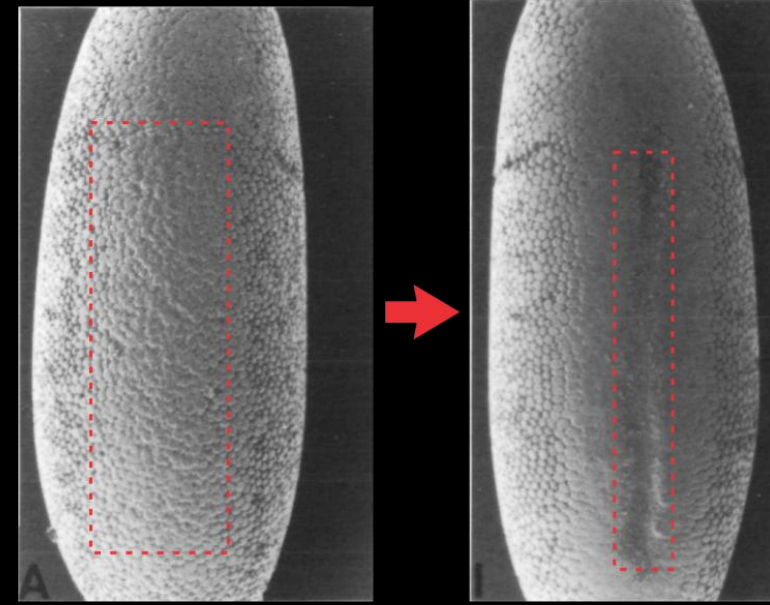
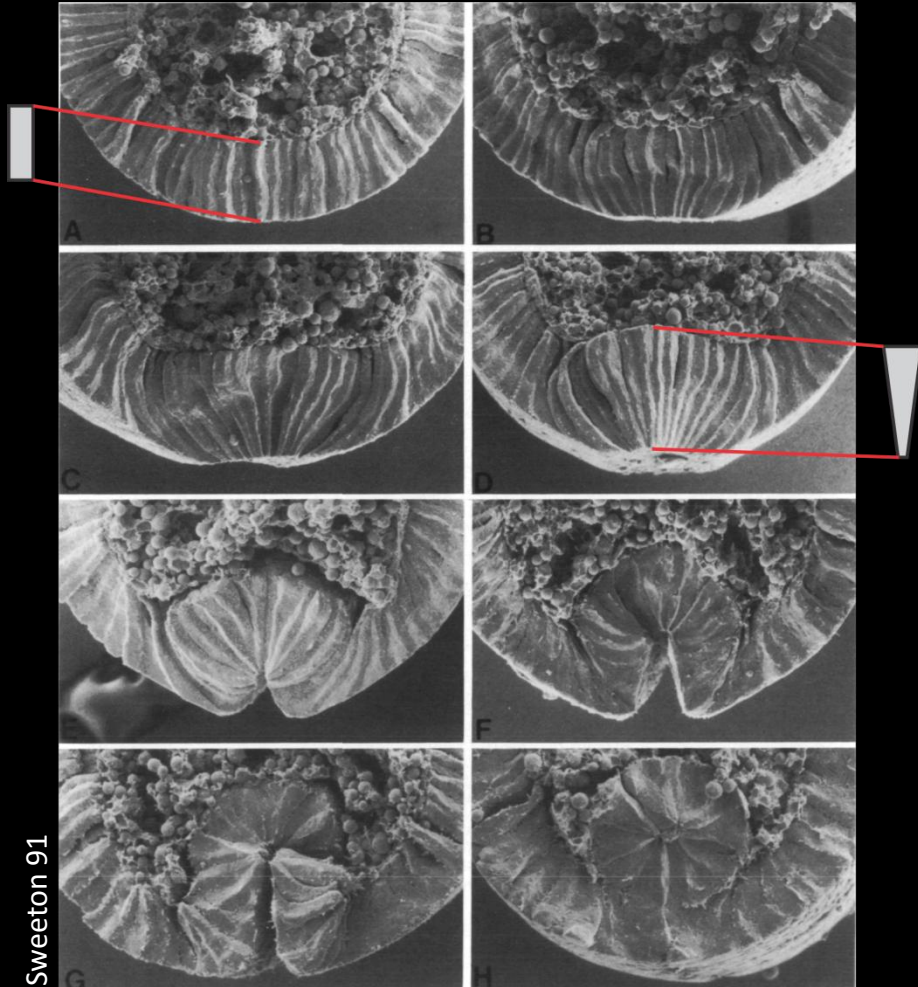


From Genes to Growth and Form

Konstantin Dombrovinski

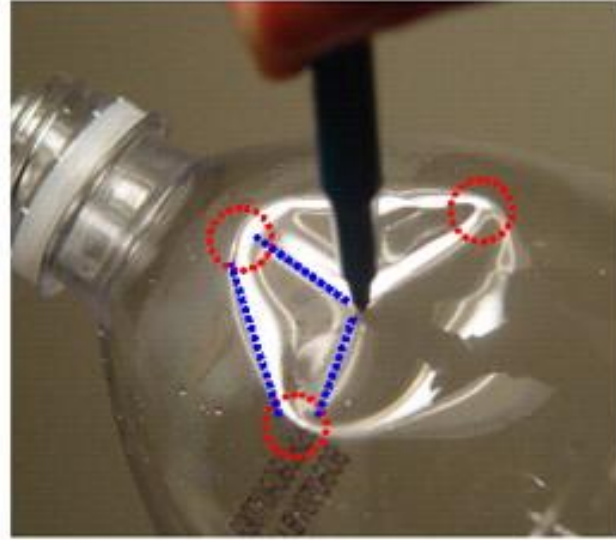
KITP, August 2016

Gastrulation (Ventral Furrow)



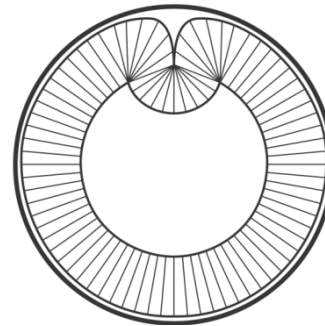
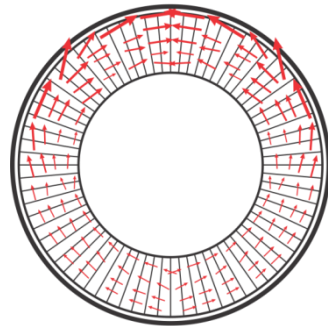
Sweeton 91

Dynamics = passive response + active forcing

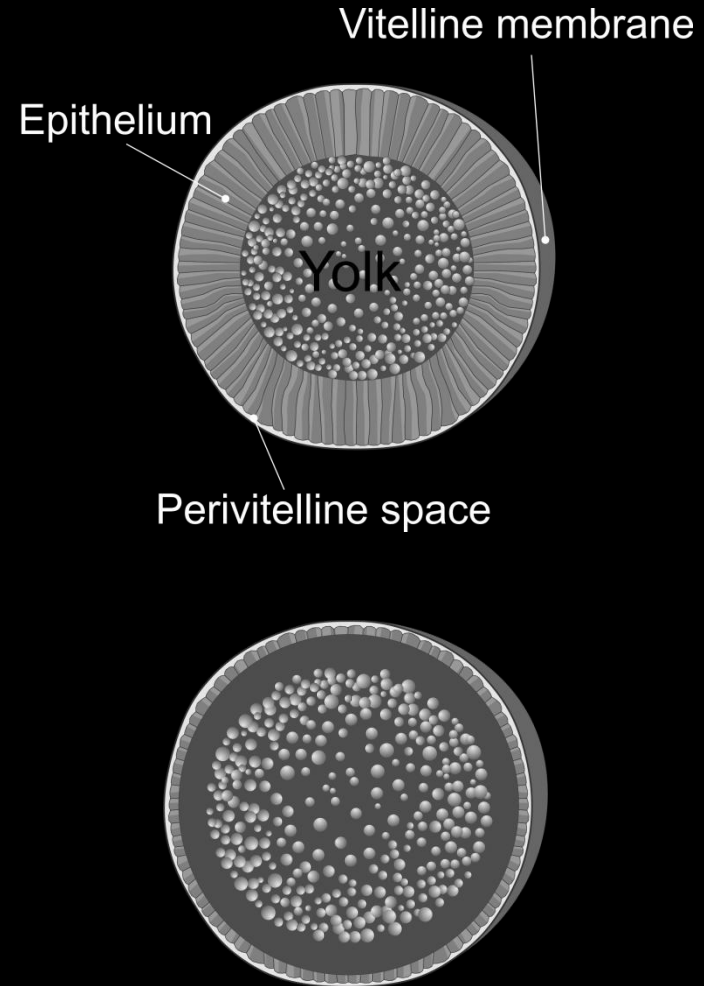
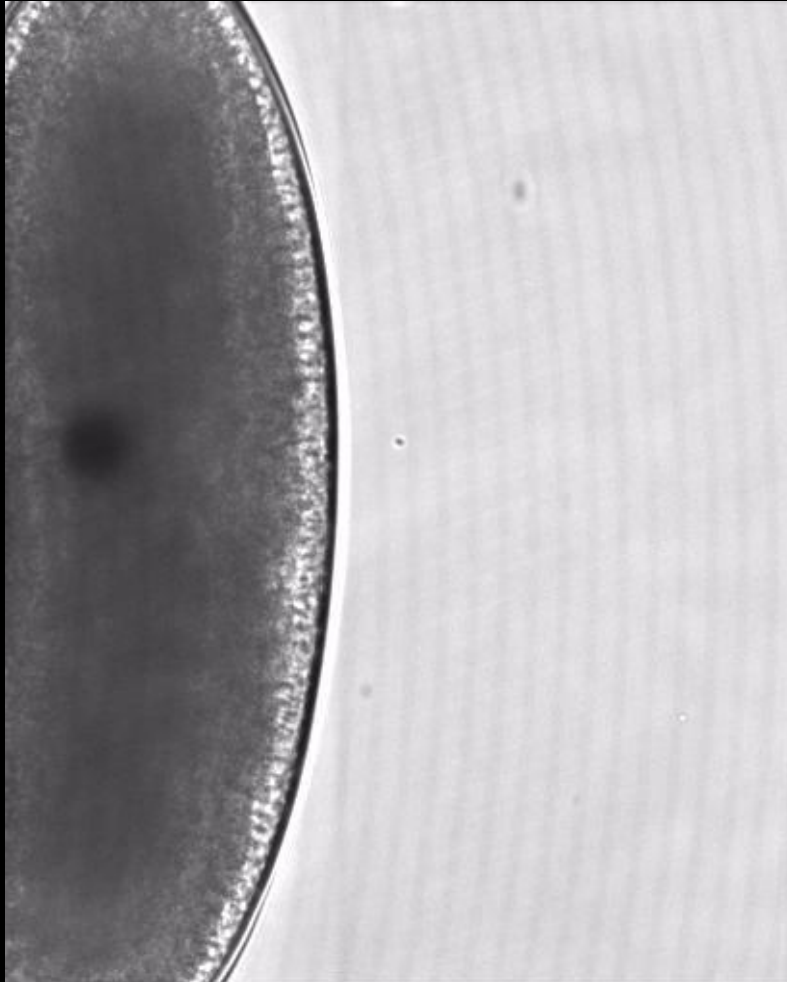


Force

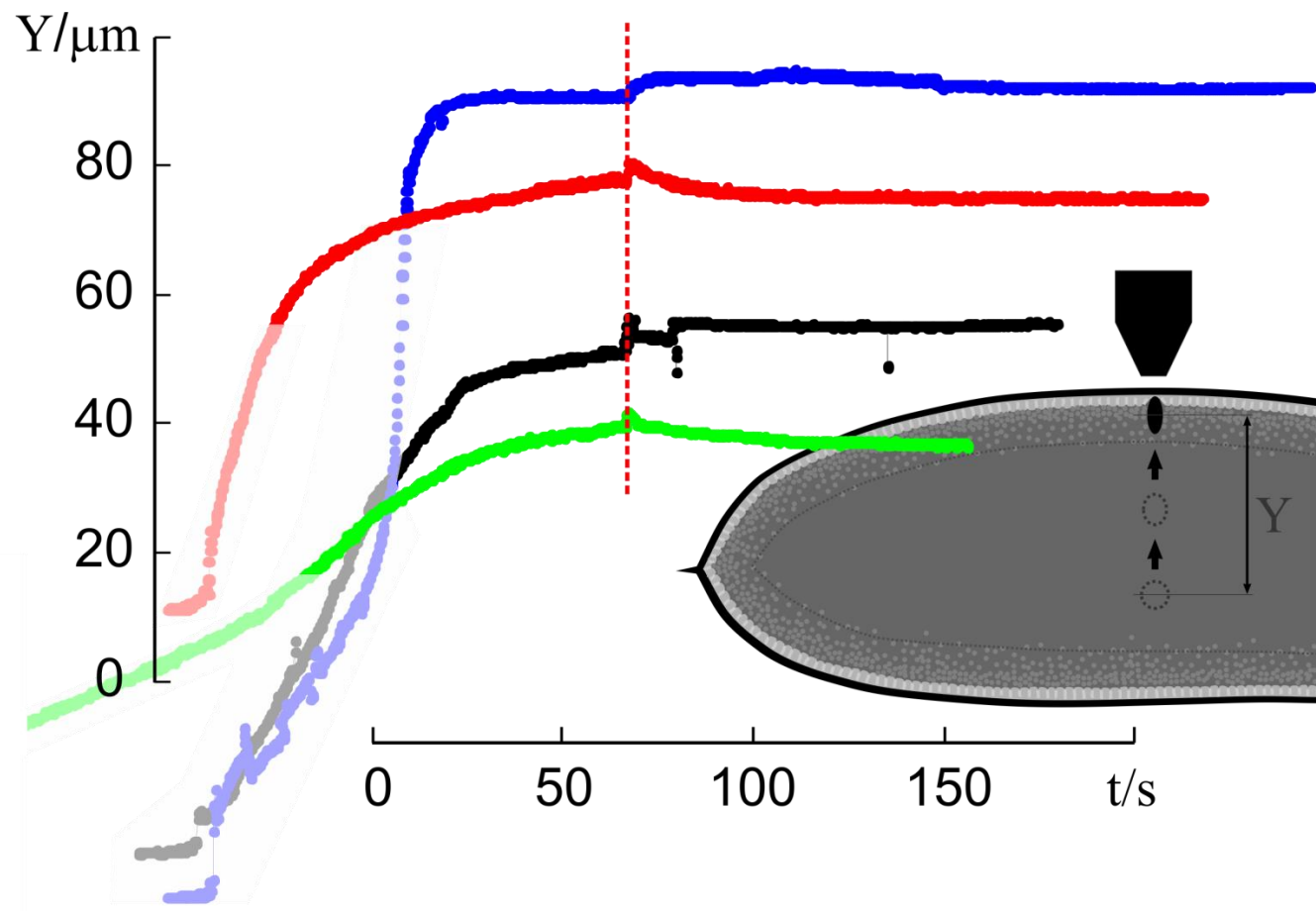
Deformation



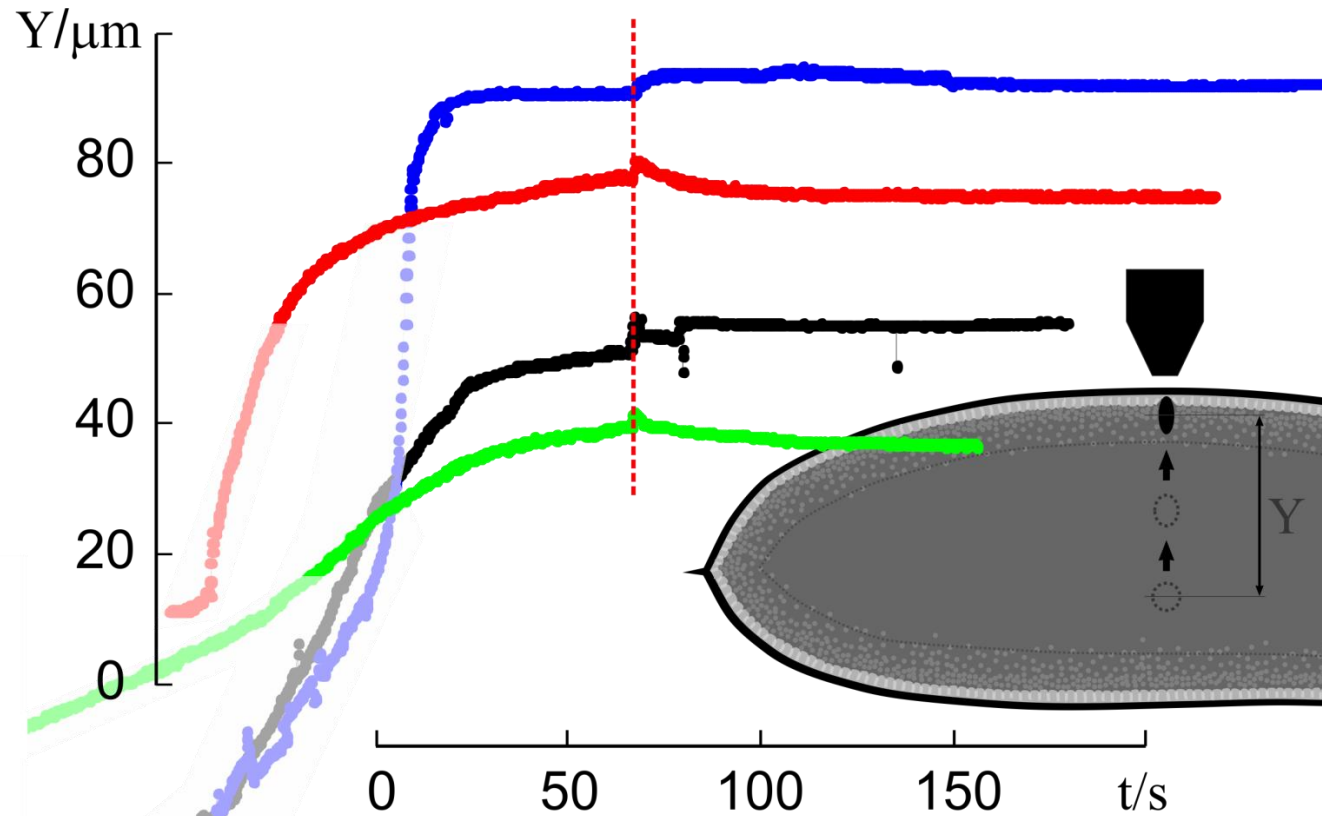
Ferrofluids: measuring tissue properties



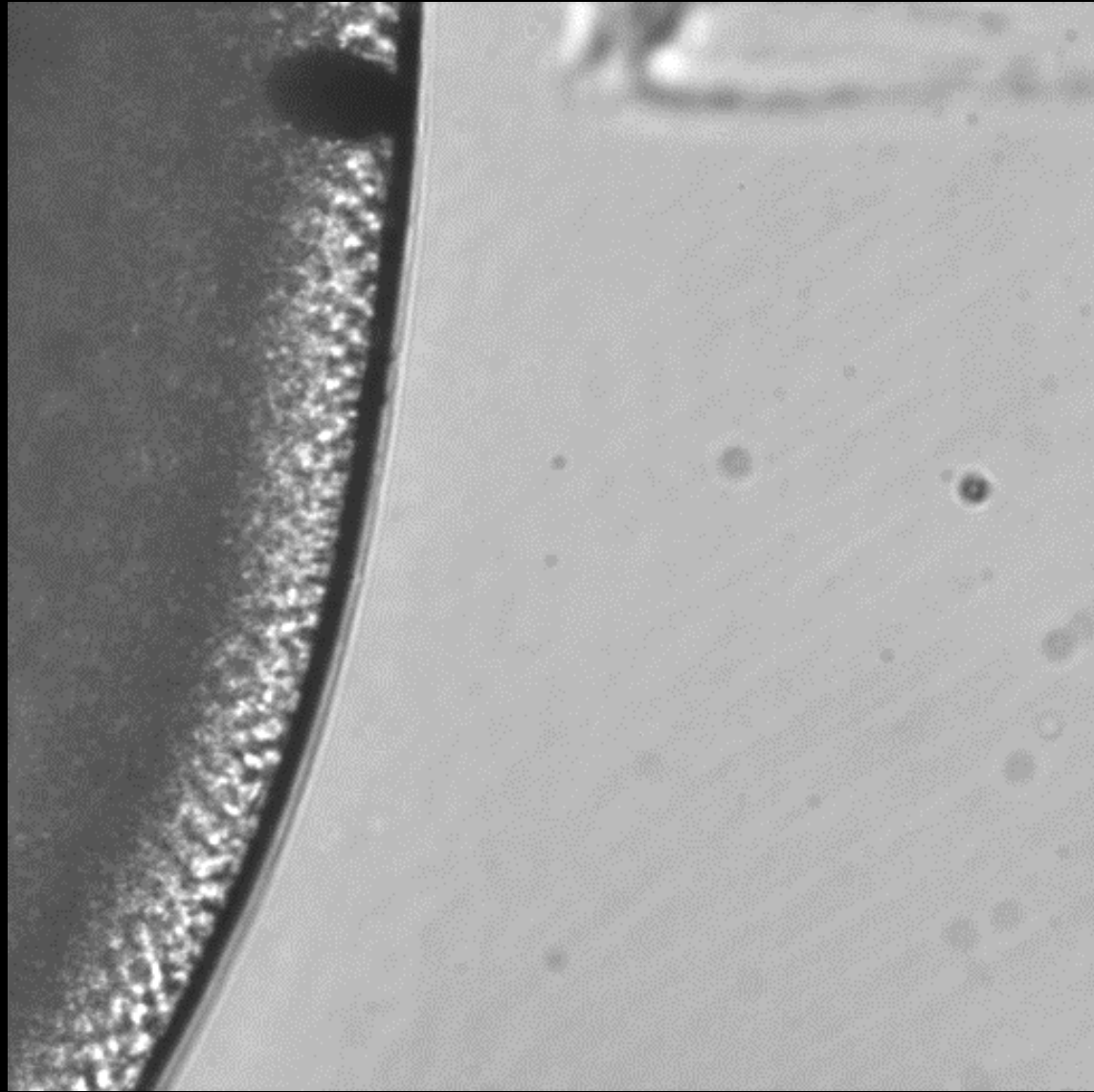
Viscous interior

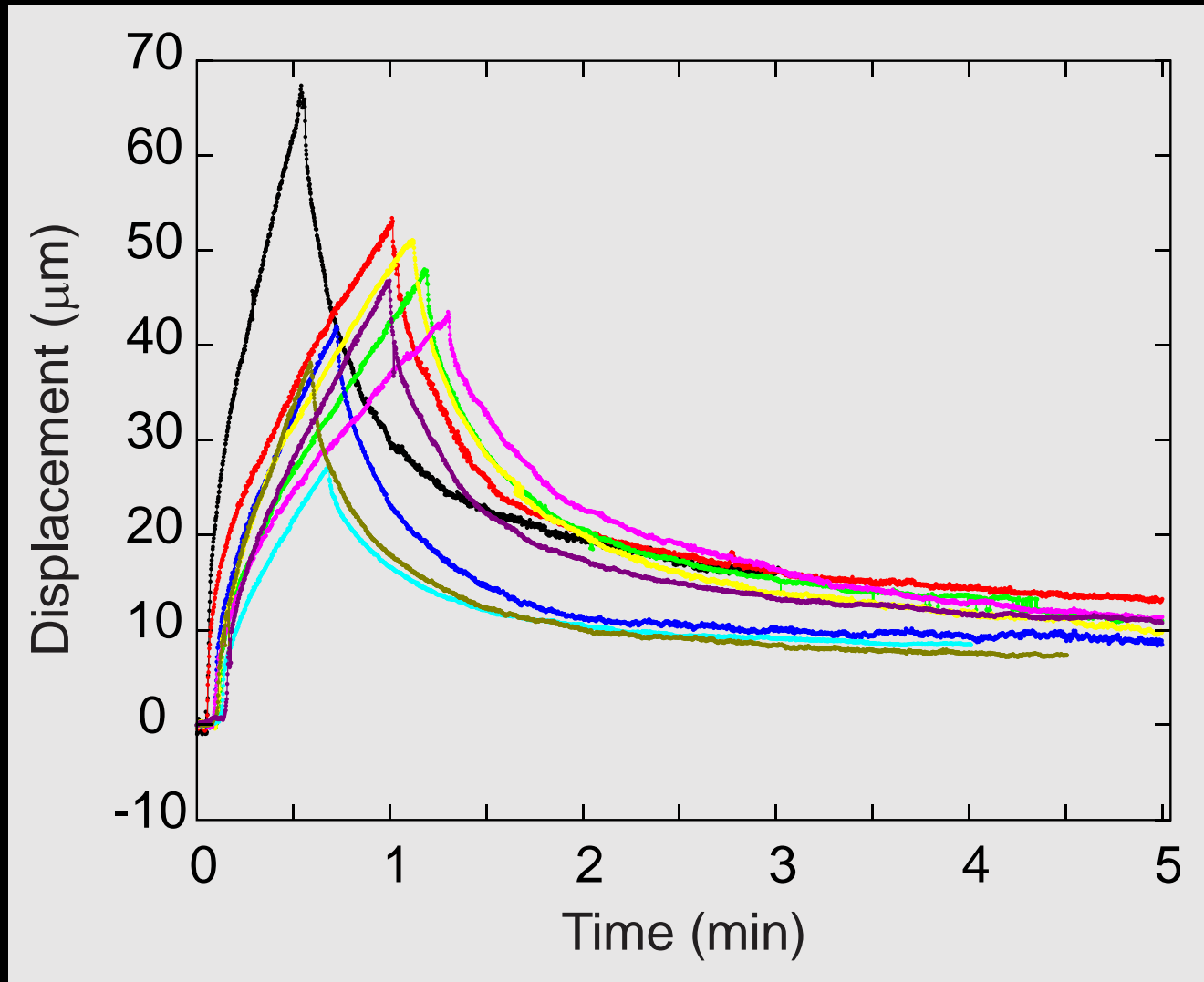


Viscous interior

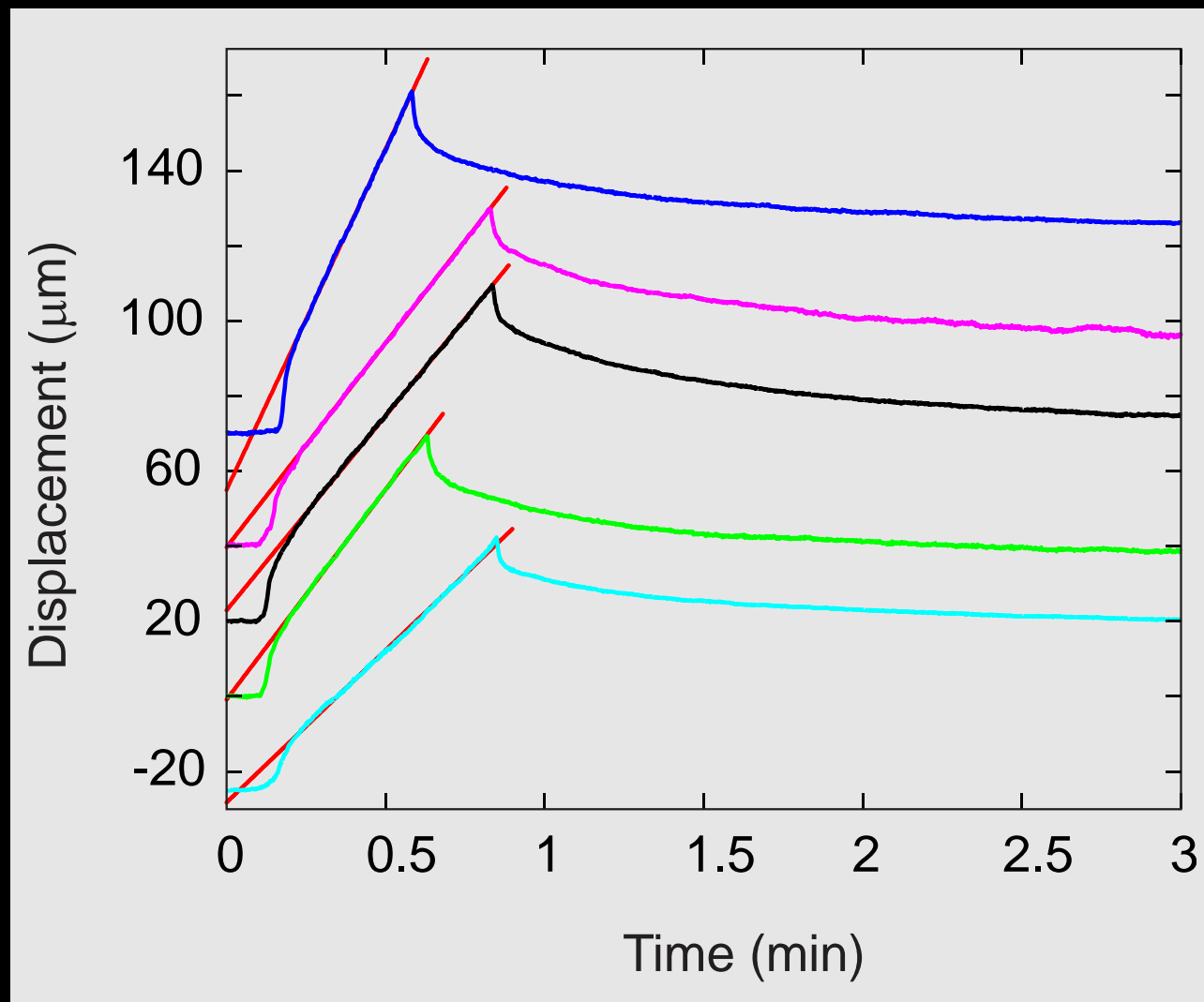
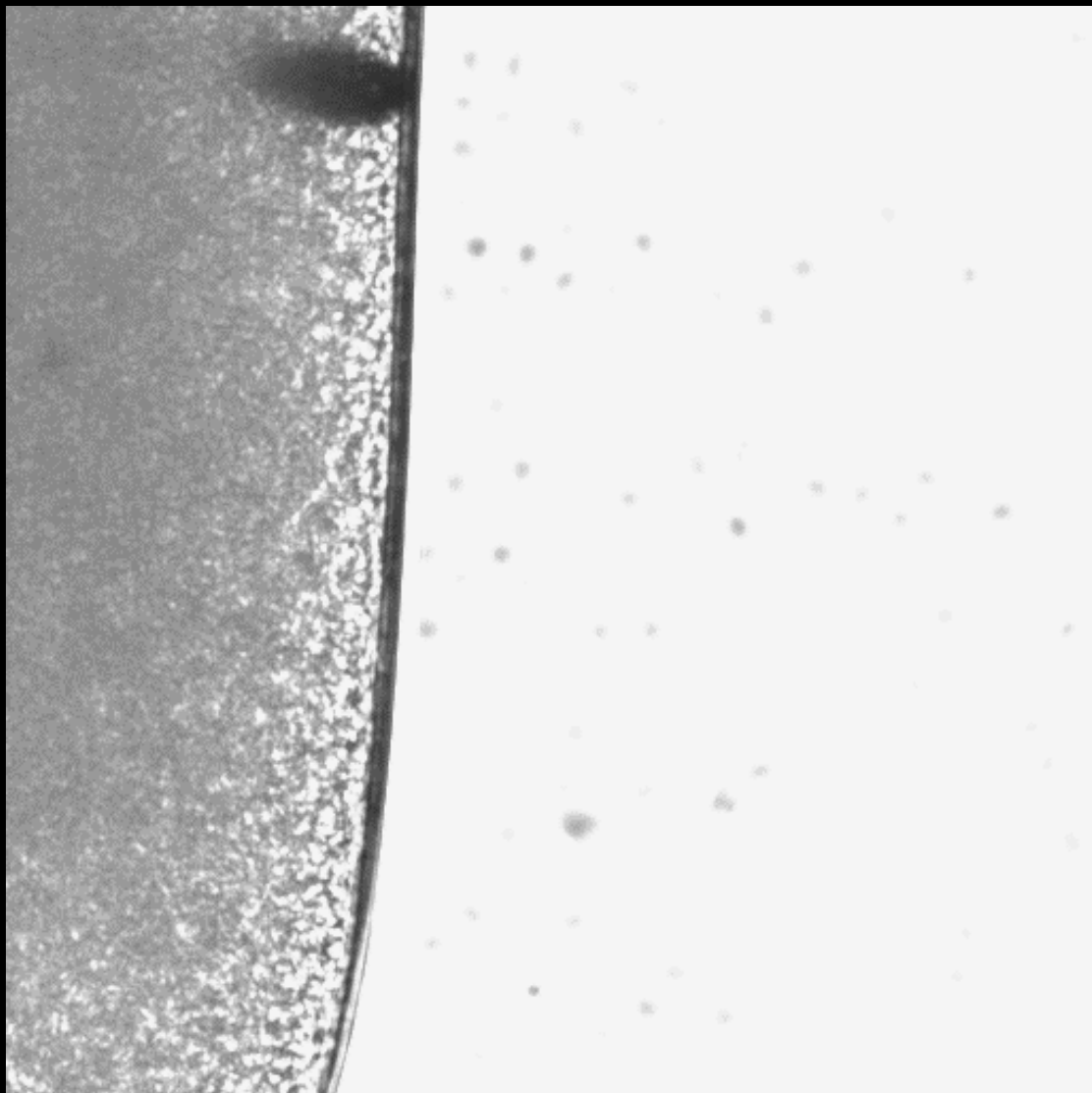


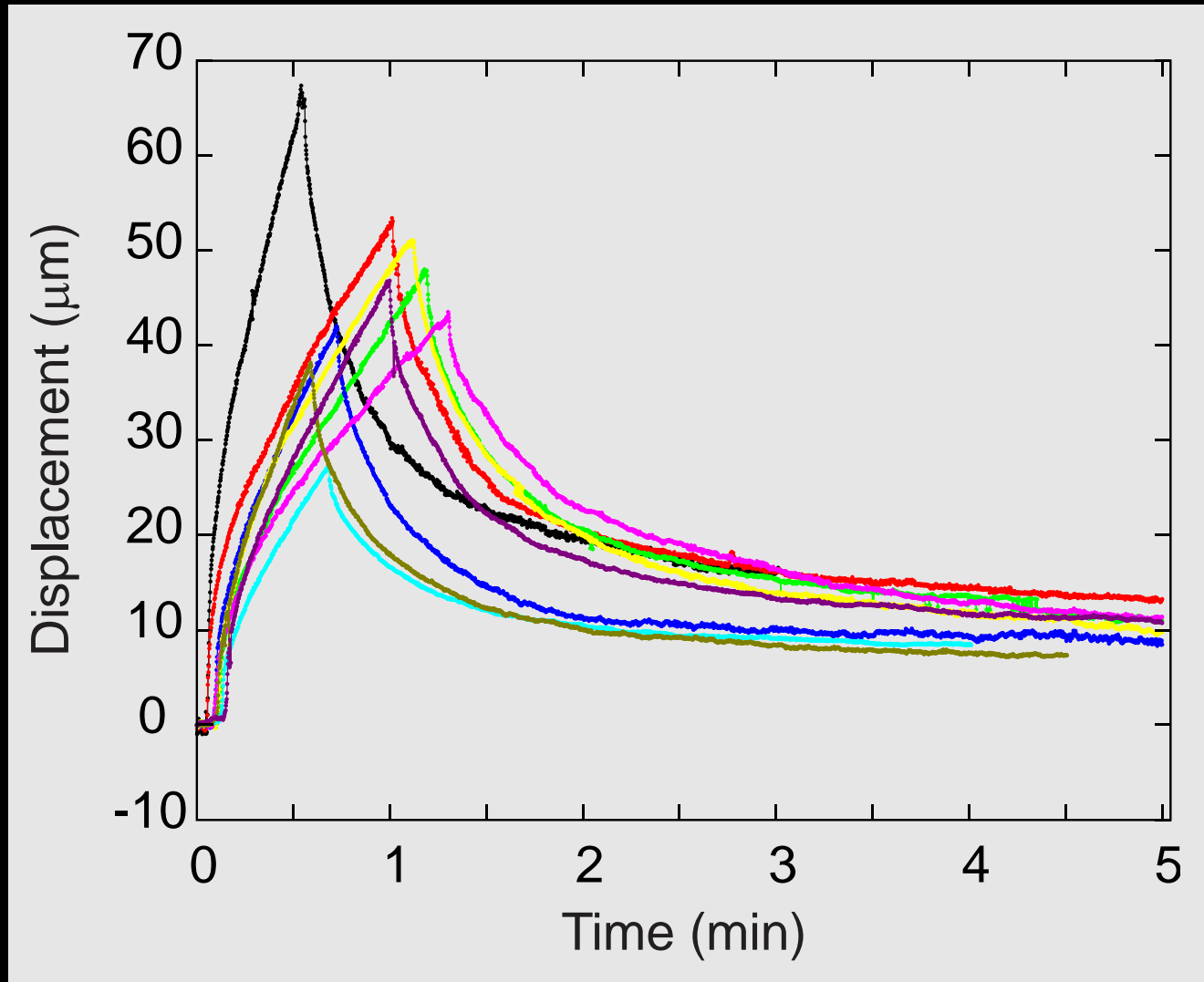
$$\eta = 1000 \text{ cP}$$



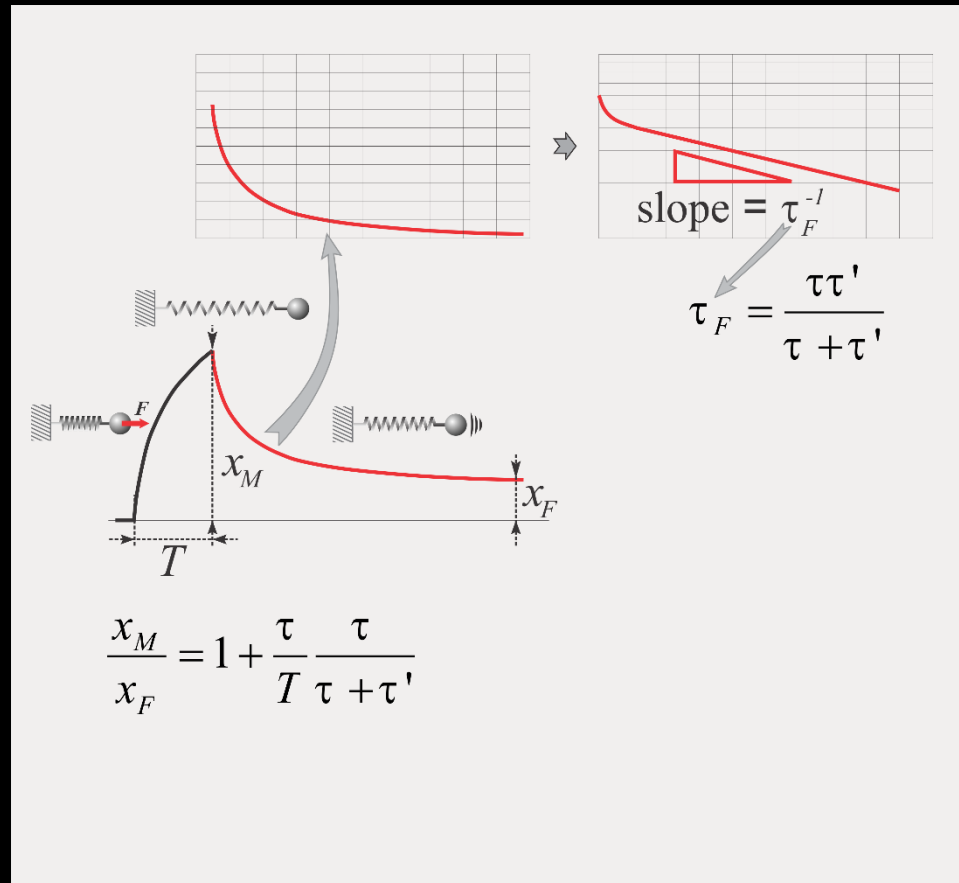


Control: constant force

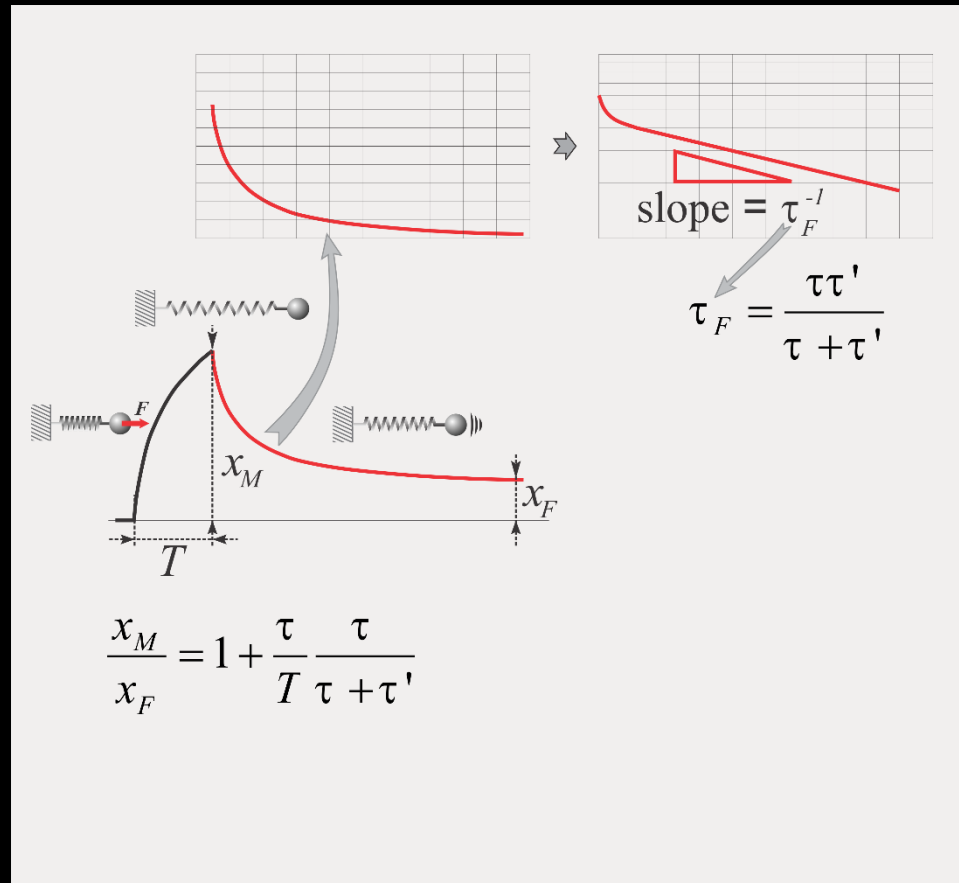




Recoil curves: analysis

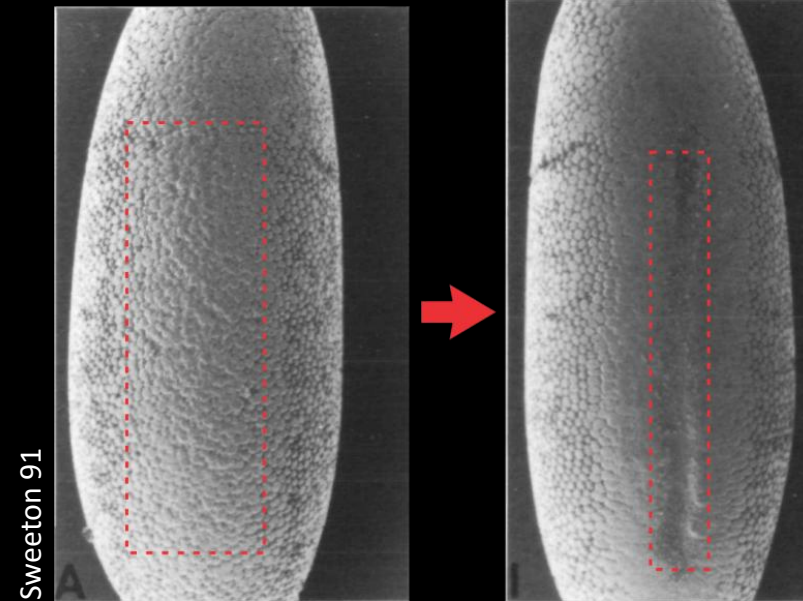


Recoil curves: analysis

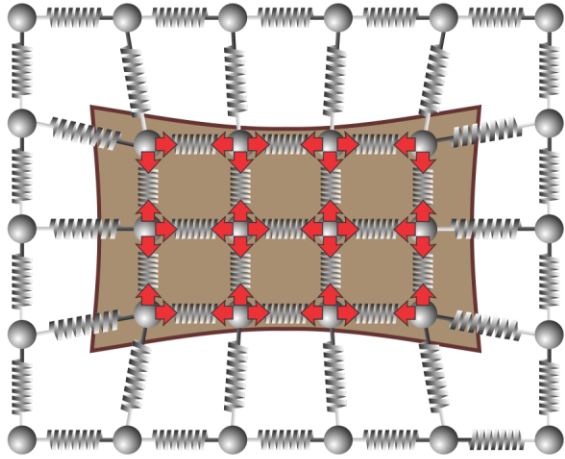


$$\tau = 3.7 \text{ min}$$

Gastrulation (Ventral Furrow)

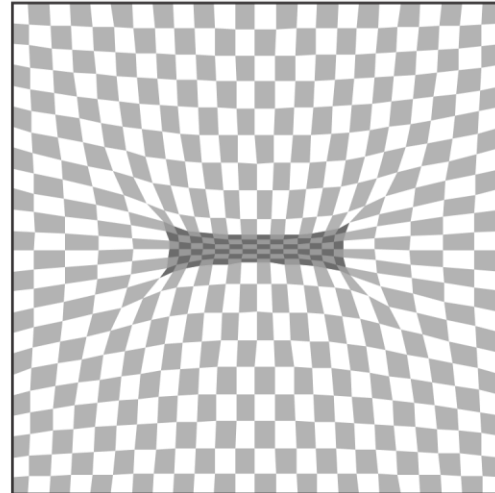
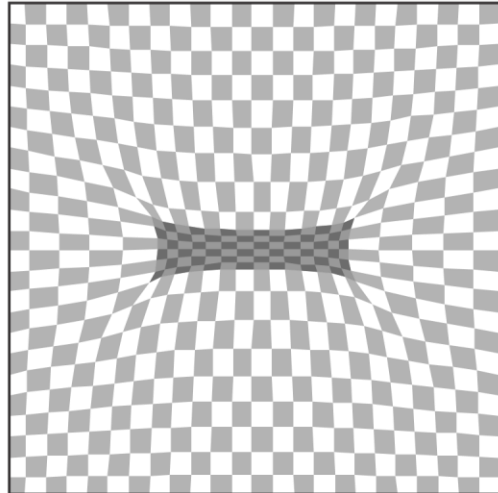
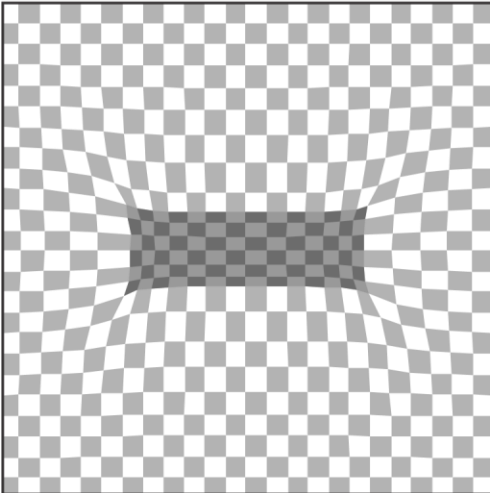


Implications for the dynamics

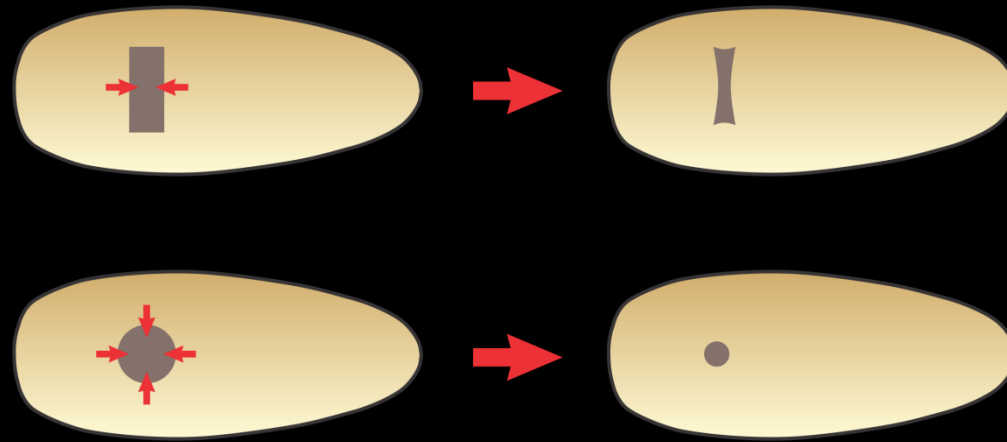
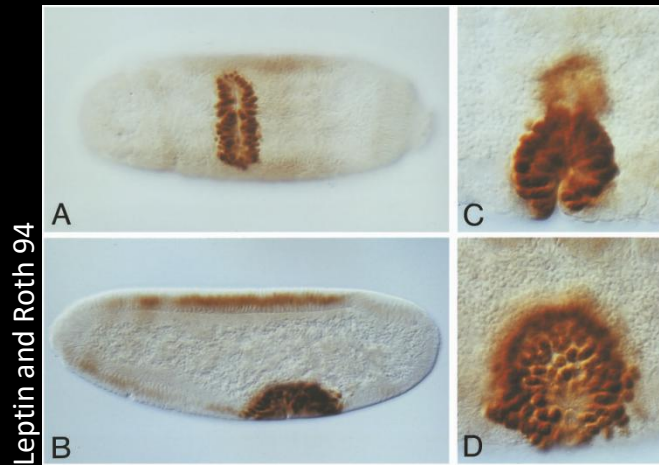


$$\eta \partial_t \mathbf{u} = \frac{E}{2(1+\sigma)} \nabla^2 \mathbf{u} + \frac{E}{2(1+\sigma)(1-2\sigma)} \nabla \nabla \cdot \mathbf{u} + \nabla \cdot \boldsymbol{\mu}$$

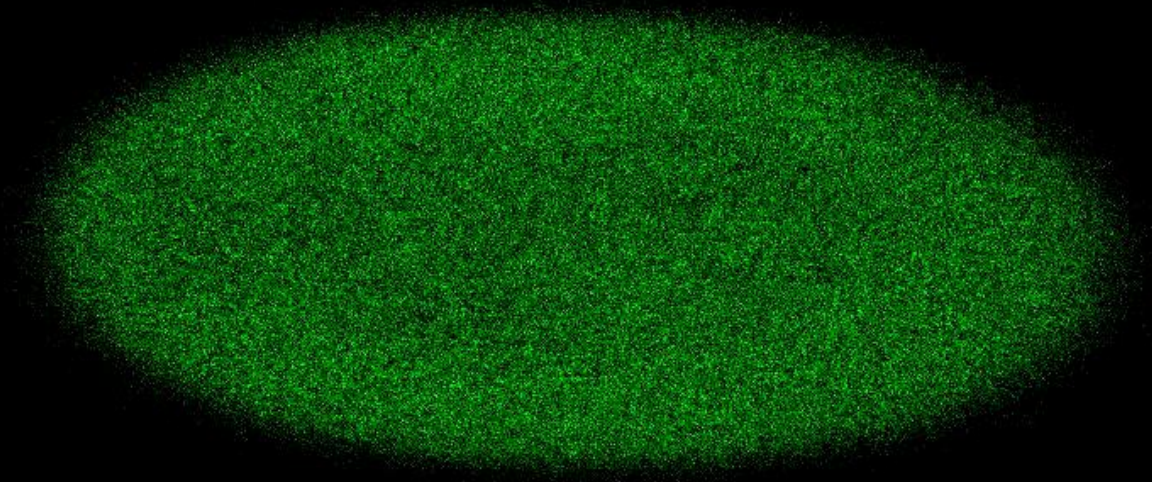
$$\boldsymbol{\mu} = \mathbf{I} \mu_0$$



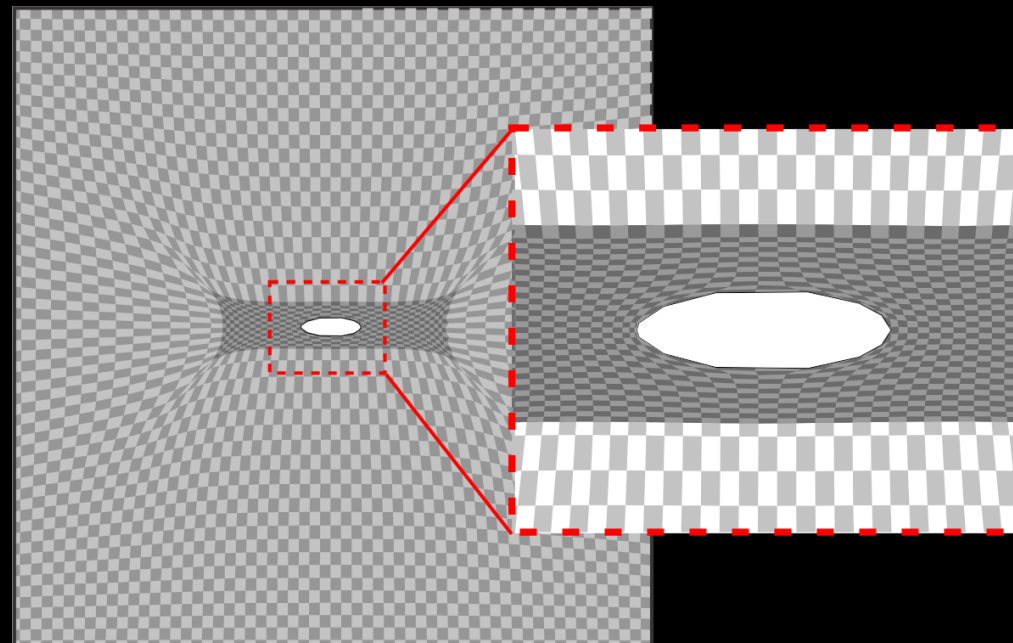
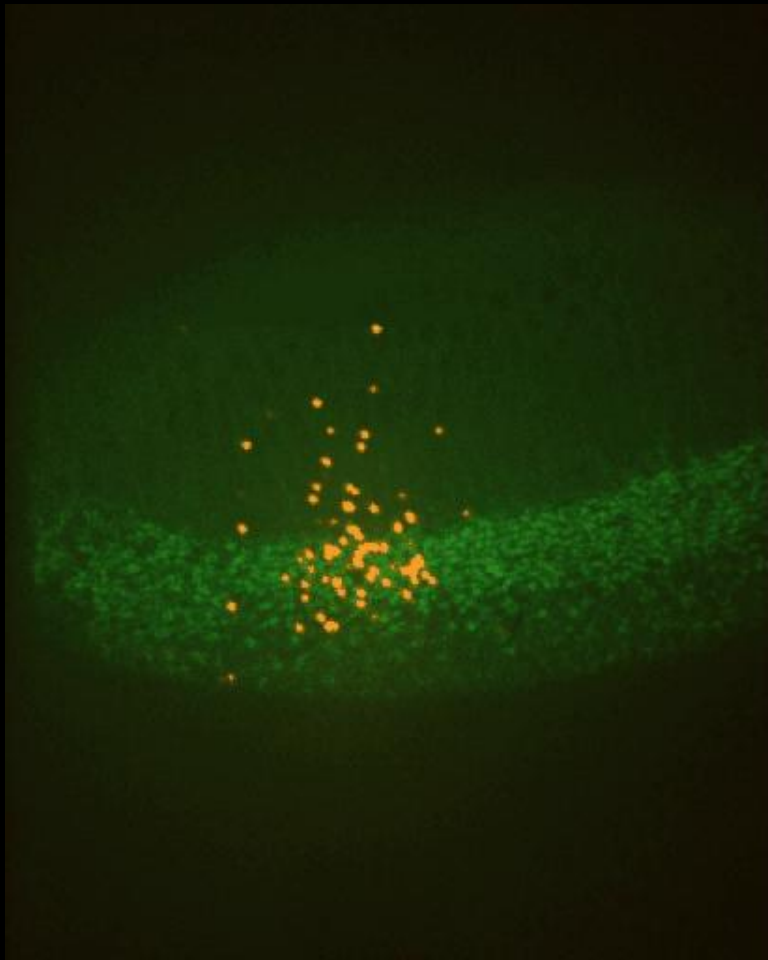
Implications for the dynamics



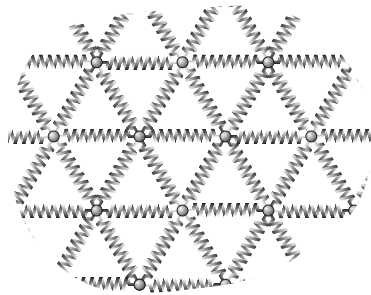
Implications for the dynamics



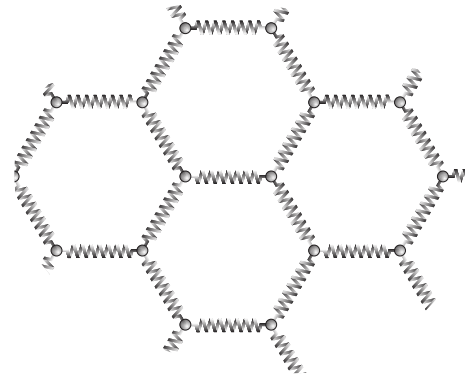
Implications for the dynamics



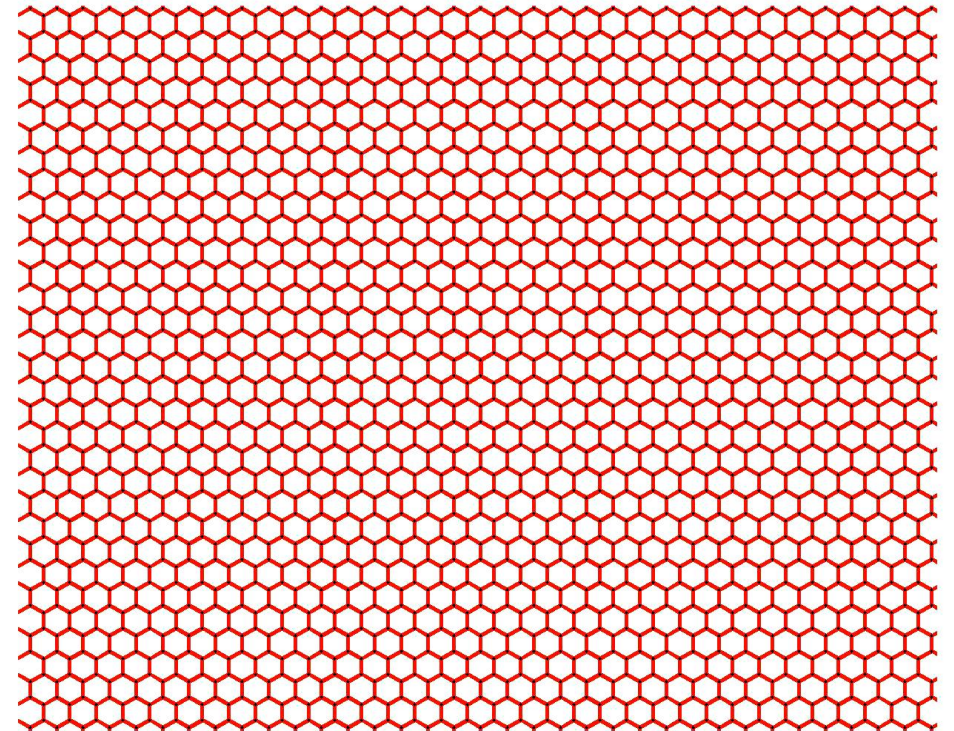
Stiff versus floppy



Stiff



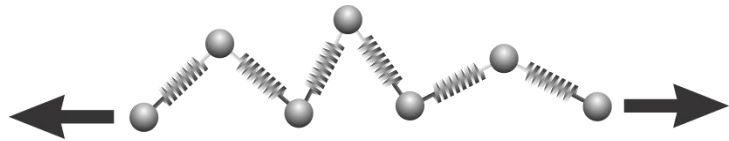
Floppy



How to test if network is floppy?

Pull twice.

Pull once: weak recoil

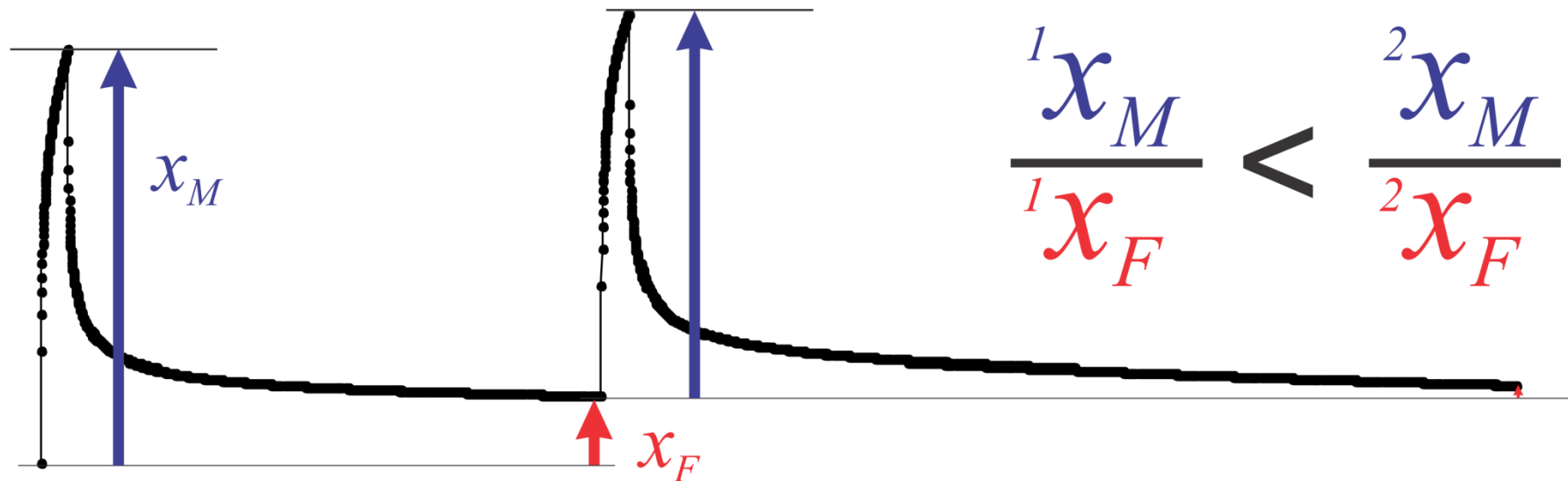


Floppy

Pull again: stronger recoil

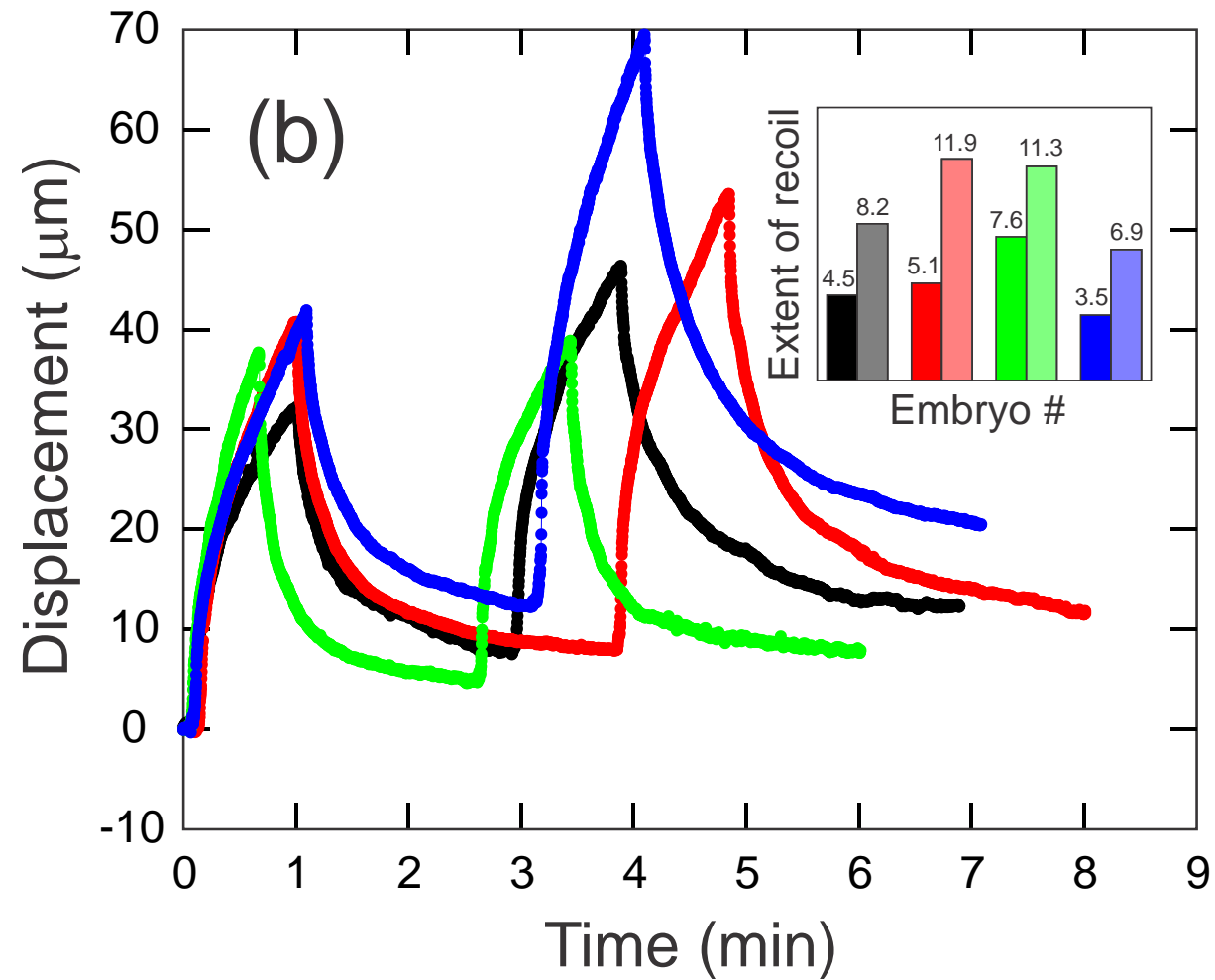


Not floppy

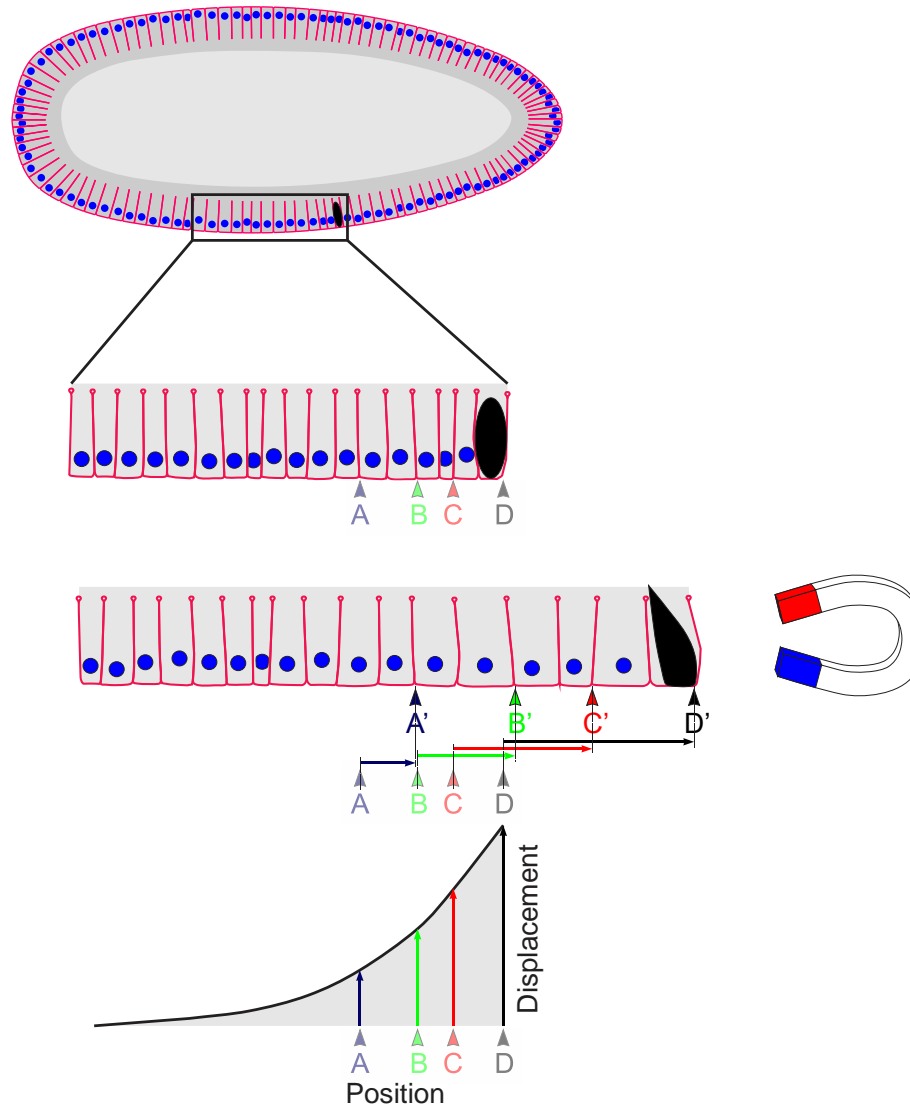


Proof of principle simulation

Fly epithelium as a floppy network



Geometry of the experiment



Linear elasticity: quantitative analysis

$$\eta \partial_t \mathbf{u} = \frac{E}{2(1+\sigma)} \nabla^2 \mathbf{u} + \frac{E}{2(1+\sigma)(1-2\sigma)} \nabla \nabla \cdot \mathbf{u} + \mathbf{f}$$

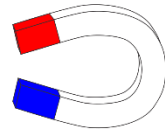
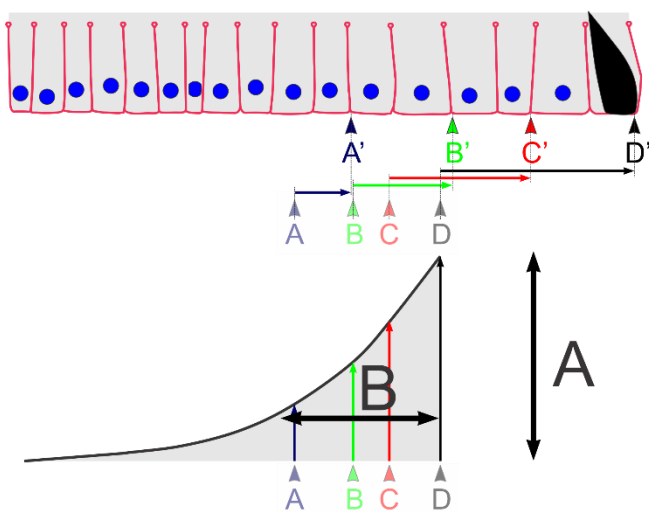
$$u_x(\mathbf{r} = 0) = \frac{A(1+\sigma)}{4\pi E} \log \left[1 + \frac{8E\pi^2}{(1+\sigma)\eta\xi^2} t \right]$$

$$\sigma_u \sim \sqrt{t}$$

Linear elasticity: scaling analysis

$$\eta \partial_t \mathbf{u} = \frac{E}{2(1+\sigma)} \nabla^2 \mathbf{u} + \frac{E}{2(1+\sigma)(1-2\sigma)} \nabla \nabla \cdot \mathbf{u} + \mathbf{f}$$

$$\partial_t \int d\mathbf{r} u_x = \text{const} \quad \int d\mathbf{r} u_x \sim t$$



$$A \sim t^\alpha$$

$$B \sim t^\beta$$

$$AB^2 \sim t^\alpha t^{2\beta} \sim t$$

$$\alpha + 2\beta = 1$$

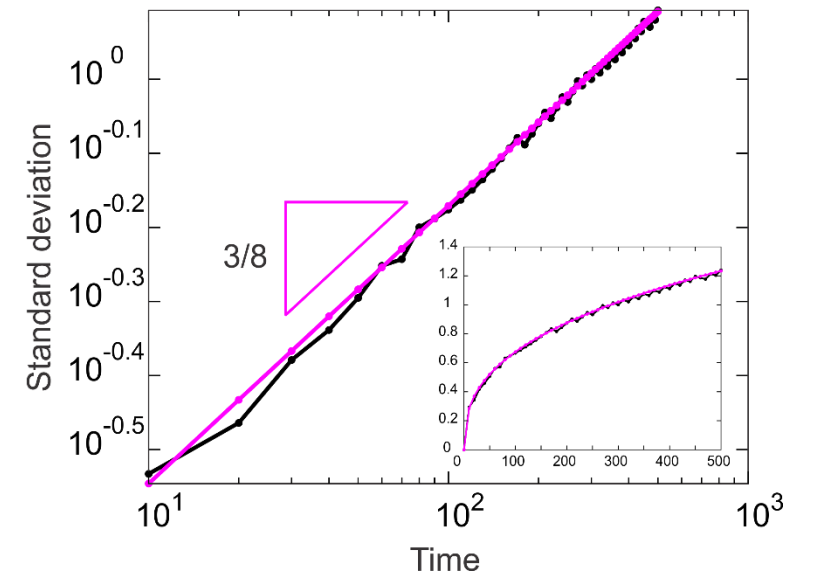
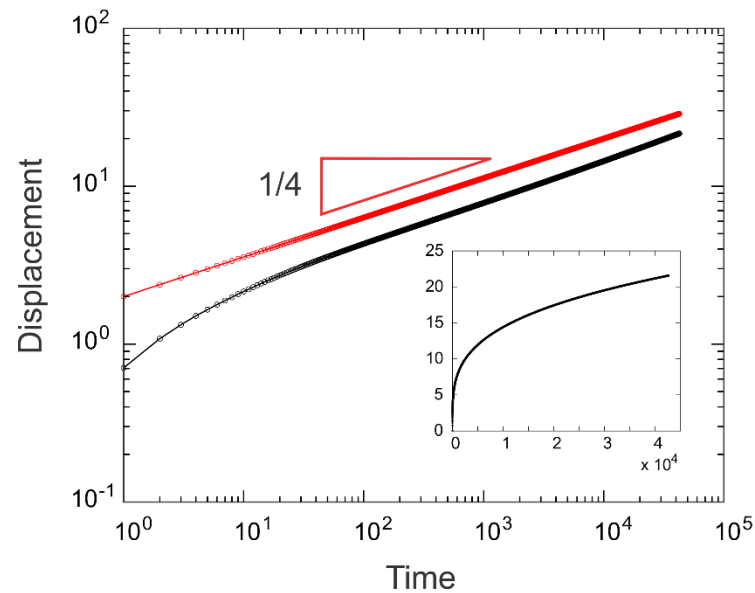
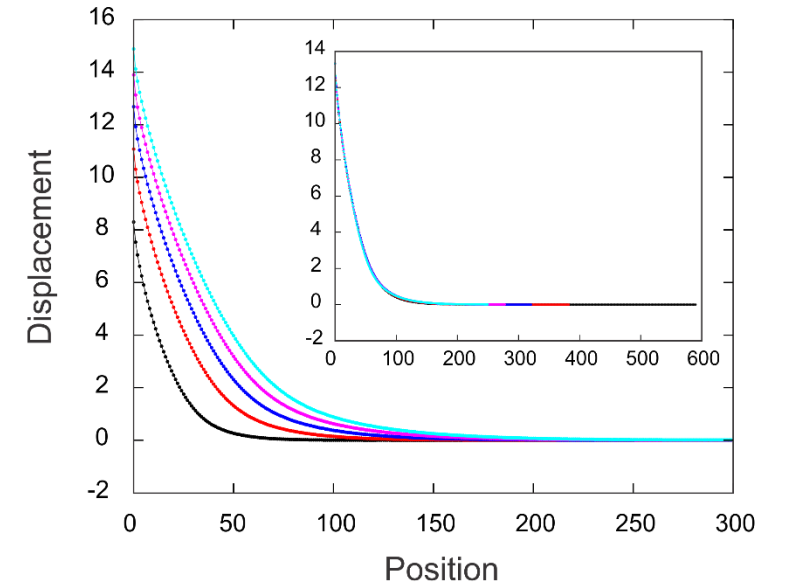
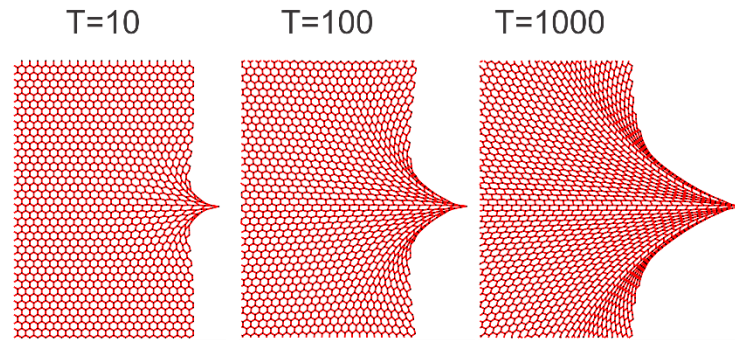
$$u_x \sim t^\alpha g\left(\frac{x}{t^\beta}, \frac{y}{t^\beta}\right)$$

$$\alpha - 1 = -2\beta + \alpha$$

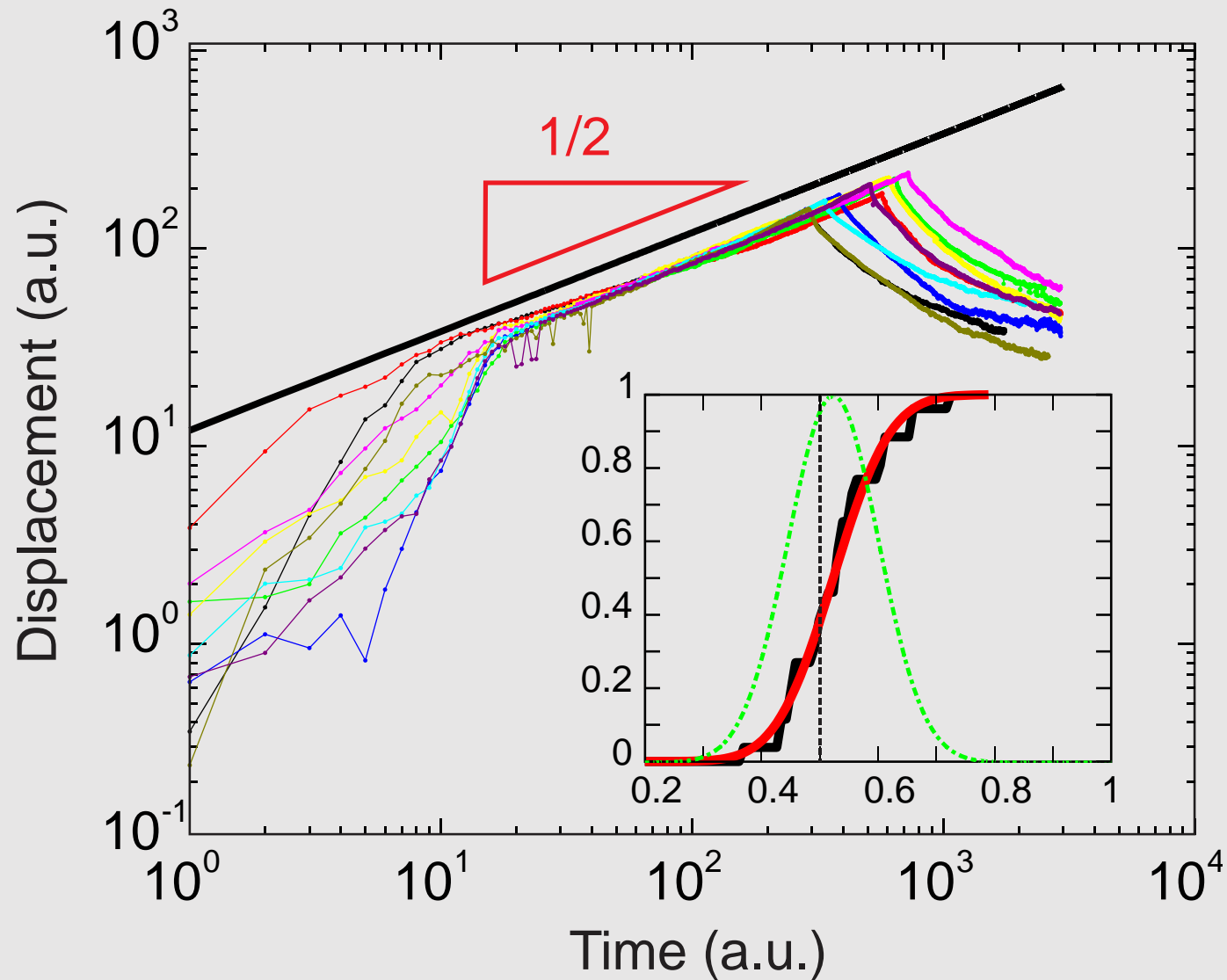
$$\alpha = 0 \quad \beta = \frac{1}{2}$$

Scaling: nonlinear case

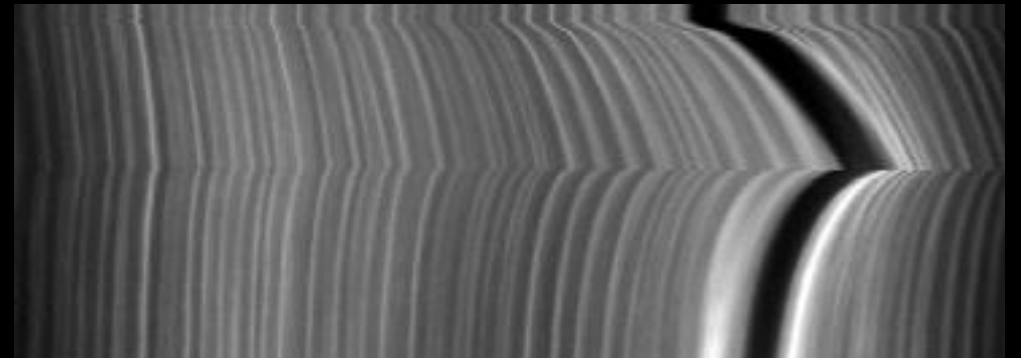
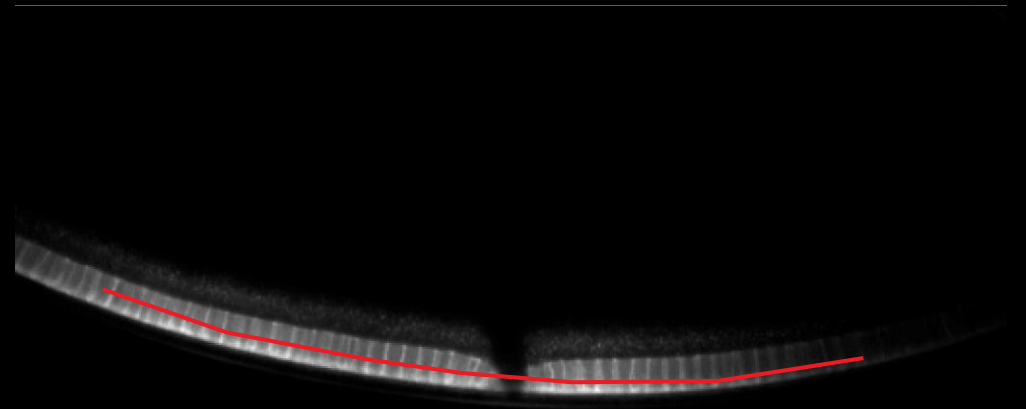
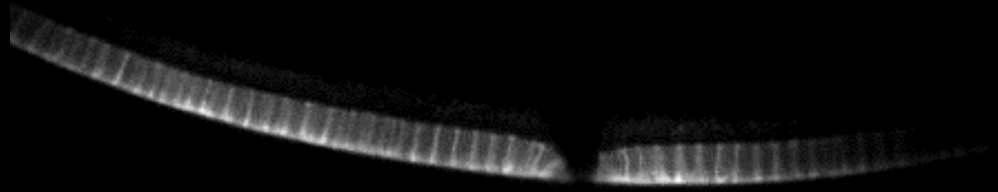
$$E \sim [\nabla \cdot \mathbf{u}]^2$$



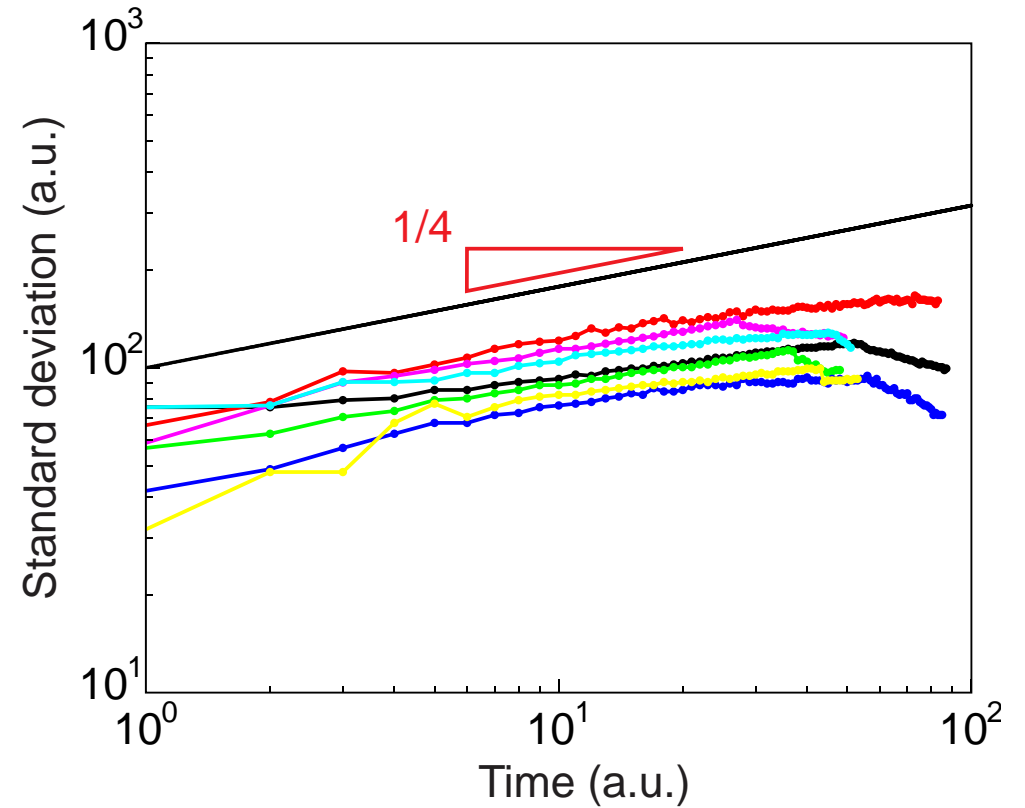
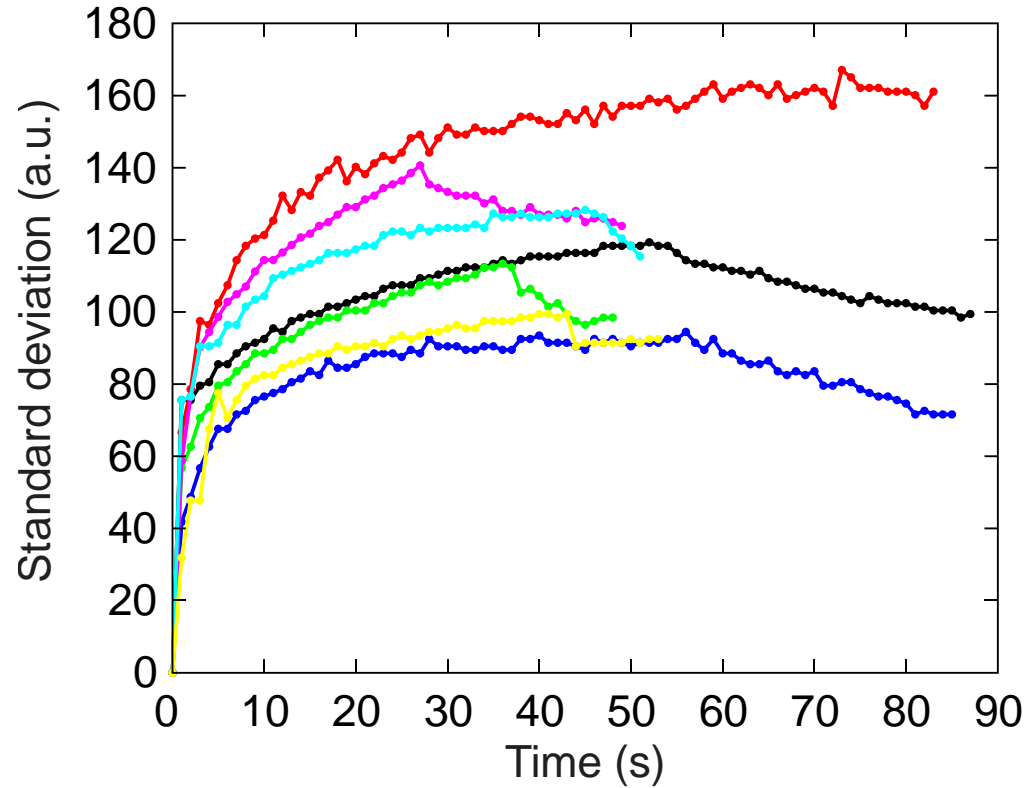
Data: power law behavior



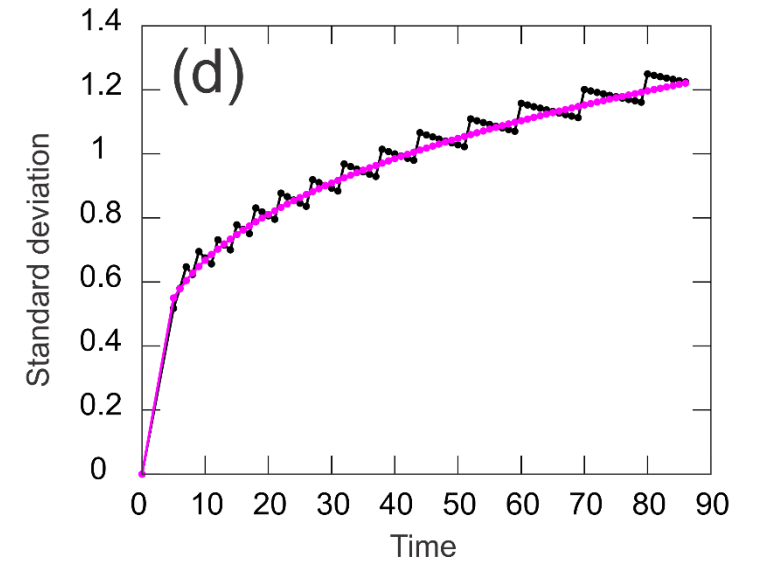
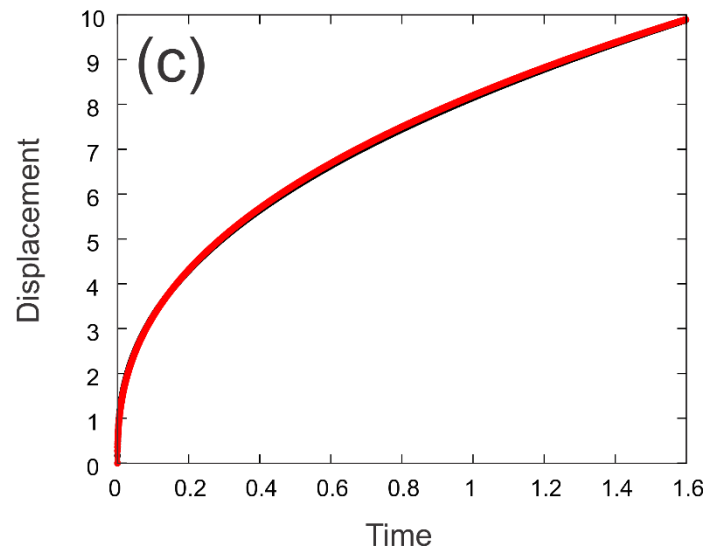
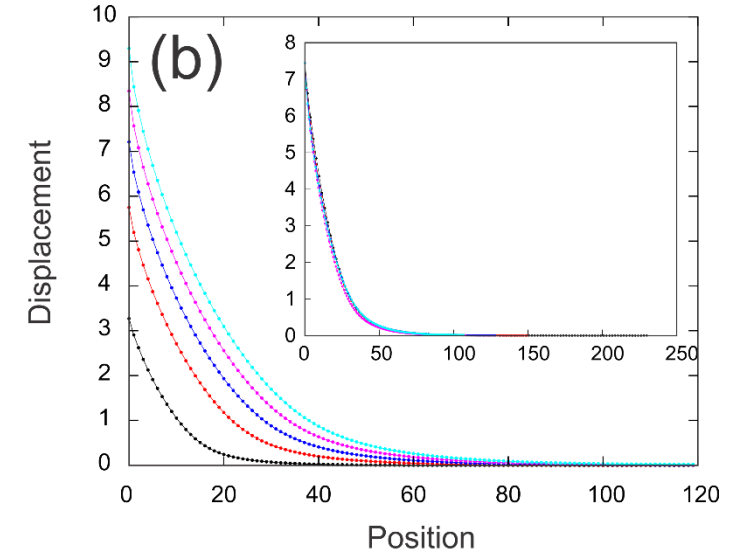
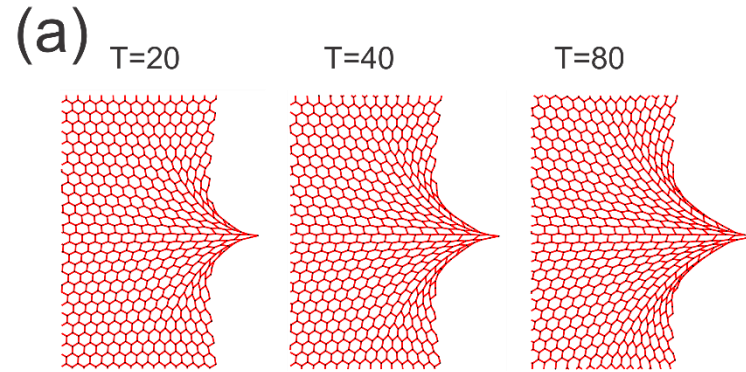
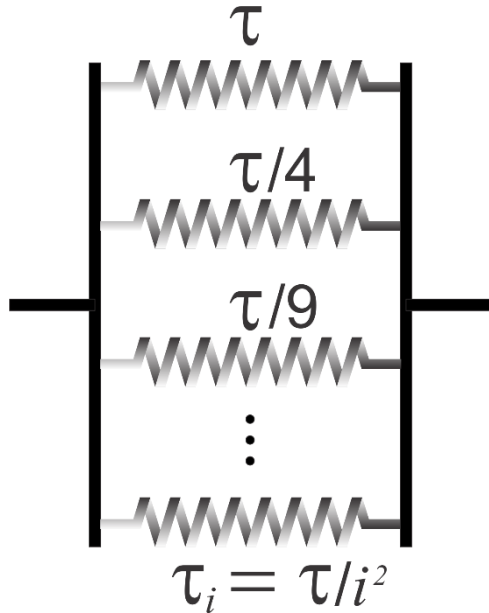
Following deformation imaging labeled membranes



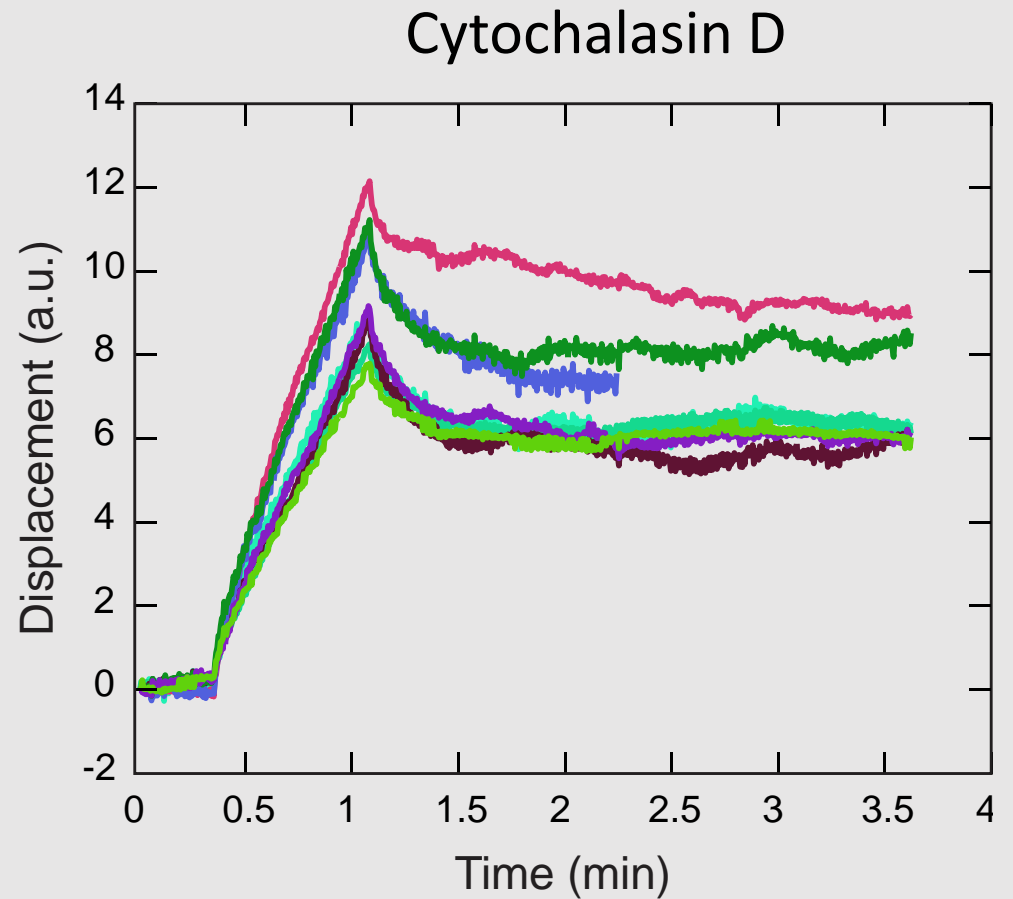
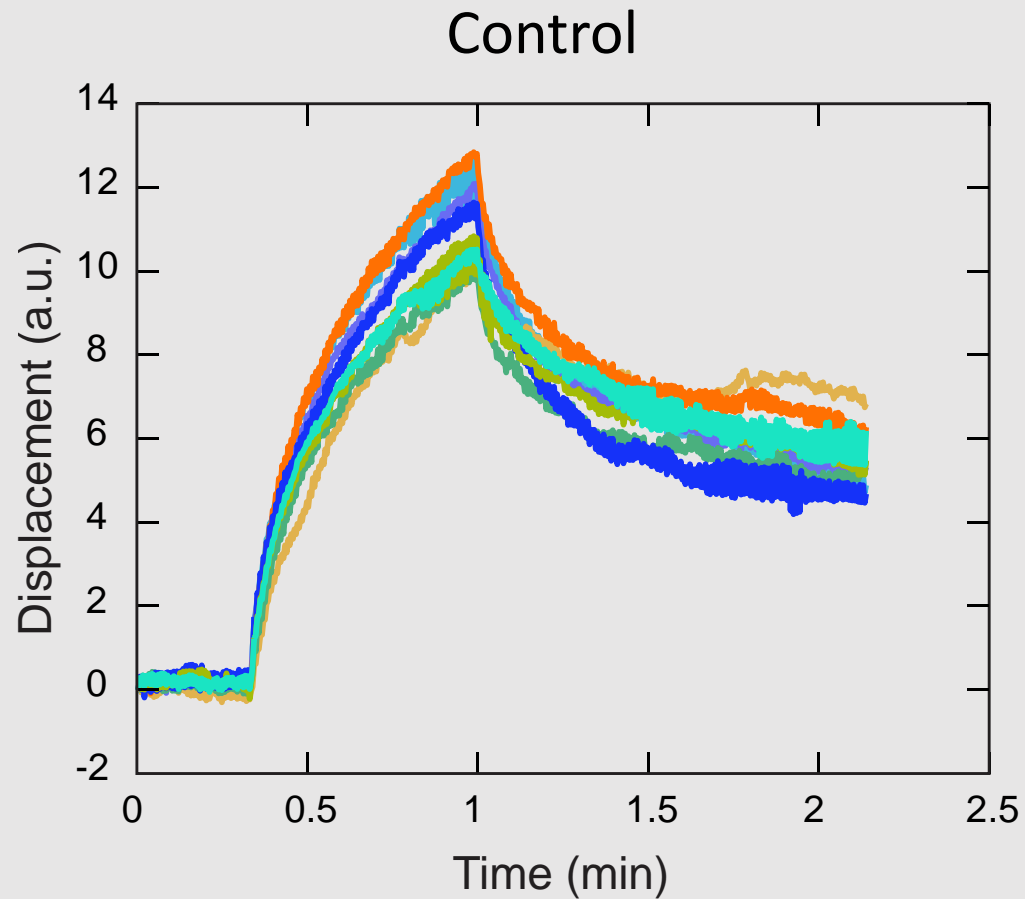
Growth of domain size: experiment



Capturing the individual values of the exponents



Where does elasticity reside?



Out of plane deformation: adiabatic?

