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# Dynamic Alignment in Driven MHD Turbulence

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# Energy Transfer

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$$\partial_t \mathbf{z}^\pm \mp \mathbf{V}_A \cdot \nabla \mathbf{z}^\pm + \mathbf{z}^\mp \cdot \nabla \mathbf{z}^\pm = -\nabla P, \quad \mathbf{z}^\pm = \mathbf{v} \pm \mathbf{b}$$

- Iroshnikov (1964) Kraichnan (1965)

**Isotropic. Weak interactions**  $\tau_l \sim l V_A / \delta v_l^2$ .  $E(k) \propto k^{-3/2}$ .

- Goldreich & Sridhar (1995)

**Anisotropic. Critical balance**  $l_{\parallel}/l_{\perp} \sim V_A / \delta v_{\perp}$ .  $E(k_{\perp}) \propto k_{\perp}^{-5/3}$ .

[Muller & Biskamp (2000); Haugen, Brandenburg & Dobler (2004); Cho & Vishniac (2000); Cho, Lazarian & Vishniac (2002)] [Maron & Goldreich (2001); Muller et al. (2003)]

- Dynamic Alignment (Boldyrev 2005; 2006):

**Magnetic field and velocity fluctuations align within a scale dependent angle  $\theta_\lambda$**   
**3-d anisotropic and**  $E(k_{\perp}) \propto k_{\perp}^{-3/2}$

[Maron & Goldreich (2001); Muller, Biskamp & Grappin (2003); Muller & Grappin (2005); Mason, Cattaneo & Boldyrev (2006); Mason, Cattaneo & Boldyrev (2008)]

# Theory of Polarization Alignment

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## Decaying MHD turbulence

- Evolves towards the perfectly aligned configuration  $\mathbf{b} = \pm \mathbf{v}$

[Dobrowolny et al. (1980); Grappin et al. (1982); Pouquet et al. (1986)]

## Driven MHD turbulence

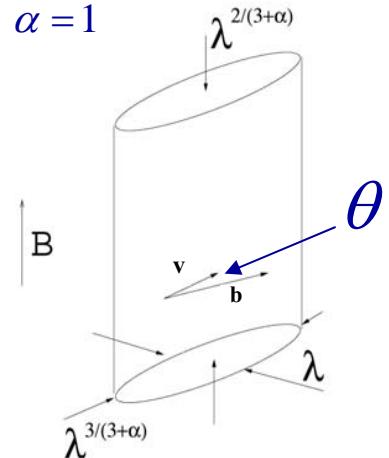
- Energy cascade must be maintained by the nonlinear terms
- Magnetic field and velocity fluctuations align within a scale dependent angle  $\theta_\lambda$
- If  $\theta_\lambda \propto \lambda^{\alpha/(3+\alpha)}$  then constant energy flux implies

$$E(k_\perp) \propto k_\perp^{-(5+\alpha)/(3+\alpha)}$$

- Conservation of cross helicity: minimizing total alignment angle yields  $\alpha = 1$

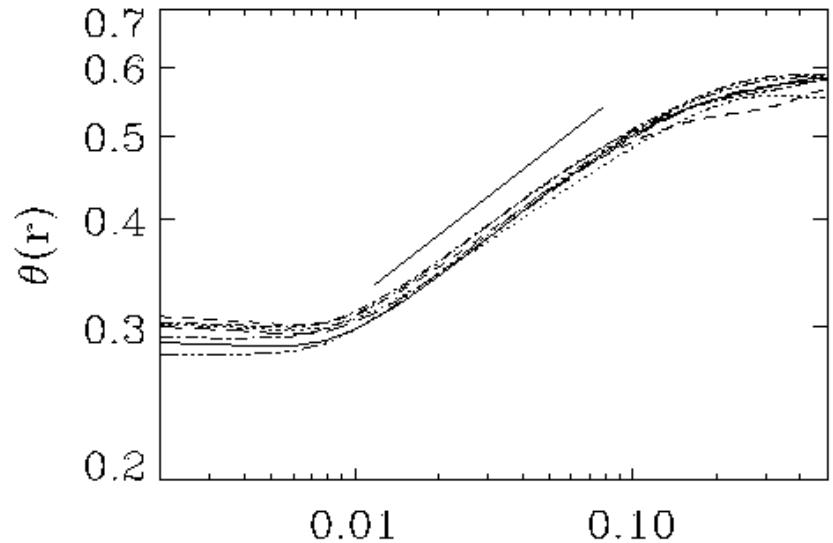
$$\theta_\lambda \sim \lambda^{1/4}, E(k_\perp) \propto k_\perp^{-3/2}$$

- Boldyrev (2005, 2006)



# Measuring Alignment

$$\begin{aligned}\partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} &= -\nabla p + \mathbf{j} \times \mathbf{B} + \nu \nabla^2 \mathbf{u} + \mathbf{f}_u \\ \partial_t \mathbf{B} &= \nabla \times (\mathbf{u} \times \mathbf{B}) + \eta \nabla^2 \mathbf{B} + \mathbf{f}_B \\ \nabla \cdot \mathbf{u} &= 0, \quad \nabla \cdot \mathbf{B} = 0\end{aligned}$$



$$1:1:B_0, 512^3, \quad P_m = \frac{\nu}{\eta} = 1, R_e = \frac{uL}{\nu} \approx 2200 \quad (u_{rms} \approx b_{rms} \approx 1, B_0 = 5)$$

- Cascade mainly in field-perpendicular plane:

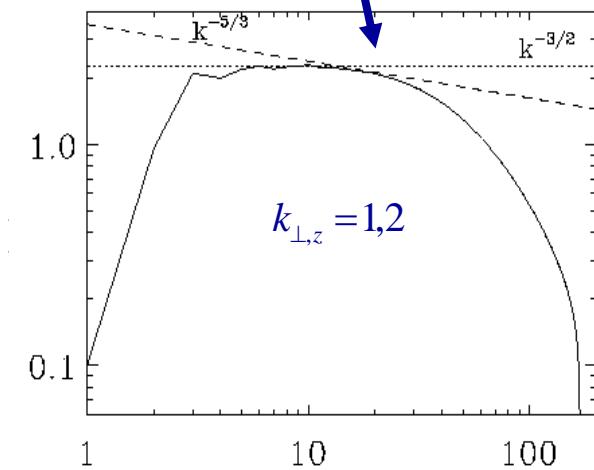
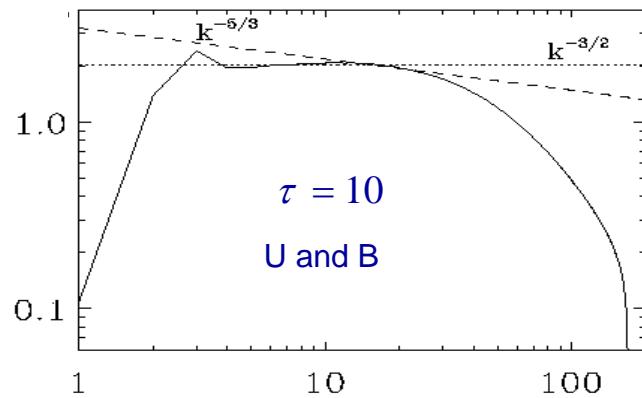
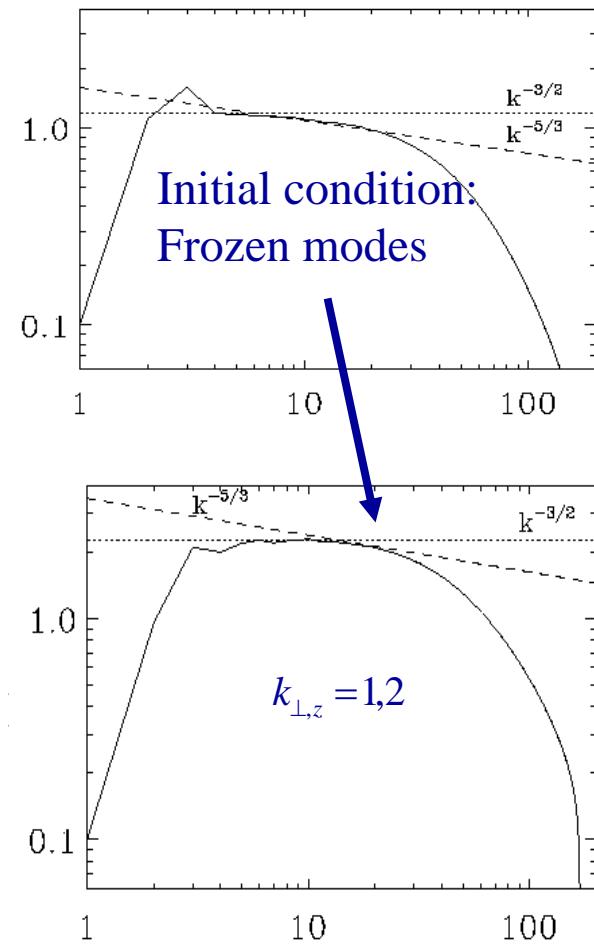
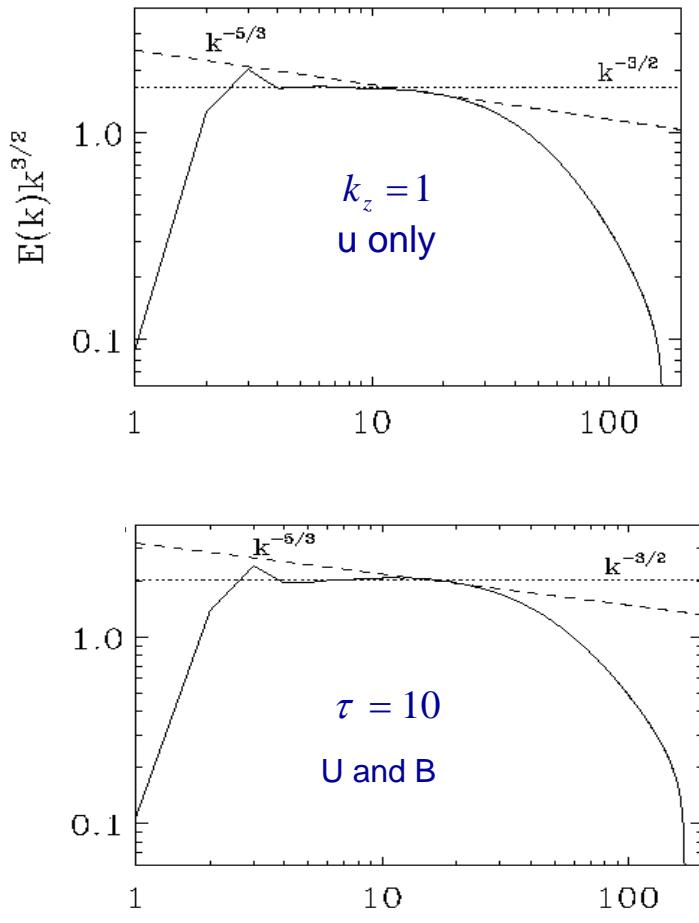
$$\delta \mathbf{v}_\lambda \equiv \mathbf{v}(\mathbf{x} + \lambda) - \mathbf{v}(\mathbf{x}), \quad \delta \tilde{\mathbf{v}}_\lambda = \delta \mathbf{v}_\lambda - (\delta \mathbf{v}_\lambda \cdot \mathbf{n}) \mathbf{n}, \quad \mathbf{n} = \frac{\mathbf{B}(\mathbf{x})}{|\mathbf{B}(\mathbf{x})|}$$

- Measure alignment between rms fluctuations

$$\frac{\left\langle \left| \delta \tilde{\mathbf{v}}_\lambda \times \delta \tilde{\mathbf{b}}_\lambda \right| \right\rangle}{\left\langle \left| \delta \tilde{\mathbf{v}}_\lambda \right| \left| \delta \tilde{\mathbf{b}}_\lambda \right| \right\rangle} \approx \sin(\theta_\lambda) \approx \theta_\lambda \propto \lambda^{1/4}$$

- Mason, Cattaneo & Boldyrev (2006)

# Energy Spectrum



- $k_{\perp} = \sqrt{k_x^2 + k_y^2}$ ,  $E(k_{\perp}) = \langle |\mathbf{v}(k_{\perp})|^2 \rangle k_{\perp} + \langle |\mathbf{b}(k_{\perp})|^2 \rangle k_{\perp}$

- Mason, Cattaneo & Boldyrev (2008); Perez & Boldyrev (2008)

# Kolmogorov's 4/5-law

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- Hydrodynamic turbulence  $\langle \delta v_L^3(\mathbf{r}) \rangle = -\frac{4}{5} \varepsilon r \rightarrow E(k) \propto k^{-5/3}$ ,

where  $\delta v_L(\mathbf{r}) \equiv [\mathbf{v}(\mathbf{x} + \mathbf{r}) - \mathbf{v}(\mathbf{x})] \cdot \mathbf{r}$

- Isotropic MHD turbulence (Politano & Pouquet, 1998)  $\delta \mathbf{z}^\pm = \delta \mathbf{v} \pm \delta \mathbf{b}$

$$\langle \delta z_L^-(\delta \mathbf{z}^+)^2 \rangle = -\frac{4}{3} \varepsilon^+ r \quad \text{and} \quad \langle \delta z_L^+(\delta \mathbf{z}^-)^2 \rangle = -\frac{4}{3} \varepsilon^- r$$

- For a strong guiding field

$$\boxed{\langle \delta z_L^-(\delta \mathbf{z}^+)^2 \rangle = -2 \varepsilon^+ r_\perp \quad \text{and} \quad \langle \delta z_L^+(\delta \mathbf{z}^-)^2 \rangle = -2 \varepsilon^- r_\perp}$$

$\rightsquigarrow$  Consistent with  $E(k_\perp) \propto k_\perp^{-3/2}$  ?

- Check the theory of dynamic alignment

$$\langle \delta z_L^-(\delta \mathbf{z}^+)^2 \rangle = \theta_r \delta v_r^3 \sim r$$

$$\delta z^+ \sim \delta v, \quad \delta z_L^- = \delta z^- \cos(\phi) \approx \delta z^- \approx \delta v \sin(\theta) \approx \delta v \theta,$$

