(More on) the String Theory of the Ω Deformation

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Domenico Orlando The String Theory of the Ω Deformation

Why are we	here?	Geometric Representation	Twisted masses	Twisted masses from String Theory	Gauge theory	Conclusions
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- Why are we here?
- 2 Gauge–Bethe Correspondence from Geometric Representation Theory
- 3 Twisted masses
- m 4 Twisted masses from String Theory: the Ω background
- 5 The gauge theory from String Theory
- 6 Conclusions



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Why are we here? ●○○	Geometric Representation	Twisted masses	Twisted masses from String Theory	Gauge theory	Conclusions
Motivatio	n				

- The Gauge–Bethe correspondence in its simplest manifestation is the equivalence of the ground states of a supersymmetric gauge theory and the spectrum in a sector of a spin chain.
- There are years of experience in the study of both sides of the correspondence.
- Main interest: We can translate problems from one side to the other
- Fresh perspective on existing problems
- New questions
- Valuable tool for both sides: new insights.



Why are we here? ○●○	Geometric Representation	Twisted masses	Twisted masses from String Theory	Gauge theory	Conclusions
The mess	age				

- The gauge–Bethe correspondence relates supersymmetric gauge theories to sectors of spin chains
- Spin chains have symmetries that relate different sectors
- Geometric representation theory describes these symmetries as acting on the ground states of the gauge theories
- String theory provides a framework in which these different gauge theories can be treated in a unified way and the spin chain symmetry understood as symmetry enhancement for coincident D-branes.



Why are we here? ○○●	Geometric Representation	Twisted masses	Twisted masses from String Theory	Gauge theory	Conclusions
Today's ta	ılk				

- Today I will try to understand this correspondence in the context of String Theory.
- First, I will rephrase the correspondence in terms of geometric representation theory
- Then, I will introduce a String Theory (D-brane) construction of the correspondence, including all the mass parameters.
- Main result: we understand the symmetry relating gauge theories in terms of strings
- Main result: we propose a construction for the twisted masses (Ω background) in terms of D branes in a non-trivial bulk.



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- The Gauge-Bethe Correspondence
 - The gauge–Bethe correspondence relates the Coulomb branch of certain supersymmetric gauge theories to the Bethe Ansatz equations of integrable systems
 - More precisely it identifies the twisted effective superpotential with the Yang–Yang function
 - The simplest example is the XXX spin chain, whose Bethe Ansatz equations read:

$$\left(\frac{\sigma_i - i/2}{\sigma_i + i/2}\right)^L = \prod_{j \neq i}^N \frac{\sigma_i - \sigma_j - i}{\sigma_i - \sigma_j + i}, \qquad i = 1, \dots, N$$

• These are the same equations that one obtains describing the low energy effective action for a two dimensional $\mathcal{N} = (2, 2)$ theory with gauge group U(N), L fundamentals, L antifundamentals and an adjoint field with twisted masses $m_Q = m_{\tilde{Q}} = -i/2$, and $m_{\oplus} = i$.

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Represent	tations				

• A representation of the algebra su(2) consists in a vector space V and an action of three operators e, f, k satisfying the relations

$$[e, f] = k$$
, $[k, e] = 2e$, $[k, f] = -2f$.

• Given the tensor product of *L* copies of the fundamental representation *V*, there is a natural inclusion of the (L + 1)-dimensional irreducible representation, $V(L) \hookrightarrow V^{\otimes L}$.



Why are we here?	Geometric Representation	Twisted masses	Twisted masses from String Theory	Gauge theory	Conclusions
Spin chaiı	า				

- I will consider the simplest example: the XXX spin chain, with periodic boundary conditions.
- System of L spins on a circle. Each spin can be ↑ or ↓. These are generators of the fundamental representation V of su(2).
- The Hamiltonian is invariant under the action of su(2) defined as

$$E = \sum_{m=1}^{L} \underbrace{\mathbb{1} \otimes \cdots \otimes \mathbb{1}}_{m-1} \otimes e \otimes \mathbb{1} \otimes \cdots \otimes \mathbb{1} \ .$$

• The spectrum of the chain is organized into representation of su(2):

$$\mathscr{H} = \mathsf{V}^{\otimes \mathsf{L}} = \bigoplus_{N=0}^{\mathsf{L}} \mathsf{V}_{\mathsf{L}-2N} \,.$$

 V_{L-2N} : magnon states. This is **not** the decomposition into irreps.



The Poor Man's Introduction to Geometric Representation

• Each of the terms $H_*[T^*Gr(N,L), \mathbb{C}]$ is identified with the (L-2N) weight space, which has dimension $\binom{L}{N}$:

$$H_*[T^*\mathrm{Gr}(L)] \simeq V^{\otimes L} = \bigoplus_{N=0}^L V_{L-2N} \simeq \bigoplus_{N=0}^L H_*[T^*\mathrm{Gr}(N,L)].$$

• The key point of the construction is the definition of the operators e and *f* which act between the homologies,

$$e, f: H_*[T^*Gr(L)] \to H_*[T^*Gr(L)].$$

In particular, we need f to act between two components of Gr(L), raising N by 1:

$$f: H_*[T^*\mathrm{Gr}(N,L)] \to H_*[T^*\mathrm{Gr}(N+1,L)].$$



where Z is the diagonal part of the cotangent bundle of the product of two Grassmannians:

 $Z = \{ (X, U_N, U'_{N+1}) \mid U_i \in Gr(N_i, L), X \in End(\mathbb{C}^L), U \subset U', X(\mathbb{C}^L) \subset U, X(U') = 0 \} .$

• Define the Hecke operator f by first acting with the pullback π_1^* , then intersecting with the fundamental class [Z] and finally acting with the pushforward π_{2*} :

$$f: H_*[T^*Gr(N, L)] \to H_*[T^*Gr(N + 1, L)]$$

 $x \mapsto f(x) = \pi_{2*}([Z] \cap \pi_1^*(x)).$



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The Poor Man's Introduction to Geometric Representation

• The spaces $H_*[T^*Gr(N, L)]$ are eigenspaces for k:

$$k = \bigoplus_{N=0}^{L} \left(L - 2N \right) \mathbb{1}_{H_*[T^* \mathrm{Gr}(N,L)]},$$

• as we wanted, the L - 2N weight space is precisely the homology of $T^*Gr(N, L)$:

 $H_*[T^*\mathrm{Gr}(N,L)] = \{ x \in H_*[T^*\mathrm{Gr}(L)] \simeq V^{\otimes L} \mid kx = (L-2N)x \} \simeq V_{L-2N}.$

• summing over all these spaces:

$$H_*[T^*Gr(L)] \simeq V^{\otimes L} = \bigoplus_{N=0}^{L} V_{L-2N} \simeq \bigoplus_{N=0}^{L} H_*[T^*Gr(N,L)].$$



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The Gauge–Bethe correspondence revisited

- The direct sum of the homologies of the cotangent bundles over the Grassmannians of \mathbb{C}^L corresponds to the ground states of the non-linear sigma models on all the $T^*Gr(N,L)$ for N = 0, 1, ..., L.
- Via geometric representation theory, this space can be given the structure of the $V^{\otimes L}$ representation of su(2)
- The Hilbert space of the $xxx_{1/2}$ spin chain has the same structure.
- The homology of the Grassmannian $H_*[T^*Gr(N,L)]$ is the (L-2N) weight space V_{L-2N} , which is spanned by the spectrum of the $xxx_{1/2}$ chain in the N magnon sector
- There is a one-to-one correspondence between the minima of the twisted superpotential of the nlsm and the solutions to the Bethe Ansatz (gauge/Bethe correspondence as an isomorphism of modules).



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Another o	dictionary				
	physics		mather	matics	
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g	round states of xx	×1/2	hw representation $V(L) \simeq H_{top}[T^*Gr(L)]$		
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Wh oc	y are we here? O	Geometric Representation	Twisted masses	Twisted masses from String Theory	Gauge theory	Conclusions		
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Gauge the	eory				

- $H^*[T^*Gr(N,L)]$: the ground states of a two dimensional U(N) theory with L fundamentals, L antifundamentals and one adjoint
- String Theory: *N* D2 branes stretching between two NS5 branes with *L* perpendicular D4 branes

	0		2	3	4	5	6	7	8	9
NS5 ^{1,2}	×	×					×	×	×	×
D_2	\times	\times	\times							
D_4	×	\times		\times	\times	×				



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NS5 ^{1,2}	×	×					×	×	×	×
D_2	×	\times	\times							
D4	×	×		×	×	×				



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$NS5^{1,2}$	×	×					×	×	×	×	-
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Twisted m	asses				

• Can we go home? Not yet: the gauge theory has an exotic ingredient: twisted masses for the adjoint and the hypers

$$\int d^4\theta X^{\dagger} e^{\theta - \bar{\theta}^+ \widetilde{m}_X + \text{h.c.}} X$$

- neither superpotential nor twisted superpotential terms.
- They cannot be viewed as perturbations of the action symmetric under a fixed superalgebra
- They are associated with a deformation of the superalgebra itself.
- A real twisted mass in 2D can be understood by lifting to an $\mathcal{N}=2$ theory in 3 dimensions.
- The lifted deformation (real mass) gives a central extension of the undeformed theory:

$$\{Q_{\alpha},\bar{Q}_{\beta}\}= \Gamma^{\mu}_{\alpha\beta} P_{\mu} + \delta_{\alpha\beta} Z,$$

where $Z \equiv m^l q_l$ is a linear combination of non-R global symmetries q_l .

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Real mas	ses				

- This leads to a simple and general construction of the twisted mass deformation in the general case:
- Couple a fictitious (nondynamical) vector multiplet { $A_{0,1,2}, \sigma$ } to the theory, for each Abelian global symmetry.
- Give the real (appropriately normalized) fields σ^{I} fixed values m^{I} .
- This preserves $\mathcal{N} = 2$ SUSY in 3 dimensions, but adds the central extension Z.
- This construction gives a simple sufficient condition for real mass deformations of theories with superpotentials which must remain invariant under the U(1) symmetry Z.
- Simplest non-trivial example:

$$W=\tilde{Q}\oplus Q\,,$$

implies
$$m_Q + m_{\oplus} + m_{\tilde{Q}} = 0$$
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Real mass	s terms from	four dime	nsions		

- For certain 3D theories there's an even simpler description: those that lift to 4D.
- This assumes the global symmetries are exact in 4D as well.
- Then the σ field lifts to $A_{\tilde{8}}$ where $\tilde{8}$ is the fourth dimension we're lifting to and A is again the nondynamical Abelian gauge field.
- The vev of σ in three dimensions corresponds to a compactification with monodromy $\tilde{R}m_lq^l$ this is the integral of the gauge connection around the fourth dimension.
- Then the fields have generalized momenta $Z = m_l q^l$ and thus Kaluza-Klein masses $Z = |m_l q^l|$.







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Fluxbrane	background			

- The fluxbrane background is obtained starting from flat space in ten dimensions and imposing identifications.
- $\bullet\,$ The D2 brane comes from a D3 brane, extended in the directions 0128
- we give a complex structure to the remaining six

$$w_1 = y_1 + iy_2 = \rho_1 e^{i \theta_1}, \quad w_2 = y_3 + iy_4 = \rho_2 e^{i \theta_2}, \quad w_3 = y_5 + iy_6,$$

• we impose the identification

$$\widetilde{x}_8 \simeq \widetilde{x}_8 + 2\pi \widetilde{R}, \qquad \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} \simeq \begin{pmatrix} e^{2\pi i m \widetilde{R}} & 0 \\ 0 & e^{-2\pi i m \widetilde{R}} \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}$$

• In terms of coordinates:

$$\begin{cases} \widetilde{x}_8 \simeq \widetilde{x}_8 + 2\pi \widetilde{R} k_1 ,\\ \theta_1 \simeq \theta_1 + 2\pi m \widetilde{R} k_1 ,\\ \theta_2 \simeq \theta_2 - 2\pi m \widetilde{R} k_1 , \end{cases} \qquad k_1 \in \mathbb{Z} ,$$

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The Ω background

• Introduce $\varphi_1 = \theta_1 - m\widetilde{x}_8$, $\varphi_2 = \theta_2 + m\widetilde{x}_8$. The flat space metric:

$$\begin{split} \widetilde{\mathrm{ds}^2} &= \mathrm{d}\vec{x}_{0...3}^2 + \mathrm{d}\rho_1^2 + \rho_1^2 \,\mathrm{d}\varphi_1^2 + \mathrm{d}\rho_2^2 + \rho_2^2 \,\mathrm{d}\varphi_2^2 \\ &+ 2m \left(\rho_1^2 \,\mathrm{d}\varphi_1 - \rho_2^2 \,\mathrm{d}\varphi_2\right) \mathrm{d}\vec{x}_8 + \left(\mathrm{I} + m^2 \left(\rho_1^2 + \rho_2^2\right)\right) \mathrm{d}\vec{x}_8^2 + \mathrm{d}x_9^2 \,, \end{split}$$

• or, in rectilinear coordinates

$$x_4 + i x_5 \equiv \rho_1 e^{i \varphi_1}, \qquad \qquad x_6 + i x_7 \equiv \rho_2 e^{i \varphi_2},$$

the metric becomes the Ω -deformation of flat space with $\varepsilon_1 = -\varepsilon_2 = m$:

$$d\vec{x}_{0...3}^{2} + \sum_{i=4}^{7} (dx_{i} + mV^{i} d\widetilde{x}_{8})^{2} + d\widetilde{x}_{8}^{2} + dx_{9}^{2},$$

where $V^i \partial_i$ is the Killing vector

$$V^i\partial_i = -x^5\partial_{x_4} + x^4\partial_{x_5} + x^7\partial_{x_6} - x^6\partial_{x_7} = \partial_{\varphi_1} - \partial_{\varphi_2}$$

Why are we here?	Geometric Representation	Twisted masses	Twisted masses from String Theory 00●0000	Gauge theory	Conclusions
The fluxtr	ab hackgrour	nd			

- To get the real mass we need to T-dualize in x₈, in order to get a D₂ brane
- The resulting background is a fluxtrap:

$$\begin{split} \mathrm{d}s^2 &= \mathrm{d}\vec{x}_{0\dots3}^2 + \mathrm{d}\rho_1^2 + \mathrm{d}\rho_2^2 + \rho_1^2 \,\mathrm{d}\varphi_1^2 + \rho_2^2 \,\mathrm{d}\varphi_2^2 \\ &\quad + \frac{-m^2 \left(\rho_1^2 \,\mathrm{d}\varphi_1 - \rho_2^2 \,\mathrm{d}\varphi_2\right)^2 + \mathrm{d}x_8^2}{1 + m^2 \left(\rho_1^2 + \rho_2^2\right)} + \mathrm{d}x_9^2 \,, \\ B &= m \, \frac{\rho_1^2 \,\mathrm{d}\varphi_1 - \rho_2^2 \,\mathrm{d}\varphi_2}{1 + m^2 \left(\rho_1^2 + \rho_2^2\right)} \wedge \mathrm{d}x_8 \,, \\ \mathrm{e}^{-\Phi} &= \frac{\sqrt{1 + m^2 \left(\rho_1^2 + \rho_2^2\right)}}{g_3^2 \sqrt{\alpha'}} \,. \end{split}$$

• The effective theory for a D₂ brane in this background acquires a real mass term *m*.

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The NS5 fluxtrap

Even if we can't use linearity, it is still possible to add an $\ensuremath{\mathsf{NS}}_5$ brane in the bulk, impose the identifications and T-dualize:

$$ds^{2} = U \left[dx_{2}^{2} + dx_{3}^{2} + d\rho_{1}^{2} \right] + d\rho_{2}^{2} + \frac{U \rho_{1}^{2} \left[d\varphi_{1}^{2} + m^{2} \rho_{2}^{2} (d\varphi_{1} + d\varphi_{2})^{2} \right] + \rho_{2}^{2} d\varphi_{2}^{2}}{\Delta^{2}} \\ + \frac{\Lambda^{2}}{(x_{3}^{2} + \rho_{1}^{2}) \Delta^{2}} \left[\left(x_{3}^{2} + \rho_{1}^{2} \right) dx_{2} - x_{2}x_{3} dx_{3} - x_{2} \rho_{1} d\rho_{1} + \frac{\sqrt{x_{3}^{2} + \rho_{1}^{2}} dx_{8}}{\Lambda} \right]^{2}, \\ B = \frac{\Lambda \left[- (x_{3}^{2} + \rho_{1}^{2}) dx_{2} + x_{2}x_{3} dx_{3} + x_{2} \rho_{1} d\rho_{1} \right] \Lambda \left[(1 + m^{2} \rho_{2}^{2}) d\varphi_{1} + m^{2} \rho_{2}^{2} d\varphi_{2} \right]}{m (x_{3}^{2} - \rho_{1}^{2}) \Delta^{2}} \\ - m \frac{U \rho_{1}^{2} d\varphi_{1} - \rho_{2}^{2} d\varphi_{2}}{\Delta^{2}} \wedge dx_{8}, \\ e^{-\Phi} = \frac{1}{g_{3}^{2} \sqrt{\alpha'}} \sqrt{\frac{1 + m^{2} (U \rho_{1}^{2} + \rho_{2}^{2})}{U}},$$

where

e

$$U = 1 + \frac{N5 a'}{x_2^2 + x_3^2 + \rho_1^2}, \quad \Delta^2 = 1 + m^2 \left(U \rho_1^2 + \rho_2^2 \right), \quad \Lambda = \frac{2mx_3 \left(x_3^2 + \rho_1^2 \right)}{\left(x_2^2 + x_3^2 + \rho_1^2 \right)^2 \Delta}.$$

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Supersym	metry				

- One can understand the supersymmetries of this string theory solution starting from the type IIB picture (D3 brane)
- In the initial flat background (prior to identifications), there are 32 Killing spinors

$$\mathcal{K}^{IIB} = \exp[\frac{1}{2}\theta_{I} \upharpoonright_{45} + \frac{1}{2}\theta_{2} \upharpoonright_{67}]\varepsilon_{0},$$

where ε_0 is a complex Weyl spinor.

• Introducing φ_1 and φ_2 , this becomes

$$\mathcal{K}^{\prime\prime\prime B} = \exp[\frac{1}{2}\varphi_{1} \Gamma_{45} + \frac{1}{2}\varphi_{2} \Gamma_{67}] \exp[\frac{m\widetilde{R}\widetilde{u}}{2} (\Gamma_{45} - \Gamma_{67})] \varepsilon_{0}.$$

• In the generic case the second exponential must vanish to preserve periodicity. Introduce the orthogonal projectors

$$\label{eq:flux} \Pi^{flux}_{\pm} = \tfrac{l}{2} \left(\mathbbm{1} \pm \Gamma_{4567} \right) \, ,$$

Why are we here?	Geometric Representation	Twisted masses	Twisted masses from String Theory	Gauge theory	Conclusions
Subersym	metrv				

• The fluxtrap background preserves 16 supersymmetries. In the type IIA picture the Killing spinors are:

$$\begin{cases} \varepsilon_L = (\mathbb{1} + \Gamma_{11}) \sqcap^{\text{flux}}_{-} \exp[\frac{1}{2}\varphi_1 \Gamma_{45} + \frac{1}{2}\varphi_2 \Gamma_{67}] \varepsilon_0, \\ \varepsilon_R = (\mathbb{1} - \Gamma_{11}) \Gamma_u \sqcap^{\text{flux}}_{-} \exp[\frac{1}{2}\varphi_1 \Gamma_{45} + \frac{1}{2}\varphi_2 \Gamma_{67}] \varepsilon_1, \end{cases}$$

• The NS5-fluxtrap background preserves 8 supersymmetries. In the type IIA picture the Killing spinors are:

$$\begin{cases} \varepsilon_{L} = (\mathbb{1} + \Gamma_{11}) \sqcap_{-}^{\mathsf{NS5}} \sqcap_{-}^{\mathsf{flux}} \exp[\frac{1}{2}\varphi_{1}\Gamma_{45} + \frac{1}{2}\varphi_{2}\Gamma_{67}] \varepsilon_{0} \\ \varepsilon_{R} = (\mathbb{1} - \Gamma_{11}) \Gamma_{u} \sqcap_{+}^{\mathsf{NS5}} \sqcap_{-}^{\mathsf{flux}} \exp[\frac{1}{2}\varphi_{1}\Gamma_{45} + \frac{1}{2}\varphi_{2}\Gamma_{67}] \varepsilon_{1} \end{cases}$$

where ε_0 and ε_\perp are constant Majorana spinors,

$$\square^{\mathsf{NS5}}_{\pm} = \tfrac{1}{2} \left(\mathbbm{1} \pm \sqcap_{2345} \right) \,,$$

and

$$\Gamma_{u} = \frac{m\rho_{1}\sqrt{U}}{\Delta}\Gamma_{5} - \frac{m\rho_{2}}{\Delta}\Gamma_{7} + \frac{1}{\Delta}\Gamma_{8}$$

The String Theory of the Ω Deformation

Why are we here?	Geometric Representation	Twisted masses	Twisted masses from String Theory 000000●	Gauge theory	Conclusions
A tale of	many epsilons				

- For our problem we only need to get one real (imaginary) twisted mass. Nevertheless, the construction can be easily generalized:
- Wilson loops in another direction (say x_9) will give a complex ε
- Identifications involving other complex planes will give more ε 's. In order to preserve supersymmetry:

$$\sum_{i} \varepsilon_{i} = 0$$

• Example: 3 real independent ε 's:

$$\widetilde{x}_{8} \simeq \widetilde{x}_{8} + 2\pi \widetilde{R}$$

$$\begin{pmatrix} x_{1} + ix_{9} \\ x_{2} + ix_{3} \\ x_{4} + ix_{5} \\ x_{6} + ix_{7} \end{pmatrix} \simeq \begin{pmatrix} e^{2\pi i \varepsilon_{1}} \\ e^{2\pi i \varepsilon_{2}} \\ e^{2\pi i \varepsilon_{3}} \\ e^{2\pi i \varepsilon_{3}} \\ e^{-2\pi i (\varepsilon_{1} + \varepsilon_{2} + \varepsilon_{3})} \end{pmatrix} \begin{pmatrix} x_{1} + ix_{9} \\ x_{2} + ix_{3} \\ x_{4} + ix_{5} \\ x_{6} + ix_{7} \end{pmatrix}$$

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D2 brane	s in the fluxtr	ab			

- Now we have all the ingredients to write our gauge theory.
- The D₂ branes are embedded in the NS-fluxtrap background

direction	0		2	3	4	5	6	7	8	9
NS5	×	×					×	×	×	×
fluxtrap	×	\times	\times	\times						×
D2	\times	\times	\times							
D4	\times	\times		\times	×	\times				

• From the point of view of the gauge theory on the D₂ branes

- $x_8 + i x_9 = \sigma$ (twisted chiral)
- $x_6 + i x_7 = \oplus$ (chiral adjoint)
- the separation of the NS $_5$ in x_3 is the Fayet-Iliopoulos term
- the separation of the NS5 in x_2 is $1/g^2$



Why are we here?	Geometric Representation	Twisted masses	Twisted masses from String Theory	Gauge theory ○●○○○○	Conclusions
The Do h	rano as a RD	Sobject			

The D_2 brane as a BPS object

Consider the static embedding

$$F_{\alpha\beta} = 0, \ x_0 = \zeta^0, \ x_1 = \zeta^1, \ x_2 = \zeta^2, \ \phi_1 = \omega \ \zeta^0, \ \phi_2 = -\omega \ \zeta^0.$$

The bosonic part of the DBI action reads

$$S = -\mu_2 \int d^3 \zeta \sqrt{1 - \frac{1 - \Delta^2 \left(1 + \Lambda^2 / U\right)}{m^2} \left(m^2 - \omega^2\right)}.$$

The equations of motion can be satisfied in two ways:

- if $\rho_1 = \rho_2 = x_3 = 0$. This is a static D₂ brane sitting in the trap.
- if $\omega = m$. This is a rotating D2 brane. A nice feature is that we are not in the linearized approximation but the frequency is fixed only by the twisted mass m and is independent of the amplitude.



Why are we here?	Geometric Representation	Twisted masses	Twisted masses from String Theory	Gauge theory	Conclusions
Static Em	bedding				

The supersymmetries preserved by the static embedding are those such that

 $\varepsilon_L = \Gamma_{\mathsf{D2}} \varepsilon_R.$

• Without the NS5 there are 8 preserved supercharges ($\mathcal{N}=2$ theory in 3d)

• With the NS5 there are 4 preserved supercharges ($\mathcal{N}=(2,2)$ theory in 2d)

$$\begin{cases} \varepsilon_{L} = (\mathbb{1} + \Gamma_{11}) \sqcap_{-}^{\mathsf{NS5}} \sqcap_{-}^{\mathsf{flux}} \Gamma_{1208} \exp[\frac{1}{2}(\varphi_{1} + \varphi_{2}) \Gamma_{67}] \varepsilon_{2}, \\ \varepsilon_{R} = (\mathbb{1} - \Gamma_{11}) \Gamma_{u} \sqcap_{+}^{\mathsf{NS5}} \sqcap_{-}^{\mathsf{flux}} \exp[\frac{1}{2}(\varphi_{1} + \varphi_{2}) \Gamma_{67}] \varepsilon_{2}. \end{cases}$$

Why are we here?	Geometric Representation	Twisted masses	Twisted masses from String Theory	Gauge theory	Conclusions
Rotating I	Embedding				

The rotating embedding ($\omega = m$) works in the same way and preserves

• 4 real supercharges without the NS5

$$\begin{cases} \varepsilon_L = (\mathbb{1} + \Gamma_{11}) \sqcap^{\text{flux}}_{-} \Gamma_{1208} \exp[\frac{1}{2}(\varphi_1 + \varphi_2) \Gamma_{67}] (\mathbb{1} \mp \Gamma_{08}) \varepsilon_2, \\ \varepsilon_R = (\mathbb{1} - \Gamma_{11}) \Gamma_u \sqcap^{\text{flux}}_{-} \exp[\frac{1}{2}(\varphi_1 + \varphi_2) \Gamma_{67}] (\mathbb{1} \mp \Gamma_{08}) \varepsilon_2. \end{cases}$$

• 2 real supercharges in presence of the NS5

$$\begin{cases} \varepsilon_{L} = (\mathbb{1} + \Gamma_{11}) \sqcap_{-}^{\mathsf{NS5}} \sqcap_{-}^{\mathsf{flux}} \Gamma_{1208} \exp[\frac{1}{2} (\varphi_{1} + \varphi_{2}) \Gamma_{67}] (\mathbb{1} \mp \Gamma_{08}) \varepsilon_{2}, \\ \varepsilon_{R} = (\mathbb{1} - \Gamma_{11}) \Gamma_{u} \sqcap_{+}^{\mathsf{NS5}} \sqcap_{-}^{\mathsf{flux}} \exp[\frac{1}{2} (\varphi_{1} + \varphi_{2}) \Gamma_{67}] (\mathbb{1} \mp \Gamma_{08}) \varepsilon_{2}. \end{cases}$$



 Why are we here?
 Geometric Representation
 Twisted masses
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 Conclusions

The last thing that remains to do is to show how the D₂ branes in the fluxtrap background acquire a twisted mass. We simply need to write the Dirac–Born–Infeld action at quadratic order:

$$S = -\mu_2 \int d^3 \zeta \ e^{-\Phi} \sqrt{-\det(g_{\alpha\beta} + B_{\alpha\beta})} \left[1 - \frac{1}{2} \bar{\psi} \left((g+B)^{\alpha\beta} \Gamma_{\beta} D_{\alpha} + \Delta^{(1)} \right) \psi \right],$$

where

$$D_{a} = \partial_{a} X^{\mu} \left(\nabla_{\mu} + \frac{1}{8} H_{\mu m n} \Gamma^{m n} \right), \quad \Delta^{(1)} = \frac{1}{2} \Gamma^{m} \partial_{m} \Phi - \frac{1}{24} H_{m n p} \Gamma^{m n p}$$

Then we expand all the terms at their respective leading order in the fields:

$$\begin{split} g_{\mu\nu} \, dX^{\mu} \, dX^{\nu} &= d\vec{x}_{0...9}^2 + \mathcal{O}(X^4) \,, \\ H_{\mu\nu\rho} \, dX^{\mu} \wedge dX^{\nu} \wedge dX^{\rho} &= 2m \left(\rho_{\perp} d\rho_{\perp} \wedge d\phi_{\perp} - \rho_{2} d\rho_{2} \wedge d\phi_{2}\right) \wedge dx_{8} + \mathcal{O}(X^5) \,, \\ e^{-\Phi} &= \frac{1}{g_{3}^2 \sqrt{\alpha'}} \left(1 + \frac{m^2}{2} \left(\rho_{\perp}^2 + \rho_{2}^2\right)\right) + \mathcal{O}(X^4) \,. \end{split}$$



Why are we here?	Geometric Representation	Twisted masses	Twisted masses from String Theory	Gauge theory ○○○○○●	Conclusions			
DBL action for the D2 brane								

• From the dilaton we get a term

$$m^2\left(\rho_1^2+\rho_2^2\right)$$

• From the **B-field** we get the mass for the fermions:

$$\frac{m}{2}\bar{\psi}\left(\Gamma_{45}-\Gamma_{67}\right) \Gamma_{8}\psi$$

Putting everything together we reproduce the expected form for the real mass term in three dimensions:

$$\begin{split} S &= \frac{I}{8\pi^2 g_3^2 (\alpha')^2} \int d^3 \zeta \left[\dot{z}_1 \dot{\bar{z}}_1 + \dot{z}_2 \dot{\bar{z}}_2 - m^2 \left(z_1 \bar{z}_1 + z_2 \bar{z}_2 \right) \right. \\ &\left. - \bar{\psi} \, \Gamma_0 \dot{\psi} - im \, \bar{\psi} \left(\Pi_-^{z_1} - \Pi_-^{z_2} \right) \Gamma_8 \psi \right], \end{split}$$



Why are we here?	Geometric Representation	Twisted masses	Twisted masses from String Theory	Gauge theory	Conclusions
Outline					

Why are we here?

2 Gauge-Bethe Correspondence from Geometric Representation Theory

3 Twisted masses

 $oldsymbol{4}$ Twisted masses from String Theory: the Ω background

5 The gauge theory from String Theory





Why are we here?	Geometric Representation	Twisted masses	Twisted masses from String Theory	Gauge theory	Conclusions •000
What hav	re we seen?				

- The gauge–Bethe correspondence is special because it relates a single spin chain to different gauge theories
- This suggests the existence of symmetries relating different gauge theories. We want to understand them in terms of String Theory.
- We propose a new approach in which the twisted masses result from a non-trivial bulk theory
- The bulk provides a natural embedding of the Ω background in string theory (as an exact CFT)
- It is easy to study the possible deformations (more than one ε , reality conditions, ...)
- It is easy to understand the supersymmetry properties, in terms of BPS objects in the bulk



Why are we here?	Geometric Representation	Twisted masses	Twisted masses from String Theory	Gauge theory	Conclusions 0000	
To do						

• Now we have a complete setup in which to study the gauge–Bethe correspondence, choosing the most appropriate duality frame



• We can generalize the action of the *su*(2) beyond the vacua. At strong coupling the full spectrum is organized under *su*(2) and we know for sure that there are BPS states that are protected and do not decouple.



Why are we here?	Geometric Representation	Twisted masses	Twisted masses from String Theory	Gauge theory	Conclusions 00●0
To do					

- Beyond the correspondence: one can study other gauge theories describing different kinds of branes in the same background
- Natural example: start with a Euclidean brane extended in 4, 5, 6, 7, 8 and reduce (T-dualize) on 8

direction	0		2	3	4	5	6	7	8	9
fluxtrap	×	×	×	×						×
E4					×	\times	×	\times		

- The E₄ extended in 4, 5, 6, 7 embedded in the fluxbrane background describe the Ω deformation of $\mathcal{N} = 4$ super-Yang–Mills
- The same bulk that produced the twisted mass, now generates a position-dependent gauge coupling

$$g_{4\Omega}^2 \propto \frac{1}{\sqrt{1 + \varepsilon^2 \left(\rho_1^2 + \rho_2^2\right)}}$$

and the instantons are localized in the trap set by the dilaton in the bulk.



