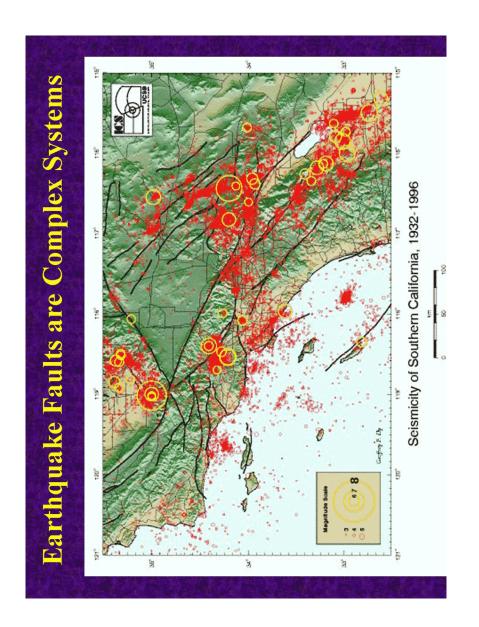
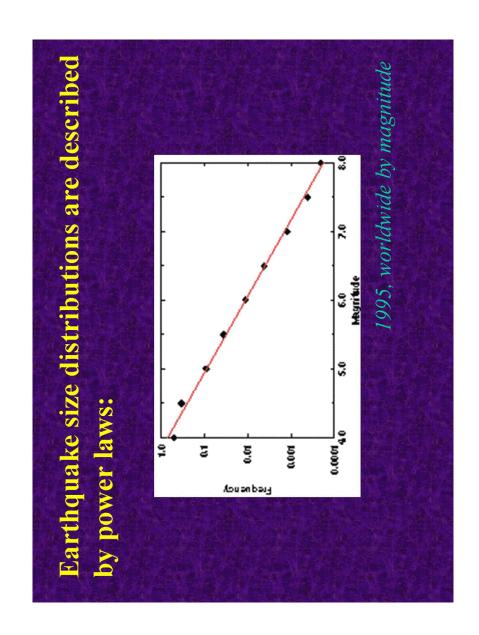
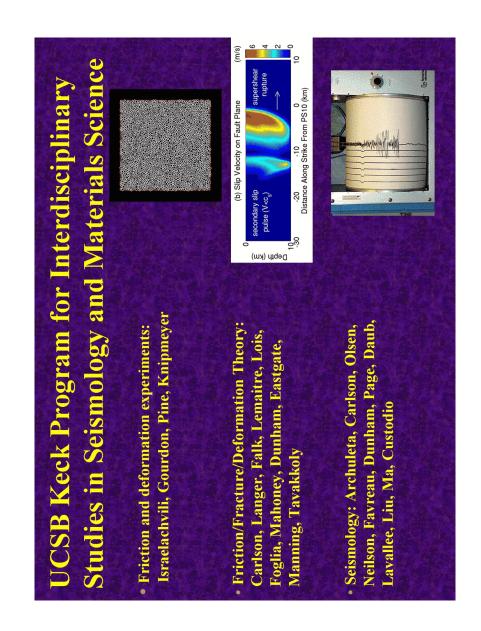
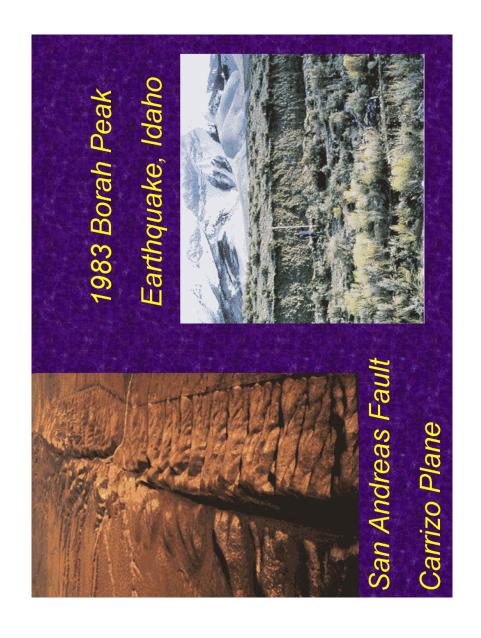


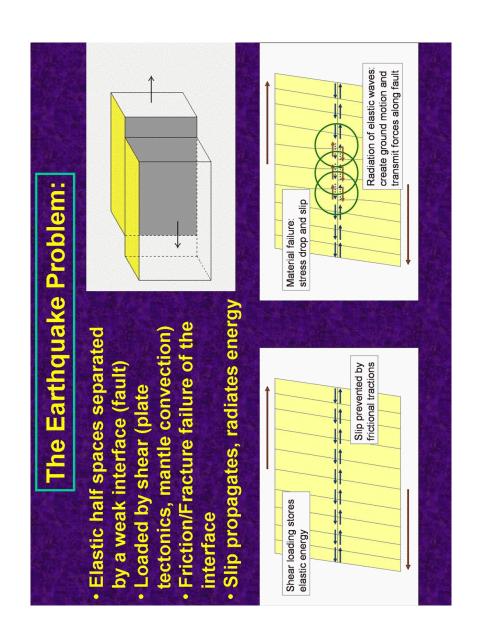
problem is important! But underdetermined parameters have a measurable impact? A better understanding of source physics to provide gorous methods to account for uncertainty Some goals for this KITP program: constraints on what could happen.

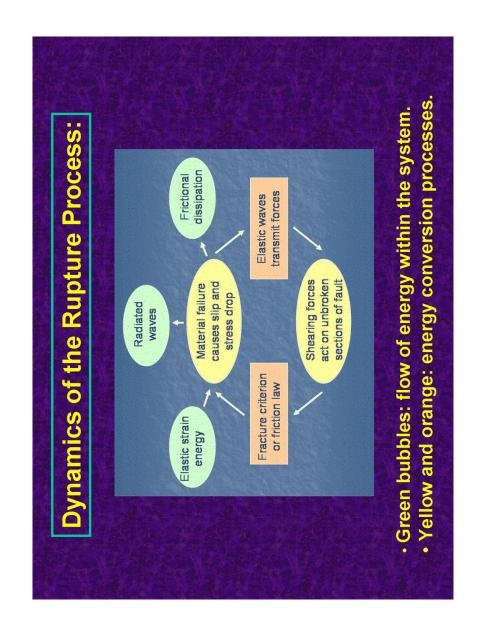


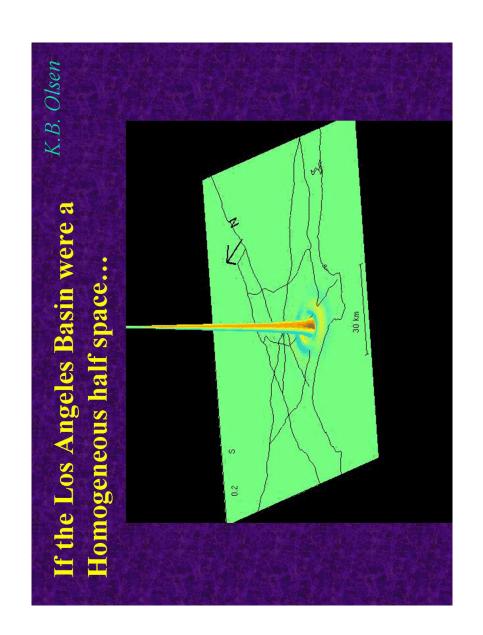


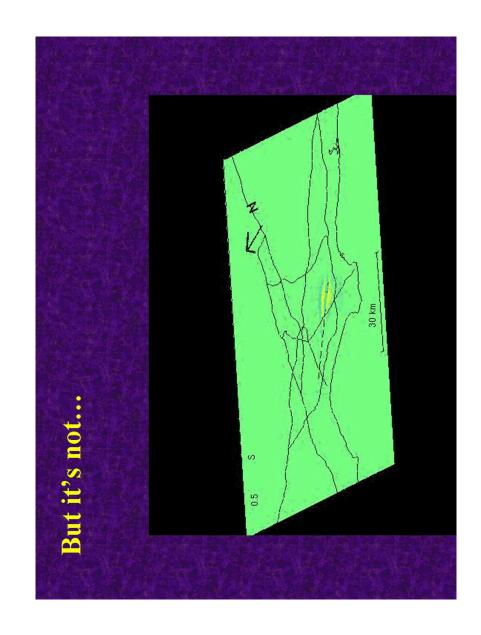


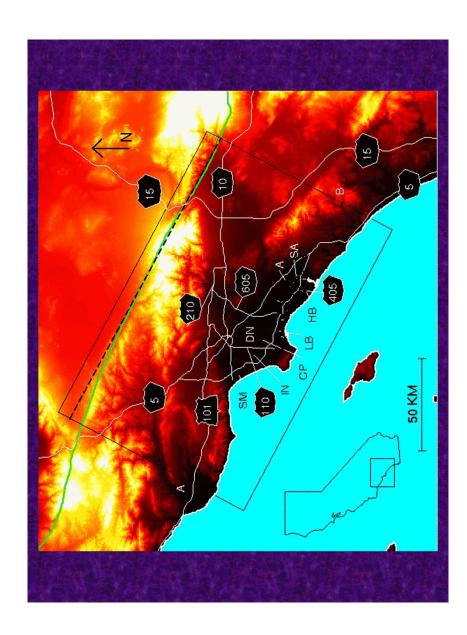


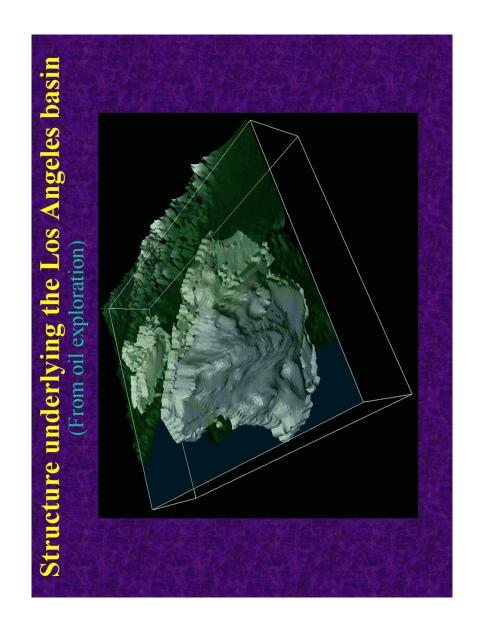


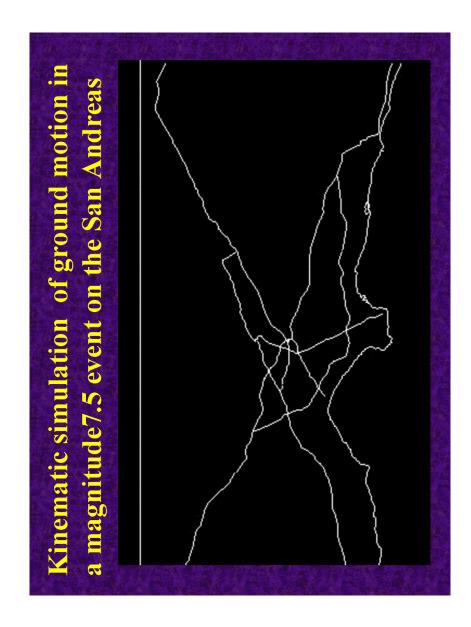


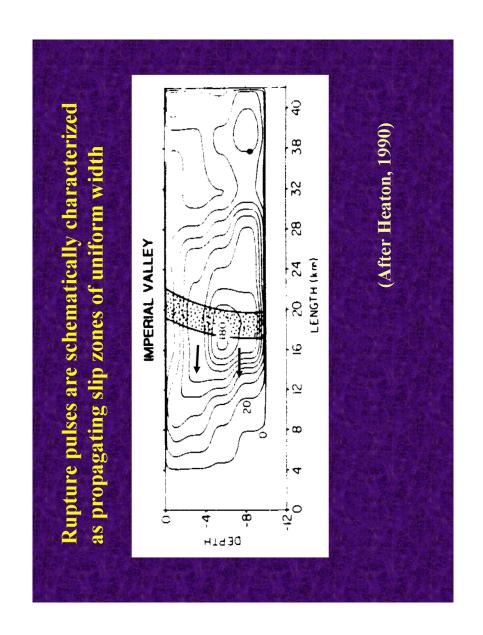


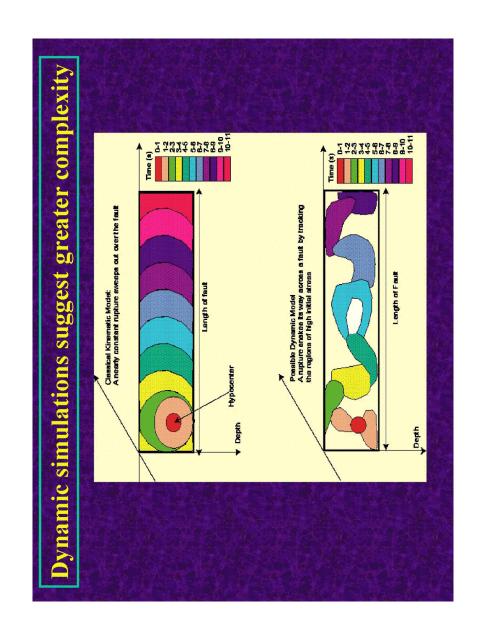


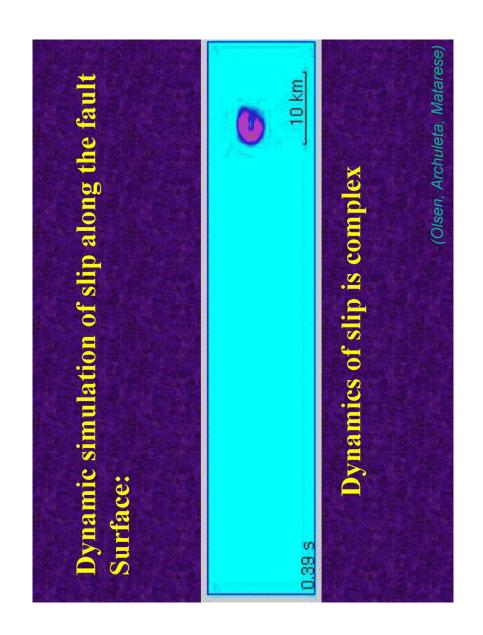


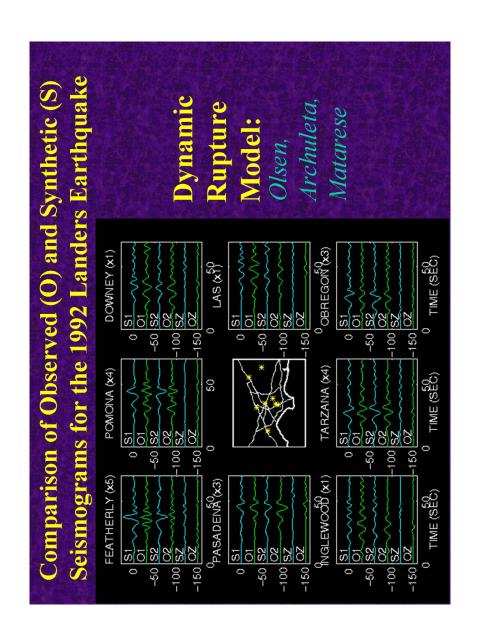




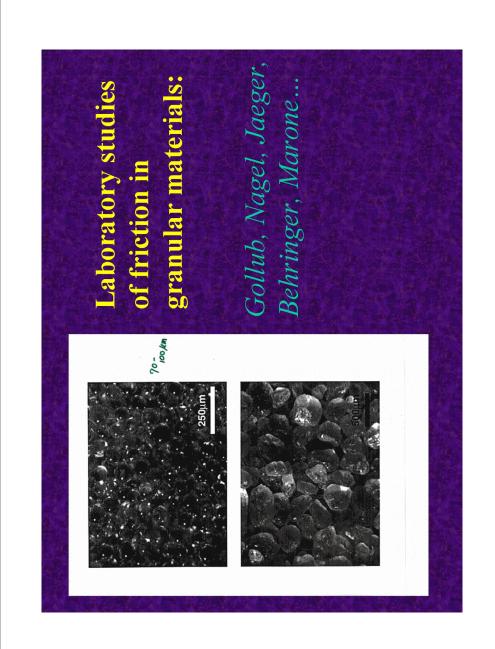


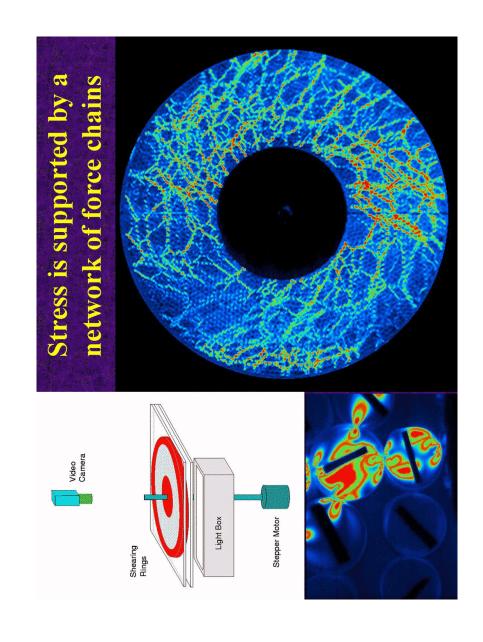


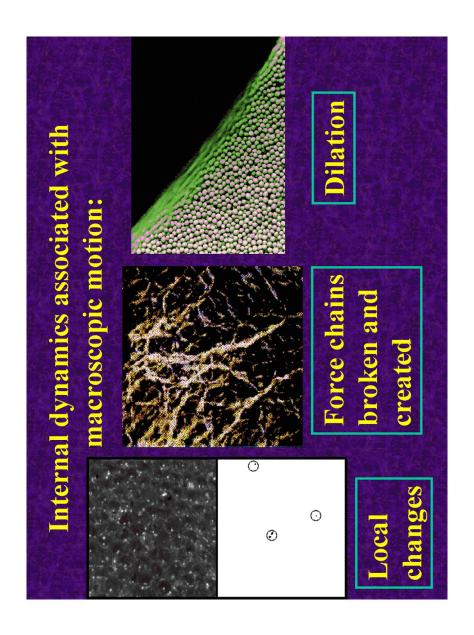


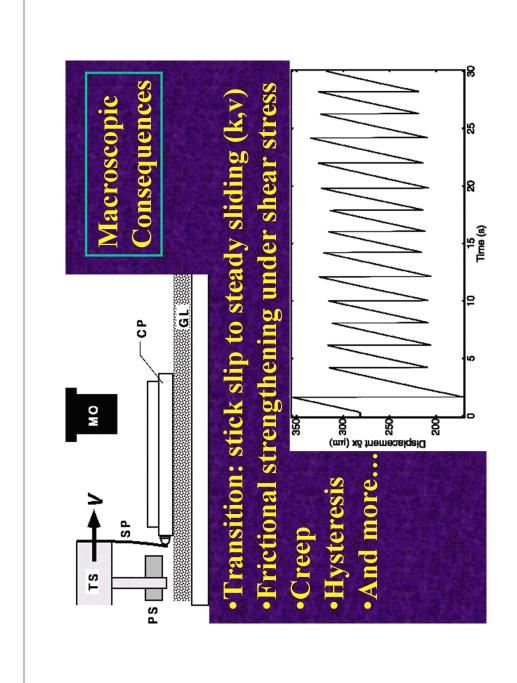


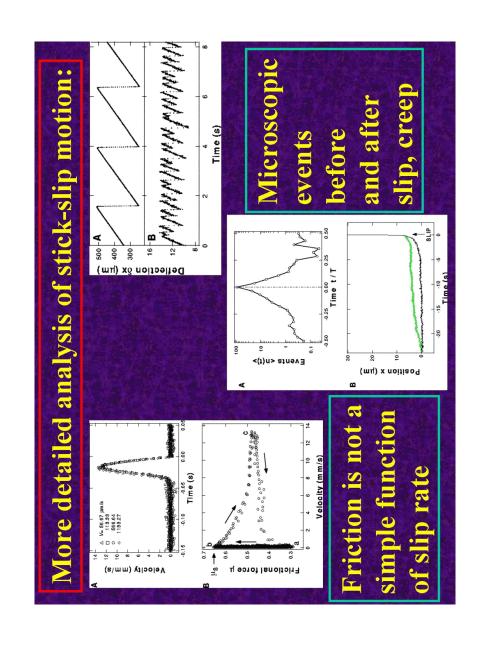


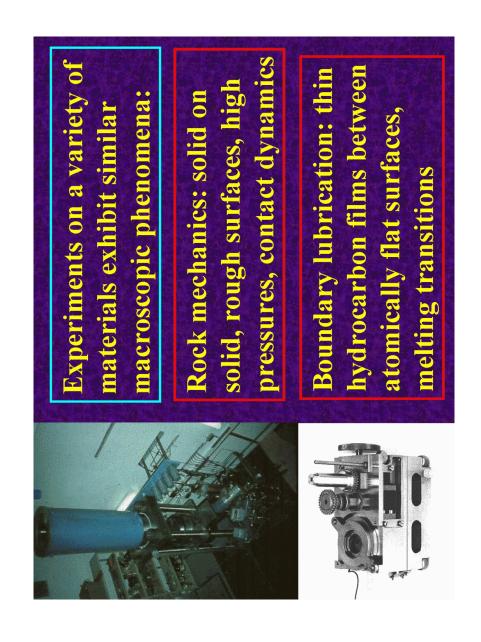


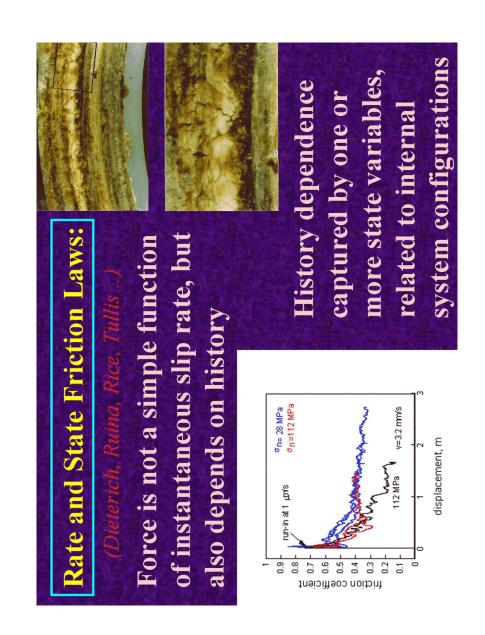




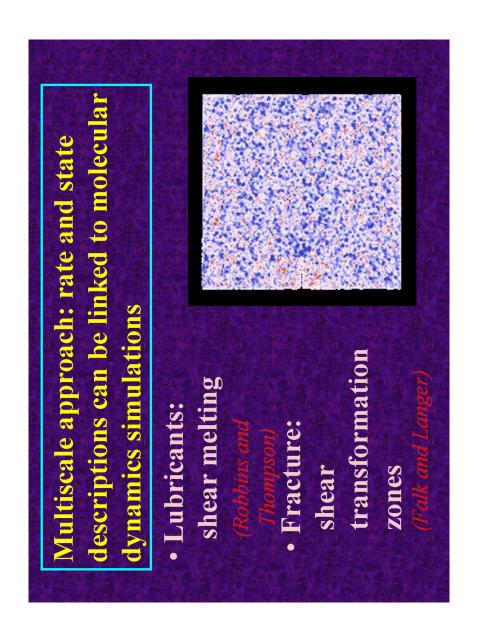


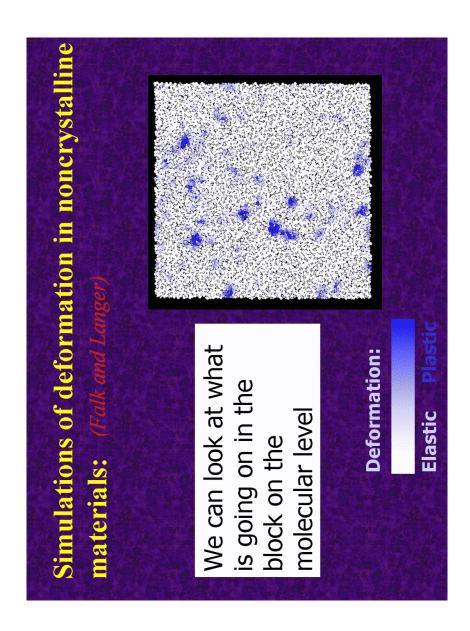


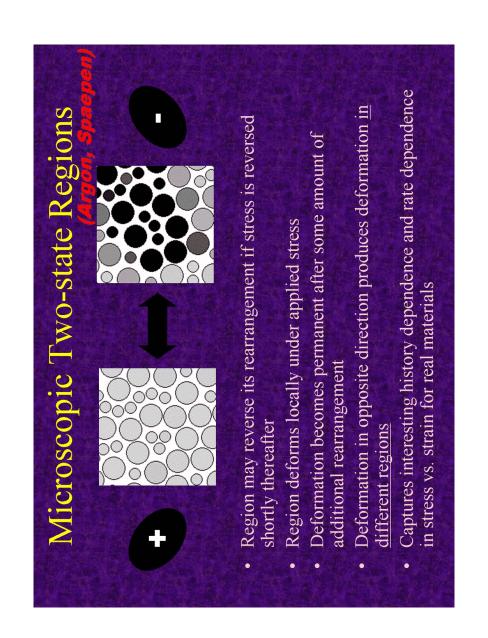


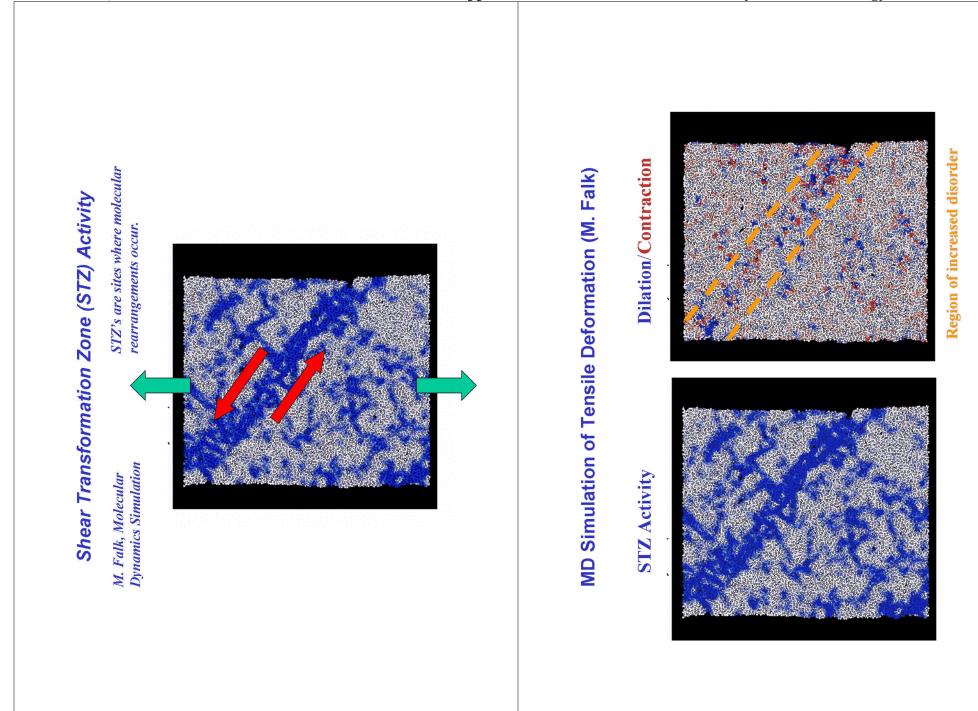


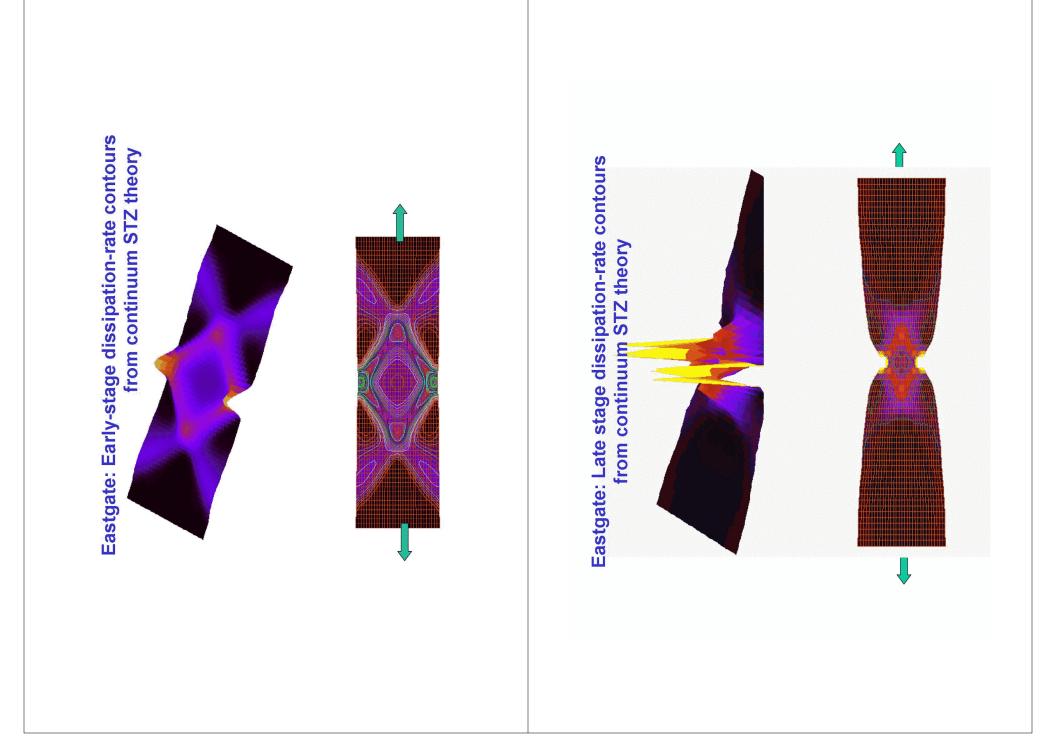








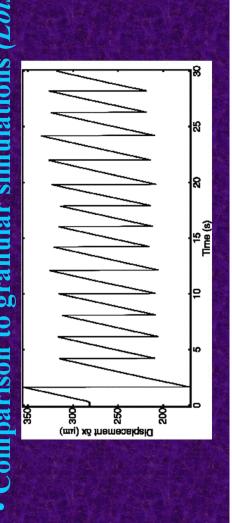




Extension of STZ theory to granular materials

(Lemaitre) Add dilatency, and granular temperature

- Produces stick-slip
- Frictional strengthening under shear stress
 - Comparison to granular simulations (Lois)

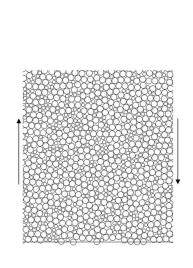


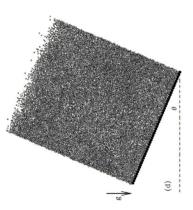
STZ Theory for Granular Materials

$$\dot{\gamma}^{pl}\propto R_-n_--R_+n_+$$
 $\dot{r}_\pm=R_\mp n_\mp-R_\pm n_\pm+w(a-bn_\pm)$ (Falk & Langer 1997) $\dot{\gamma}=\dot{\gamma}^{pl}$ $w=\sigma\dot{\gamma}/p$ $R_\pm\propto\sqrt{T}e^{\pm\kappa\sigma/p}$ Lemaitre (2002)

$$\dot{\gamma} \propto \sqrt{T} \left(\Lambda \sinh(\kappa \sigma/p) - \Delta \cosh(\kappa \sigma/p) \right)$$
$$\dot{\Delta} \propto \dot{\gamma} \left(1 - \Delta \zeta \sigma/p \right)$$
$$\dot{\Lambda} \propto \dot{\gamma} \sigma/p \left(1 - \Lambda \right)$$

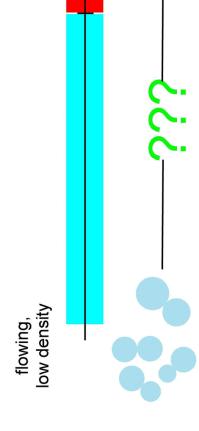
Specialize to Certain Geometries Contact Dynamics Simulations:





- Test microscopic assumptions of (kinetic theory and granular STZ) hydrodynamic equations
- Predictions of macroscopic phenomena

Density Phase Diagram for Granular Shear Flows



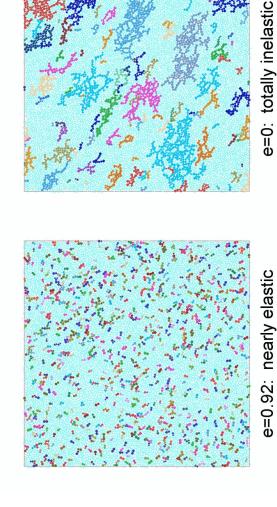
high density

jammed,

Kinetic Theory assumes binary collisions (dissipate energy)

Does Kinetic Theory fail? If so, at what density? STZ Theory assumes non-affine deformations are local, oriented

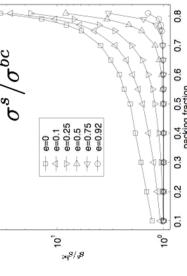
Emergence of Clusters

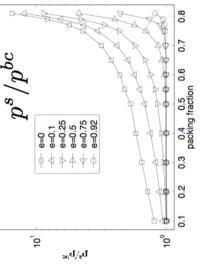


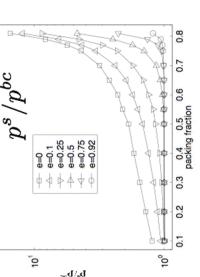
Test of the KT Binary Collision Assumption

The static part of the stress tensor is measured as If only binary collisions occur, then this can be written as

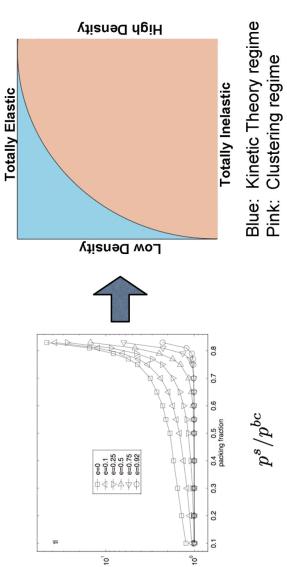
contacts



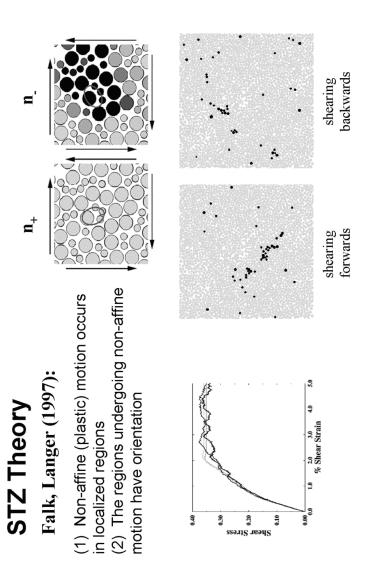




Results of Numerical Test

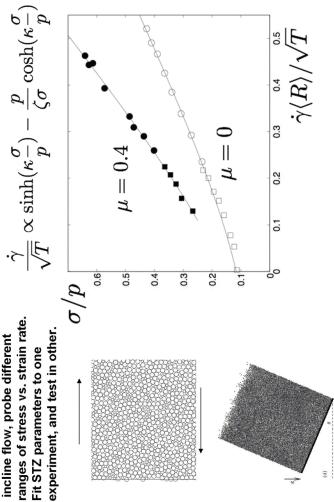


In much of the flowing phase space, kinetic theory fails.

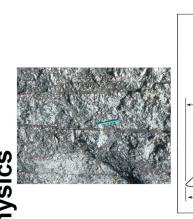


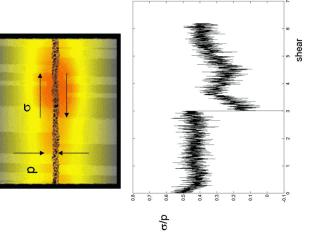
Test of STZ Flowing Steady State

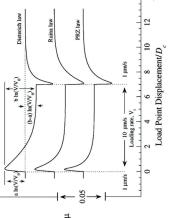
Iwo geometries, shear cell and

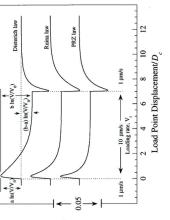


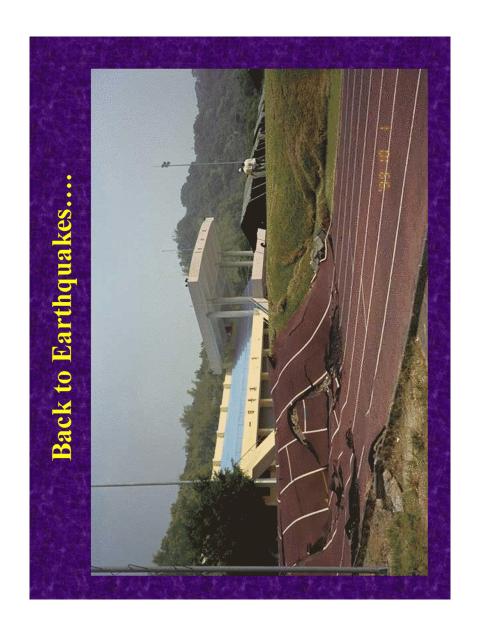
transient dynamics in friction control, materials science, Future directions: geophysics



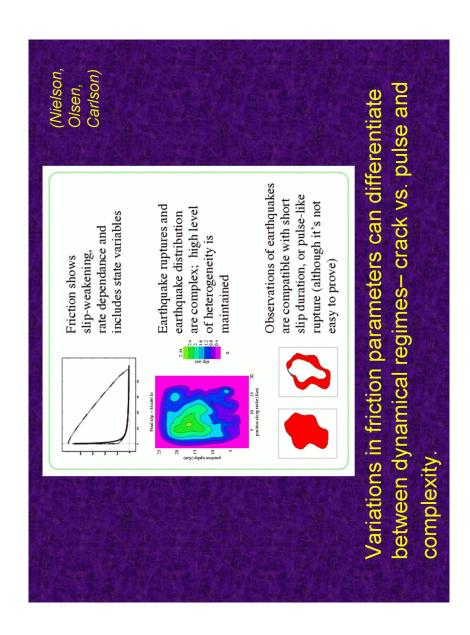








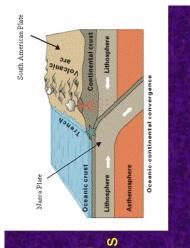


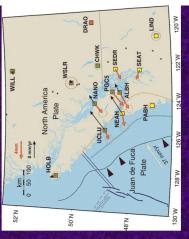


Friction Gradients:

temperature and depth). These regions subduction zones (friction depends on which do not radiate energy (i.e. no appear to exhibit slow earthquakes, Friction gradients are important for trace on seismometers)

- GPS measurements are consistent E with a slow, aseismic slip of ~2 about 40 km downdip from the earth's surface
- Slip velocity ranges from 10-8-10-7m/s (normal events: a few m/s)
 - Slip traveled parallel to the strike of the plate boundary at a speed of ~6km/day (normal: a few km/s)





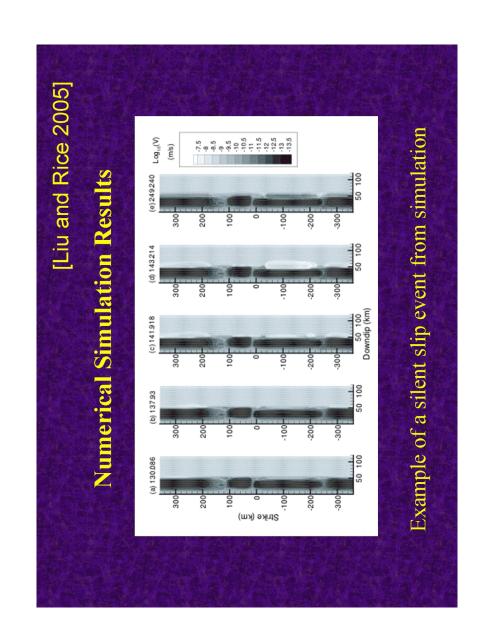
GPS stations and seismic events in Cascadia [Dragert et al. 2001]

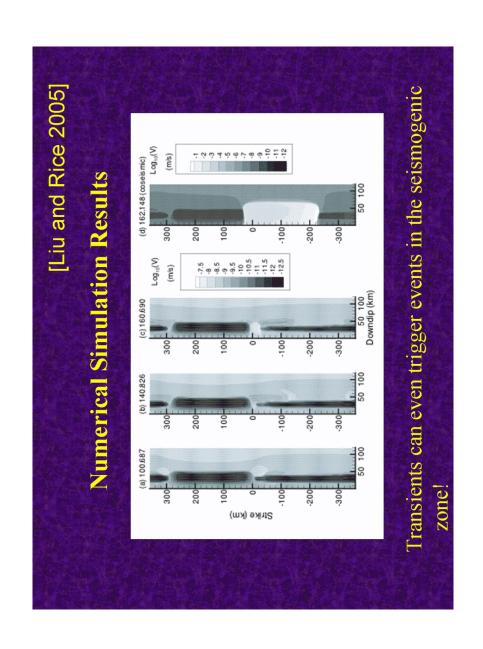
Modeling Subduction Thrusts [Liu and Rice 2005]

- velocities friction changes to rate weakening (which allows slip Normally, at ~40 km depth temperature dictates that friction is rate strengthening, but there is some evidence that at small events)
 - Also, metamorphic fluid release at depth could weaken friction to allow slip

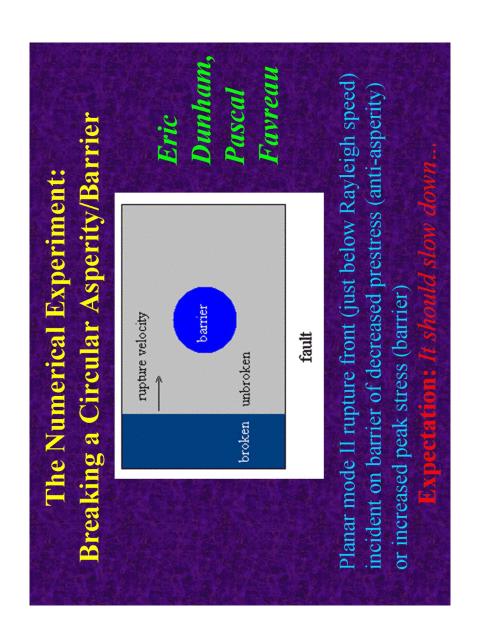
Use depth-dependent (Dieterich-Ruina) rate and state friction to model subduction zone dynamics, matching friction parameters to the geothermal gradient

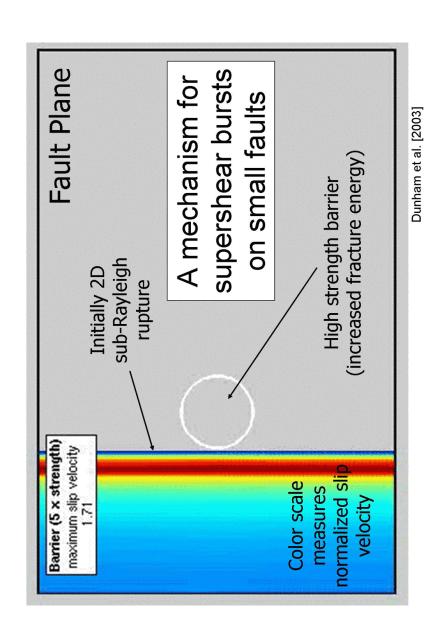
- Rate weakening friction at depths above ~30 km (depth measured
- Rate strengthening friction below ~30 km, with velocity dependence along the plate boundary) growing with depth
 - Below 120 km, steady ductile creep at the long term plate convergence rate is imposed

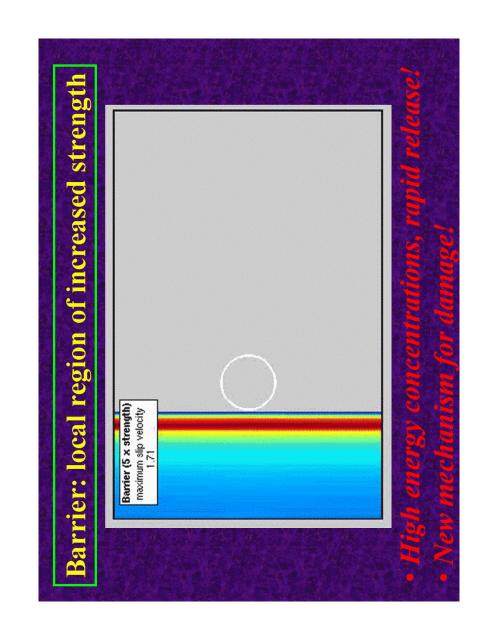


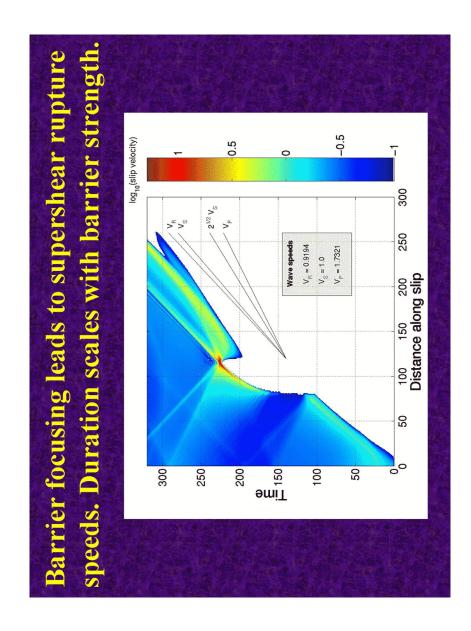




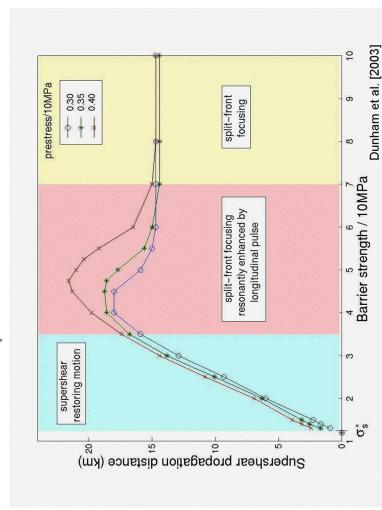


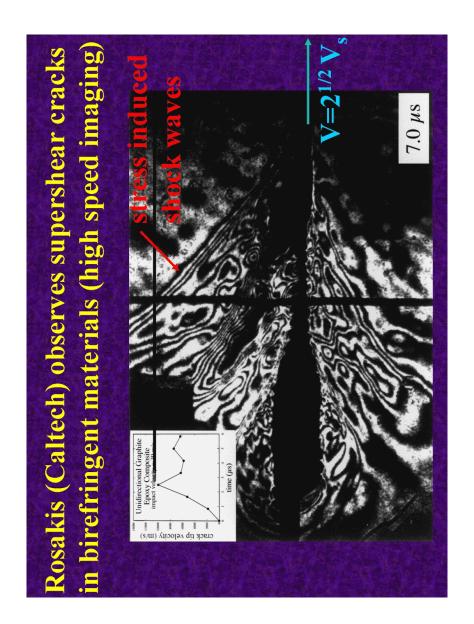


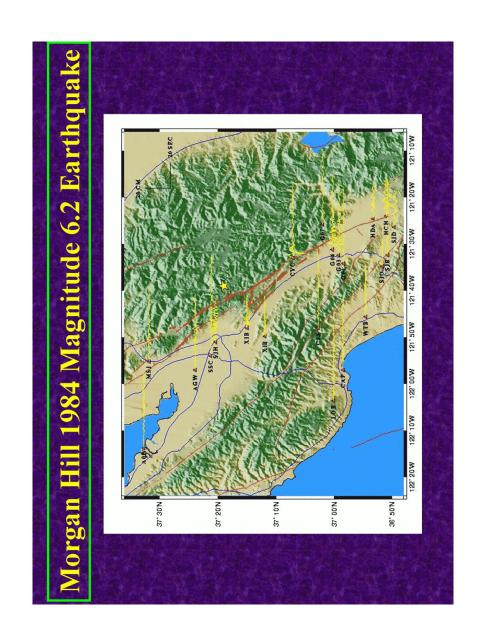


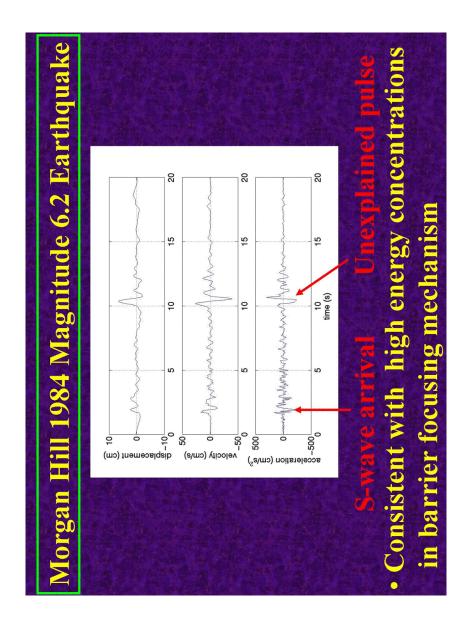












50 km

Susitna Glacier fault

Denali fault

2002 Denali Fault Earthquake

(Dunham and Archuleta)

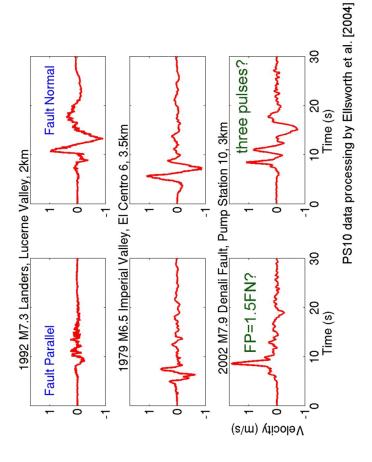
(PS10)

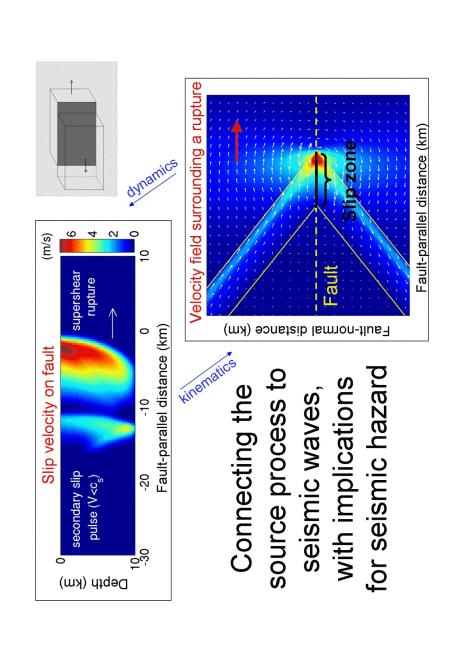
Pump Station 10 3km N of fault

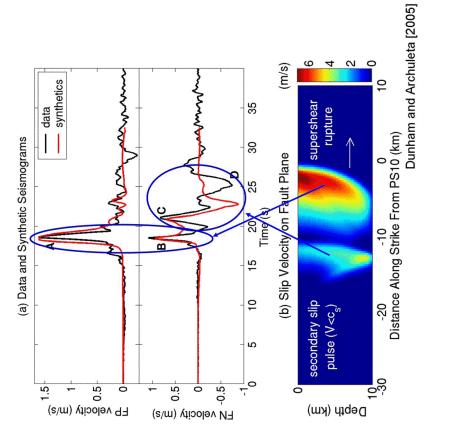


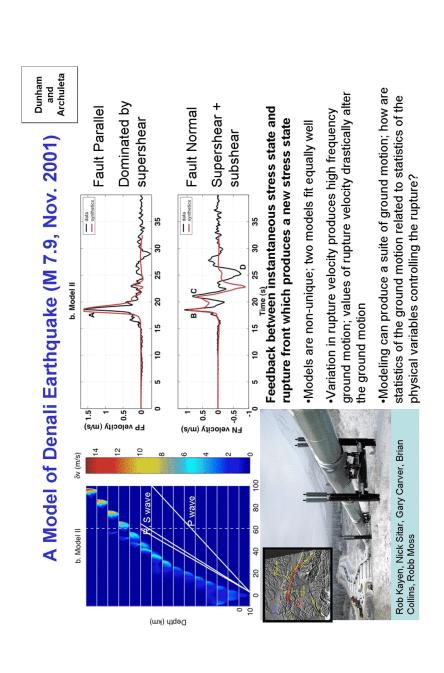
confesy USGS

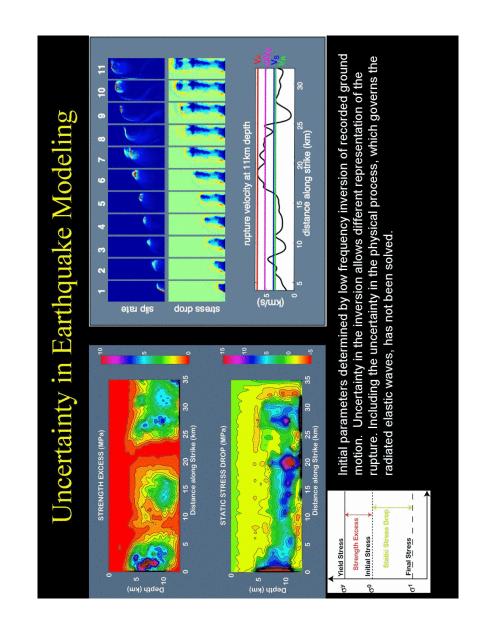
A Puzzle in the Seismograms





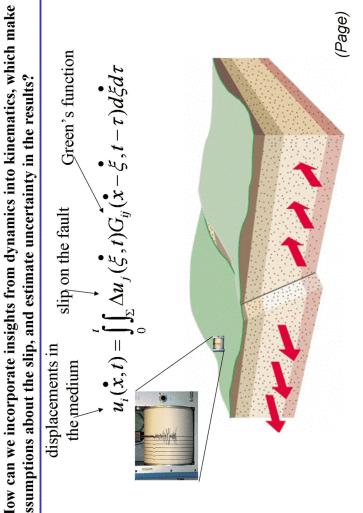


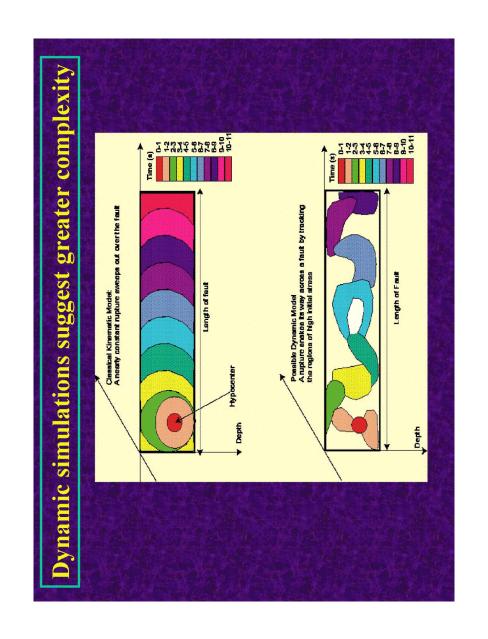


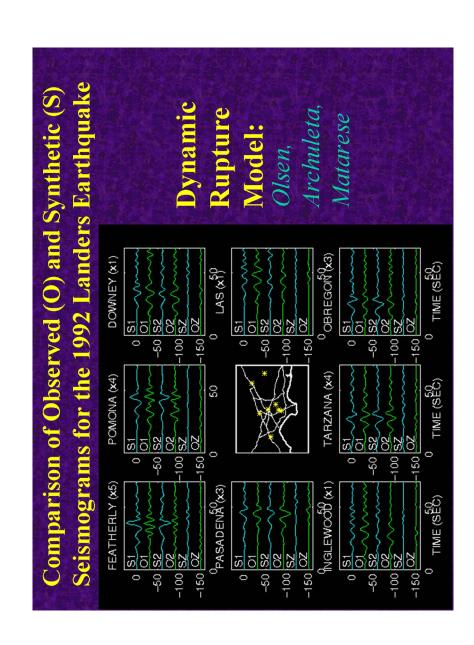


Kinematic Inversions - Background

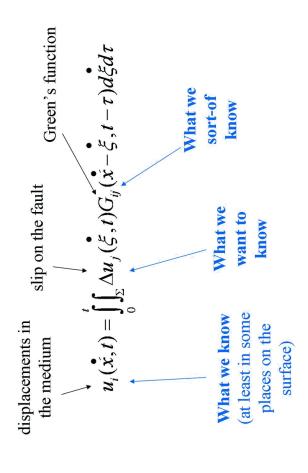
How can we incorporate insights from dynamics into kinematics, which make Fully dynamical inversions of seismograms are not computationally practical. assumptions about the slip, and estimate uncertainty in the results?



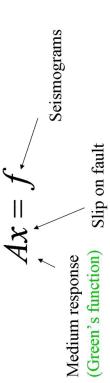




Kinematic Inversions - Background



To find Δu , we discretize the problem:

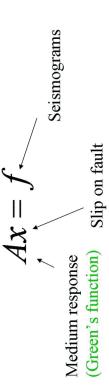


We need to invert A and find x.

Penrose's Generalized Inverse (GI):

which satisfies minimum ||x||. Among all solutions satisfying minimum ||Ax - f||, The generalized inverse of A, \tilde{A} , satisfies $\tilde{x} = \tilde{A}f$. there exists a unique solution \widetilde{x}

 \widetilde{x} is the least-squares solution.



We can find \tilde{A} with the Singular Value Decomposition:

 $=UAV^T$, where U and V are orthogonal and A is diagonal with elements λ_h

$$\tilde{A} = VA^{-1}U^{T}$$
 where $(\Lambda^{-1})_{ii} = \begin{cases} \lambda_{ii}^{-1} \text{ for } \lambda_{ii} > 0 \\ 0 \text{ for } \lambda_{ii} = 0 \end{cases}$

 $R = \widetilde{A}A$ is the resolution matrix.

Recall that our solution $\widetilde{x} = \widetilde{A}f = \widetilde{A}(Ax) = (\widetilde{A}A)x$

SQUARES OFFSET STATIC LEAST

7 4 .

SLIP

DYNAMIC

· \ \ / - /

1171

Imperial Valley Earthquake Least Squares Fit for

Olson and Apsel, 1982

- Solution very unstable
- Backslips common
- Large variations in rake, even between neighboring cells

Adding constraints to inversion to get more physical rupture

Extend notion of GI to include inequality constraints:

Among all solutions satisfying Gx > h and minimum ||Ax - f||, there exists a unique solution \widetilde{x}_c which satisfies minimum ||x||. The constrained generalized inverse of A, \tilde{A}_{c} $=A_c f$ satisfies \widetilde{x}_c

Possible constraints:

No backslip, constant rupture velocity, total moment

weight a strict constraint (tradeoff between constraint and Alternative method of Hartzell and Heaton (1983) misfit)

where Fx=d is a set of linear constraints and λ is a scalar weight.

Constrained Least Squares Olson and Apsel, 1982 Fit for Imperial Valley SQUARES 7 1 ° OFFSET SLIP LEAST - 1 DYNAMIC STATIC CONSTRAINED REDUCED TIME (sec)

Stabilizing the solution

STABILIZED

CONSTRAINED LEAST SQUARES

STATIC OFFSET

DYNAMIC SLIP

ROSE A LEAST SQUARES

STATIC OFFSET

DYNAMIC SLIP

ROSE A LEAST SQUARES

THE LOSE A LEAST SQUARES

THE LOS

the null space component

of A to zero)

they do not participate in

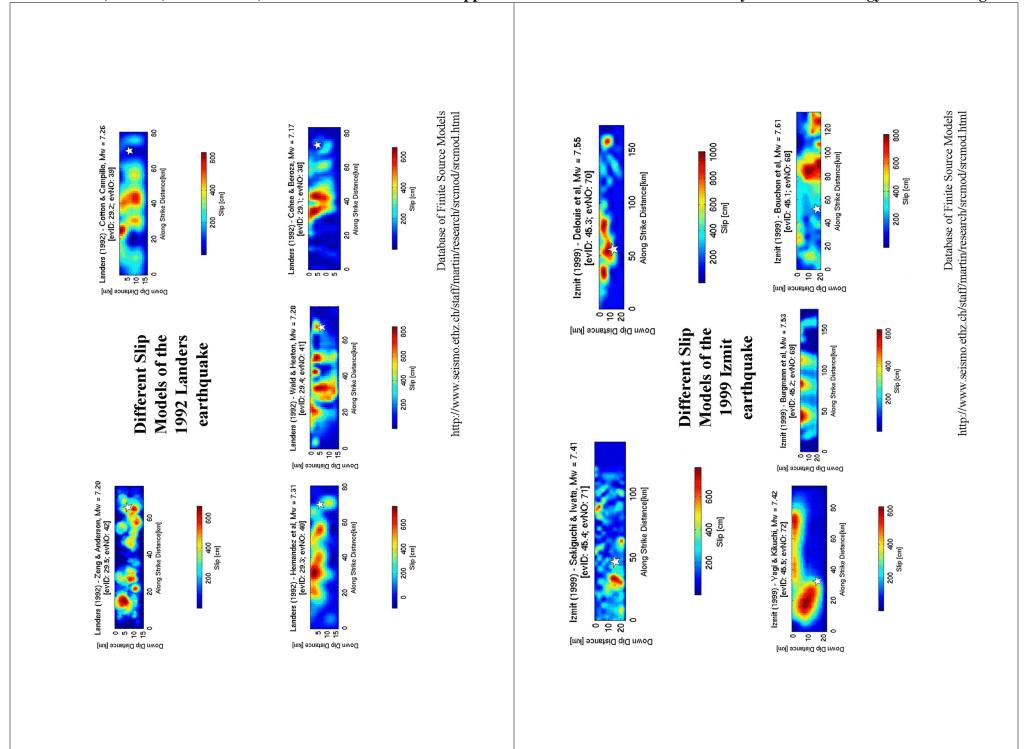
Treat small singular

values as zero

solution (since GI sets

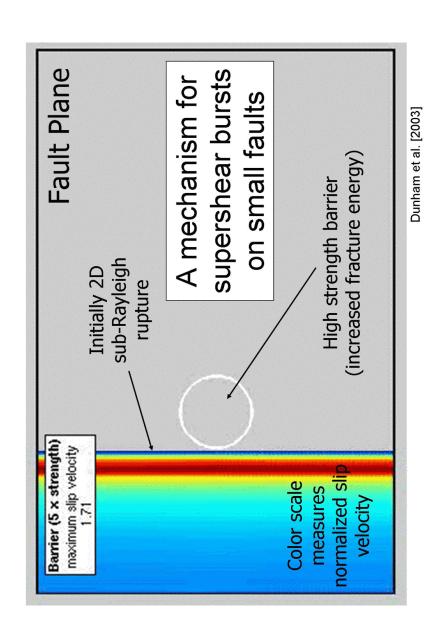
Preferred solution is more physical, but has larger misfit

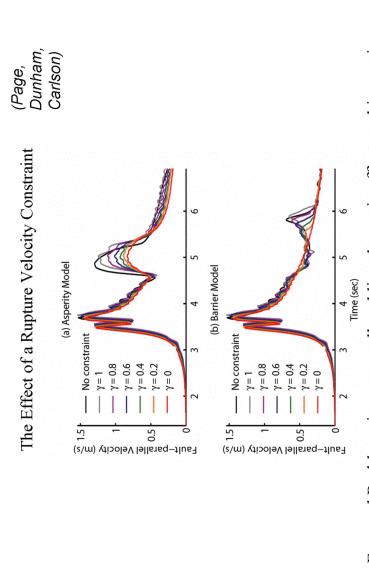
Olson and Apsel, 1982



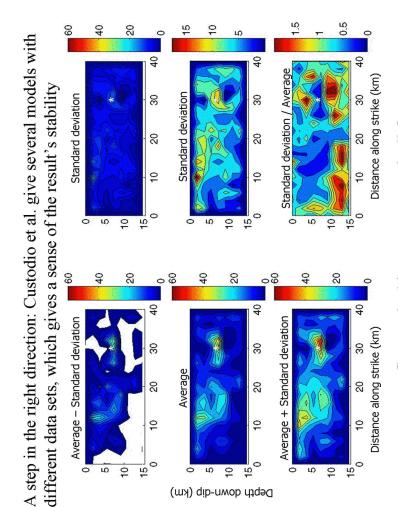
Current problems with kinematic inversions

- Often only one model is given
- No sense of "error" in the result
- Which parts of the result are best-constrained?
- How much of the answer is dependent on the constraints?
- Why do different inversions have such different slip models?





Forward Problem: incrementally adding dynamic effects to kinematic simulations.

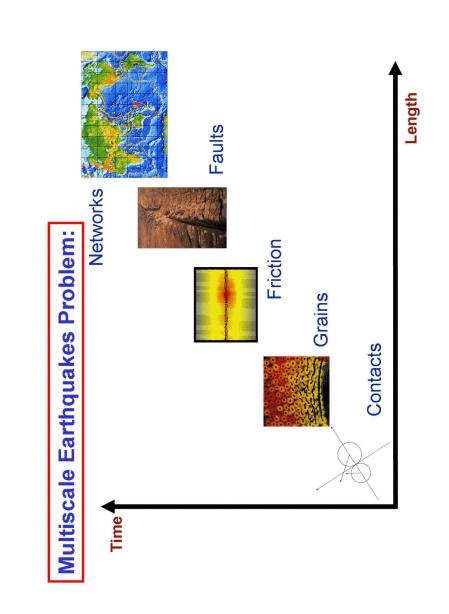


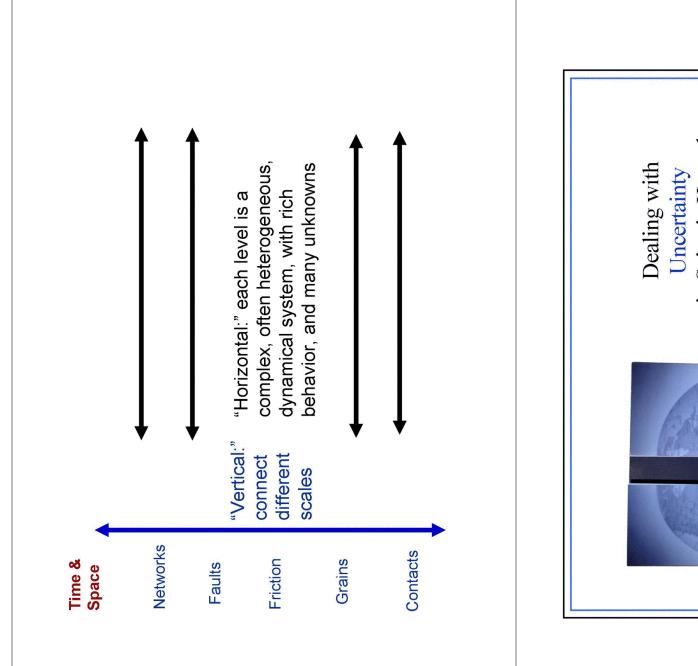
Can we do this more systematically?

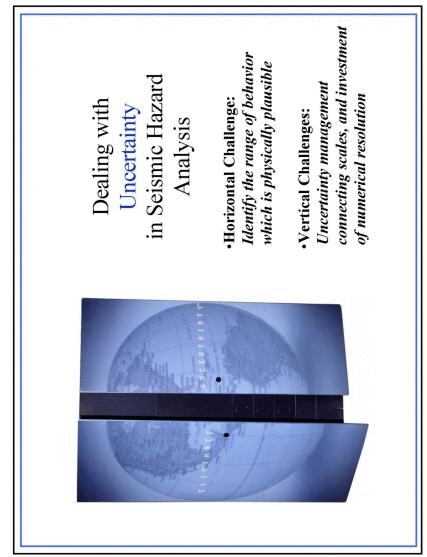
Applying control-theoretic techniques to the inverse problem

- Small singular values of A give directions of highest instability
- Extend to include analysis of sensitivities of constraints
- Effect of uncertainty in Green's function (site response, path effects, velocity structure uncertainty, etc.)
- ▶ How to weight different stations / components (which are most affected by noise in Green's function, for example)

Goal: A better measure of just how much we can resolve in kinematic inversions

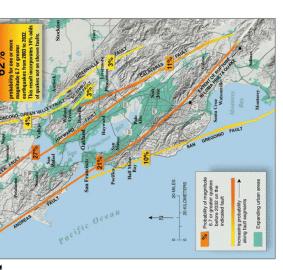






Economics and policy are based on regional hazard estimates, which require:

- More rigorous statistical methodologies for assimilating data
- Methods to systematically incorporate physical constraints on ground motion based on dynamics



Working Group 2002 (WG02) Earthquake Probability Study for the San Francisco Bay Region

(Morgan Page, poster session)

