetic energy
 - MDHD: injection of magnetic helicity
 - MDHD induces relaxation of injected sign of mag. helicity to large scales and drives velocity flows.
 - interesting ambiguity with stratified MRI and tachocline

Laboratory Plasma Dynamos: MDHD

- injected magnetic helicity drives system away from relaxed state; MDHD fights to bring it back
- relaxed state has magnetic helicity on largest scale subject to boundary conditions
- MDHD sustains large scale field against decay
- MDHD “amplifies” large scale magnetic helicity
- analogue to astrophysical coronae: MDHD also important
- in astrophysics

Dynamo Evolution Equations: Unifying LSDs (e.g. B07)

$$\partial_t(\mathbf{A} \cdot \mathbf{B}) = -2\eta(\mathbf{J} \cdot \mathbf{B}) - \nabla \cdot (\Phi \mathbf{B} + \mathbf{E} \times \mathbf{A})$$

$$\partial_t \overline{\mathbf{a} \cdot \mathbf{b}} = -2\overline{\boldsymbol{\mathcal{E}} \cdot \overline{\mathbf{B}}} - 2\eta \overline{\mathbf{j} \cdot \mathbf{b}} - \nabla \cdot (\overline{\phi \mathbf{b}} + \overline{\mathbf{e} \times \mathbf{a}})$$

needed to understand saturation

$$\partial_t(\overline{\mathbf{A}} \cdot \overline{\mathbf{B}}) = 2\overline{\boldsymbol{\mathcal{E}} \cdot \overline{\mathbf{B}}} - 2\eta \overline{\mathbf{J} \cdot \overline{\mathbf{B}}} - \nabla \cdot (\overline{\Phi} \overline{\mathbf{B}} + \overline{\mathbf{E}} \times \overline{\mathbf{A}})$$

choose one: bottom required
when shear is important

$$\partial_t \overline{\mathbf{B}} = \nabla \times (\overline{\mathbf{V}} \times \overline{\mathbf{B}}) + \nabla \times \overline{\boldsymbol{\mathcal{E}}} + \nu_M \nabla^2 \overline{\mathbf{B}}$$

$$\partial_t \overline{\boldsymbol{\mathcal{E}}} = \overline{\partial_t \mathbf{v} \times \mathbf{b}} + \overline{\mathbf{v} \times \partial_t \mathbf{b}}$$

$$\partial_t \mathbf{b} = \dots$$

$$\partial_t \mathbf{v} = \dots$$

$$\partial_t \overline{\mathbf{V}} = \dots$$

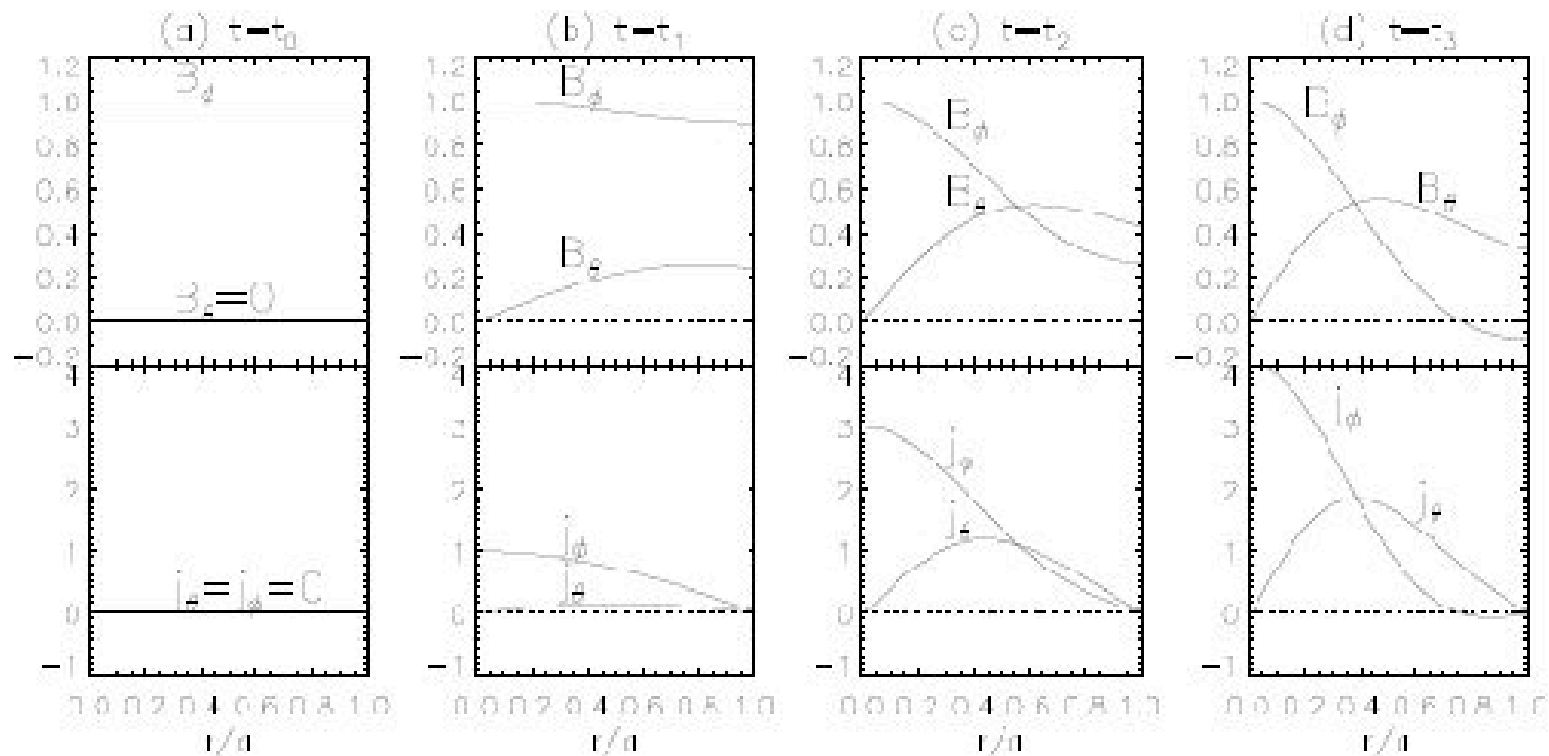
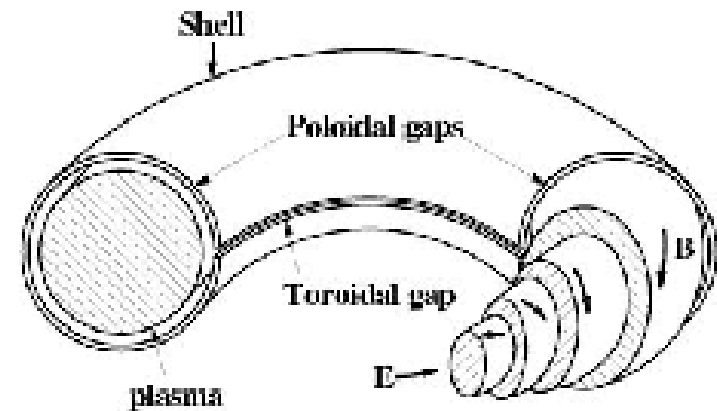
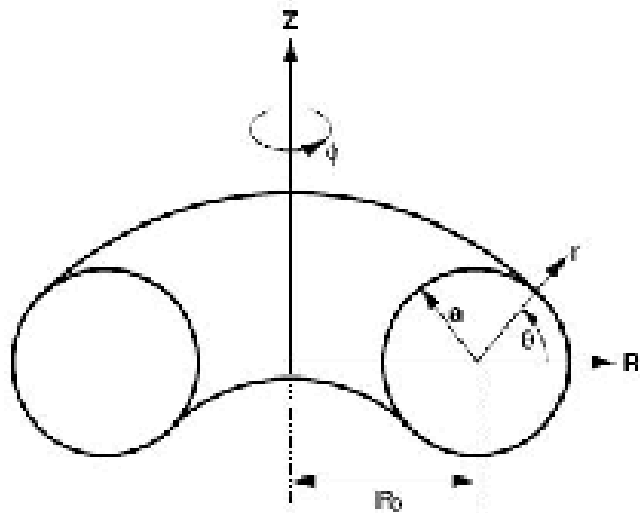
facilitates “minimal tau” closure for
dynamical theory e.g. BF02...Br-Sub05

$$\mathbf{E} = -\mathbf{V} \times \mathbf{B} + \eta \mathbf{J},$$

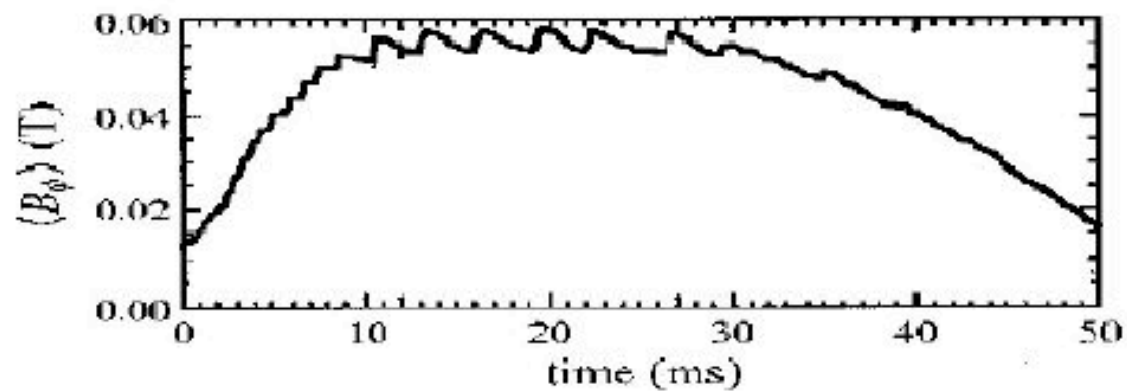
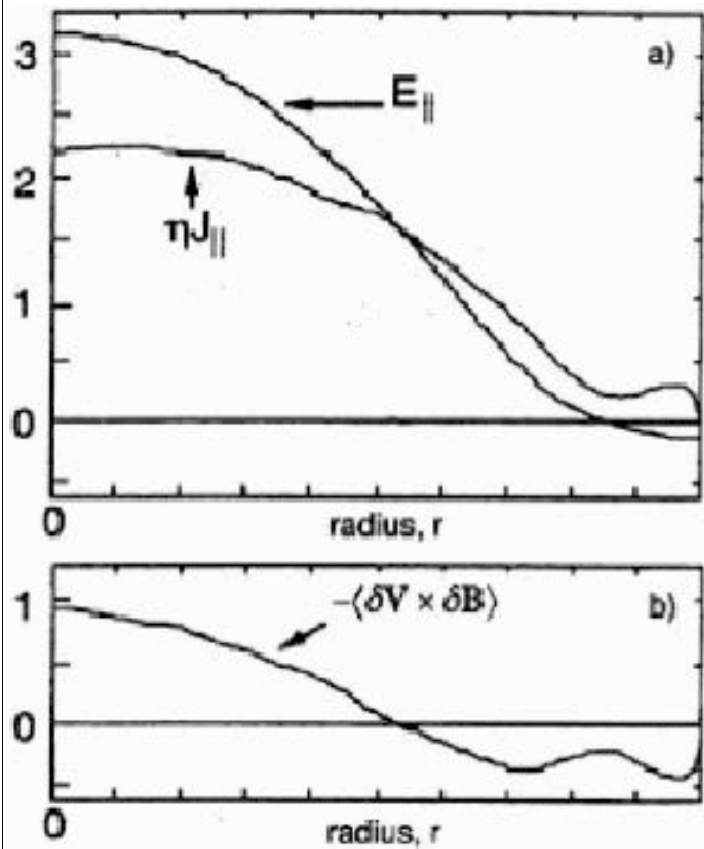
$$\overline{\mathbf{E}} = -\overline{\boldsymbol{\mathcal{E}}} - \overline{\mathbf{V}} \times \overline{\mathbf{B}} + \eta \overline{\mathbf{J}}$$

$$\mathbf{e} = \boldsymbol{\mathcal{E}} - \mathbf{v} \times \mathbf{b} - \mathbf{v} \times \mathbf{B} - \overline{\mathbf{V}} \times \mathbf{b} + \eta \mathbf{j}$$

Case I: MDHD: Tokamak Dynamo (figs from Ji & Prager 01)



MDHD: Tokamak Dyn (cont.)



Case I Tokamak Dynamo (continued)

Mean field is strong, fluctuations weak.

$$\partial_t(\overline{\mathbf{a} \cdot \mathbf{b}}) = 0 = -2\overline{\boldsymbol{\mathcal{E}} \cdot \mathbf{B}} - \nabla \cdot (\overline{\phi \mathbf{b}} + \overline{\mathbf{e} \times \mathbf{a}}) \quad (7)$$

$$\overline{\boldsymbol{\mathcal{E}} \cdot \mathbf{B}} = \nabla \cdot \overline{\mathbf{h}} = \eta \overline{\mathbf{J}} \cdot \overline{\mathbf{B}} - \overline{\mathbf{E}} \cdot \overline{\mathbf{B}} \quad (8)$$

$$\overline{\mathbf{E}} \cdot \overline{\mathbf{B}} = -\nabla \cdot (\overline{\Phi \mathbf{B}} + \overline{\mathbf{E}} \times \overline{\mathbf{A}}) \quad (9)$$

Helicity Injection: e.g.

$$\int \nabla \cdot (\overline{\Phi \mathbf{B}}) dV = \int \overline{\Phi \mathbf{B}} \cdot d\mathbf{S} = (\overline{\Phi}_2 - \overline{\Phi}_1) \Psi_t = V_s \Psi_t$$

V_s is voltage drop, Ψ_t is toroidal flux.

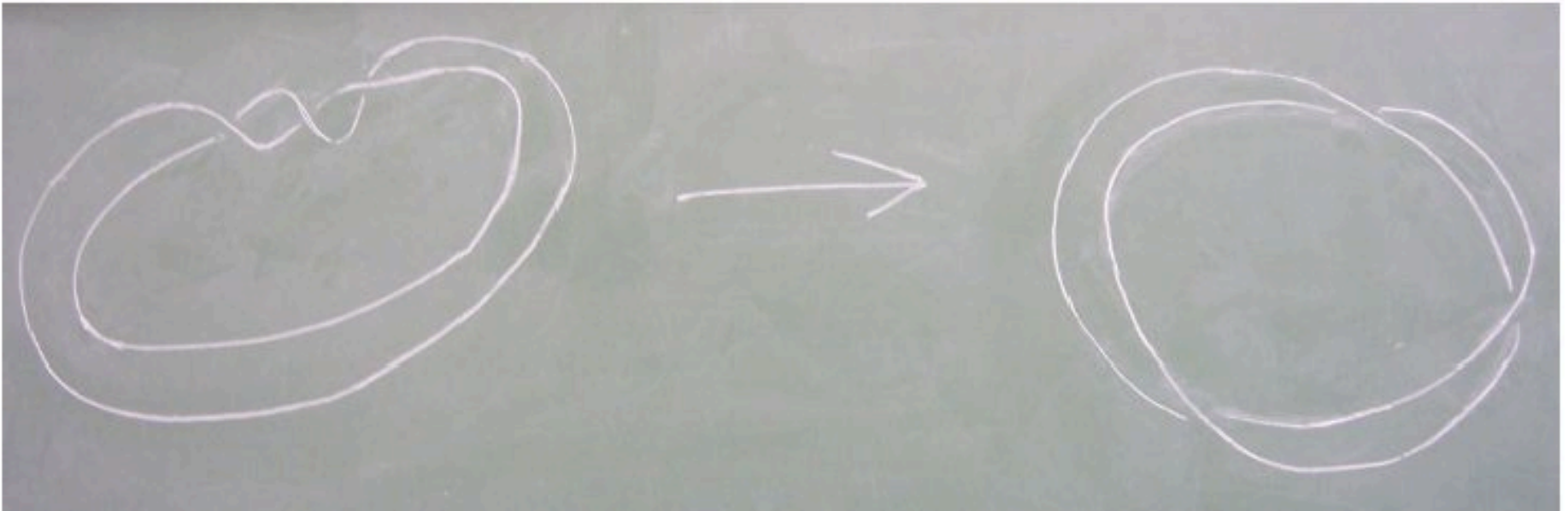
Integrating over the full volume:

$$\int \overline{\boldsymbol{\mathcal{E}}_{\parallel}} \cdot \overline{\mathbf{J}} dV = \int \Lambda \overline{\boldsymbol{\mathcal{E}} \cdot \mathbf{B}} dV = \int \Lambda \overline{\mathbf{h}} \cdot d\mathbf{S} - \int (\overline{\mathbf{h}} \cdot \nabla \Lambda) dV \simeq \int \eta \overline{\mathbf{J}}_{\parallel}^2 dV. \quad (10)$$

When surface term vanishes, outward flux of small scale helicity ($\overline{\mathbf{h}} > 0$) is, on average, in the direction of decreasing $\Lambda \equiv \frac{\overline{\mathbf{J} \cdot \mathbf{B}}}{B^2} (> 0)$. Helicity flux acts to “homogenize” helicity gradient.

also Strauss 85; Bhattacharjee Hameri 86; Bellan 00; Otolani & Schnack 93

MDHD (dynamical magnetic relaxation)



MDHD: Spheromak and Jet Formation (cont)

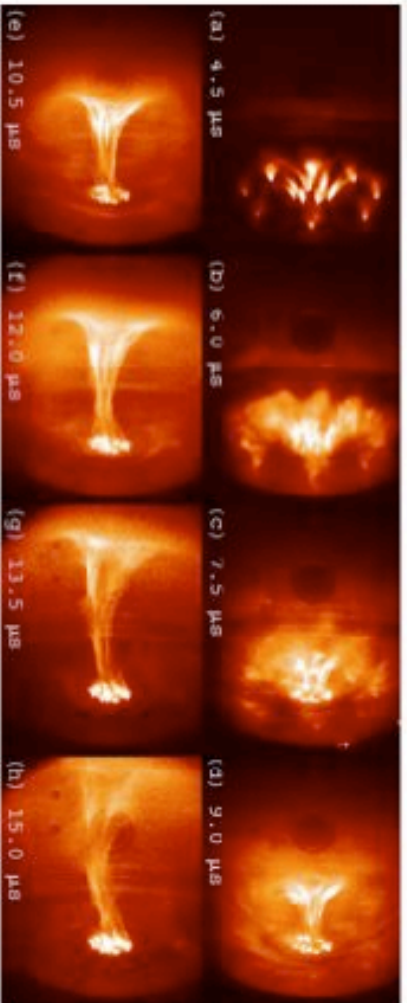


Figure 3. Images of plasma evolution (shot 1310, peak $\alpha_{\text{gas}} \approx 66 \text{ m}^{-1}$) in which a plasma column forms and persists for many Alfvén transit times, illustrating the magnetic topology required for an astrophysical jet.

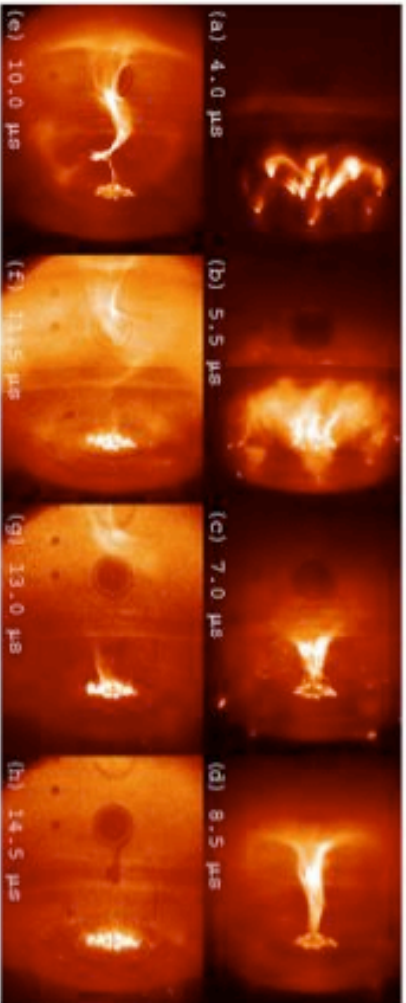


Figure 4. Images of plasma evolution (shot 1233, peak $\alpha_{\text{gas}} \approx 71 \text{ m}^{-1}$) in which a helical instability, probably a current-driven kink, develops on the ideal MHD time-scale, illustrating one possible source of jet internal structure.

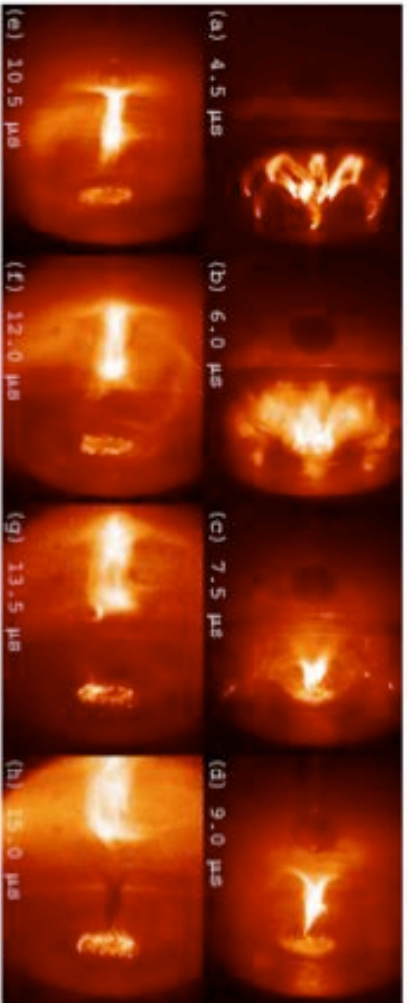


Figure 6. Images of plasma evolution (shot 1181, peak $\alpha_{\text{gas}} \approx 129 \text{ m}^{-1}$) in which the plasma detaches from the electrodes, illustrating the possibility of field-line opening in the anode.

MDHD: Spheromak and Jet Formation

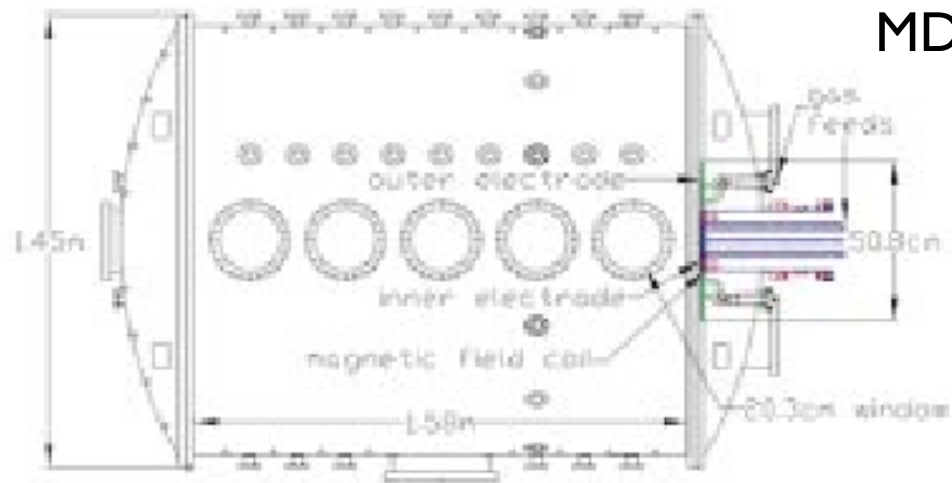


Figure 1. Side-view schematic of vacuum chamber and planar coaxial gun setup.

Hsu and Bellan 02

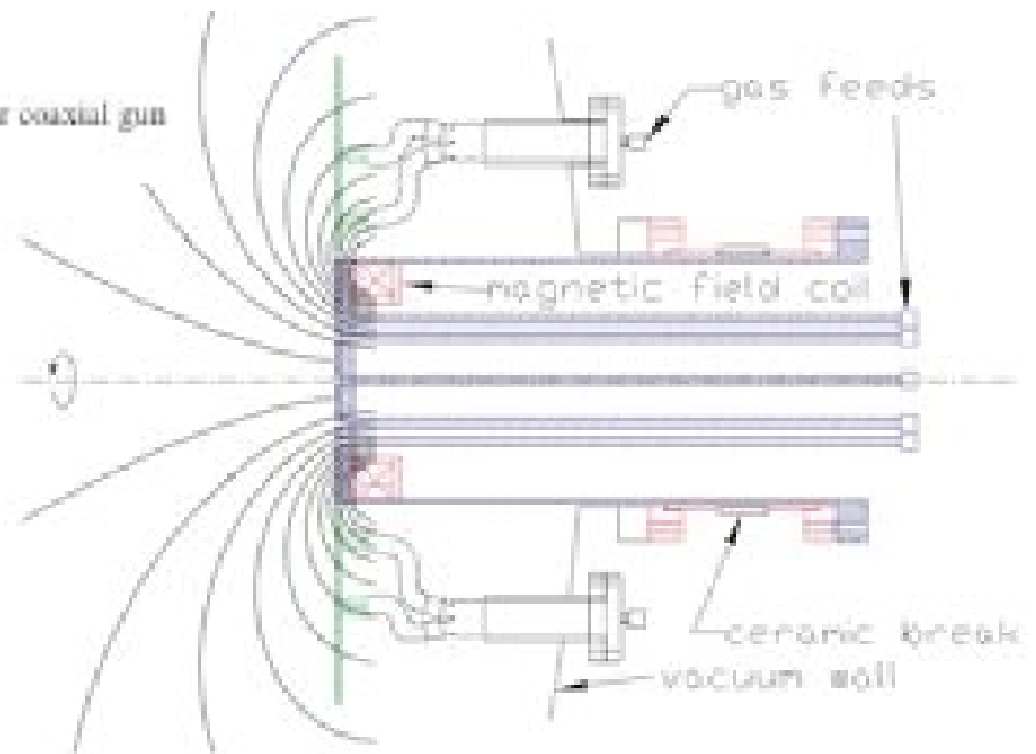
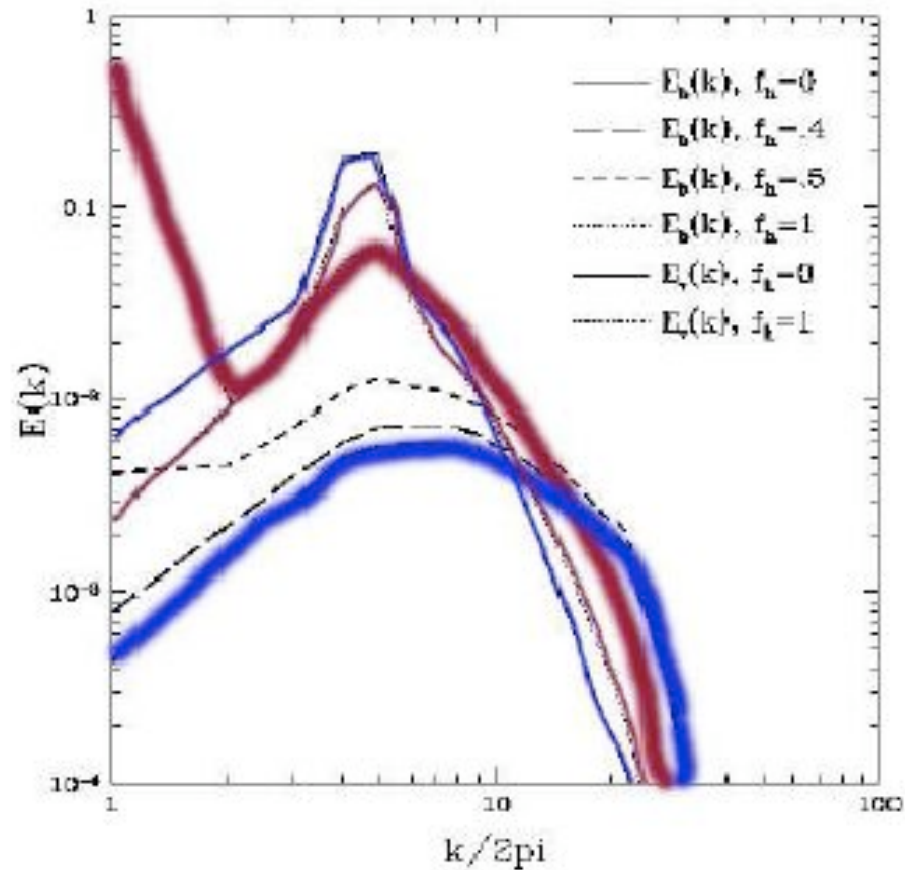


Figure 2. Side-view schematic of planar coaxial gun, including gas feeds, external magnetic field coil, poloidal flux ϕ contours and symmetry axis.

Case 2: FDHD: α^2 Dynamo in Periodic Box

LSD and SSD
concurrent



(simulation from Maron & Blackman 03; see also Brandenburg 01)

- NOTE: “Bi-helical Equilibrium” for $f_h = 1$

α^2 Dynamo in Periodic Box (cont)

Differential Equations to be solved:

$$\partial_t \langle \overline{\mathbf{A}} \cdot \overline{\mathbf{B}} \rangle = 2 \langle \overline{\mathcal{E}} \cdot \overline{\mathbf{B}} \rangle - 2\eta \langle \overline{\mathbf{J}} \cdot \overline{\mathbf{B}} \rangle + \cancel{\nabla \cdot \langle \rangle_1}$$

$$\partial_t \langle \mathbf{a} \cdot \mathbf{b} \rangle = -2 \langle \overline{\mathcal{E}} \cdot \overline{\mathbf{B}} \rangle - 2\eta \langle \mathbf{j} \cdot \mathbf{b} \rangle + \cancel{\nabla \cdot \langle \rangle_2}$$

$$\partial_t \overline{\mathcal{E}} = \partial_t \overline{\mathbf{v} \times \mathbf{b}} = \overline{\mathbf{v} \times \partial_t \mathbf{b}} + \overline{\partial_t \mathbf{v} \times \mathbf{b}}$$

$$= -\frac{1}{3} (\overline{\mathbf{v} \cdot \nabla \times \mathbf{v}} - \overline{\mathbf{b} \cdot \nabla \times \mathbf{b}}) \overline{\mathbf{B}} - \frac{1}{3} \overline{\mathbf{v}^2} f(\overline{\mathbf{B}}) \nabla \times \overline{\mathbf{B}} - \overline{\mathbf{v} \times \mathbf{b}} / \tau$$

$$\left| \begin{aligned} \partial_t \mathbf{b} &= -\nabla \times \mathbf{e} = \nabla \times (\mathbf{v} \times \overline{\mathbf{B}}) + \nabla \times (\mathbf{v} \times \mathbf{b}) - \nabla \times \overline{\mathbf{v} \times \mathbf{b}} + \eta \nabla^2 \mathbf{b} + g(\overline{\mathbf{V}}) \\ \partial_t \mathbf{v} &= \mathbf{f} - \mathbf{v} \cdot \nabla \mathbf{v} + \overline{\mathbf{v} \cdot \nabla \mathbf{v}} - \nabla p + \mathbf{j} \times \overline{\mathbf{B}} + \overline{\mathbf{J}} \times \mathbf{b} + \mathbf{j} \times \mathbf{b} - \overline{\mathbf{j} \times \mathbf{b}} + \nu \nabla^2 \mathbf{v} + f(\overline{\mathbf{V}}) \end{aligned} \right|$$

- minimal τ closure for triple corr. in $\partial_t \overline{\mathcal{E}}$ (used in BF02 (dynamo), BF03 (scalar diffusion))
(note also: Vainshstein Kitchatinov 83; Kleeorin + al. 96; Raedler + al. 03)

τ is damping time, not correl. time.

- No first order smoothing needed

α^2 Dynamo in Periodic Box (cont)

$$\partial_t H_1^M = \frac{2k_1\tau}{3} (k_2^2 H_2^M - H_2^V) H_1^M - 2\beta k_1^2 H_1^M - 2\nu_M k_1^2 H_1^M$$

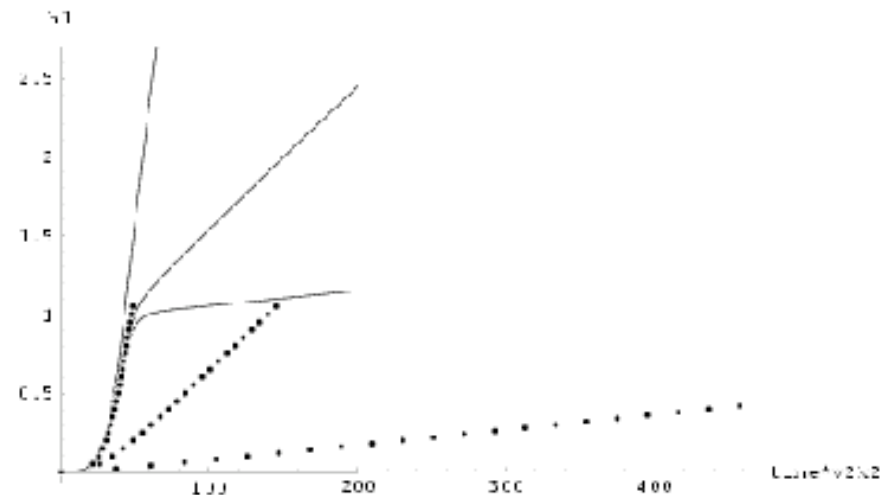
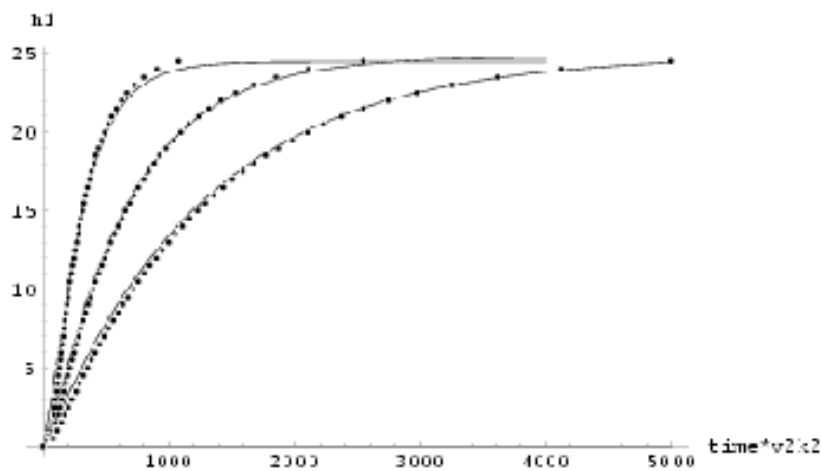
$$\partial_t H_2^M = -\frac{2k_1\tau}{3} (k_2^2 H_2^M - H_2^V) H_1^M + 2\beta k_1^2 H_1^M - 2\nu_M k_2^2 H_2^M$$

$$\partial_t H_2^V = 0$$

- Helical velocity driven dynamo “pumps” magnetic helicity of one sign to large scales and the other sign to small scales

α^2 Dynamo in Periodic Box (cont)

Large Scale Helical Field Growth: 2-scale (Blackman & Field 02) vs. empirical fit formula of Brandenburg (01) Curves left to right: $R_M = 100, 250, 500$: h_1 normalized Large scale magnetic helicity.



- At end of kinematic regime: $\overline{\mathbf{B}}^2 \sim f_h v_2^2 \left(\frac{k_1}{k_2} \right)$
- At end of resistive regime: $\overline{\mathbf{B}}^2 \sim f_h v_2^2 \left(\frac{k_2}{k_1} \right)$

MULTI-SCALE THEORY (B03;B05)

$$\partial_\tau h_1 = \frac{2}{3} \left(f_h + h_2 + \left(\frac{k_3}{k_2} \right)^{\frac{4}{3}} h_3 \right) \frac{k_1}{k_2} h_1 - 2 \left(\frac{q(h_1)}{3} + \frac{q(h_1)}{3} \left(\frac{k_2}{k_3} \right)^{\frac{4}{3}} + \frac{1}{R_M} \right) \left(\frac{k_1}{k_2} \right)^2 h_1 \quad (11)$$

$$\begin{aligned} \partial_\tau h_2 = & \frac{-2}{3} \left(\frac{k_3}{k_2} \right)^{\frac{4}{3}} f_u h_3 h_2 - \frac{2}{3} (f_h + h_2) \frac{k_1}{k_2} h_1 + \frac{2q(h_1)}{3} \left(\frac{k_1}{k_2} \right)^2 h_1 \\ & - 2 \left(\frac{q(h_1)}{3} g_u \left(\frac{k_2}{k_3} \right)^{\frac{4}{3}} + \frac{1}{R_M} \right) h_2 \end{aligned} \quad (12)$$

and

$$\begin{aligned} \partial_\tau h_3 = & \frac{2}{3} \left(\frac{k_3}{k_2} \right)^{\frac{4}{3}} f_u h_3 h_2 - \frac{2}{3} \left(\frac{k_3}{k_2} \right)^{\frac{4}{3}} \left(\frac{k_1}{k_2} \right) h_3 h_1 + \frac{2q(h_1)}{3} \left(\frac{k_2}{k_3} \right)^{\frac{4}{3}} \left(\frac{k_1}{k_2} \right)^2 h_1 \\ & + \frac{2q(h_1)}{3} g_u \left(\frac{k_2}{k_3} \right)^{\frac{4}{3}} h_2 - \frac{2}{R_M} \left(\frac{k_3}{k_2} \right)^2 h_3 \end{aligned} \quad (13)$$

At end of fast growth regime:

$$h_1 \simeq 1 - (k_2/k_3)^{4/3} + (k_2/k_3)^{8/3} \quad (14)$$

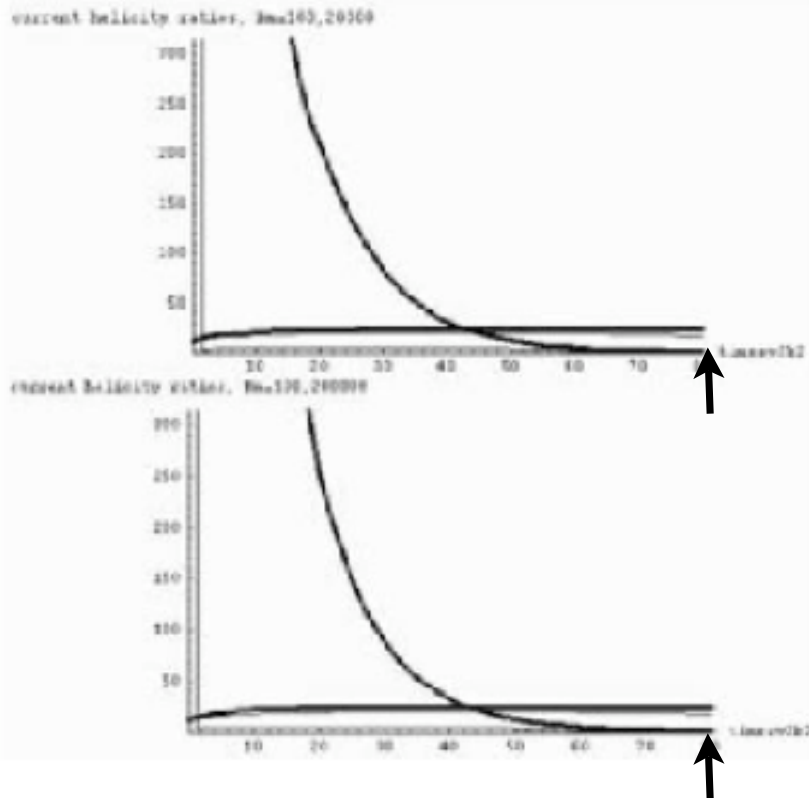
$$h_2 \simeq -1 + (k_2/k_3)^{4/3} \quad (15)$$

and

$$h_3 \simeq -(k_2/k_3)^{8/3} \quad (16)$$

3-scale approach justifies 2 scale approach:

“Small scale” mag and current helicity initially peaks at tiny scales, but quickly inverse transfers to forcing scale before kinematic regime ends



$$\frac{k_3^2 h_3}{k_2^2 h_2} = \left(\frac{k_2}{k_3} \right)^{2/3}$$

Figure 3. The absolute magnitude of the current helicity ratios $|k_2^2 h_2 / k_1^2 h_1|$ and $|k_3^2 h_3 / k_1^2 h_1|$, and helical magnetic energy ratios $|k_2 h_2 / k_1 h_1|$ and $|k_3 h_3 / k_1 h_1|$ assuming an initial seed of $h_2(0) = h_3(0) = -h_1(0)/2 = 0.0005$, for $k_1 = 1, k_2 = 5, k_3 = 160$. The top row shows plots for $R_M = 100$ (thin lined curves) and $R_M = 2 \times 10^4$ (thick lined curves) and the bottom row shows plots for $R_M = 100$ (thin lined curves) and $R_M = 2 \times 10^5$ (thick lined curves). In each plot, the quantities at k_3 dominate at early times, but then become subdominant to the values at k_2 at later times. The magnetic energy plot is shown for a broader time range. The location of the crossover for the large- R_M cases of 2×10^4 and 2×10^5 is independent of R_M : the crossovers occur for the thick pairs of lines at the same time in the top and bottom rows. The crossover occurs much earlier for $R_M = 100$ because the resistive wavenumber is closer to k_3 and thus the resistivity is more effective at early times in draining the current helicity and magnetic energy at k_3 than in the larger- R_M cases. For the current helicity, the crossover for $R_M = 100$ occurs so early that it is not visible on the graph. Before the end of the kinematic regime ($t \lesssim 100$), the crossovers are complete and k_2 emerges as the dominant small scale. Since $k_3 = 160$ here, $R_M = 100$ corresponds to $Pr_M \approx 1$.

Lessons from α^2 in periodic box

- coupling small scale magnetic helicity evolution into theory correctly predicts the saturation; two scale model works well

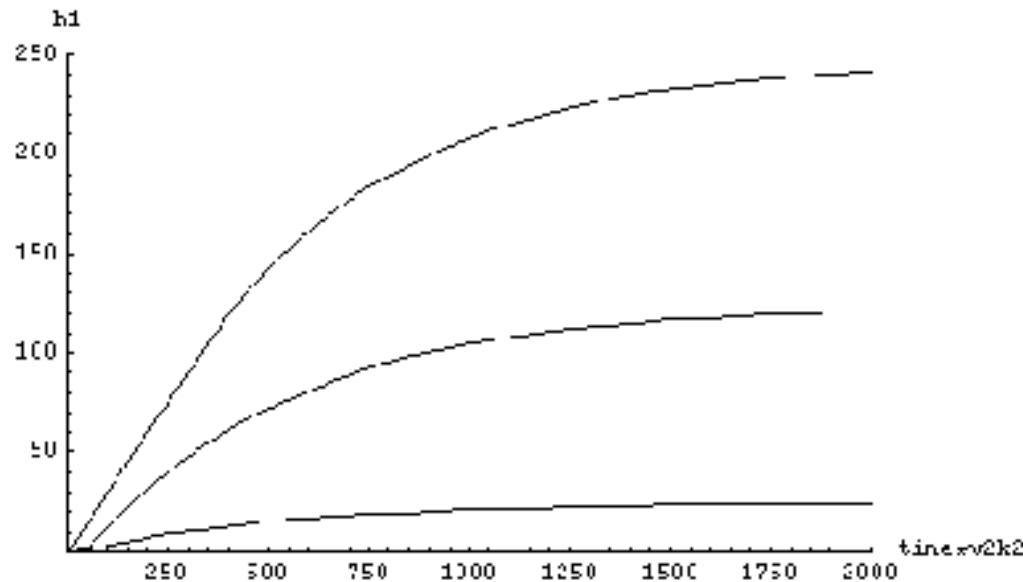
- $$\alpha = \frac{\alpha_0 + R_M \left(\frac{\beta \bar{\mathbf{J}} \cdot \bar{\mathbf{B}}}{B_{eq}^2} - \frac{\nabla \cdot \bar{\mathbf{J}}}{2\nu_f B_{eq}^2} - \frac{\partial \alpha / \partial t}{2\nu_M k_f^2} \right)}{1 + R_M \bar{B}^2 / B_{eq}^2}$$

- reduces to Cattaneo & Hughes 96 Gruzinov & Diamond 94 for steady state uniform field (note also Kleorin & Ruzmaikin 82)
- simulations and theory agree in dynamical evolution but early times warrant better resolution to isolate kinematic from resistive regime
- kinematic growth produces significant LS field before resistive regime
- this kinematic regime is not necessarily enough; would like avoidance of resistively limited regime
- alleviating SS mag helicity buildup is key to avoid catastrophic quenching. This is facilitated with shear and helicity fluxes



BOUNDARY TERMS

- Effect of adding a **loss** term proportional to H_2 on the growth of H_1 for three different values of loss. From top to bottom, these factors are 10, 5 and 1 (=no loss), respectively. Here $R_M = 200$ and $k_2/k_1 = 5$.



- loss of SS mag helicity helpful but both large and ss losses expected (Blackman & Field 00ab; Blackman & Brandenburg 03)
- cycle could remain fast even if saturated large scale field reduced.
- understand the relative losses in a real system self-consistently
- Brandenburg & Sandin 04: open boundaries + shear required

Case 3: FDHD with helicity fluxes and shear

- Vishniac-Cho flux (01), recast by Subramanian & Brandenburg (04,06); flux along surfaces of cons. shear $F_{VC,i} \propto \epsilon_{ink} S_{nj} B_j B_k$
($S_{nj} \equiv \partial_n \bar{V}_j - \partial_j \bar{V}_n$)
- advective flux (Shukurov et al. 06) $F_{ad,i} \propto \alpha_m \bar{U}_i$
- Numerical evidence supports that SS helicity fluxes facilitate fast, robust LSD action when shear is present:
 - e.g. Brandenburg & Sadin 04 + Br-Sub 05+..: VC flux in forced turbulence with shear in solar like rotation profile with and without forcing kinetic helicity sustains LSD; shear required
 - e.g. Kapyla et al. 2008: LSD from convection + shear with surfaces of constant shear aligned toward open boundaries; Tobias et al. (08): no LSD under similar conditions BUT shear is aligned toward periodic boundaries disallowing F_{vc}

Case 3 (cont): Time dependent α - Ω with helicity flux

Galactic dynamos with Shear and small scale helicity fluxes (Shukurov et al. 2006; Sur et al 2007):

$$\mathcal{E} = \alpha \bar{B} - \eta_t \bar{J}$$

$$\alpha = \alpha_K + \alpha_m$$

$$\alpha_m = \frac{1}{3} \rho^{-1} \overline{\tau j \cdot \mathbf{b}}$$

$$\frac{\partial \bar{B}_r}{\partial t} = -\frac{\partial}{\partial z} (\bar{U}_z \bar{B}_r + \mathcal{E}_\phi) + \eta \frac{\partial^2 \bar{B}_r}{\partial z^2},$$

$$\frac{\partial \bar{B}_\phi}{\partial t} = -\frac{\partial}{\partial z} (\bar{U}_z \bar{B}_\phi - \mathcal{E}_r) + \eta \frac{\partial^2 \bar{B}_\phi}{\partial z^2} + q \Omega_0 \bar{B}_r,$$

$$\frac{\partial \alpha_m}{\partial t} = -2 \eta k_0^2 \left(\frac{\mathcal{E} \cdot \mathbf{B}}{B_{\text{eq}}^2} + \frac{\alpha_m}{R_m} \right) - \nabla \cdot (\alpha_m \bar{U})$$

$$\bar{B}_r = \bar{B}_\phi = 0 \quad \text{at } z = \pm h.$$

$$C_U = \frac{U_0}{\eta k_1}, \quad C_\Omega = \frac{\Omega_0}{\eta k_1^2}, \quad C_\alpha = \frac{\alpha_0}{\eta k_1}$$

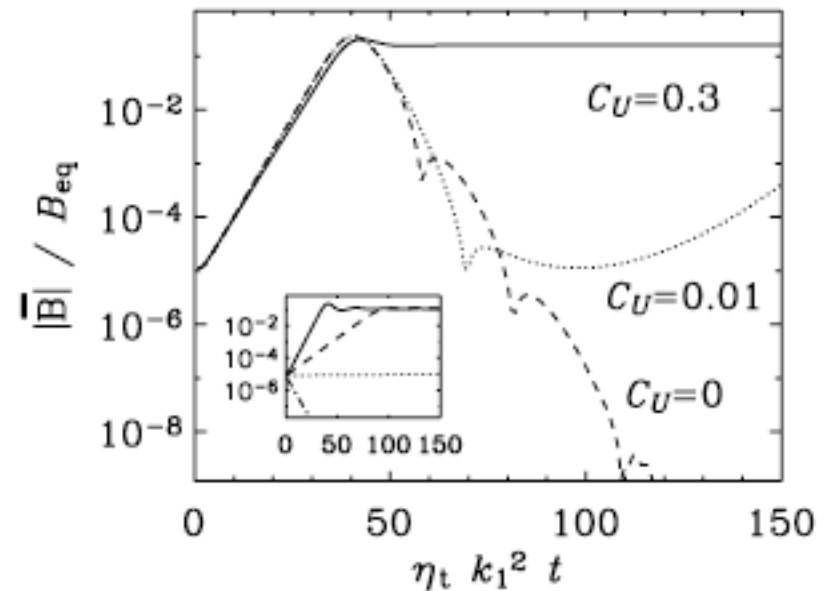
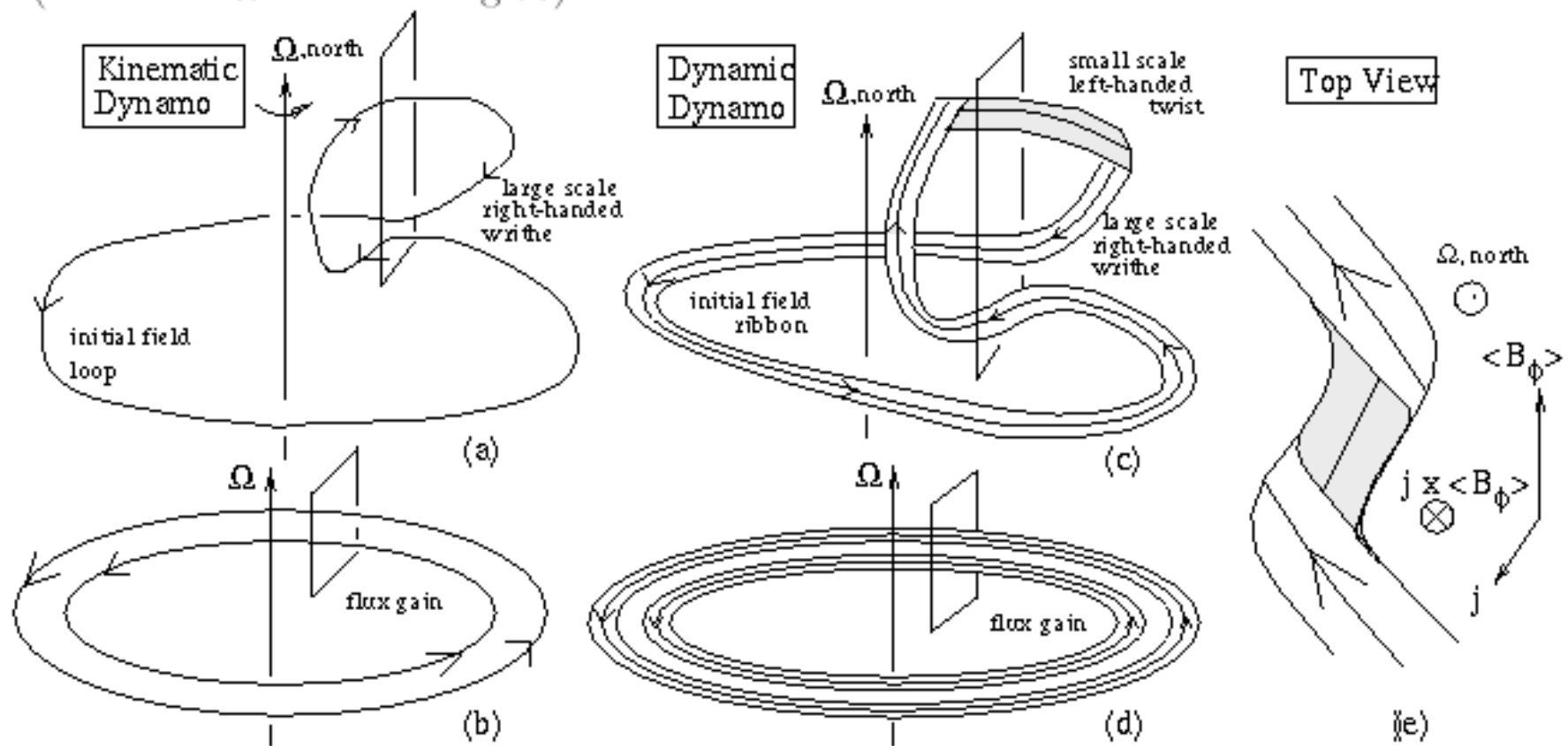


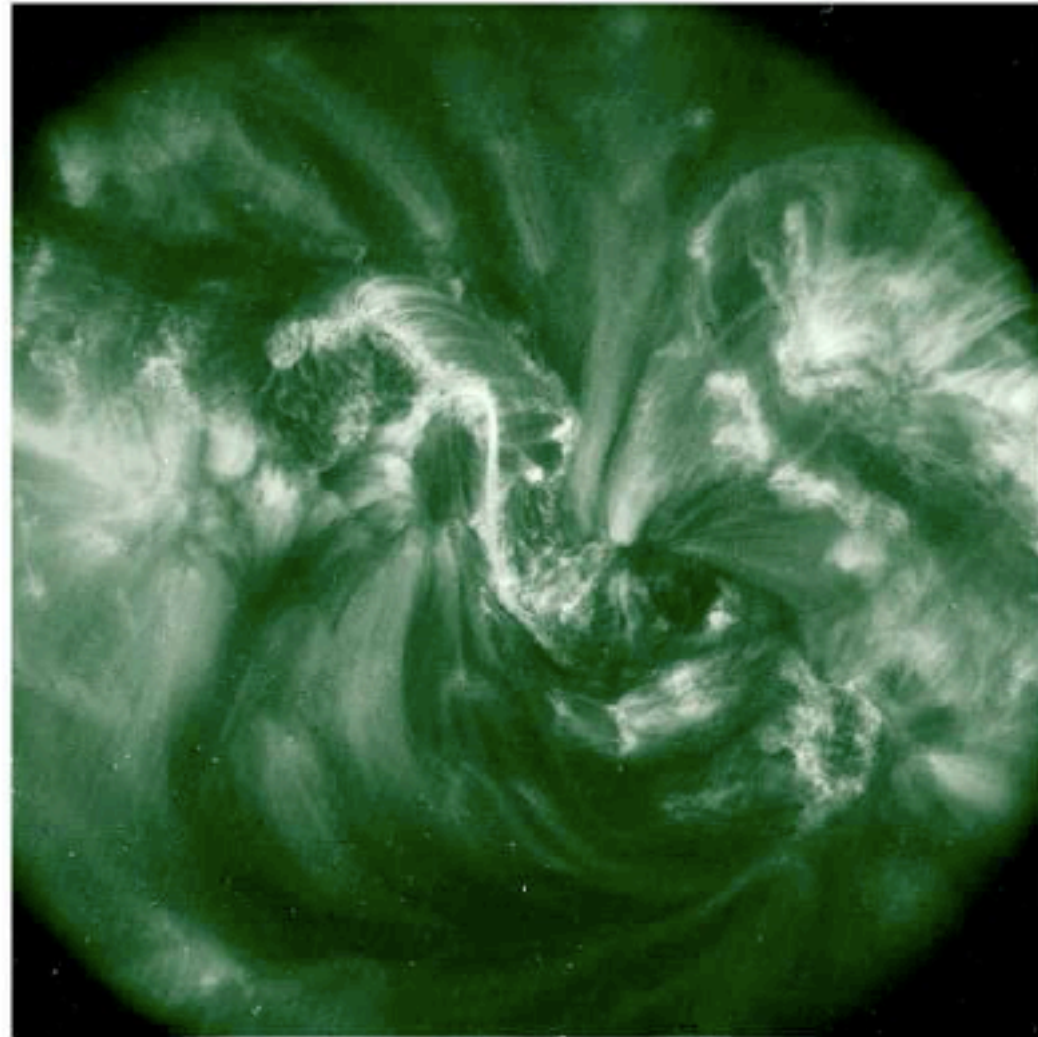
Fig. 1. Evolution of the field strength at $z = 0$ obtained by solving Eqs. (4)–(7) with vertical advection (solid line, $C_U = 0.3$) and without it (dashed line, $C_U = 0$), for $C_\Omega = -2$, $C_\alpha = 1$ and $R_m = 10^5$. The dynamo is neutrally stable at $C_\alpha = 0.26$ for $C_U = 0.3$ and $C_\Omega = 2$. The dotted curve, obtained for $C_U \ll 1$, shows that even weak advection can affect the long-term evolution of magnetic field. For $C_U = 0$, nonlinear effects make the α profile flatter at small $|z|$; this causes an oscillatory decay of the field. The inset shows similar results for $C_U = 0.1$ (solid), 1.5 (dashed), 2 (dotted) and 3 (dash-dotted).

HELICAL DYNAMO: REVISING THE "TEXTBOOK" PICTURE

(Blackman & Brandenburg 03)



TRACE Image of a Sigmoid (Gibson et al. 2003) (195 Å)



MAGNETIC HELICITY INJECTION INTO A CORONA

- Relative helicity injection

$$\frac{dH_c}{dt} = -2 \int_c \mathbf{E} \cdot \mathbf{B} dV_c + 2 \int_c (\mathbf{E} \times \mathbf{A}_p) \cdot d\mathbf{S} \quad (1)$$

$$= -\frac{1}{2\pi} \int \int_{\mathbf{B}_n \cdot \mathbf{B}'_n > 0} \frac{d\theta}{dt} B_n B'_n dS dS' + \frac{1}{2\pi} \int \int_{\mathbf{B}_n \cdot \mathbf{B}'_n < 0} \frac{d\theta}{dt} |B_n B'_n| dS dS' \quad (2)$$

$$= \frac{dH_r}{dt}(\text{twist}) \quad + \quad \frac{dH_r}{dt}(\text{writhe}) \quad (3)$$

(e.g. Berger & Ruzmaikin 2000; Demoulin et al. 2002, 2003)

Solar Corona Observational Issues

- polarity from Zeeman; \mathbf{B}_t is tricky
- $C = \langle \mathbf{J} \cdot \mathbf{B} \rangle$ gives handedness; C vs. H_r and issue wrt λ
- Chae (01,04); Local Correlation Tracking (LCT) technique for measuring helicity injection (see also Shuck 2005; Lim et al. 2007, compare LCT and LFFF)

- Observed twist and writhe have **opposite** signs. Invariant w/solar cycle (Rust & Kumar 1996, Pevtsov et al. 2001)
- **Writhe trends:** **N** (+ =r.h.) in north; **S** (− =l.h.) in south
- **Twist trends:** l.h. in north; r.h. in south
- Twist on smaller scale than writhe
- *What sign of helicity is injected in a given hemisphere?* BOTH

- Further subtlety: $H\alpha$ filaments exhibit “dextral” (r.h.) twist in North and “sinistral” (l.h.) in south (Martin & McAllister 1994+)
- But** r.h. $H\alpha$ filaments are supported by l.h. fields (Rust 1999)

Case 4: MDHD α^2 dynamo (dynamical magnetic relaxation)

(Blackman & Field 03, Blackman 05)

Equations for Driven Two-Scale Helical Dynamo

$$\partial_t H_1^M = \frac{2k_1\tau}{3} (k_2^2 H_2^M - H_2^V) H_1^M - 2\beta k_1^2 H_1^M - 2\nu_M k_1^2 H_1^M$$

$$\partial_t H_2^M = -\frac{2k_1\tau}{3} (k_2^2 H_2^M - H_2^V) H_1^M + 2\beta k_1^2 H_1^M - 2\nu_M k_2^2 H_2^M$$

$$\partial_t H_2^V = 0$$

Equations for Driven Unihelical Magnetic Relaxation

$$\partial_t H_1^M = \frac{2k_1\tau}{3} (k_2^2 H_2^M - H_2^V) H_1^M - 2\beta k_1^2 H_1^M - 2\nu_M k_1^2 H_1^M$$

$$\partial_t H_2^M = 0$$

$$\partial_t H_2^V \simeq \frac{2k_1\tau}{3} k_2^2 (k_2^2 H_2^M - H_2^V) H_1^M - 2\beta k_2^2 k_1^2 H_1^M - 2\nu k_2^2 H_2^V$$

- Unihelical relaxation drives injected magnetic helicity to large scales

Driven Unihelical Relaxation (Blackman Field 03, Blackman 05)

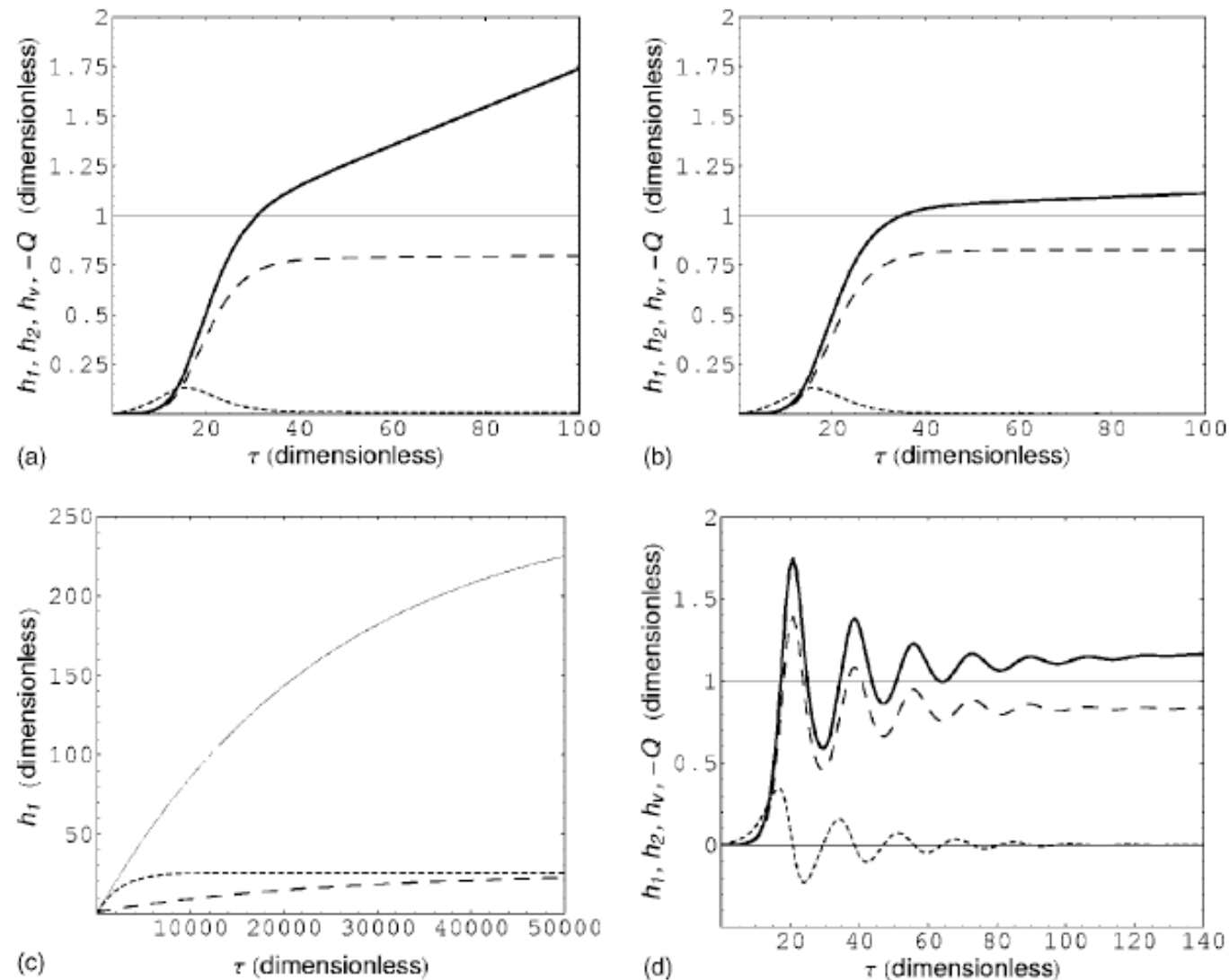
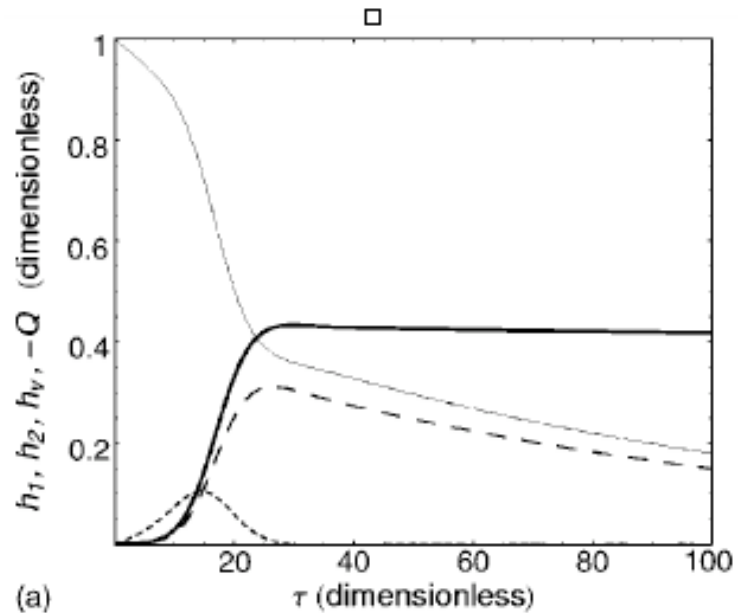
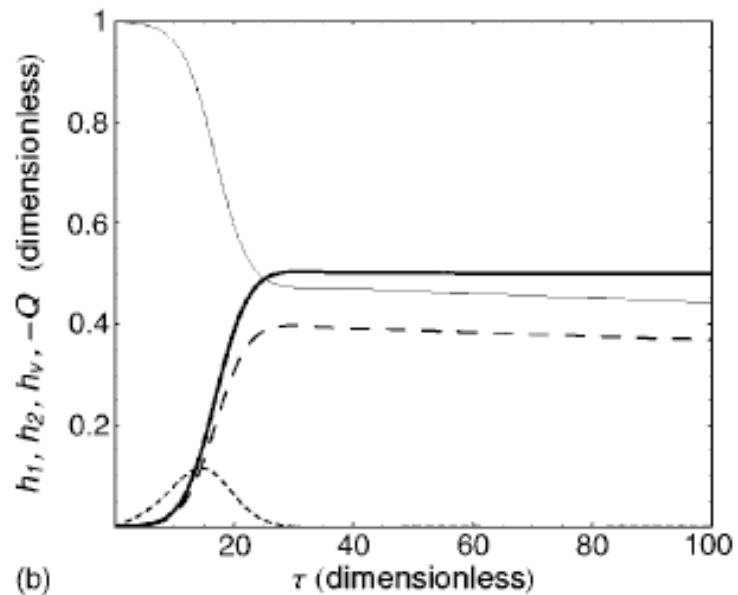


FIG. 2. (a) Same as Fig. 1(a), but case C2: fixed $h_2=1$. (b) Same as Fig. 1(b), but case C2: fixed $h_2=1$. (c) h_1 in case C2 for late times: solid curve is for $R_M=2000, R_V=200$; short dashed curve is for $R_M=R_V=200$; long dashed curve is for $R_M=R_V=2000$. (d) Same as (b), but with $f=1/10$. Notice that $-Q$ now oscillates about 0. The curves in (a) and (b) are identified as follows: At late times (not shown) the oscillations damp, and the solutions are indistinguishable from the $f=1$ case.

Free Unihelical Relaxation

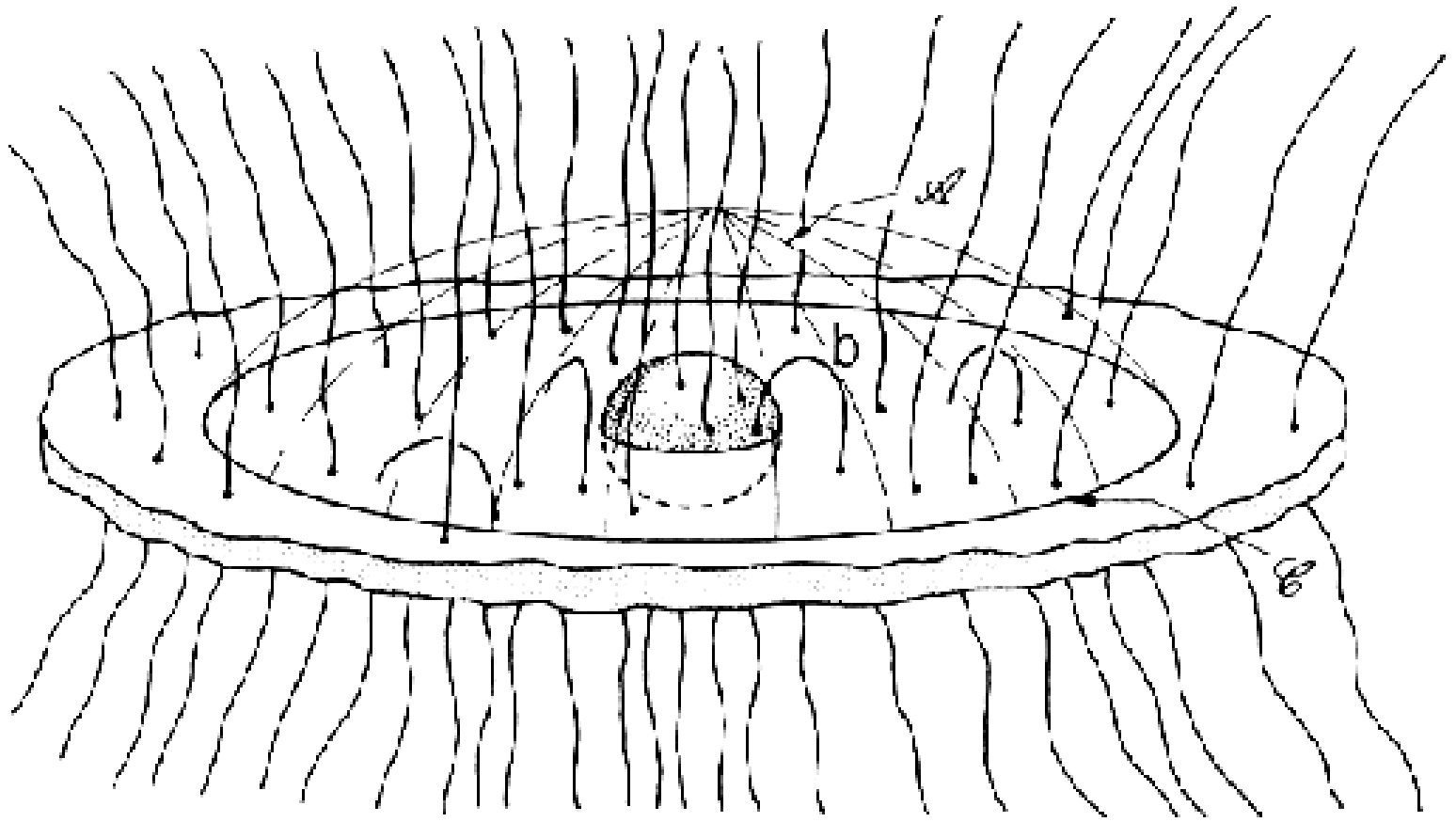


(a)



(b)

FIG. 1. Solutions for $k_1=1$, $f=1$, $k_2=5$, (a) $R_M=R_V=200$, case C1: h_2 free (b) $R_M=R_V=2000$, case C1: h_2 free. The curves in (a) and (b) are identified as follows: h_1 is the thick solid line, h_2 is the thin solid line, h_v is the long dashed line, $-Q$ is the short dashed line.



(Thorne et al. 1986)

Jets: Interior + Exterior Dynamos

- consensus: astrophysical jets are result of magnetically mediated launch at unresolved scales less than $50 R_{\text{engine}}$
- ironically: less consensus on relative strength of magnetic fields on observable scales $> 50 R_{\text{launch}}$
- Suggest at least jet launch is the end state of coupled helical dynamos: FDHD fields from disk escape to corona where they open up to even larger scales via MDHD; analogue to lab plasmas
- “large” scale with respect to disk is “small scale” with respect to corona
- analogue in solar corona: couple interior and exterior dynamos to get global scale fields

Do LSD large R_m dynamos depend on details of reconnection?

- Topology? : not so much
 - Mean field is degenerate with respect to SS topology
 - Mean field topology can change fast: effective R_m of “mean field” in turbulent flow is large
- On getting rid of SS mag energy? very indirectly
 - turbulent cascade takes non-helical mag. energy down to resistive scales quickly preventing “lock up”; structures develop to accommodate forcing rate
 - fast robust LSD requires alleviating the buildup of SS helicity, and fluxes do this faster than local reconnection
 - helicity from interior to exterior can be dissipated by reconnection in corona



Transient Large Scale Dynamos + Poynting Flux

(Blackman et al. 06; Nordhaus et al. 07)

(Context: Supernovae, pre-Planetary Nebulae, GRB..)

E.G. Blackman et al. / New Astronomy 11 (2006) 452–464

461

$$P_m = 0.033; c_p = 0.03; c_t = 0.001; Q = 5.0; \delta/L = 1.00$$

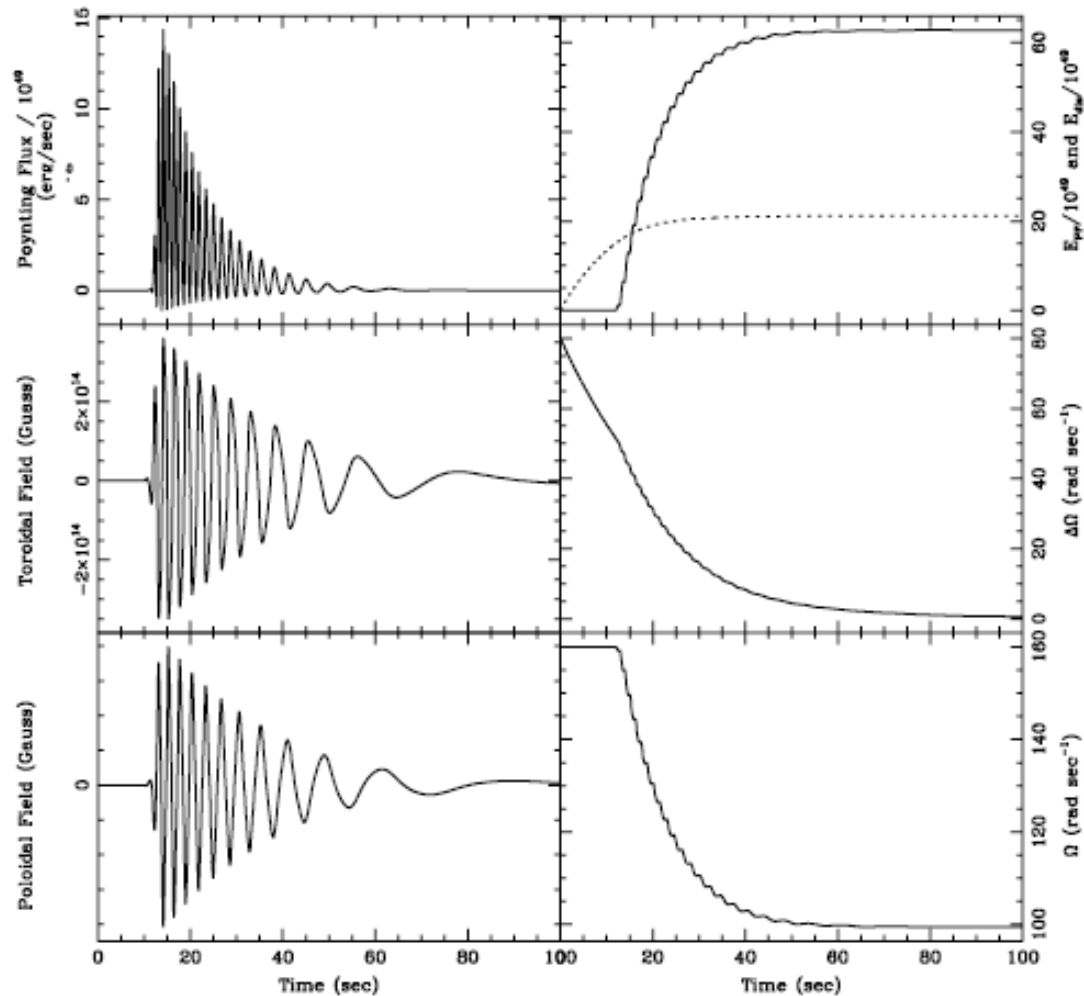


Fig. 4. Similar to Figs. 1 and 2 but with the parameters of row 17 in Table 1. This is an example of a model in which energy due to turbulent dissipation is large at early times after which magnetic energy dominates. In this case, 100% of energy in the rotational layer is available for field growth.