# Exoplanet Population Inference 

A Tutorial

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## Today I'Il mostly talk about transiting exoplanets*.

## The methods can apply <br> more broadly.

* this is what I know about and work on!


## Exoplanet population inference


data: NASA Exoplanet Archive


Burke, Christiansen et al. (2015)

# Take these catalogs and get the physics of planet formation and evolution. 

## That's hard.


data: NASA Exoplanet Archive


Fulton \& Petigura (2018)

## What is an occurrence rate?

## The expected number of planets per star.

# The fraction of stars with planets. 

## The expected number of planets per star per unit planet property.

etc.

# None of these definitions <br> is inherently better than the others. 

## But. They are all different.

## They have different units.

# They all depend on a specific (often unstated) <br> definition of "planets". 

So. It can be hard to compare and understand how they relate.

## Them: * "The occurrence rate is 10\%."

# Them: * "The occurrence rate is 10\%." 

## Yall: "what does it all mean?!?1?"

* including me and others in the room


Fulton \& Petigura (2018)

## what do these numbers mean?




Fulton \& Petigura (2018)

## what do these numbers mean?




Simulations
github.com/dfm/exostar19

## How to estimate an occurrence rate?

# Inverse detection efficiency 

(2) Probabilistic modeling

3 Approximate Bayesian Computation

## Inverse detection efficiency

$$
N_{\text {expect }}=\frac{1}{N_{\text {tot }}} \sum_{j=1}^{N} \frac{1}{P_{\mathrm{det}}\left(x_{j}\right)}
$$

Note: don't do this!

## Probabilistic modeling

$$
N_{\text {expect }}=\arg \max _{N_{\text {expect }}} p\left(N_{\text {obs }},\left\{x_{j}\right\} \mid N_{\text {expect }}, N_{\text {tot }}\right)
$$

## Approximate Bayesian Computation



## Approximate Bayesian Computation



# Inverse detection efficiency 

(2) Probabilistic modeling

3 Approximate Bayesian Computation
(1) Inverse detection efficiency $u$
(2) Probabilistic modeling

## II

(3) Approximate Bayesian Computation
(1) Inverse detection efficiency u
(2) Probabilistic modeling

## II

(3) Approximate Bayesian Computation

## $\mathbf{P}\left(q_{0}\right)_{\text {turenumber }}$ of planets



## observed  <br> the properties <br> of the planets <br> and the star

$$
\begin{aligned}
& \text { observed number true number } \\
& \text { of planets } \\
& \text { of planets } \\
& \text { the properties } \\
& \text { of the planets } \\
& \text { and the star }
\end{aligned}
$$

# Start with either zero <br> or one planet(s). 

## There are four options.

## true number of planets



## $q_{j}=0$ <br> 1 <br> 1-Pdet $\left(x_{j}\right)$

$\mathbf{P}_{\text {det }}\left(\mathrm{X}_{\mathrm{j}}\right)$
value of $\mathbf{P}\left(n_{j} \mid x_{j}, q_{j}\right)$

# But. We don't Know the true number of planets. 

Marginalize!

$$
P\left(n_{j} \mid x_{j}\right)=\sum_{q_{j} \in\{0,1\}} P\left(q_{j}\right) P\left(n_{j} \mid x_{j}, q_{j}\right)
$$

$$
\begin{aligned}
P\left(n_{j} \mid x_{j}\right) & =\sum_{q_{j} \in\{0,1\}} P\left(q_{j}\right) P\left(n_{j} \mid x_{j}, q_{j}\right) \\
& =Q P\left(n_{j} \mid x_{j}, q_{j}=1\right)+(1-Q) P\left(n_{j} \mid x_{j}, q_{j}=0\right)
\end{aligned}
$$

$$
\begin{aligned}
P\left(n_{j} \mid x_{j}\right)= & \sum_{q_{j} \in\{0,1\}} P\left(q_{j}\right) P\left(n_{j} \mid x_{j}, q_{j}\right) \\
= & Q P\left(n_{j} \mid x_{j}, q_{j}=1\right)+(1-Q) P\left(n_{j} \mid x_{j}, q_{j}=0\right) \\
& \underbrace{}_{\text {this is the parameter }} \begin{array}{l}
\text { that we want to fit for! }
\end{array}
\end{aligned}
$$

# But. We don't know the properties of the unobserved planets. 

Marginalize!
systems with

$$
\begin{aligned}
P\left(n_{j}=0\right) & =\int p\left(x_{j}\right) P\left(n_{j}=0 \mid x_{j}\right) \mathrm{d} x_{j} \\
& =1-Q \int p\left(x_{j}\right) P\left(n_{j}=1 \mid x_{j}, q_{j}=1\right) \mathrm{d} x_{j} \\
& =1-Q P_{0}
\end{aligned}
$$

systems with
detected planets

$$
\begin{aligned}
P\left(n_{j}=1\right) & =p\left(x_{j}\right) P\left(n_{j}=1 \mid x_{j}\right) \\
& =p\left(x_{j}\right) Q P\left(n_{j}=1 \mid x_{j}, q_{j}=1\right)
\end{aligned}
$$

systems with
$P\left(n_{j}=0\right)=\int p\left(x_{j}\right) P\left(n_{j}=0 \mid x_{j}\right) \mathrm{d} x_{j}$

$$
\begin{aligned}
& =1-Q \int p\left(x_{j}\right) P\left(n_{j}=1 \mid x_{j}, q_{j}=1\right) \mathrm{d} x_{j} \\
& =1-Q P_{0}
\end{aligned}
$$

detection
systems with
detected planets

$$
\begin{aligned}
P\left(n_{j}=1\right) & =p\left(x_{j}\right) P\left(n_{j}=1 \mid x_{j}\right) \\
& =p\left(x_{j}\right) Q P\left(n_{j}=1 \mid x_{j}, q_{j}=1\right)
\end{aligned}
$$

## Put it all together.

> the fraction
> of stars with
> observed planets

occurrence rate

$$
\begin{gathered}
\text { the fraction } \\
\text { of stars with } \\
\text { observed planets }
\end{gathered}
$$

$$
\begin{aligned}
& \text { moseme } \\
& \text {, itars wint } \\
& \text { obsered pimases } \\
& Q=\frac{N_{1}}{N_{0}+N_{1}} \frac{1}{P_{0}} \neq \frac{1}{N_{0}+N_{1}} \sum_{j=1}^{N_{1}} \frac{1}{P_{j}}
\end{aligned}
$$


see: dfm.io/posts/histogram1

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# Inverse detection efficiency is not the right estimator. 

# Instead, take the fraction of detections and divide by the average detection efficiency*. 

## The key ingredient is the detection efficiency model.



Burke, Christiansen et al. (2015)

## Remember: an occurrence rate depends on a lot of decisions!

# Stellar sample 

## Range of planet parameters

3 Units
. Planet multiplicity

## Complications

## 2 <br> Uncertainties

## 3. False positives

Heterogeneous catalogs

You end up needing to do an integral over all the properties of all the planets and false positives that you didn't observe.

## Mathematica ${ }^{\text {TM }}$ can't do that integral.

## Eric Agol can't do that integral.

## MCMC can't do that integral*.

\author{

* in finite time.
}

This is where you use approximate Bayesian computation (ABC).

## This is where you use

approximate Bayesian computation (ABC). likelihood-free inference.

# Likelihood-free inference 

 is a method for doingrigorous inference with
stochastic models.
a realistic catalog

# If you can simulate it then you can do inference. 

The promise of "likelihood-free inference".


Hsu et al. (2019)

## There's still lots to do!

Simulated Detections


EPOS; Mulders et al. (2018)

Simulated Detections


EPOS; Mulders et al. (2018)

## Take homes

An occurrence rate needs to come with a lot of metadata.

## Comparing occurrence rates:

Check the units.
Check the parameter ranges.

# Don't sum the inverse detection probabilities for your planets! 

* a more reliable estimator is just as easy to compute!

If you're using a method that seems inturive, make sure the math checks out!

## Likelihood-free inference seems like a promising way forward.

* a.k.a. Approximate Bayesian Computation (ABC)


## [t's over.

## Extras.

$$
p\left(\left\{n_{j}\right\},\left\{x_{j}\right\} \mid Q\right)=\left[1-Q P_{0}\right]^{N_{0}}\left[\prod_{j=1}^{N_{1}} Q p\left(x_{j}\right) P\left(n_{j}=1 \mid x_{j}, q_{j}=1\right)\right]
$$

$\log p\left(\left\{n_{j}\right\},\left\{x_{j}\right\} \mid Q\right)=N_{0} \log \left(1-Q P_{0}\right)+N_{1} \log Q+$ constant
$\log p\left(\left\{n_{j}\right\},\left\{x_{j}\right\} \mid Q\right)=N_{0} \log \left(1-Q P_{0}\right)+N_{1} \log Q+$ constant

$$
Q=\frac{\downarrow}{N_{0}+N_{1}} \frac{1}{P_{0}}
$$



Simulations
github.com/dfm/exostar19

## Note: this is preliminary \& really just a toy...



assuming:
no mutual inclination
only geometric transit probability

$$
\begin{array}{r}
0.5<R_{P} / R_{\text {Earth }}<8 ; 10<a / R_{\text {star }}<30 \\
\text { Kepler data: } \\
\text { github.com } / \text { dfm } / \text { exostar19 }
\end{array}
$$

## Note: this is preliminary \& really just a toy...



assuming:
no mutual inclination
only geometric transit probability
$0.5<R_{P} / R_{\text {Earth }}<8 ; 10<a / R_{\text {star }}<30$
Kepler data:
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