

SIMPLIFYING MODELS WITHOUT LOSING BIOCHEMICAL COMPLEXITY

Natalie Arkus, Michael Brenner Division of Engineering and Applied Sciences, Cambridge, Massachusetts

Models in Biology

There is an abundance of biological models containing many equations and free parameters.

Two examples:

Heat Shock Response (HSR) in *E. coli*: (El Samad et al., PNAS, 102, 2736-2741)

 β -catenin Degradation in the Wnt Signaling Pathway:

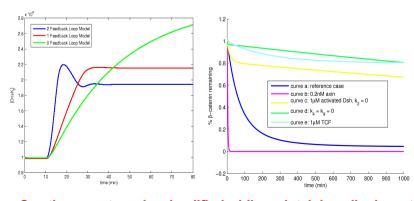
(Lee et al., PloS Biology, 1, 116-132)



Yet, the biological data to which the models are fit are relatively simple:

HSR:

Wnt Signaling:



Can these systems be simplified while maintaining all relevant biological information?

Application of Dominant Balance

Example of Dominant Balance:

$$10000 = 6000 + 3900 + 10 + 20 + 60 + .01 + .0004 + 5 + 3 + 1.9896$$

$$\approx 6000 + 3900$$

Applied to Biological Models:

Step 1: Look for a separation of time or concentration flux scales \rightarrow this will allow differential equations to be approximated as algebraic.

Example:

$$\frac{dx_1}{dt} = x_1x_2 - 0.003x_1$$

$$\frac{dx_2}{dt} = x_1^2 - 0.3x_2$$

x2 degrades and thus equilibrates relatively quickly

$$\implies 0 \approx x_1^2 - 0.3x_2$$

The system can therefore be simplified from 2 ODEs to 1:

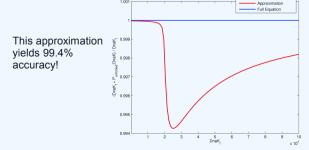
$$\frac{dx_1}{dt} = \frac{x_1^3}{0.3} - 0.003x_1$$

Step 2: Approximate algebraic equations by keeping only the most dominant terms.

Example:

$$[DnaK_f] = [DnaK_t] - [P_{unfolded} : DnaK] - [\sigma^{32} : DnaK]$$

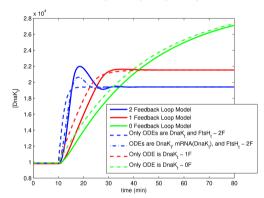
$$\approx [DnaK_t] - [P_{unfolded} : DnaK]$$



Simplified Biological Models that Retain all Biological Information

The reduced HSR system:

$$\begin{array}{lcl} \frac{d[DnaK_t]}{dt} & = & K_{tr1}\frac{A}{B+C[DnaK_t]+D[FtsH_t]} - \alpha_{prot}[DnaK_t] \\ \\ \frac{d[FtsH_t]}{dt} & = & K_{tr2}\frac{A}{B+C[DnaK_t]+D[FtsH_t]} - \alpha_{prot}[FtsH_t] \end{array}$$



The reduced model of the Wnt signaling pathway:

$$\frac{dx_3}{dt} = Ax_{12} - k_5x_3$$

$$\frac{dx_{11}}{dt} = \frac{-x_{11}(k_9x_3 + k_{13})(K_{16} + x_{11})^2}{K_8(1 + TCF^0K_{16})}$$

$$\frac{dx_{12}}{dt} = -Bx_{12}$$

$$\frac{-Full 7 ODE \text{ system}}{\text{Reduced system for curve a consisting of } x_3 \text{ and } x_{11}}{\text{Reduced system for curve b consisting of } x_3, x_{11}, \text{ and } x_{12}}$$

$$-Full 7 ODE \text{ system, curve b}}{\text{Reduced system for curve d consisting of } x_2, x_3, \text{ and } x_{11}}$$

$$-Full 7 ODE \text{ system, curve d}}{\text{Reduced system for curve d consisting of only } x_{11}}$$

$$-Full 7 ODE \text{ system, curve d}}{\text{Reduced system for curve d consisting of only } x_{11}}$$

$$-Full 7 ODE \text{ system, curve d}}{\text{Reduced system for curve e consisting of only } x_{11}}$$

$$-Full 7 ODE \text{ system, curve d}}{\text{Reduced system for curve e consisting of only } x_{11}}$$

$$-Full 7 ODE \text{ system, curve d}}{\text{Reduced system for curve e consisting of only } x_{11}}$$

For both systems, A, B, C, and D are simply constants that are functions of the original parameters and variables of the system

For example, for the Wnt signaling pathway

$$A = \frac{k_4 k_6 G S K^0 x_{12} A P C^0}{K_7 (k_3 x_2 + k_4 + k_{-6})}$$