DNA Melting

D. Poland and H.A. Scheraga, *Theory of helix-coil transitions in biopolymers*, 1970R.M. Wartell and A.S. Benight, *Phys. Rep.* 126, 67 (1985)

http://www.biophys.uni-duesseldorf.de/POLAND/poland.html http://www.bioinformatics.org/meltsim/

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B-type double helix

right-handed

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pitch spacing = 34 Å

residues per turn =10

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General features of melting curves from experimental studies

- Short chains (<300 bp or so):
 - --- single peak with a width 0.3-0.7°C
 - peak position depends on relative A-T and G-C contents

 $T_M = 42 \cdot (G+C) + 64^{\circ}C$ at 0.0745M Na⁺

• Medium-sized chains (a few thousand bps)

well resolved peaks spanning over 15°C or so

• Long chains (more than one million bps)

single melting peak spanning over 15°C or so sensitive to compositional variations

Theoretical Issues

- Why is the melting of individual domains so sharp?
- What is the nature of the transition for very long chains?



Ingredients:

- open/close for each bp represented by an Ising variable
- each closed pair has a weight *w_i* (random field)
- each loop of *l* open pairs has a weight $s^* f(l)$ (ferromagnetic coupling)
 - s : loop initiation factor, typically 10⁻⁵

f(l): excess loop entropy, power-law function l^{-b}

| ⁵ ' i ³ ' | 5' i 3' dlog[Na ⁺] T _{ij} ^{1.0M-Na+} | | | T _{ij} 0.0745M-Na+ | | | R D Blake et al |
|----------------------------------|--|--------|--------|-----------------------------|---------------------|------------------------|--|
| 3° j 5' | °C/°K | °C | °K | °C | ΔH_{ij}^{a} | $\Delta S_{ij}^{\ b)}$ | $D^{-1} = \frac{15}{1000}$ |
| $1 \frac{A \cdot T}{T \cdot A}$ | 21.00 | 81.85 | 355.01 | 58.23 | 8.00 | 22.53 | <i>Bioinformatics</i> 15 , 370 (1999) |
| $2 \mathbf{A} \cdot \mathbf{T}$ | 20.11 | 86.72 | 359.88 | 64.10 | 8.31 | 24.64 | |
| A · T 3 A · T | 19.78 | 89.08 | 362.24 | 66.77 | 8.45 | 24.86 | |
| G·C 4 A·T | 17.76 | 99.49 | 372.65 | 79.51 | 9.13 | 24.50 | helix to coil entropy increase: |
| 5 A·T | 17.10 | 103.18 | 376.34 | 83.94 | 9.36 | 24.87 | $\Delta S \simeq 12.5 k_B / bp$ |
| 6 G·C | 16.87 | 104.43 | 377.59 | 85.45 | 9.44 | 25.00 | |
| 7 C·G | 16.21 | 107.96 | 381.12 | 89.72 | 9.67 | 25.37 | |
| 8 G·C | 14.18 | 118.49 | 391.65 | 102.50 | 10.34 | 27.52 | |
| 9 G·C | 13.20 | 124.54 | 397.70 | 109.69 | 10.72 | 26.95 | |
| G·C 10 C·G | 13.20 | 124.61 | 397.77 | 109.76 | 10.72 | 26.95 | |

a) kcal·mol ij^{-1} . b) cal·mol ij^{-1} -deg⁻¹.



Excess free energy of a loop:

$$\Delta G / k_B T \simeq -\ln[\mathbf{s} f(l)] - 2\ln l + l \ln w$$
$$= -(2 - b)\ln l - \ln \mathbf{s} - l\left[\mathbf{a} \frac{\Delta T}{T_M}\right]$$

b > 2: large loops unfavorable $\Rightarrow 1^{st}$ order transition

b < 2: loops of sufficiently large size are excited \Rightarrow continuous transition

Width of the transition region:

minimum loop size:
$$l_c \simeq s^{-1/(2-b)} \simeq 10^{20} \,\mathrm{bp}$$
for $b = 1.75$ (SAW)transition region: $\Delta T \simeq T_M / a l_c = 360 \mathrm{K} / (12.5 \times 10^{20}) \simeq 3 \times 10^{-19} \mathrm{K}$

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Why is this important? ΔH ABBAABAAABBBABABBABBBBAAAAAABABBABA inter-contact region of length L **Exponential tail:** $P(x) = A \exp(qx), \quad x = \Delta H / k_B T$ Energy gain: finding best contact in a segment of length L, $\Delta H_m / k_B T \approx -\frac{1}{q} \ln \left(AL\right)$ \Rightarrow Loop entropy cost: $\Delta s / k_B \approx \mathbf{b} \ln L - \ln \mathbf{s}$ $\Rightarrow \qquad \Delta G/k_{B}T \approx \left(\boldsymbol{b} - \frac{1}{q}\right) \ln L - \ln \boldsymbol{s} - \frac{1}{q} \ln A$ Transition: $q = q_c = 1/b$ $\Rightarrow \qquad \mathbf{x} \sim \exp(-const./|T - T_c|^{1/2}) \qquad \text{Kosterlitz-Thouless!}$



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$$b = \exp(dl) \to 1$$
,

Laplace transform

$$\hat{P}(s) = \int_{-\infty}^{0} dx \exp(sx) P(x)$$

Functional low equation

$$d\hat{P}(s)/dl = \hat{P}\ln\hat{P} + \boldsymbol{b} \ s\Big[\hat{P}(s) - \hat{P}(s+1)\Big]$$

Infinitely many fixed-point solutions:







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