

Role of Cross-Helicity

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Loosely speaking, this is $\underline{u} \cdot \underline{B}$ Local cross-helicity $\frac{\underline{u} \cdot \underline{B}}{|\underline{u}| |\underline{B}|}$ - alignment $\cos \theta$ Total cross-helicity $\int_V \underline{u} \cdot \underline{B} dV$

$$\frac{\int_V \underline{u} \cdot \underline{B} dV}{\left(\int_V u^2 dV\right)^{1/2} \left(\int_V B^2 dV\right)^{1/2}}$$

Debatably a misnomer! (Due to D. Montgomery?)

Moffatt (1969) - physical interpretation gives sense to name.

Related to use of Elsasser variables

$$\underline{\Lambda}_+ = \frac{\underline{u} + \underline{B}}{\sqrt{\mu_0 \rho}}, \quad \underline{\Lambda}_- = \frac{\underline{u} - \underline{B}}{\sqrt{\mu_0 \rho}}$$

$$\underline{u} \cdot \underline{B} = \frac{1}{4} \sqrt{\mu_0 \rho} (\Lambda_+^2 - \Lambda_-^2)$$

Equations (Alfvénic units)

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$$\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} = -\nabla p + \underline{j} \times \underline{B} + \underline{F} + \nu \nabla^2 \underline{u} \quad (1)$$

$$\frac{\partial \underline{B}}{\partial t} = \nabla \times (\underline{u} \times \underline{B}) + \eta \nabla^2 \underline{B} \quad (2)$$

$$\nabla \cdot \underline{u} = 0, \quad \nabla \cdot \underline{B} = 0 \quad (3)$$

or

$$\frac{\partial \underline{\Lambda}_+}{\partial t} = -\underline{\Lambda}_- \cdot \nabla \underline{\Lambda}_+ - \nabla(p + \frac{1}{2} B^2) + \underline{F} + \frac{1}{2}(\nu + \eta) \nabla^2 \underline{\Lambda}_+ + \frac{1}{2}(\nu - \eta) \nabla^2 \underline{\Lambda}_-$$

$$\frac{\partial \underline{\Lambda}_-}{\partial t} = -\underline{\Lambda}_+ \cdot \nabla \underline{\Lambda}_- - \nabla(p + \frac{1}{2} B^2) + \underline{F} + \frac{1}{2}(\nu - \eta) \nabla^2 \underline{\Lambda}_+ + \frac{1}{2}(\nu + \eta) \nabla^2 \underline{\Lambda}_-$$

$$\nabla \cdot \underline{\Lambda}_+ = 0, \quad \nabla \cdot \underline{\Lambda}_- = 0.$$

(note simplification if $\nu = \eta$; odd!)
 $\underline{B} \cdot (1) + \underline{u} \cdot (2), \int dV \Rightarrow \int \underline{u} \cdot \underline{B} dV$
 conserved in ideal ($\nu = \eta = 0$) unforced ($\underline{F} = 0$) case (Woltjer 1958; HKM 1969)

 $\Rightarrow (\underline{F} \propto \nu)$ cross-helicity evolves on diffusive timescale.

Archontis Dynamo

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Archontis, 1999; Cameron + DJG 2006; Archontis, Dorci & Nordlund 2007)

2 π -periodic cube, not scale separated

$$\underline{F} = \nu (\sin z, \sin x, \sin y)$$

[ABC without cosines]

motivation: $\underline{u} = (\sin z, \sin x, \sin y)$ gives (probably) fast kinematic dynamo.

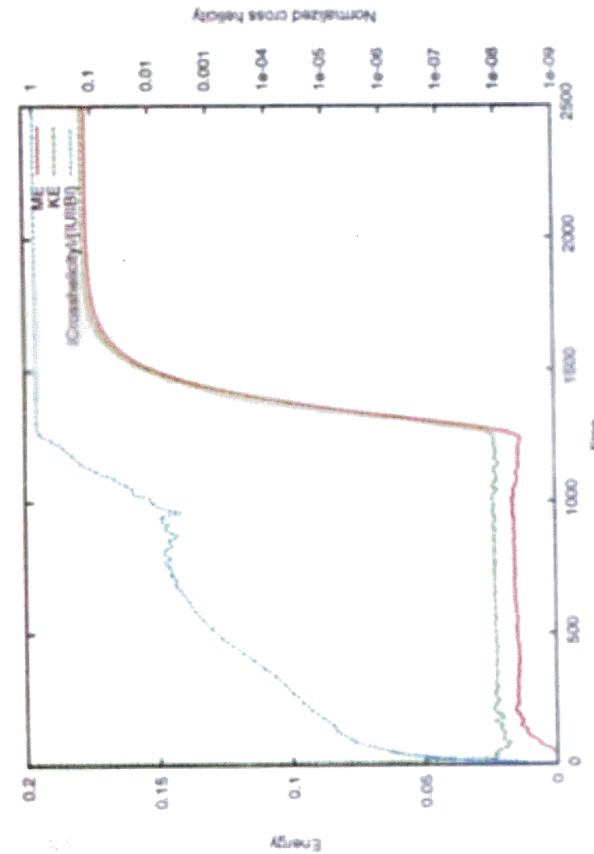
N.B. without cosines, this \underline{u} does not solve Navier-Stokes with $\underline{F} = \nu \nabla \times \underline{u}$.

Amazing fact: at high R_m & R_e , adding a seed \underline{B} gives steady dynamo solution with $\underline{u} = \underline{B} + O(\nu)$ [take $\nu = \eta$]

$$= \frac{1}{2} (\sin z, \sin x, \sin y) + \text{small terms which don't tend to zero as } \nu \rightarrow 0$$

[by symmetry, can also have $\underline{u} = -\underline{B} + O(\nu)$]

Result discovered numerically; little analytic progress since)



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Figure 19. Evolution of kinetic and magnetic energies, as well as the cross-helicity, as a function of time. The cross-helicity is shown using the logarithmic scale of the right-hand side of the graph whereas the energies use the linear scale on the left-hand side. The cross-helicity is normalized by $\sqrt{(KE)(ME)}/(8\pi^3)$; the simulation was started with a weak seed magnetic field.

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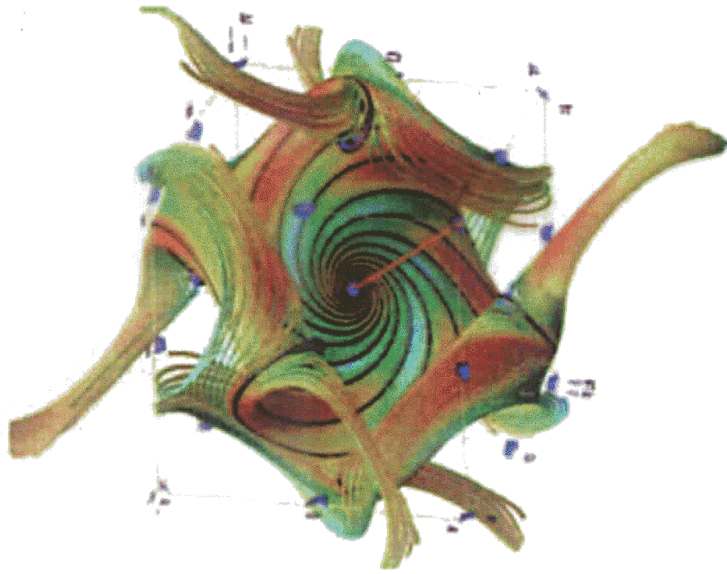


Figure 17. The structure of the 2D manifold, colour coded by Λ -plane. The relationship between the spiral arms and the heteroclinic orbits is apparent.

Other examples found, eg for $\frac{\nu}{\eta} = 4$, $\frac{\nu}{\eta} = \frac{1}{4}$; also modified $\textcircled{6}$
 ABC force $\underline{F} = (\sin z + \epsilon \cos y, \sin x + \epsilon \cos z, \sin y + \epsilon \cos x)$
 $0 \leq \epsilon \leq 1$

Lots of these seem to be stable (ie attracting)

"Most" $Re = \infty$ Euler flows are unstable - we're used to having to live with turbulence.

All $\underline{u} = \pm \underline{B}$ ideal unforced MHD solutions are neutrally stable (Friedlander and Vishik 1995)

\Rightarrow as $\nu \rightarrow 0$ and $\eta \rightarrow 0$, maybe 50% of Alfvénic solutions are stable?

Perhaps the MHD universe is less turbulent than we think, if Elsasser states are attracting!