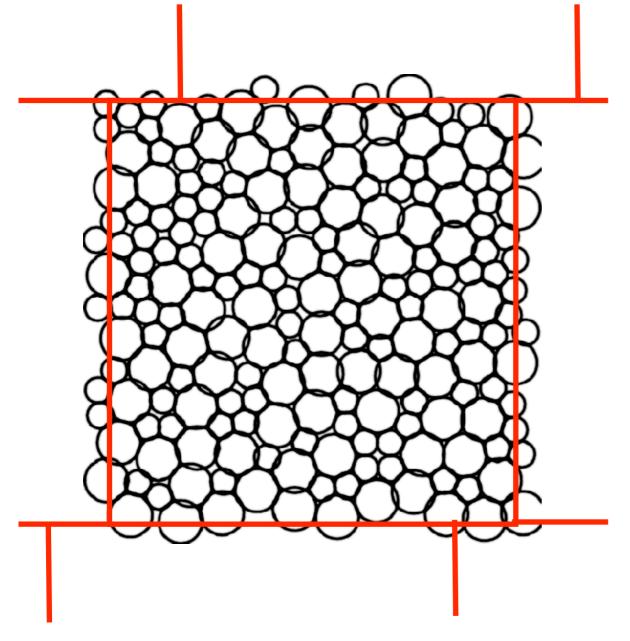
Avalanches and Diffusion in Amorphous Solids Under Athermal, Quasistatic Shear



Craig Maloney

Collaborators: M. O. Robbins (Hopkins)

Funding: NSF DMR-0454947 and PHY99-07949

KITP June 2010

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Outline

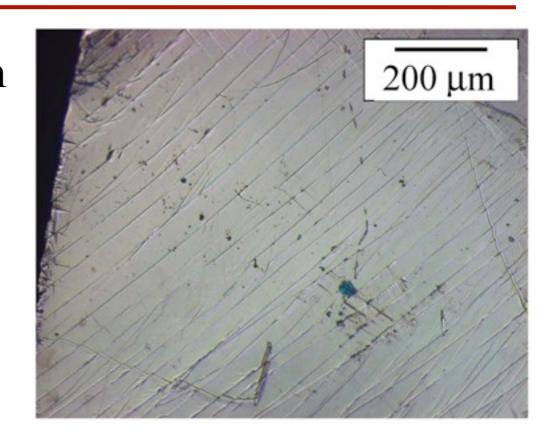
- Amorphous solids
 - Types
 - Athermal quasistatic shear (AQS)
- Slip lines in Lennard-Jones solids
 - CEM + M.O. Robbins (J. Phys 2008, PRL 2009)
 - Spatial structure of plasticity
 - Effective diffusion
- Jamming
 - (CEM. PRL Submitted)
 - Bubble model / critical scaling near jamming
 - Effective diffusion
 - Avalanches





The question(s) I am asking

- For "simple" amorphous solids in AQS:
 - What is the elementary mechanism(s) which accommodates applied shear?
 - How are they organized in space and time?
 - (How does this impact viscoplastic rheology)?



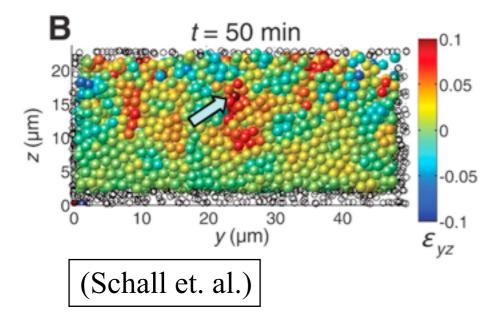




Types of amorphous solids

- Types
 - Emulsions / Foams
 - Granular packings
 - Colloidal suspensions
 - Atoms / Molecules

Local shear strain under driving:



Polydisperse PMMA spheres in density-matched solvent

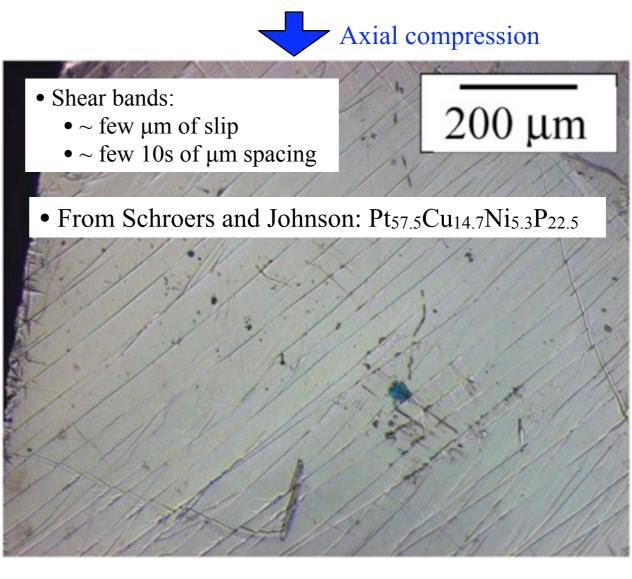
Solid-like (glassy) regime, no applied shear strain

(Weeks et. al.)



Types of amorphous solids

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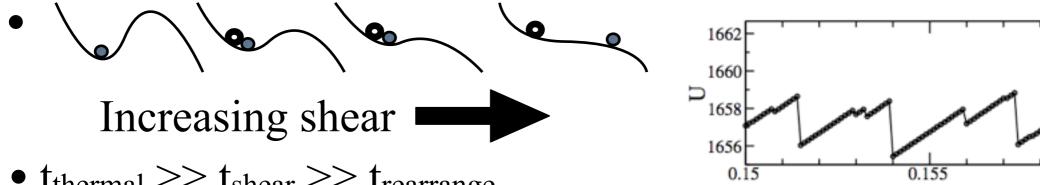






Athermal, quasistatic shear (AQS)

- Differences in particle-scale physics (do they matter?):
 - Inertial or overdamped?
 - "Real" temperature
 - Dissipation mechanisms / hydrodynamics
 - Attractive forces / adhesion
 - Coulomb friction / covalent bonding
- Energy landscape picture of AQS (Malandro and Lacks)

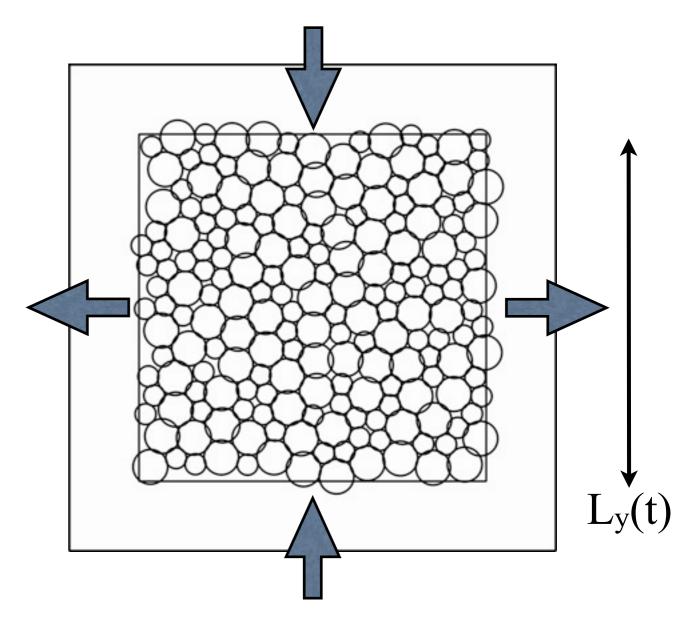


- $t_{thermal} >> t_{shear} >> t_{rearrange}$
- first Temperature to zero, then shear rate to zero.

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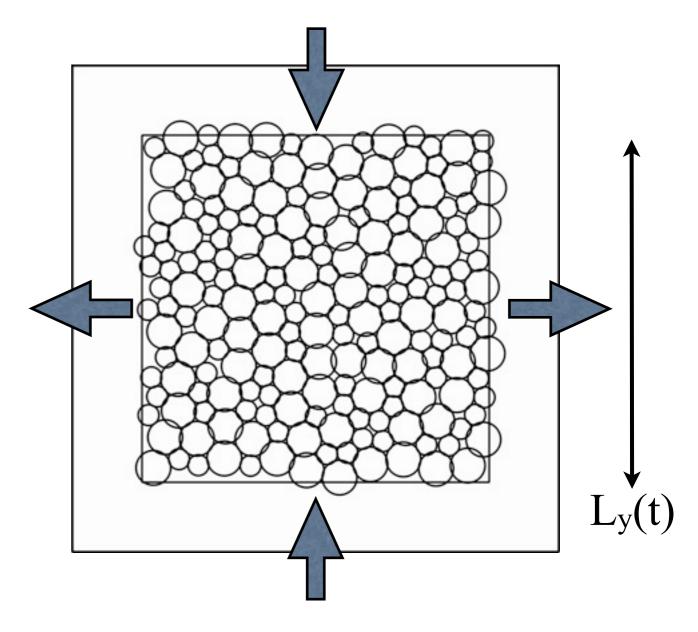
control: $L_y(t)$, $L_x(t)$ conserve area



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• 2D Molecular Dynamics:

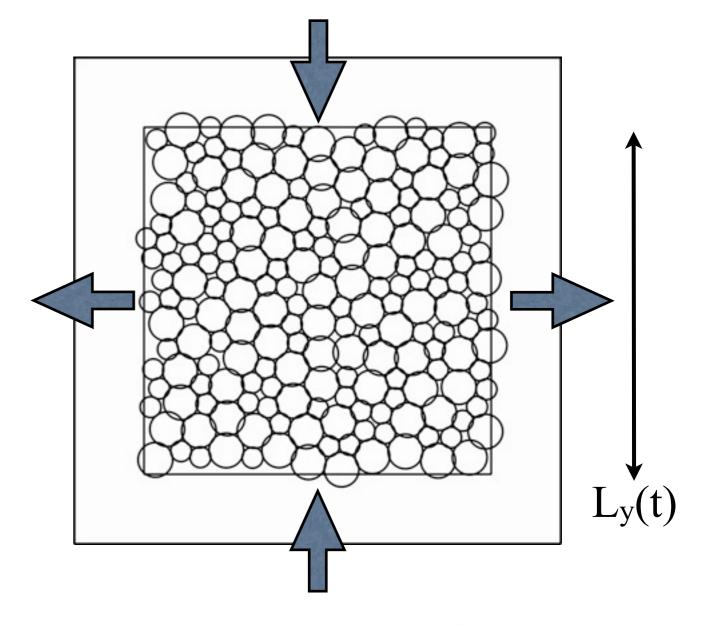
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- 2D Molecular Dynamics:
- binary Lennard-Jones

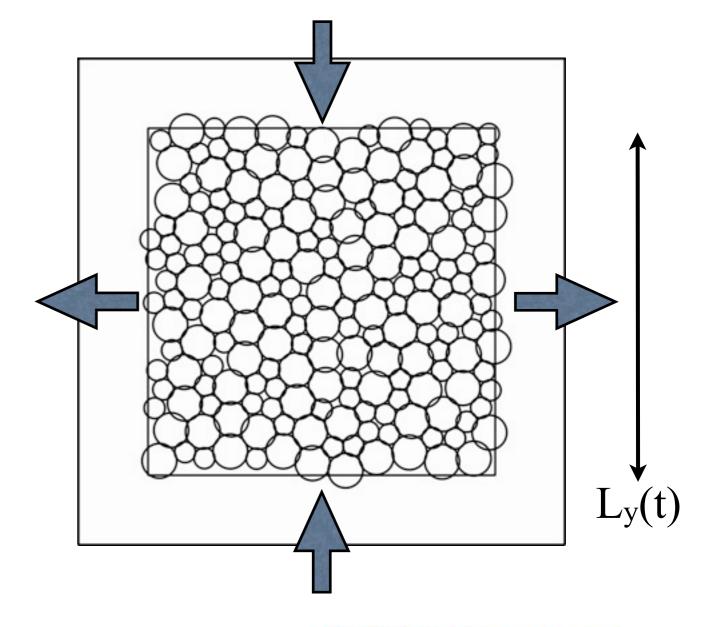
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- 2D Molecular Dynamics:
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- quenched at Pressure=0

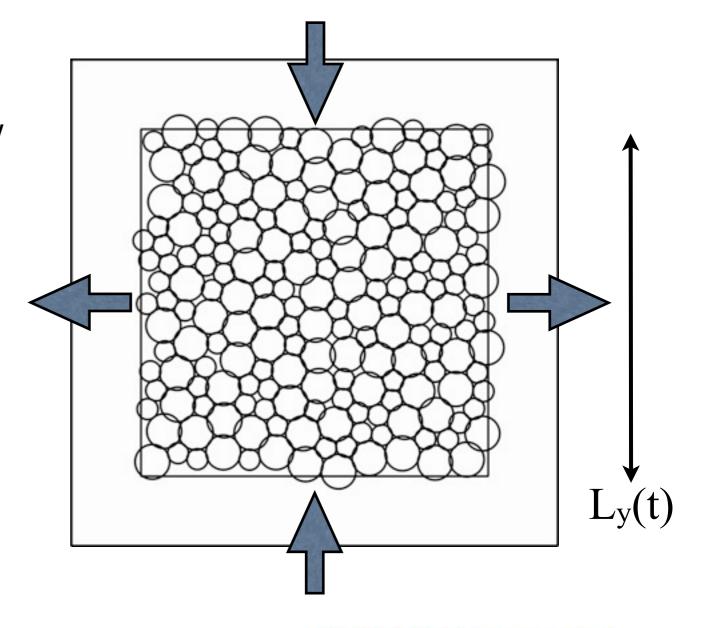
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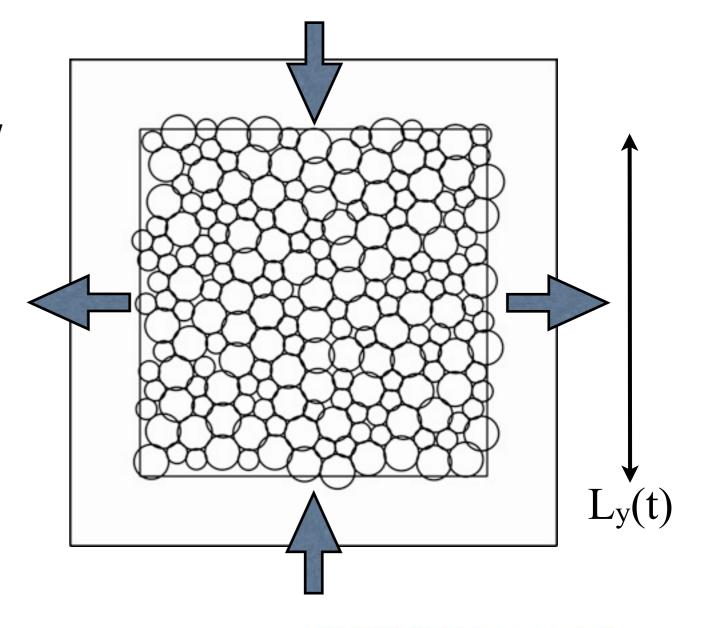
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- 2D Molecular Dynamics:
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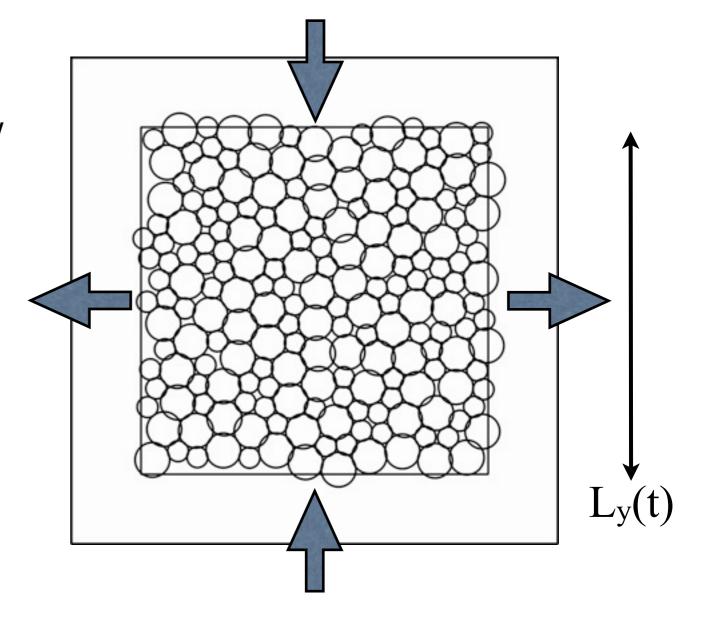
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- periodic boundaries

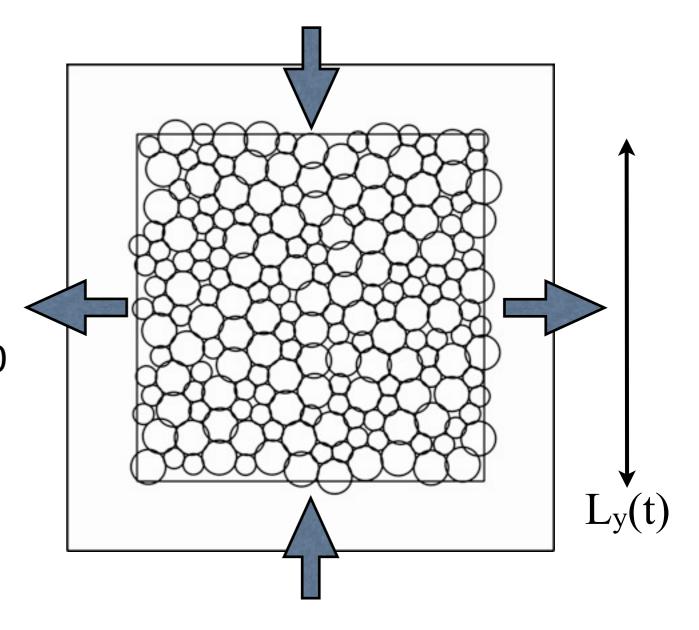
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- system sizes up to 3000x3000
 - ~ 10M particles

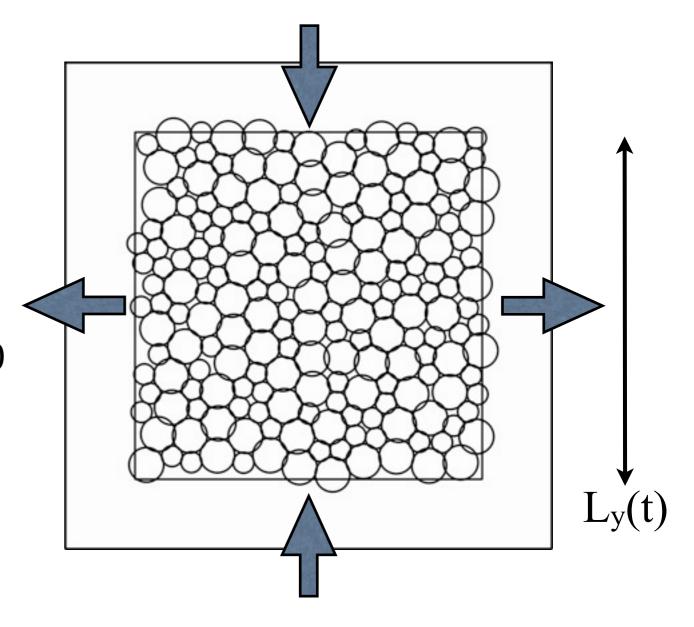
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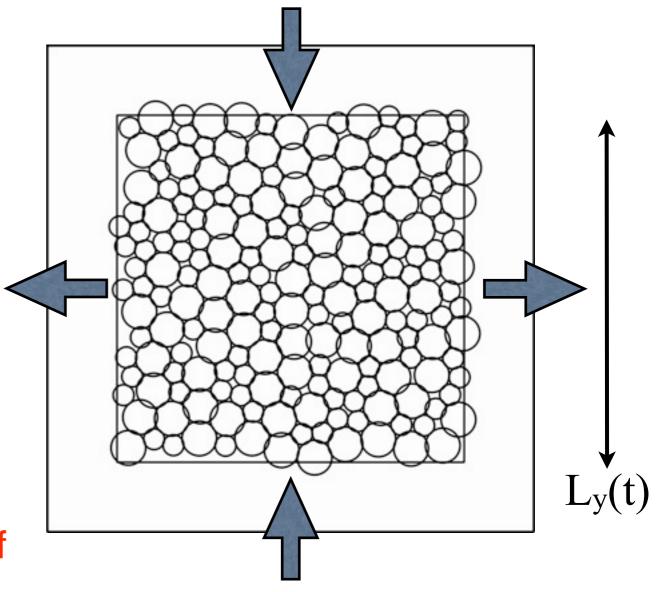


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- Quasi-static limit (about 500 CPU days / run)
- Strain window, Δγ, plays role of time!

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control: $L_y(t)$, $L_x(t)$ conserve area



Local vorticity, ω

For each triangle:

$$\frac{\partial u_i}{\partial x_j} = F_{ij}$$

$$\epsilon_1 = \frac{F_{xx} - F_{yy}}{2}$$

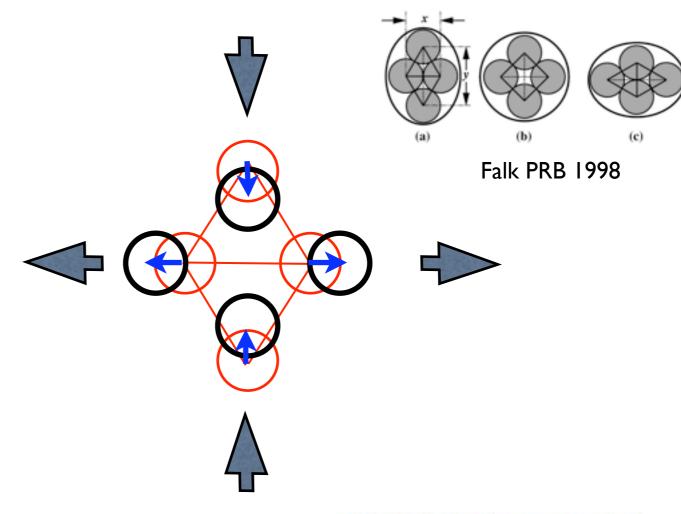
$$\epsilon_2 = \frac{F_{xy} + F_{yx}}{2}$$

Invariants:

$$\epsilon = \sqrt{\epsilon_1^2 + \epsilon_2^2}$$

$$\omega = F_{xy} - F_{yx}$$

"Canonical" atomistic Eshelby shear transformation: pure shear $\epsilon_1 > 0 \epsilon_2 = 0 \omega = 0$



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Local vorticity, ω

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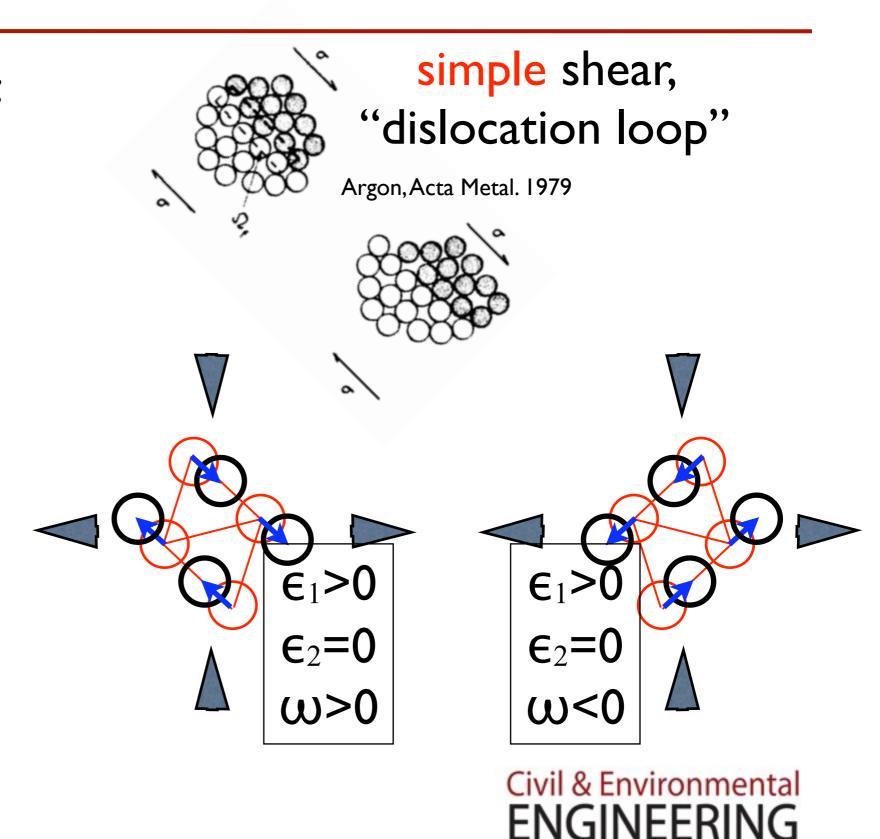
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Correlations in steady state

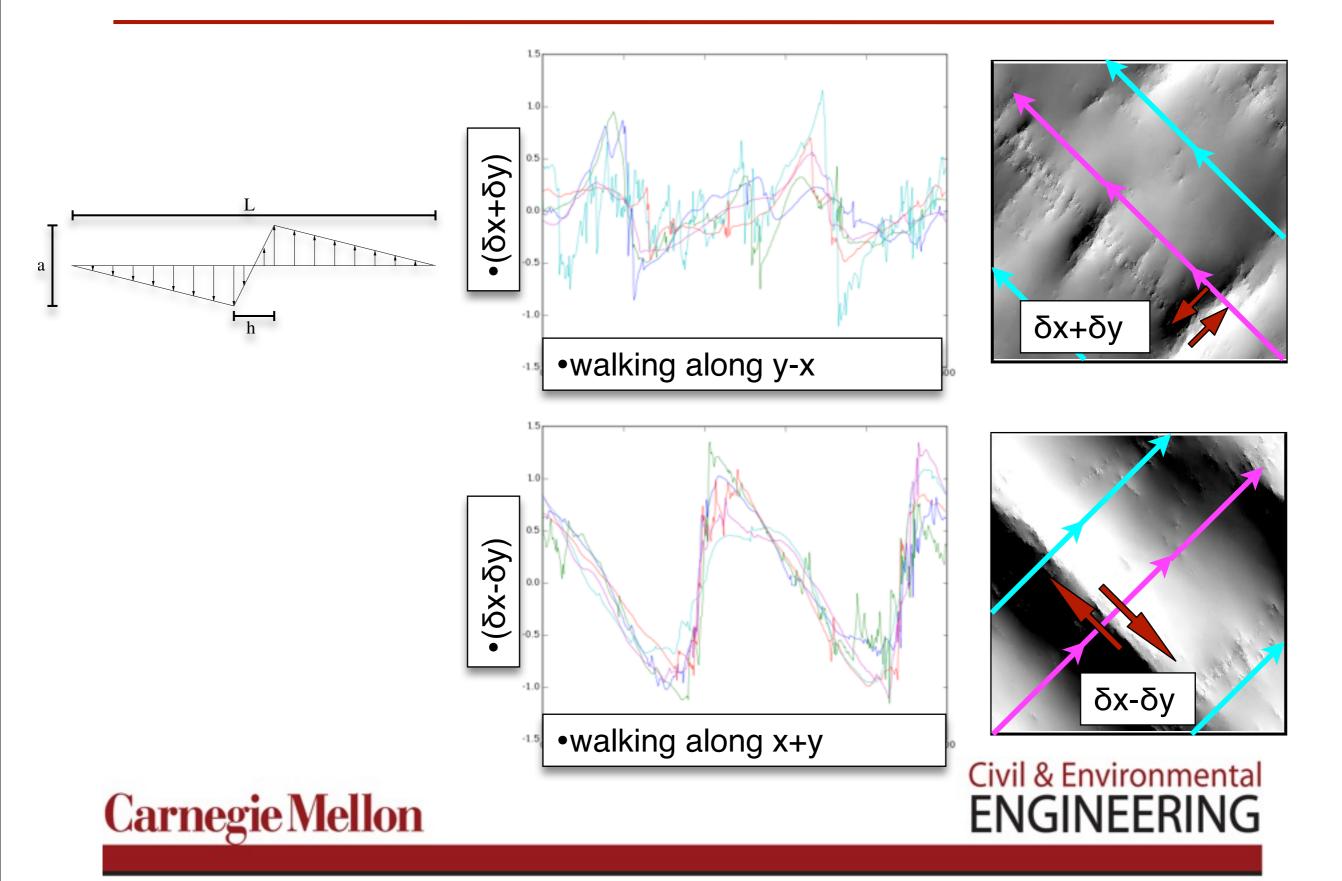
6.0% to 6.1% 6.0% to 6.2% 6.0% to 6.4% γ: $|\Delta r|$ ω Civil & Environmental

ENGINEERING

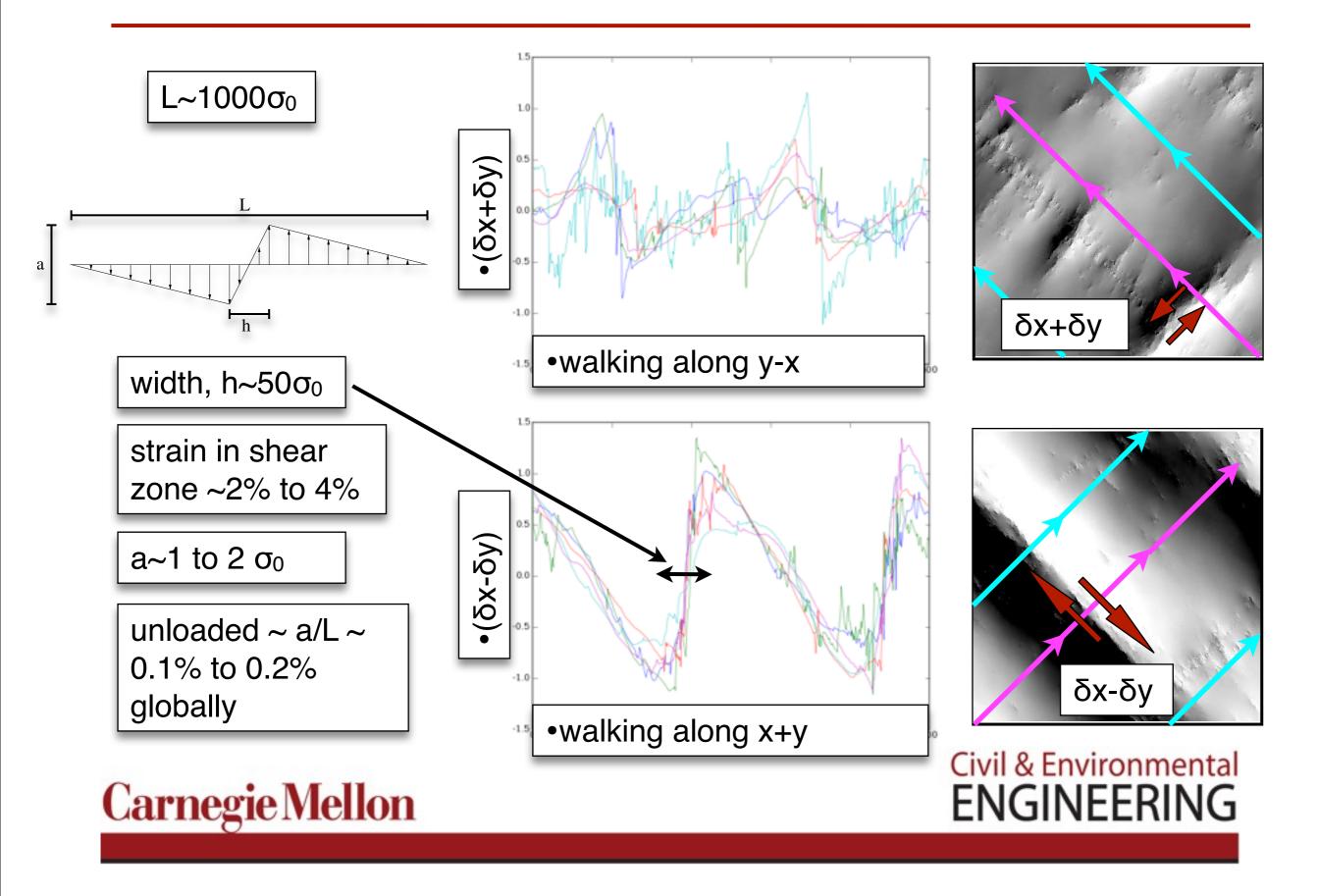
Saturday, June 12, 2010

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Transverse displacement traces (6.1% -> 6.2%)



Transverse displacement traces (6.1% -> 6.2%)



•System is either:

- active along δx=δy
- active along $\delta x = -\delta y$
- or quiescent

+2

+1

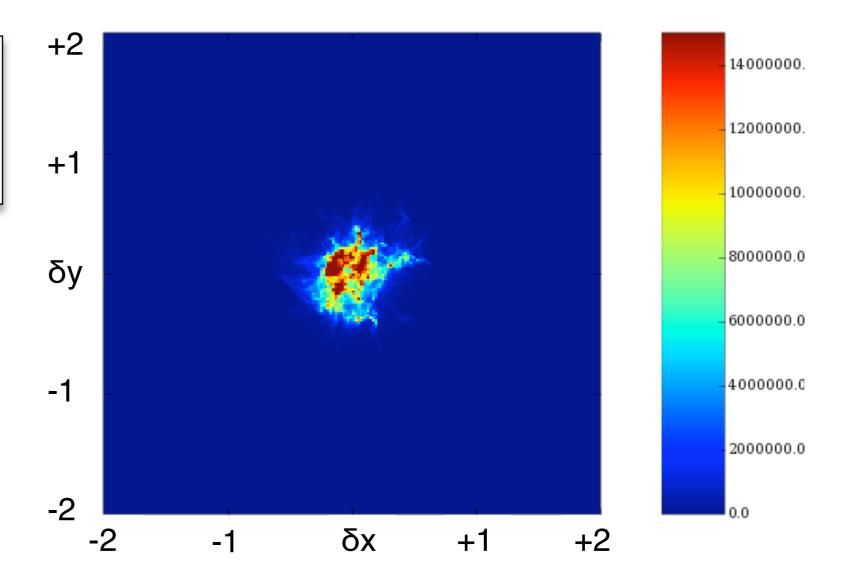
δу

-1

-2 -2 -1 δx +1 +2

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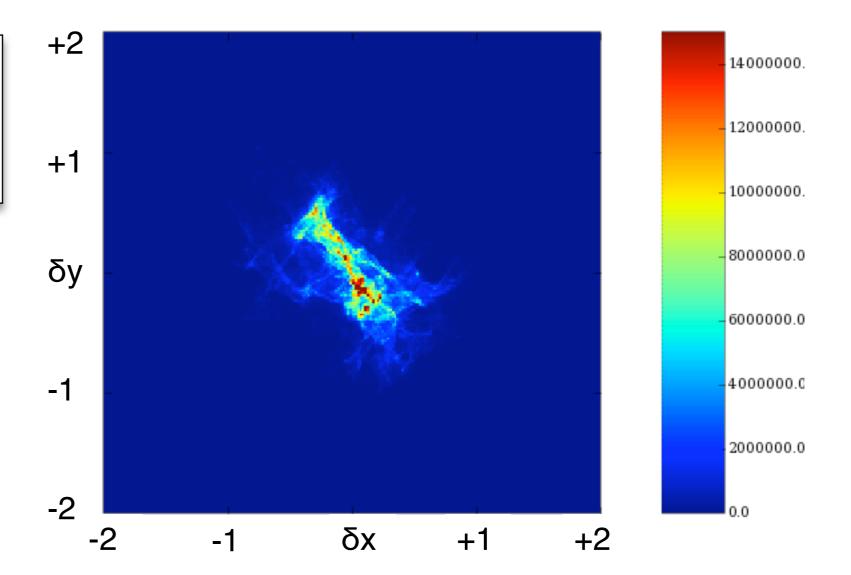
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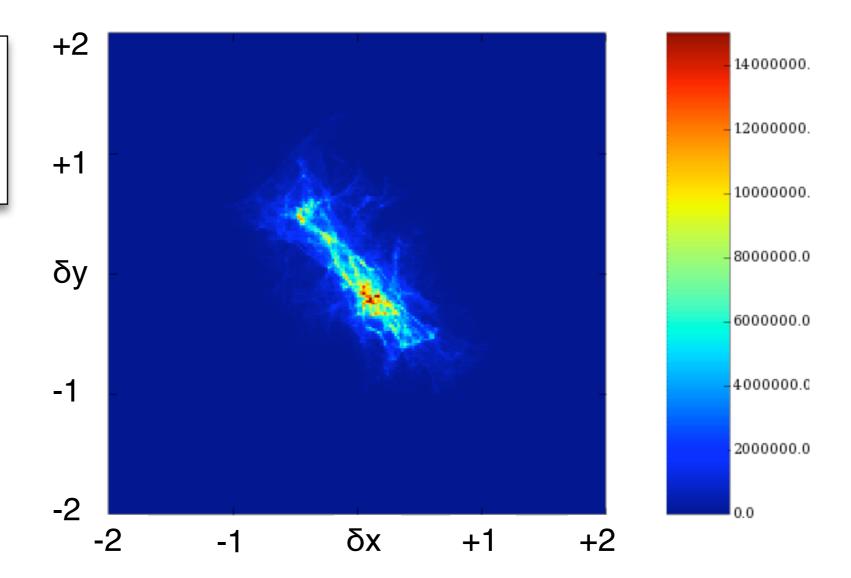


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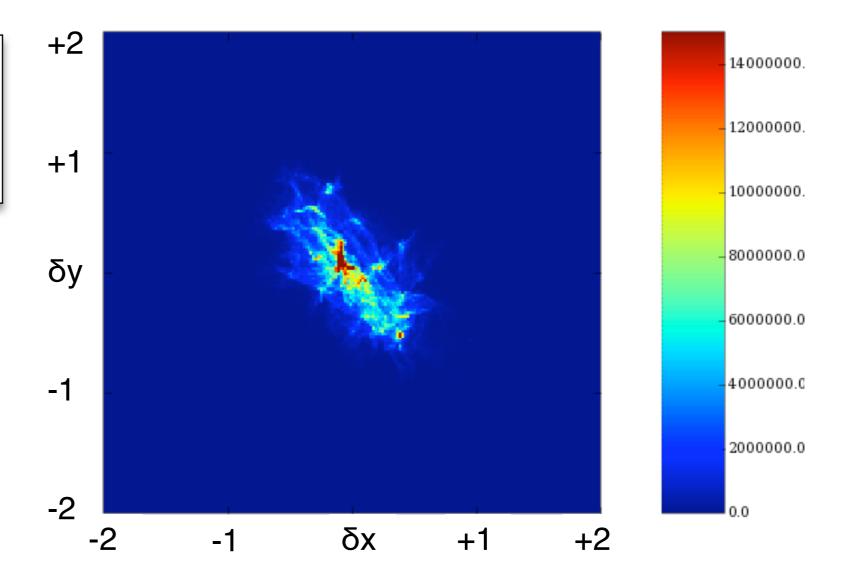


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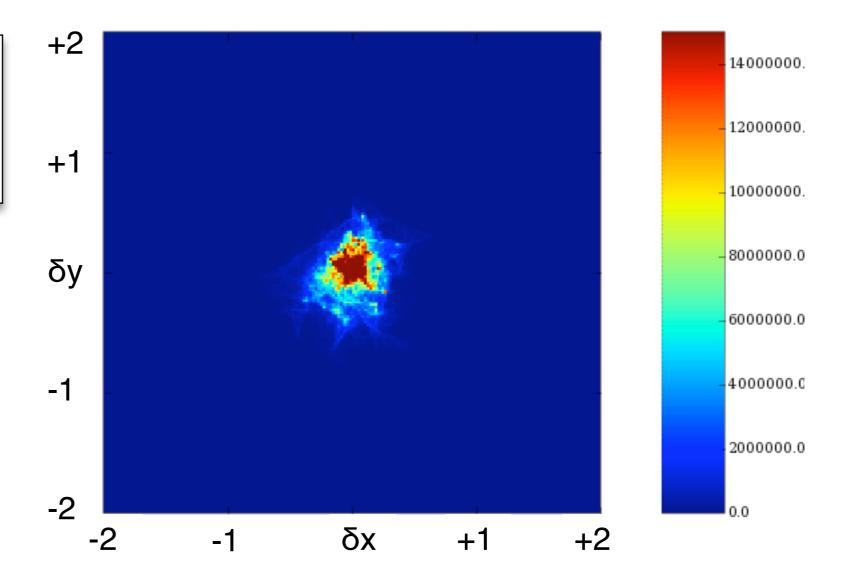
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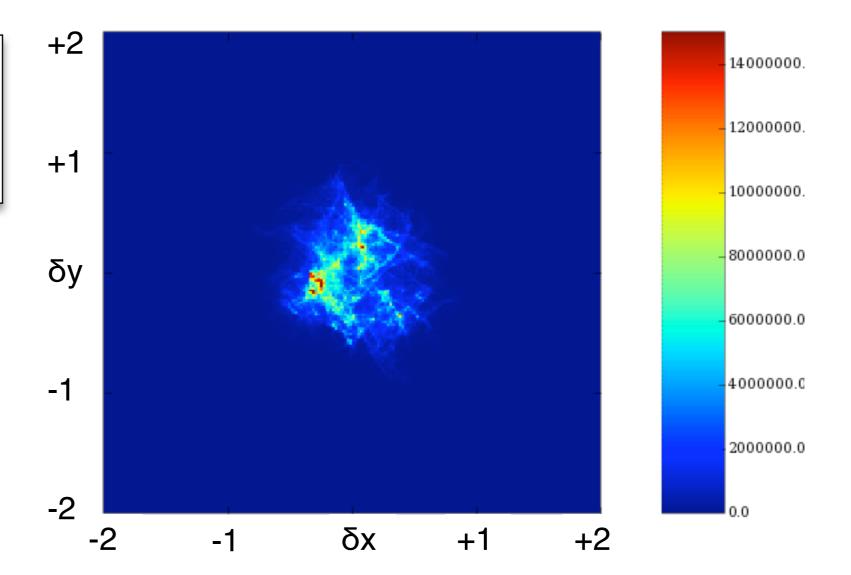
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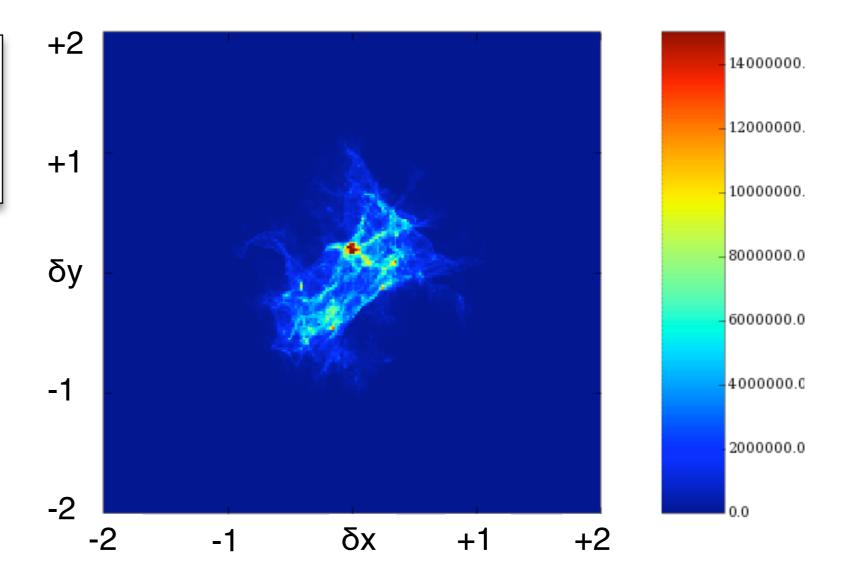


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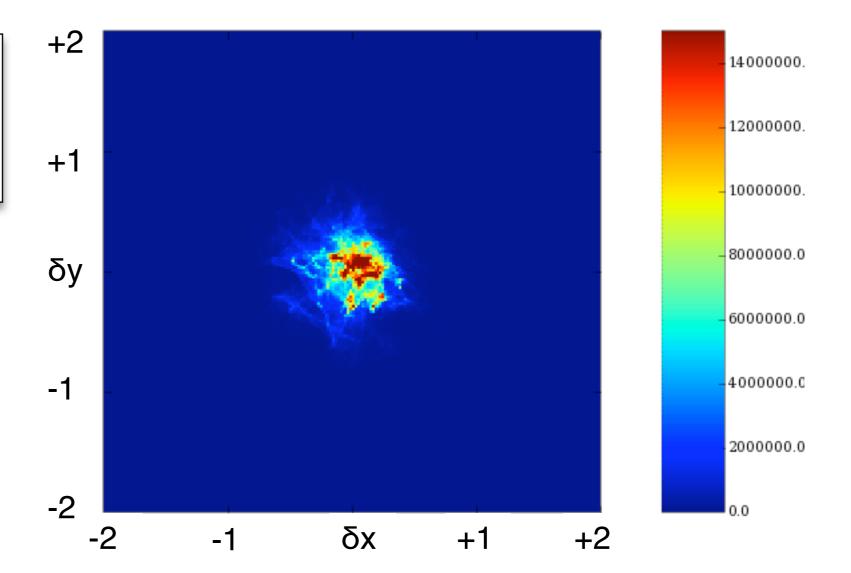
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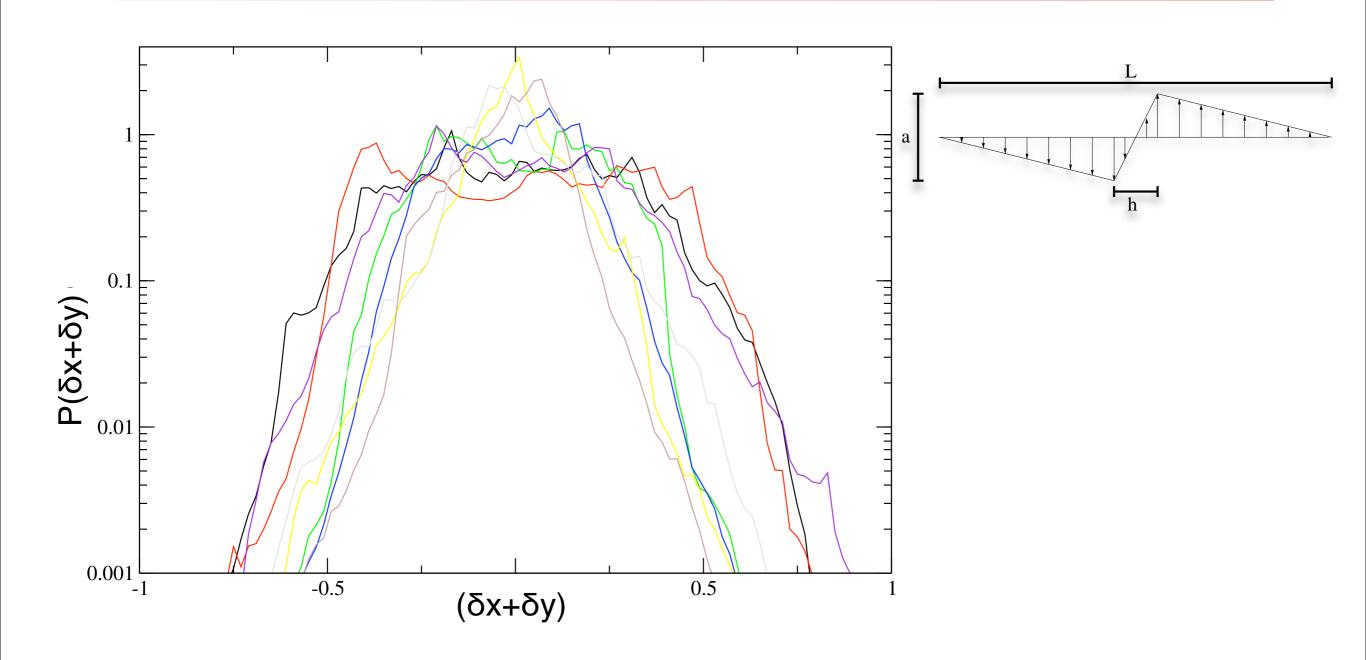


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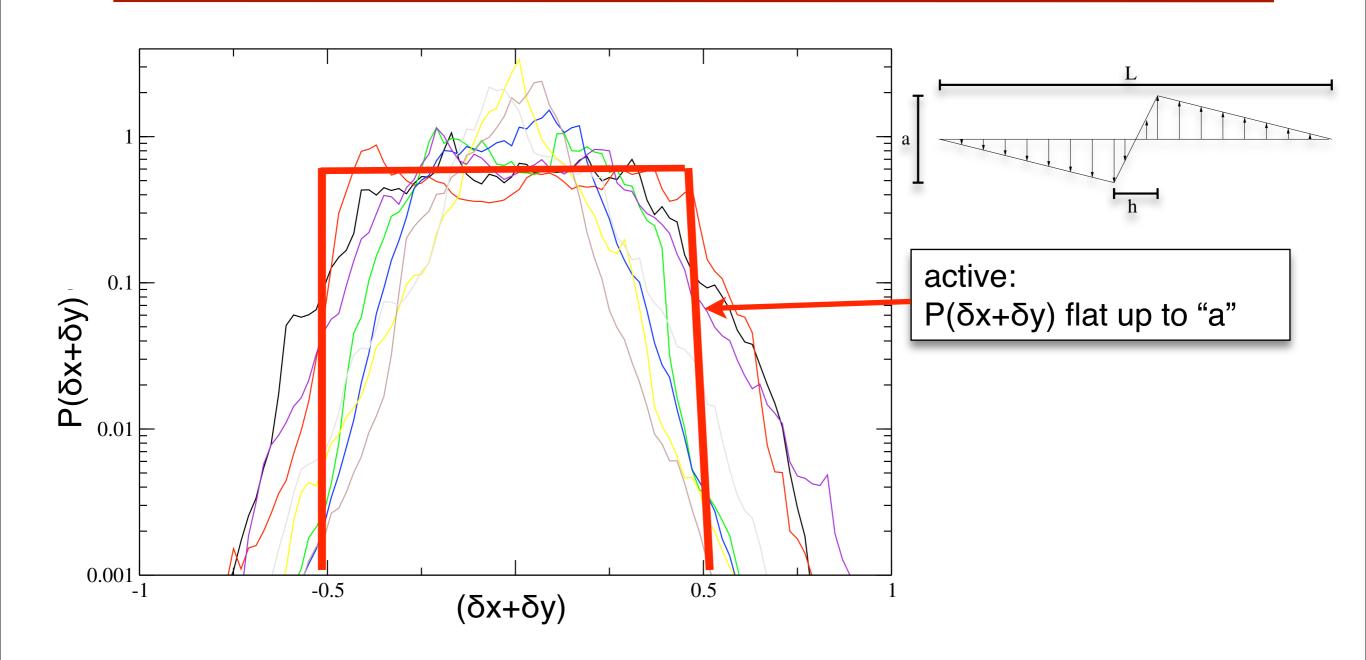






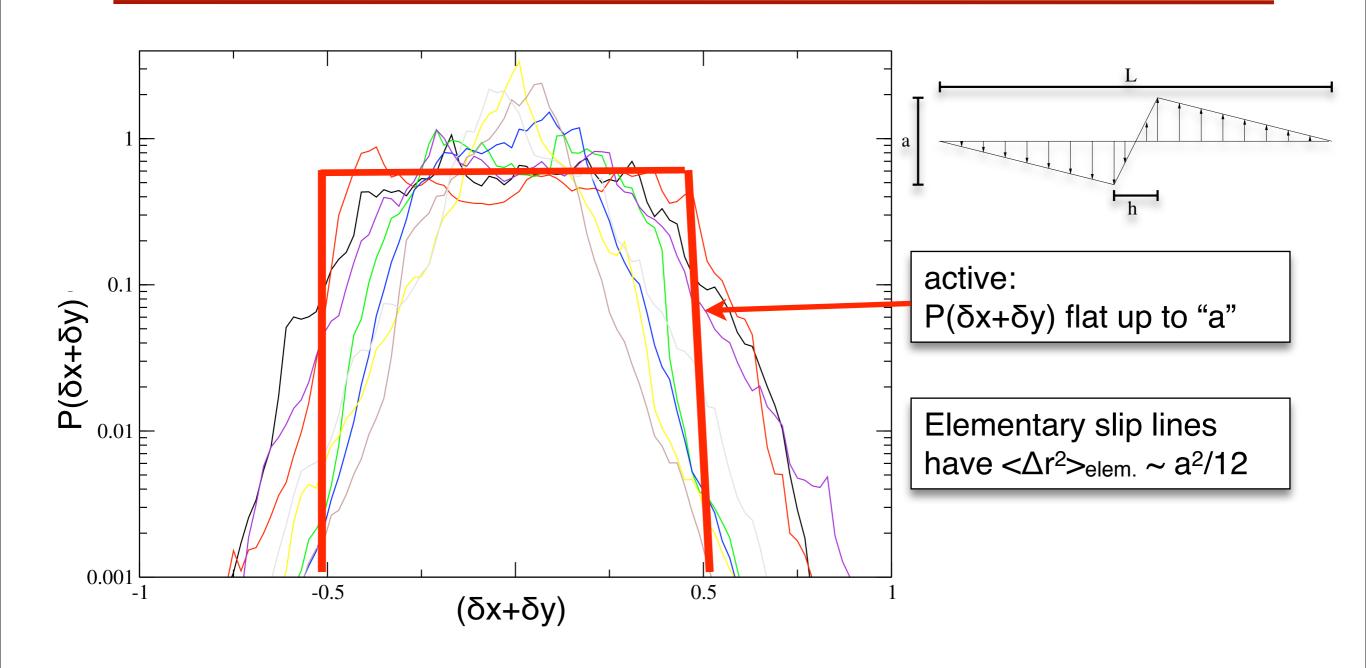






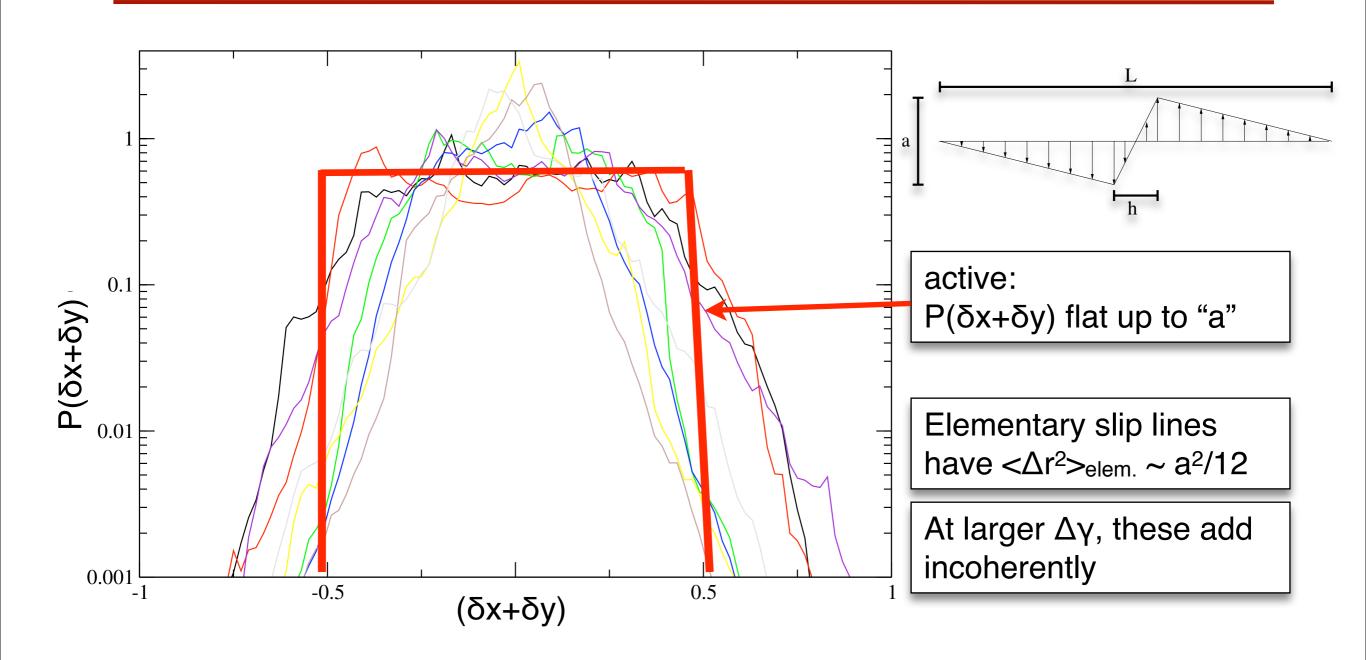






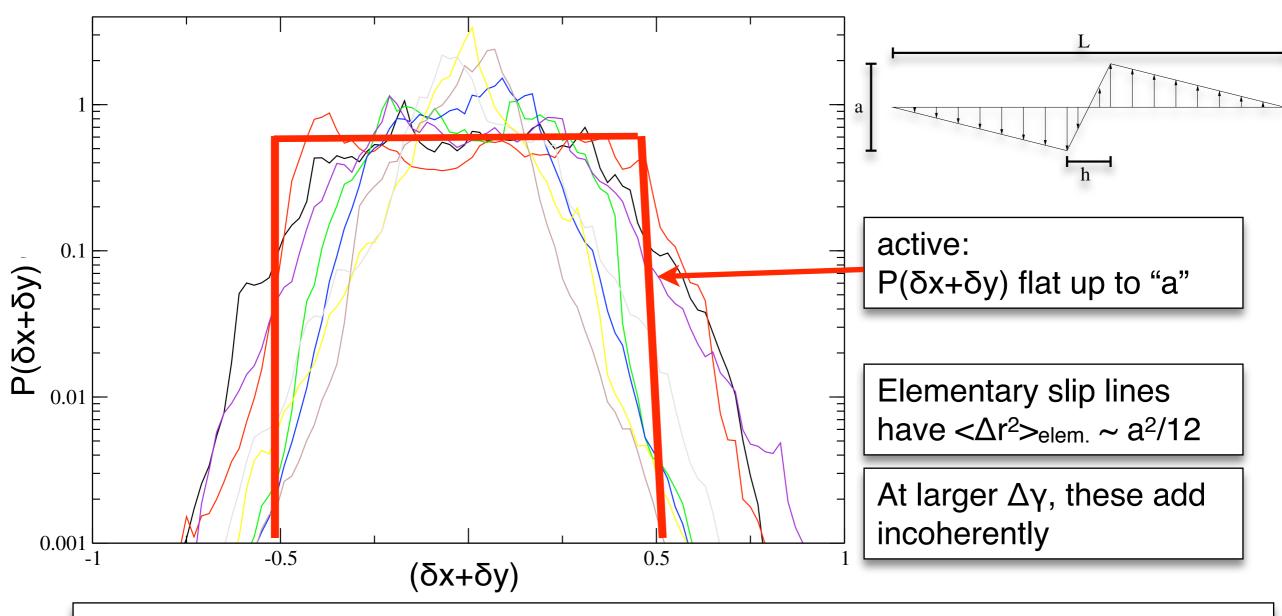








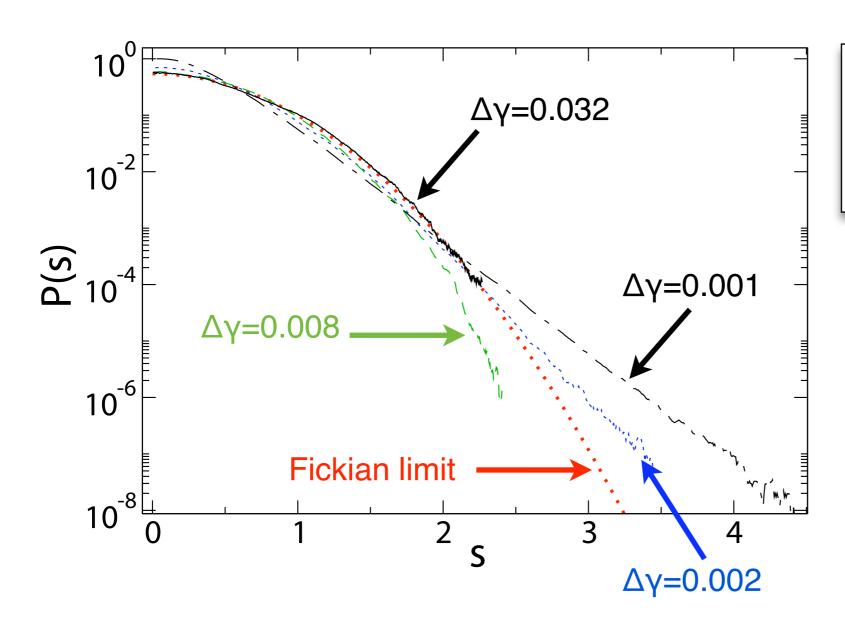




 $<\!\!\Delta r^2\!\!> = \{N_{events}\} \, \{<\!\!\Delta r^2\!\!>_{elem.}\} = \{\Delta\gamma/(a/L)\} \, \{a^2/12\} = La/12 \, \Delta\gamma$



$P(\Delta r)$ for various $\Delta \gamma$



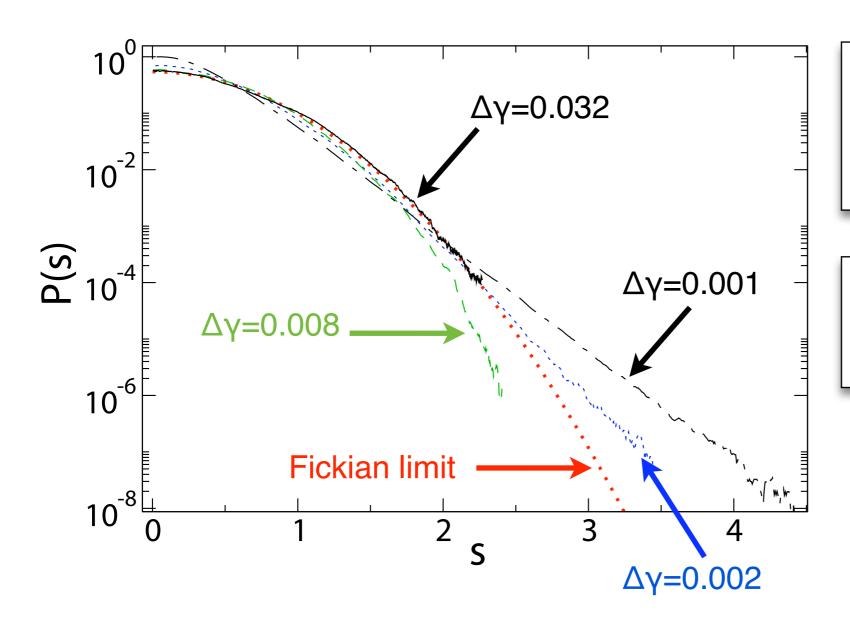
All distributions rescaled by Fickian expectation:

$$s = \langle \Delta r^2 \rangle / \Delta \gamma$$





$P(\Delta r)$ for various $\Delta \gamma$



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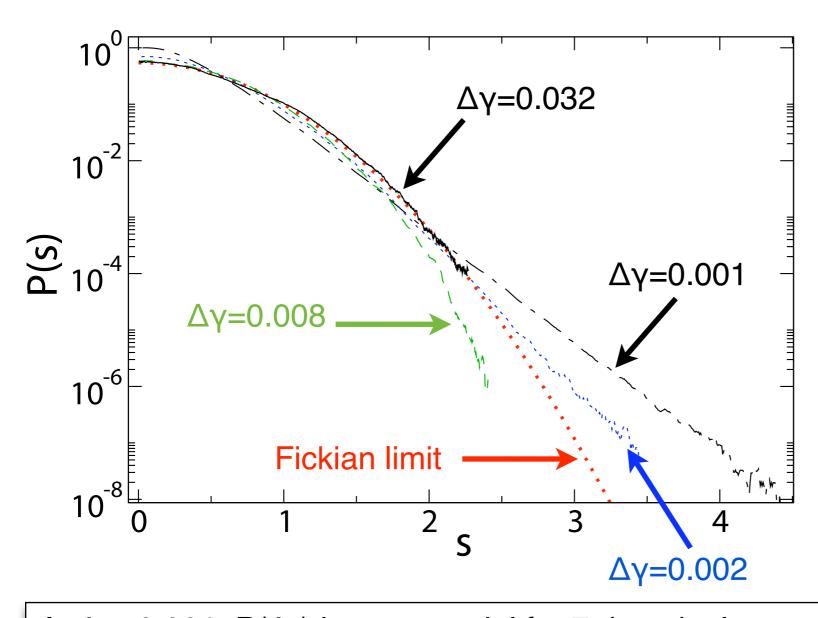
$$s = \langle \Delta r^2 \rangle / \Delta \gamma$$

Looks Fickian but:

- spatial correlations
- • $<\Delta r^2>/\Delta \gamma$ depends on L

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$P(\Delta r)$ for various $\Delta \gamma$



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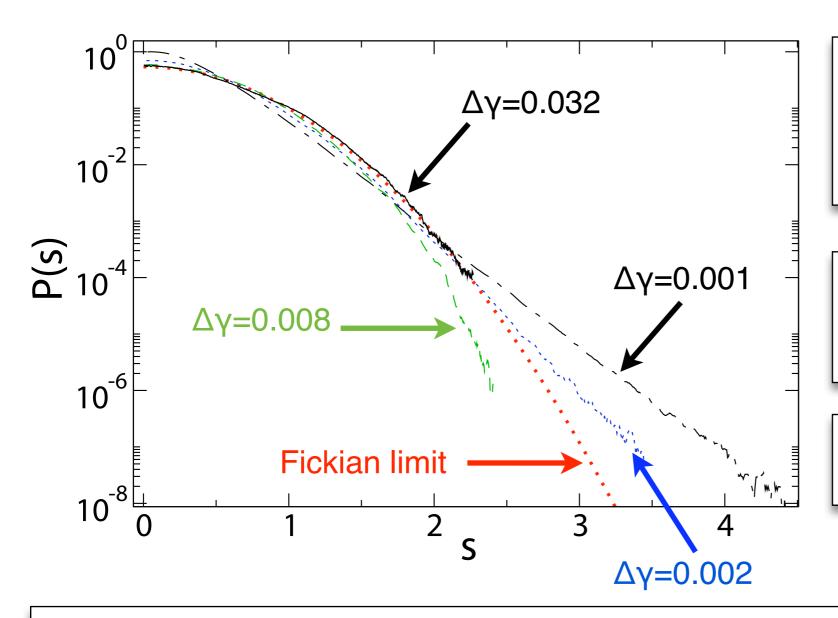
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At $\Delta\gamma$ =0.001, P(Δr) is exponential for 7 decades! Crossover to Fickian ($\Delta\gamma$ ~0.032) consistent with thick bands filling space



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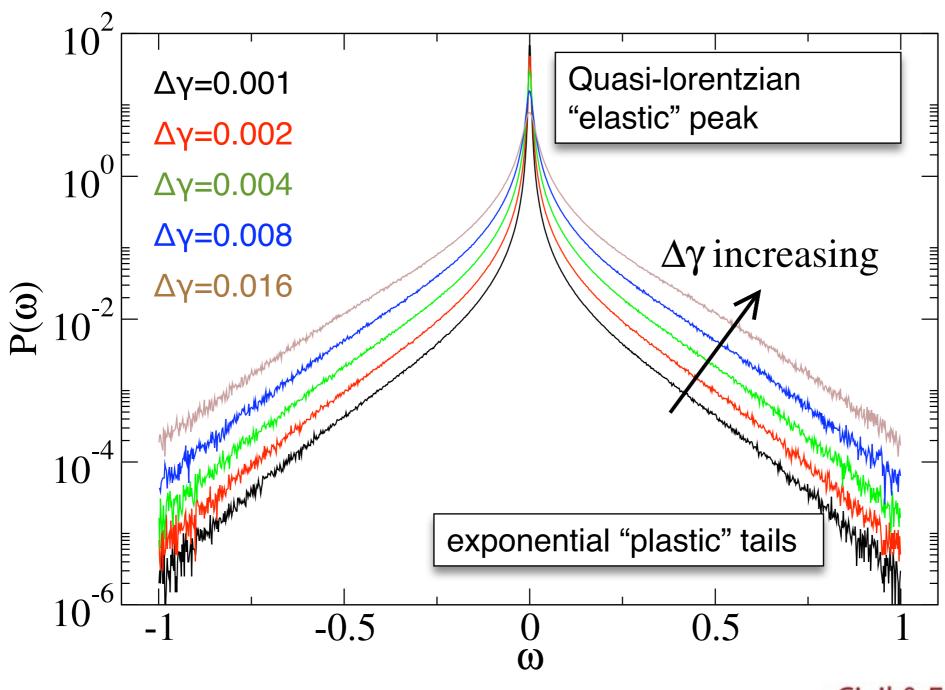
•Slip line argument:

 $a=(12s/L) \sim 0.7\sigma_0$

At $\Delta\gamma$ =0.001, P(Δr) is exponential for 7 decades! Crossover to Fickian ($\Delta\gamma$ ~0.032) consistent with thick bands filling space

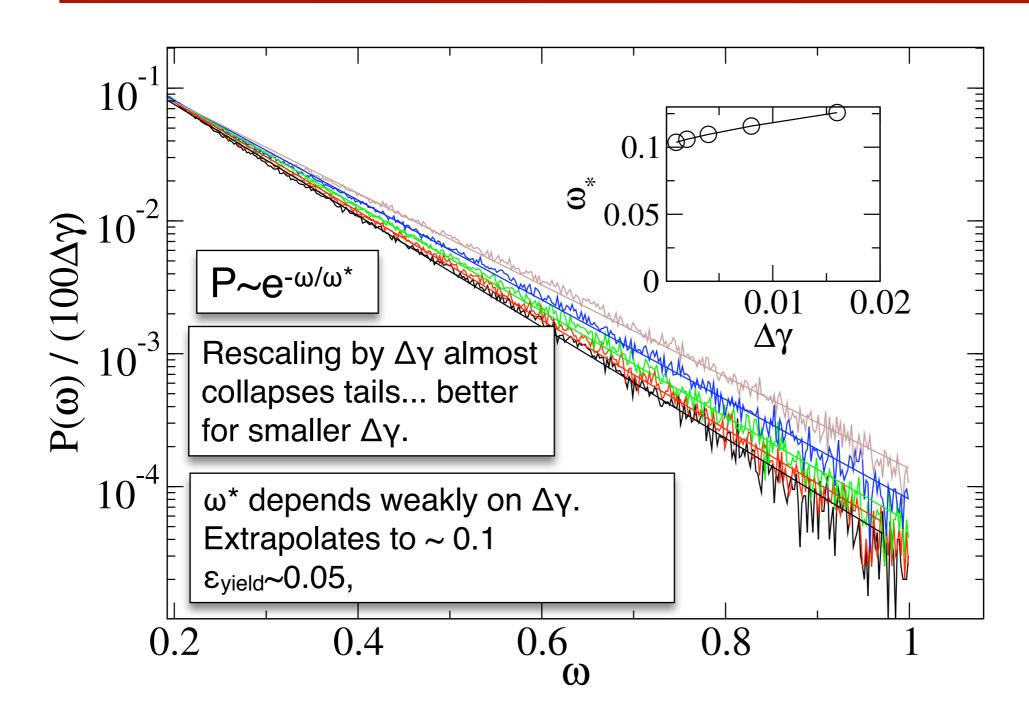


$P(\omega;\Delta\gamma)$



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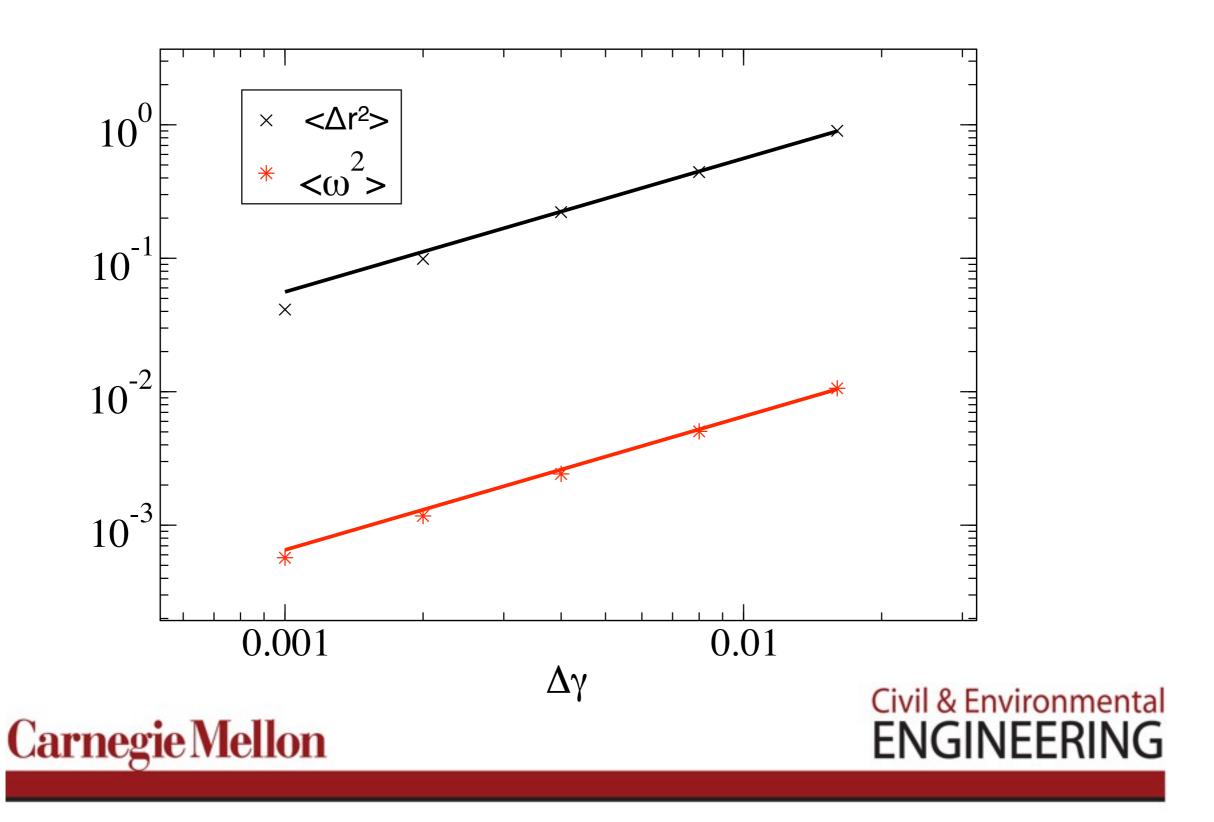
P(ω; Δ γ). Scale by Δ γ , fit to $e^{-ω/ω*}$



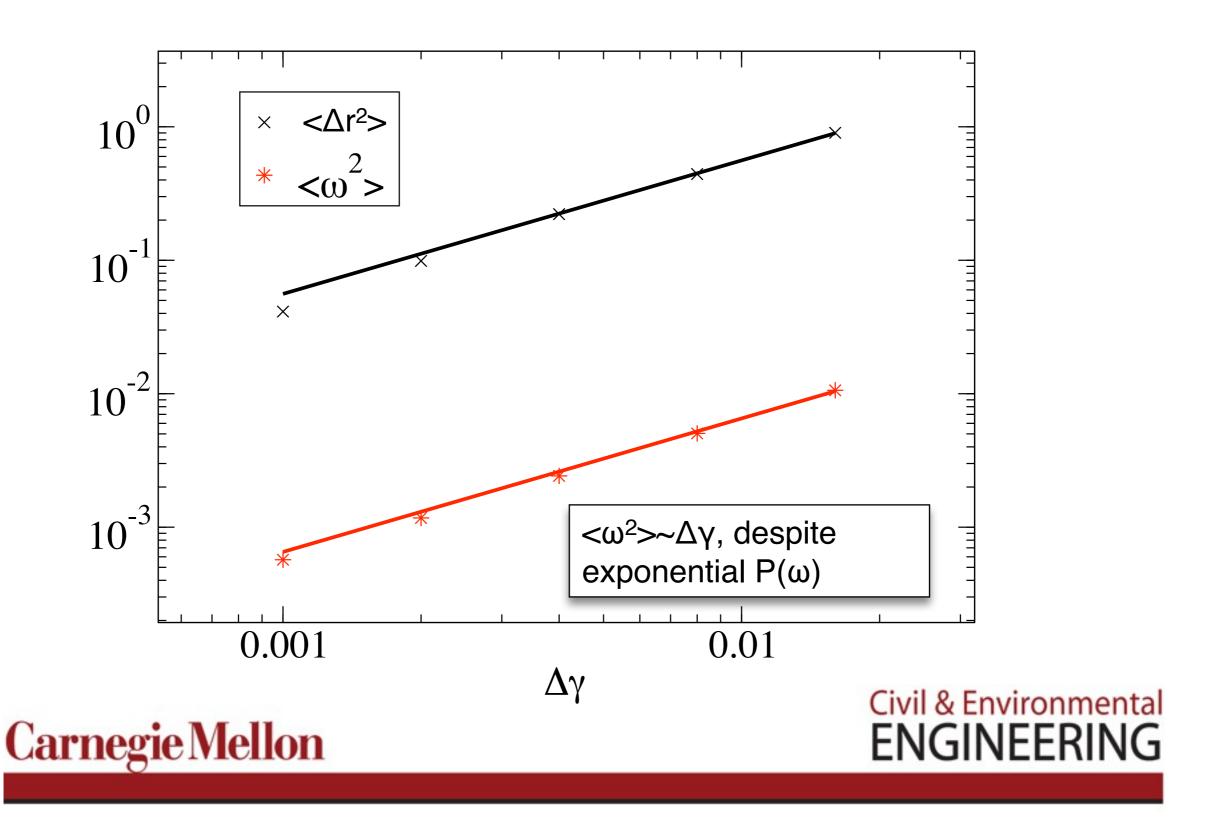




RMS ω vs $\Delta\gamma$



RMS ω vs $\Delta\gamma$







• Slip in bands: $a\sim\sigma_0$, $h\sim50\sigma_0$, $\gamma_{band}\sim1\%$ (for L~1000)





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- (system size dependent) "time" scale $\Delta \gamma = a/L \sim 1/1000 \sim 0.001$





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- A flat "elementary" $P(\Delta r)$ gives: $D_{eff} = \langle \Delta r^2 \rangle / \Delta \gamma = (La/12)$





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- $<\omega^2>\sim\Delta\gamma$, BUT, P(ω) highly non-Gaussian: P \sim e ω/ω^*



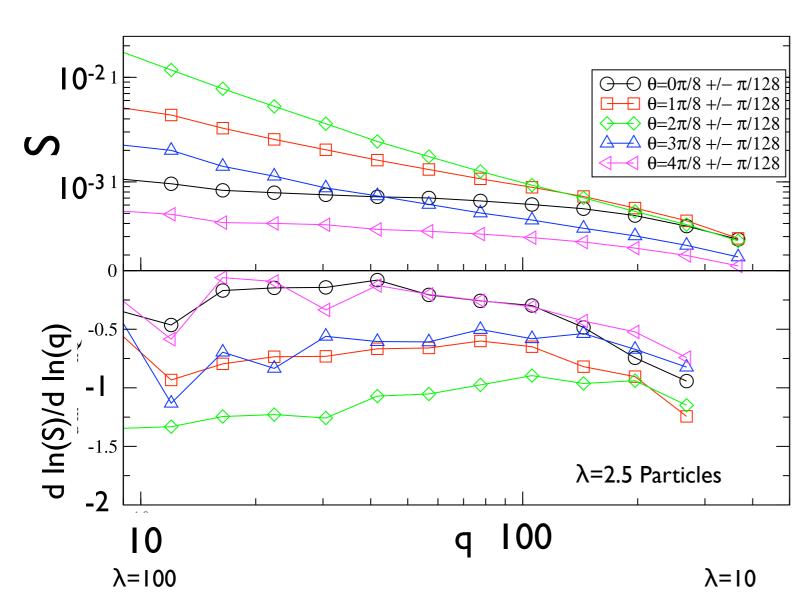


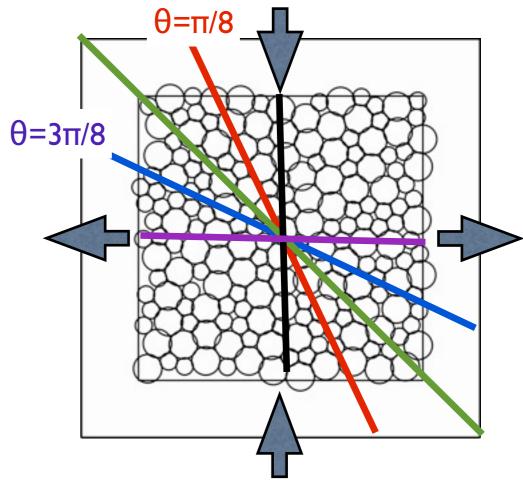
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- $<\omega^2>\sim\Delta\gamma$, BUT, P(ω) highly non-Gaussian: P \sim e ω/ω^*
- ω^* ~0.1 compatible with yield strain ϵ_{yield} ~0.05





Structure factor for $\Delta \gamma = 0.04$ $S(\vec{q}) = \left| \int \omega(\vec{r}) exp[i\vec{q} \cdot \vec{r}] dr \right|^2$





 $\theta=\pi/8$ and $\theta=3\pi/8$ have same shear stress, different normal stress.

$$S(q;\theta)=A(\theta)q^{-\alpha(\theta)}$$

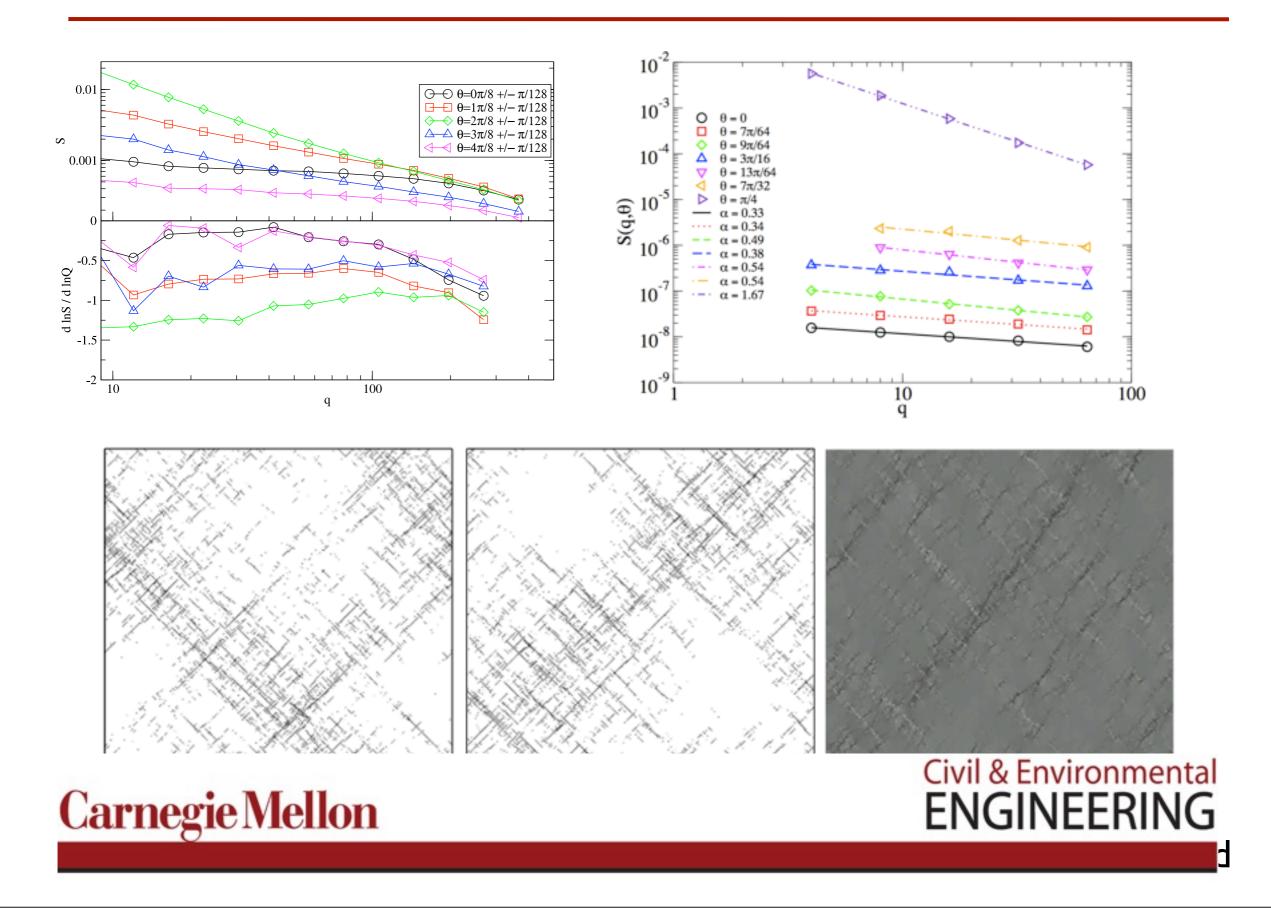
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α depends on angle!

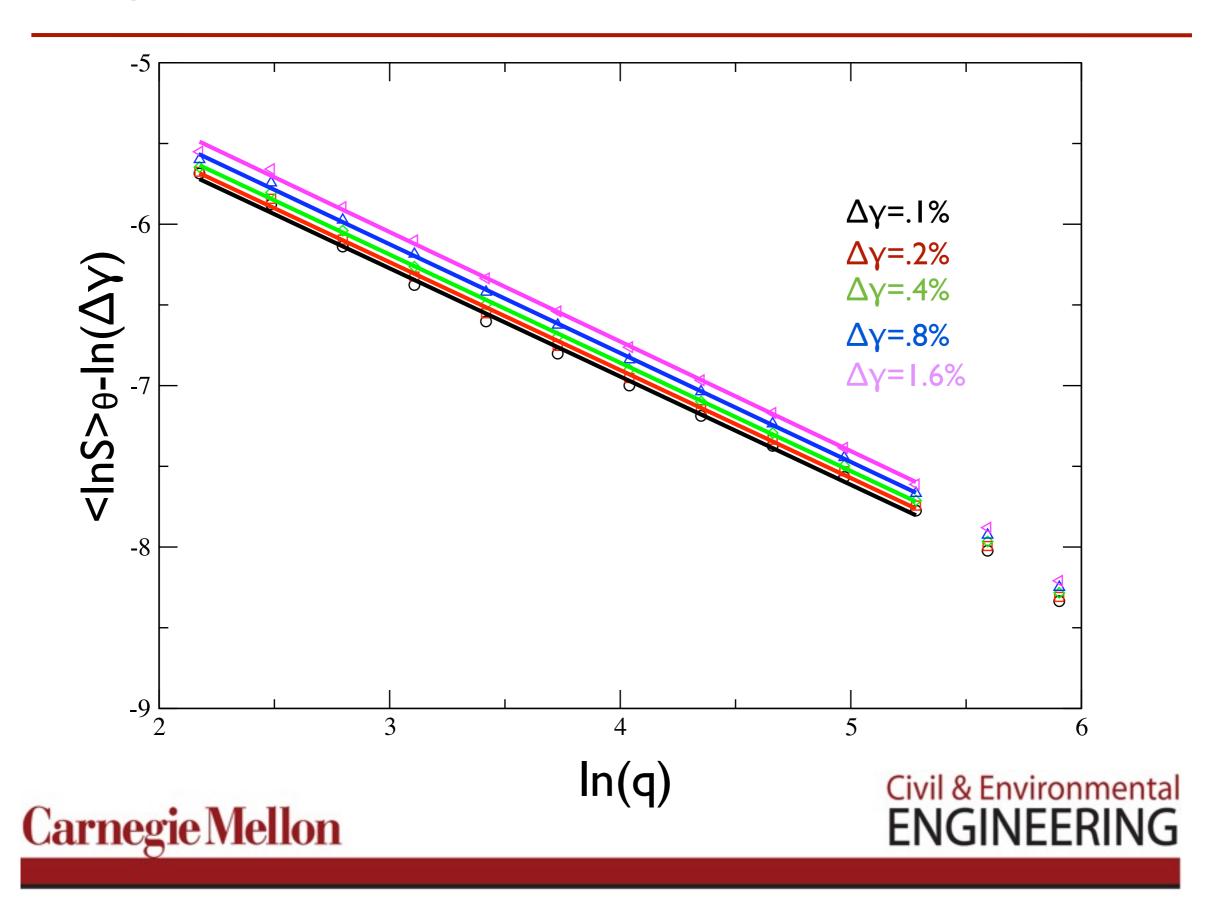
α: has "shear" symmetry

θ: does not

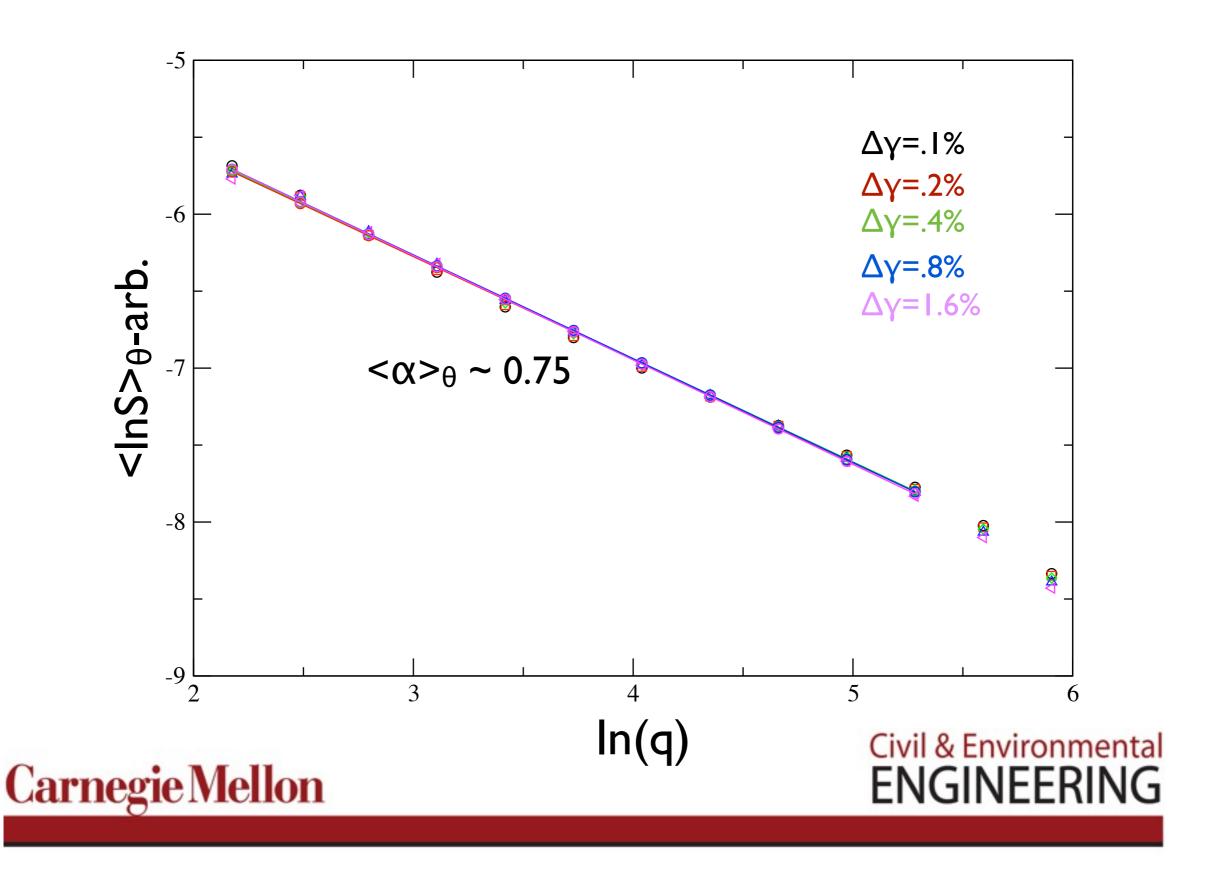
Compare to Talamali et. al. (Vandembroucq talk)



<LogS $>_{\theta}$ scaled by $\Delta\gamma$

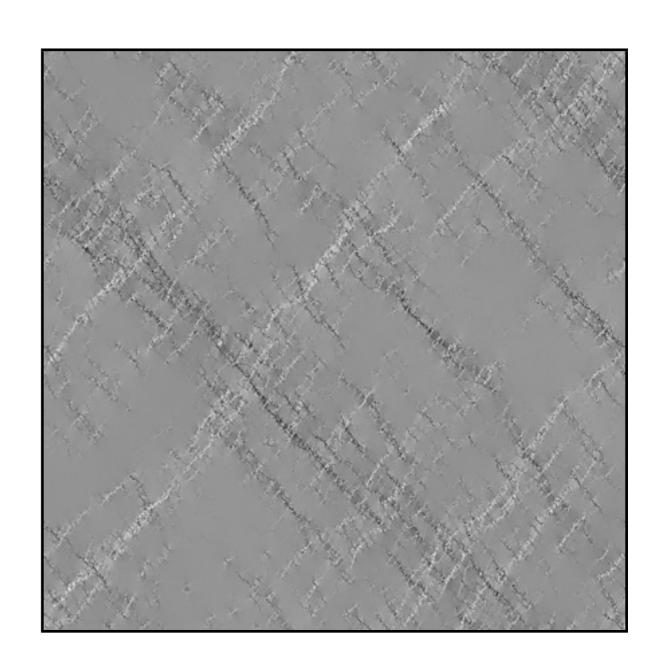


<LogS>_θ best-rescaling



Summary: Spatial structure of strain

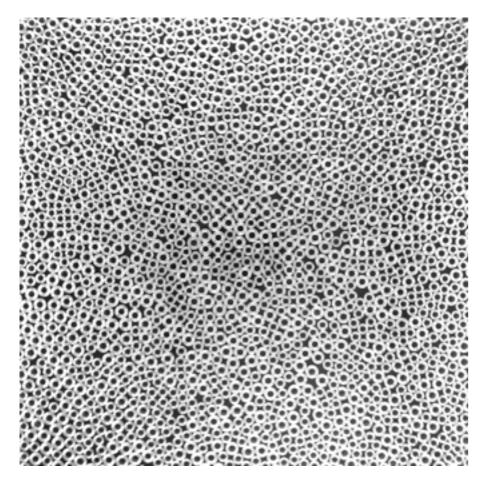
- Measured vorticity, ω , for various, $\Delta \gamma$
- In steady state, $S(q,\theta)=A(\theta)q^{\alpha}$
- α has "shear symmetry"
- $A(\theta)$: Mohr-Coulomb effect
- $S/\Delta\gamma$ collapse implies: ω is decorrelated



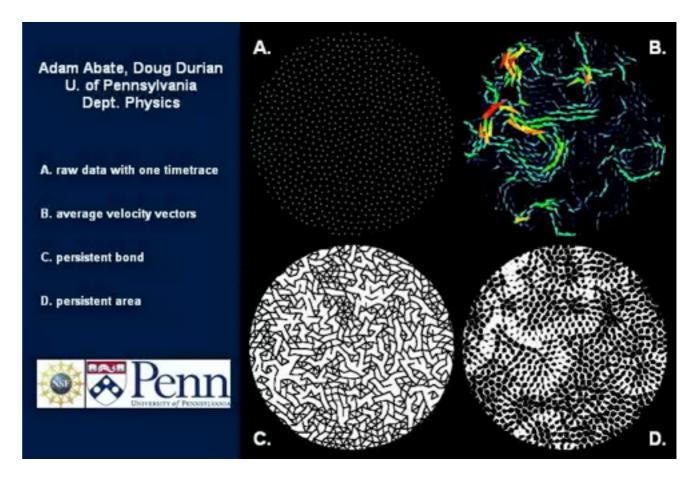
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Jammed systems



From F. Lechenault

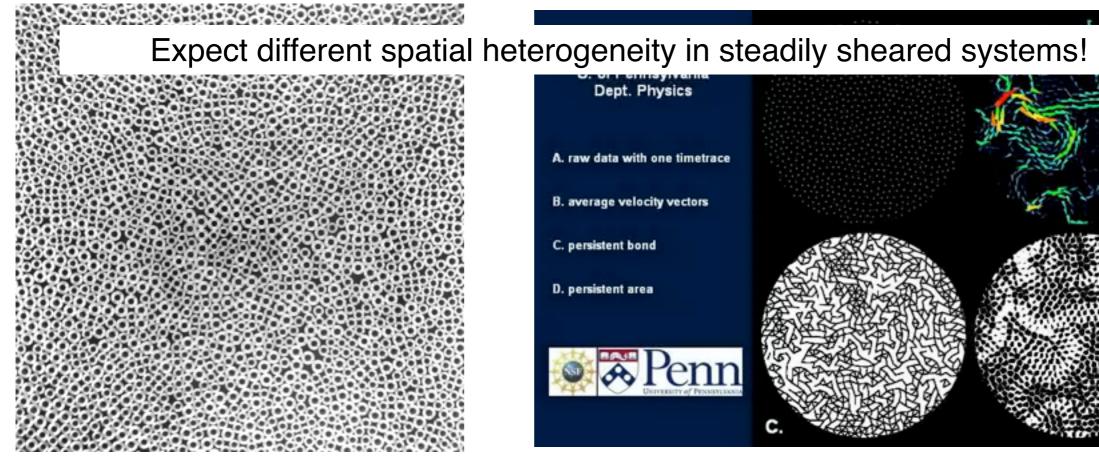


From A. Abate





Jammed systems

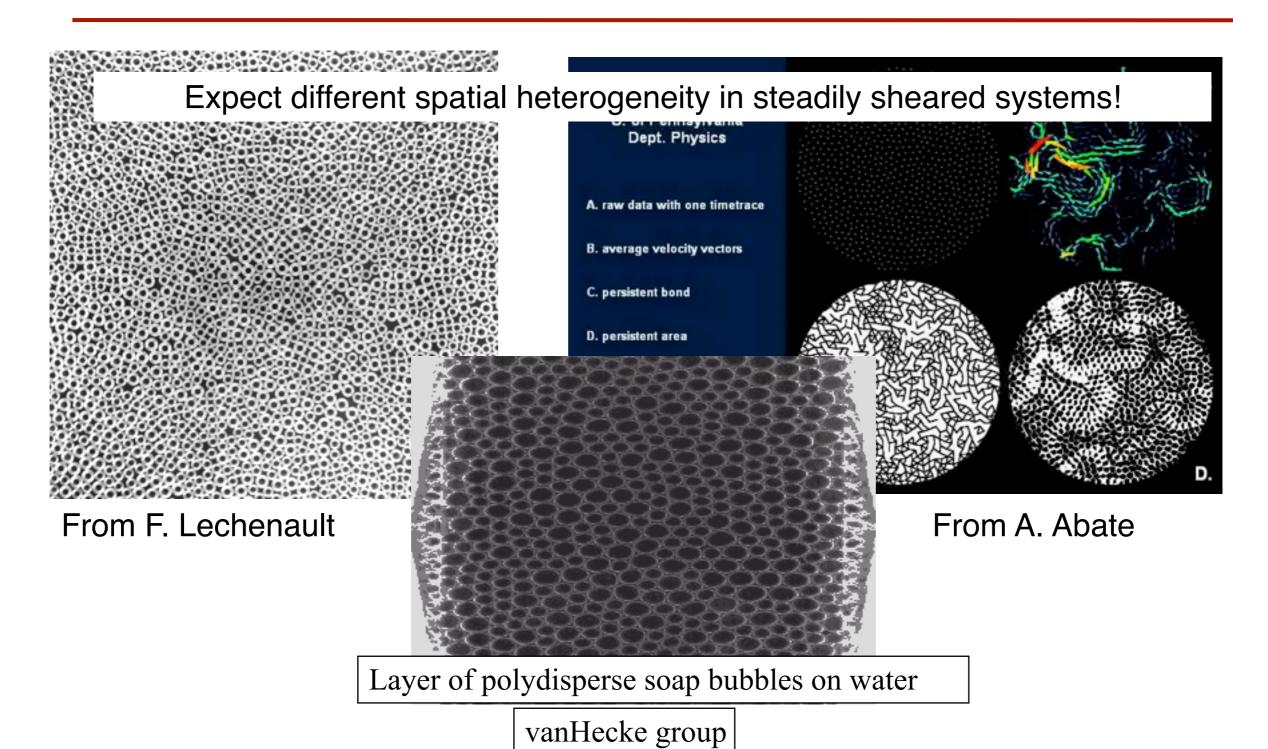


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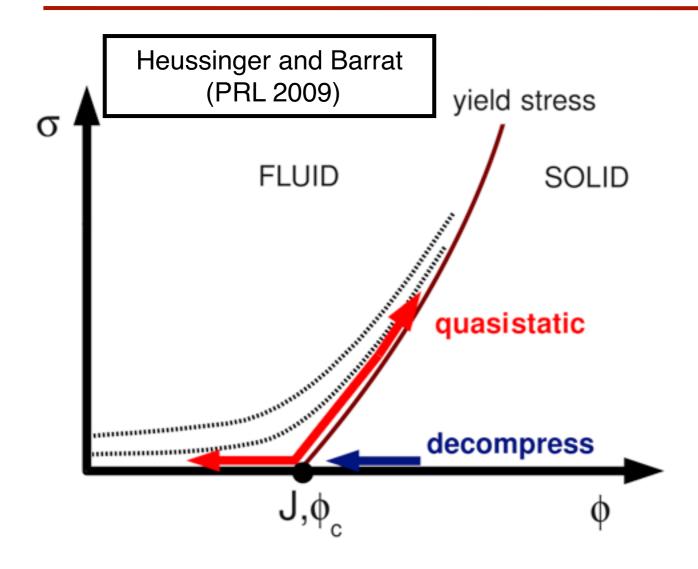


Jammed systems



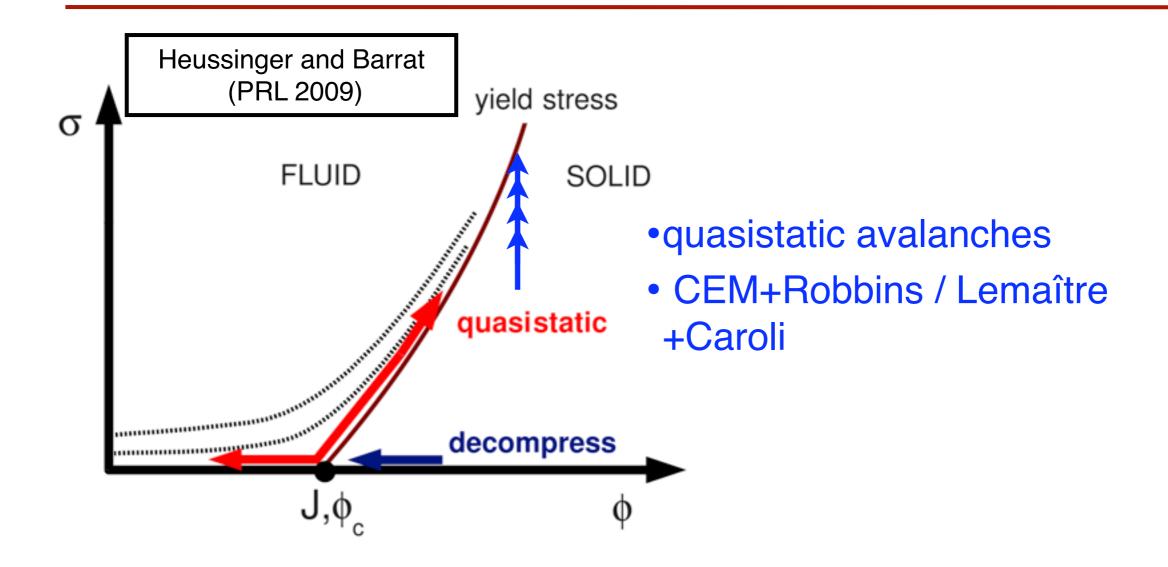
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Jamming and critical scaling at ϕ_c



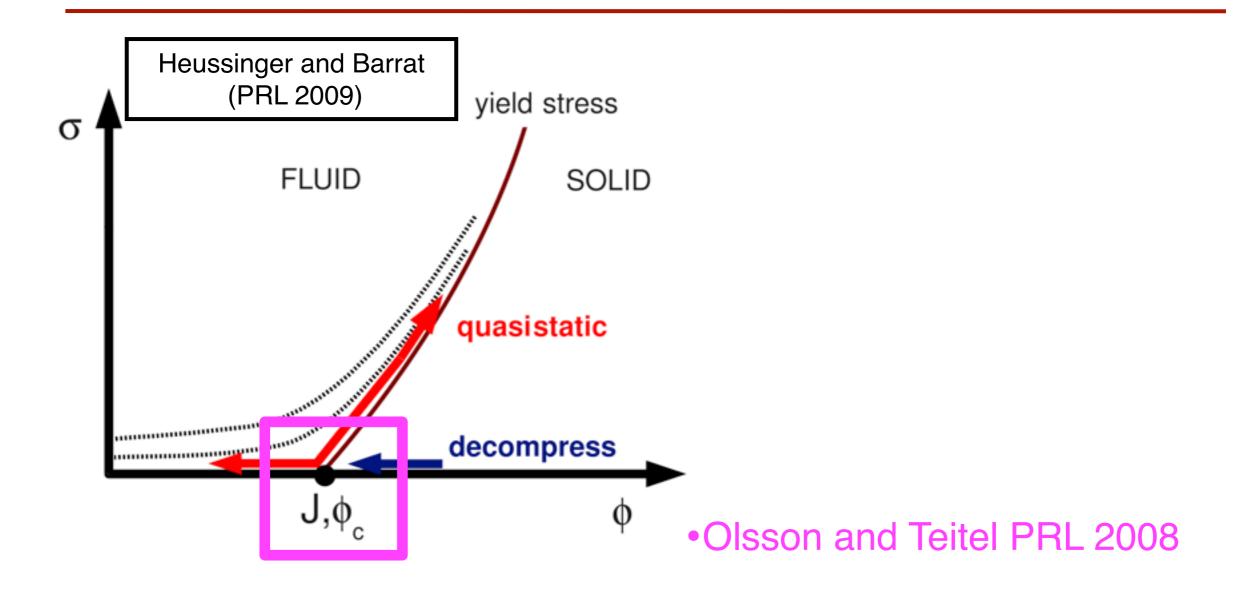








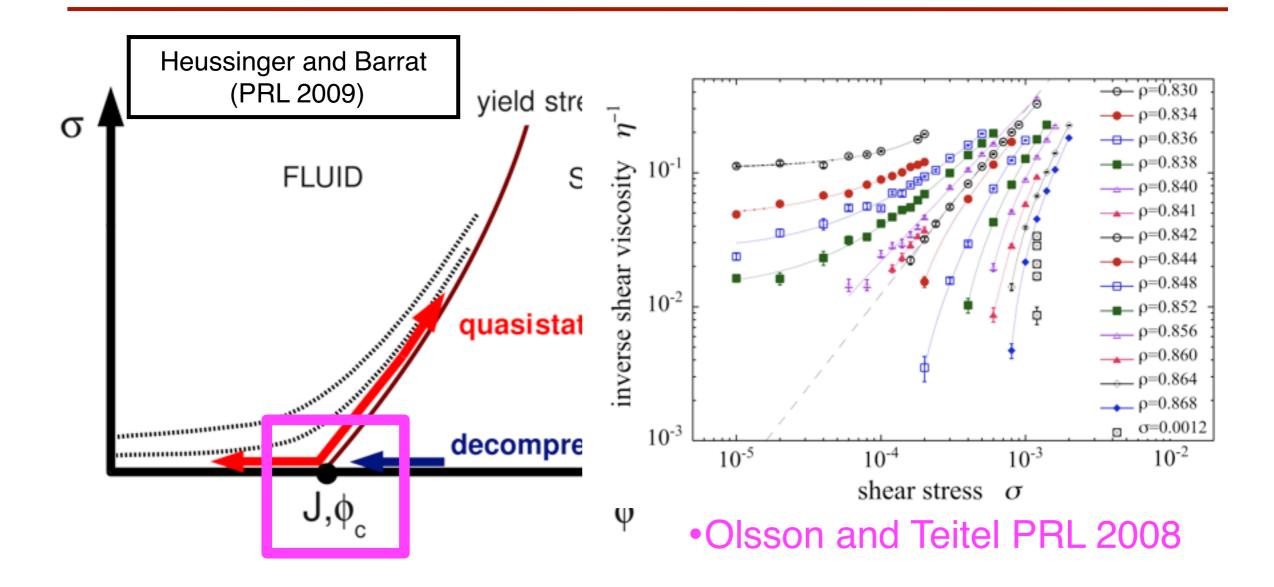




- φ,σ rheology scaling near "point J"
- Olsson and Teitel (bubbles), Hatano (grains)...



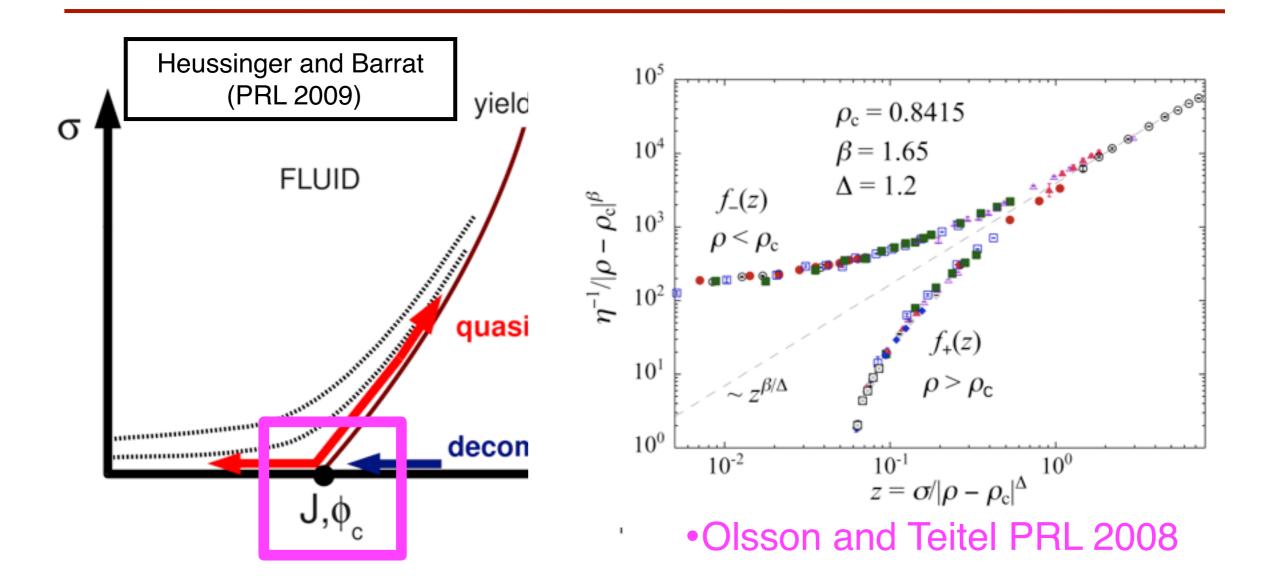




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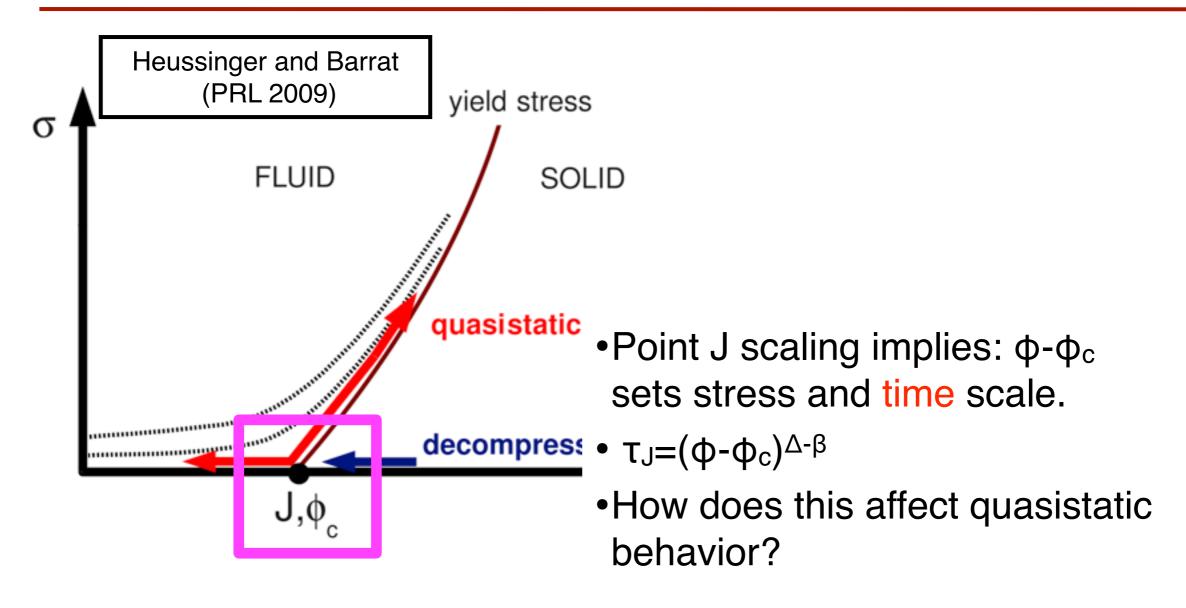






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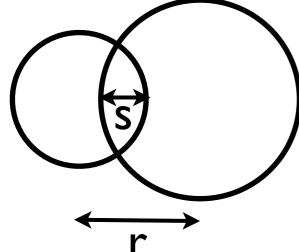


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- •Olsson and Teitel (bubbles), Hatano (grains)...





$$\delta \vec{v}_i = \vec{F}_i/D; \quad \delta \vec{v}_i = \vec{v}_i - y_i \dot{\gamma} \hat{x}; \quad \dot{\vec{r}}_i = \vec{v}_i$$



$$a = \frac{(R_i + R_j) - r_{ij}}{R_i + R_j}$$
$$U = \frac{\epsilon}{2}a^2$$

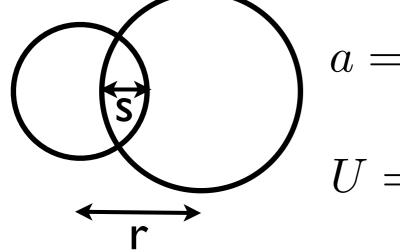
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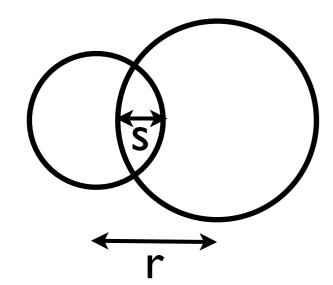
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• 50:50 bidisperse

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$$\delta \vec{v}_i = \vec{F}_i/D; \quad \delta \vec{v}_i = \vec{v}_i - y_i \dot{\gamma} \hat{x}; \quad \dot{\vec{r}}_i = \vec{v}_i$$



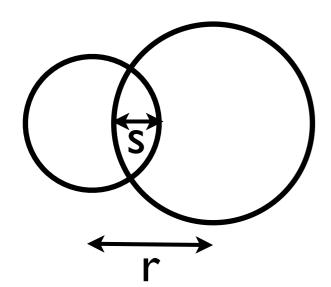
$$a = \frac{(R_i + R_j) - r_{ij}}{R_i + R_j}$$
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- 50:50 bidisperse
- R_large = 1.4 R_small = 1.4 σ_0

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$$\delta \vec{v}_i = \vec{F}_i/D; \quad \delta \vec{v}_i = \vec{v}_i - y_i \dot{\gamma} \hat{x}; \quad \dot{\vec{r}}_i = \vec{v}_i$$



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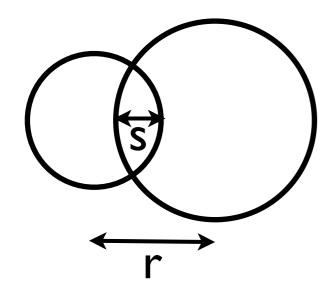
$$U = \frac{\epsilon}{2}a^2$$

- 50:50 bidisperse
- R_large = 1.4 R_small = 1.4 σ_0
- Drag force, Dδv, proportional to motion w/r/t homogeneous flow

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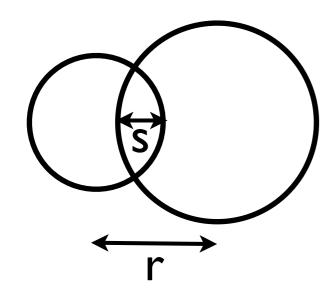
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- 50:50 bidisperse
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- Must balance potential force, F

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$$\delta \vec{v}_i = \vec{F}_i/D; \quad \delta \vec{v}_i = \vec{v}_i - y_i \dot{\gamma} \hat{x}; \quad \dot{\vec{r}}_i = \vec{v}_i$$



$$a = \frac{(R_i + R_j) - r_{ij}}{R_i + R_j}$$
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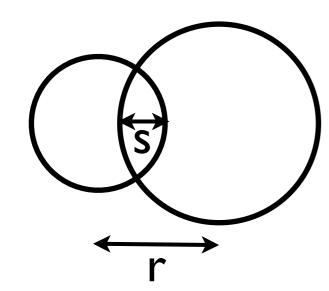
Only single timescale in model:

- 50:50 bidisperse
- R_large = 1.4 R_small = 1.4 σ_0
- Drag force, Dδv, proportional to motion w/r/t homogeneous flow
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$$\delta \vec{v}_i = \vec{F}_i/D; \quad \delta \vec{v}_i = \vec{v}_i - y_i \dot{\gamma} \hat{x}; \quad \dot{\vec{r}}_i = \vec{v}_i$$



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Only single timescale in model:

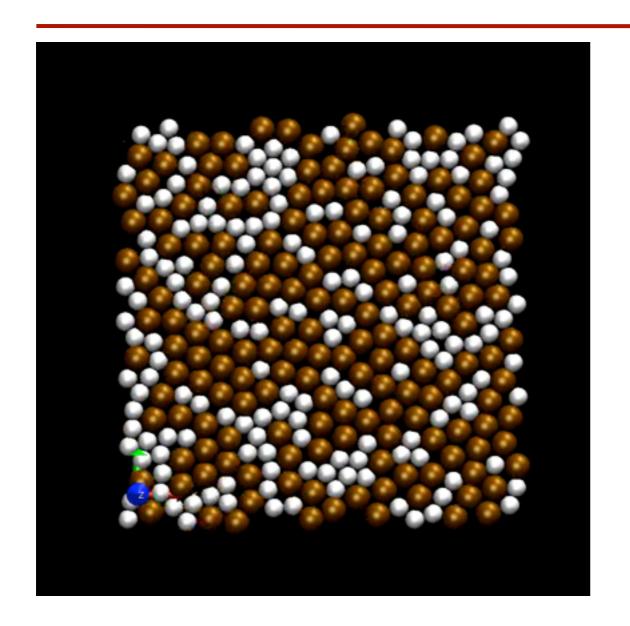
 $\tau_D \doteq D\sigma_0^2/\epsilon$

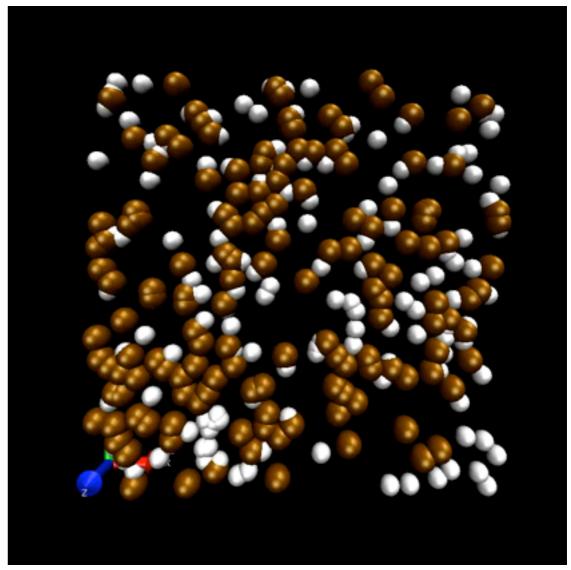
- 50:50 bidisperse
- R_large = 1.4 R_small = 1.4 σ_0
- Drag force, Dδv, proportional to motion w/r/t homogeneous flow
- Must balance potential force, F

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"Slow" shear at various density





 $\Phi = 1.0$

 $d\gamma/dt=1.25x10^{-6}$

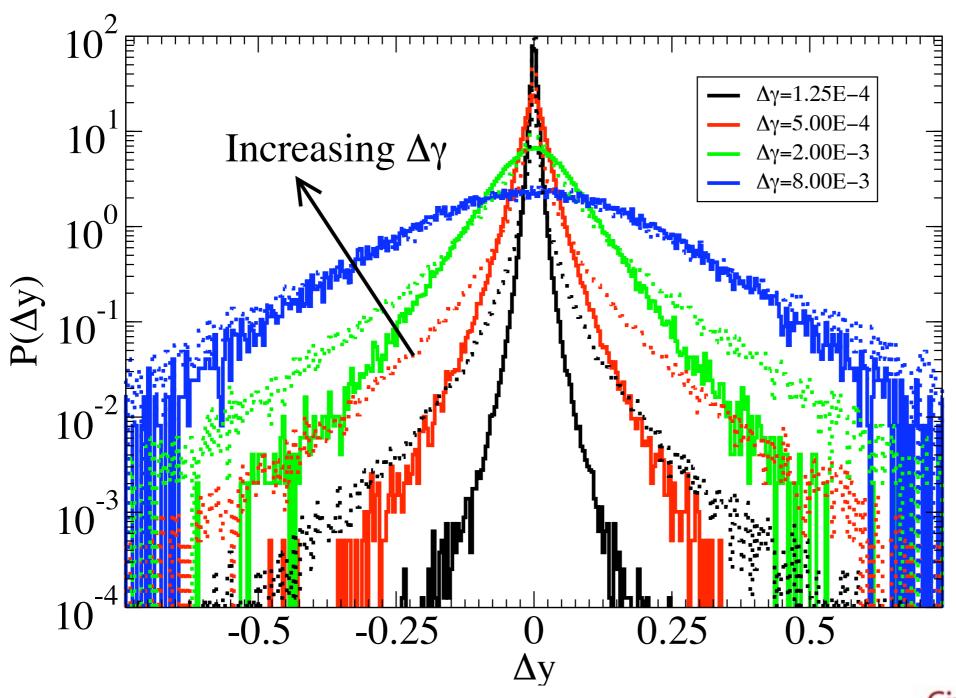
 $\Phi = 0.85$

How are they different?





Transverse displacement distribution

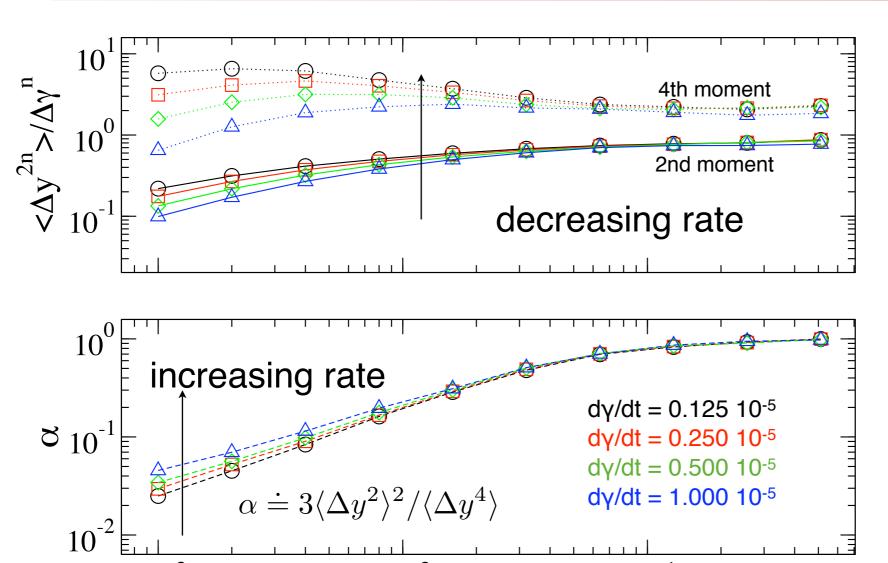


 $P(\Delta y)$ much broader for ϕ =1.0 than ϕ =0.85 at early $\Delta \gamma$

 $P(\Delta y)$ similar for ϕ =1.0 and ϕ =0.85 at late $\Delta \gamma$

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2nd and 4th moments (ϕ =1.0)



 10^{-2}

 $\Delta \gamma$

 10^{-1}

no rate dependence at plateau, we're quasistatic!

From LJ slip-line arguments:

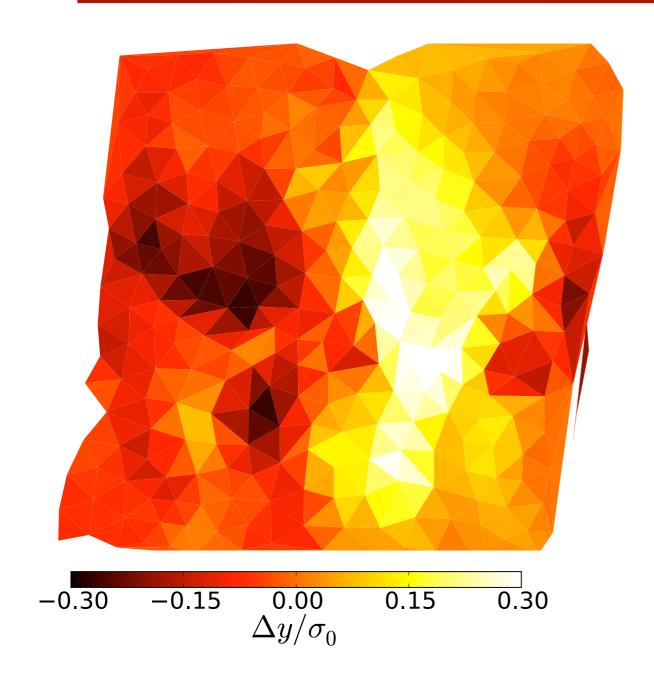
Deff~ La/12

a~0.8σ

 $\Delta \gamma^* \sim a/L \sim .05$

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Typical displacement over $\Delta \gamma \sim 0.05$



From LJ slip-line arguments:

Deff~ La/12

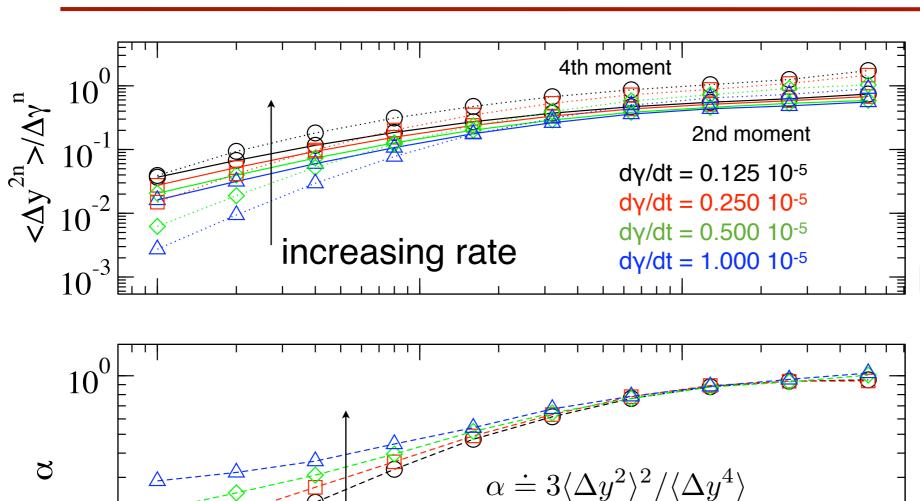
a~0.8σ

 $\Delta \gamma^* \sim a/L \sim .05$





2nd and 4th moments (ϕ =0.85)



increasing rate

 $\Delta \gamma$

 10^{-1}

 10^{-2}

slight rate dependence at plateau

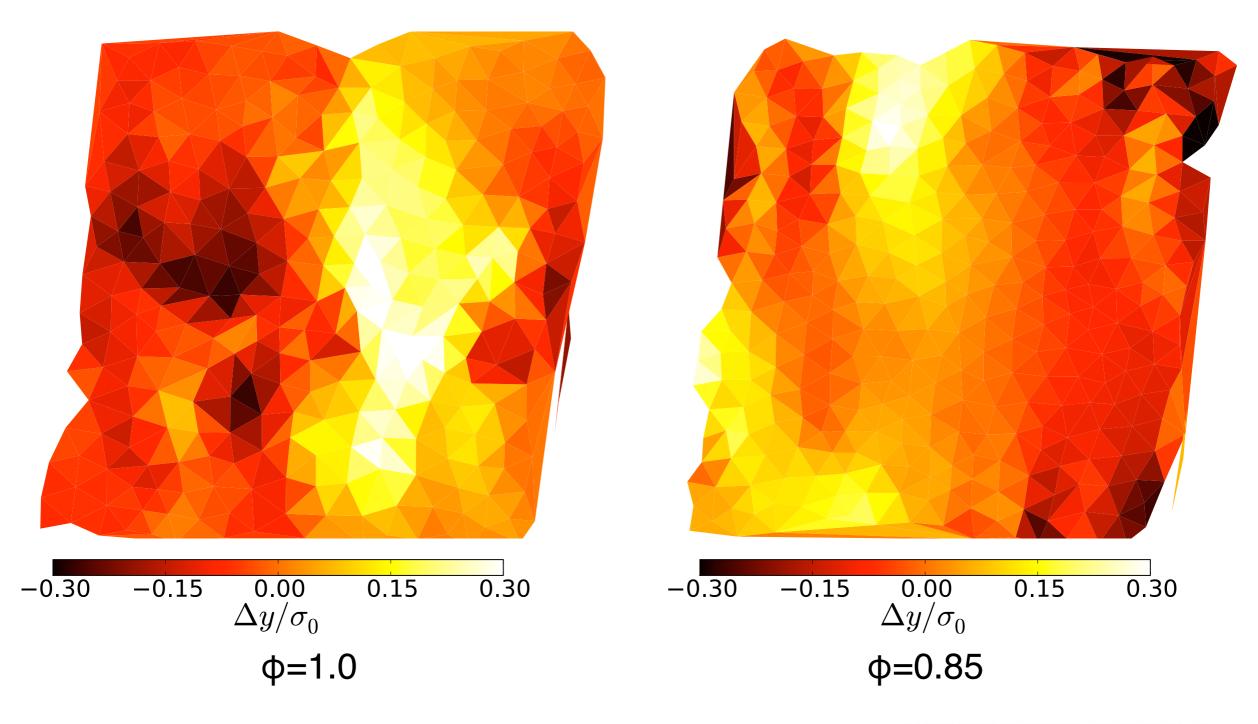
at slowest rate, D_{eff} within 10% of D_{eff} for ϕ =1.0

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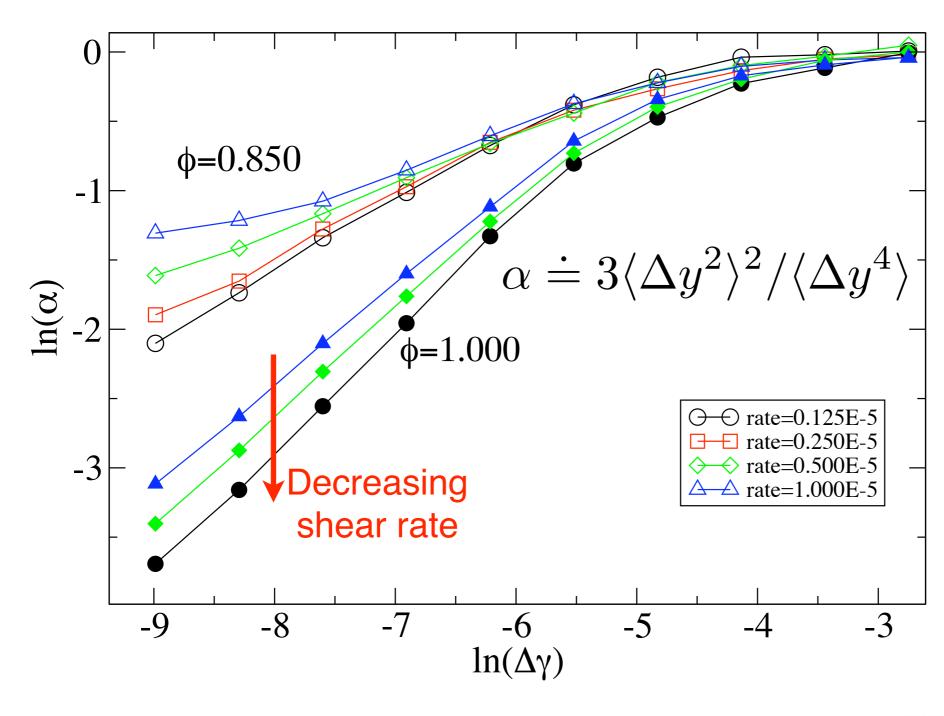
10

Typical displacement over $\Delta \gamma \sim 0.05$



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Non-gaussian parameter, α



cross-over to
Gaussian is
roughly
independent of φ
and dγ/dt.

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Conclusion (Diffusion)

•Slip lines argument gives:

```
slip amplitude = a \sim 0.8\sigma
strain quantum = \Delta \gamma_* \sim a/L \sim 0.05
```

- Displacement fields at $\Delta\gamma\sim0.05$ look like slip lines with consistent slip amplitude
- Seems surprisingly robust with respect to φ!
 - systems near ϕ_c much less intermittent at small $\Delta \gamma$
 - but surprisingly similar in Fickian regime!





$$\frac{dU}{dt} = \left. \frac{\partial U}{\partial \gamma} \right|_{s} \dot{\gamma} + \sum_{i} \frac{\partial U}{\partial \vec{s}_{i}} \dot{\vec{s}}_{i} = \sigma \dot{\gamma} - \sum_{i} \vec{F}_{i} \cdot \delta \vec{v}_{i}$$





$$\frac{dU}{dt} = \left| \frac{\partial U}{\partial \gamma} \right|_{s} \dot{\gamma} + \sum_{i} \frac{\partial U}{\partial \vec{s}_{i}} \dot{\vec{s}}_{i} = \sigma \dot{\gamma} - \sum_{i} \vec{F}_{i} \cdot \delta \vec{v}_{i}$$





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•Energy change under affine deformation = σ





$$\frac{dU}{dt} = \left| \frac{\partial U}{\partial \gamma} \right|_{s} \dot{\gamma} + \sum_{i} \frac{\partial U}{\partial \vec{s}_{i}} \dot{\vec{s}}_{i} = \sigma \dot{\gamma} - \sum_{i} \vec{F}_{i} \cdot \delta \vec{v}_{i}$$

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- •Energy change under affine deformation = σ
- Identify as input power



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- •Energy change under affine deformation = σ
- Identify as input power
- Identify as dissipation rate



$$\frac{dU}{dt} = \left| \frac{\partial U}{\partial \gamma} \right|_{s} \dot{\gamma} + \sum_{i} \frac{\partial U}{\partial \vec{s}_{i}} \dot{\vec{s}}_{i} = \sigma \dot{\gamma} - \sum_{i} \vec{F}_{i} \cdot \delta \vec{v}_{i}$$

- •Energy change under affine deformation = σ
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$$\Gamma \dot{\gamma} = \sigma \dot{\gamma} - \frac{dU}{dt} = \sum_{i} \vec{F}_{i} \cdot \delta \vec{v}_{i} = D \sum_{i} \delta v_{i}^{2}$$

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$$\frac{dU}{dt} = \left| \frac{\partial U}{\partial \gamma} \right|_{s} \dot{\gamma} + \sum_{i} \frac{\partial U}{\partial \vec{s}_{i}} \dot{\vec{s}}_{i} = \sigma \dot{\gamma} - \sum_{i} \vec{F}_{i} \cdot \delta \vec{v}_{i}$$

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$$\langle \Gamma \rangle = \langle \sigma \rangle = \frac{DN}{\dot{\gamma}} \langle \delta v^{2} \rangle$$

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$$\frac{dU}{dt} = \left| \frac{\partial U}{\partial \gamma} \right|_{s} \dot{\gamma} + \sum_{i} \frac{\partial U}{\partial \vec{s}_{i}} \dot{\vec{s}}_{i} = \sigma \dot{\gamma} - \sum_{i} \vec{F}_{i} \cdot \delta \vec{v}_{i}$$

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Γ is energy dissipated per unit strain

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$$\frac{dU}{dt} = \left| \frac{\partial U}{\partial \gamma} \right|_{s} \dot{\gamma} + \sum_{i} \frac{\partial U}{\partial \vec{s}_{i}} \dot{\vec{s}}_{i} = \boxed{\sigma \dot{\gamma}} - \boxed{\sum_{i} \vec{F}_{i} \cdot \delta \vec{v}_{i}}$$

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 •Ono et. al. PRE 2003

Γ is energy dissipated per unit strain

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$$\frac{dU}{dt} = \left| \frac{\partial U}{\partial \gamma} \right|_{s} \dot{\gamma} + \sum_{i} \frac{\partial U}{\partial \vec{s}_{i}} \dot{\vec{s}}_{i} = \sigma \dot{\gamma} - \sum_{i} \vec{F}_{i} \cdot \delta \vec{v}_{i}$$

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$$\Gamma \dot{\gamma} = \sigma \dot{\gamma} - \frac{dU}{dt} = \sum_{i} \vec{F}_{i} \cdot \delta \vec{v}_{i} = D \sum_{i} \delta v_{i}^{2}$$

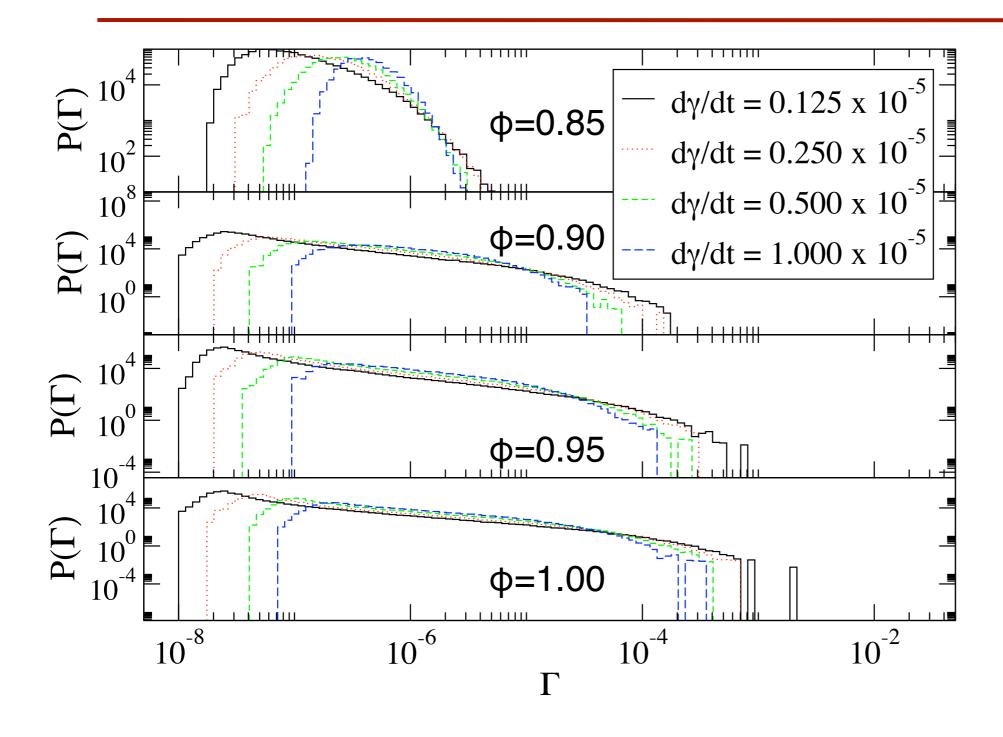
$$\langle \Gamma \rangle = \langle \sigma \rangle = \frac{DN}{\dot{\gamma}} \langle \delta v^2 \rangle \qquad \mbox{ •Ono \it et. al. PRE 2003} \\ \mbox{ •Rheology = fluctuations}$$

- Γ is energy dissipated per unit strain

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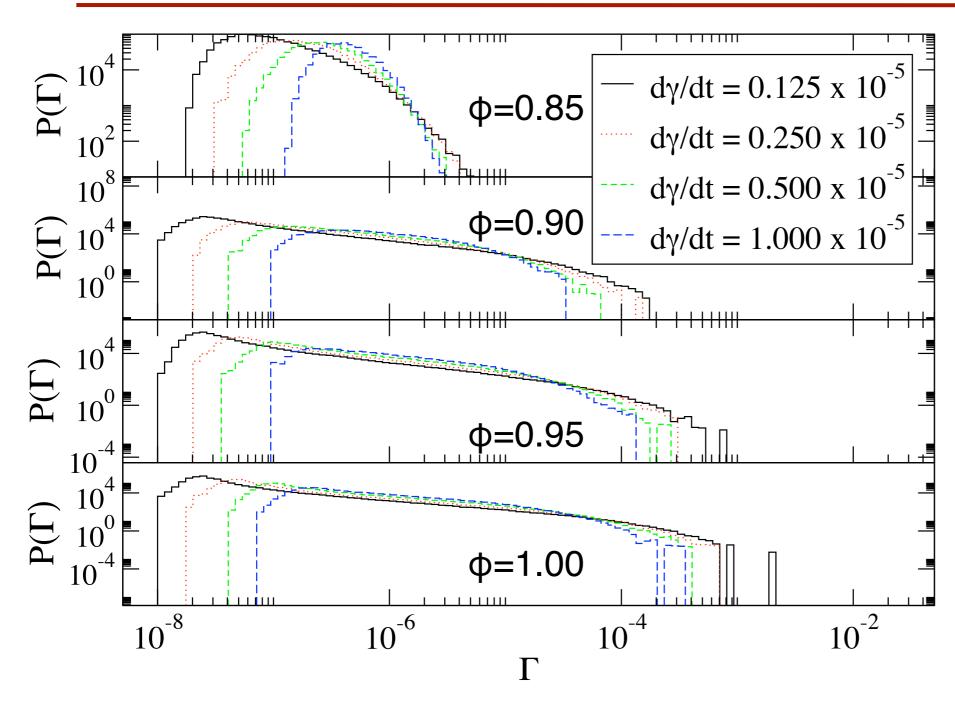
Γ distribution (like acoustic emission spectrum)







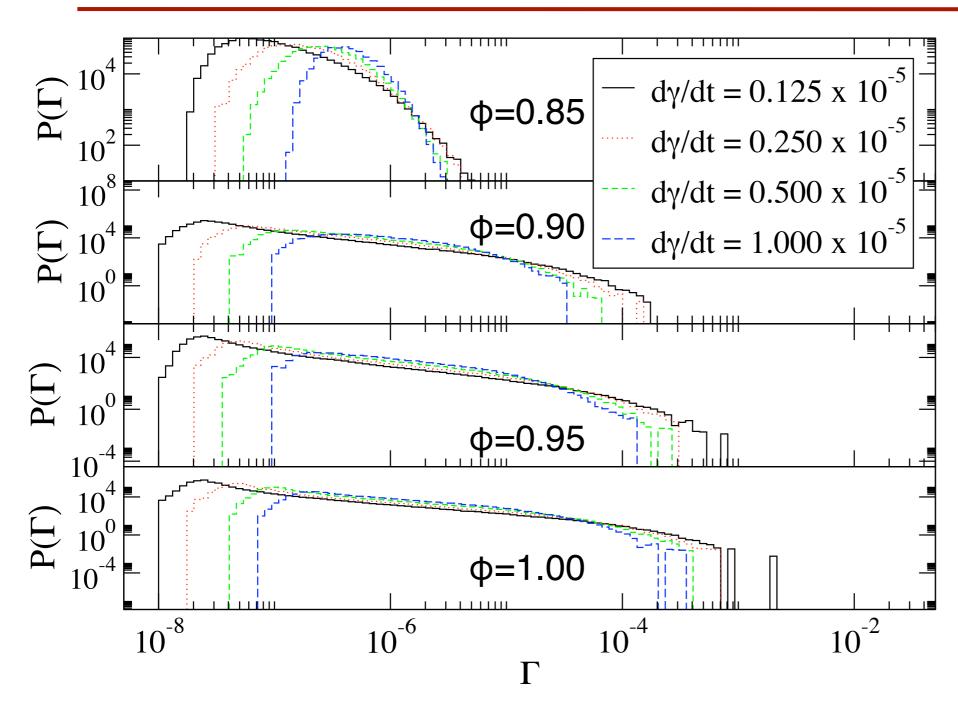
Γ distribution (like acoustic emission spectrum)



power-law regime

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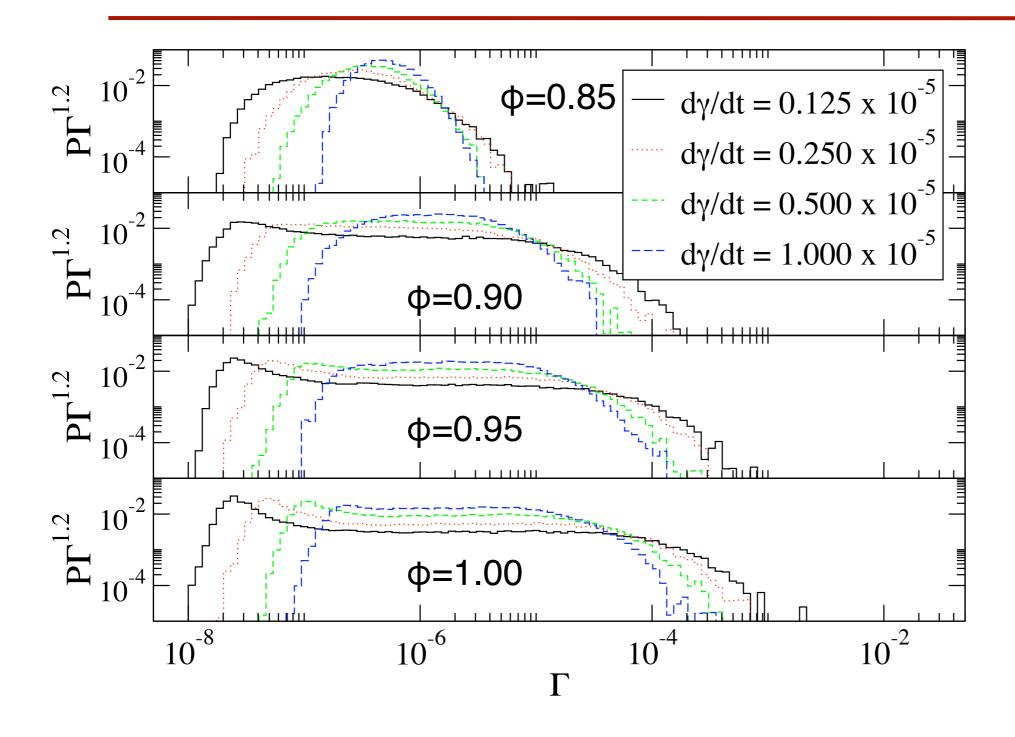
Γ distribution (like acoustic emission spectrum)



- power-law regime
- exponent~-1.2

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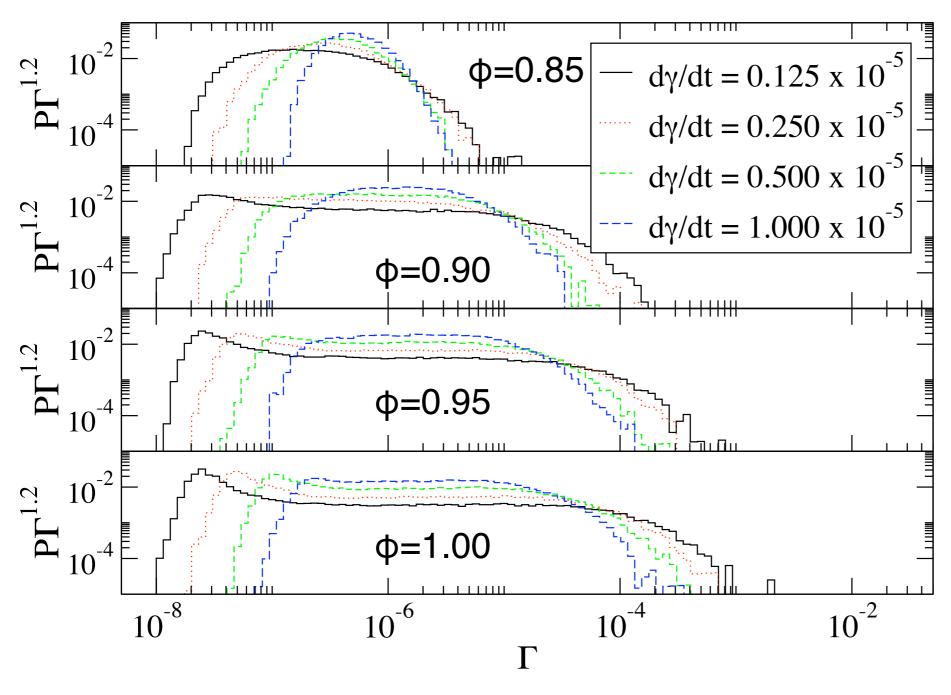
Γ distribution power-law rescaling





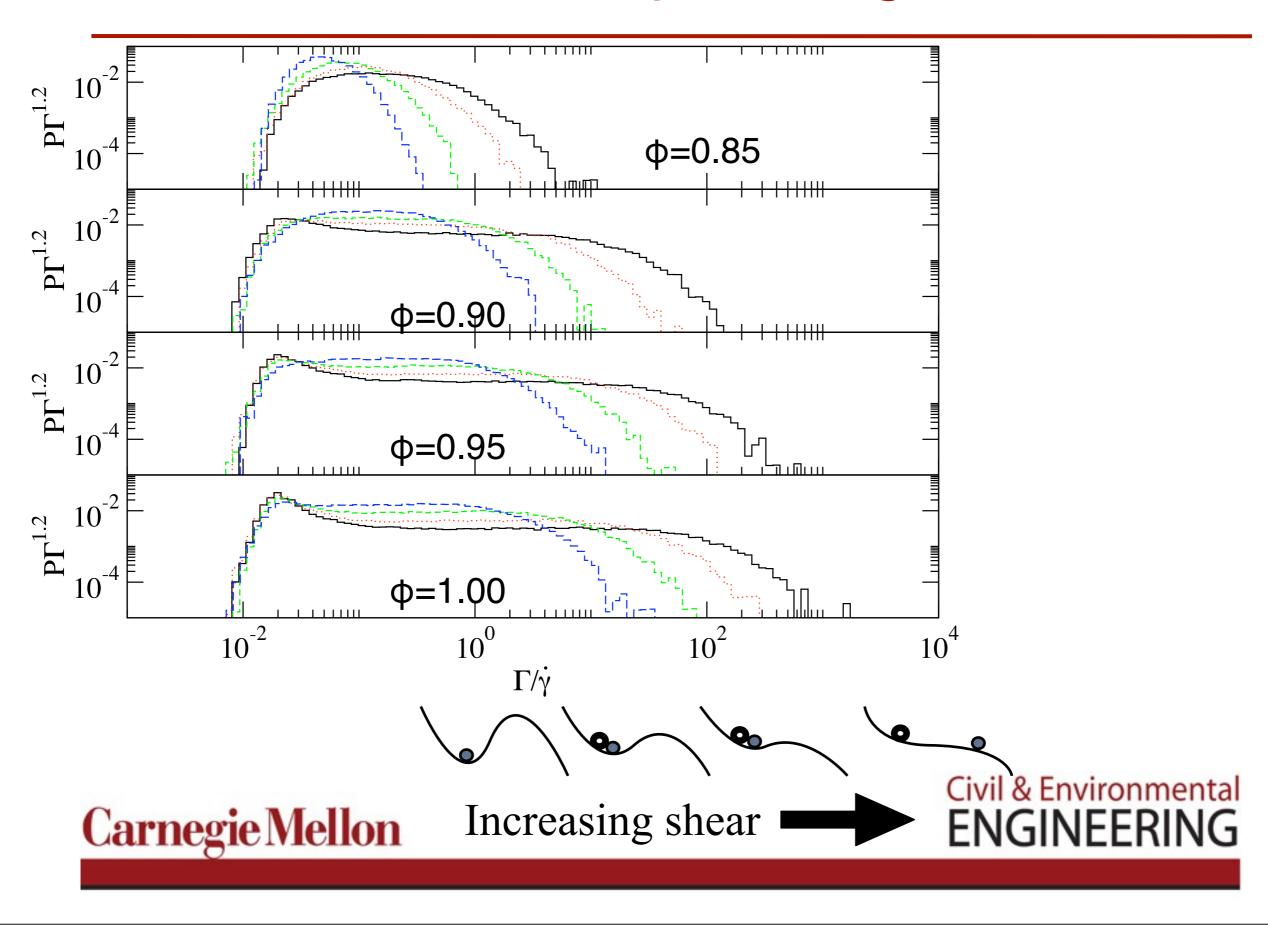


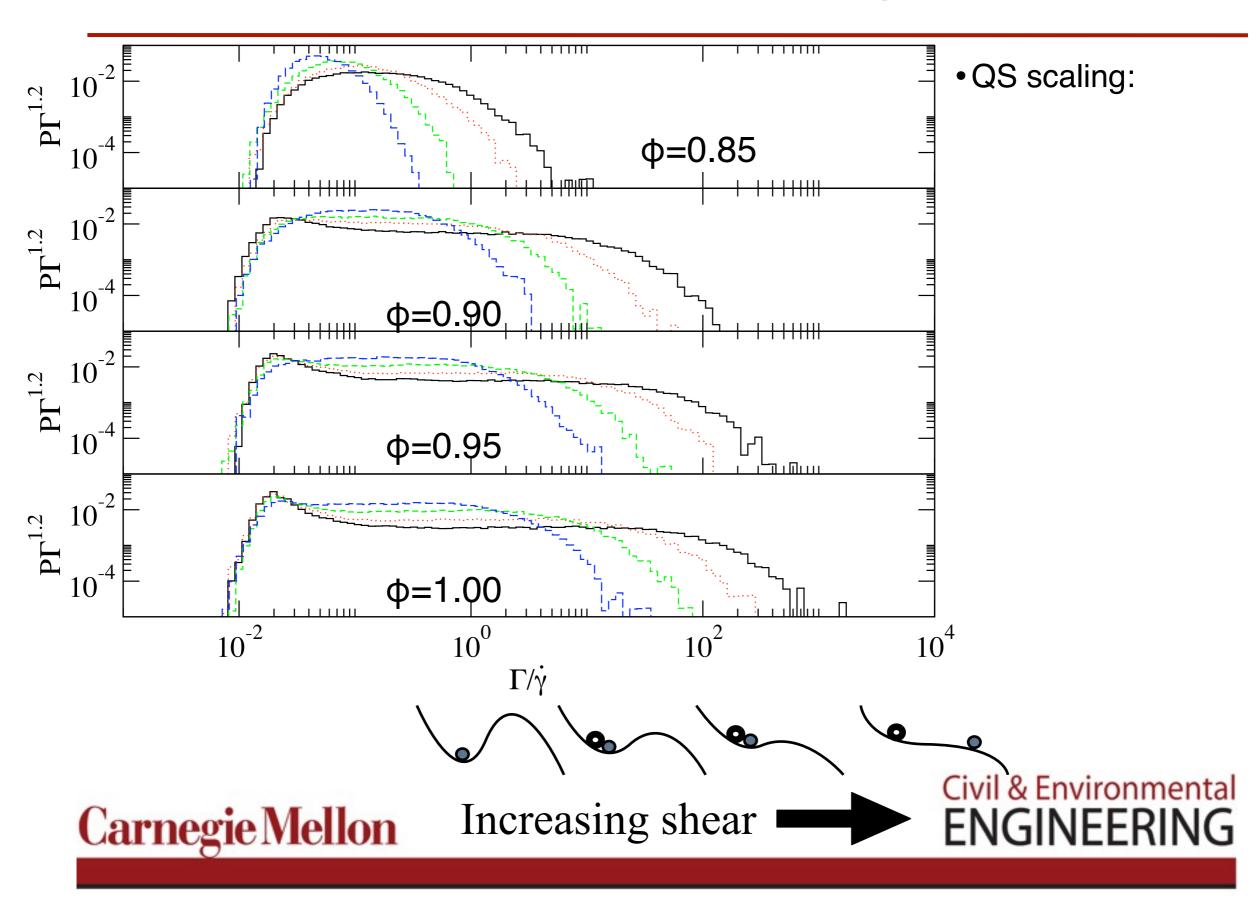
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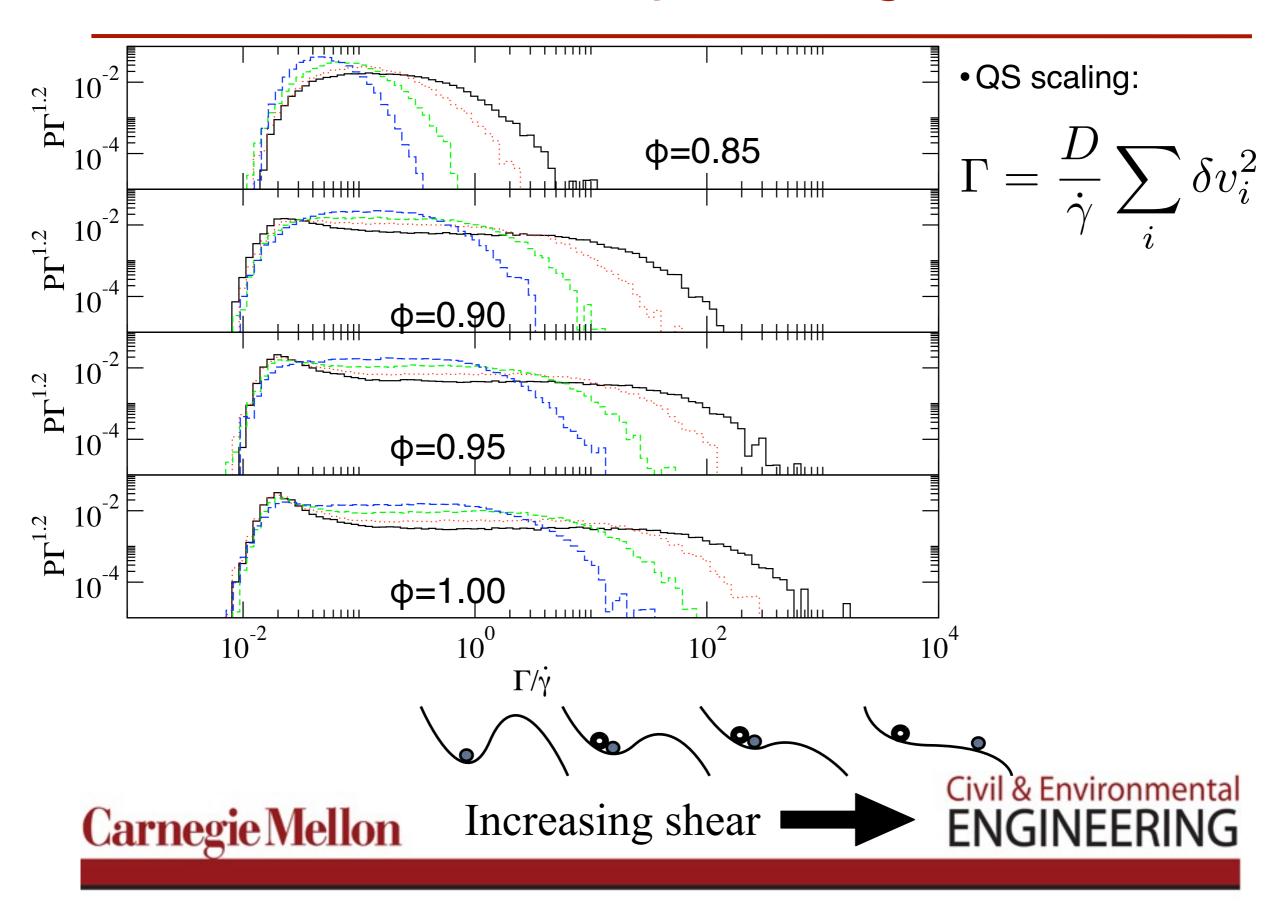


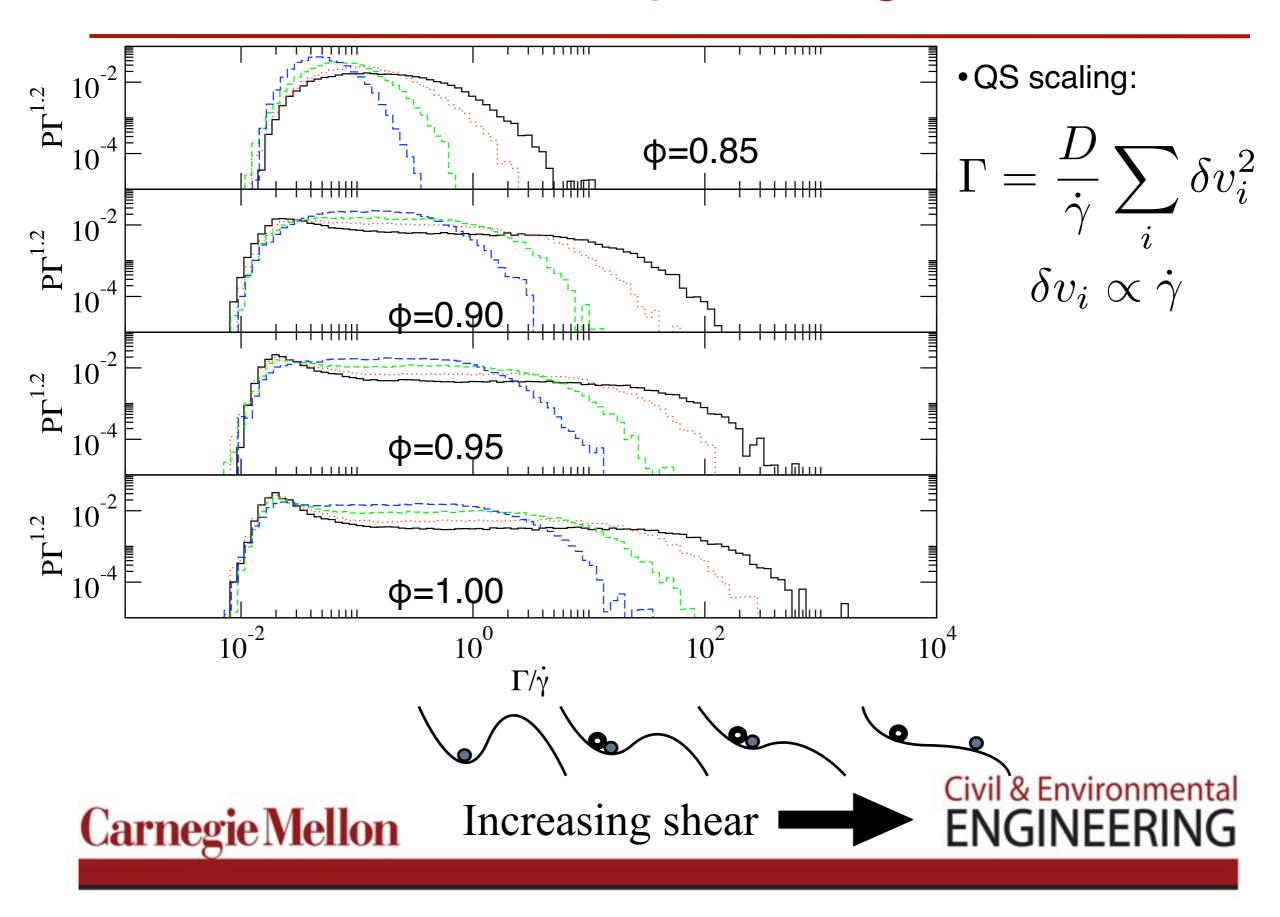
• Scale P by Γ^{-1.2}

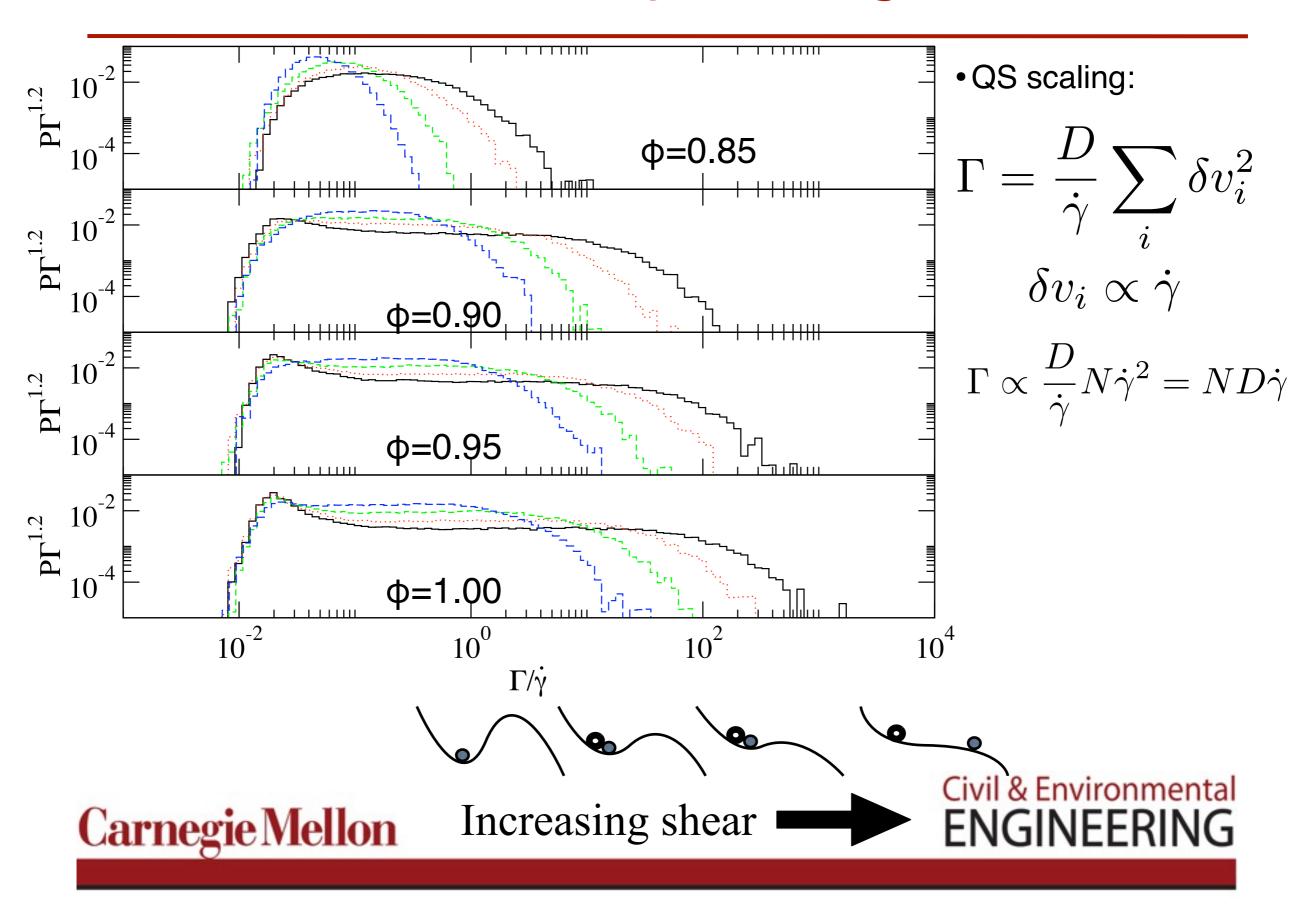
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Instantaneous energy dissipation:





- Instantaneous energy dissipation:
 - $\phi > \phi_c$, $d\gamma/dt \rightarrow 0$:





- Instantaneous energy dissipation:
 - $\phi > \phi_c$, $d\gamma/dt -> 0$:
 - Quasistatic peak





- Instantaneous energy dissipation:
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 - Quasistatic peak
 - Power law regime with exponent ~ 1.2





- Instantaneous energy dissipation:
 - $\phi > \phi_c$, $d\gamma/dt \rightarrow 0$:
 - Quasistatic peak
 - Power law regime with exponent ~ 1.2
 - •Questions:





Conclusion (avalanches/dissipation)

- Instantaneous energy dissipation:
 - $\phi > \phi_c$, $d\gamma/dt \rightarrow 0$:
 - Quasistatic peak
 - Power law regime with exponent ~ 1.2
 - •Questions:
 - Slip line argument predicts D_{eff} ~ L. Can we see it?





Conclusion (avalanches/dissipation)

- Instantaneous energy dissipation:
 - $\phi > \phi_c$, $d\gamma/dt \rightarrow 0$:
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 - Power law regime with exponent ~ 1.2
 - •Questions:
 - Slip line argument predicts D_{eff} ~ L. Can we see it?
 - How does combined rate/size dictate Fickian cross-over?





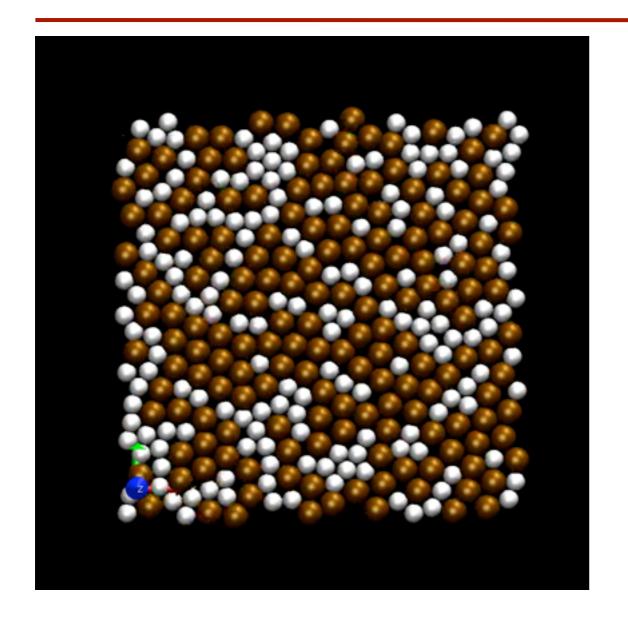
Conclusion (avalanches/dissipation)

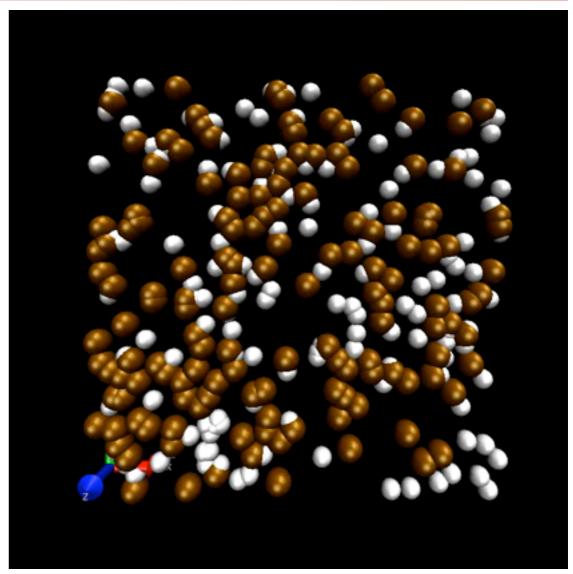
- Instantaneous energy dissipation:
 - $\phi > \phi_c$, $d\gamma/dt \rightarrow 0$:
 - Quasistatic peak
 - Power law regime with exponent ~ 1.2
 - •Questions:
 - Slip line argument predicts D_{eff} ~ L. Can we see it?
 - How does combined rate/size dictate Fickian cross-over?
 - Is physics the same at the same τ_J dγ/dt?





THE END





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Thanks!





Numerical models / algorithms

Various interaction potentials:

$$U_{harm} = (\epsilon/2) s^2$$

$$U_{hertz} = \epsilon s^{5/2}$$

$$U_{Lennard-Jones} = \epsilon(r^{-12}-r^{-6})$$

Binary distribution in 2D

Athermal, Quasistatic Procedure:

- Minimize potential energy
- •Shear boundaries and particles
- Repeat

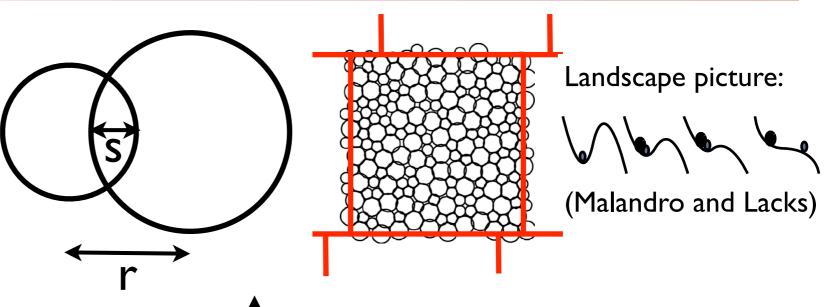
Represents: $\tau_{pl} << \tau_{dr} << \tau_{th}$

- •Bulk metallic glass in the zero temperature, zero strain rate limit
- •Granular material or emulsion in zero strain rate limit

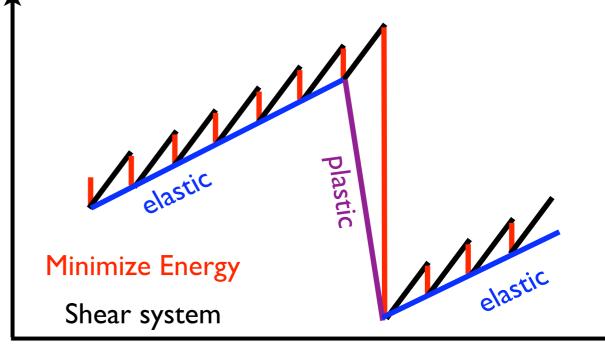
Behavior:

•Discrete plastic jumps separate smooth, reversible elastic segments

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Energy

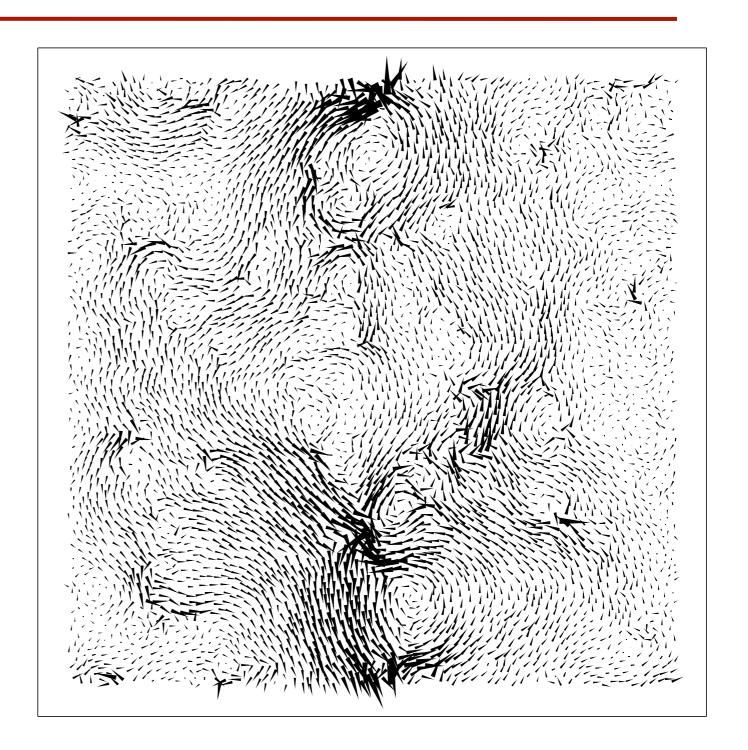


Strain

Linear elastic response (at zero temperature)

- Take a binary Lennard-Jones system
- Quench instantaneously from T=infinity to T=0
- Apply infinitesimal shear strain
- Compute deviations from homogeneous shear
- Note vortex-like patterns... lengthscale?

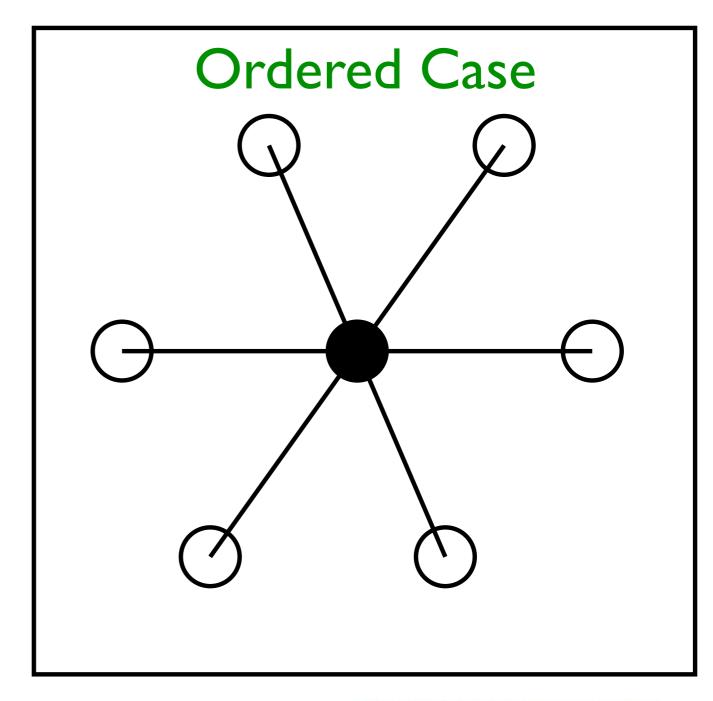
A. Tanguy et. al. PRB 2002





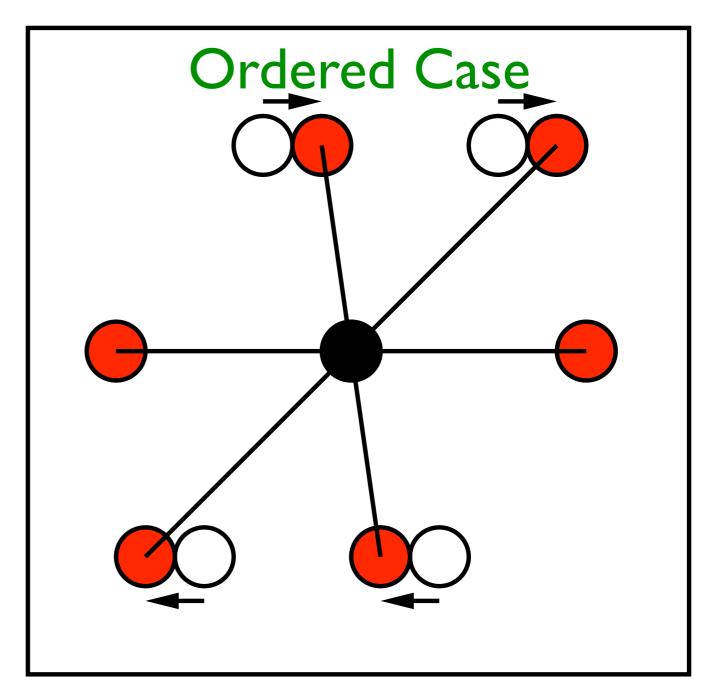


- Single particle toy problem:
 - Start at F=0



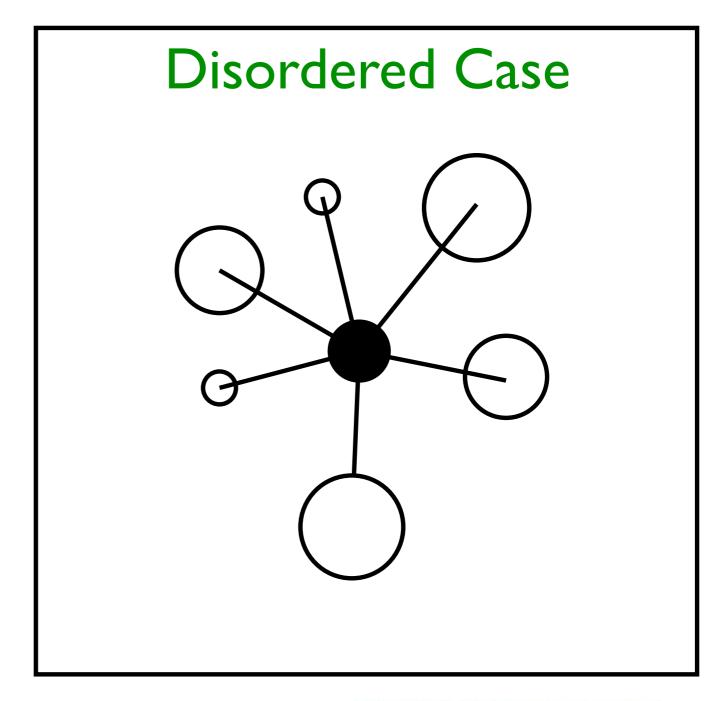
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- Single particle toy problem:
 - Start at F=0
 - Apply affine shear
 - Forces remain zero
 - No correction necessary



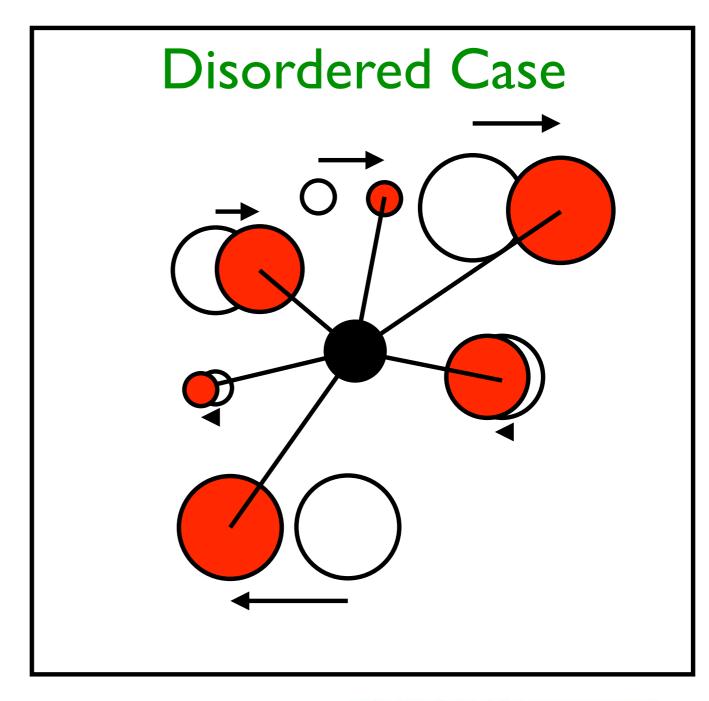
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- Single particle toy problem:
 - Start at F=0



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- Single particle toy problem:
 - Start at F=0
 - Apply strain

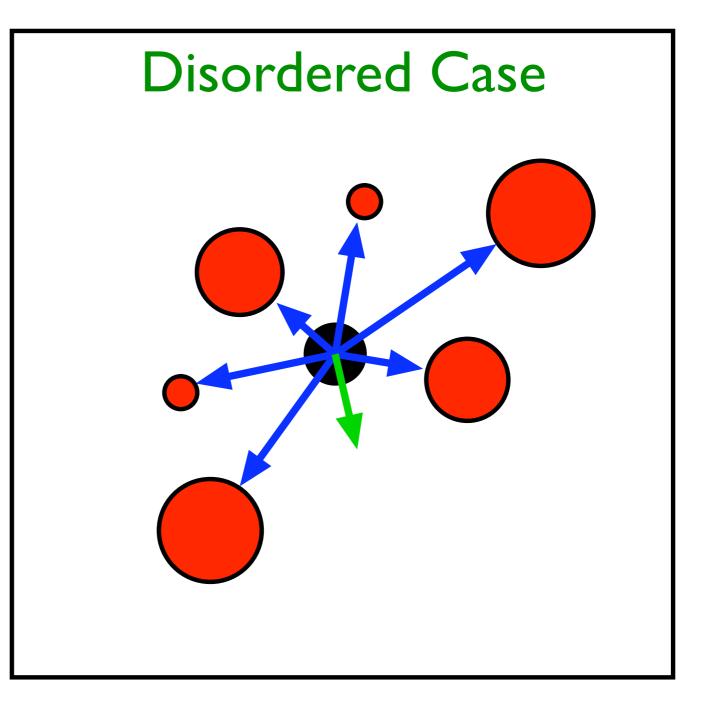


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- Single particle toy problem:
 - Start at F=0
 - Apply strain

Use Hessian to compute "Affine force"

$$\vec{\Xi}_i = \gamma \sum_j \mathbf{H}_{ij} \hat{\mathbf{x}} \delta y_j$$

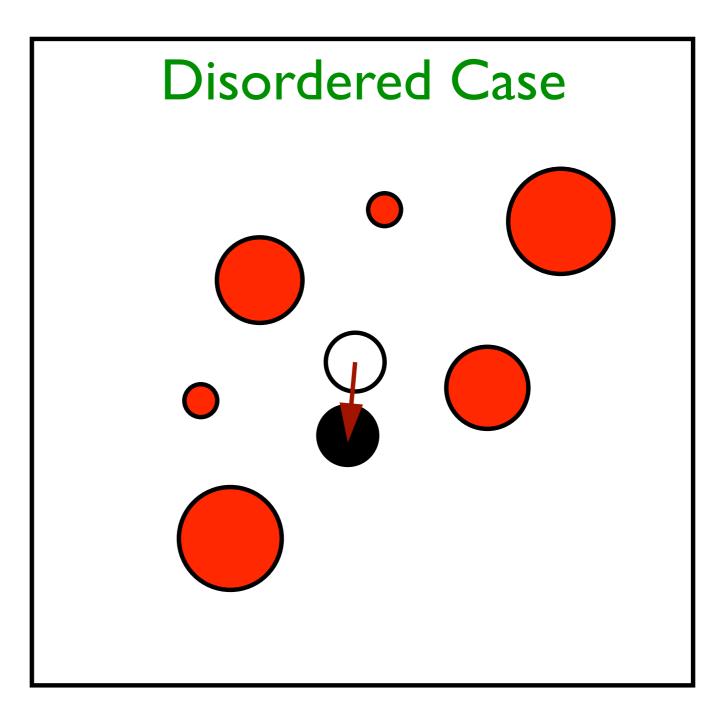


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- Single particle toy problem:
 - Start at F=0
 - Apply strain

Use Hessian to find position correction

$$\vec{\Xi}_i = \mathbf{H}_{ii} \vec{dr}_i$$
 $\vec{dr}_i = \mathbf{H}_{ii}^{-1} \vec{\Xi}_i$

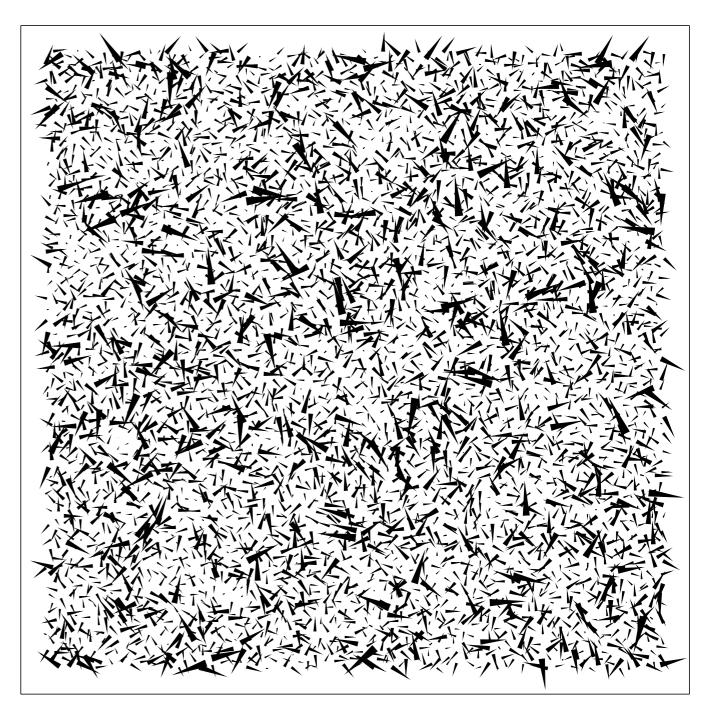


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Back to full assembly:

$$\vec{\Xi}_i = \gamma \sum_j \mathbf{H_{ij}} \hat{\mathbf{x}} \delta y_{ij}$$

- Measure of local disorder.
- Only short range correlations in our samples.



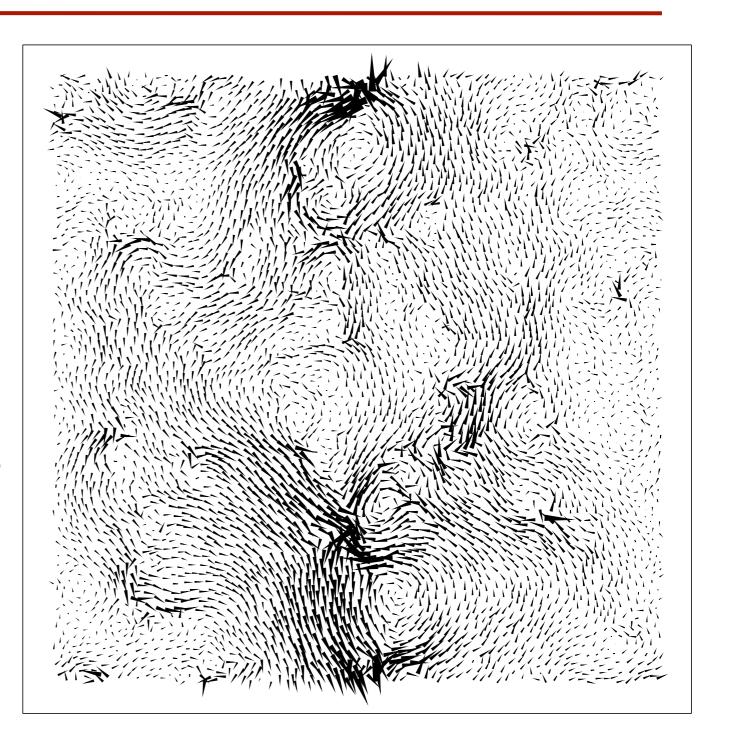
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Back to full assembly:

$$\vec{dr}_i = \gamma \sum_j \mathbf{H}_{ij}^{-1} \vec{\Xi}_j$$

Force balance:

Affine forces, Ξ , must be balanced by correction forces, $H^{-1}_{ij}dx_j$

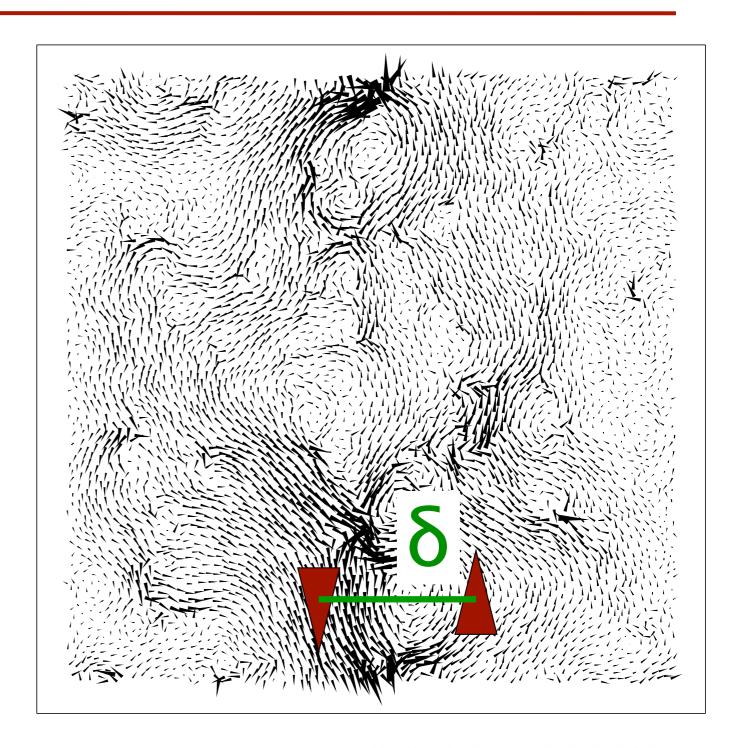


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Spatial autocorrelation function $g(\delta)$

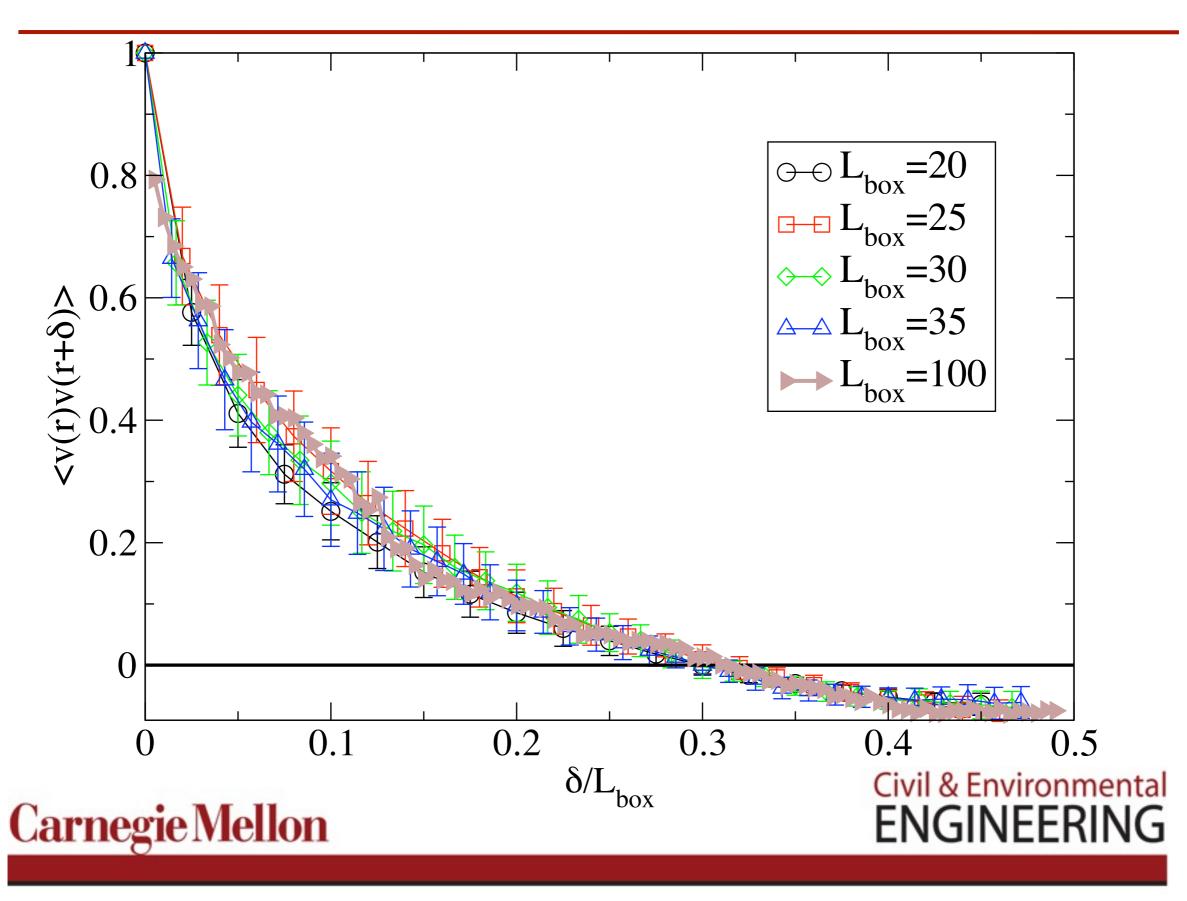
$$g(\vec{\delta}) \doteq \int \vec{v}(\vec{r}) \cdot \vec{v}(\vec{r} + \vec{\delta}) d\vec{r}$$

- Usual autocorrelation
- Measures "vortex size"
- •Characteristic length?



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Spatial autocorrelation function $g(\delta)$



Recall:
$$\vec{dr}_i = \gamma \sum_j \mathbf{H}_{ij}^{-1} \vec{\Xi}_j$$





Recall:
$$\vec{dr}_i = \gamma \sum_j \mathbf{H}_{ij}^{-1} \vec{\Xi}_j$$

Then:
$$\vec{dr}_i = \gamma \sum_p \left(\frac{\Xi_p}{\lambda_p}\right) \vec{\psi}_{ip}$$





Recall:
$$\vec{dr}_i = \gamma \sum_j \mathbf{H}_{ij}^{-1} \vec{\Xi}_j$$

Then:
$$\vec{dr}_i = \gamma \sum_p \left(\frac{\Xi_p}{\lambda_p}\right) \vec{\psi}_{ip}$$

- •Assume:
 - = is a random dipole field
 - Ψ_p are plane waves

•
$$\lambda_p = k_p^2$$
 ; $\Xi_p = k_p$

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Approximate dr_i as random sum of plane waves:

$$\vec{dr}_i \sim \sum_{k=(m,n)} \phi_{mn} \frac{e^{2\pi i \vec{k} \cdot \vec{x}_i/L}}{|\vec{k}|}$$

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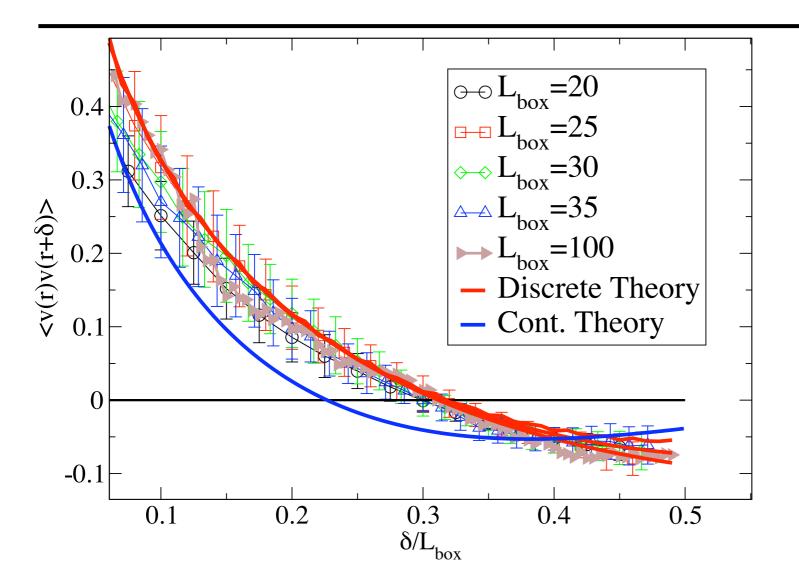
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Then $g(\delta)$ is:

$$g(\vec{\delta}) \sim \sum_{k=(m,n)} \frac{\cos(2\pi \vec{k} \cdot \vec{\delta}/L)}{k^2}$$

$$g(\vec{\delta}) \sim \sum_{k=(m,n)} \frac{\cos(2\pi \vec{k} \cdot \vec{\delta}/L)}{k^2}$$



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Similar to DiDonna +Lubenksy,

 $\bullet g(k) \sim 1/k^2$

but:

Fully discrete derivation

Blue curve:

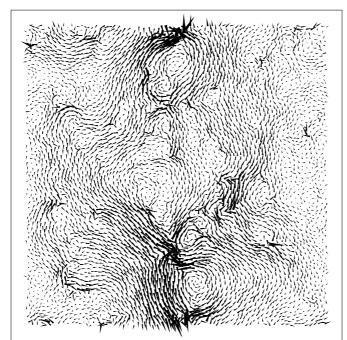
Semi-continuum

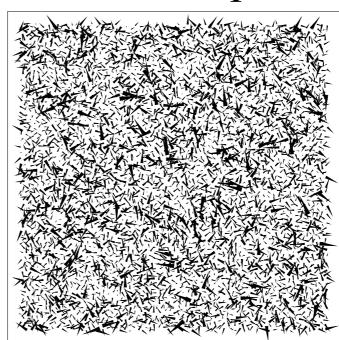
Red curve(s):

Partial sum (n=40)
3 different angles

Summary: Elastic response

- Linear elastic (zero temperature) response is inhomogeneous.
- Displacement fluctuations appear as vortices
- Size scales with system size... no characteristic length
- "Affine forces": a new measure of local disorder.
- Fluctuations derived from approximating eigenmodes as plane waves and affine forces as a random dipoles.

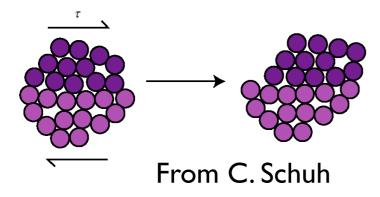


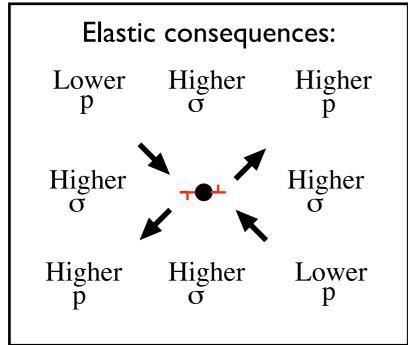


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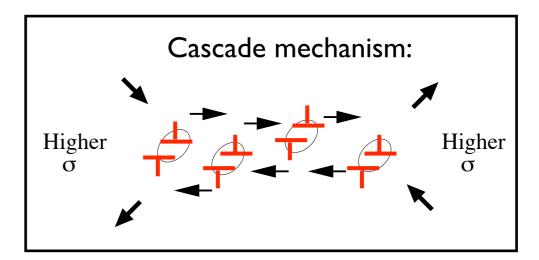
Plastic response (Shear Transformation Zones)

No crystal... so no dislocations... but then what controls plasticity?





- •Shear Transformation Zone (STZ) Mechanism:
 - Argon and Kuo: bubble raft experiments
 - •Maeda and Takeuchi: computer simulations
 - •Bulatov and Argon: banding mechanism
 - •Falk and Langer: mean field theory

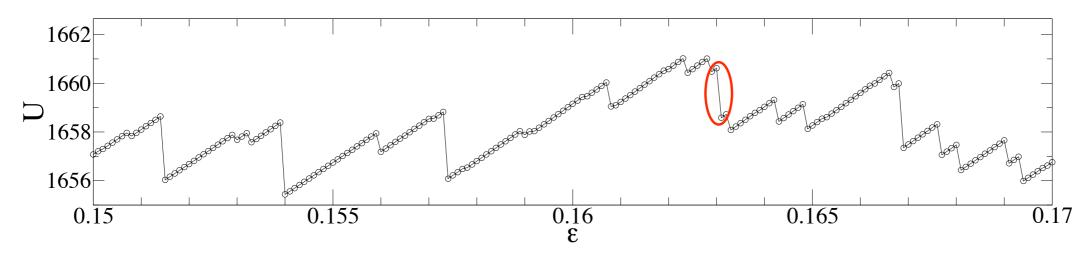


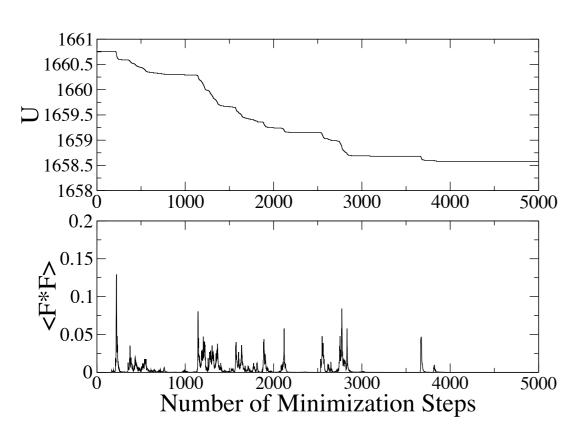
Analogous to dislocation glide:

What are the consequences of organization of local shear zones?



Typical plastic cascade



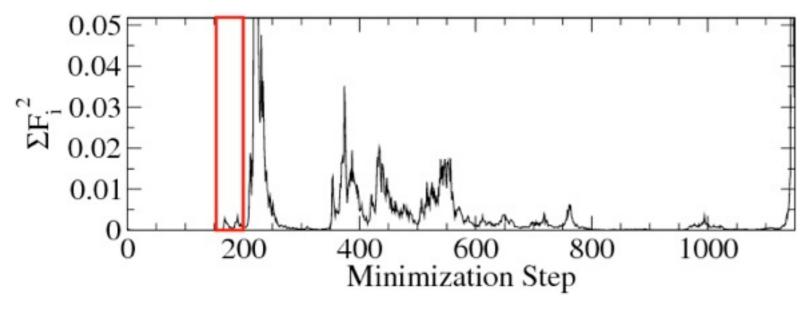


- Protocol: shear, relax...
- Single typical plastic event
- All relaxation at one strain
- "Number of minimization steps" analogous to time <F²>~dU/dt
- Descent is intermittent...

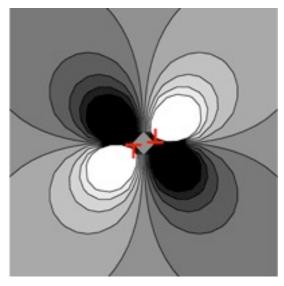


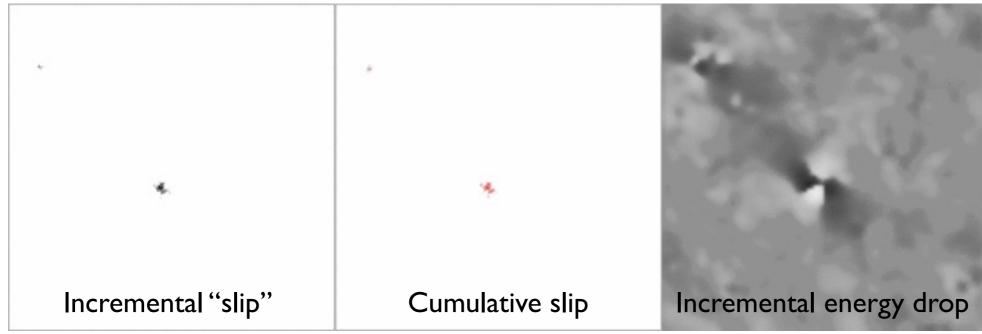
Typical plastic cascade

Initial portion of descent from previous slide:



Expected energy change after nucleation of localized slip:





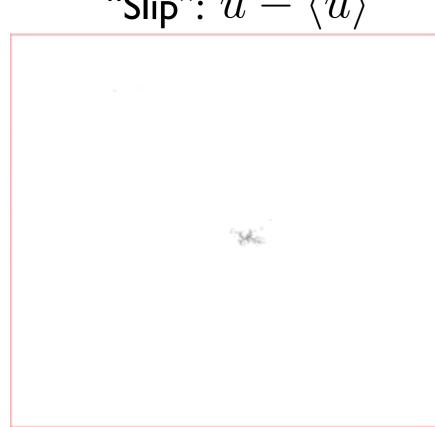
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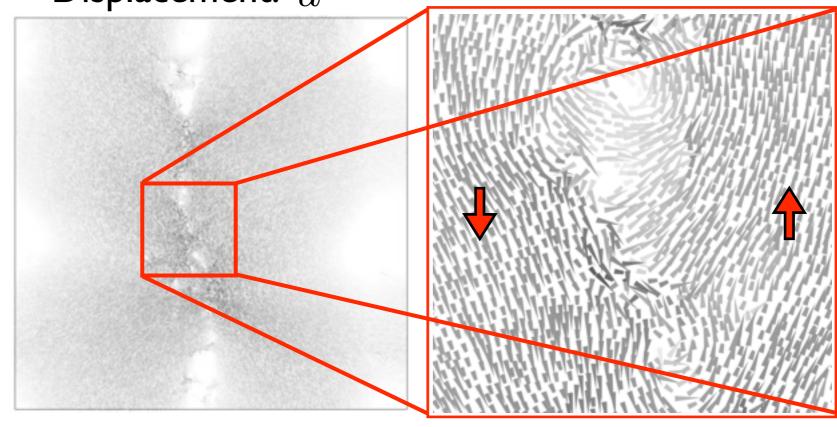
Typical plastic cascade

At the end of the whole cascade, we are left with a slip line:

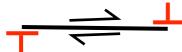
"Slip": $\vec{u} - \langle \vec{u} \rangle$





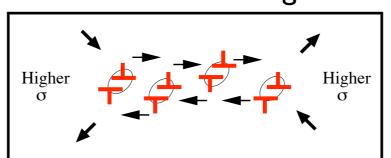


Analogous to dislocation glide:



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But with local shearing zones:

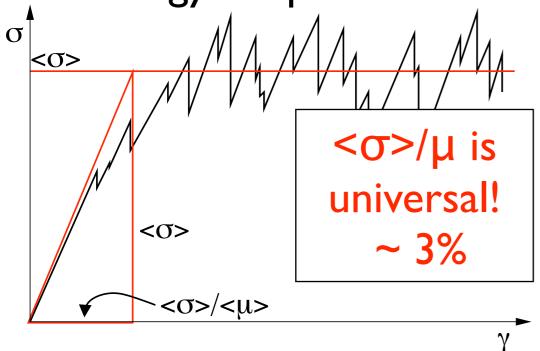


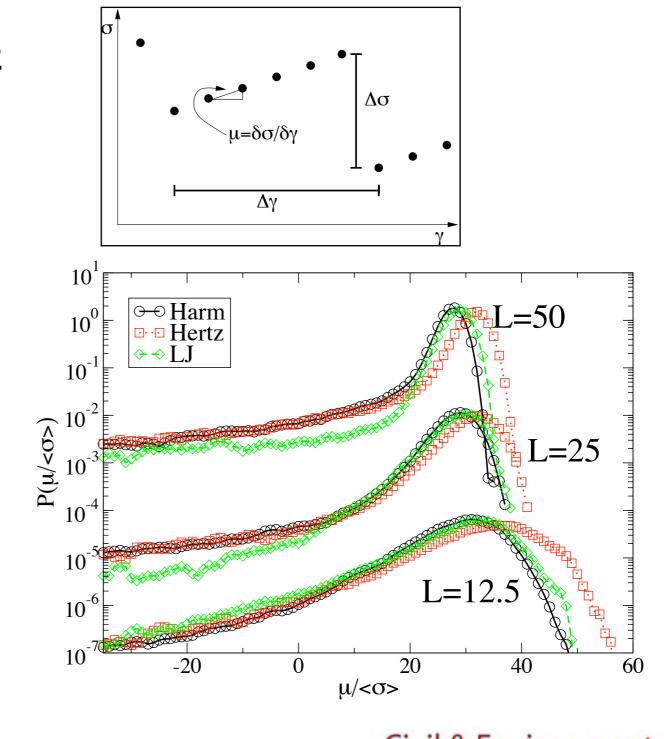
Statistics and size scaling

Collect statistics for different system size and interaction potentials:

- •"Modulus"
- •Elastic interval
- Stress drop

Energy drop



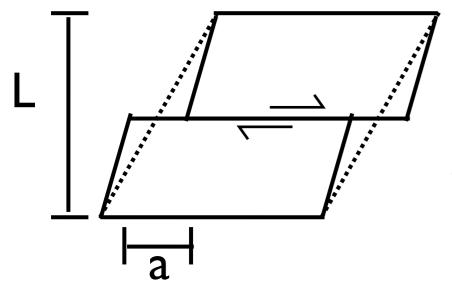


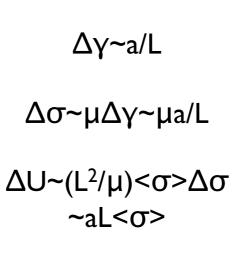
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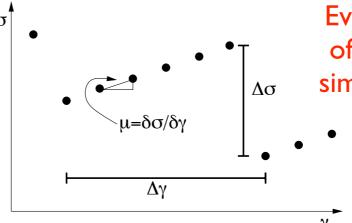
Statistics and size scaling

Collect statistics for different system size and interaction potentials:

- •"Modulus"
- •Elastic interval: $\Delta \gamma$
- •Stress drop: $\Delta \sigma$
- •Energy drop: ΔU

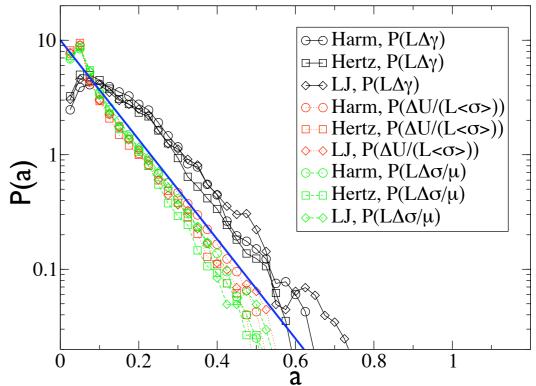






Event size independent of potential and scales simply with system size!





Scaling argument: slip by length "a"

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Summary: Plastic response

- Plastic response is intermittent with large, system-spanning events (avalanches)
- Avalanches composed of clusters of local slip (STZs)
- STZs interact elastically
- Universal yield strain $\varepsilon \sim 3\%$... agrees with experiments
- Universal slip amplitude $a \sim .1$ particle diameters... experiments difficult

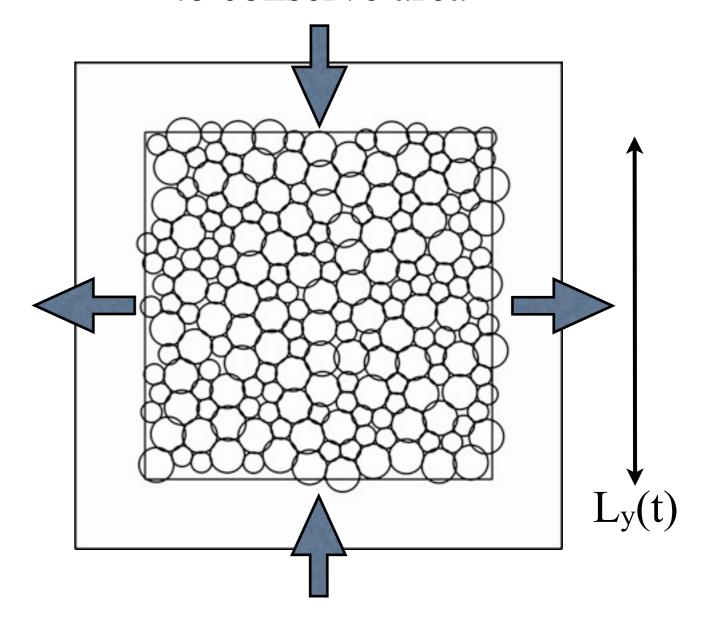




Zero temperature molecular dynamics

- 2D Molecular Dynamics:
 - binary Lennard-Jones quenched at Pressure=0
 - relative velocity damping (Kelvin/DPD)
 - axial, fixed area strain
 - periodic boundaries
 - system sizes up to $3000x3000 \sim 10M$ particles
 - Quasi-static limit (about 500 CPU days / run)

prescribed $L_y(t)$, $L_x(t)$ to conserve area



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Local vorticity, ω

For each triangle:

$$\frac{\partial u_i}{\partial x_j} = F_{ij}$$

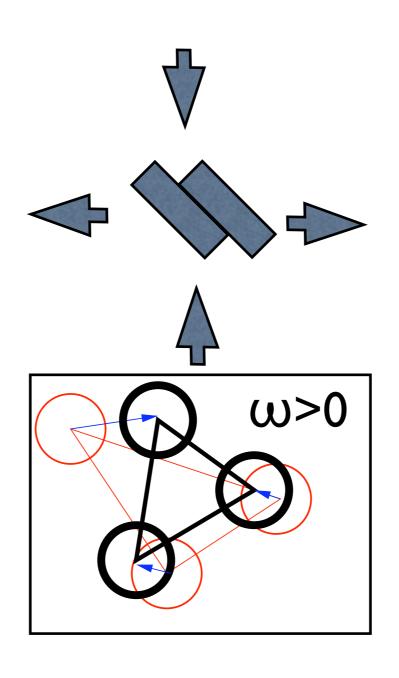
$$\epsilon_1 = \frac{F_{xx} - F_{yy}}{2}$$

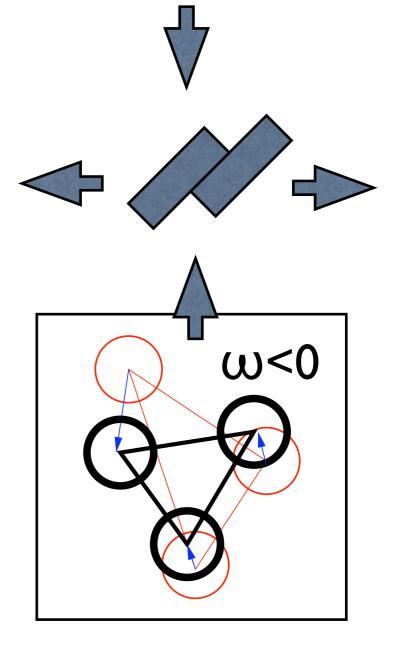
$$\epsilon_2 = \frac{F_{xy} + F_{yx}}{2}$$

Invariants:

$$\epsilon = \sqrt{\epsilon_1^2 + \epsilon_2^2}$$

$$\omega = F_{xy} - F_{yx}$$



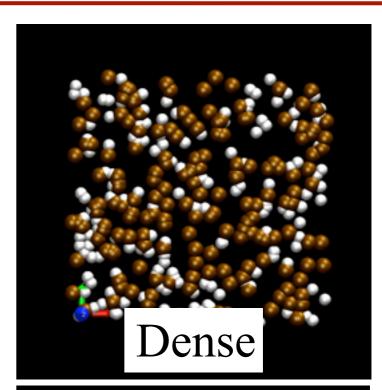


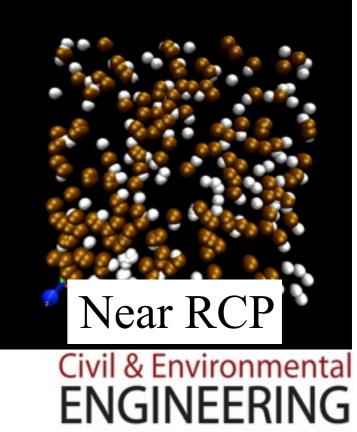
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Future directions

•Recall:

- Differences in elementary physics:
 - Inertial or overdamped?
 - "Real" temperature
 - Dissipation mechanisms / hydrodynamics
 - Coulomb friction
 - Attractive forces / adhesion
- •How do microscopic details affect the intermittency, slip avalanches, elasticity, rheology, and yield?
- Currently looking at:
 - densities near random close packing (RCP)
 - massless (mean field bubbles) and massive (frictionless granular DEM) models.





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