Exoplanet Population Inference A Tutorial

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Today I'll mostly talk about Ganstine exoplanets*.

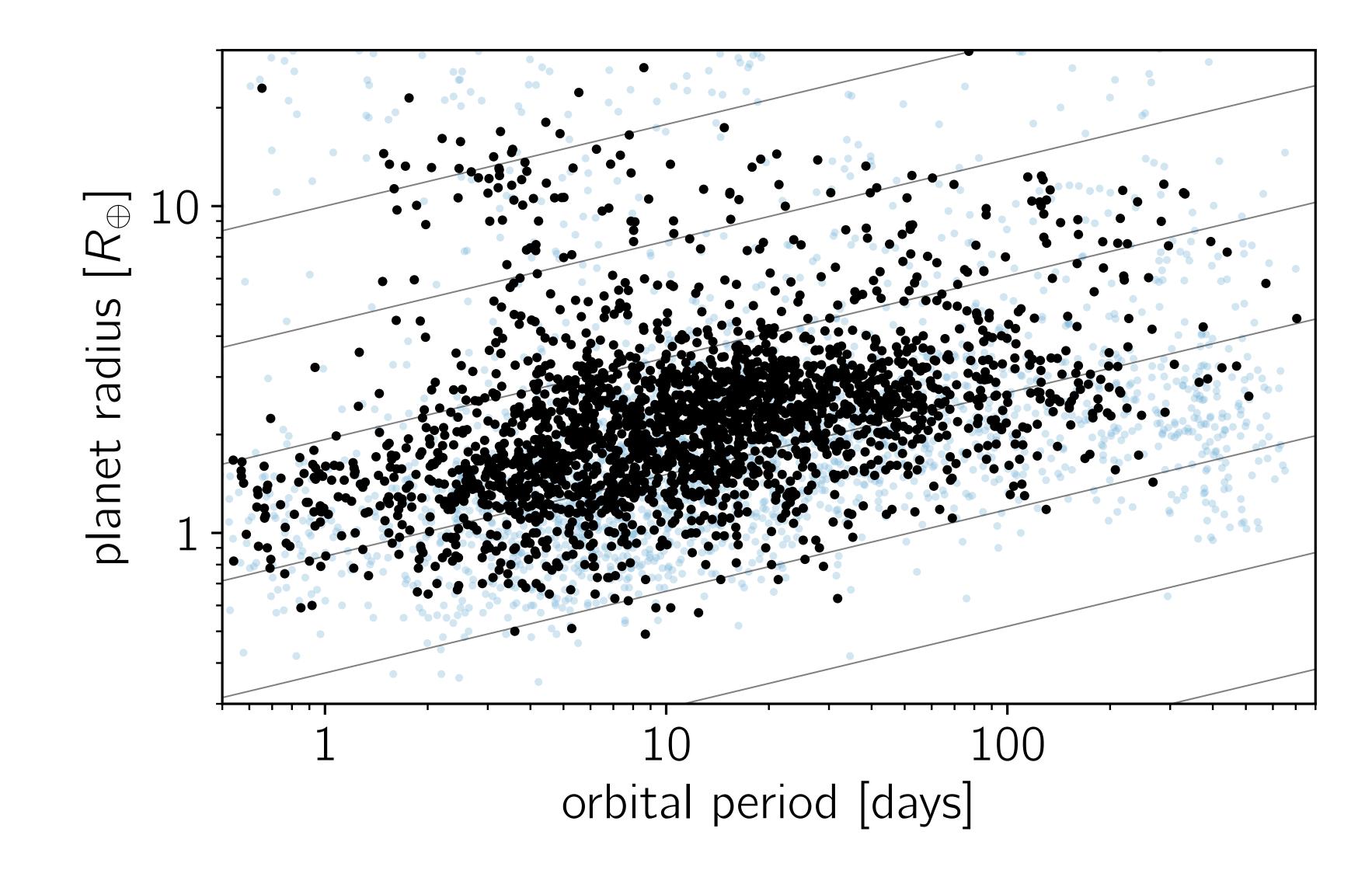
The methods can apply



* this is what I know about and work on!

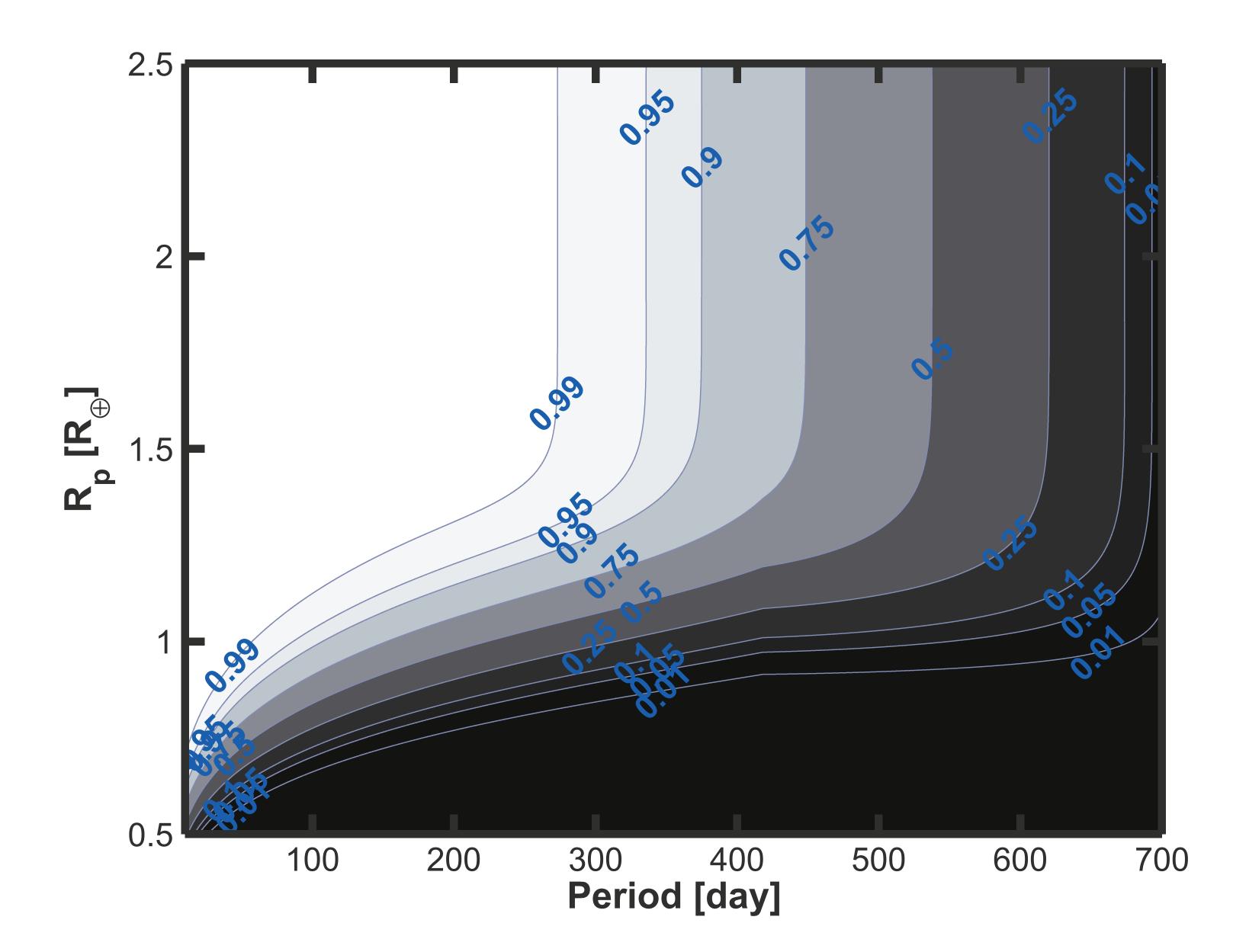


Exoplanet population inference



data: NASA Exoplanet Archive

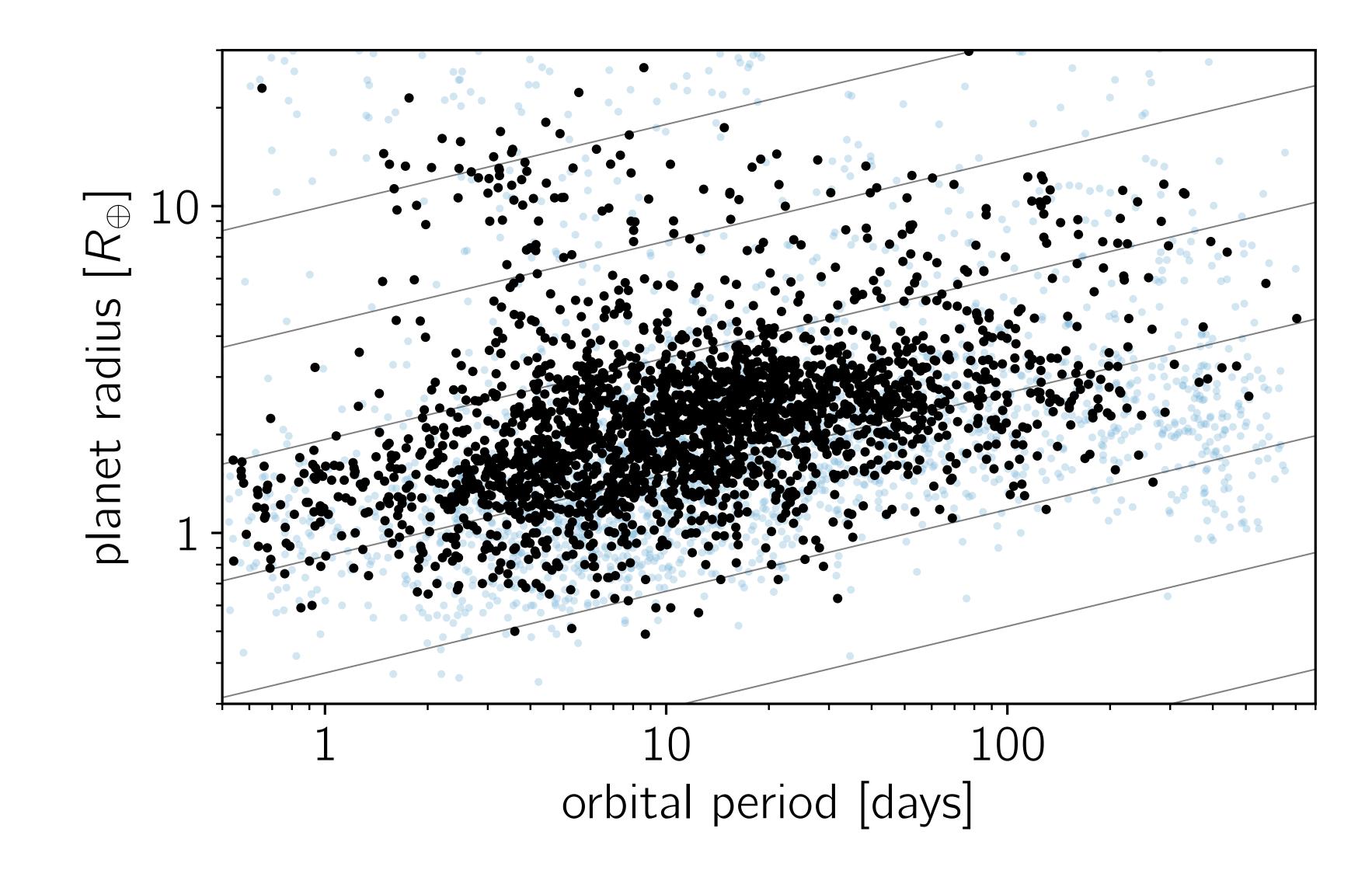




Burke, Christiansen et al. (2015)

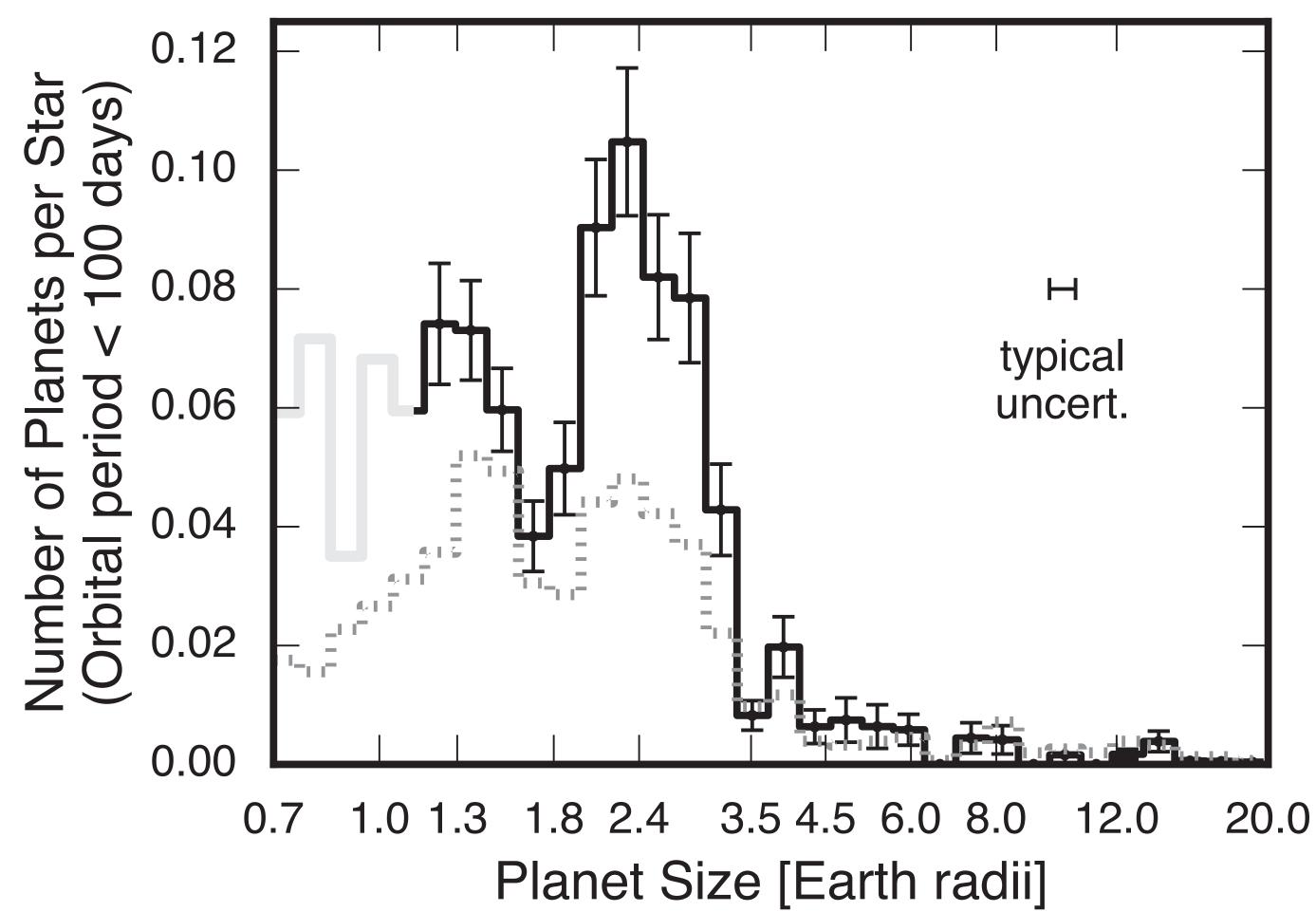
Take these catalogs andget the Divsics of planetformation and evolution.

That's hare.



data: NASA Exoplanet Archive







What is an occurrence rate?

The <u>expected number</u> of planets per star.

The fraction of stars with planets.

The expected number of planets per star per unit planet property.



None of these definitions is <u>inherently better</u> than the others.





They all depend on a specific (often unstated) clefinition of "planets".

So. It can be hard to compare and understand how they relate.

Teme * "The occurrence rate is 10%."

* including me and others in the room

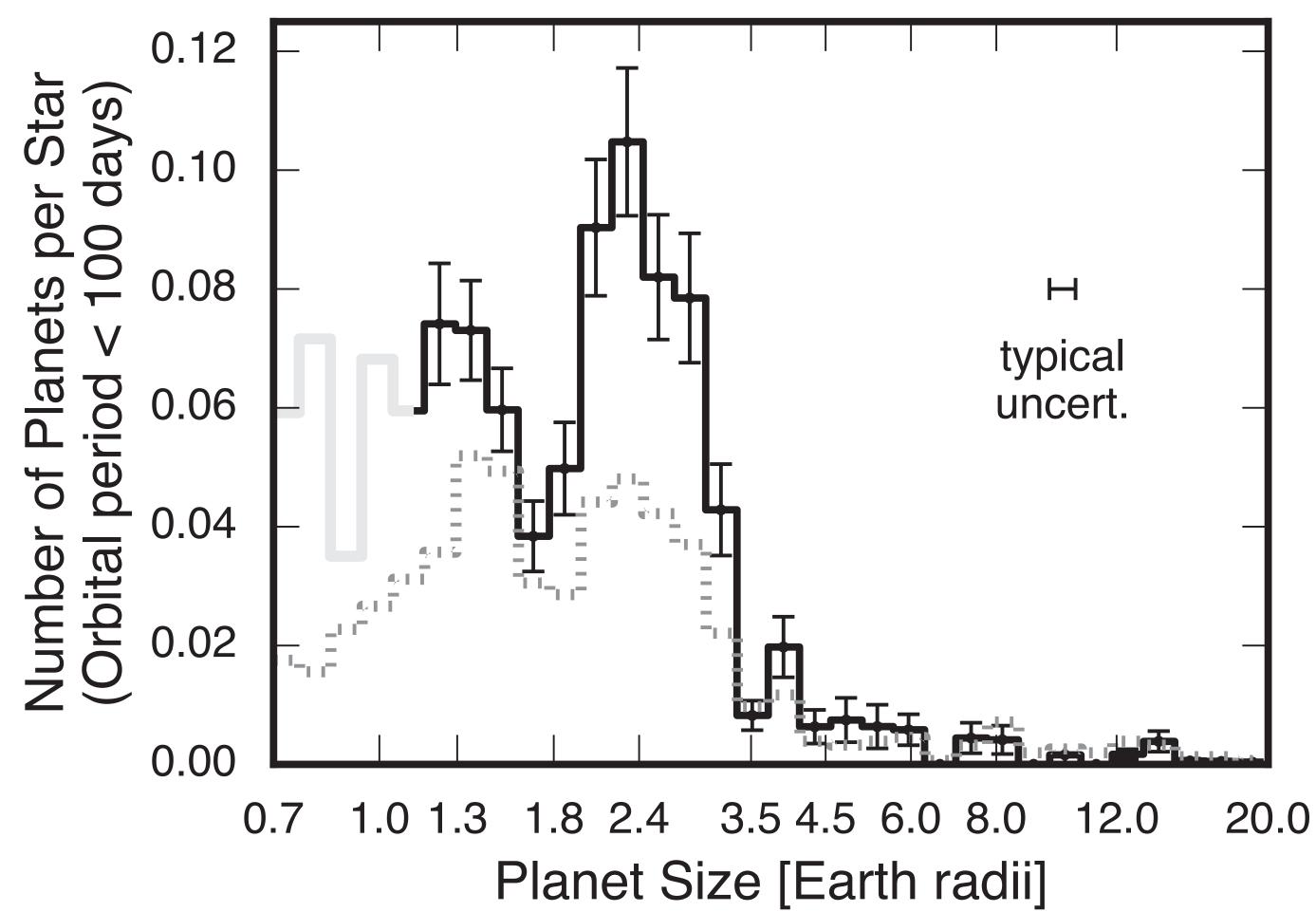


The occurrence rate is 10%."

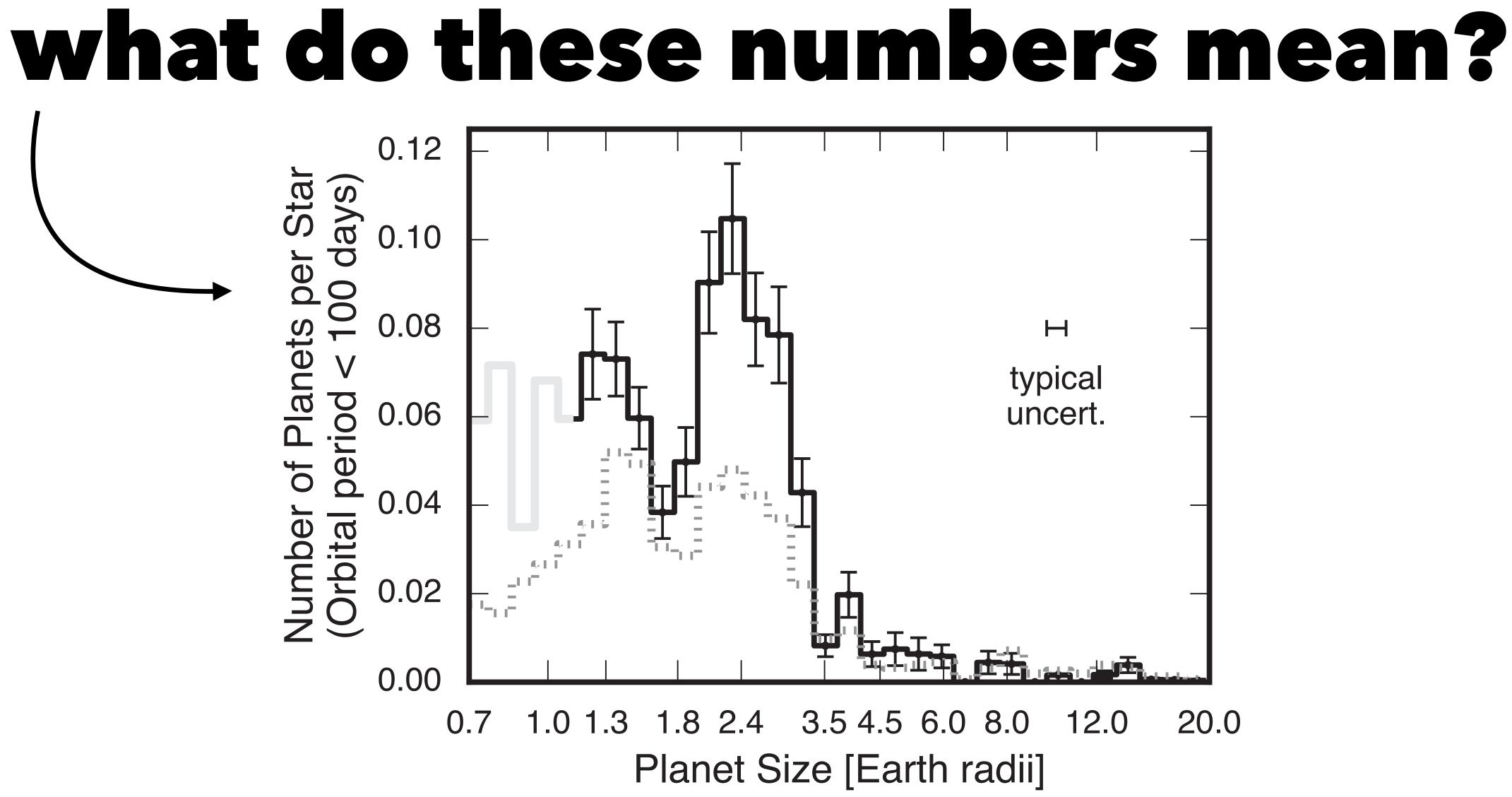
The what does it all mean?!?1?"

* including me and others in the room

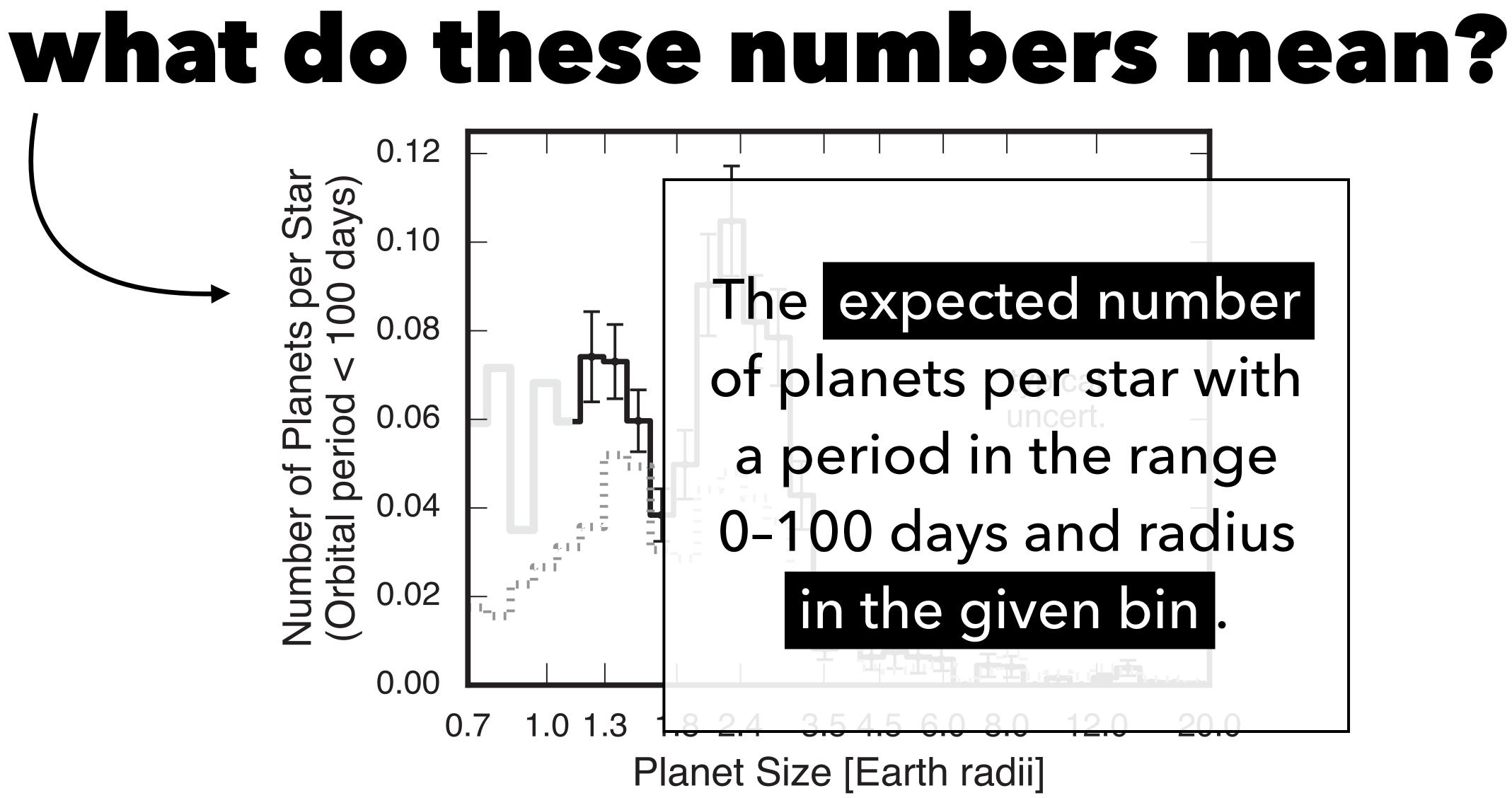




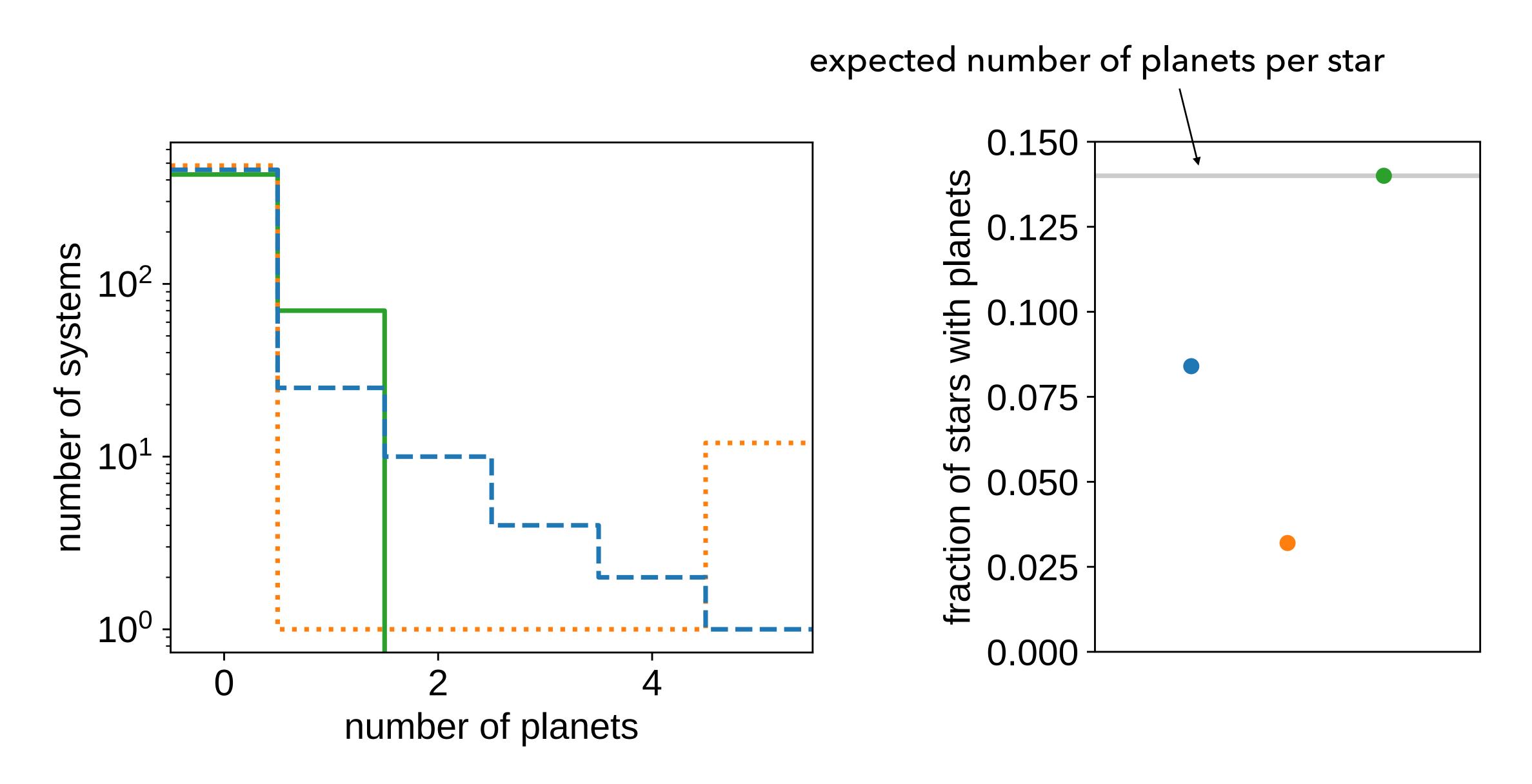












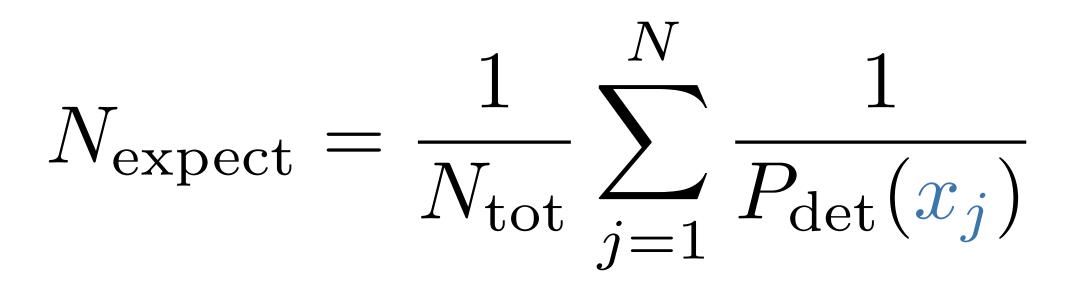
Simulations github.com/dfm/exostar19



How to estimate an occurrence rate?

Inverse detection efficiency Probabilistic modeling

Inverse detection efficiency



Note: don't do this!

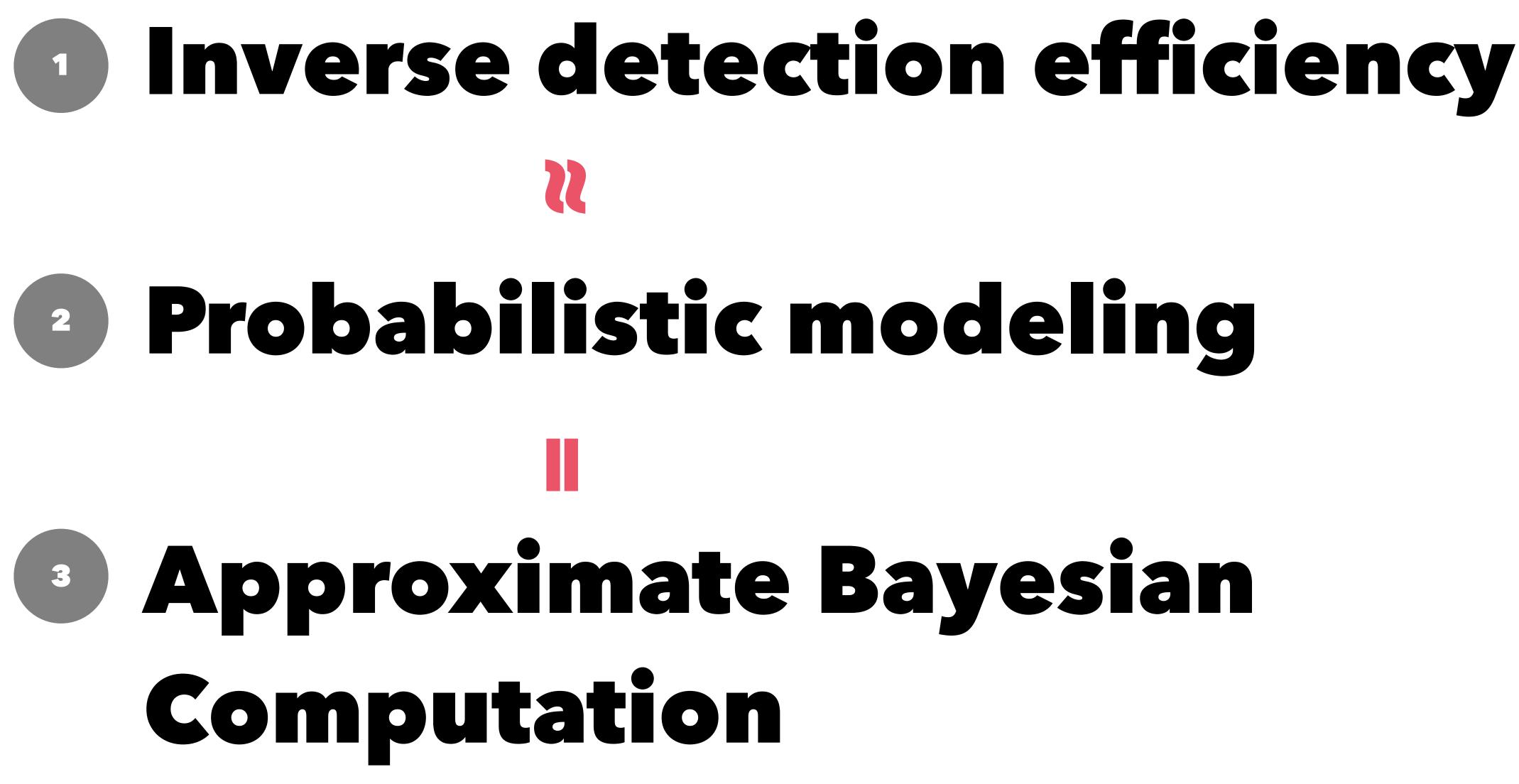
Probabilistic modeling

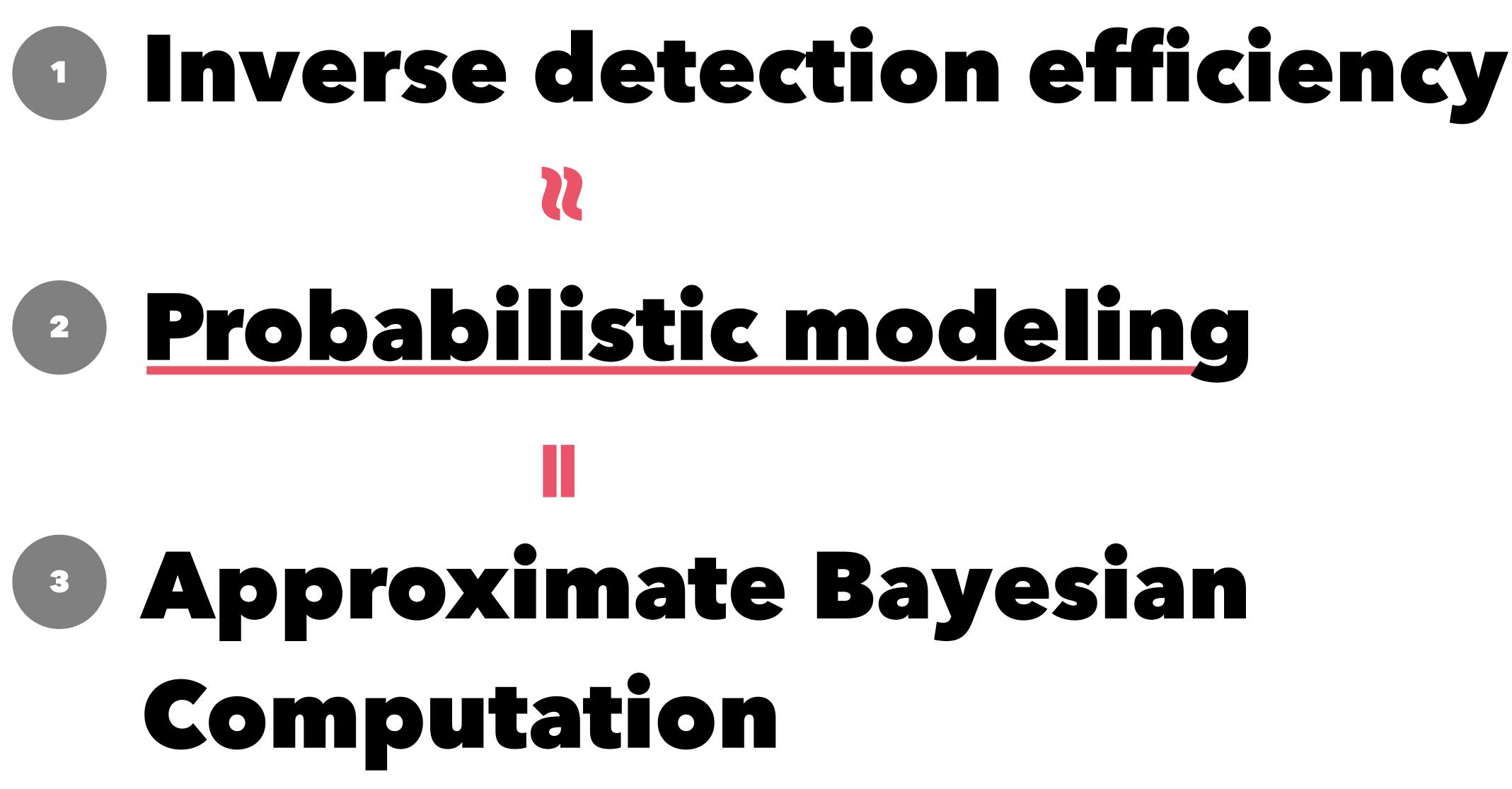
$N_{\text{expect}} = \arg \max_{N_{\text{expect}}} p(N_{\text{obs}}, \{x_j\} | N_{\text{expect}}, N_{\text{tot}})$





Inverse detection efficiency Probabilistic modeling

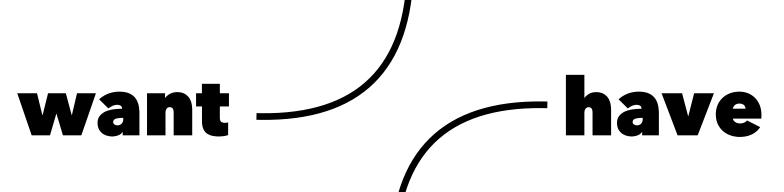






observed of planets

P(**C**) true number of planets



the properties oserved number Min Xi of the planets and the star and the star

observed number of planets

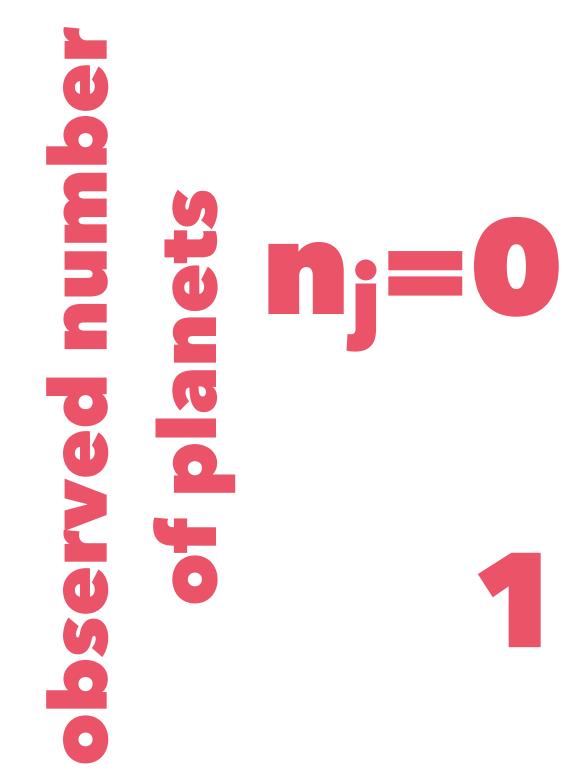
true number of planets

P(n; X; C;

the properties of the planets and the star

Start with either Zero or One planet(s).

There are for options.





true number of planets



Pdet(Xj)



But. We don't <u>Know</u> the true number of planets.



 $P(n_j \mid x_j) = \sum P(q_j) P(n_j \mid x_j, q_j)$ $q_j \in \{0, 1\}$

$P(n_j \mid x_j) = \sum P(q_j) P(n_j \mid x_j, q_j)$ $q_i \in \{0, 1\}$ $= Q P(n_i | x_i, q_i = 1) + (1 - Q) P(n_i | x_i, q_i = 0)$

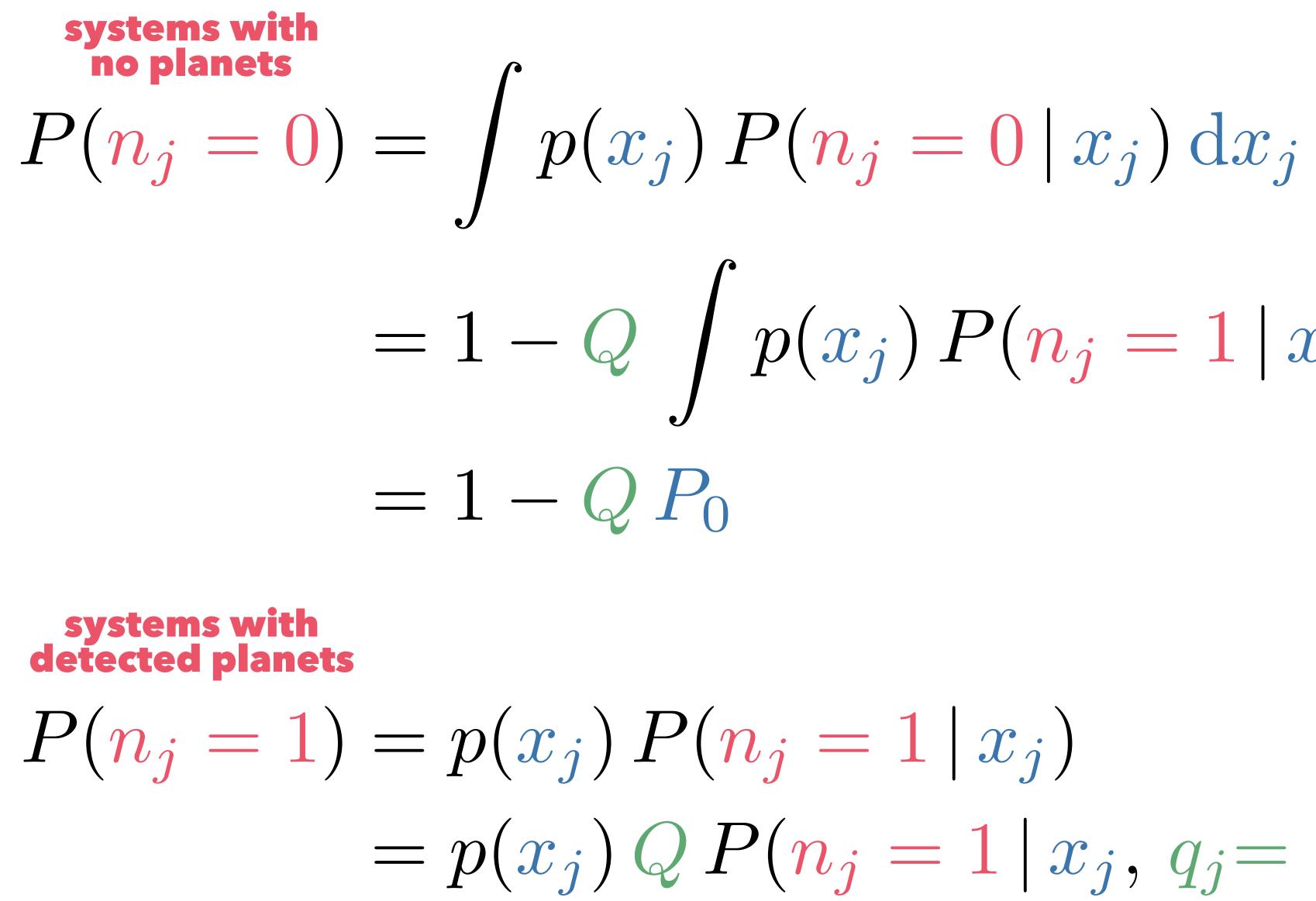


$P(n_j \mid x_j) = \sum P(q_j) P(n_j \mid x_j, q_j)$ $q_i \in \{0, 1\}$ $= Q P(n_{i} | x_{i}, q_{i} = 1) + (1 - Q) P(n_{i} | x_{i}, q_{i} = 0)$ this is the parameter that we want to fit for!



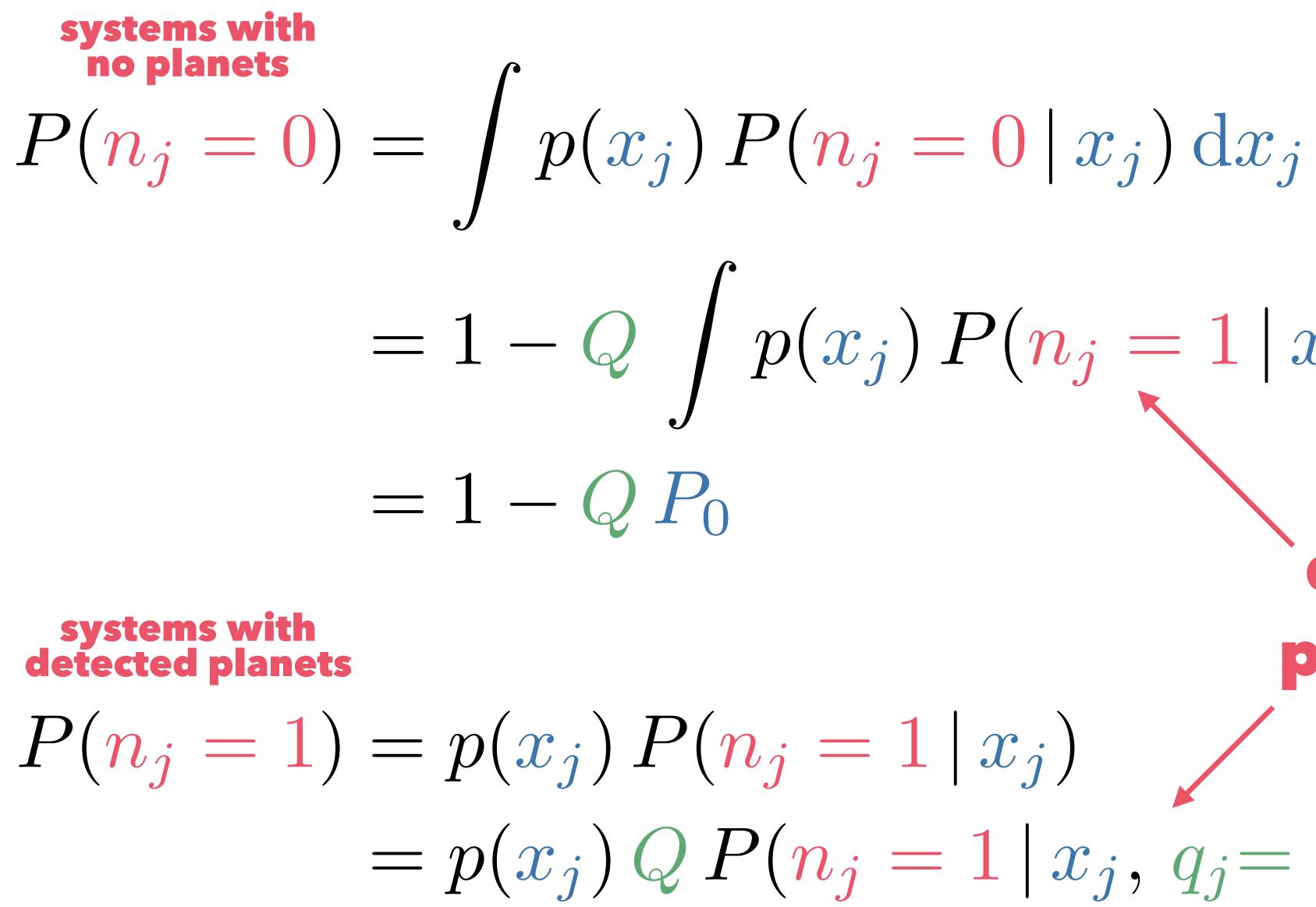
But. We don't know the properties of the Unobserved planets.





$= 1 - Q \left(p(x_j) P(n_j = 1 | x_j, q_j = 1) \, \mathrm{d} x_j \right)$

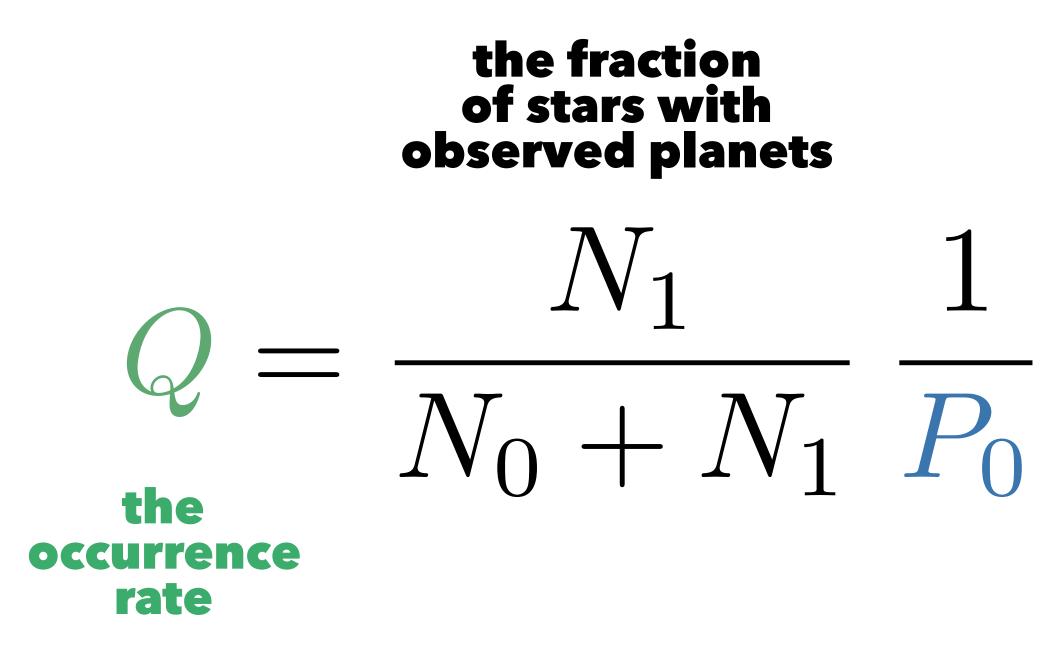
 $= p(x_j) Q P(n_j = 1 | x_j, q_j = 1)$

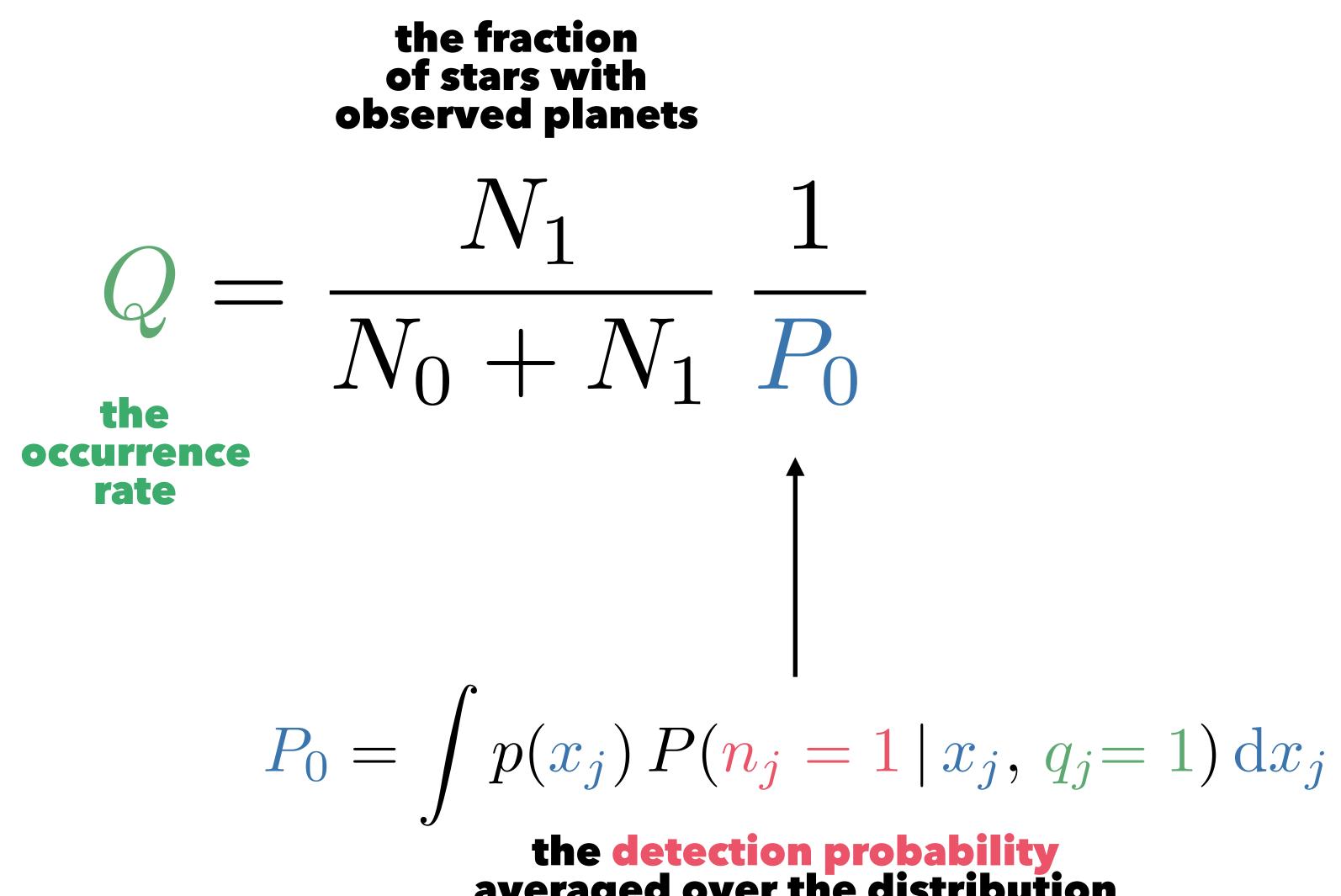


$= 1 - Q \int p(x_j) P(n_j = 1 | x_j, q_j = 1) dx_j$ detection probability $= p(x_j) Q P(n_j = 1 | x_j, q_j = 1)$

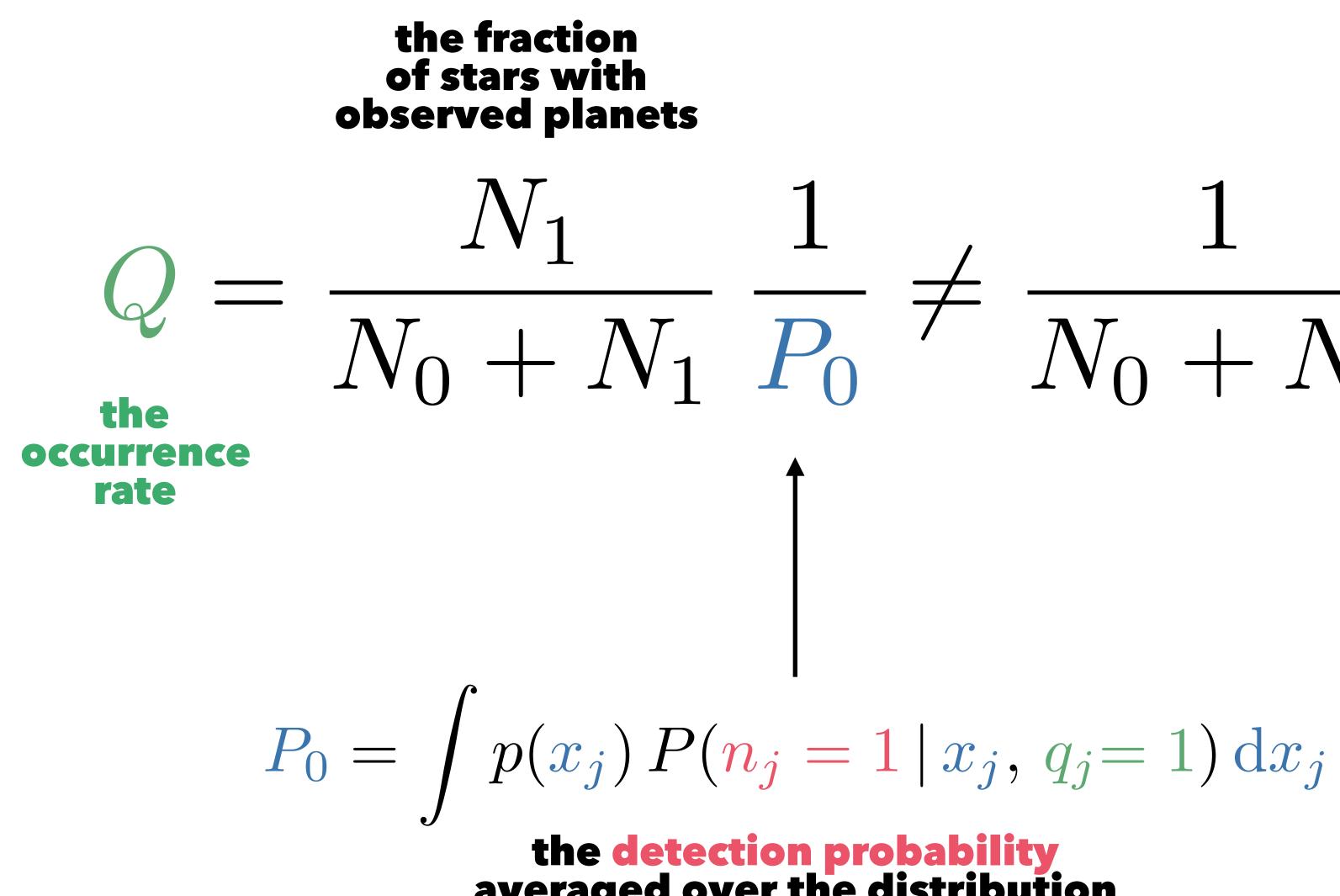
Put it all together.

An exercise for the reader...



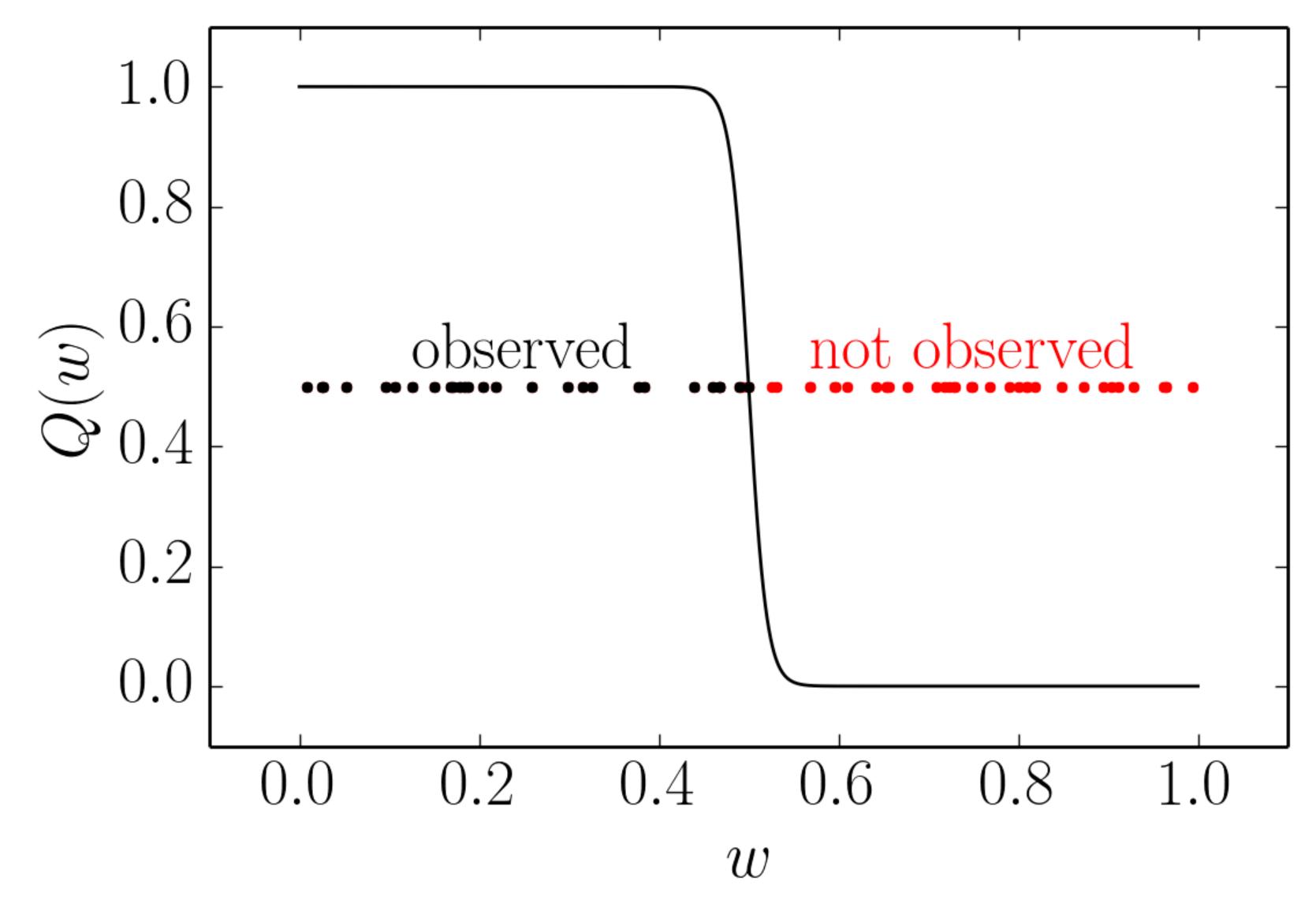


the detection probability averaged over the distribution of planet and stellar properties



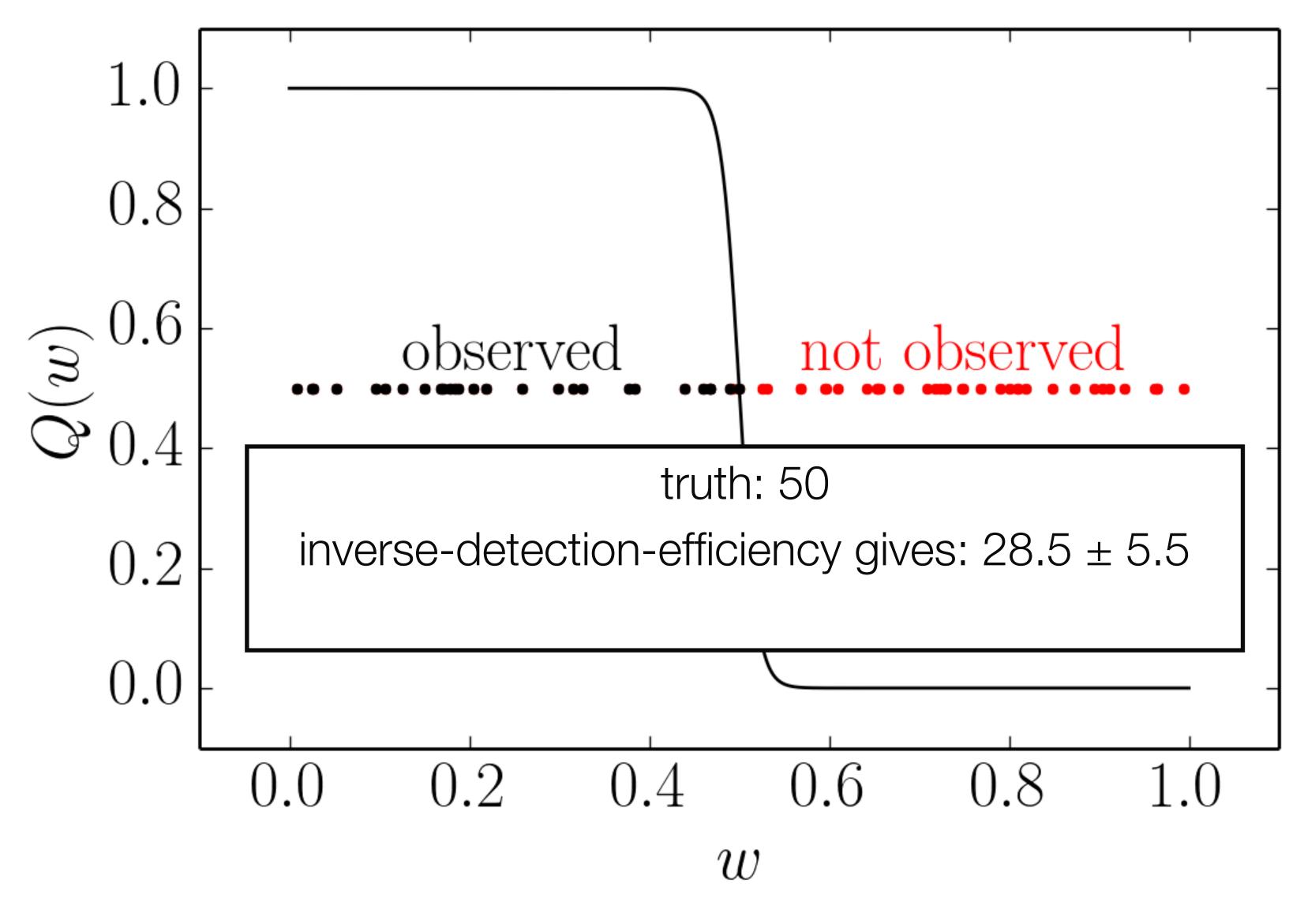
the detection probability averaged over the distribution of planet and stellar properties

 $N_0 + N_1$ $-P_i$



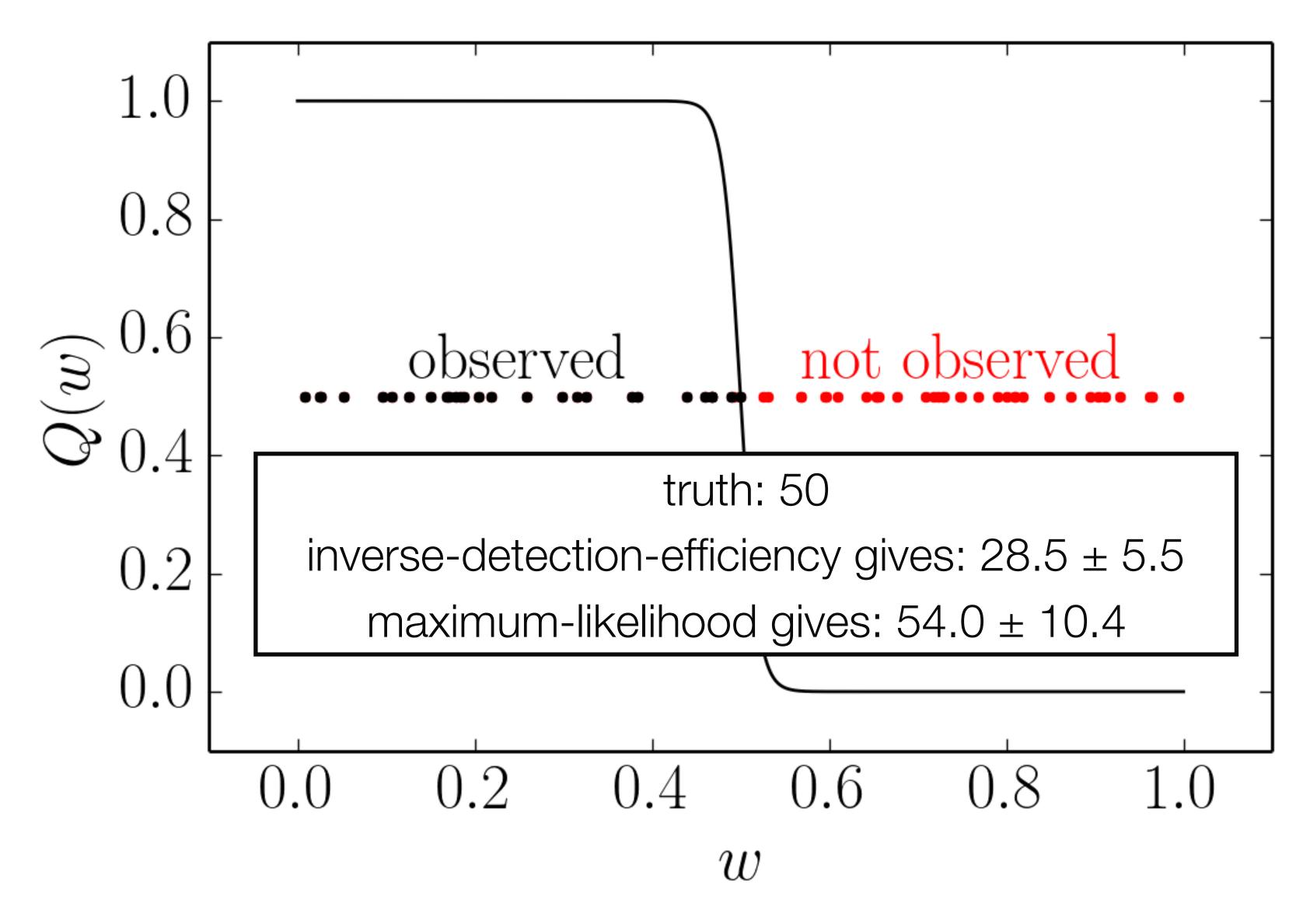
see: dfm.io/posts/histogram1





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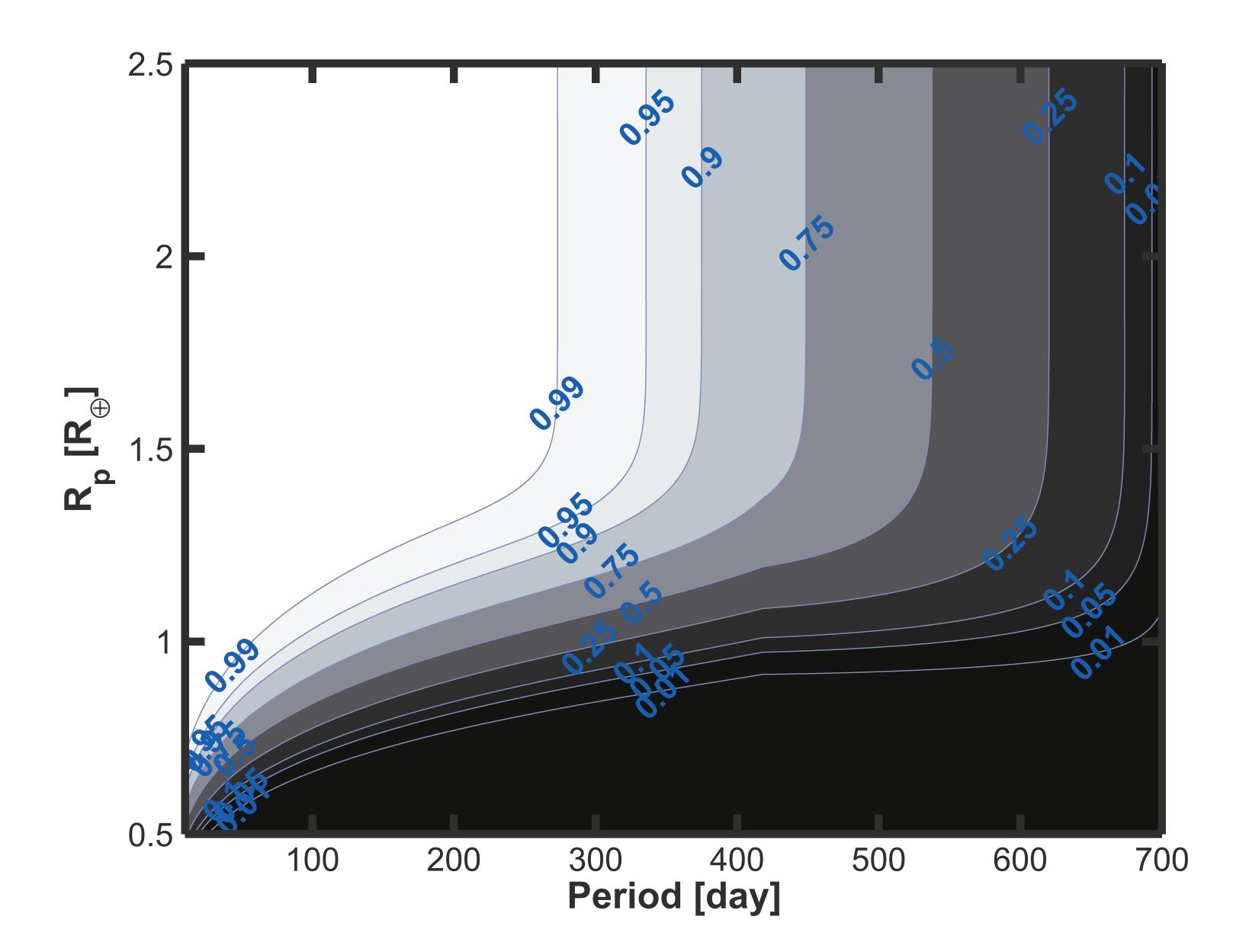
Inverse detection efficiency is not the right estimator.

Instead, take the fraction of detections and divide by the average detection efficiency*.

* averaged over the correct distribution for all planet and star properties



The key ingredient is the detection efficiency model.



Burke, Christiansen et al. (2015)

Remember: an occurrence rate depends on a lot of decisions!

1) Stellar sample

Provide a state of an example of planet parameters

3 Units

Planet multiplicity





Complications



2 Uncertainties

False positives

A Heterogeneous catalogs



You end up needing to do an integral over all the properties of all the planets and false positives that you cicn tobserve.



MathematicaTM Can't do that integral.



Eric Agol Canfe do that integral.



NCNC Eant do that integral*.



* in finite time.



This is where you use approximate Bayesian computation (ABC).

This is where you use approximate Bayesian computation (ABC). likelihood-free inference.

Likelihood-free inference is a method for doing rigorous inference with stochastic models.

If you can simulate it then you can do inference.

a realistic catalog

The promise of "likelihood-free inference".

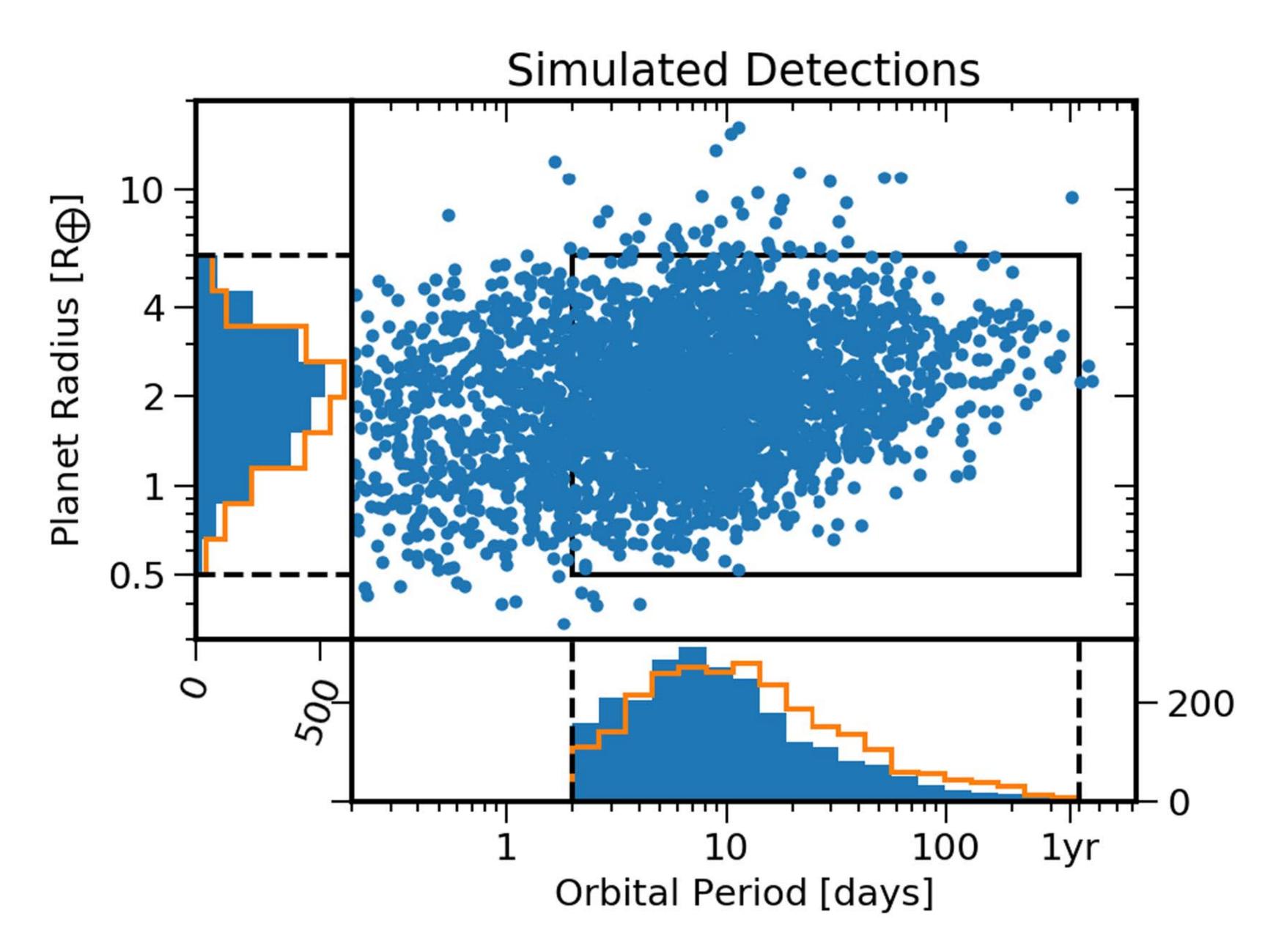


	16-		0 031 +	0 183 +	0 13 +	0 001 +	0 23 +	0.501 +	0 153 +				2	
Pla	12	<0.043% <0.026%	0.027 %	0.073 %	0.11 %	0.053 %	0.16 %	0.3 %	0.32 %	<0.78%	<2%		-10 ⁰	
			$0.025 \pm$	$0.092 \pm$	$0.12 \pm$	$0.165 \pm$	$0.21 \pm$	$0.317 \pm$	$0.93 \pm$	$1.8 \pm$	$2 \pm$	E		
	3+		0.018 %	0.064 % <0.075%	0.094 %		0.16 %	0.39 %	0.56 %	1%	0.92 %			
					$0.0594 \pm 0.045 \%$	0.08/± 0.081%	0.24 ± 0.19 %	0.61 ± 0.27 %	0.51 ± 0.39 %	$1.1 \pm 1.1 \%$	<2%	-		
		0.033 ± 0.031 %	<0.039%		0.14 ±	0.34 ±	0.33 ±	0.374 ±	1.51 ±	0.92 ±	2.6 ±	-		
				0.048 %	0.12 %	0.2 %	0.2 %	0.26 %	0.76 %	0.75 %	1.7 %			
		<0.11%	< 0.056%	0.091 ±	0.3 ±	0.74 ±	2.21 ±	2.25 ±	3.6 ±	2.9 ±	5.1 ±	-10^{-1}	-10^{-1}	
				0.089 %	0.19 %	0.45 %	0.7 %	0.85 %	1.1 %	1.7 %	3.2 %		_	
		<0.032%	$0.035 \pm$	$0.093 \pm 0.11 \%$	1.08 ± 0.32 %	2.52 ± 0.73 %	3.74 ± 0.82 %	6.19 ± 1.2 %	3.72 ± 1.4 %	7.78 ± 2.7 %	7.55 ± 4.4 %			2
	ン	<0.035%	0.022 / 0	0.11 / 0	$1.03 \pm$	$3.31 \pm$	0.82 /8 5.5 ±	$5.37 \pm$	$6.48 \pm$	5.6 ±	4.4 /0 5.4 ±	-		
			0.029 %	0.11 %	0.43 %	0.64 %	0.9 %	1.5 %	2.1 %	3.1 %	6.2 %	-		d ² f
		0.025 ± 0	$0.0591 \pm$	0.24 ±	0.7 ±	1.11 ±	0.58 ±	1.27 ±	1.3 ±	2.2 ±	17 ±	-		2
	1.75-	0.041 %	0.042 %	0.17 %	0.6 %	0.74 %	0.52 %	0.77 %	2 %	2.6 %	9.8 %			
			0.085 ±	0.624 ±	1.37 ±	2.17 ±	2.83 ±	2.1 ±	2.1 ±	3.24 ±	18 ±		-10 ⁻²	
	1.5	0.087 %	0.1 %	0.22 %	0.77 %	0.94 %	1.2 %	1.1 %	1.8 %	2.6 %	13 %	E		
		0.107 -	$0.244 \pm$	$0.917 \pm$	$1.94 \pm$	$3.24 \pm$	$2.5 \pm$	$1.1 \pm$	$2.23 \pm$	<9.1%	<22%		F	
	1.25	0.12 %		0.28 %	0.44 %	1.1 %	1.3 %	1%	6.6 %			-		
		0.27 ± 0.21 %	0.136 ± 0.12 %	0.27 ± 0.35 %	2.46 ± 0.65 %	3.77 ± 1.9 %	4.8 ± 2.5 %	6 ± 4 %	11.2 ± 5.8 %	<18%	<36%	-		
	1-	0.21 / 0	0.12 / 0	$1.01 \pm$	$3.75 \pm$	5 ±	8.29 ±	5.2 ±				-		
	0.75	0.13 %		0.51 %	1.3 %	2.1 %	5.7 %	3.3 %	<13%	<58%	<61%			
		0.35 ±	0.31 ±	2.6 ±	7.77 ±	8.33 ±	~160/	~710/	~1000/	<050/	~000/		-10 ⁻³	
		0.25 %	0.35 %	1.3 %	2.3 %	5.1 %	<16%	<21%	<100%	<95%	<80%			
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Hsu et al. (2019)

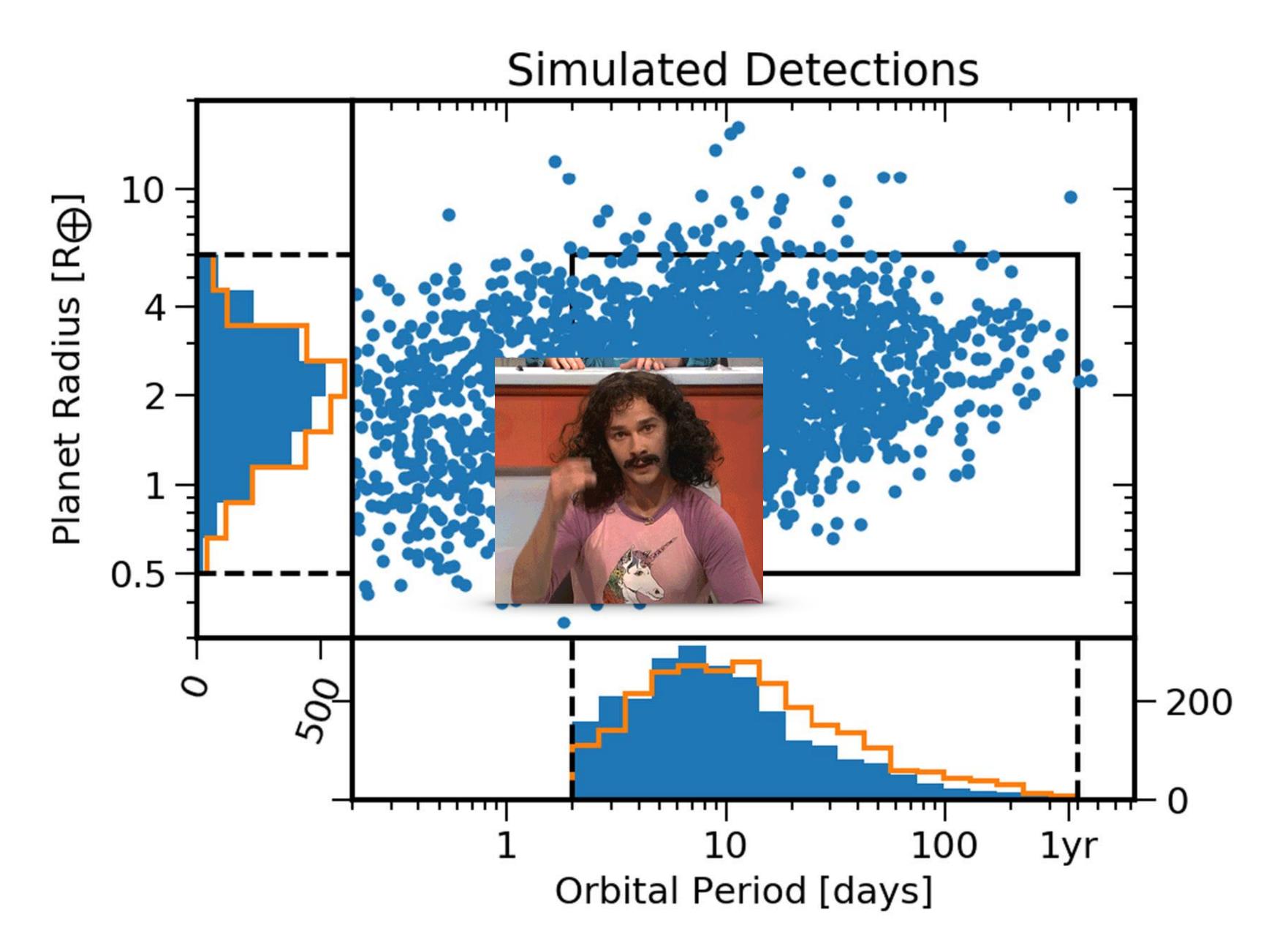


There's still lots to do!



EPOS; Mulders et al. (2018)





EPOS; Mulders et al. (2018)





An occurrence rate needs to come with a loi of metadata.

Comparing occurrence rates:

Check the Units.





Don't sum the inverse detection probabilities for your planets!

* a more reliable estimator *is just as easy* to compute!



If you're using a method that seems intuitive, make sure the math checks out !

Likelihood-free inference seems like a promising way forward.

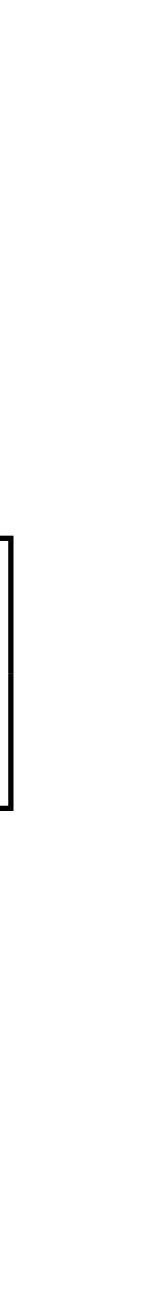
* a.k.a. Approximate Bayesian Computation (ABC)





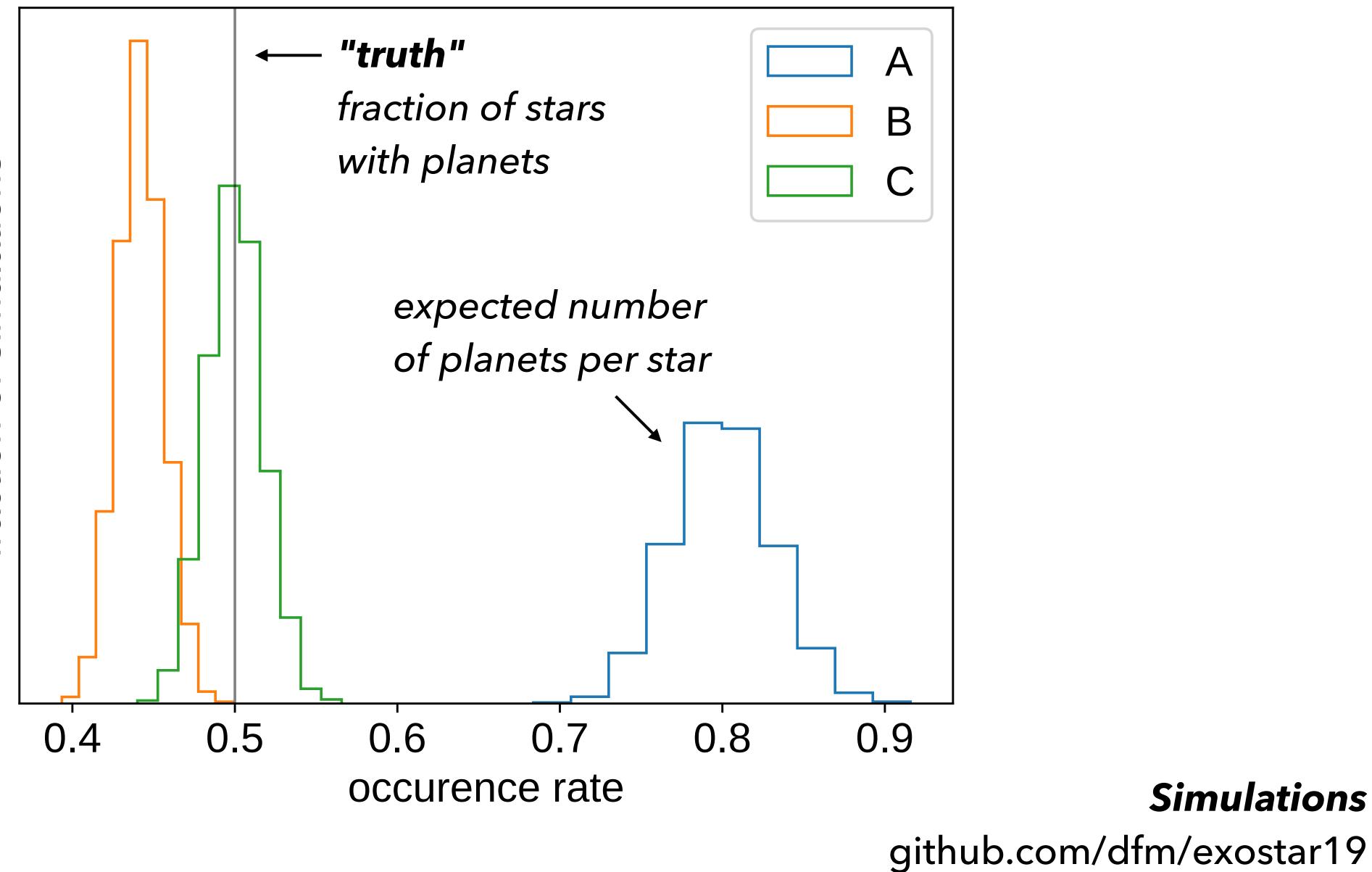


$p(\{n_j\}, \{x_j\} | Q) = [1 - Q P_0]^{N_0} \left[\prod_{j=1}^{N_1} Q p(x_j) P(n_j = 1 | x_j, q_j = 1) \right]$



 $\log p(\{n_j\}, \{x_j\} | Q) = N_0 \log (1 - Q P_0) + N_1 \log Q + \text{constant}$

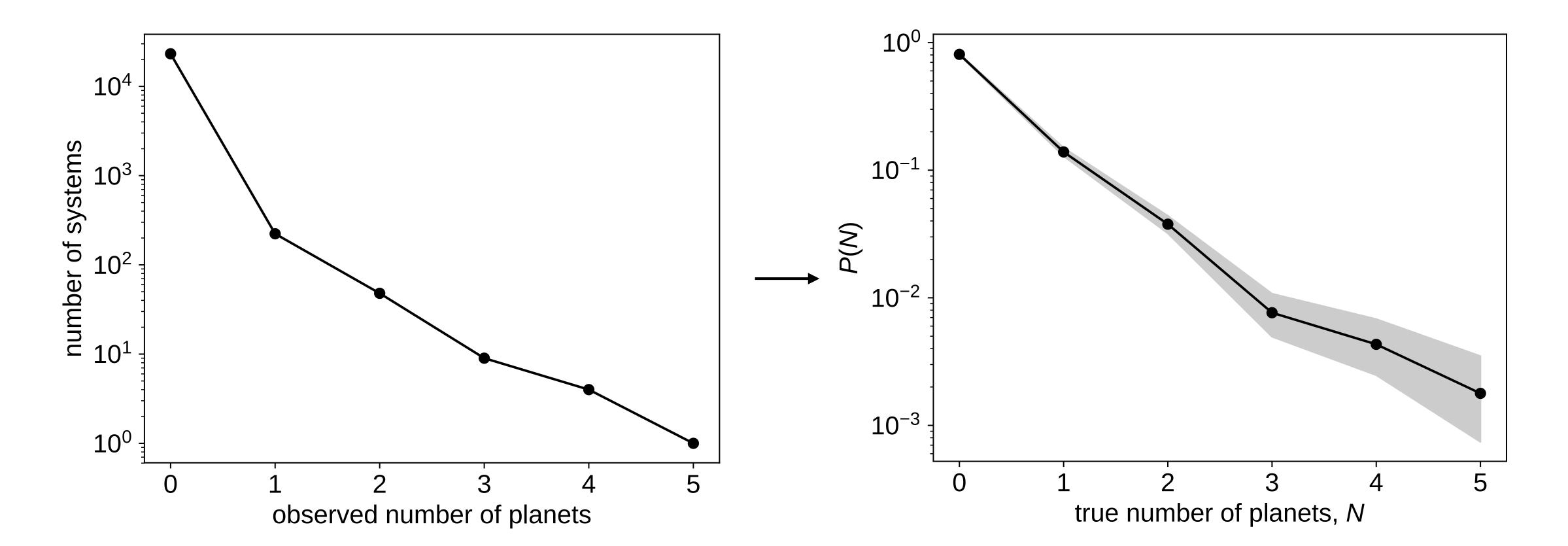
$\log p(\{n_j\}, \{x_j\} | Q) = N_0 \log (1 - Q P_0) + N_1 \log Q + \text{constant}$ $Q = \frac{N_1}{N_0 + N_1} \frac{1}{P_0}$



fraction of simulations



Note: this is preliminary & really just a toy...

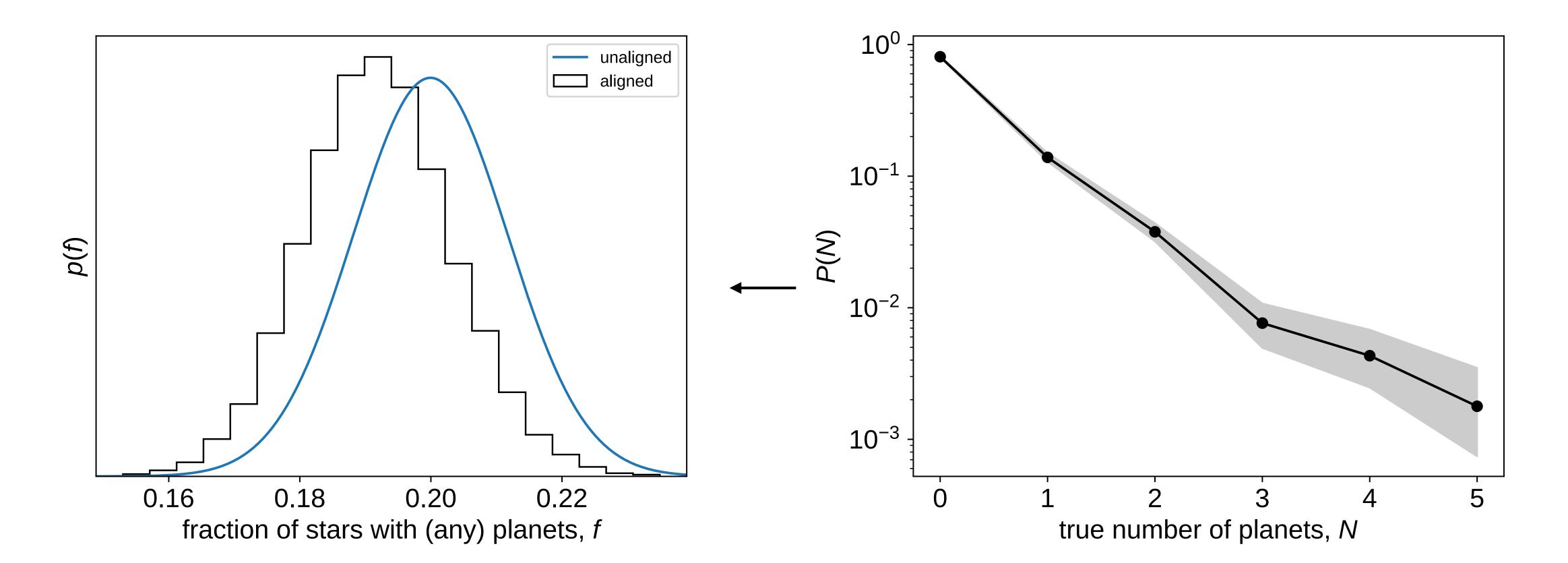


assuming: no mutual inclination only geometric transit probability

 $0.5 < R_P/R_{Earth} < 8; 10 < a/R_{star} < 30$ Kepler data: github.com/dfm/exostar19



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