

a talk about

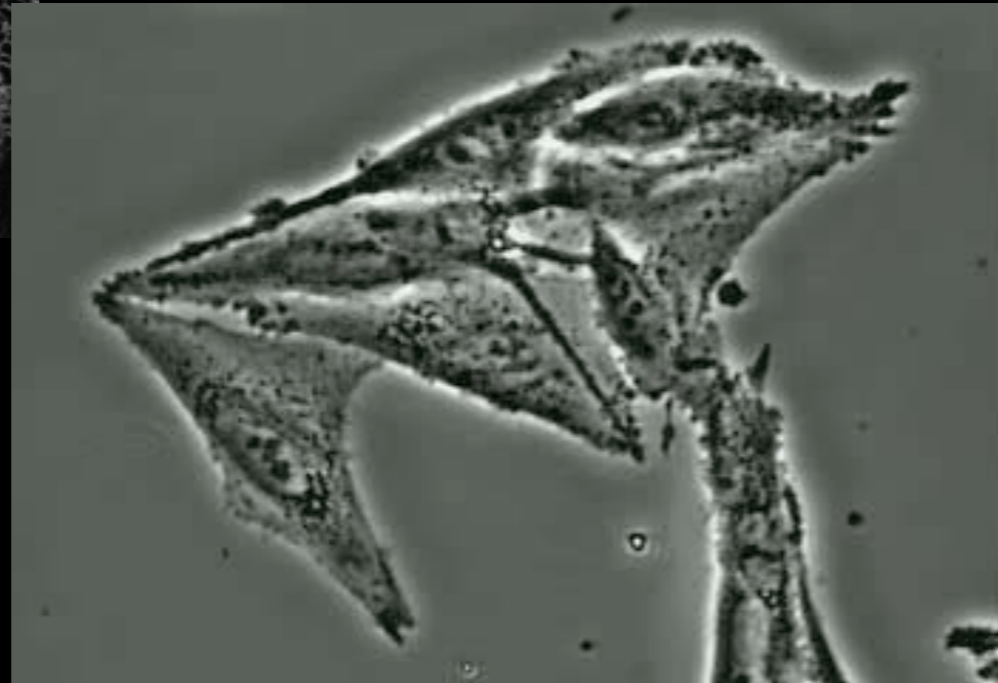
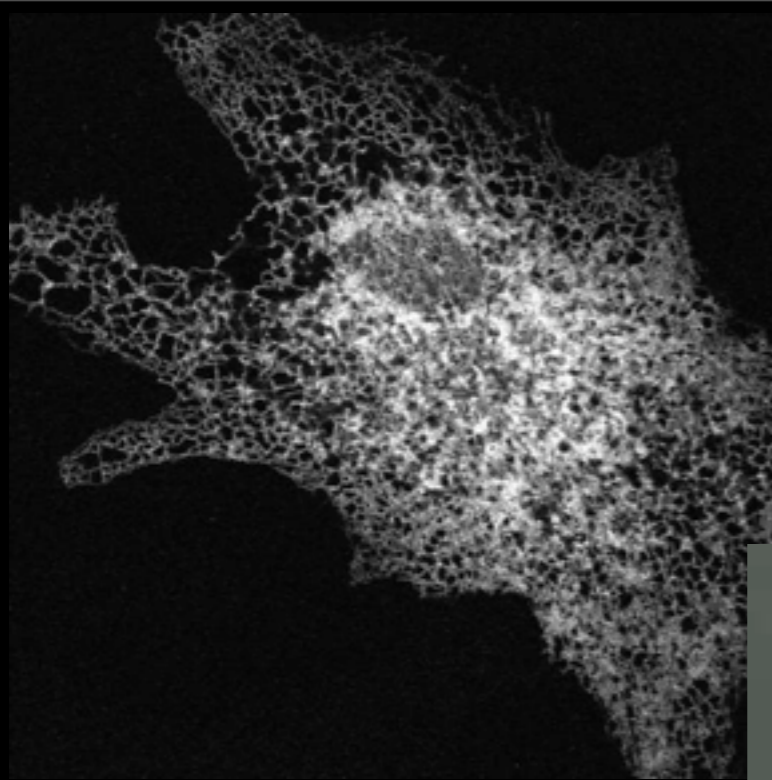
Adaptive Methods for the Simulation of Growth

Petros KOUMOUTSAKOS

with : Basil BAYATI, Michael BERGDORF, Philippe CHATELAIN, Florian MILDE, Diego ROSSINELI, Gerardo TAURIELLO

GEOMETRIES

- Complex
- Deforming
- Multiscale



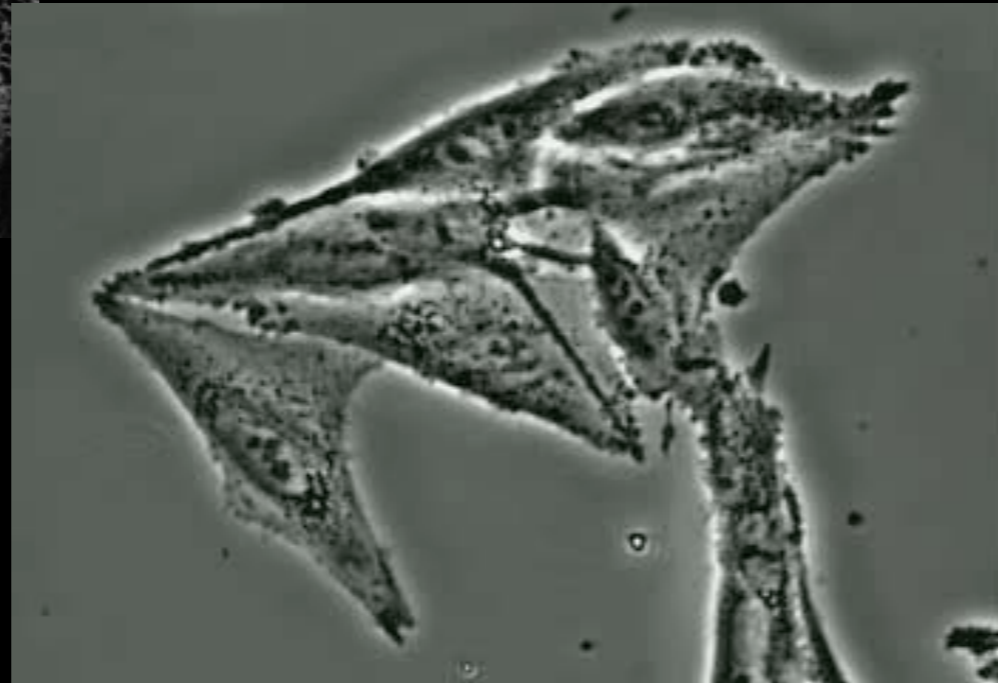
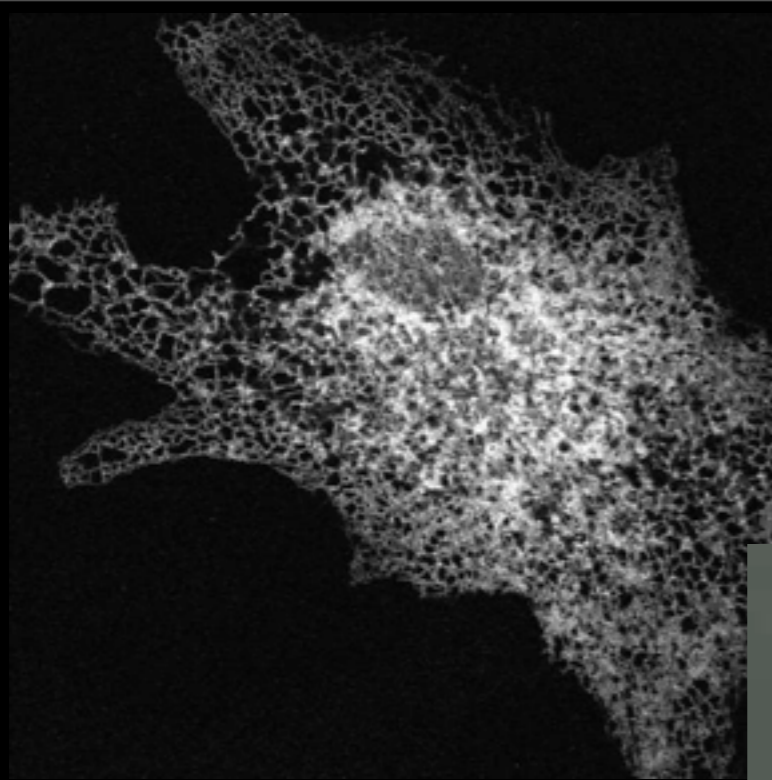
PHYSICS

- Heterogeneous
- Unsteady
- Multiscale



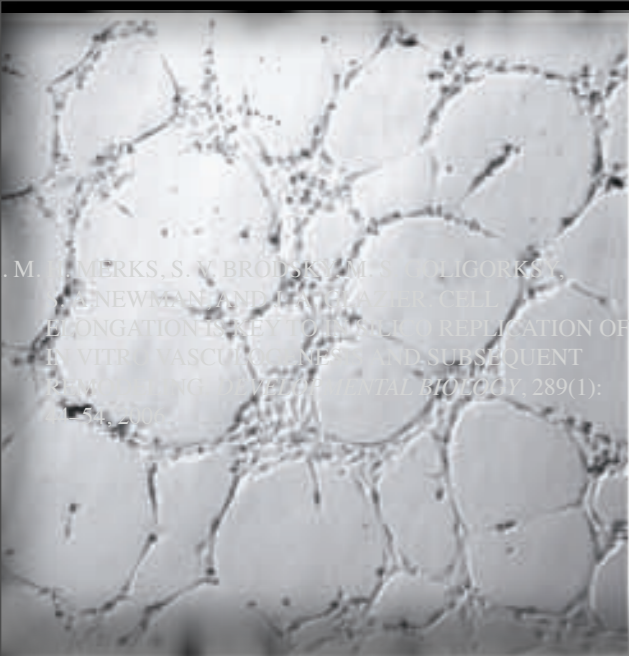
What methods do we need ?

Adaptivity
Multiscaling (multi-resolution/physics)
Large Deformations
Heterogeneity
Efficient

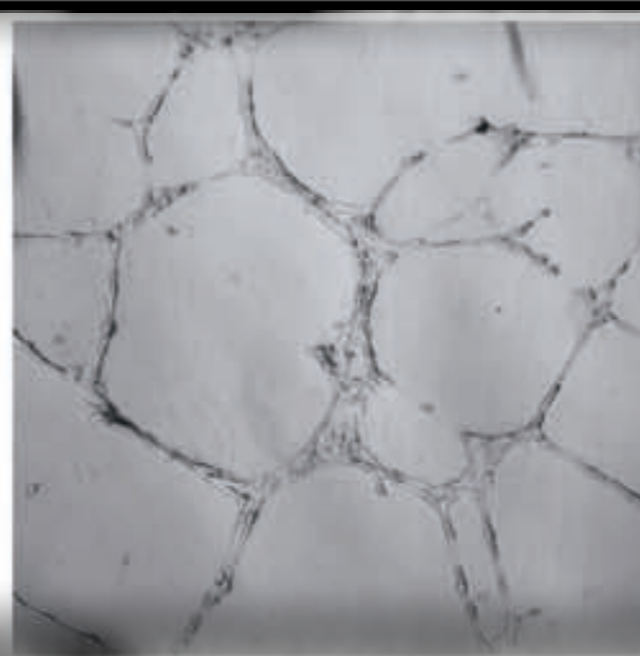
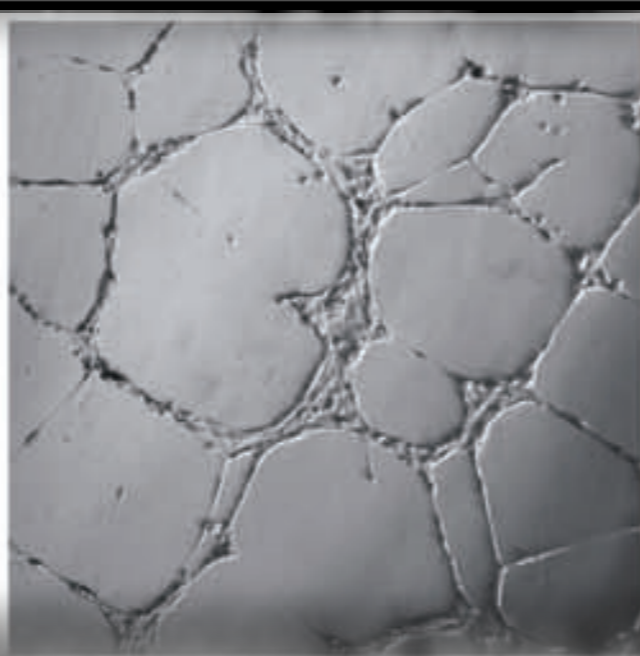


- LAGRANGIAN
- HETEROGENEOUS
- SCALABLE





J. M. MERKS, S. V. BRODSKY, M. S. POLIGORSKY,
 J. NEWMAN, AND D. A. LAJBERG. CELL
 DIVISION IS KEY TO INITIAL REPLICATION OF
 IN VITRO VASCULAR TISSUE AND SUBSEQUENT
 VASCULARIZATION. *EXPERIMENTAL BIOLOGY*, 289(1):
 65-72, 2002.



Vasculogenesis

blood vessel formation in embryonic development



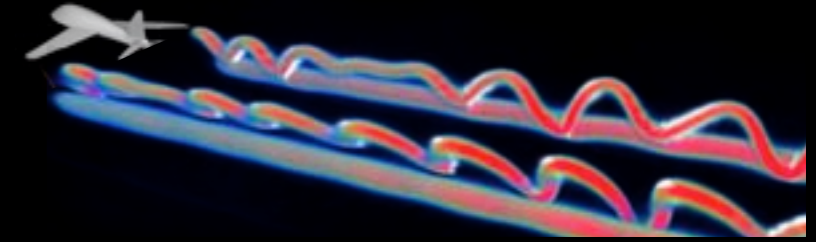
Crown Breakup - maragoni instability

drop impact onto an ethanol sheet

[2] S. T. THORODDSEN, T. G. ETOH, AND K. TAKEHARA. CROWN BREAKUP BY MARANGONI INSTABILITY. *J. FLUID MECH.*, 557(-1):63-72, 2006.

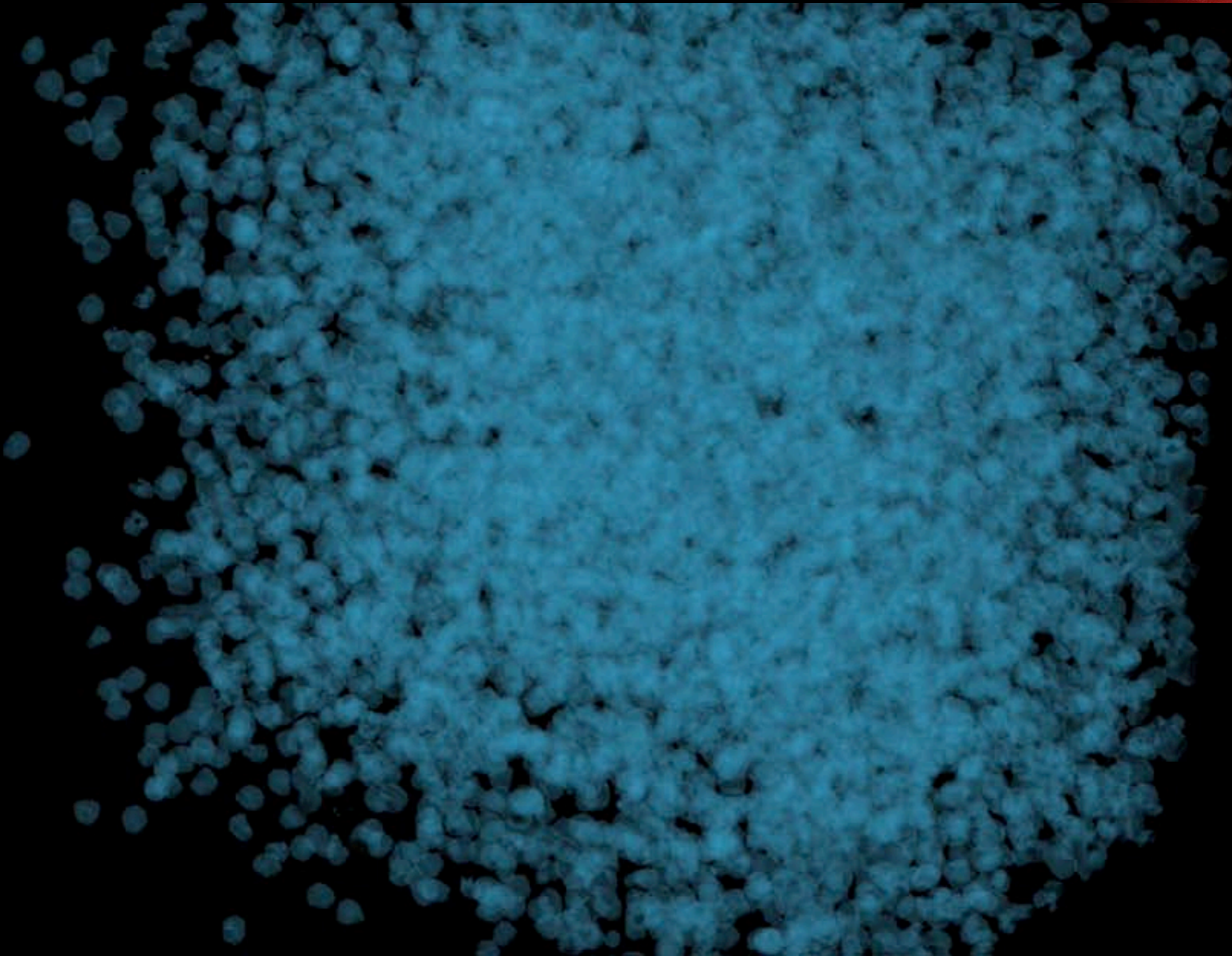
16384 Cores - 10 Billion Particles - 60% efficiency

Runs at IBM Watson Center - BLue Gene/L



Chatelain P., Curioni A., Bergdorf M., Rossinelli D., Andreoni W., Koumoutsakos P., Billion Vortex Particle Direct Numerical Simulations of Aircraft Wakes, Computer Methods in Applied Mech. and Eng. 197/13-16, 1296-1304, 2008

512 Cores - 10 Million Particles

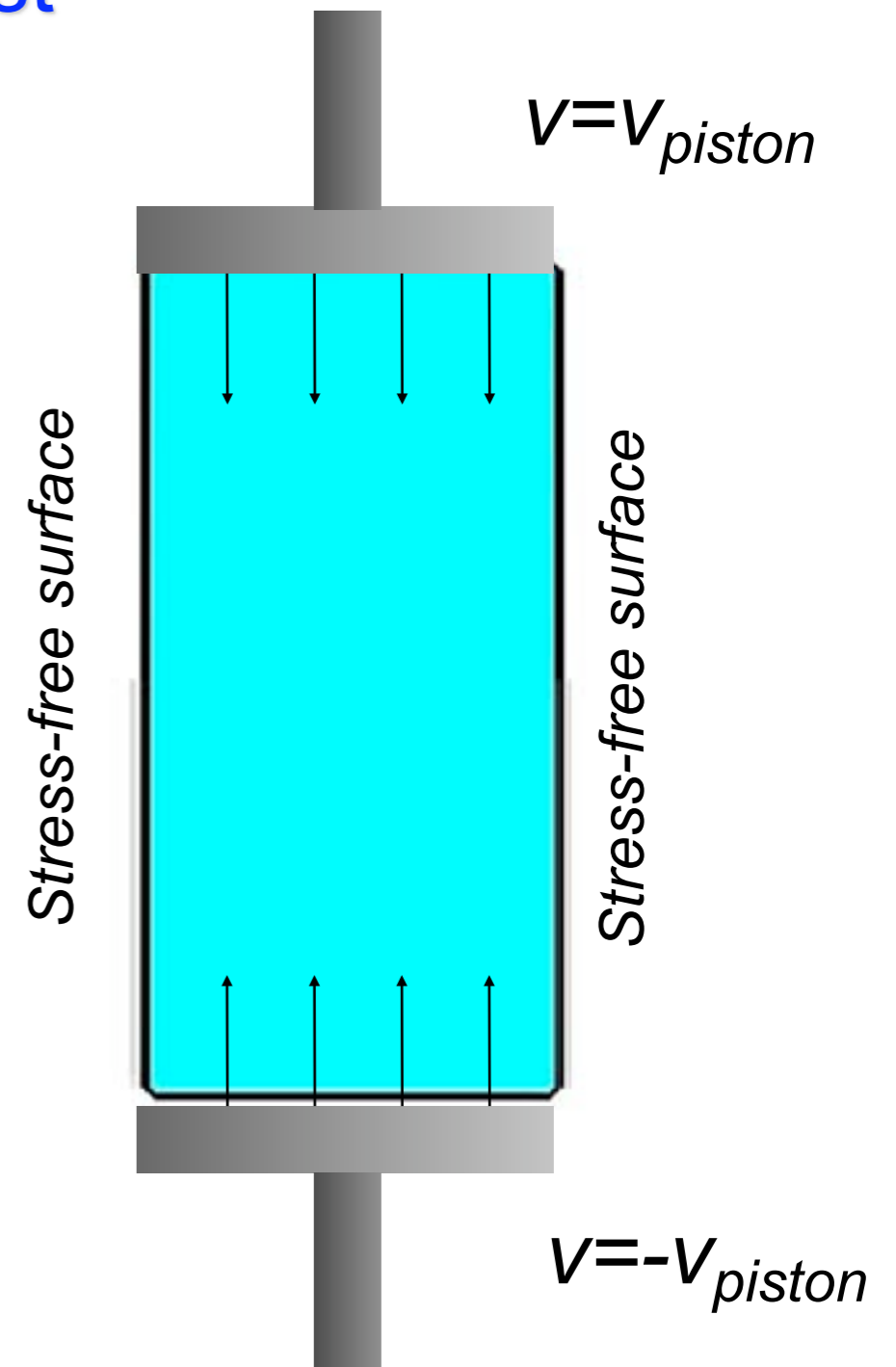


Milde F., Bergdorf M., Koumoutsakos P., A hybrid model of sprouting angiogenesis, Biophysical J.. 2008

Particle Simulation of Elastic Solid

Plane Strain Compression Test

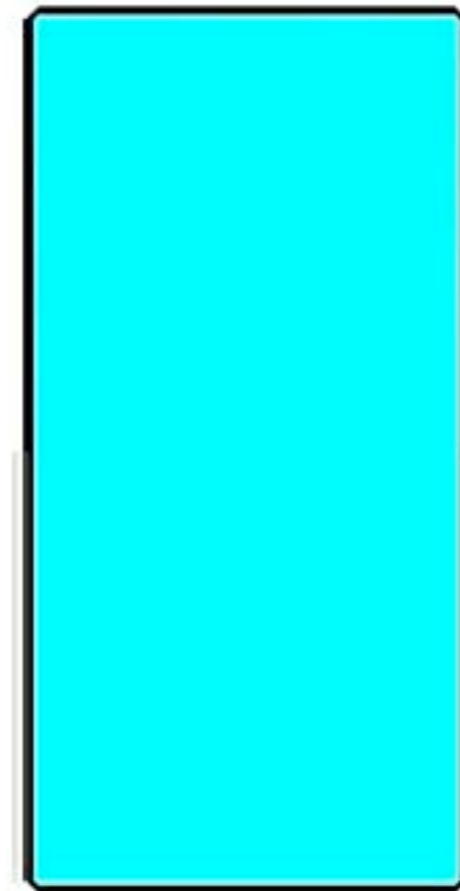
- Pistons move with constant velocity
- Elastic solid fixed to the pistons
- Highly dynamic deformation of large extent



Particle Simulation of Elastic Solid

Plane Strain Compression Test

- Pistons move with constant velocity
- Elastic solid fixed to the pistons
- Highly dynamic deformation of large extent



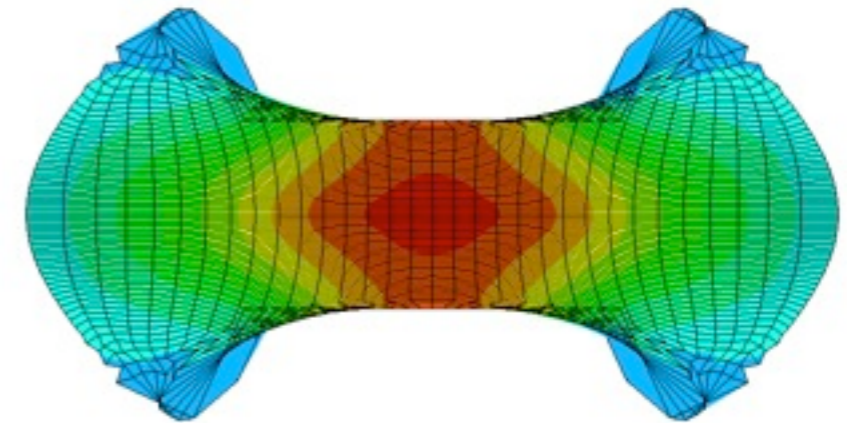
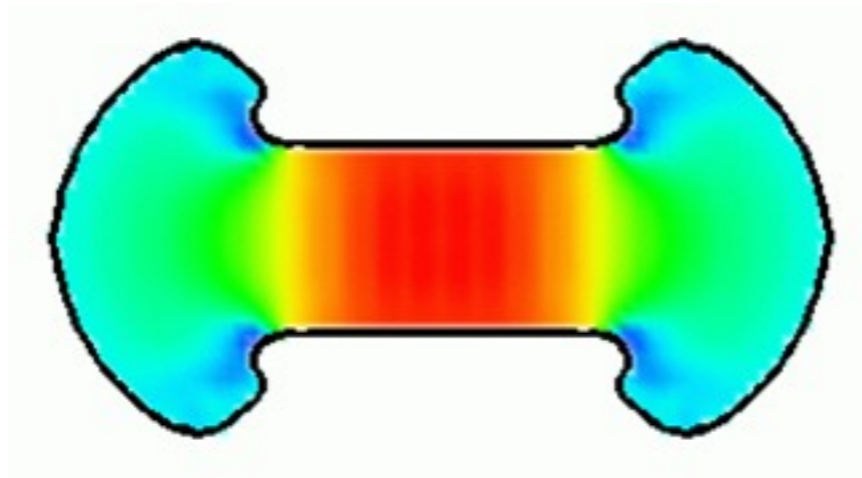
Plane Strain Compression Test

Redistributed
Particle solution

FEM solution (ABAQUS
6.4/Explicit)

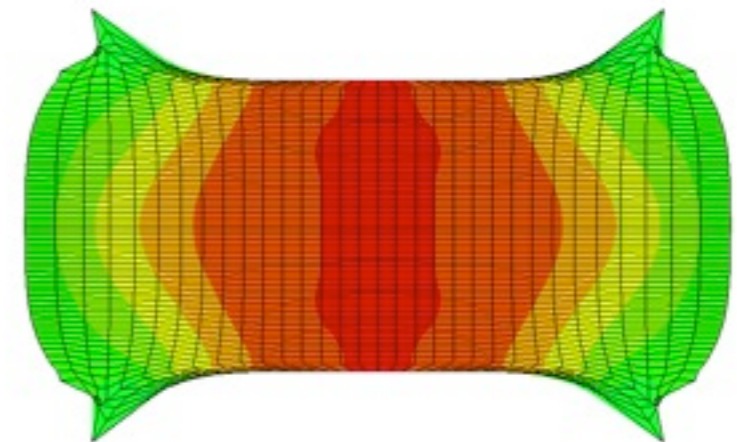
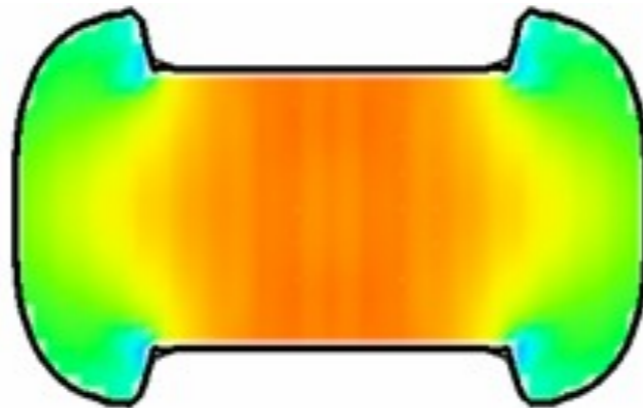
Linear Elasticity

Young's Modulus =100
Poisson ratio=0.49 ~2000
particles/nodes



Nonlinear Elasticity

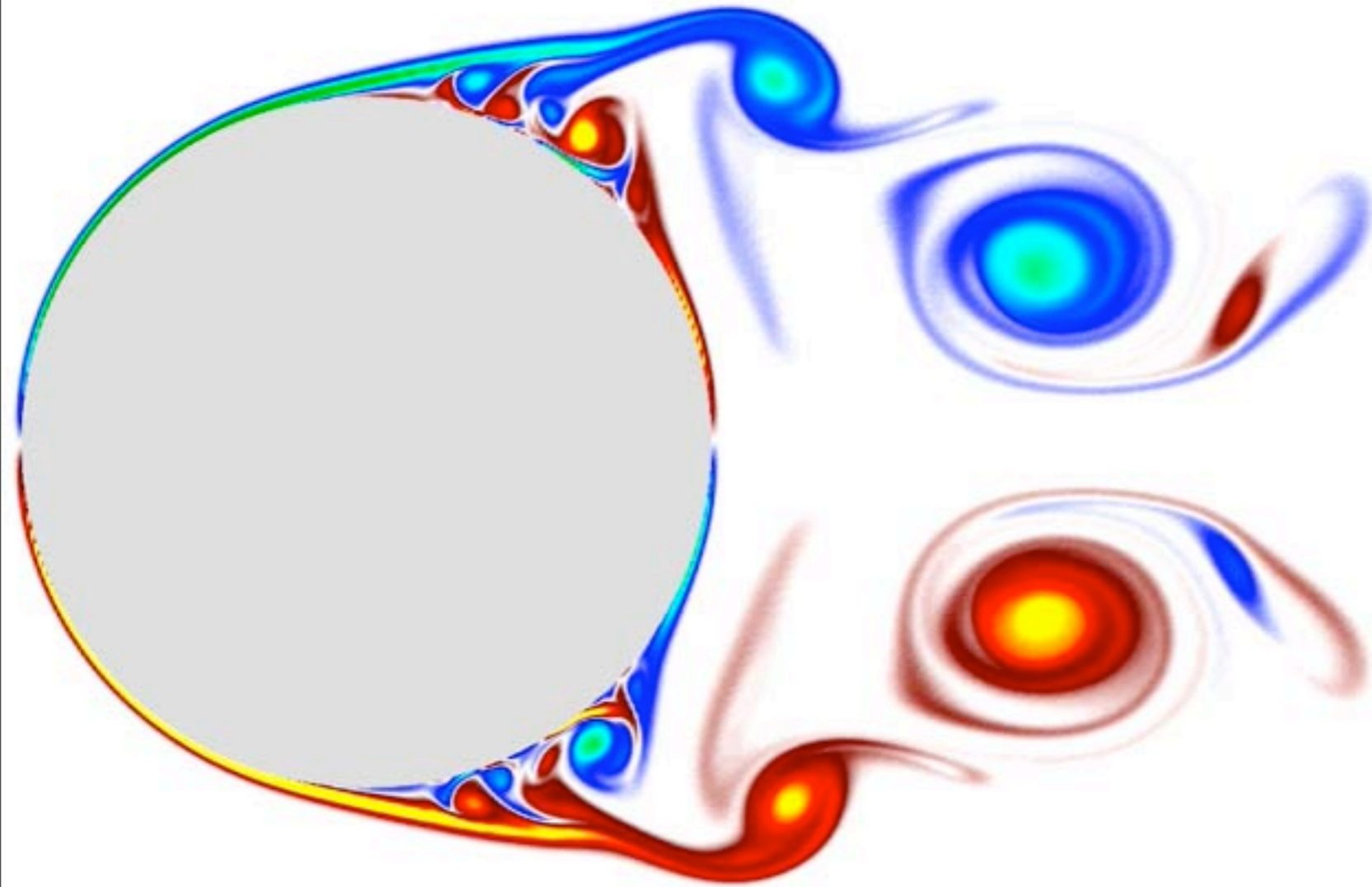
Hyperelastic Material
 $C_{10}=2.2$, $D=0.001$
~2000 particles/nodes



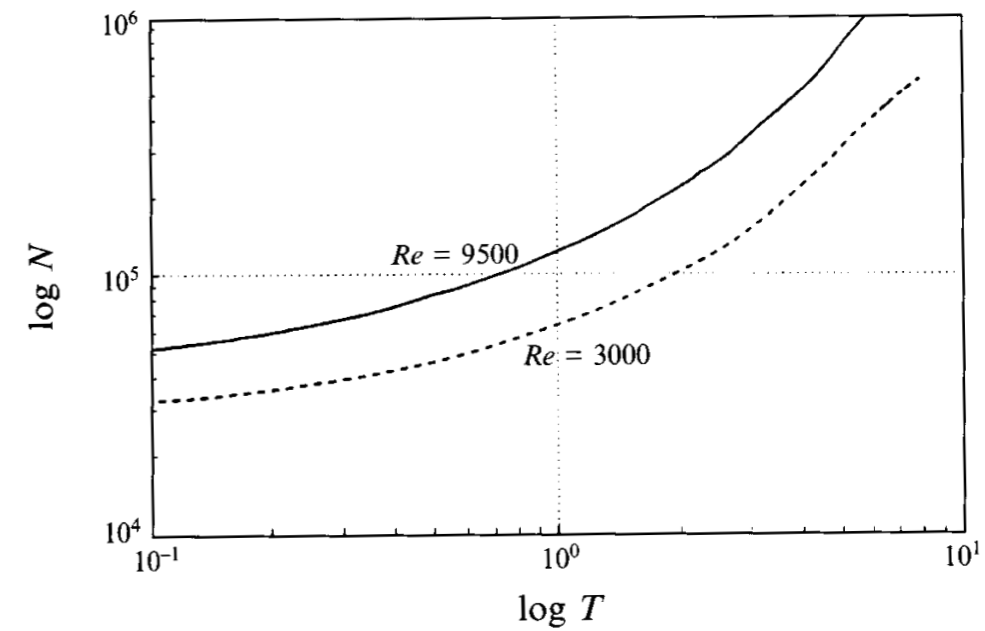
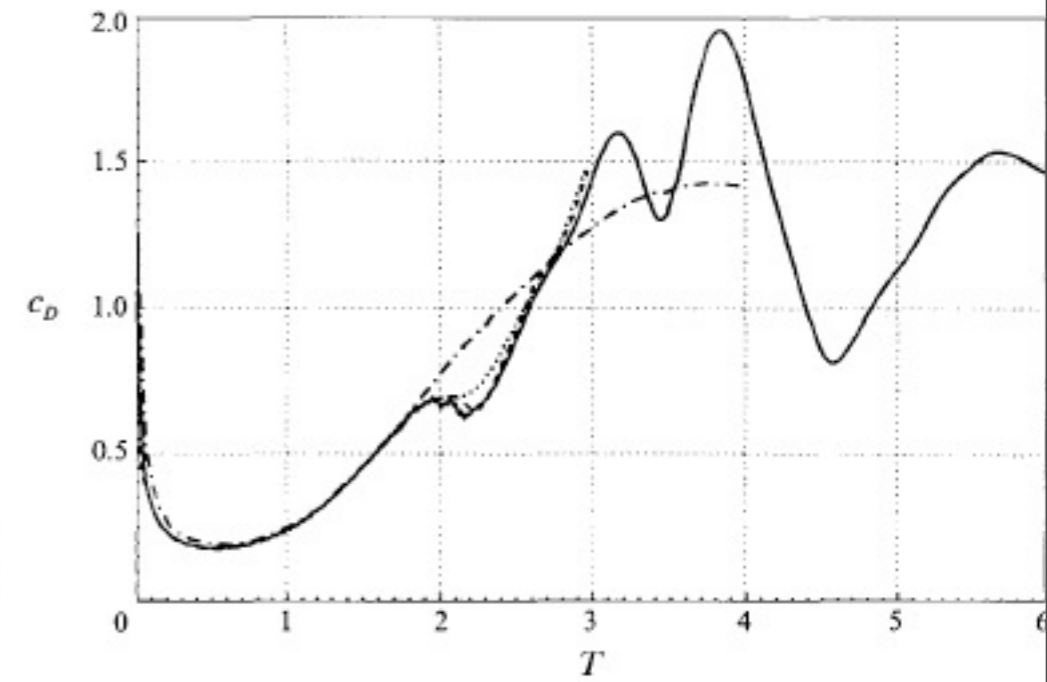
S.E. Hieber and P. Koumoutsakos A Lagrangian particle method for the simulation of linear and nonlinear elastic models of soft tissue. *al.*,
J. Comp. Physics, 2008

<http://www.icos.ethz.ch/cse>

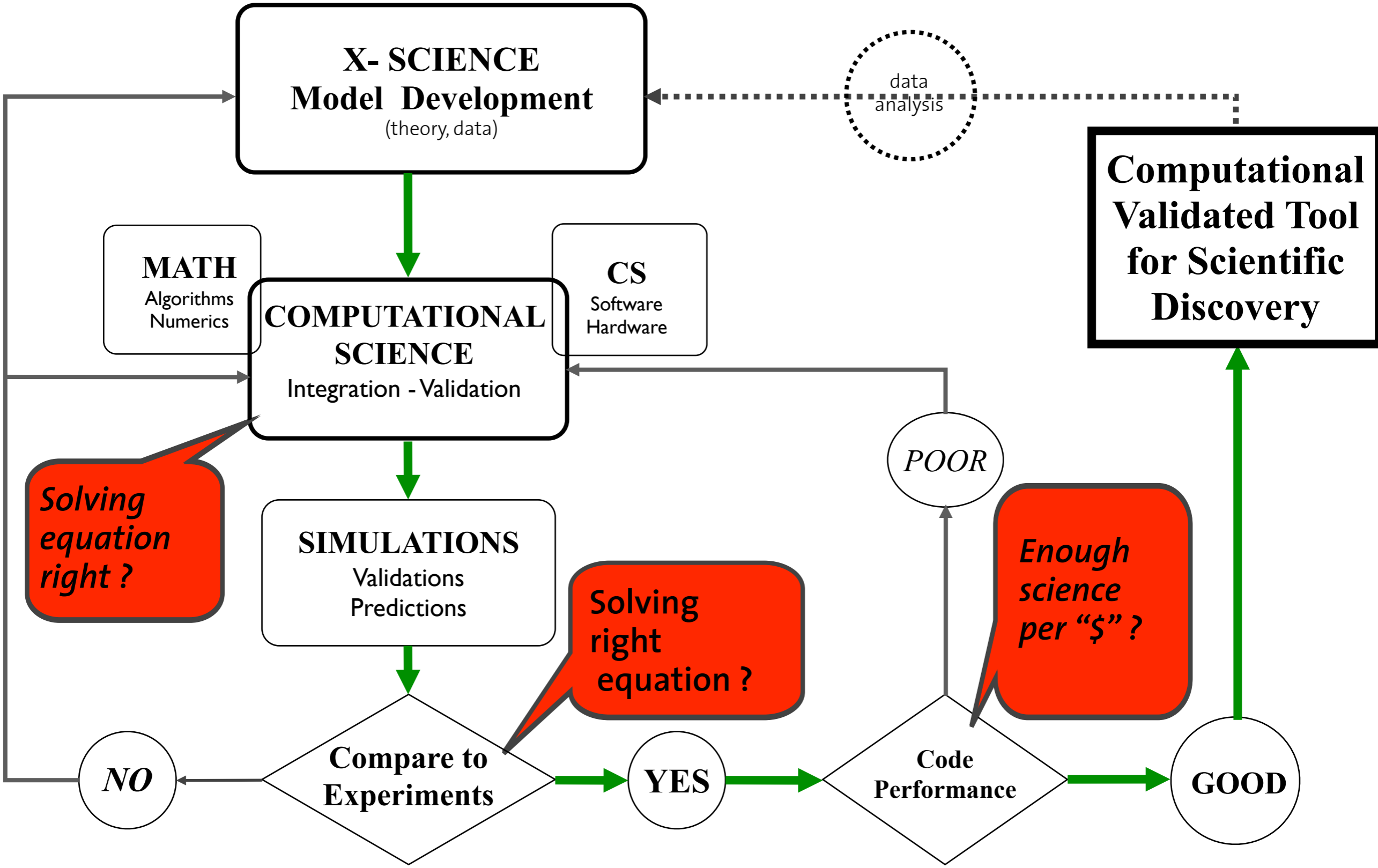
Why Adaptive Methods ?



Koumoutsakos & Leonard, JFM, 1995



Anatomy of a Simulation & 3 Gaps in Computing

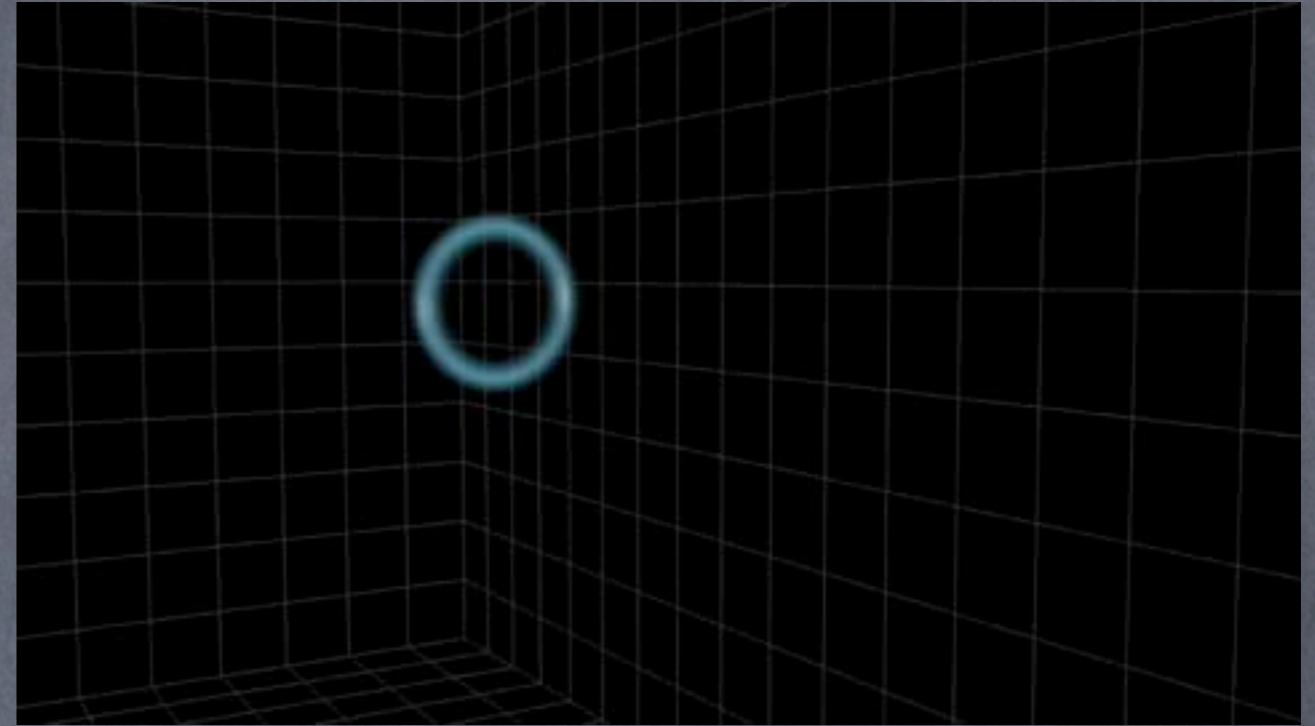


Adapted from : US-DOE

Particles : “Smooth” – Discrete

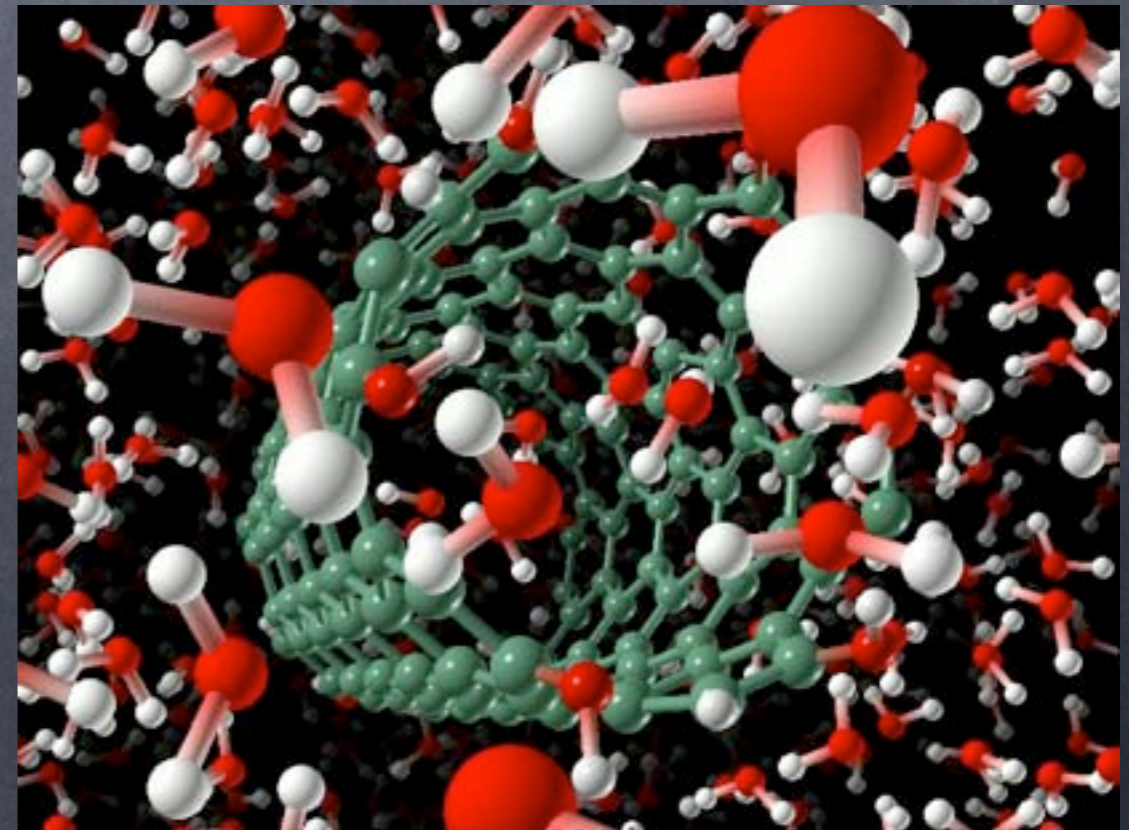
Smooth = APPROXIMATE

- Smoothed Particle Hydrodynamics
- Vortex Methods
- Lagrangian level sets



Discrete = MODEL

- Molecular Dynamics (MD)
- Dissipative Particle Dynamics
- Stochastic Simulation



Particle Methods: an **N-BODY** problem

Particle (**position, value**)

$i, j = 1, \dots, N$

$$\frac{dx_i}{dt} = U(q_j, q_i, x_i, x_j, \dots)$$

$$\frac{dq_i}{dt} = F(q_j, q_i, x_i, x_j, \dots)$$

SMOOTH

Particles are **quadrature** points for continuum properties
RHS of ODEs: quadratures of integral equations

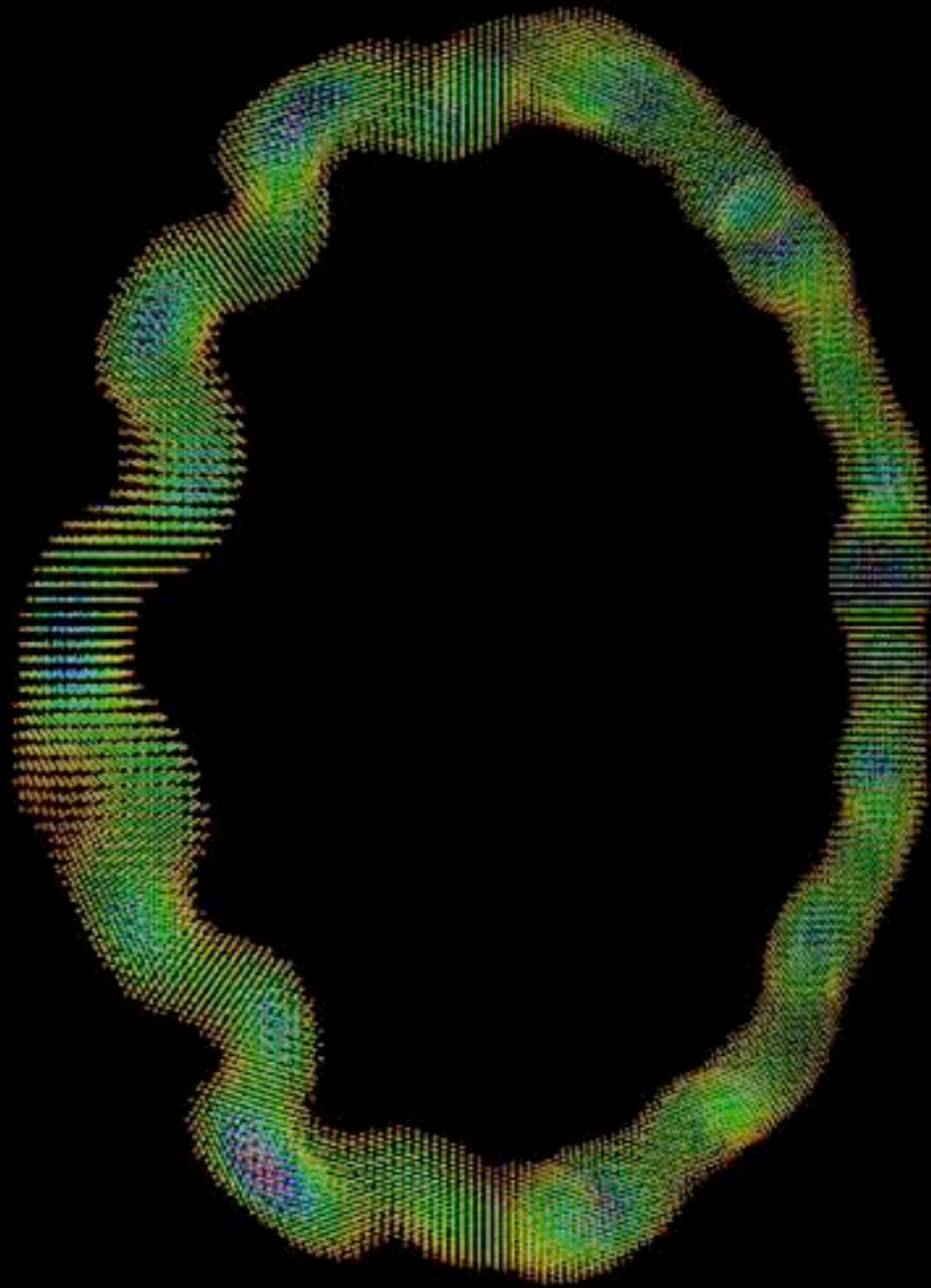
DISCRETE:

Particles as carriers of physical properties – Models
RHS of ODEs : Physical models – Particle interactions



Multipole Algorithms, Fast Poisson solvers, Adaptivity, multiresolution, multiphysics

PARTICLES Smooth & Discrete



Smooth/Discrete Particles

"To let a drop of ink fall into water is a simple and most beautiful experiment."

D'Arcy Wentworth Thompson

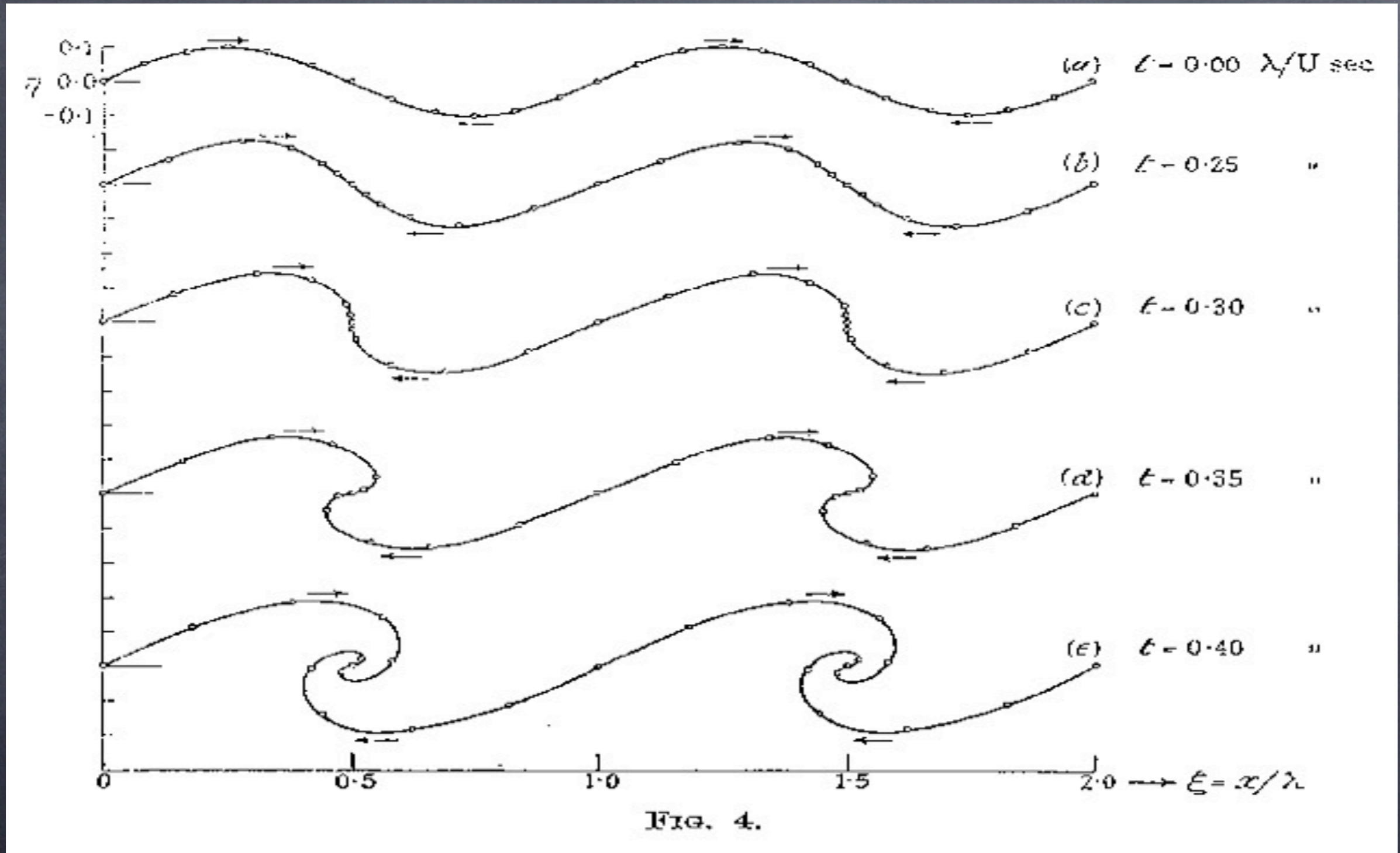
On Growth and Form

J. H. Walther, P. Koumoutsakos, Three-dimensional vortex methods for particle-laden flows with two-way coupling, J. Comput. Phys., 167, 39-71, 2001



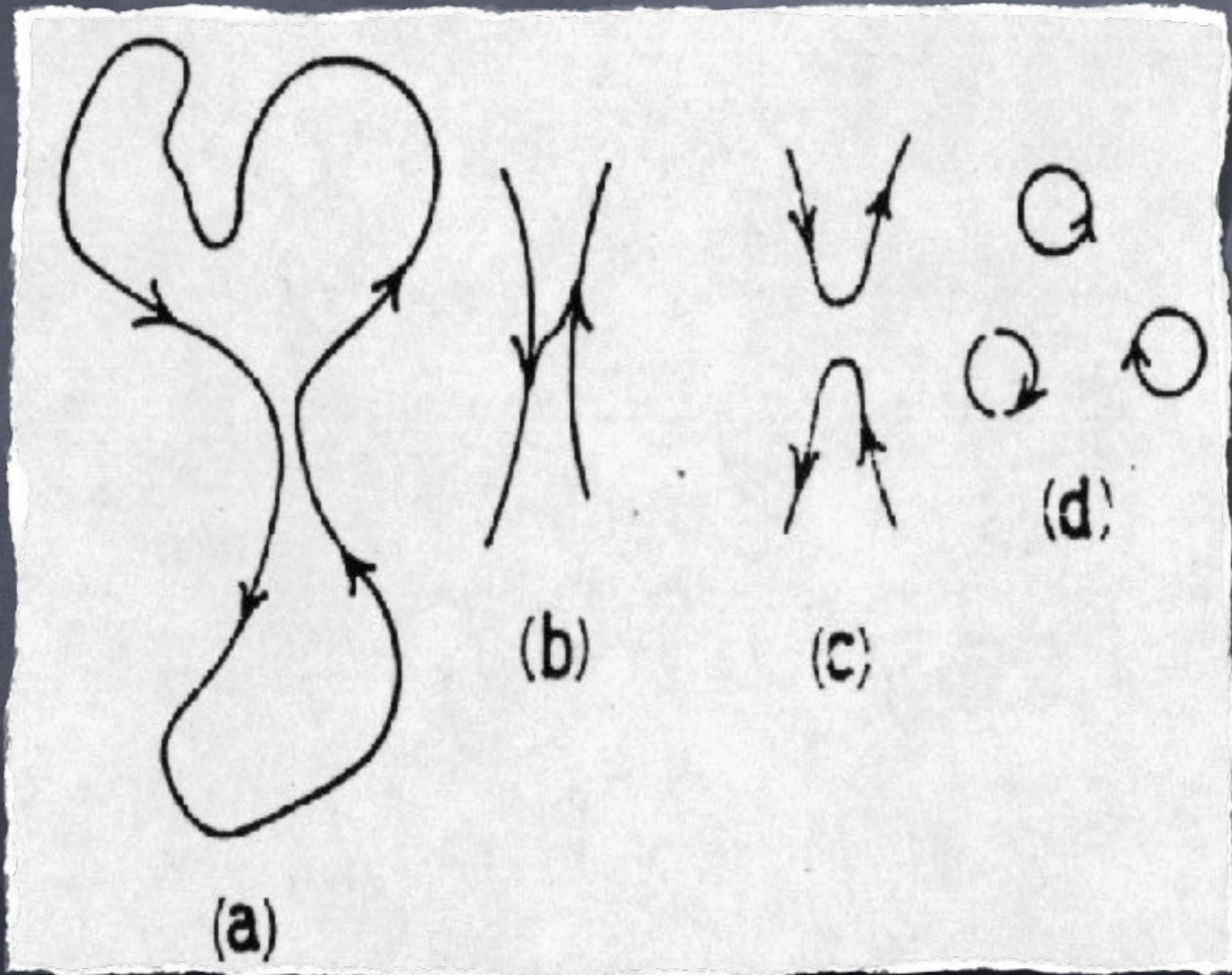
A BRIEF HISTORY of PARTICLE METHODS

The 1920's



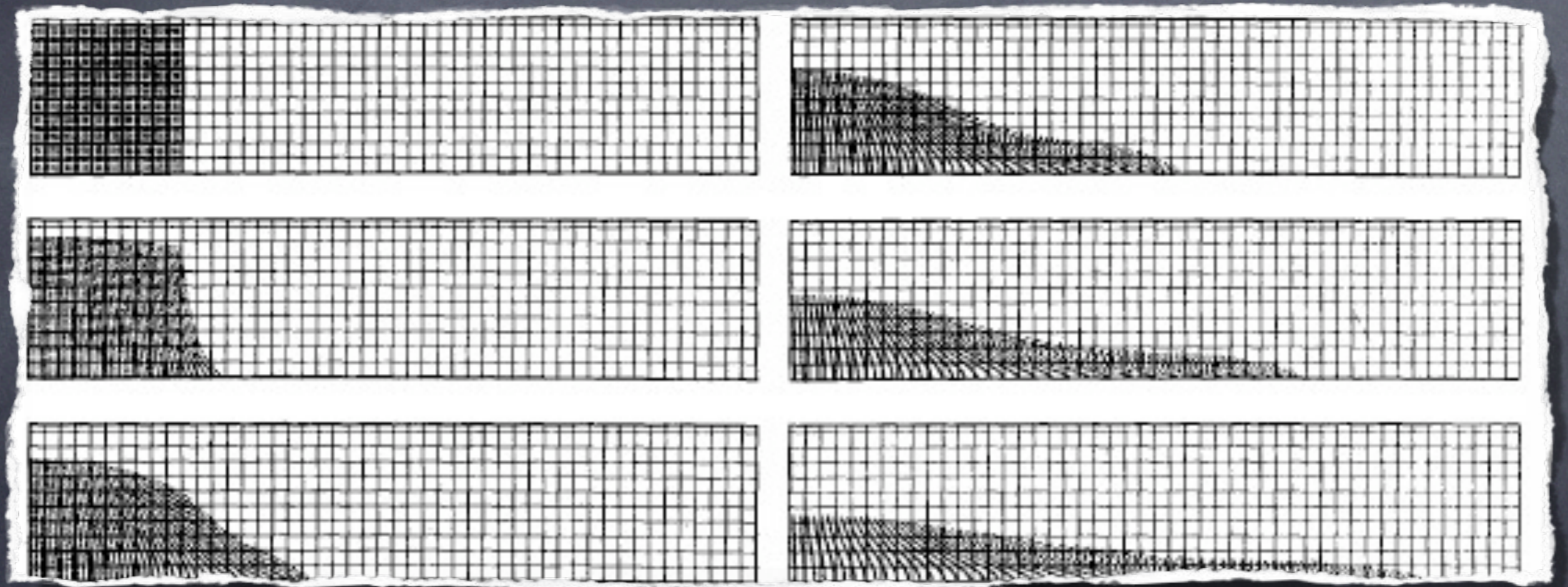
Rosenhead - Hand Calculations of a Vortex Sheet

The 50's



Feynman – Vortex Filaments: How do they break and reconnect ?

The 60's : Marker And Cell (MAC) - (velocity - pressure)

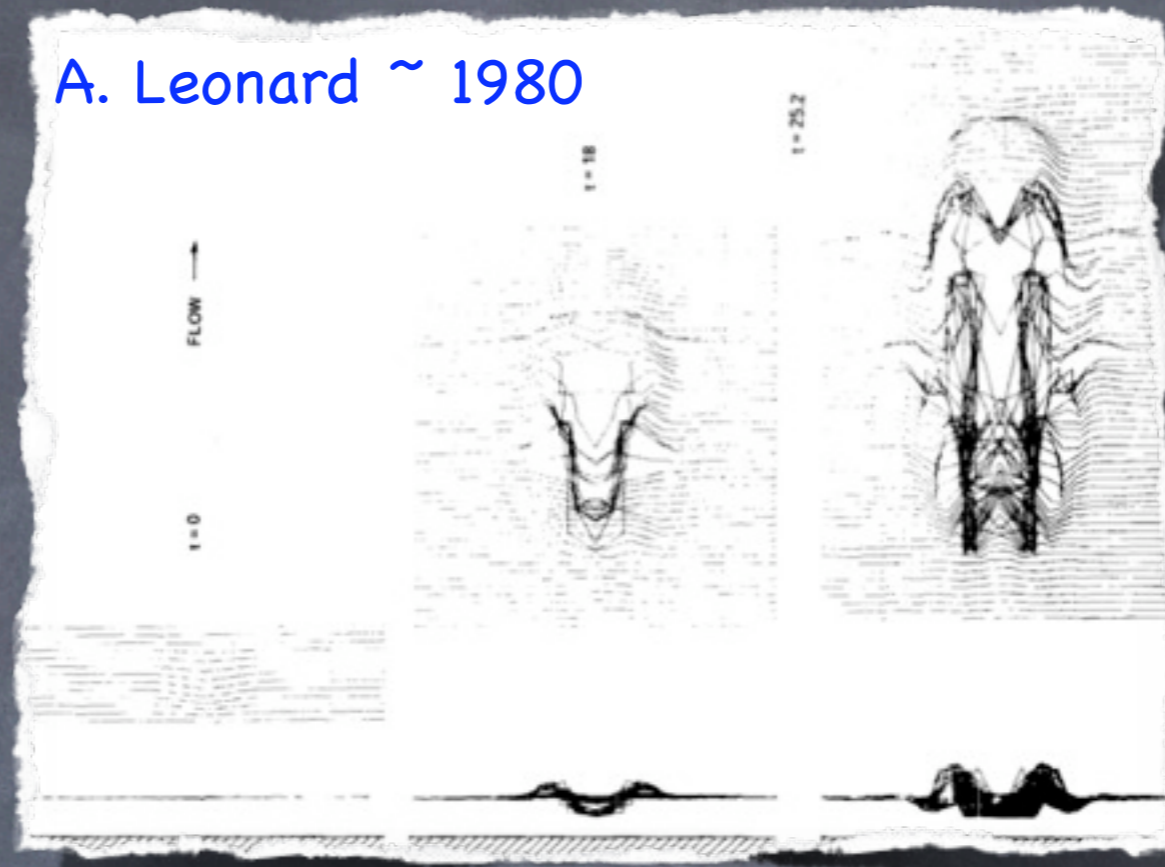


F.H. Harlow and E.J. Welch

Numerical Calculation of Time-Dependent Viscous Incompressible Flow of Fluid with Free Surface, Harlow, Francis H. and Welch, J. Eddie, *Physics of Fluids*, 1965

vortex Particle Methods : From the 60's to the 80's

A. Leonard ~ 1980



A. Chorin ~ 1970



FIGURE 1. Flow at (a) $R = 1000$, $t = 12$; (b) $R = 1000$, $t = 24$; (c) $R = 100$, $t = 16$.

C. Peskin ~ 1980



t = 00.01

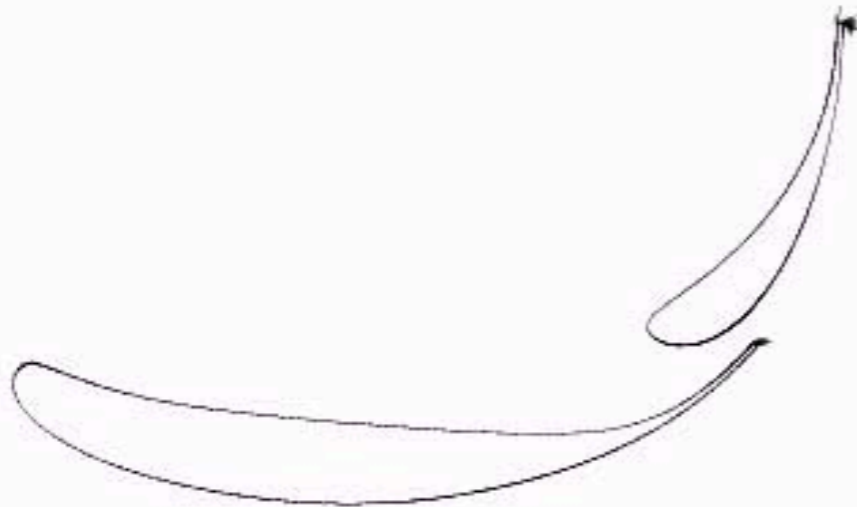
What stopped Vortex Methods ?

3D - Boundaries

Cost

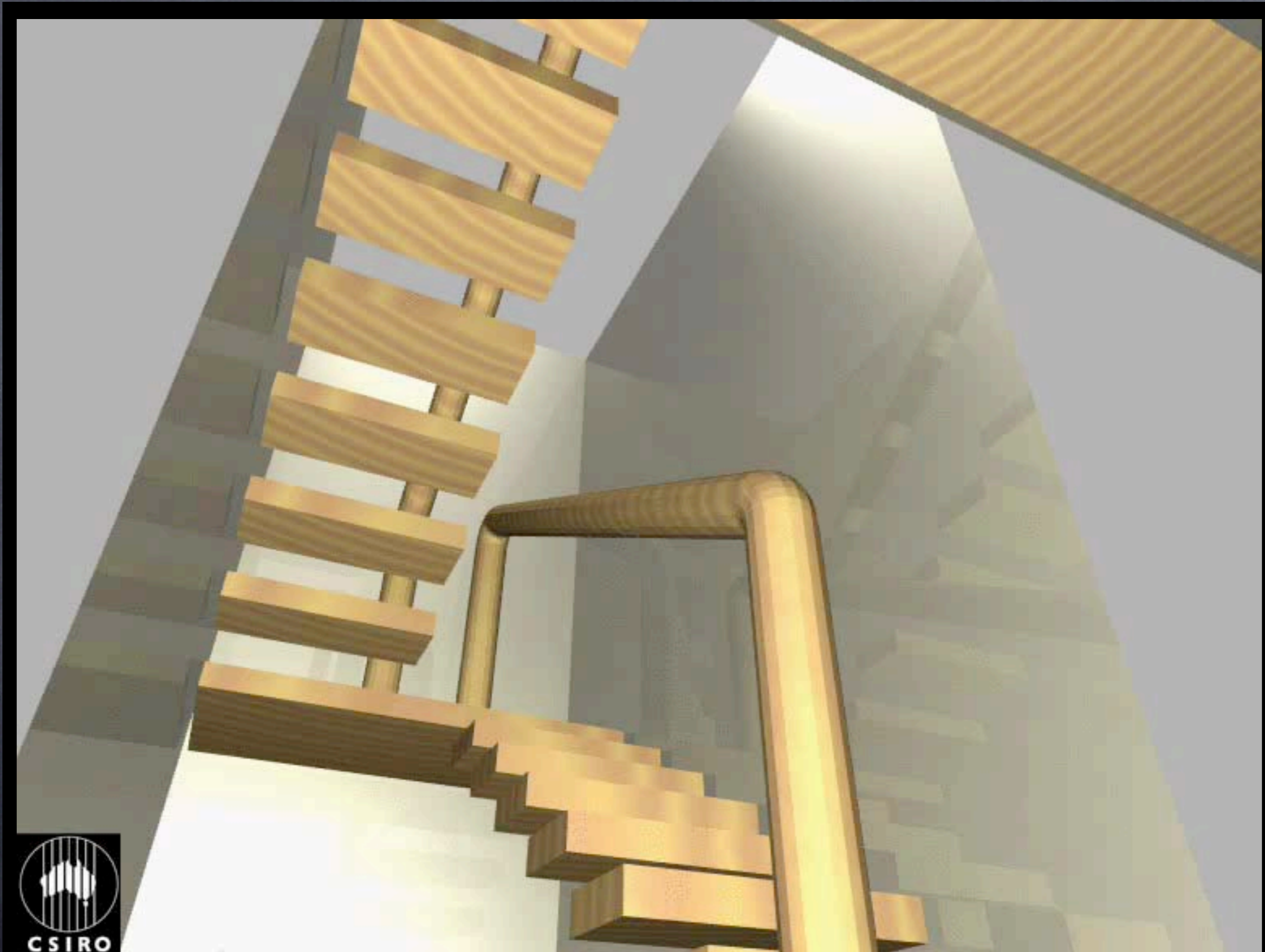
No theory of convergence

.....



Particles strike back : SPH (Monaghan, Lucy, 1970's)

GRID FREE + LAGRANGIAN/ADAPTIVE + NO POISSON EQUATION



Growth of Black Holes
Springel, MPI -
Hernquist, Harvard



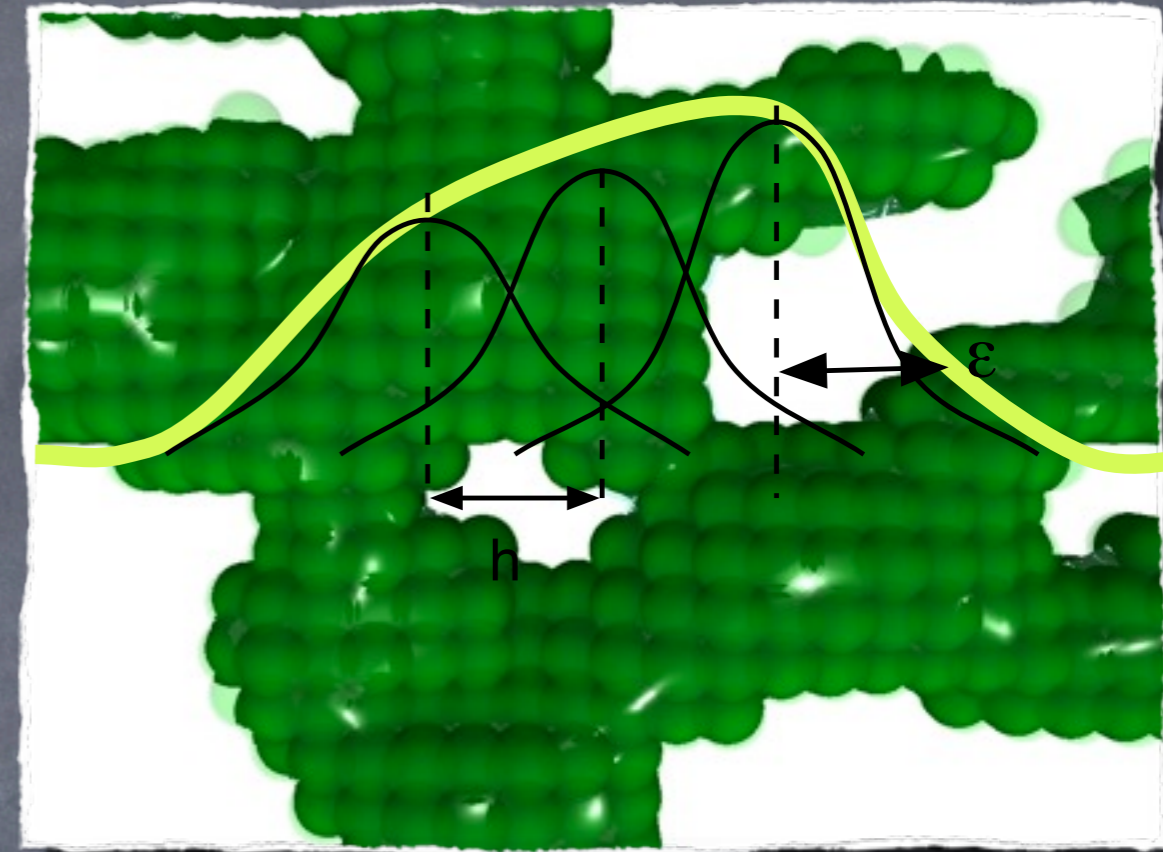
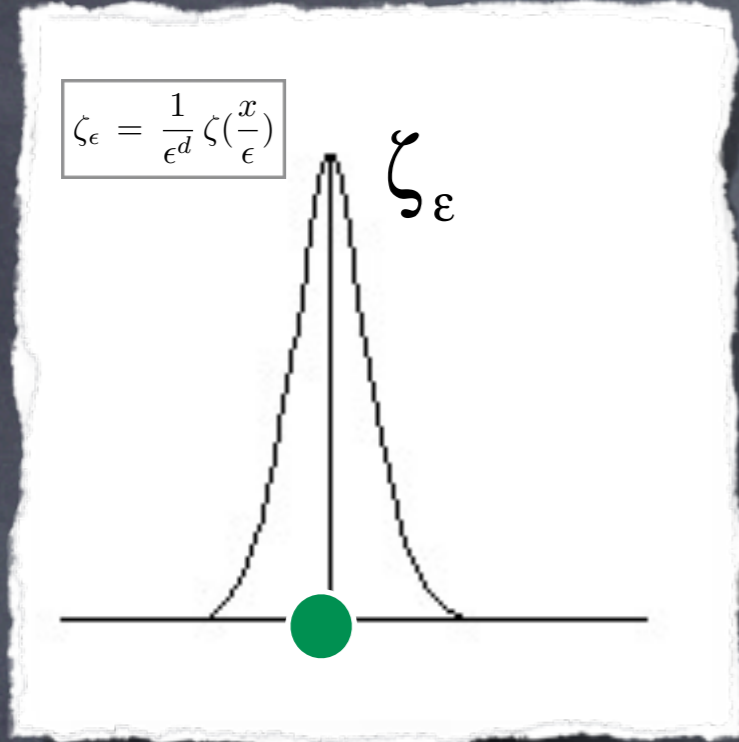
Lucy, 1974 : A numerical scheme for the testing of the fission hypothesis, Astron. J.

FLUIDS and PARTICLES : CFD and GRAPHICS



Star Trek

How does it work ?



Particles $p = 1, \dots, N$

locations x_p volumes $v_p = h_p^d$

properties

$$Q_p(t) = q(x_p, t)$$

Function approximation

$$q_\epsilon^h(x, t) = \sum_{p=1}^{N_p} h_p^d Q_p(t) \zeta_\epsilon(x - x_p(t))$$

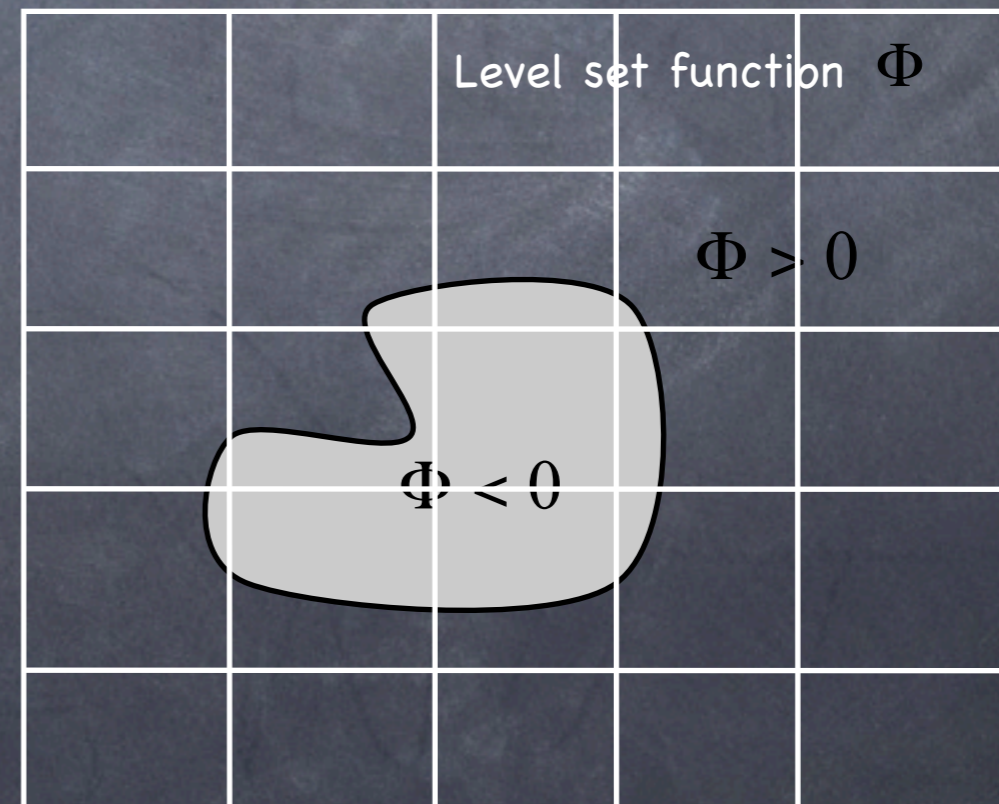
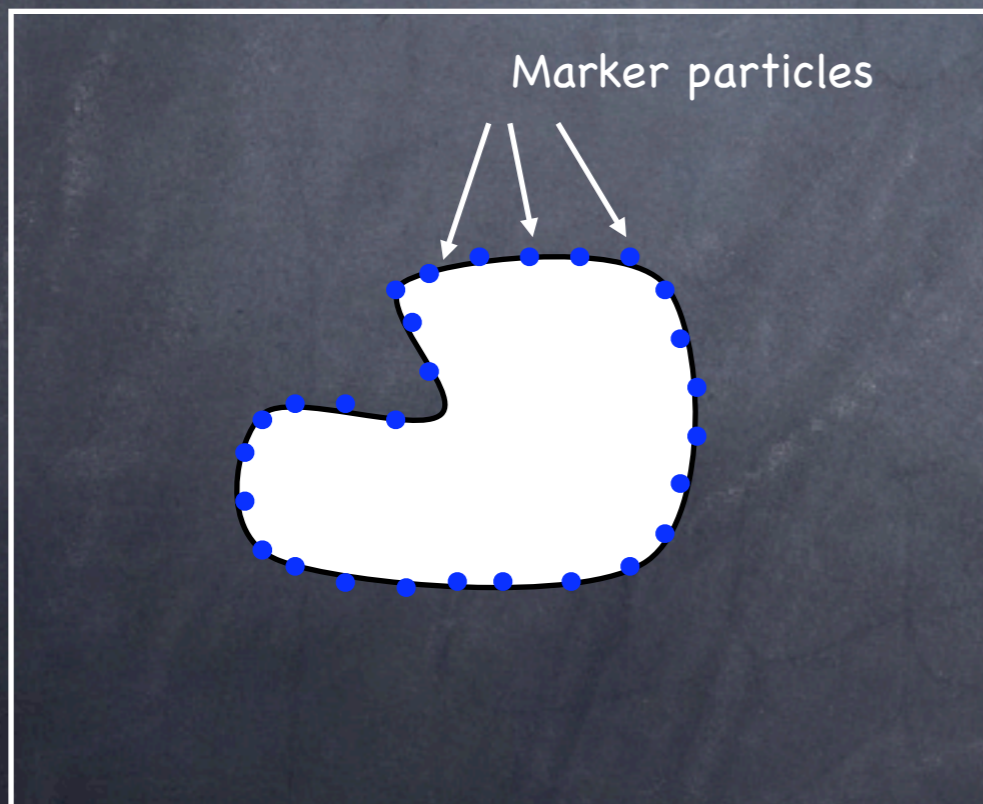
Interface Tracking versus Capturing

Tracking

- Explicit description
- Lagrangian framework
- Interface distortion requires reseeding

Capturing

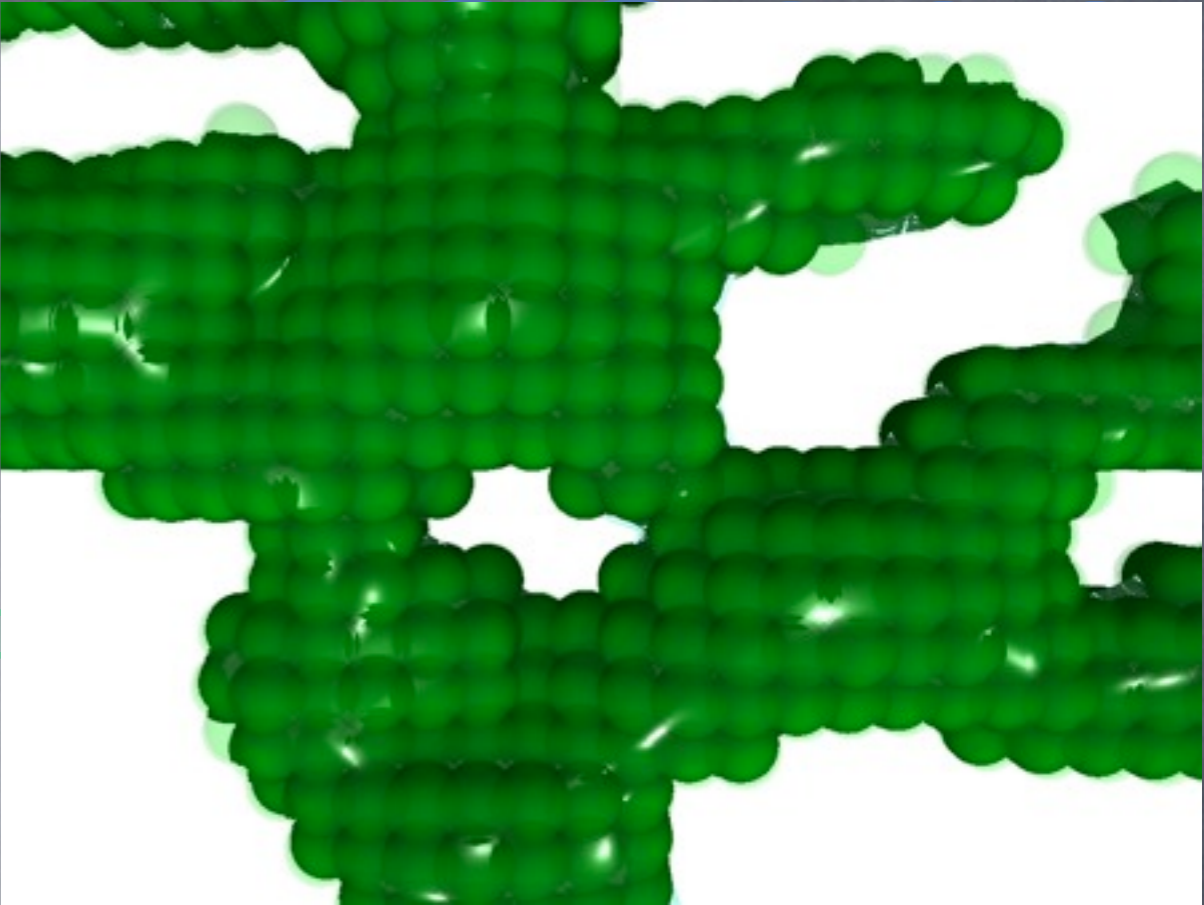
- Implicit description
- Eulerian framework



PARTICLE METHODS : Geometry

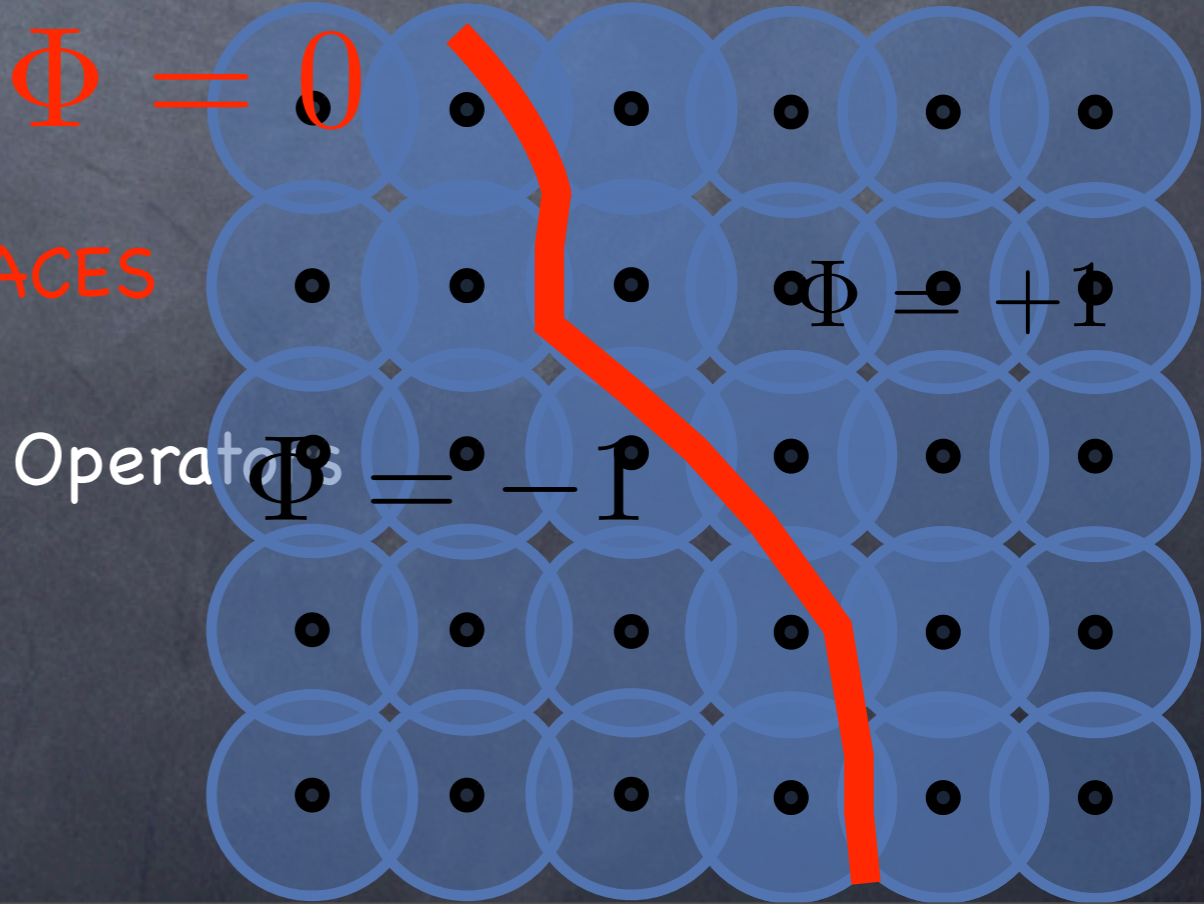
Volume particles

- Particles are quadrature points
- Easy to discretize **COMPLEX GEOMETRIES**



Surface particles

- **Particle - Level Sets - COMPLEX SURFACES**
- Surface Operators - Anisotropic Volume Operators



PARTICLES + LAGRANGIAN ADAPTIVITY

$$\frac{\partial q}{\partial t} + \nabla \cdot (\mathbf{u}q) = \mathcal{L}(q, \mathbf{x}; t)$$

Lagrangian form: $\frac{Dq}{Dt} = \mathcal{L}(q, \mathbf{x}; t)$

PARTICLES

→ no **linear** stability constraints
= no **CFL** ($dt < dx/u$) condition

$$\frac{d\mathbf{x}_p}{dt} = \mathbf{u}(\mathbf{x}_p, t),$$

positions

initial values

on lattice

$$\frac{dv_p}{dt} = v_p (\nabla \cdot \mathbf{u})(\mathbf{x}_p, t),$$

volumes

$$v_p = h^d$$

$$\frac{dQ_p}{dt} = v_p \mathcal{L}^{\varepsilon, h}(q, \mathbf{x}_p, t).$$

weights

$$Q_p = q(\mathbf{x}_p, 0) v_p$$

CONTINUUM : Lagrangian Form of Governing Equations

Positions

$$\frac{D\mathbf{x}_p}{Dt} = \mathbf{u}_p$$

Volumes

$$\frac{Dv_p}{Dt} = v_p(\nabla \cdot \mathbf{u})_p$$

Mass Conservation

Properties

$$\rho_p \frac{D\mathbf{u}_p}{Dt} = (\nabla \cdot \boldsymbol{\sigma})_p$$

Momentum Conservation

$$\boldsymbol{\sigma}_p = -p_p I + \bar{\boldsymbol{\sigma}}_p$$

evaluation depends on
the constitutive model

Interfaces

$$\frac{D\Phi_p}{Dt} = 0$$

Particle level sets : 3D curvature-driven flow:

$$\frac{\partial \Phi}{\partial t} + \mathbf{u} \cdot \nabla \Phi = 0$$

$$\Gamma(t) = \{\mathbf{x} \in \Omega \mid \phi(\mathbf{x}, t) = 0\}$$

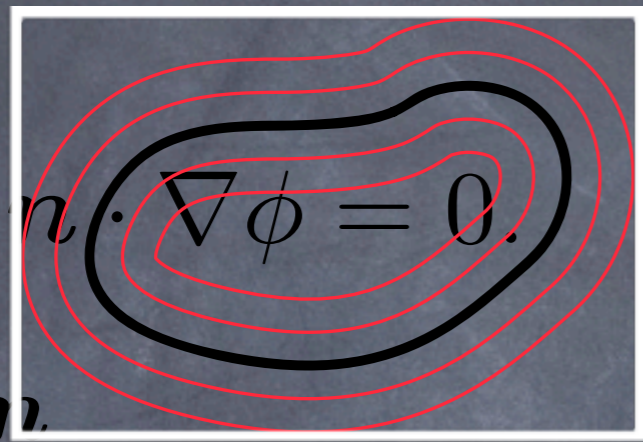
Collapsing Dumbbell

$$\Phi_\epsilon^h(x, t) = \sum_{p=1}^{N_p} h_p^d \Phi_p(t) \zeta_\epsilon(x - x_p(t))$$

$$|\nabla \phi| = 1$$

$$\frac{\partial \phi}{\partial t} + \kappa \mathbf{n} \cdot \nabla \phi = 0$$

$$\kappa = \nabla \cdot \mathbf{n}$$



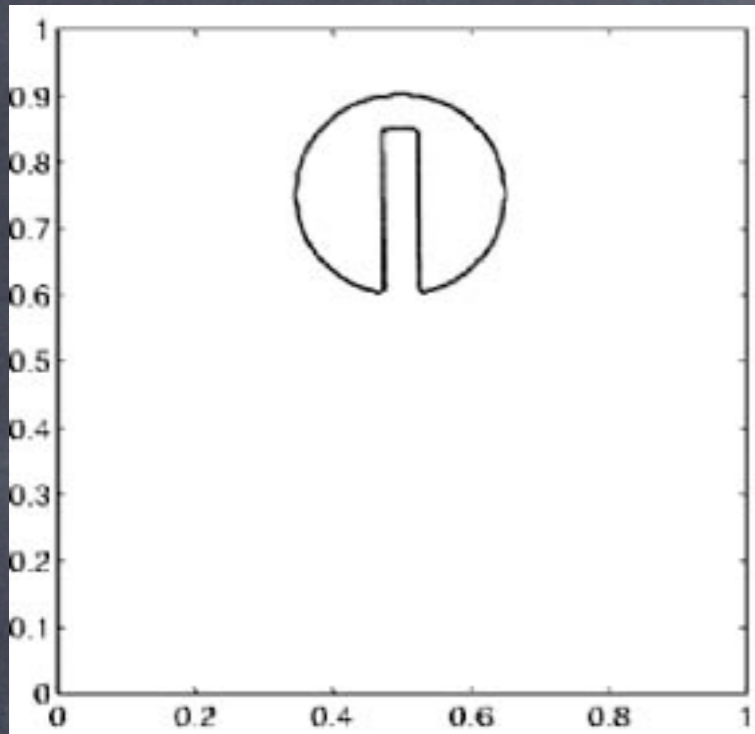
$$\frac{D\Phi_p}{Dt} = 0 \quad \frac{dx_p}{dt} = \mathbf{u}$$

Particle Approximation

A Lagrangian Particle Level Set Method, Hieber and Koumoutsakos, J. Comp. Phys. 2005

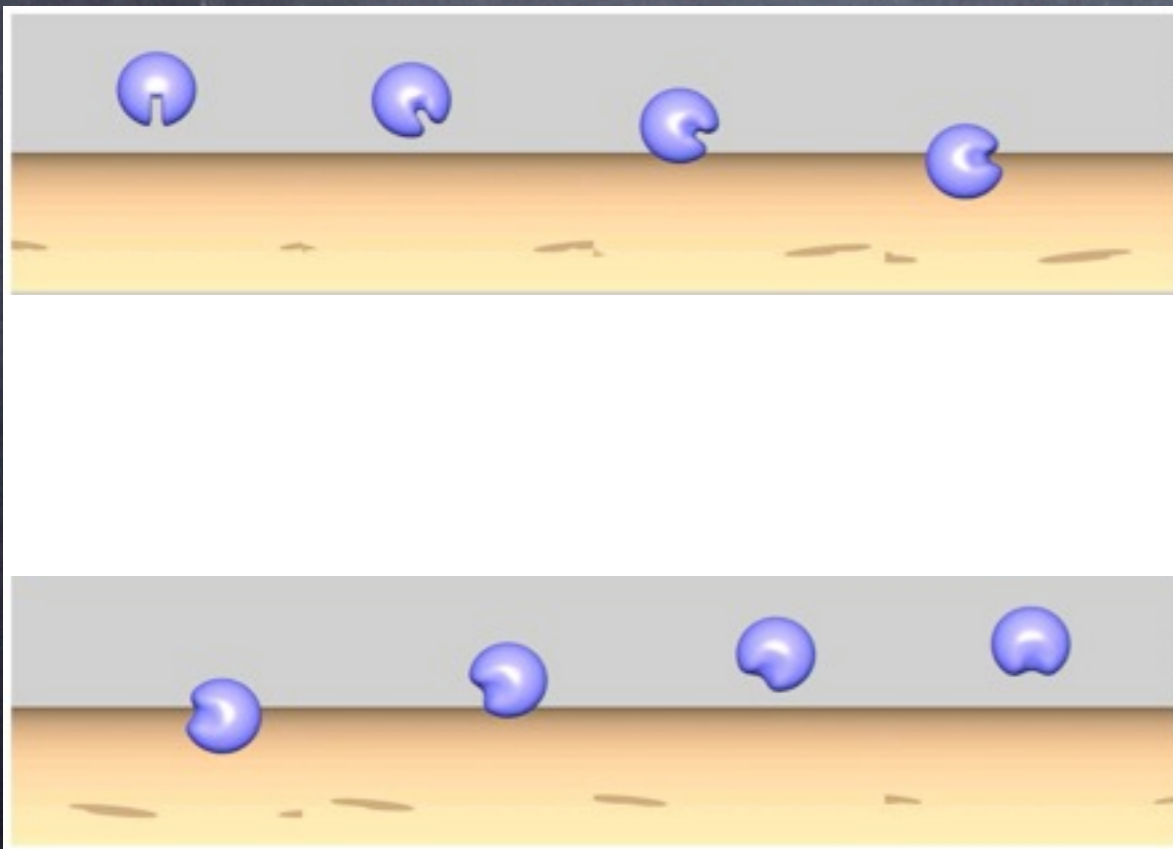


Benchmark: Rigid Body Motion



- Problem of rotating slotted disk/sphere
- Particle level sets exact for rigid body motion

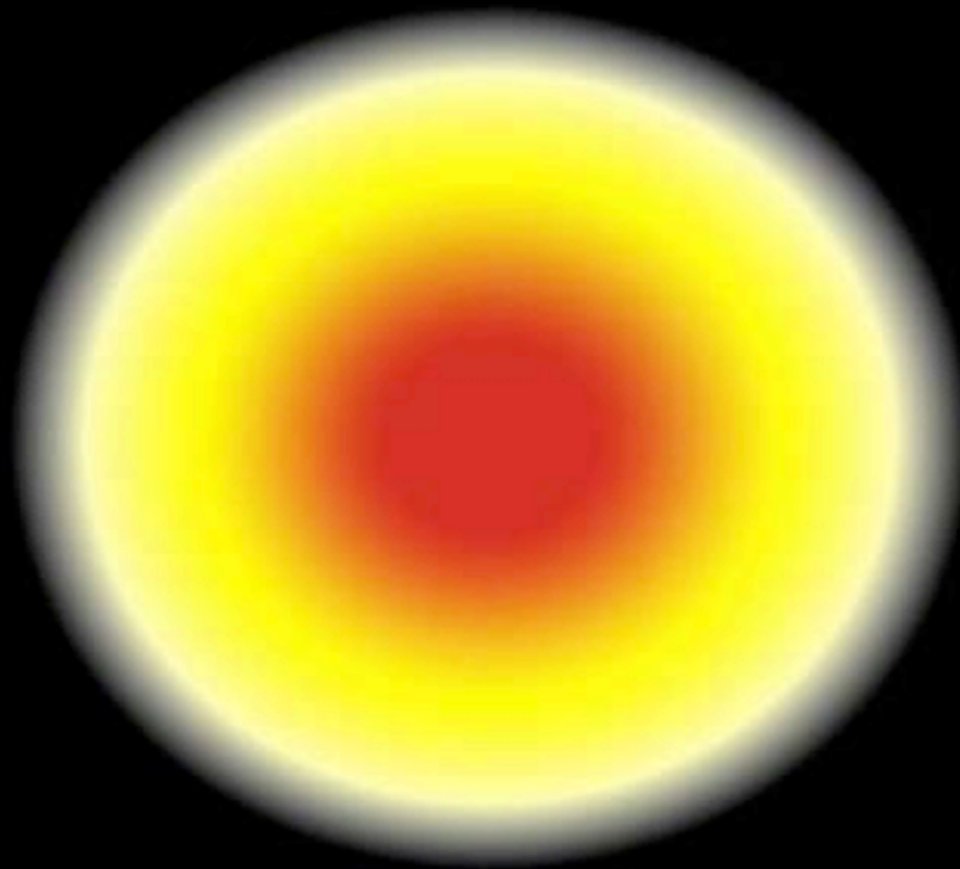
Particle level set method
(800 particles)



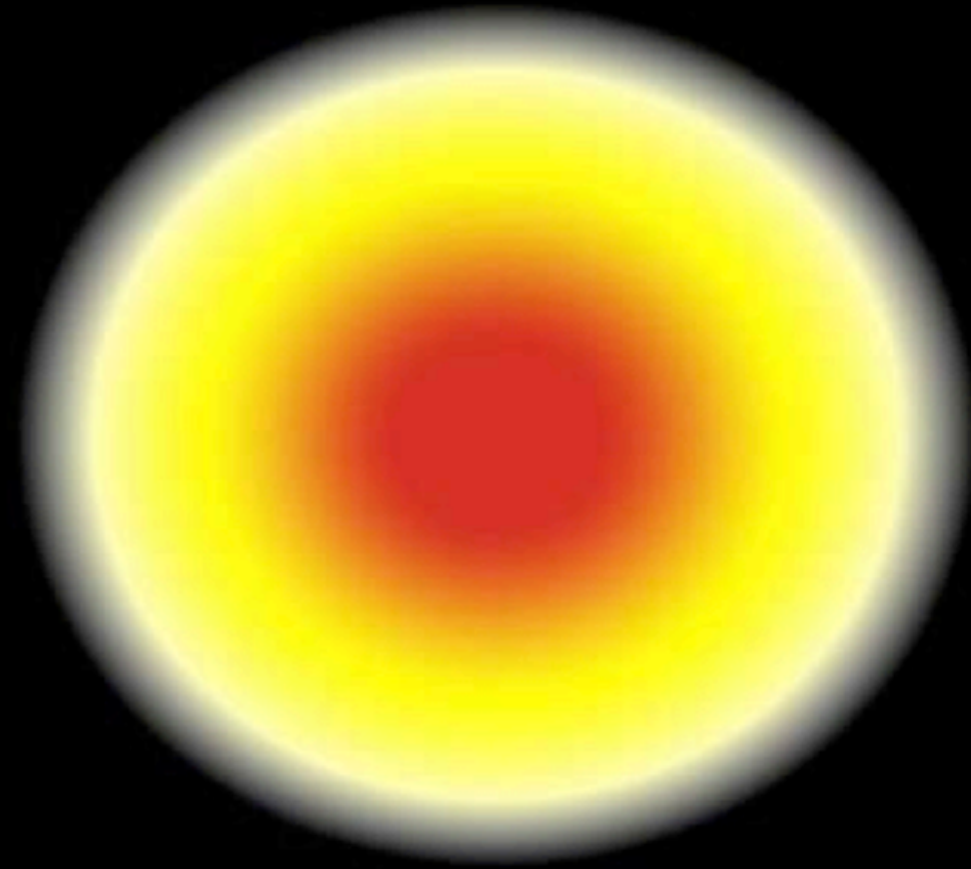
Particle Level Sets (exact !)



Are grid-free Particle Methods Accurate ?



$t = 0.00$



$t = 0.00$

Solution of the Euler equation with particle methods.

Smooth Particles must **Overlap**

Particle Approximation =

Mollification

$$\Phi_\epsilon(x) = \int \Phi(y) \zeta_\epsilon(x - y) dy$$

+

Quadrature

$$\Phi_\epsilon^h(x, t) = \sum_{p=1}^{N_p} h_p^d \Phi_p(t) \zeta_\epsilon(x - x_p(t))$$

$$\begin{aligned} \|\Phi - \Phi_\epsilon^h\| &\leq \|\Phi - \Phi_\epsilon\| + \|\Phi_\epsilon - \Phi_\epsilon^h\| \\ &\leq C_1 \epsilon^r + C_2 \left(\frac{h}{\epsilon}\right)^m \|\Phi\|_\infty \end{aligned}$$

NOTES :

- **Must have $h/\epsilon < 1$** for the quadrature to be accurate i.e. **PARTICLES MUST OVERLAP.**
- References : J. Raviart (1970's), O. Hald (1980's), T. Hou (1990's), G.H. Cottet (1990's)

Lagrangian distortion and REMESHING

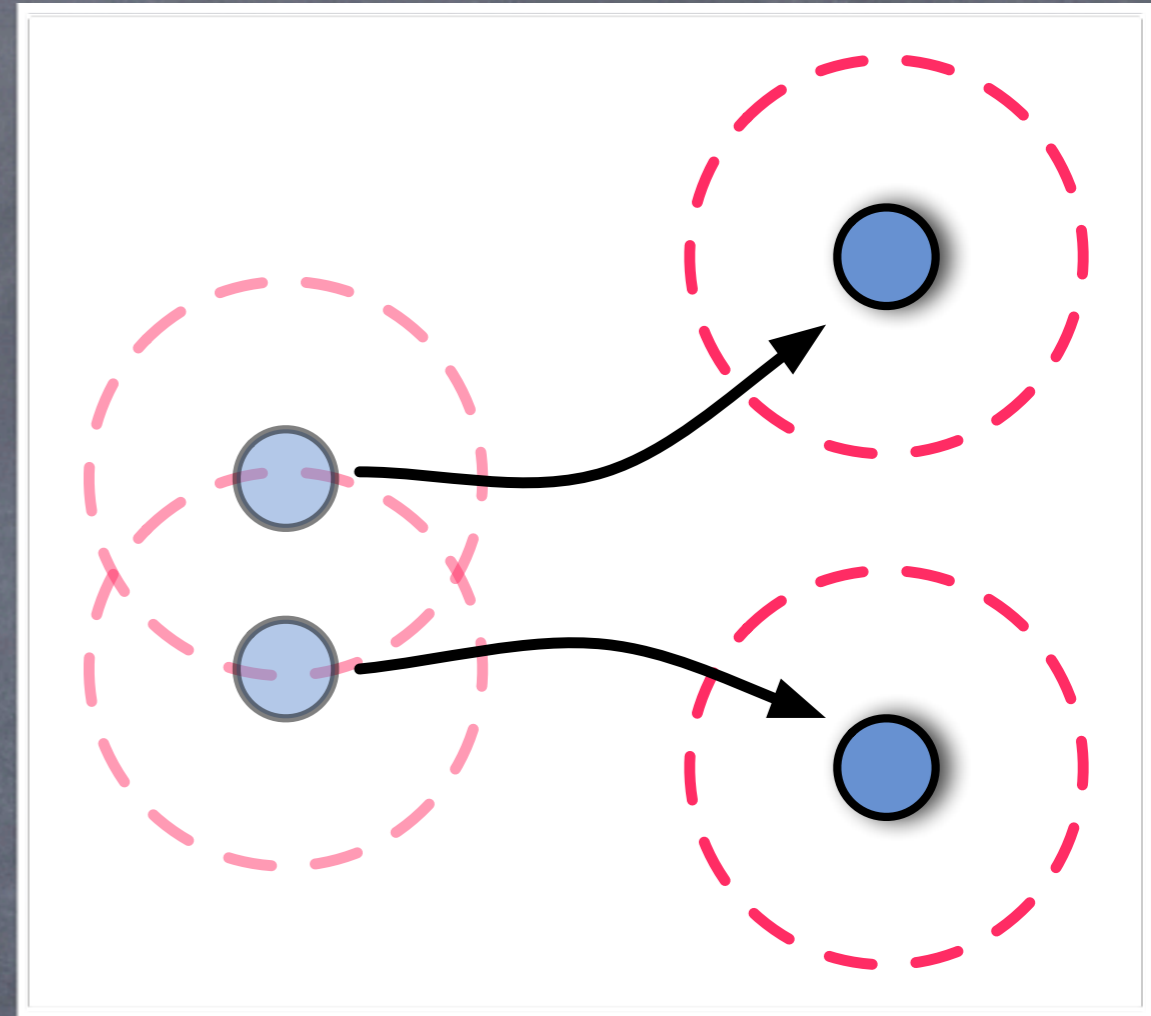
Particles follow flow trajectories

- distortion of particle locations
- loss of **overlap**
- loss of **convergence**

Preventive action: **remeshing**

Reinitialize particles on a regular grid.

$$Q_i^{\text{new}} = \sum_p Q_p \zeta^h(\mathbf{i}h - \mathbf{x}_p)$$



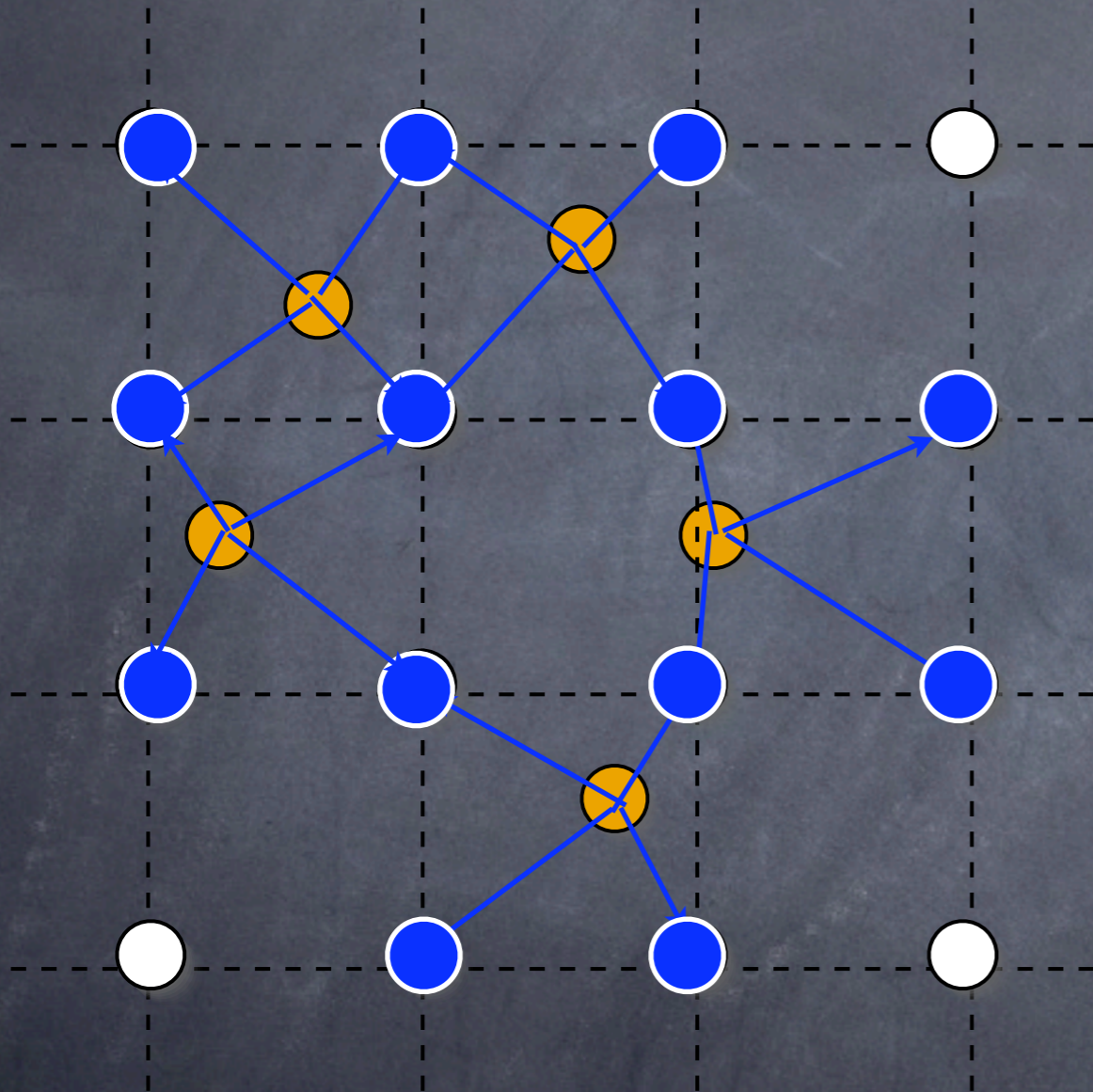
Limiting: Introduction of a grid

Enabling:

- Fast Poisson solvers
- Access **versatility** of finite differences
- Enabling efficient **multiresolution** adaptivity

Remeshing = Regularization = Resampling

A new regularized particle set from the old one



$$Q_p^{\text{new}} = \sum_{p'} Q_{p'} M(j h - x_{p'})$$

Interpolation Kernel $M(x)$

- **Moment conserving**
- Tensorial Product of 1D kernels

REFERENCES :

Vortex Methods : PK and Leonard , JFM, 1995, and PK, JCP, 1997

SPH : Chaniotis, Poulikakos and PK, JCP, 2002

Hybrid Particle Mesh

Techniques

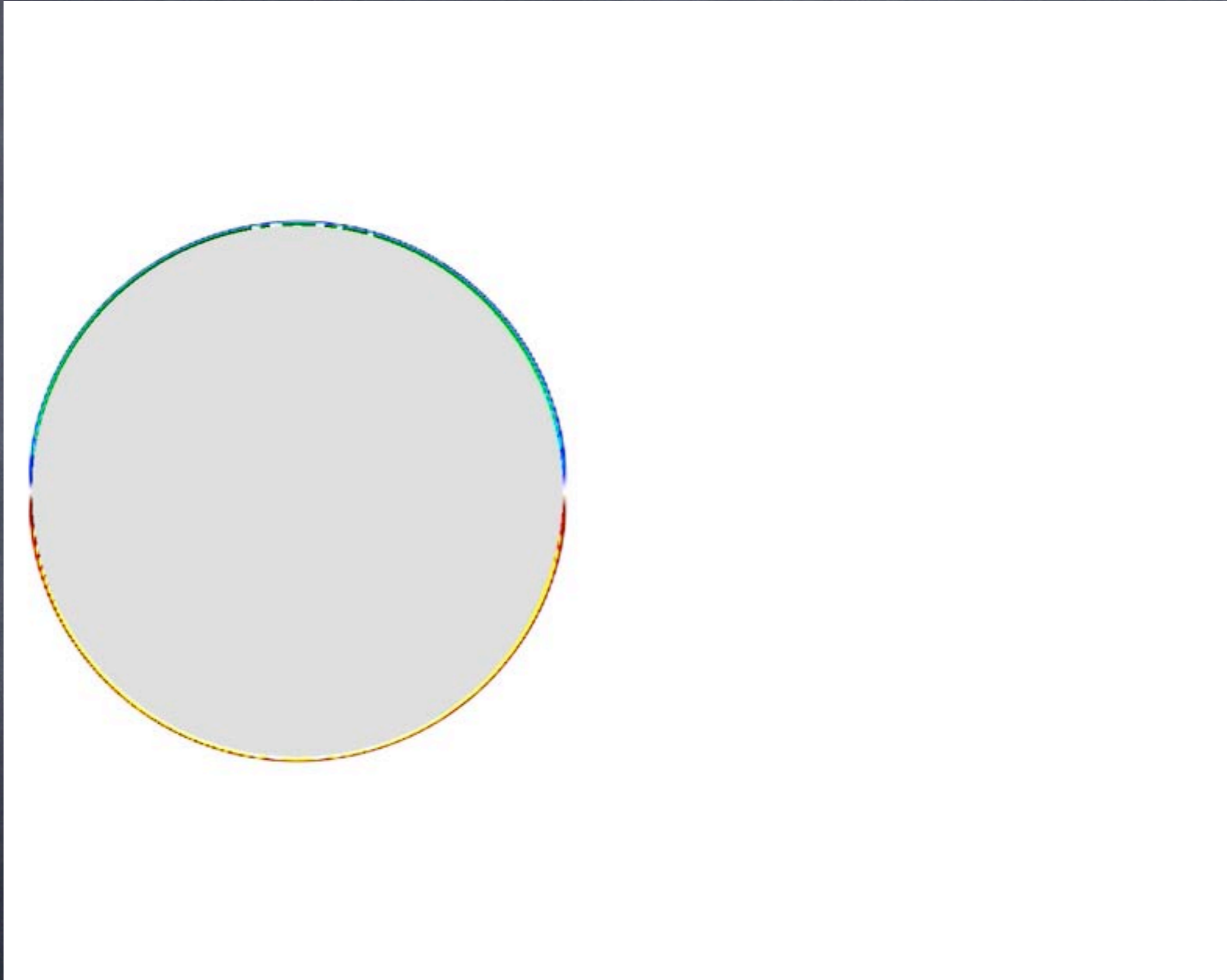
step 1 : ADVECT : Particles

step 2 : REMESH : Particles to Mesh nodes

step 3 : SOLVE : field equations / Derivatives on
Mesh

step 4 : RESAMPLE : Mesh Nodes BECOME Particles

Particle Methods are **adaptive** yet **Inefficient**



Koumoutsakos and Leonard, JFM, 1994

Particles and Multiple Scales/Physics

Wavelet - Particle Method

Keypoints: Wavelets guide particle refinement.
Lagrangian convection of small scales

Multi-Particle Methods

Keypoints: Coupling Discrete and Smooth Particle Methods
Interface of different physics and numerics

While particles are on grid locations

Wavelet-particle method

mollification kernel \longleftrightarrow basis/scaling function

Multiresolution analysis (MRA) $\{\mathcal{V}^l\}_{l=0}^L$ of particle quantities

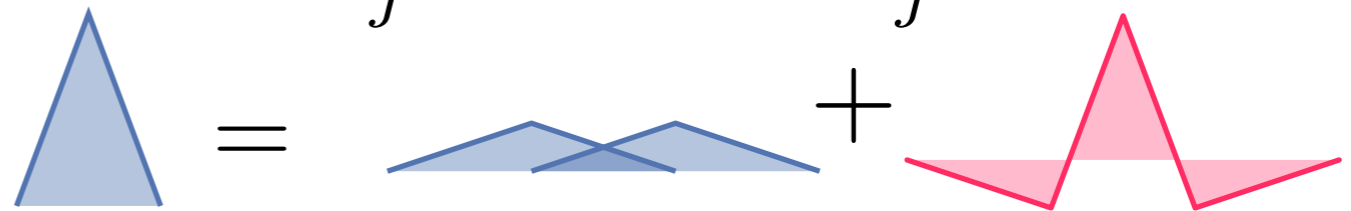
Refineable kernels
as basis functions of \mathcal{V}^l

$$\zeta_k^l = \sum_j h_{j,k}^l \zeta_j^{l+1}$$



Wavelets as basis functions of the
complements \mathcal{W}^l

$$\zeta_k^{l+1} = \sum_j \tilde{h}_{j,k}^l \zeta_j^l + \sum_j \tilde{g}_{j,k}^l \psi_j^l$$

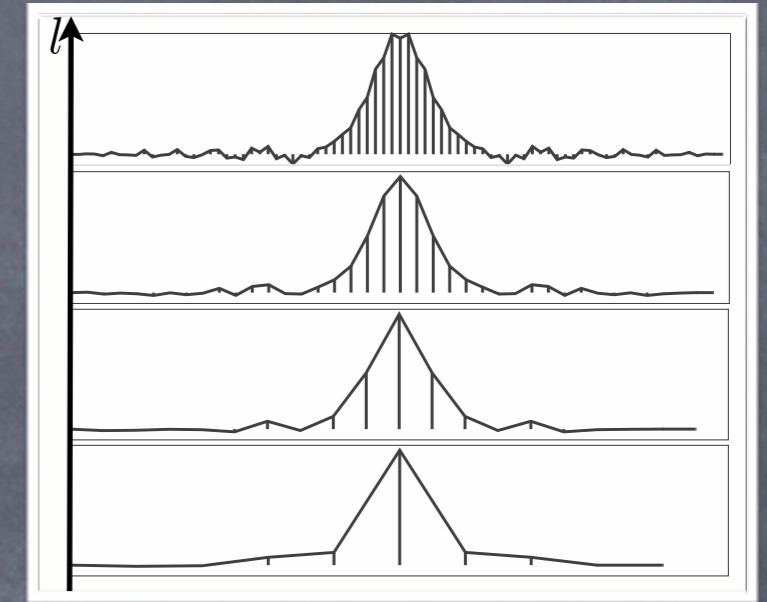


Multiresolution function representation:

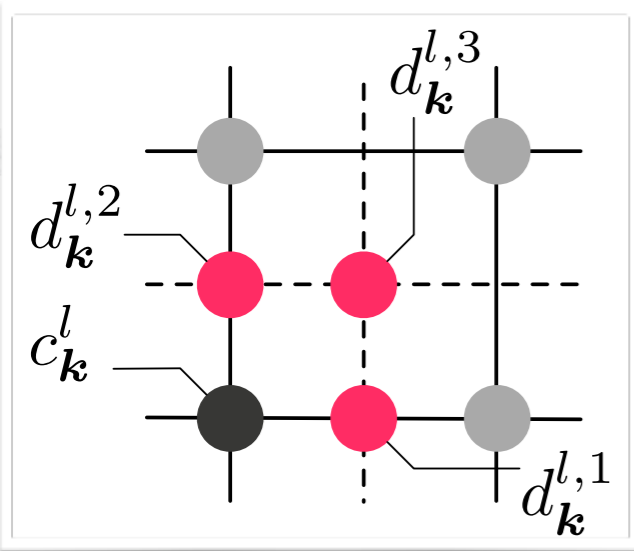
Analysis (collocation): $d_k^l \sim | \text{fine} - \text{Prediction}(\text{coarse}) |$

$$q^L = \sum_k c_k^0 \zeta_k^0 + \sum_{l < L} \sum_k d_k^l \psi_k^l$$

GROUND LEVEL
WAVELETS
DETAIL COEFFICIENTS



Each wavelet is associated with a specific grid point/particle (2D)



Compression/Adaptation:

Discard insignificant detail coefficients: $|d_k^{l,m}| < \epsilon$

Compressed → Adapted grid

$$\|q^L - q_{\geq}^L\| < \epsilon$$

Remeshing + MultiResolution Analysis

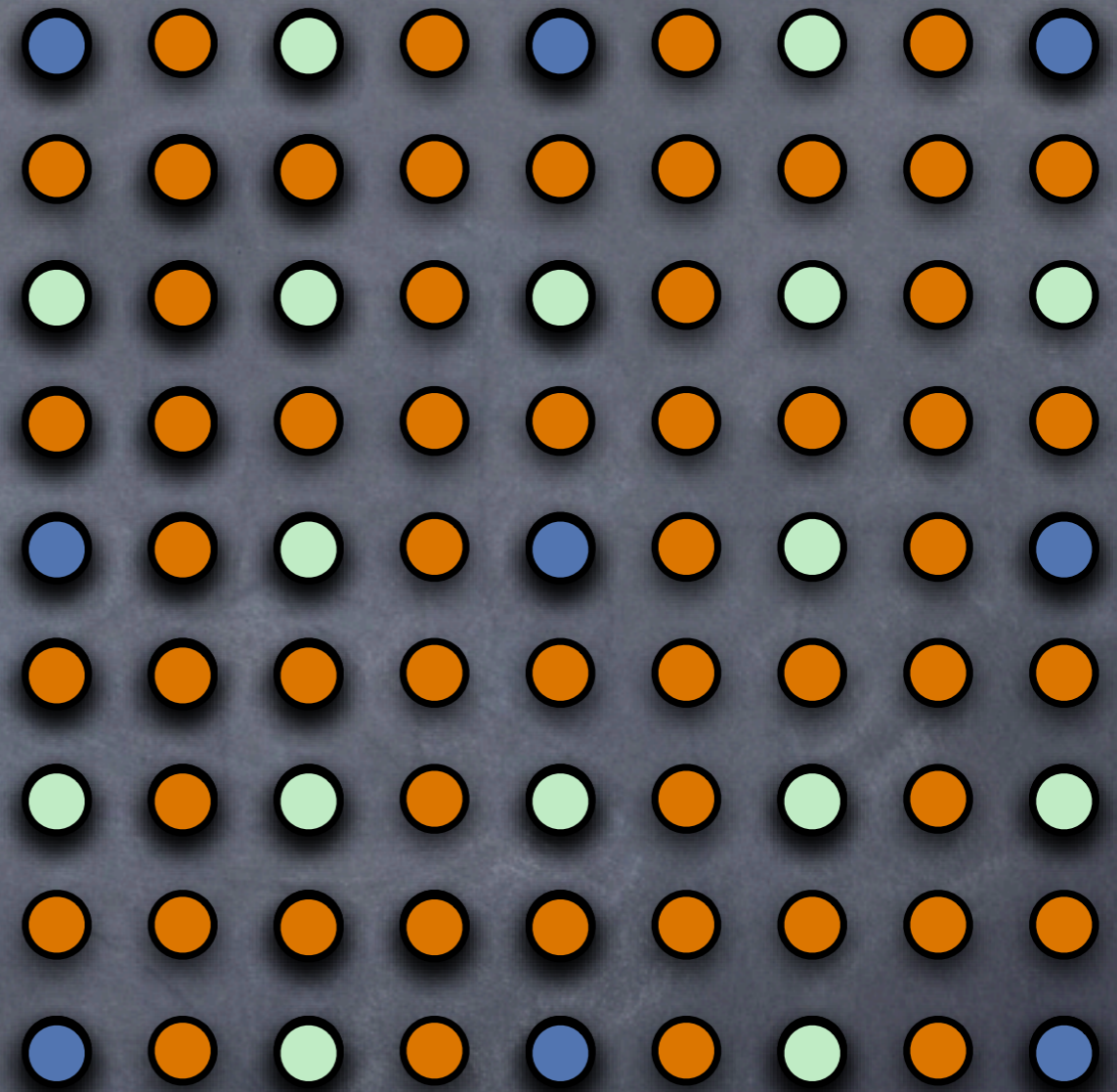
1. Remesh
2. Wavelets- Compress/Adapt
3. Convect
4. Wavelets Reconstruct
5. GOTO 1

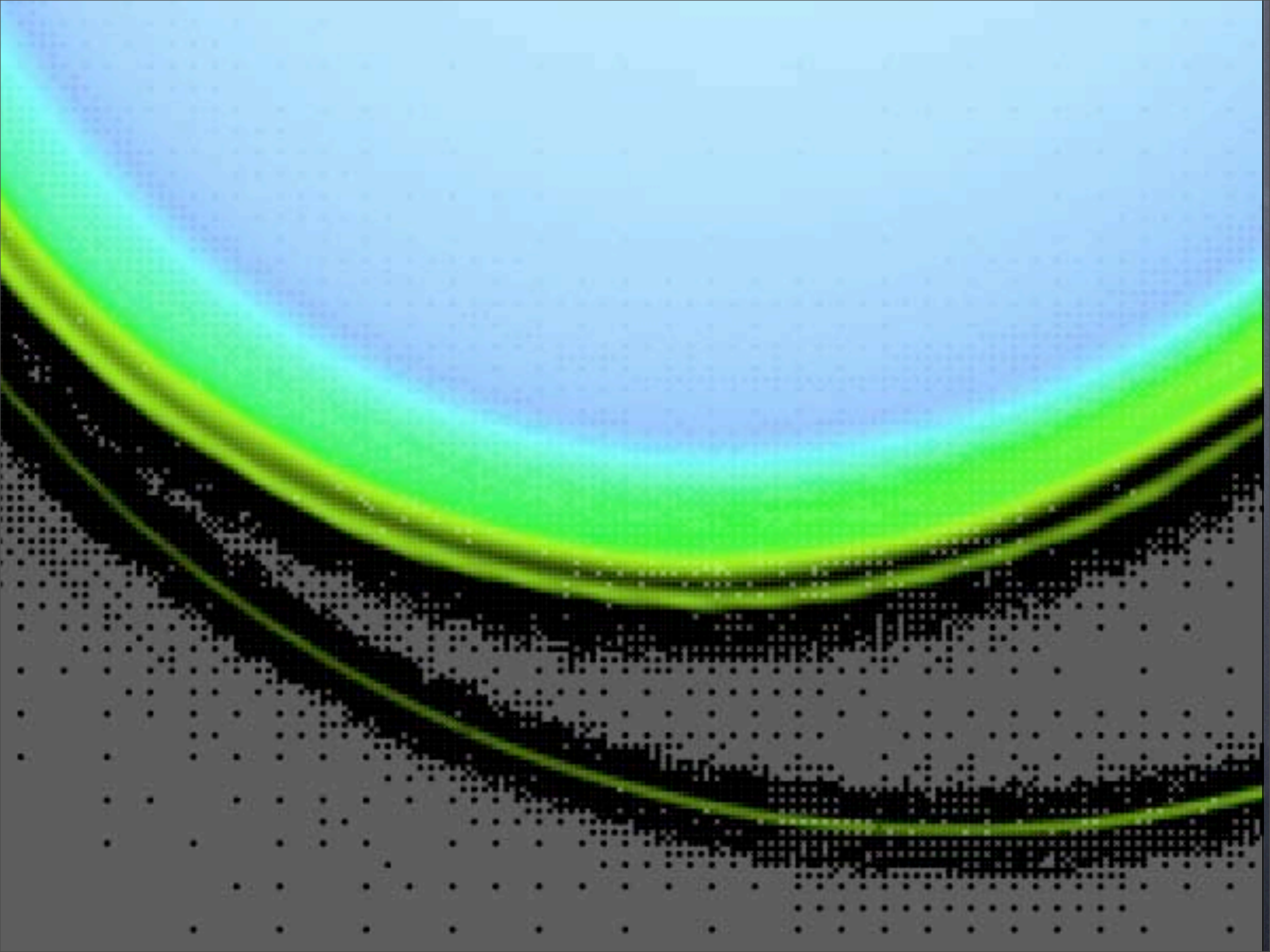
$$q^L = \sum_k c_k^0 \zeta_k^0 + \sum_{l < L} \sum_k d_k^l \psi_k^l$$

“ground” level

detail
coefficients

wavelets





Wavelet - Particle Level sets

$$\frac{\partial \Phi}{\partial t} + \mathbf{u} \cdot \nabla \Phi = 0$$

$$\mathbf{u} = \mathbf{n} \nabla \cdot \mathbf{n}$$

$$\Gamma(t) = \{ \mathbf{x} \in \Omega \mid \phi(\mathbf{x}, t) = 0 \}$$

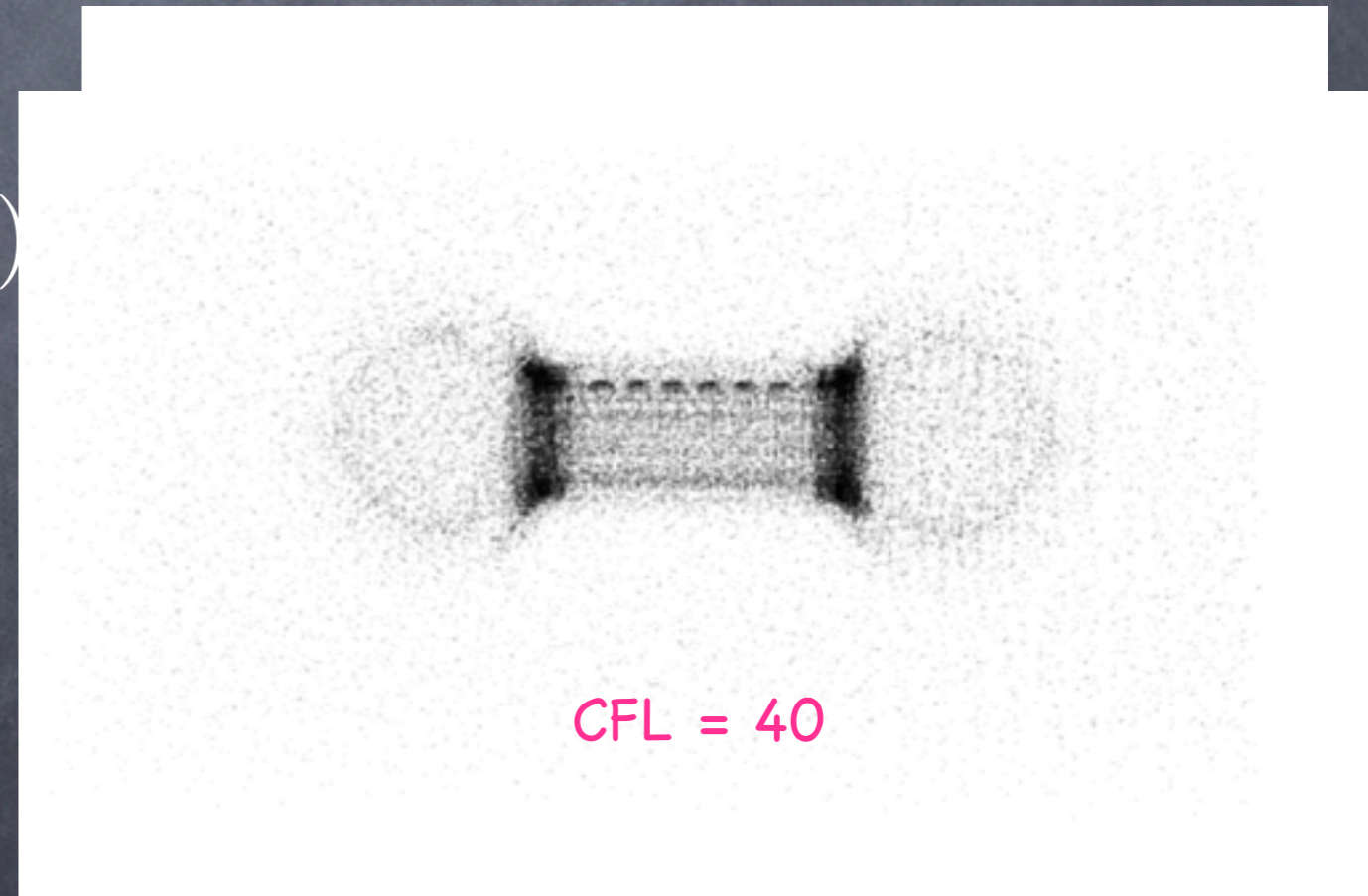
$$|\nabla \phi| = 1$$



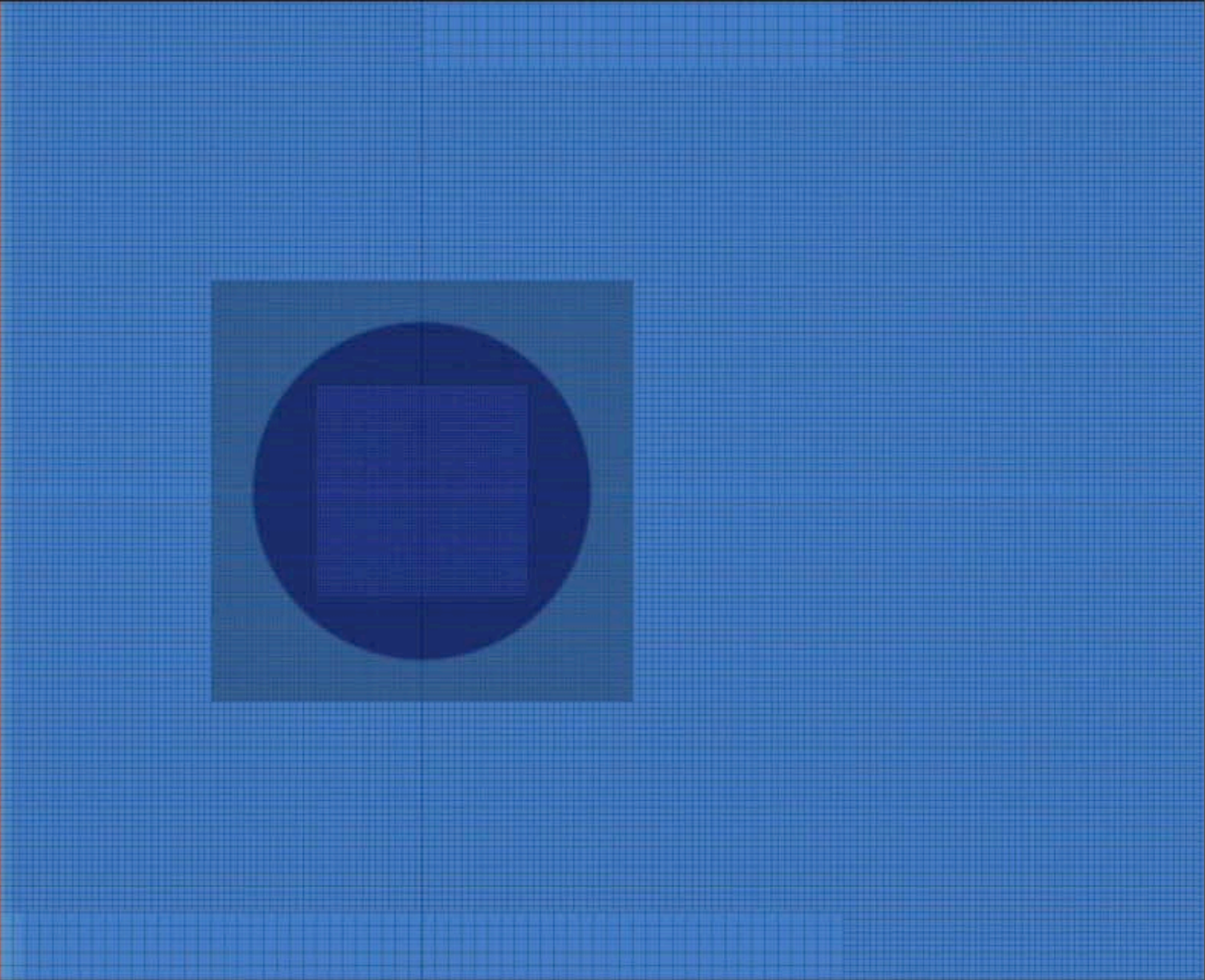
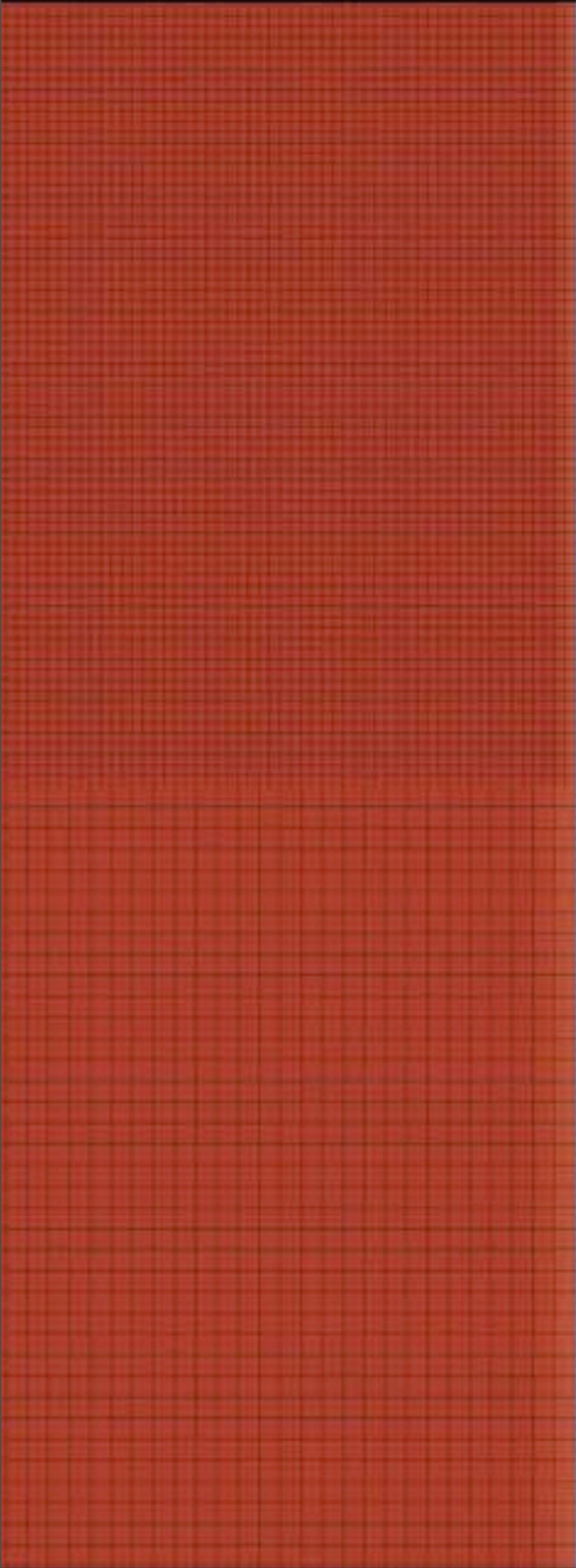
Solve with particles:

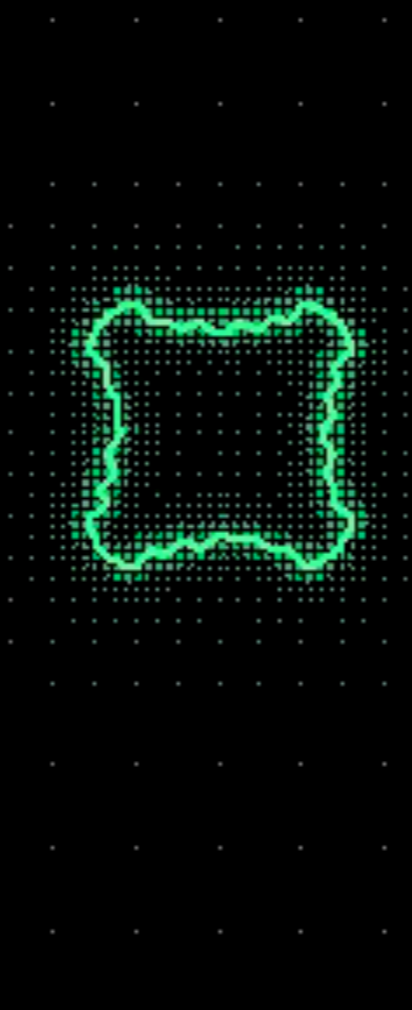
$$\Phi_\epsilon^h = \sum_{p=1}^{N_p} h_p^d \Phi_p(t) \zeta_\epsilon(x - x_p(t))$$

$$\frac{dx_p}{dt} = \mathbf{u}_p \quad \frac{d\Phi_p}{dt} = 0$$

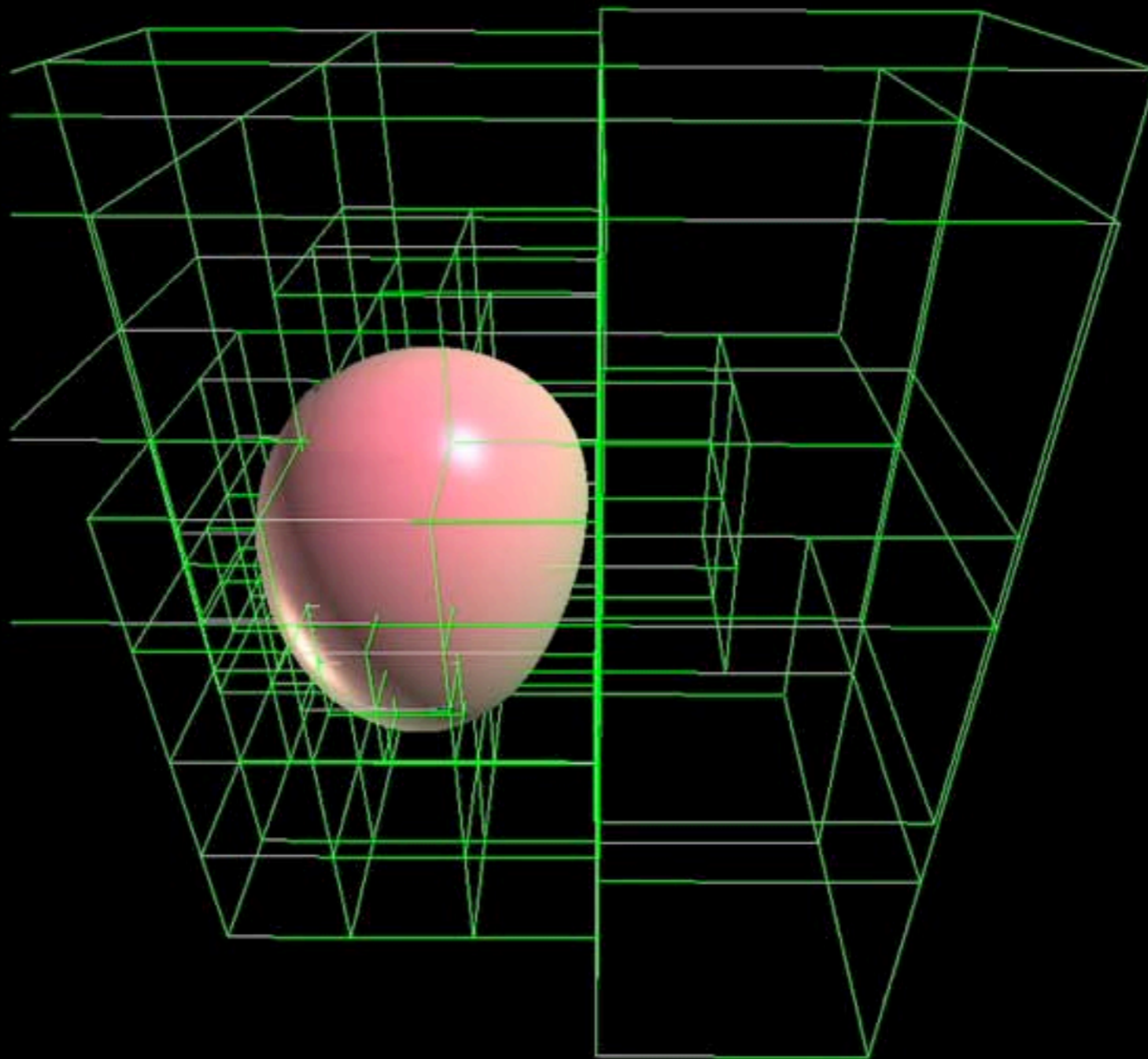


CFL = 40

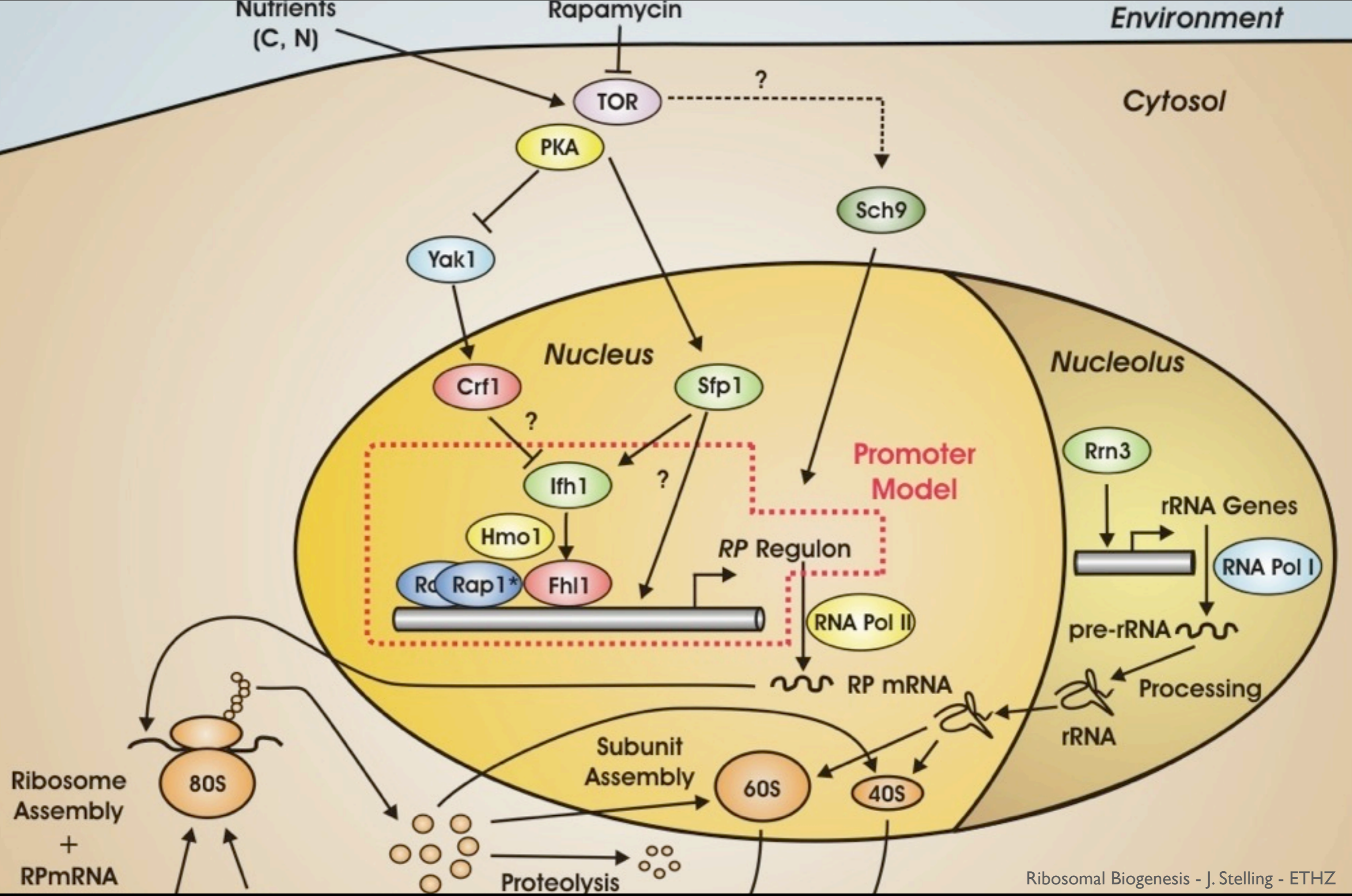




Wavelet Particle Level sets - 3D



Key Issues : Data Structures & Software Engineering



Ribosomal Biogenesis - J. Stelling - ETHZ

Stochastic Simulation Algorithms

- For **M reactions**, time until **any** reaction

$$\tau \sim \mathcal{E}(1/a_0) \quad a_0 = \sum_{j=1}^M a_j$$

- Reaction **index**: point-wise distribution $p(j = l) = \frac{a_l}{a_0}$

- One timestep:
 - Sample τ
 - Sample the index j
 - Update the $X_i, t=t+\tau$

exact BUT slow

- The SSA simulates every reaction event !

- **τ -leaping** : several reaction events over one time step,
- Assumption : **reaction propensities a_i remain essentially constant** over τ , in spite of several firings
- Over this given τ , the number of reaction firings K_j^P is governed by a Poisson distribution

$$K_j^P \sim \mathcal{P}(a_j \tau)$$
$$\mathbf{X}(t + \tau) = \mathbf{X}(t) + \sum_{j=1}^M K_j^P \boldsymbol{\nu}_j.$$

Cost ~ M Poisson samplings

τ leaping : **Fast** BUT **Inexact**

- τ leaping : Can generate **negative populations**
- **Binomial τ leaping** : Approximate the unbounded Poisson distributions with Binomial ones Tian & Burrage,
J. Chem. Phys. 2004 Chatterjee et al.,
J. Chem. Phys. 2005
- Modified τ leaping Cao et al.,
J. Chem. Phys. 2005
 - Critical reactions, i.e. those likely to drive some populations negative, handled by SSA
 - Other reactions advanced by τ leaping

R-leaping : Accelerate SSA by reaction leaps

Leaps : prescribe number of firings L across all channels

- Time increment τ_L is Gamma-distributed $\tau_L \sim \Gamma(L, 1/a_0(\mathbf{x}))$
- In this interval we will have K_m firings of channel R_m
- with :
$$\sum_{m=1}^M K_m = L$$
- In R-leaping, (as in SSA), the index j of every firing obeys a point-wise distribution
$$P(j = l) = \frac{a_l(\mathbf{x})}{a_0(\mathbf{x})} \text{ for } l = 1, \dots, M.$$

Auger, Chatelain, Koumoutsakos, **R-leaping: Accelerating the stochastic simulation algorithm by reaction leaps.**
J. Chem. Phys. , 125, 84103, 2006

- Define L

$$\tau_L \sim \Gamma(L, 1/a_0(\mathbf{x}))$$

- Sample the index j

$$P(j = l) = \frac{a_l(\mathbf{x})}{a_0(\mathbf{x})} \quad \text{for } l = 1, \dots, L.$$

- Number of reactions for channel m

$$K_m = \sum_{l=1}^L \delta_{l,m}$$

- Update species and time :

$$\mathbf{X}(t + \tau_L) = \mathbf{X}(t) + \sum_{j=1}^M K_j \boldsymbol{\nu}_j$$

R-leaping : Accelerate SSA by reaction leaps

- L firings distributed across M reaction channels
 - In τ leaping: K_j^P are independent Poisson variables.
 - In R-leaping, K_j are not independent.
- L as a control parameter
 - System can be brought to a desired state X
 - Time is not a-priori specified
 - New approaches to controlling negative species

R-leaping : How to Sample the the M K_j

R_0 Algorithm

- Pointwise Sampling of L *independent* reaction indices

$$p(j = l) = \frac{a_l}{a_0}$$

- Simple BUT scales with L - close to the work load of SSA!

Reaction index \rightarrow

	1	2	3	...	M
1	x				
2			x		
3					x
...			x		
L	x				
K	2		2		1

Firing \downarrow

Ro-sampling scales with L and, in particular when compared with τ -leaping that scales with M , the method is inefficient for large leap sizes, $L \gg M$.

R-Leaping Theorem

The distribution of K_1 is a binomial distribution :

$$\mathcal{B}(L, a_1(\mathbf{x})/a_0(\mathbf{x}))$$

and for every $m \in \{2, \dots, M\}$ the conditional distribution of K_m

given the event $\{(K_1, \dots, K_{m-1}) = (k_1, \dots, k_{m-1})\}$ is

$$K_m \sim \mathcal{B} \left(L - \sum_{i=1}^{m-1} k_i, \frac{a_m(\mathbf{x})}{a_0(\mathbf{x}) - \sum_{i=1}^{m-1} a_i(\mathbf{x})} \right)$$

This result is invariant under any permutation of the indices

R-leaping : How to Sample the the M K_j

R_0 Algorithm

- Pointwise Sampling of L *independent* reaction indices

$$p(j = l) = \frac{a_l}{a_0}$$

- Simple BUT scales with L - close to the work load of SSA!

Reaction index \rightarrow

	1	2	3	...	M
1	x				
2			x		
3					x
...			x		
L	x				
K	2		2		1

Firing \downarrow

Ro-sampling scales with L and, in particular when compared with τ -leaping that scales with M , the method is inefficient for large leap sizes, $L \gg M$.

R_1 Algorithm

- Sampling M *correlated* binomial variables

$$\mathcal{B}(L, a_j/a_0)$$

- Create correlations with conditional distributions

$$\text{If } K_i = k_i, \forall i < m,$$

$$K_m \sim \mathcal{B}\left(L - \sum_{i=1}^{m-1} k_i, \frac{a_m}{a_0 - \sum_{i=1}^{m-1} a_i}\right)$$

Reaction index \rightarrow

	1	2	3	...	M
1	x				
2			x		
3					x
...			x		
L	x				
K	2		2		1

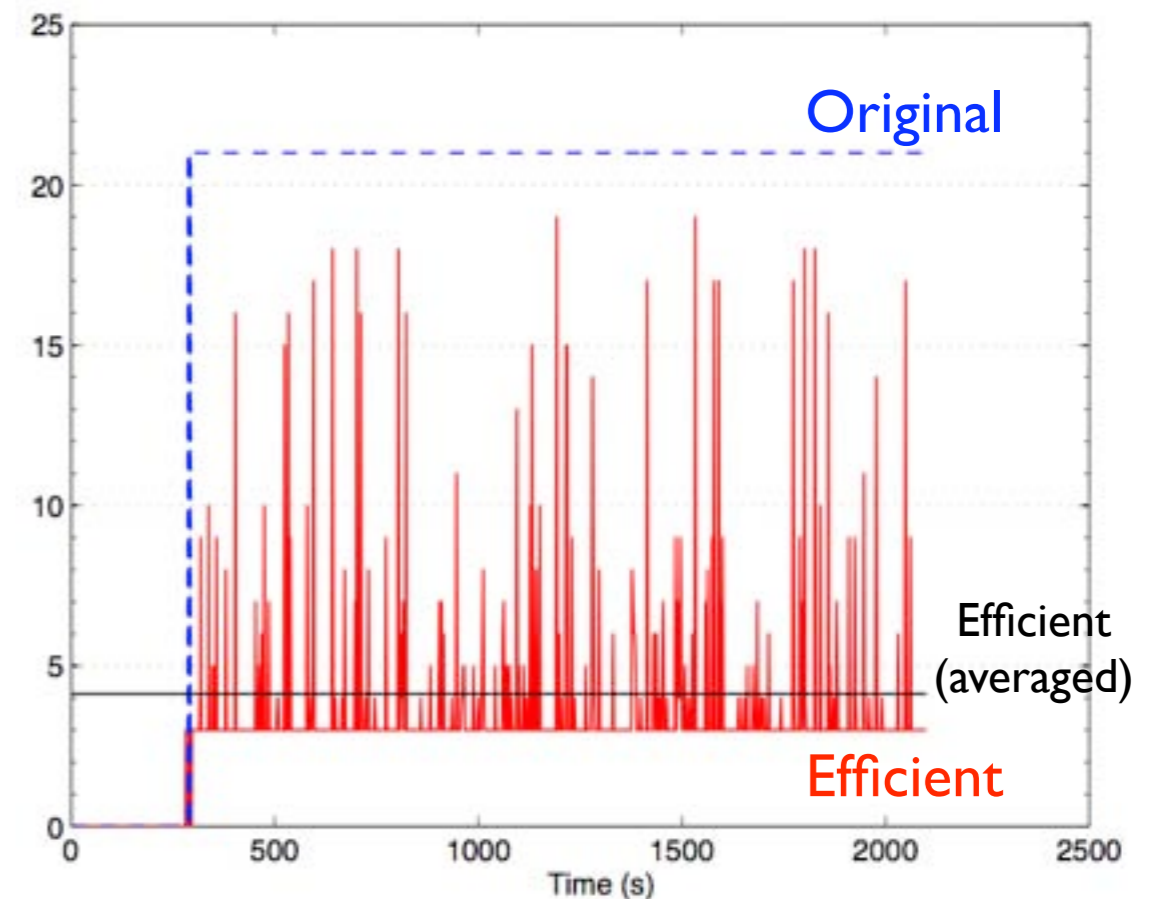
Firing \downarrow

R-leaping : Efficient Sampling / **Sorting**

- Sampling the $M K_j$ efficiently (**SORT the reactions**)
 - M can be large ($\sim 10^2$) for bio-chemical systems!
 - Efficient sampling effectively loops over a fraction of M .

- The larger the system, the bigger the payoff.
- The more disparate the reaction rates are, the smaller the fraction.
- Price to pay: carry out re-ordering often enough (cheap!)

Number of binomial samples per time step
LacYLacZ activities in E. Coli., $M=22$



Stochastic simulation: R-leaping

- **Controlling the leap approximation**
 - All three methods of τ leaping are transposable to R-leaping
 - Absolute change of a_j
 - Relative change of a_j
 - Relative change of a_j but efficiently through the relative changes in populations

- **LacZ/LacY genes expression and enzymatic/transport activities of LacZ/LacY proteins in E. Coli**

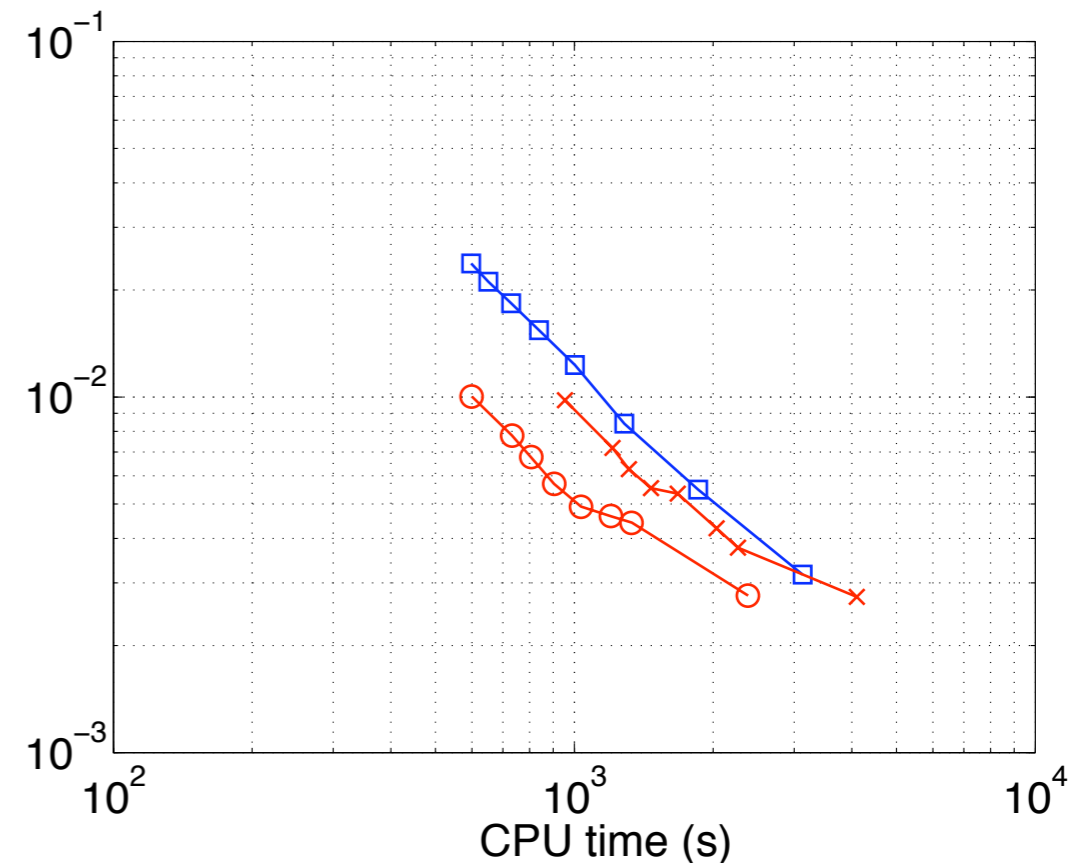
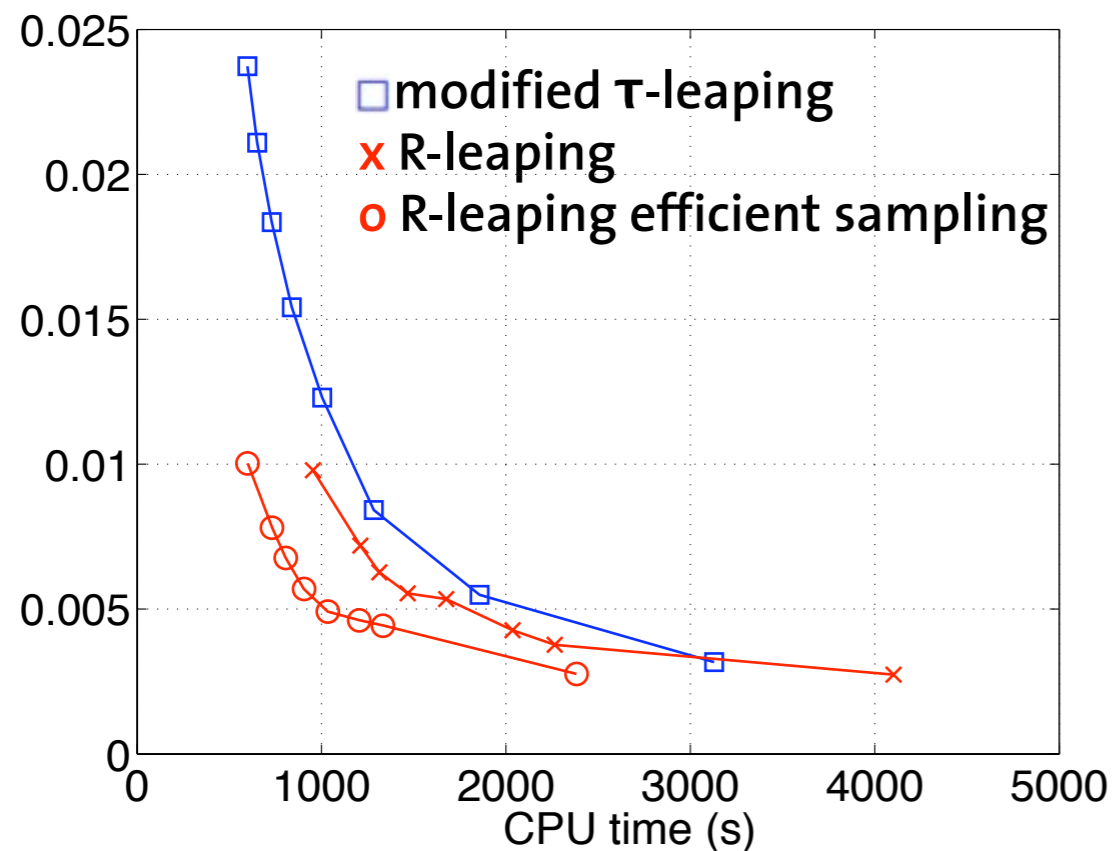
Kierzek,
Bioinformatics 2002

- Moderately large system ($M = 22$)
- Disparate rates
- Scarce reactants and negative species

	Reaction Channel	Reaction rate
R_1	$\text{PLac} + \text{RNAP} \rightarrow \text{PLacRNAP}$	0.17
R_2	$\text{PLacRNAP} \rightarrow \text{PLac} + \text{RNAP}$	10
R_3	$\text{PLacRNAP} \rightarrow \text{TrLacZ1}$	1
R_4	$\text{TrLacZ1} \rightarrow \text{RbsLacZ} + \text{PLac} + \text{TrLacZ2}$	1
R_5	$\text{TrLacZ2} \rightarrow \text{TrLacY2}$	0.015
R_6	$\text{TrLacY1} \rightarrow \text{RbsLacY} + \text{TrLacY2}$	1
R_7	$\text{TrLacY2} \rightarrow \text{RNAP}$	0.36
R_8	$\text{Ribosome} + \text{RbsLacZ} \rightarrow \text{RbsRibosomeLacZ}$	0.17
R_9	$\text{Ribosome} + \text{RbsLacY} \rightarrow \text{RbsRibosomeLacY}$	0.17
R_{10}	$\text{RbsRibosomeLacZ} \rightarrow \text{Ribosome} + \text{RbsLacZ}$	0.45
R_{11}	$\text{RbsRibosomeLacY} \rightarrow \text{Ribosome} + \text{RbsLacY}$	0.45
R_{12}	$\text{RbsRibosomeLacZ} \rightarrow \text{TrRbsLacZ} + \text{RbsLacZ}$	0.4
R_{13}	$\text{RbsRibosomeLacY} \rightarrow \text{TrRbsLacY} + \text{RbsLacY}$	0.4
R_{14}	$\text{TrRbsLacZ} \rightarrow \text{LacZ}$	0.015
R_{15}	$\text{TrRbsLacY} \rightarrow \text{LacY}$	0.036
R_{16}	$\text{LacZ} \rightarrow \text{dgrLacZ}$	6.42×10^{-5}
R_{17}	$\text{LacY} \rightarrow \text{dgrLacY}$	6.42×10^{-5}
R_{18}	$\text{RbsLacZ} \rightarrow \text{dgrRbsLacZ}$	0.3
R_{19}	$\text{RbsLacY} \rightarrow \text{dgrRbsLacY}$	0.3
R_{20}	$\text{LacZ} + \text{lactose} \rightarrow \text{LacZlactose}$	9.52×10^{-5}
R_{21}	$\text{LacZlactose} \rightarrow \text{product} + \text{LacZ}$	431
R_{22}	$\text{LacY} \rightarrow \text{lactose} + \text{LacY}$	14

Results

- **LacZ/LacY genes expression and enzymatic/transport activities of LacZ/LacY proteins in E. Coli**
- Histogram errors vs CPU time

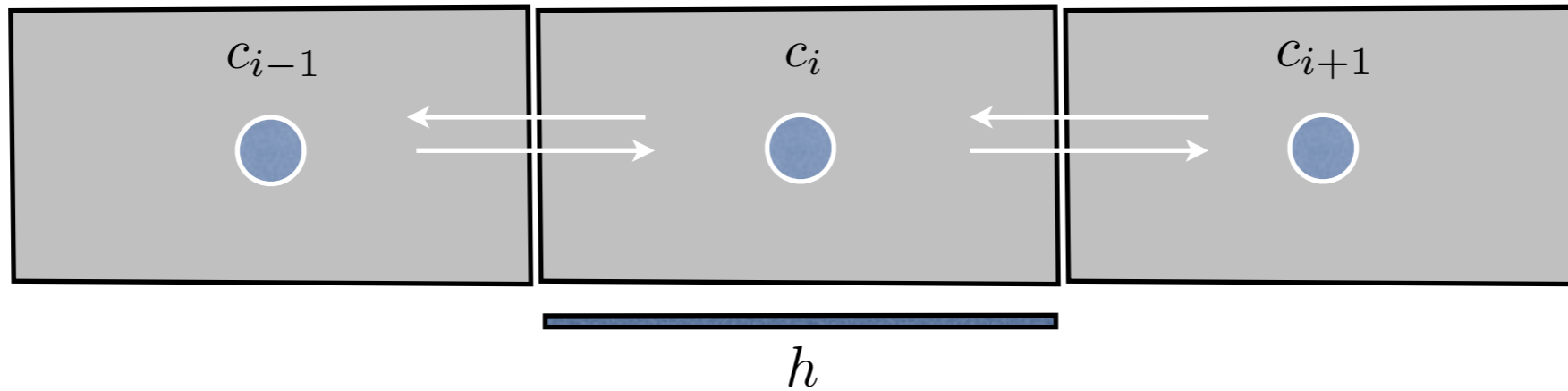


- Efficient sampling offers factor 2 in speed w.r.t. modified τ -leaping!

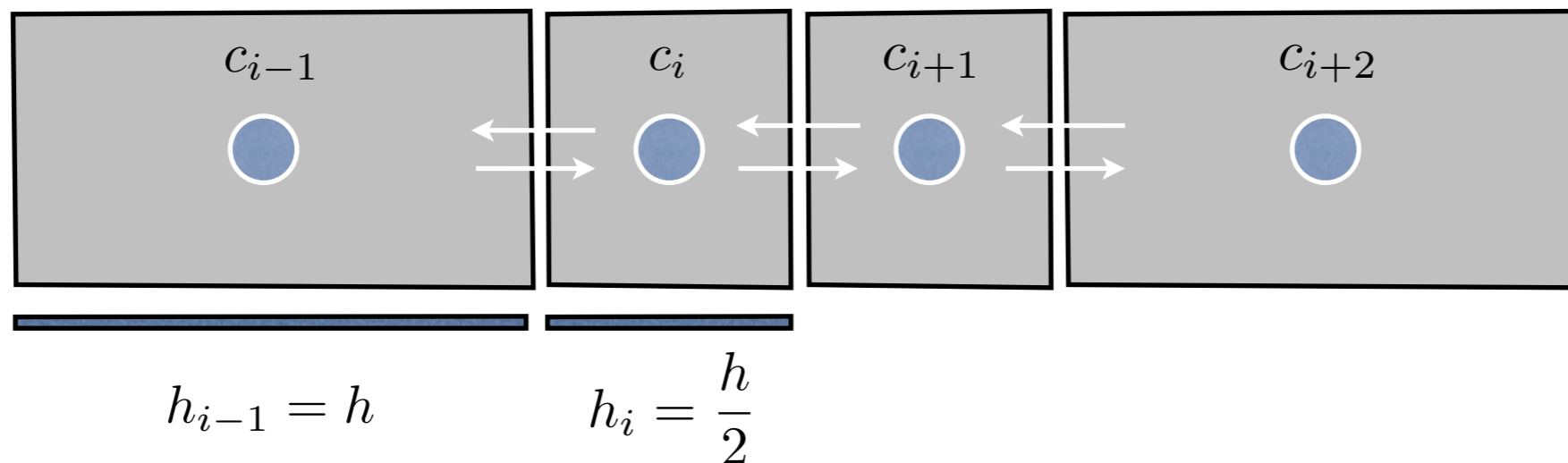
R-LEAP for Stochastic Diffusion on Non-uniform Discretizations

Diffusion events between cells, i.e. propensity for diffusion from cell i to cell j : $a_{i,j}(\mathbf{x}) = X_i \cdot k_{i,j}$

Uniform Cells: $k_{i,j} = \frac{D}{h^2}$



Non-uniform Cells: $k_{i,j} = ?$



Stochastic Diffusion on Non-Uniform Mesh Using a Finite Volume [1]

Continuum

$$\frac{\partial u}{\partial t} = -\nabla \cdot J$$

$$J = -D(x)\nabla u$$

Diffusion Process

$$\frac{dU_i}{dt} = -(k_{i,i+1} + k_{i,i-1})U_i + k_{i+1,i}U_{i+1} + k_{i-1,i}U_{i-1}$$

$$\frac{\partial U_i}{\partial t} = -\int_i \nabla \cdot J dx$$

Using the Divergence Theorem

$$\frac{\partial U_i}{\partial t} = J(c_i - \frac{h_i}{2}) - J(c_i + \frac{h_i}{2})$$

Approximating the Gradient in Fick's Law

$$\nabla u(c_i - \frac{h_i}{2}) \approx \frac{u(c_i) - u(c_{i-1})}{c_i - c_{i-1}} = \frac{1}{c_i - c_{i-1}} \left(\frac{U_i}{h_i} - \frac{U_{i-1}}{h_{i-1}} \right)$$

$$\frac{dU_i}{dt} = -\left(\frac{D_{i,i+1}}{h_i|c_i - c_{i+1}|} + \frac{D_{i,i-1}}{h_i|c_i - c_{i-1}|} \right) U_i + \left(\frac{D_{i+1,i}}{h_{i+1}|c_i - c_{i+1}|} \right) U_{i+1} + \left(\frac{D_{i-1,i}}{h_{i-1}|c_i - c_{i-1}|} \right) U_{i-1}$$

Reaction Rates for Diffusion Events:

$$k_{i,j} = \begin{cases} \frac{D_{i,j}}{h_i|c_i - c_j|} & \text{if } |i - j| = 1 \\ 0 & \text{otherwise} \end{cases}$$

[1] D. Bernstein. Simulating mesoscopic reaction-diffusion systems using the gillespie algorithm. *Phys. Rev. E*, 2005.

SSA using AMR

- Inhomogeneous volume
- random collisions and reactions in each volume element
- different species in each volume element
- Validity of spatial discretization lies in the assumption that:

$$\frac{\tau_R}{\tau_D} \gg 1$$

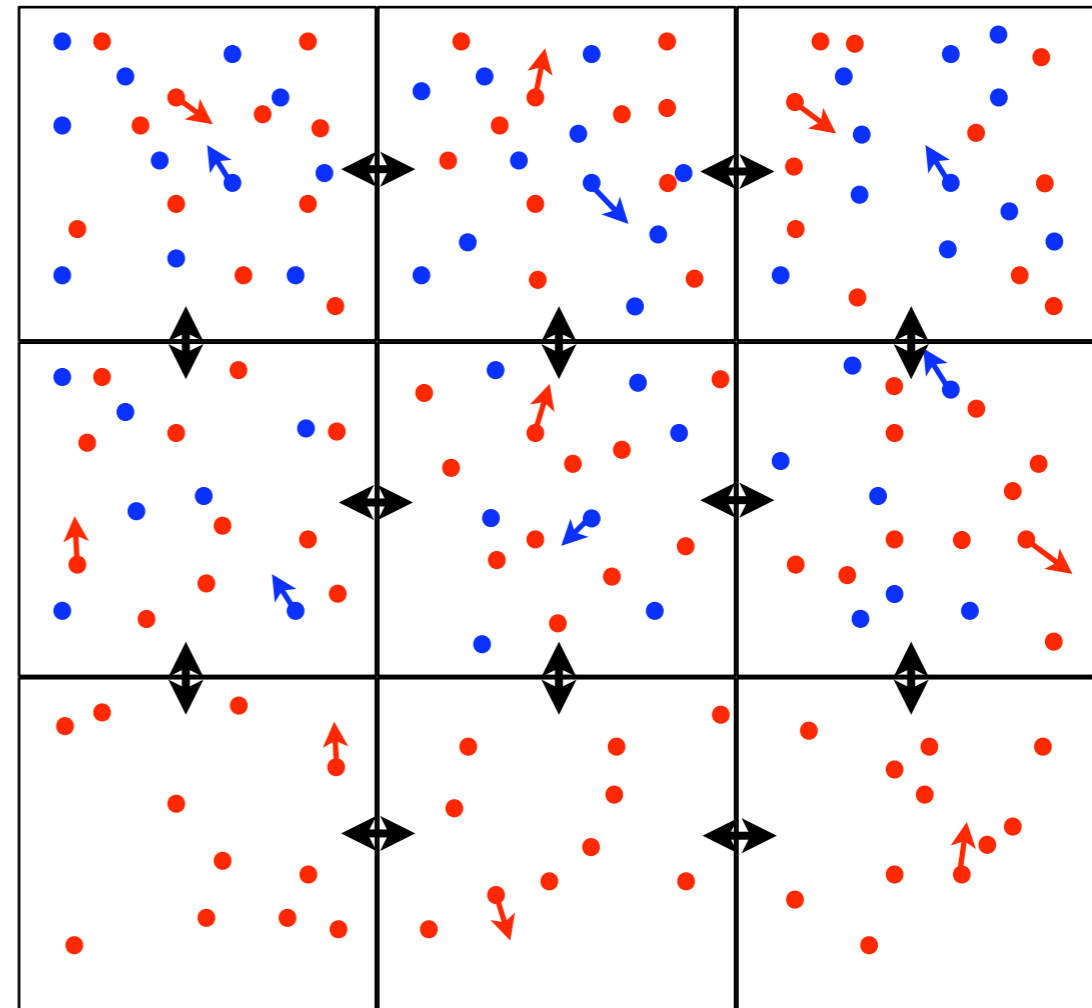
Kuramoto,
Prog. Theor. Phys.
1974

- τ_R is the mean free time with respect to reactive collisions in a volume element and τ_D is the mean time during which a molecule will remain in a volume element.

- For a bimolecular reaction with rate k and diffusion coefficient D , this can be estimated by

$$\frac{\hat{\tau}_R}{\hat{\tau}_D} = \frac{D}{h^2 k}$$

Bayati et al.,
PCCP. 2008



- h must therefore be small for the discretization to be valid

SSA using AMR

- Diffusion in 2-D (3-D similar derivation)

$$u^{(s)} \triangleq u^{(s)}(x, y, t)$$

- concentration of species s

$$\bar{u}_i^{(s)} \triangleq h^{-2} \int_i u_i^{(s)} dV$$

- average concentration of species s in volume element i

$$U_i^{(s)} \triangleq \int_i \bar{u}_i^{(s)} dV = \bar{u}_i^{(s)} h^2$$

- number of molecules

- start with macroscopic equations for diffusion

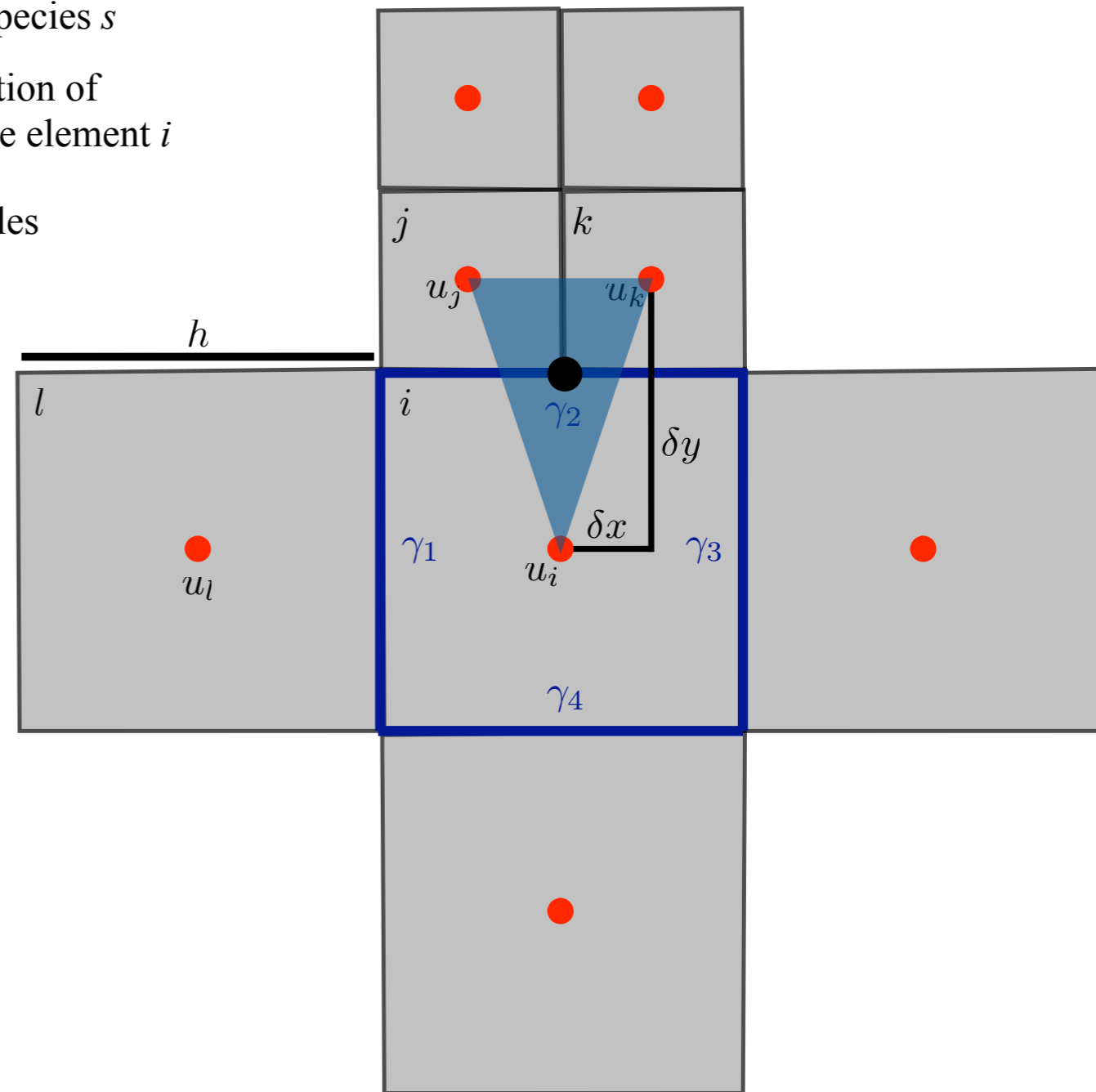
$$\frac{\partial u^{(s)}}{\partial t} = -\nabla \cdot \mathbf{J}$$

$$\mathbf{J} = -D\nabla u^{(s)}$$

- Integrating the conservation equation over a volume element i , applying the divergence theorem on the right-hand-side, and decomposing the surface integral into faces yields:

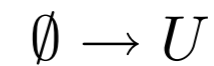
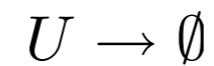
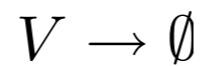
$$\frac{dU_i^{(s)}}{dt} = -\sum_{a=1}^4 \int_{\gamma_a} \mathbf{J} \cdot \mathbf{n} dS$$

Bernstein,
PRE. 2005

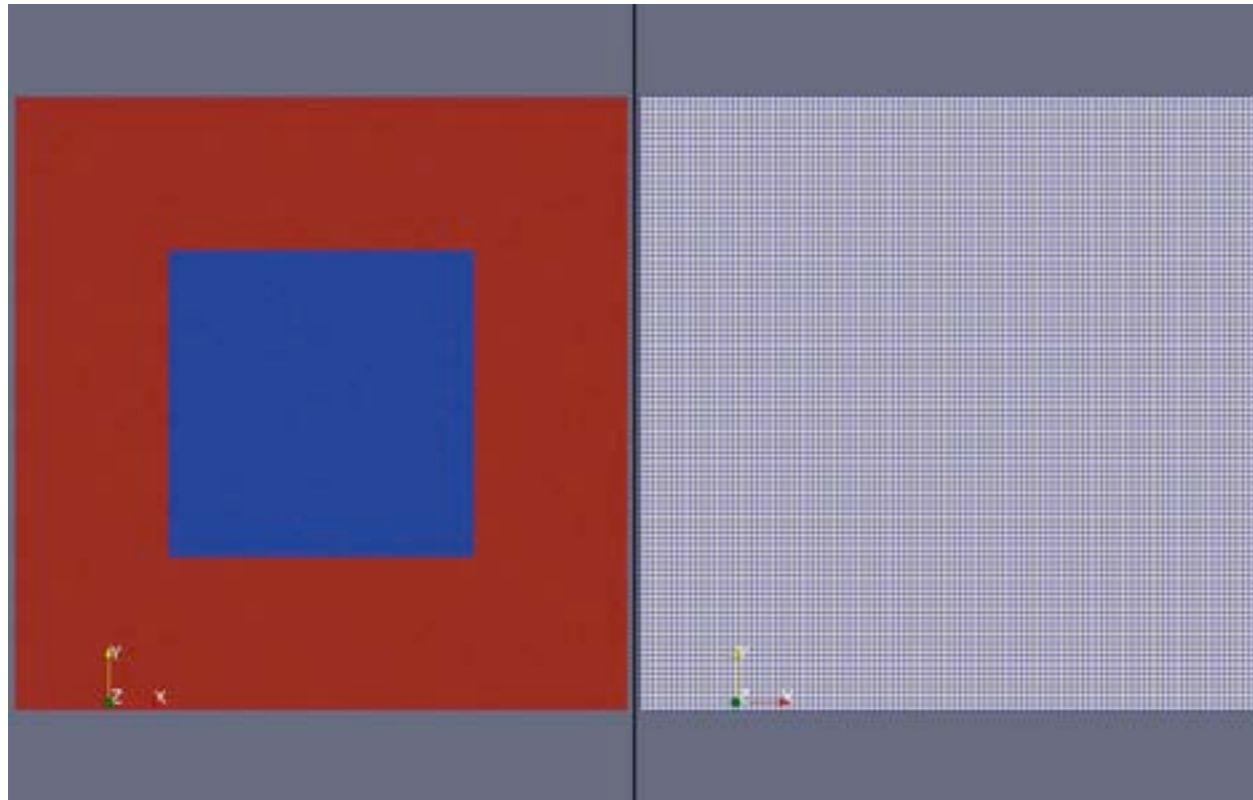


SSA using AMR

- Gray-Scott Reaction-Diffusion System in 2-D



Pearson,
Science. 1993



- Stochastic

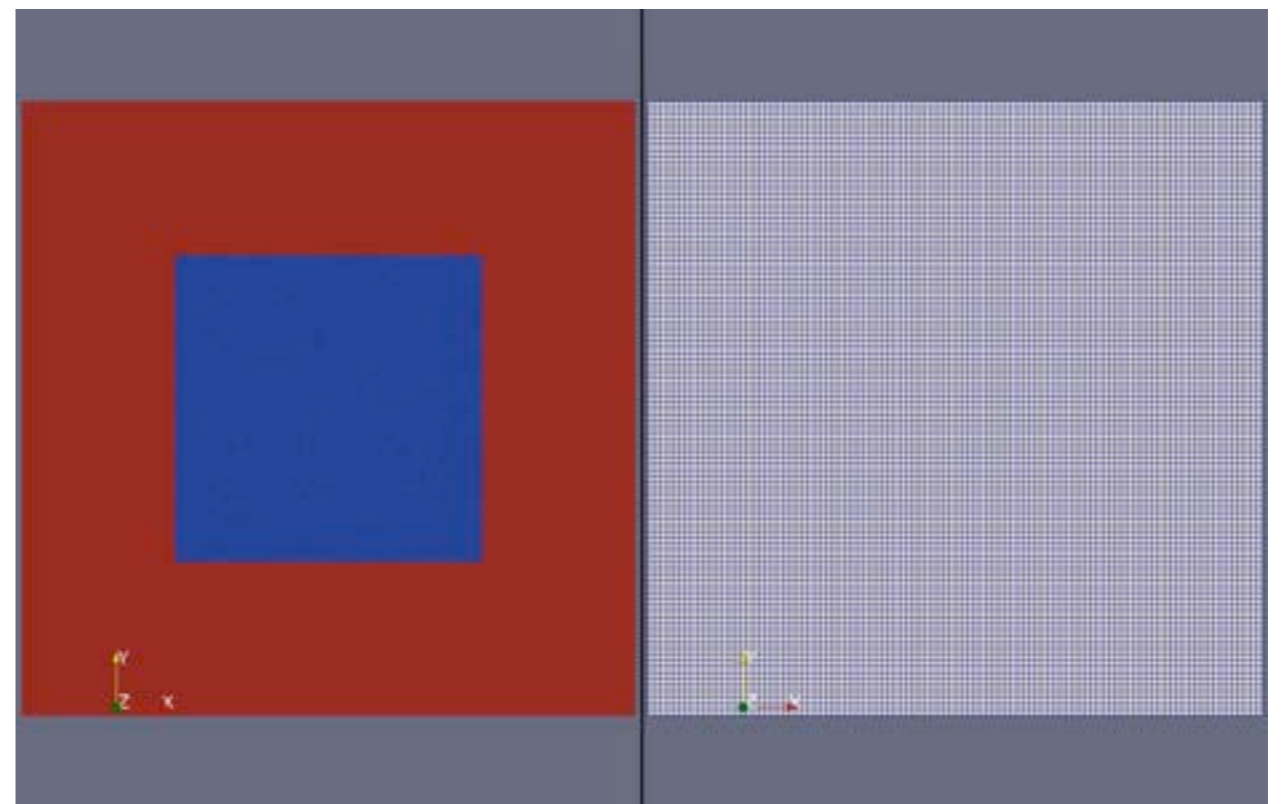
- *Imperfect* refinement criterion
-some fluctuations are tagged
as gradients

$$h_{min} = \frac{1}{400} \quad h_{max} = \frac{1}{100}$$

- Deterministic

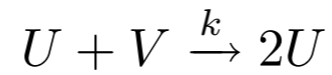
- Gradient-based AMR - finite differences

Henshaw et al.,
J. Comp. Phys.
2008



SSA using AMR

- Fisher-Kolmogorov Reaction-Diffusion System in 2-D

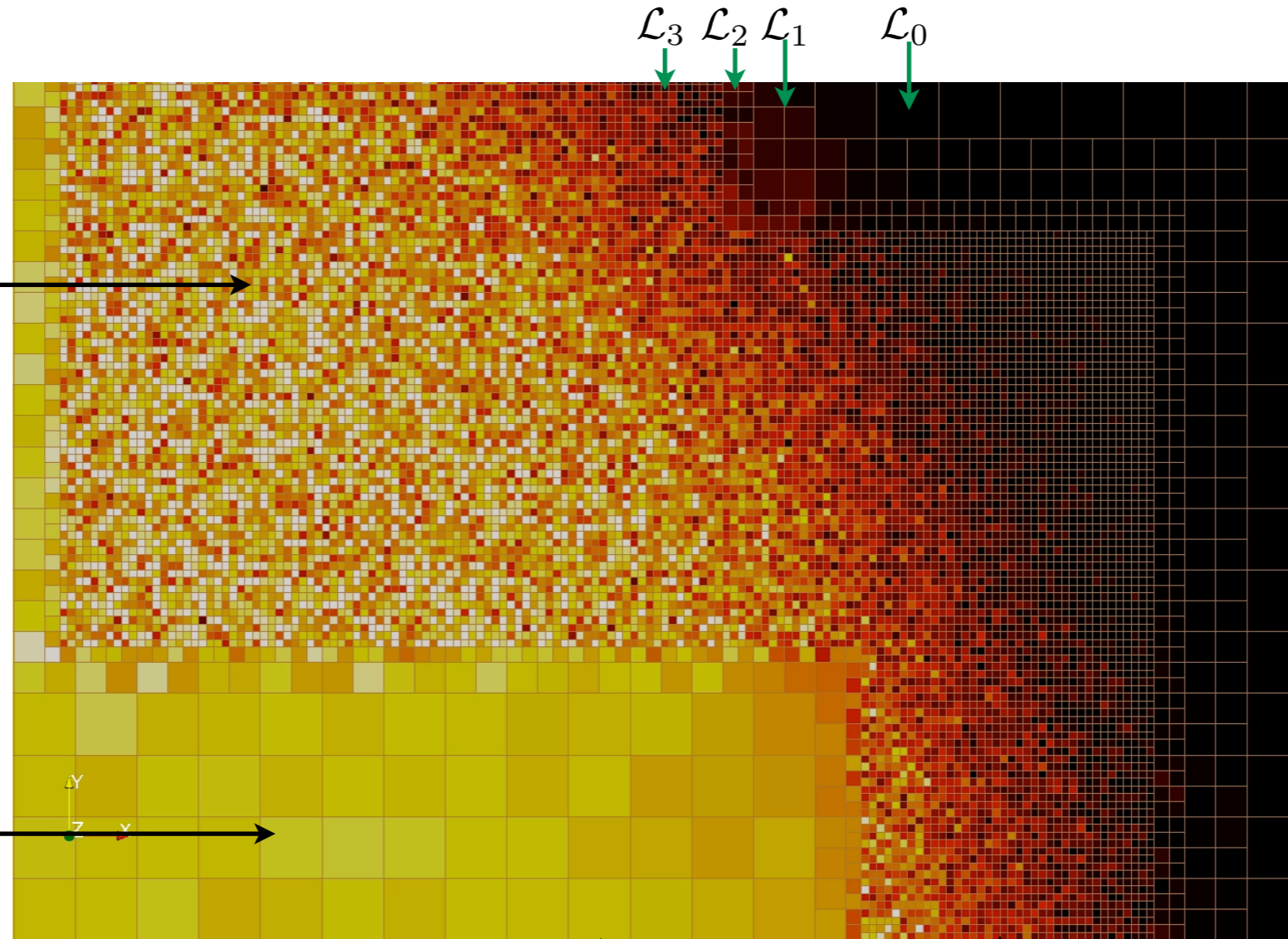


Fisher,
Ann. Eugenics
1937

- Fluctuations are stronger in smaller cells
- Not mesh effects
- $\langle U \rangle = 15$

different physics

- Weak fluctuations in coarse region
- $\langle U \rangle = 960$



concentration, u



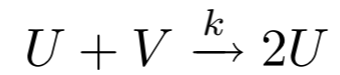
$$h_{max} = \frac{1}{100}$$

$$h_{min} = \frac{1}{800}$$

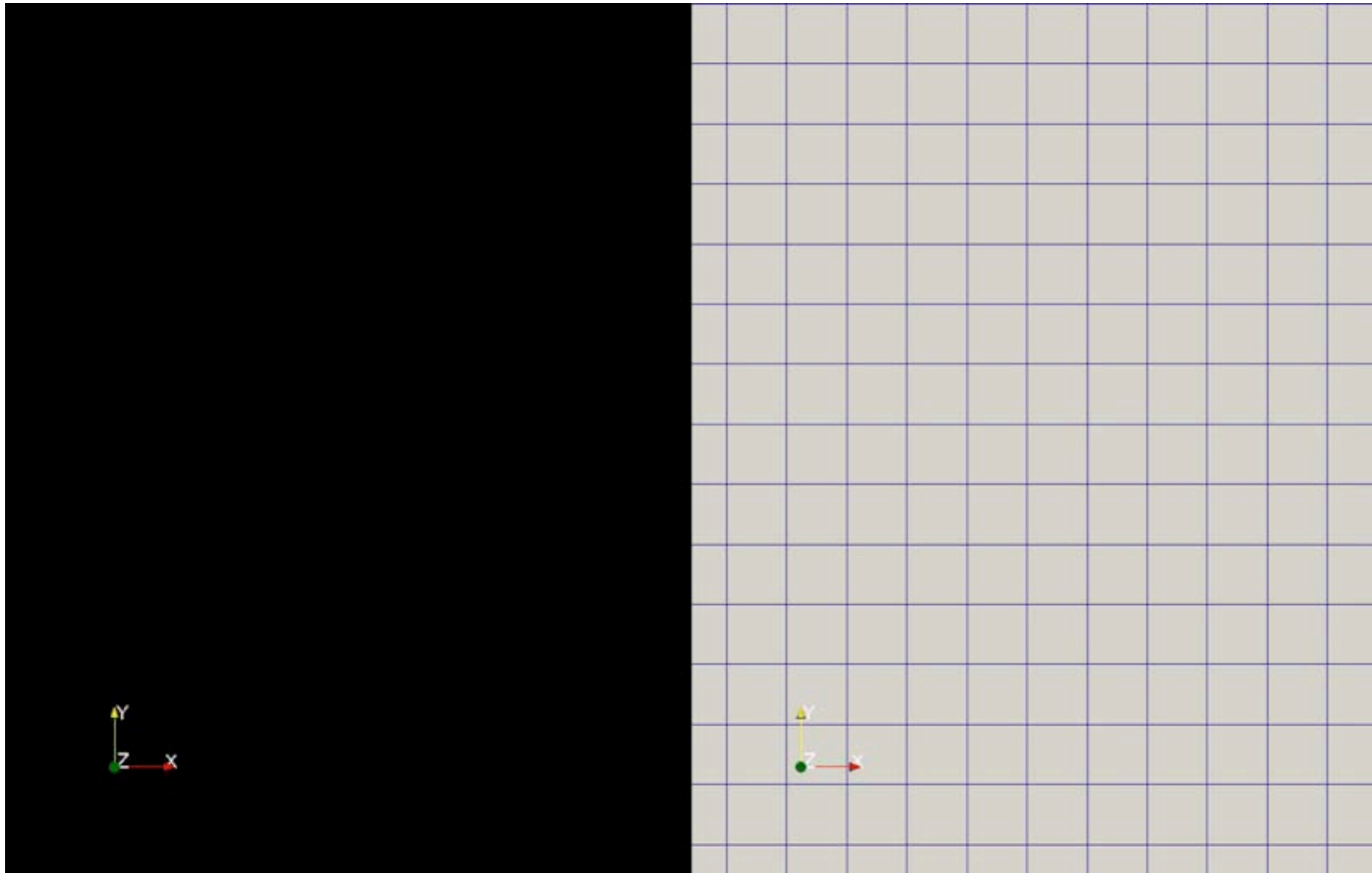
$$\frac{\hat{\tau}_R}{\hat{\tau}_D} = 25$$

SSA using AMR

- Fisher-Kolmogorov Reaction-Diffusion System in 2-D

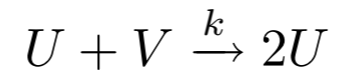


Fisher,
Ann. Eugenics
1937



SSA using AMR

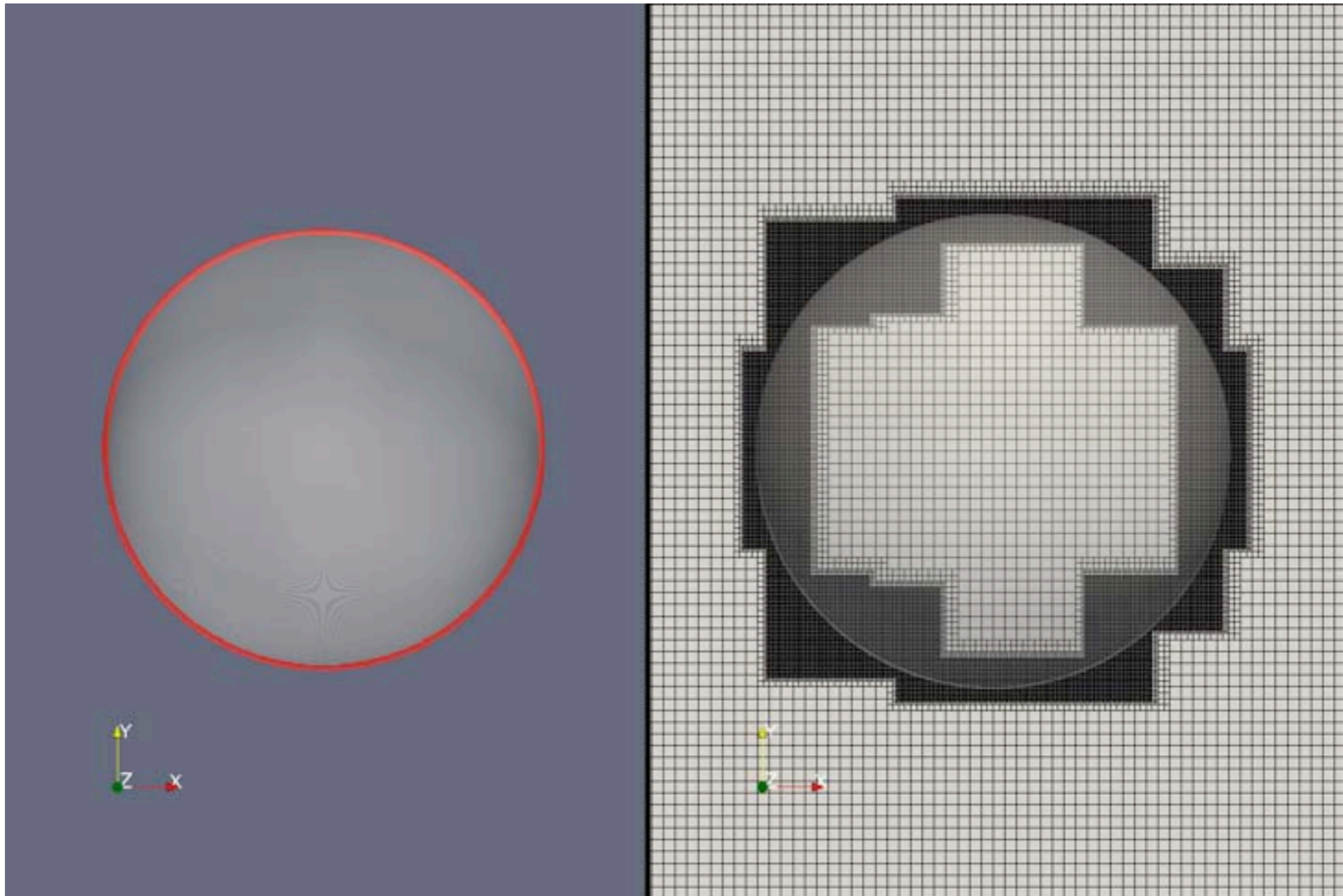
- Fisher-Kolmogorov Reaction-Diffusion System in 2-D



Fisher,
Ann. Eugenics
1937

$$u \in [0.45, 0.55]$$

- halo* is projected 1-D analytical solution

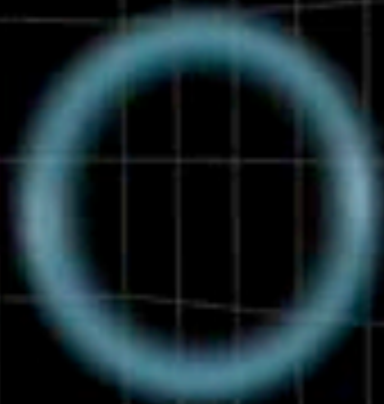


Vorticity $\omega = \nabla \times \mathbf{u}$



$$\frac{D\omega}{Dt} = \omega \cdot \nabla \mathbf{u} + \nu \nabla^2 \omega$$

Vorticity $\boldsymbol{\omega} = \nabla \times \mathbf{u}$



$$\frac{D\boldsymbol{\omega}}{Dt} = \boldsymbol{\omega} \cdot \nabla \mathbf{u} + \nu \nabla^2 \boldsymbol{\omega}$$

FLUIDS - Macroscale Conservation Laws

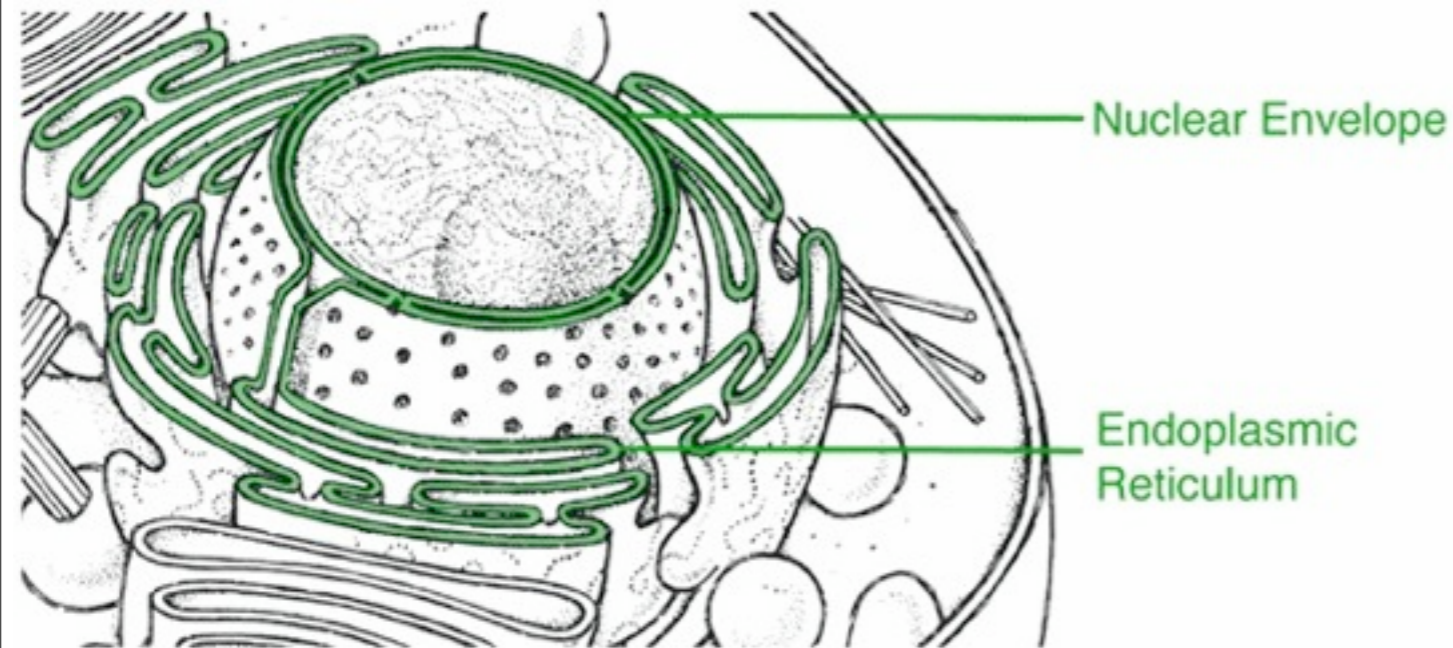


Figure: De Duve, Une visite guidée de la cellule vivante, 1987.

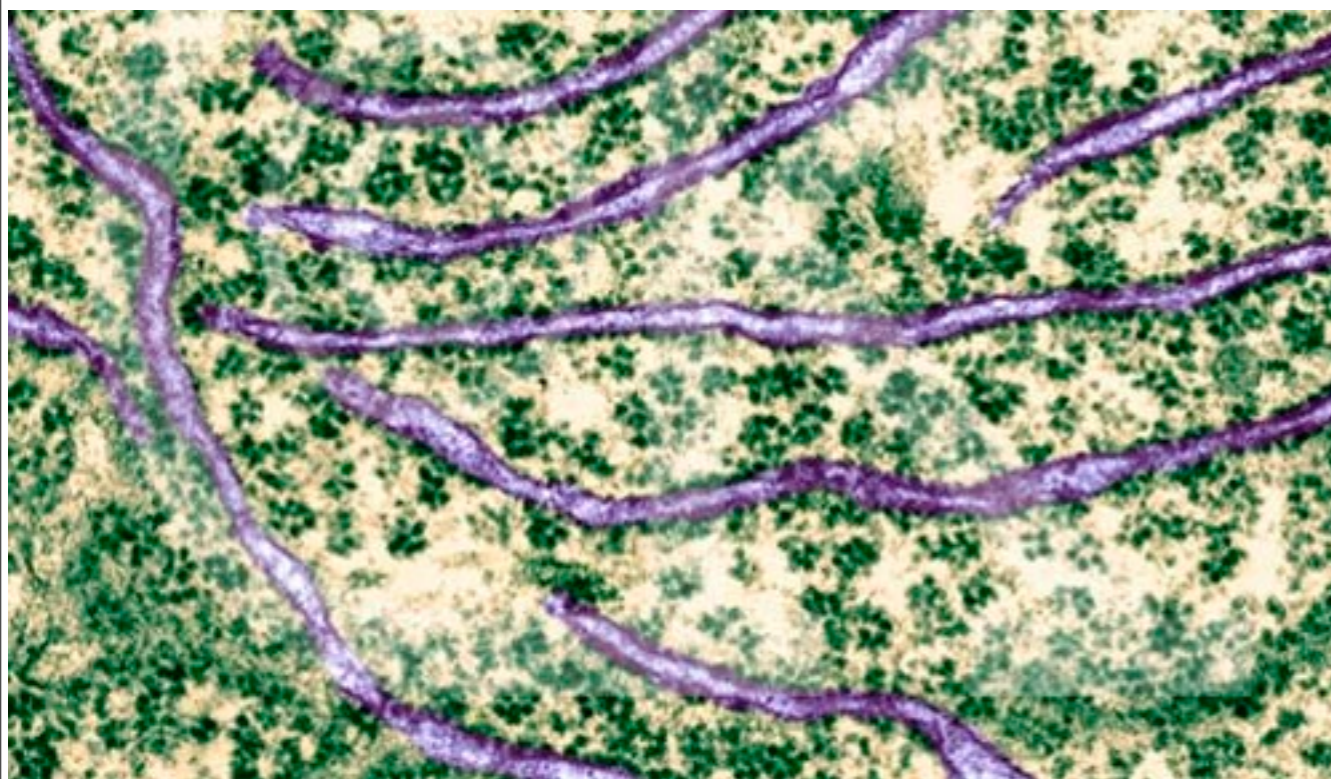
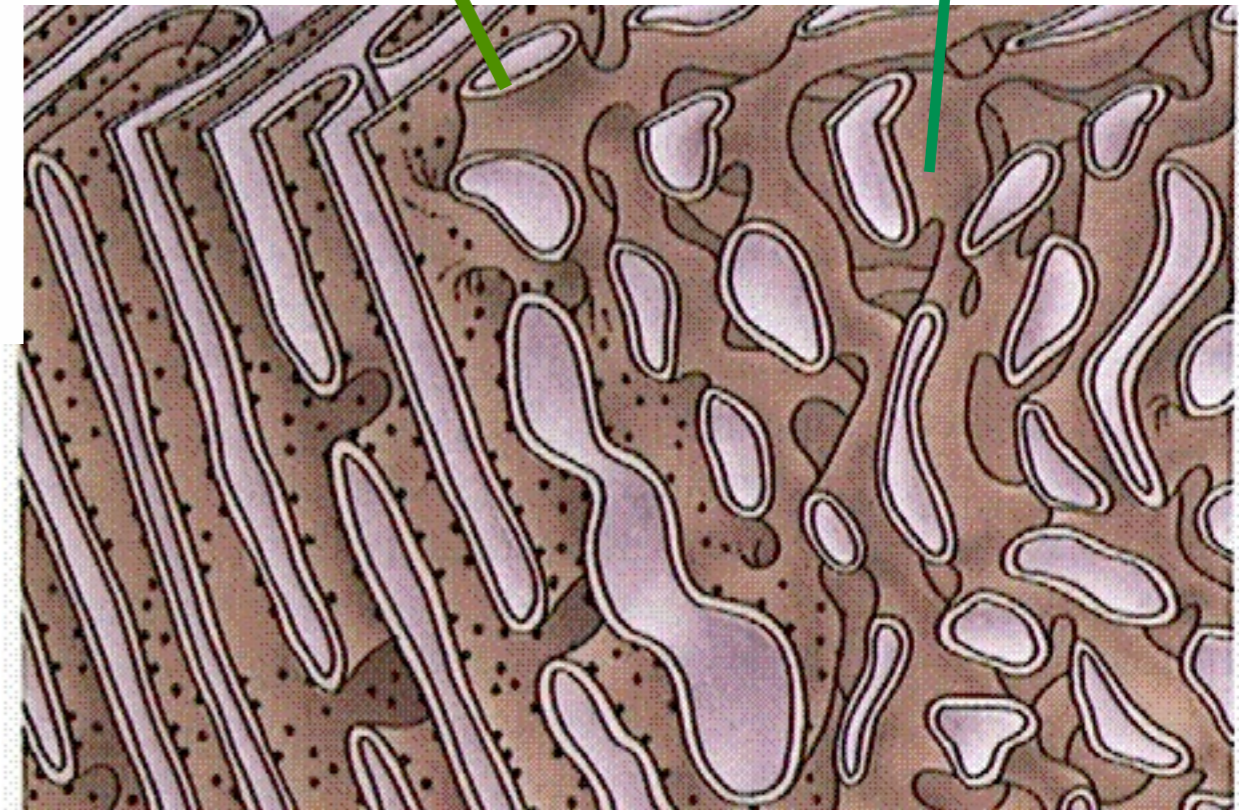


Figure: D. Kunkel, (c) www.DennisKunkel.com

Lumen

Membrane

Figure: Purves et al., Life: The Science of Biology, W.H. Freeman.

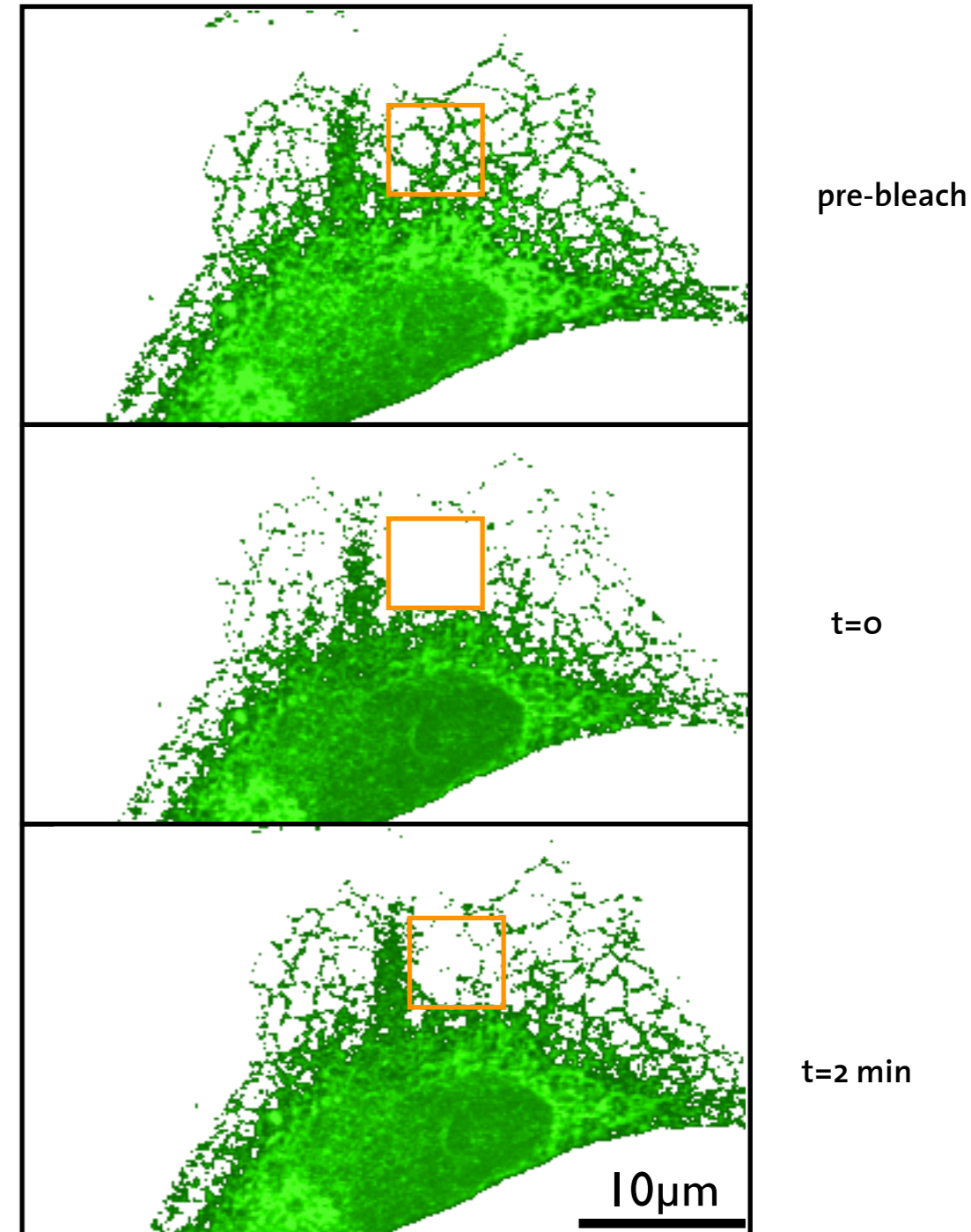
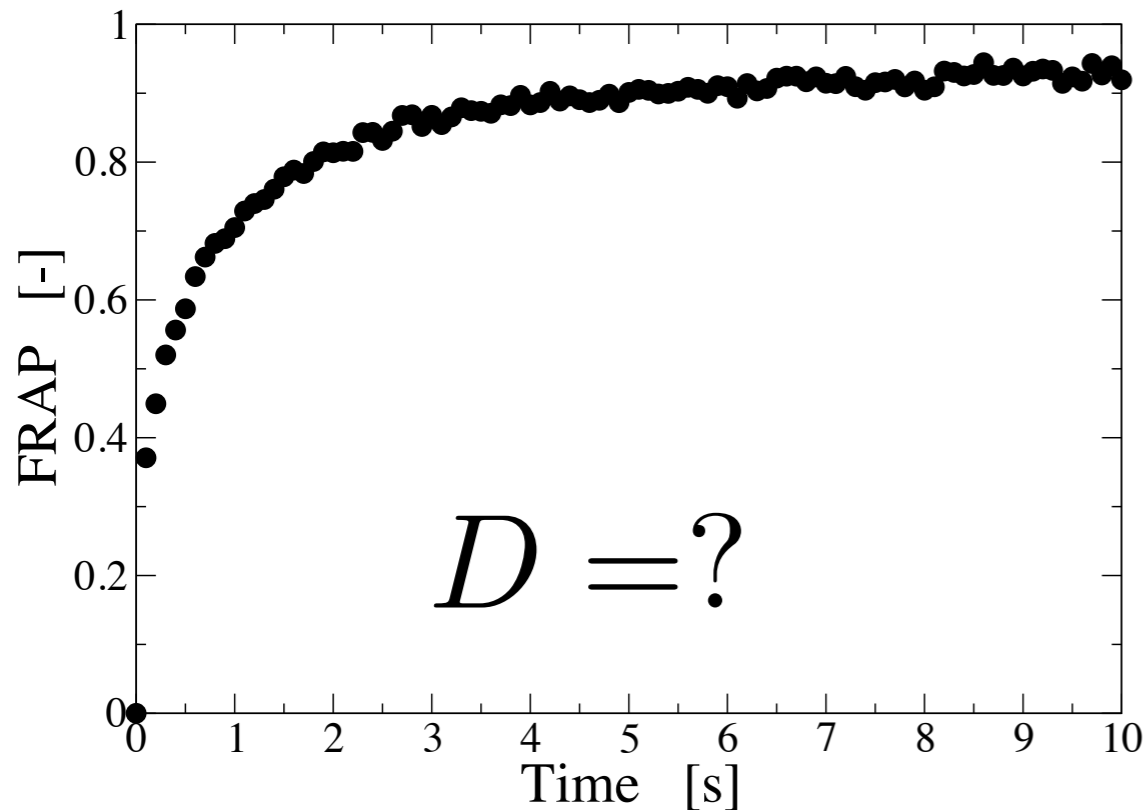


The main **biosynthetic organelle** in Eukaryotes: Protein and lipid synthesis. Enclosed by a **contiguous** membrane

COMPLEX GEOMETRIES : Diffusion in the ER

FRAP : Fluorescence Recovery After Photobleaching

- Tag protein fluorescently
- Laser Bleach **region of interest**
- Monitor influx of unbleached protein



Diffusion

Continuum **assumption** $\frac{\partial u(\mathbf{x}, t)}{\partial t} = \nabla \cdot (D(\mathbf{x}, t) \nabla u(\mathbf{x}, t))$

Cases: $D(\mathbf{x}, t) = D(\mathbf{x})$ $D(\mathbf{x}, t) = D$ $D(\mathbf{x}, t) = \nu(\mathbf{x}, t) \mathbb{1}$
Normal Homogeneous Isotropic

Recall CFD : “**Vorticity**” becomes “**Concentration**”

$\frac{D\omega}{Dt} = \omega \cdot \nabla \mathbf{u} + \nu \nabla^2 \omega$	$\frac{dx_p}{dt} = \mathbf{u}$
-----------------------------------------------------------------------------	--------------------------------

Diffusion Approximations

Diffusion

$$\frac{\partial c}{\partial t} = \nu \Delta c$$

Particles

$$C_\epsilon^h(x, t) = \sum_{p=1}^{N_p} h_p^d c_p(t) \zeta_\epsilon(x - x_p(t))$$

Particle Strength Exchange

$$\frac{dc_q}{dt} = \frac{\nu}{\epsilon^2} \sum_{p=1}^{N_p} (h_p^d c_p - h_q^d c_q) \zeta_\epsilon(x_q - x_p)$$

Degond & Mas-Gallic, Math. Comput. 53:509. 1989.

Extendable to any diffusion operator

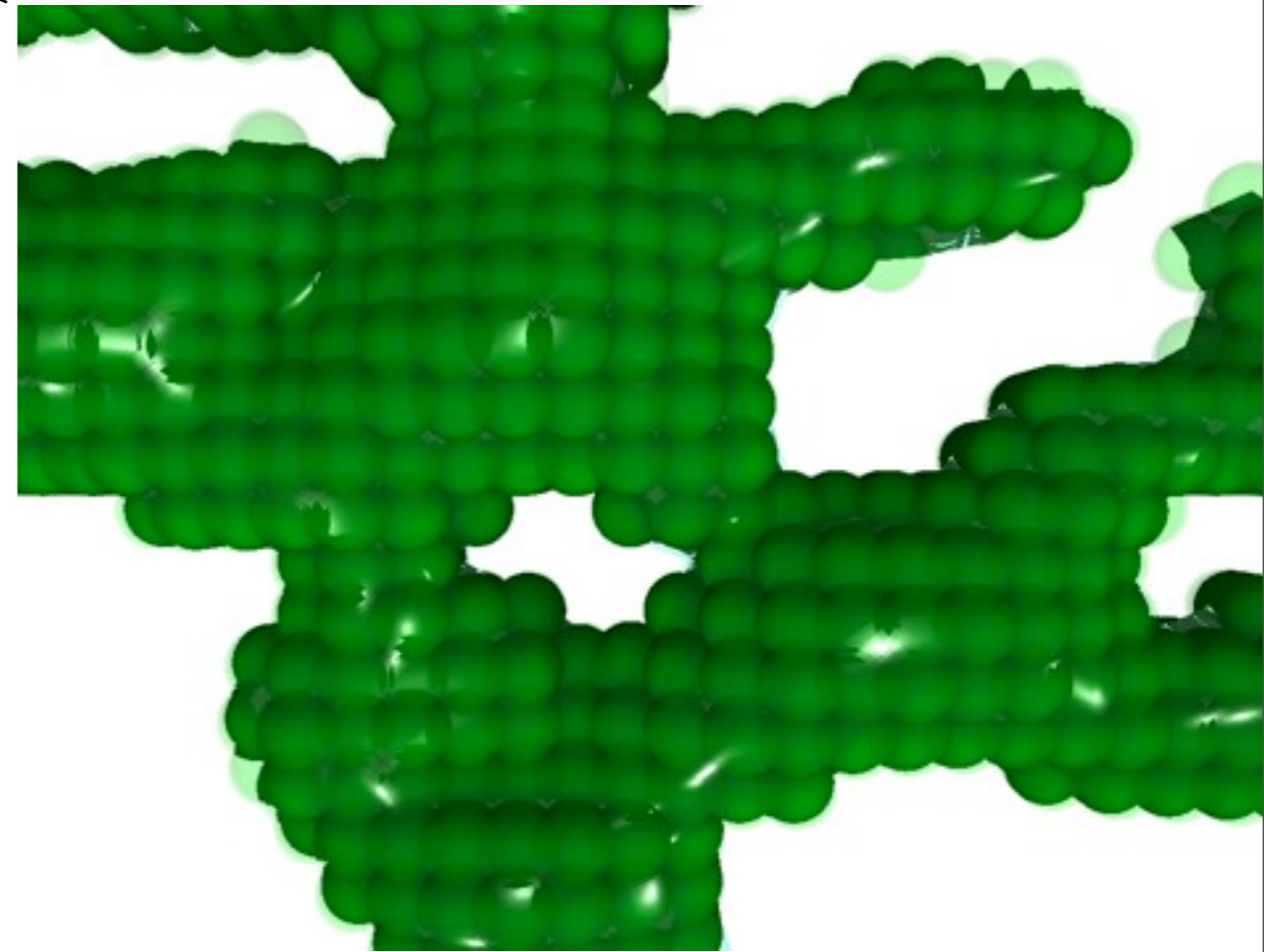
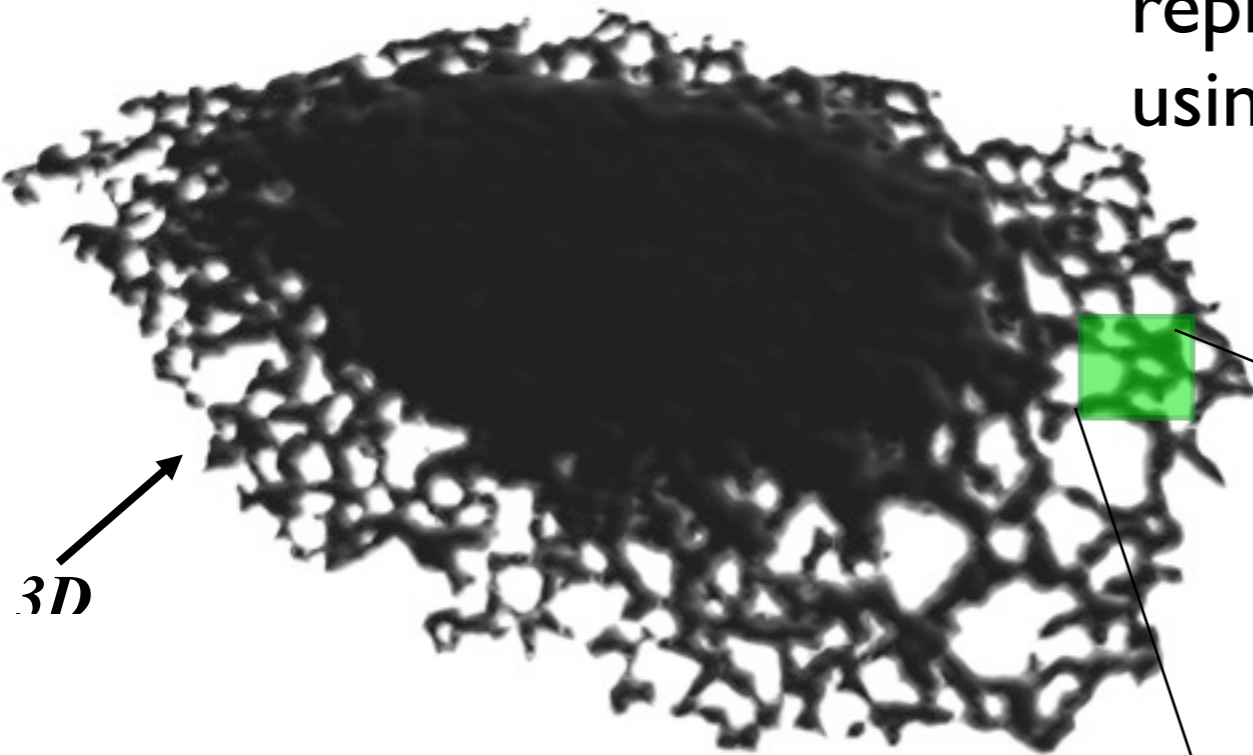
Accuracy $\sim \frac{1}{N^4}$

Cost $\sim N$

PSE is Orders of magnitude better than random walk

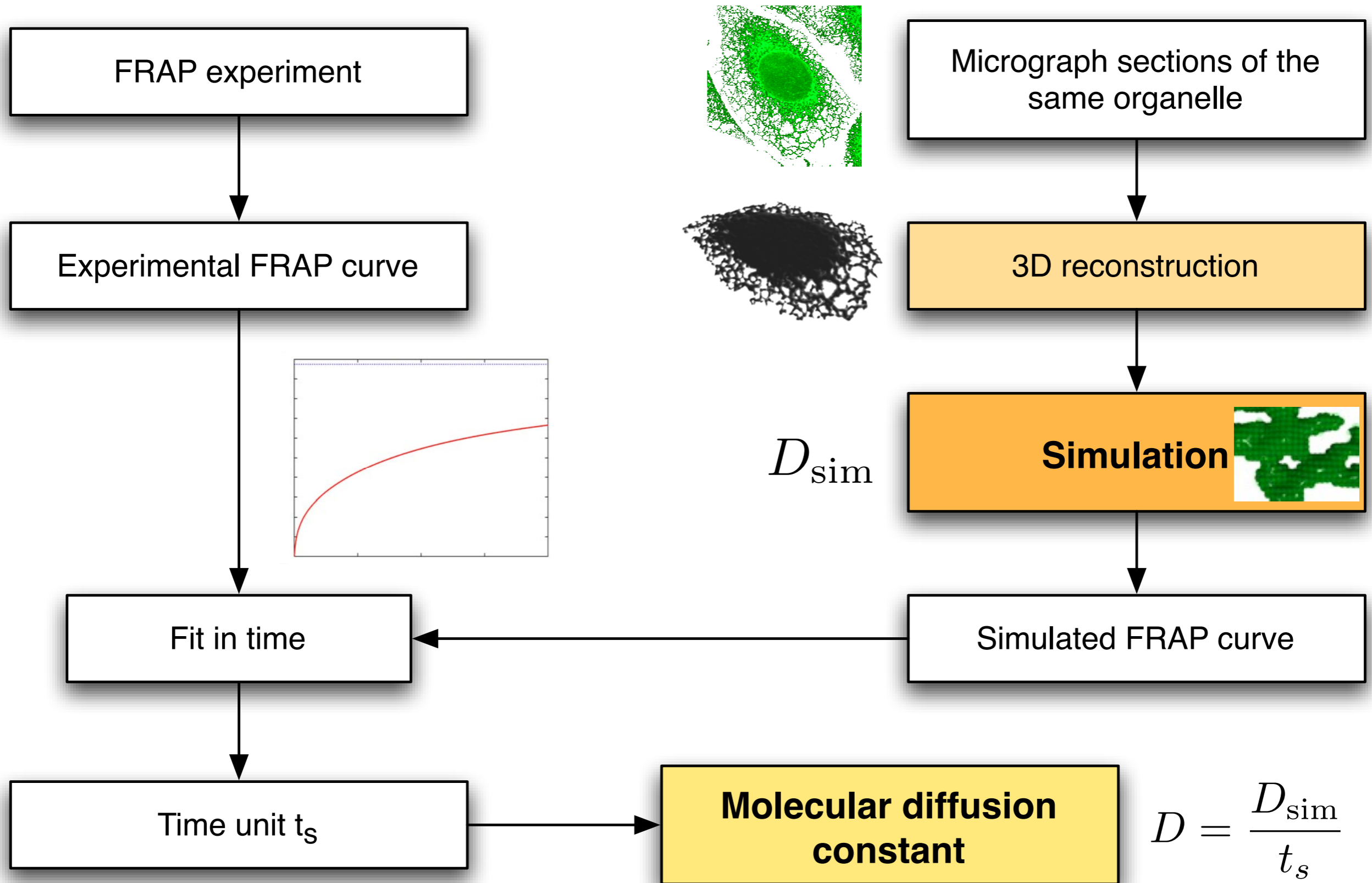
Diffusion in the Endoplasmic Reticulum

representation of complex geometries
using Lagrangian Particle Level Sets

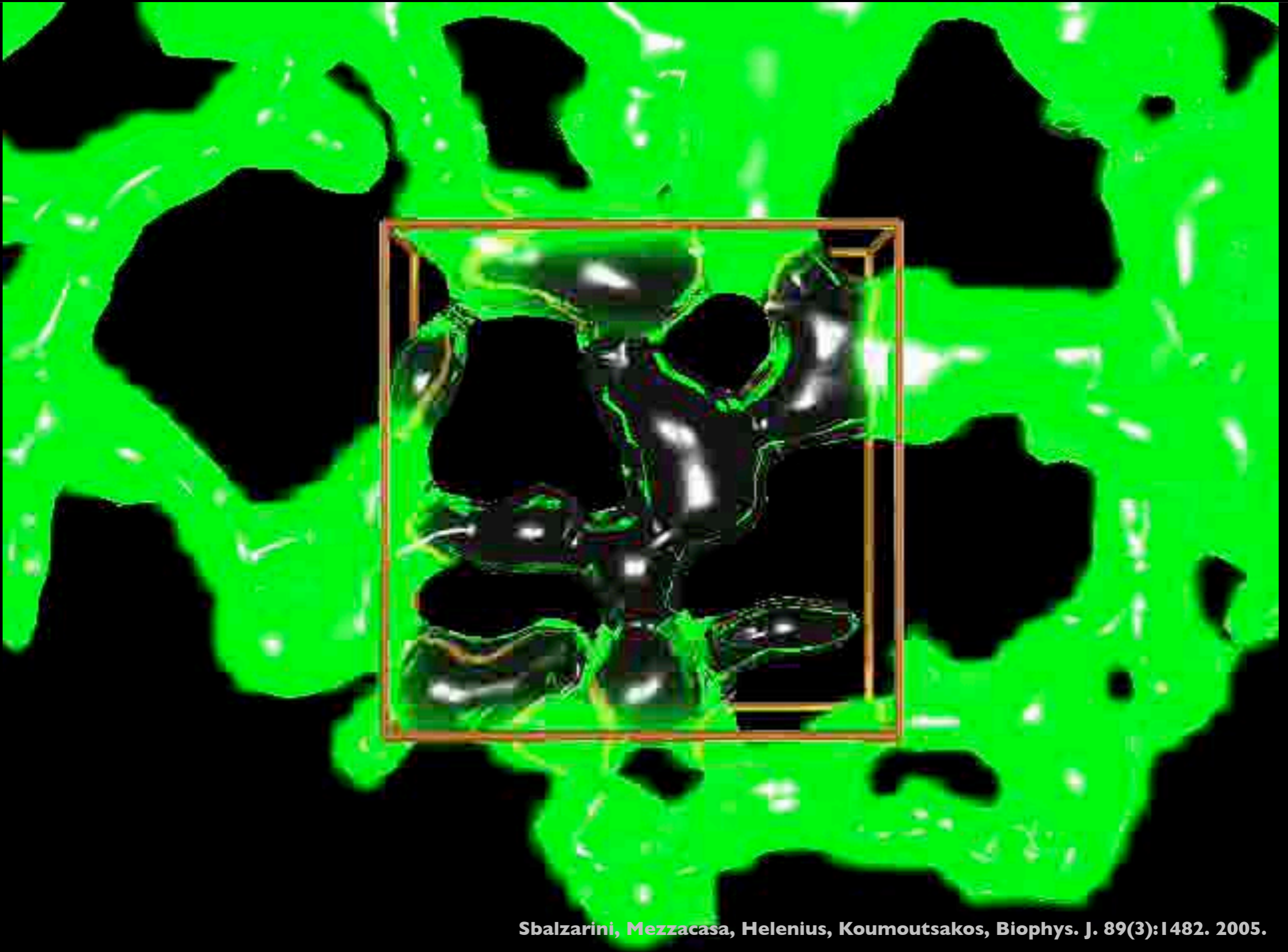


Simulation of diffusion in the lumen of
reconstructed **real** biological geometries

Integrate Imaging and Simulations

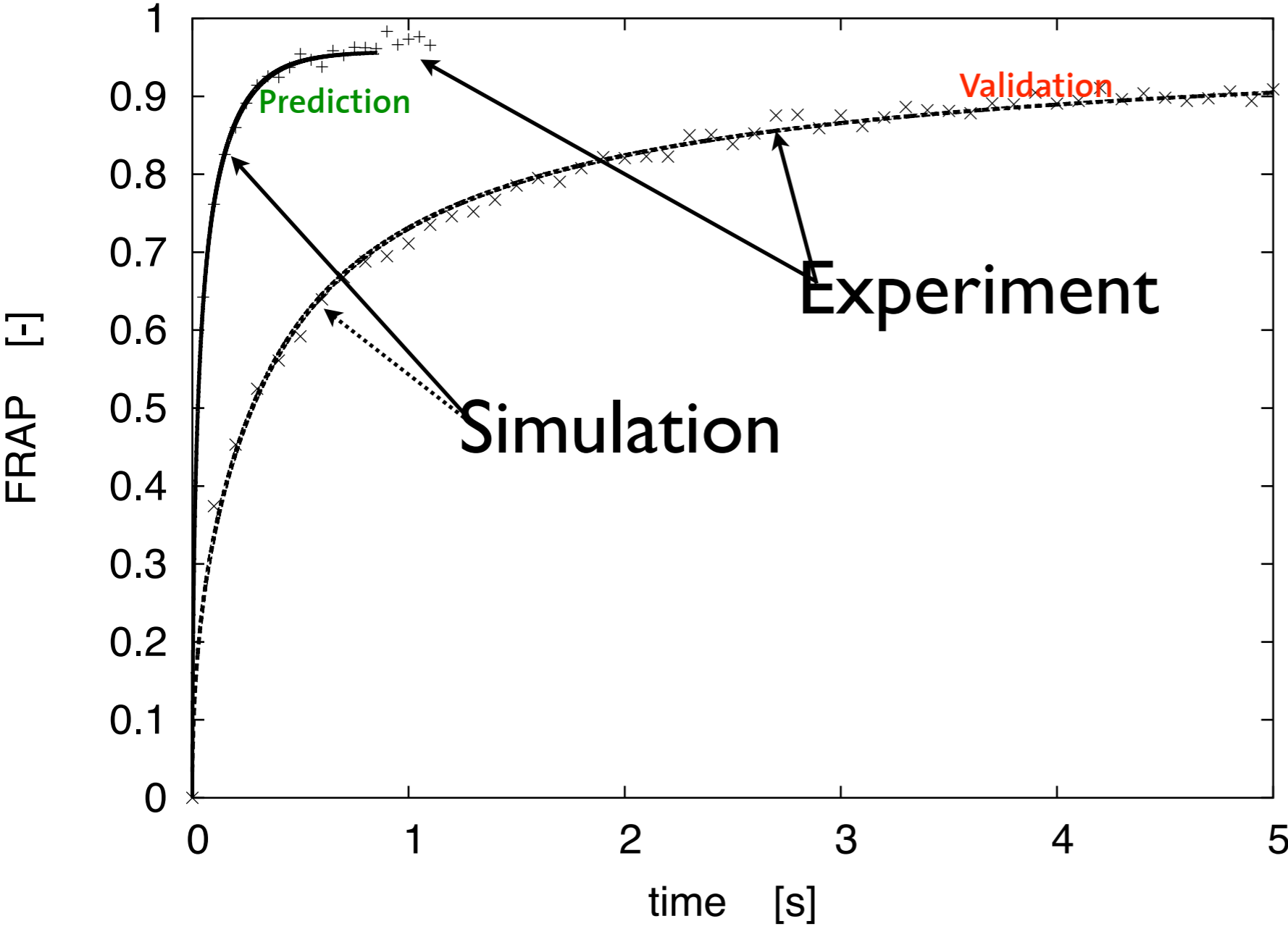


Diffusion in the Real Endoplasmic Reticulum - LUMEN



Sbalzarini, Mezzacasa, Helenius, Koumoutsakos, *Biophys. J.* 89(3):1482. 2005.

Simulations and Experiments in the same Geometry



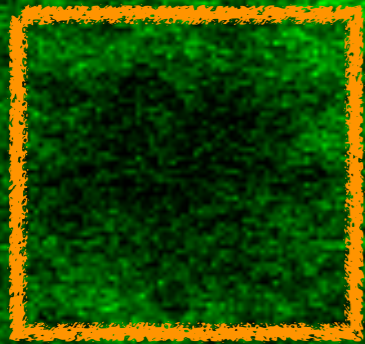
Simulation and Experiment in the **same** ER



in vivo diffusion constant from fit

“...but, can you do this on a **surface** ?” – A. Helenius

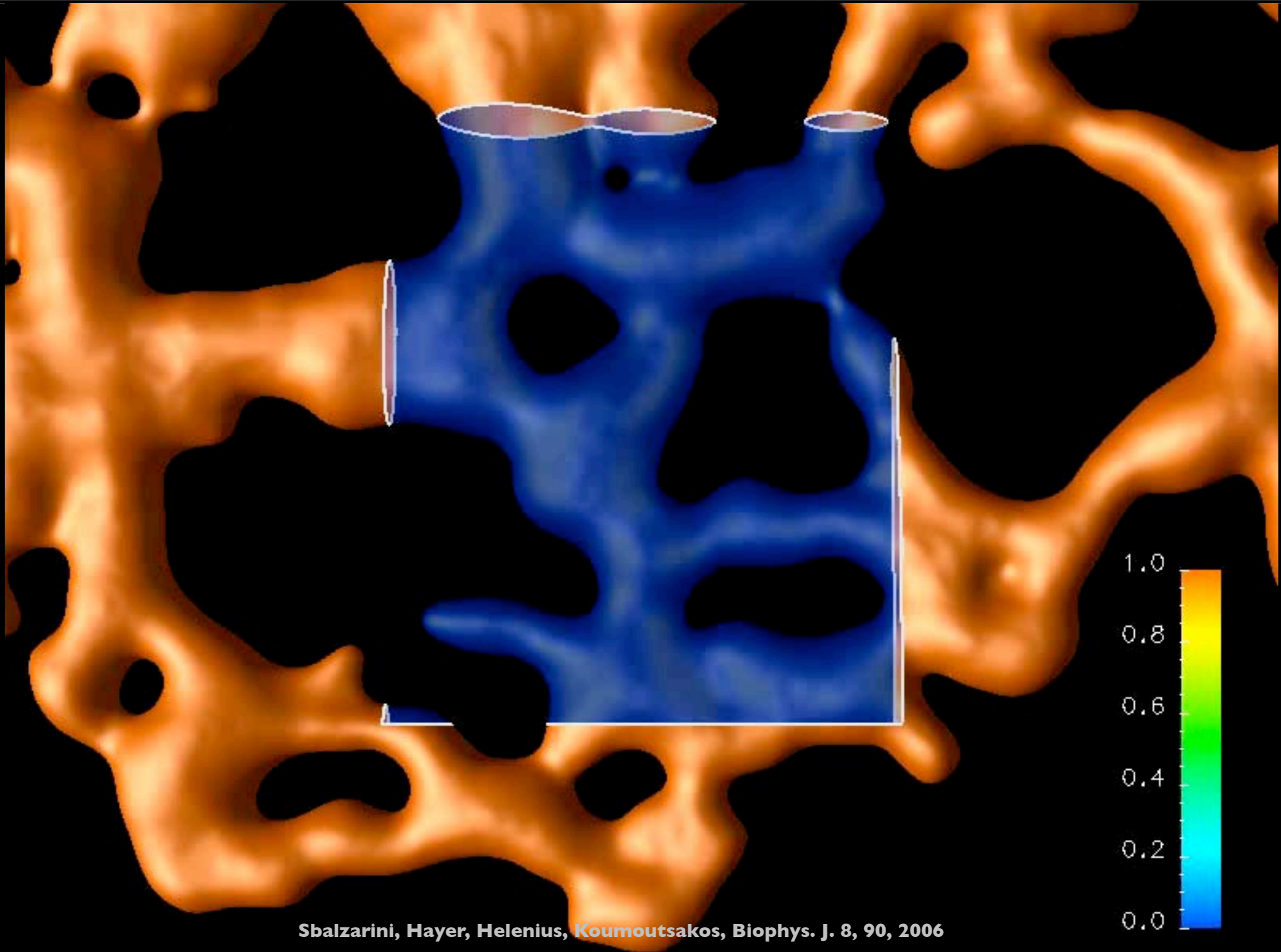
Movie: Helenius group, D-BIOL, ETHZ



Membrane:

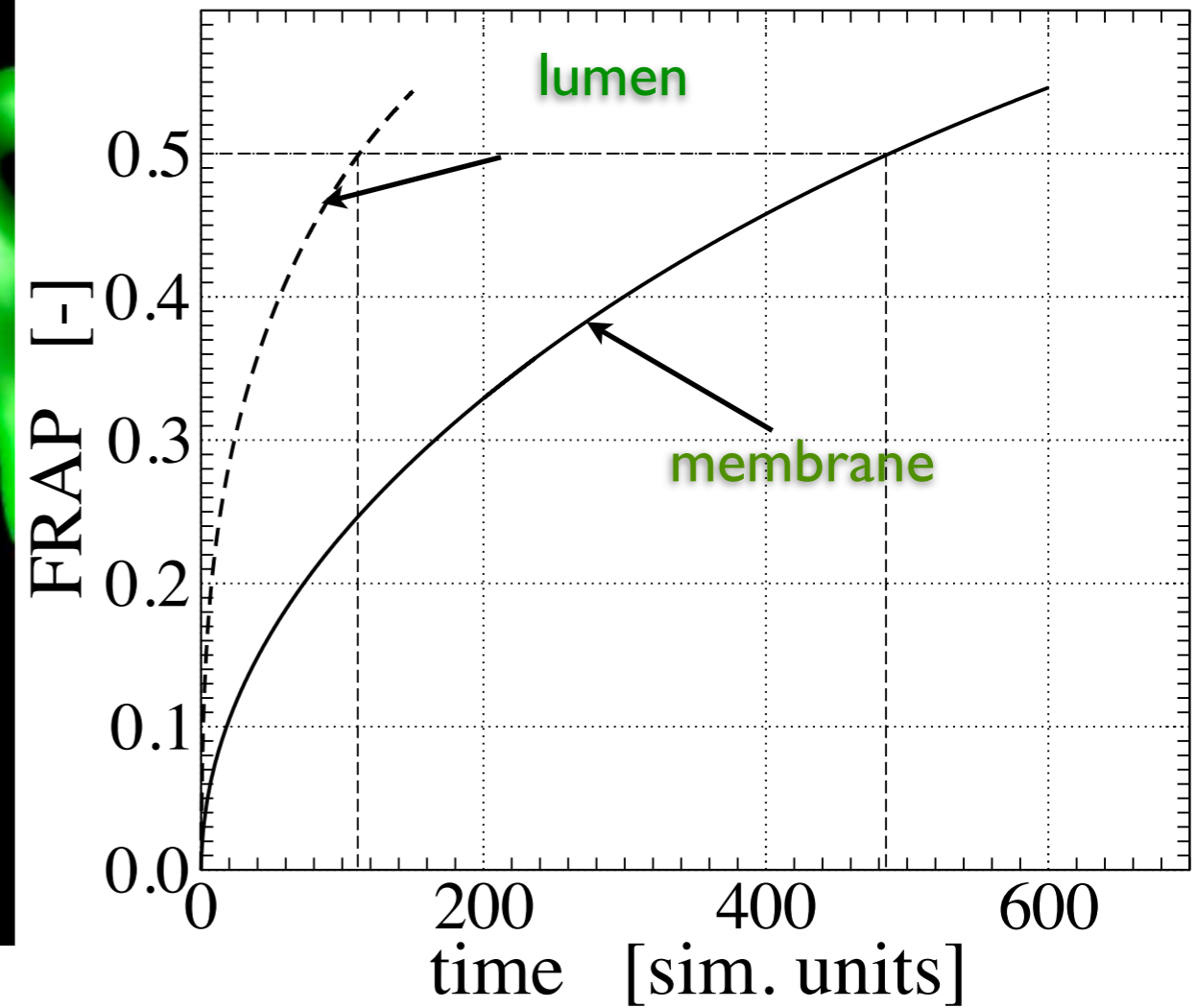
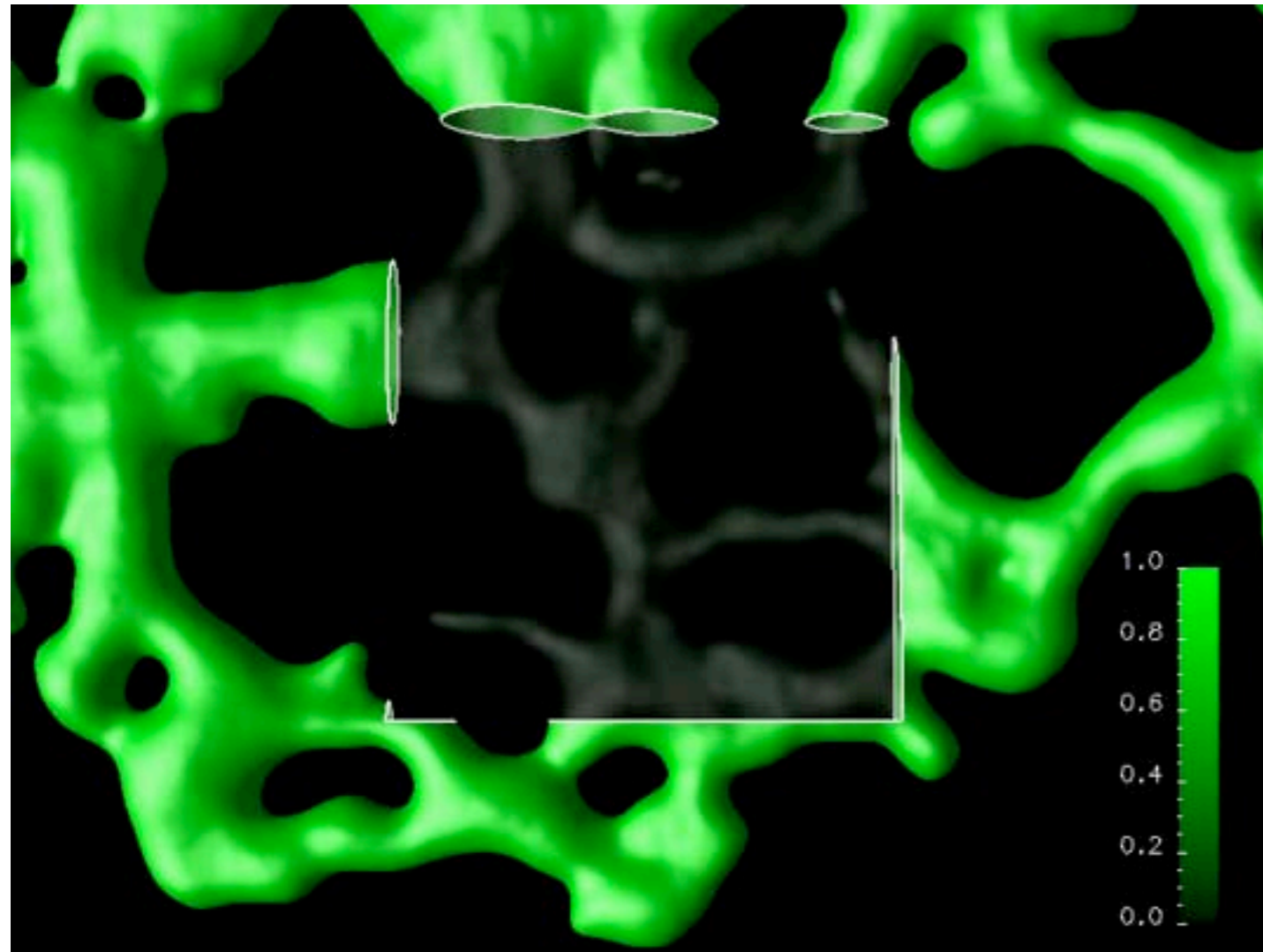
tsO45-VSVG-GFP

Diffusion in the Real Endoplasmic Reticulum - SURFACE



Sbalzarini, Hayer, Helenius, Koumoutsakos, *Biophys. J.* 8, 90, 2006

Diffusion on reconstructed ER of VERO cells

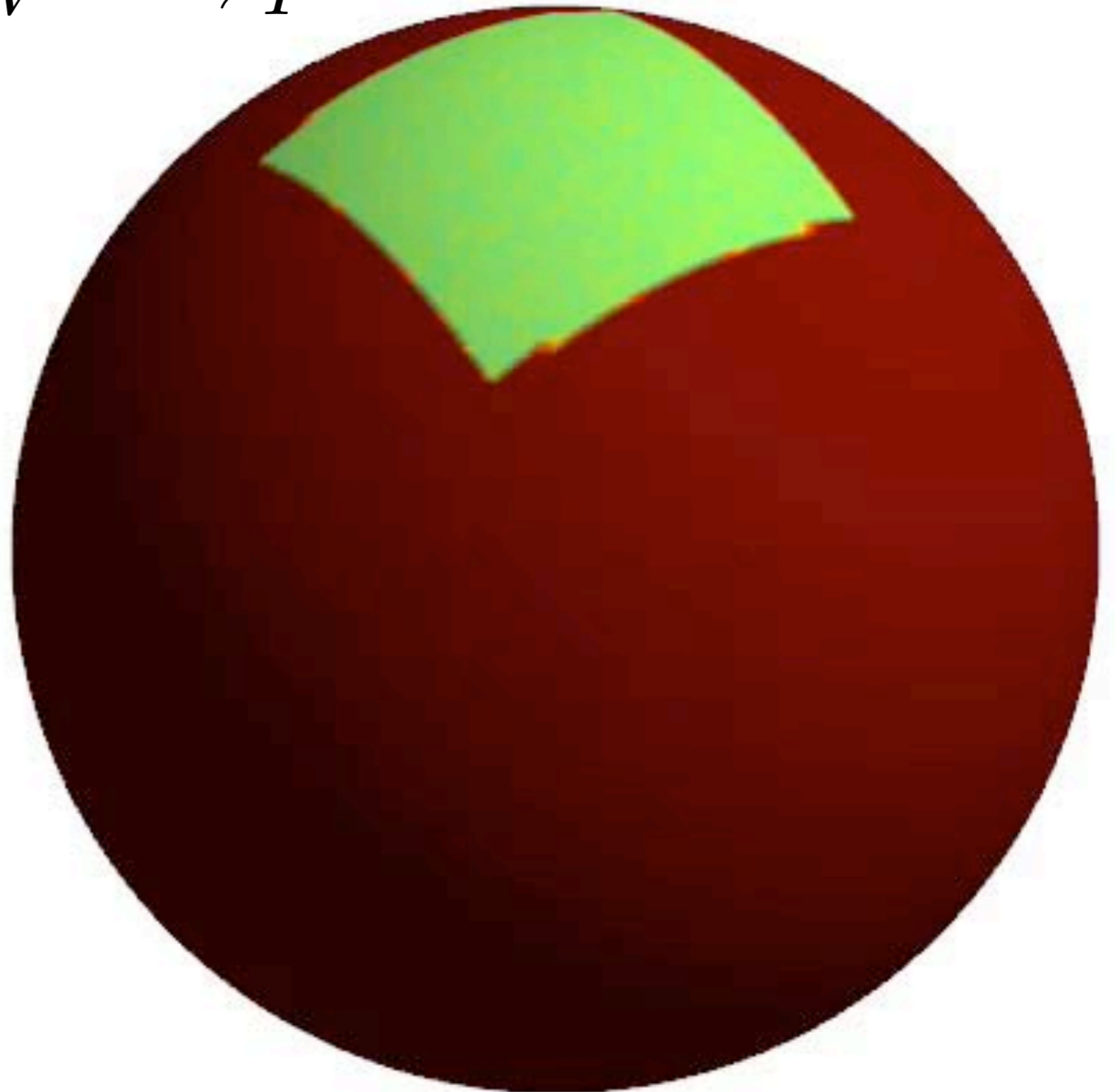
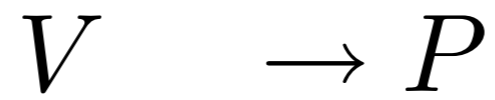
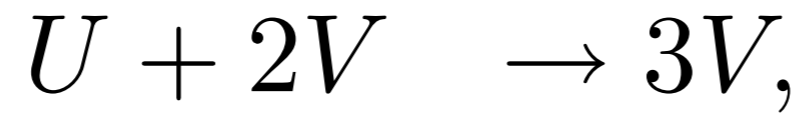


ssGFP-KDEL in the ER lumen $\nu = 34 \pm 0.95 \mu\text{m}^2/\text{s}$

tsO45-VSVG-GFP in the ER membrane $\nu = 0.16 \pm 0.07 \mu\text{m}^2/\text{s}$

Using the *same diffusion constant* recovery speed varies by **>400%**.

Gray Scott system

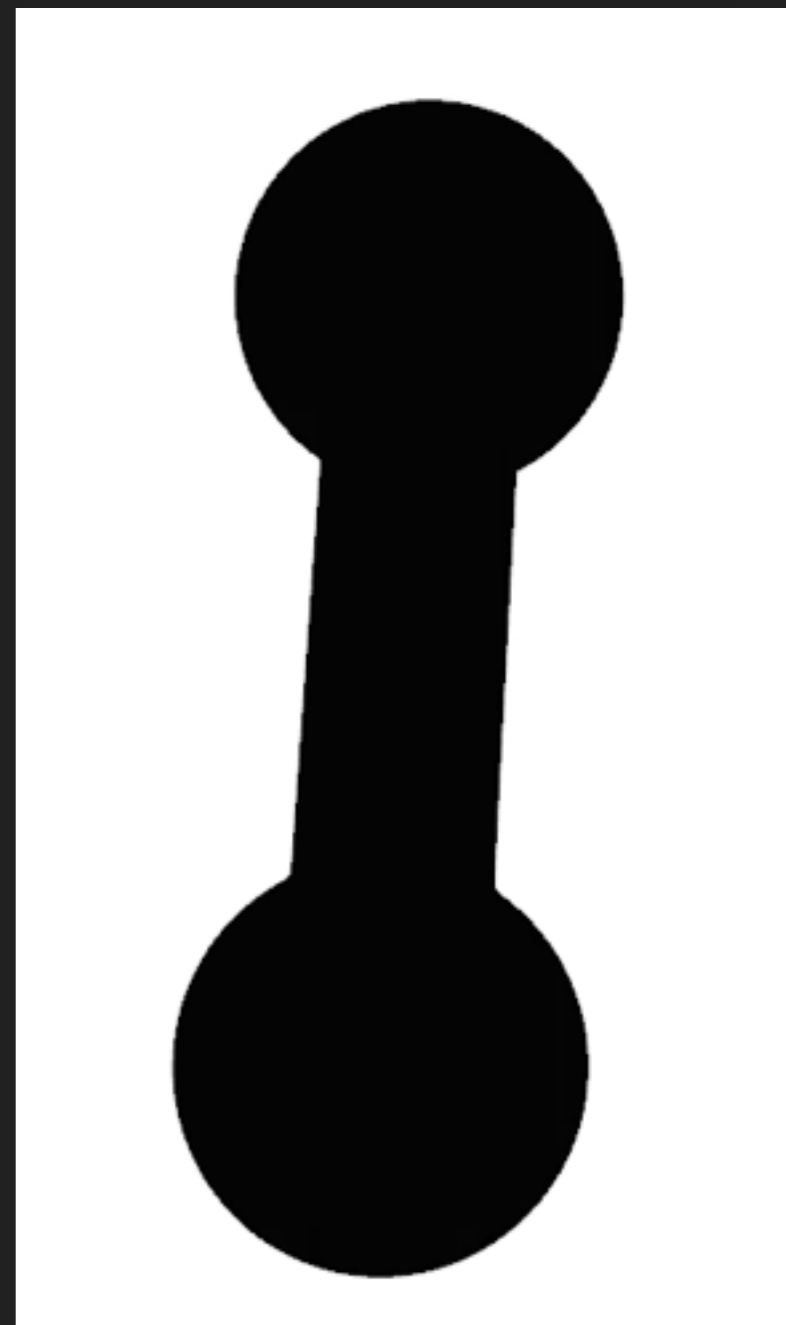


Deterministic



“Well, the *stripes* are easy, but what about the *horse* part “ ?

Turing



Hieber and Koumoutsakos, Lagrangian Particle Level Sets, *J. Comput. Phys.*, 2005

GROWTH : Reaction-Diffusion on Deforming Geometries

RDG - Equations

- Reaction-Diffusion on growing surface

$$\frac{\partial c_i}{\partial t} + \nabla_{\Gamma(t)} \cdot (c_i \mathbf{u}) = D_i \Delta_{\Gamma(t)} c_i + R_i(\mathbf{c}) \quad \text{on } \Gamma(t), i = 1 \dots N,$$

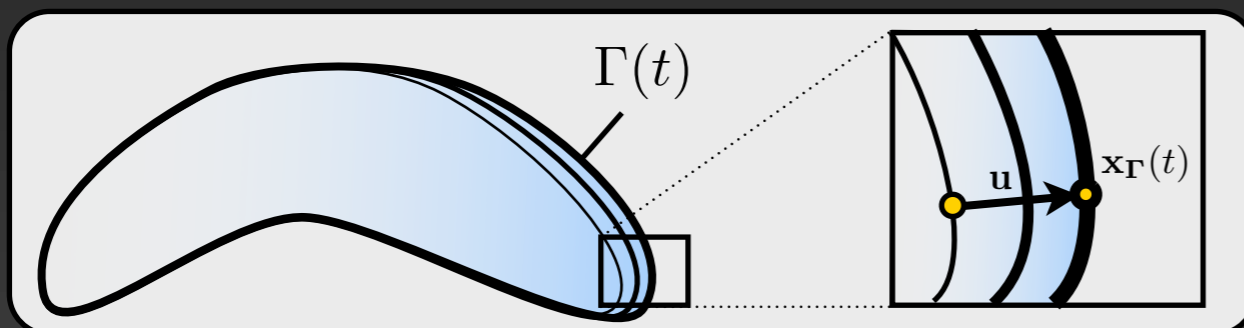
N = Number of species,

$\mathbf{c} = [c_1, \dots, c_N]$ = Concentrations,

D_i = Diffusion constant for species i ,

$R_i(\mathbf{c})$ = Reaction terms for species i .

- Surface changes over time



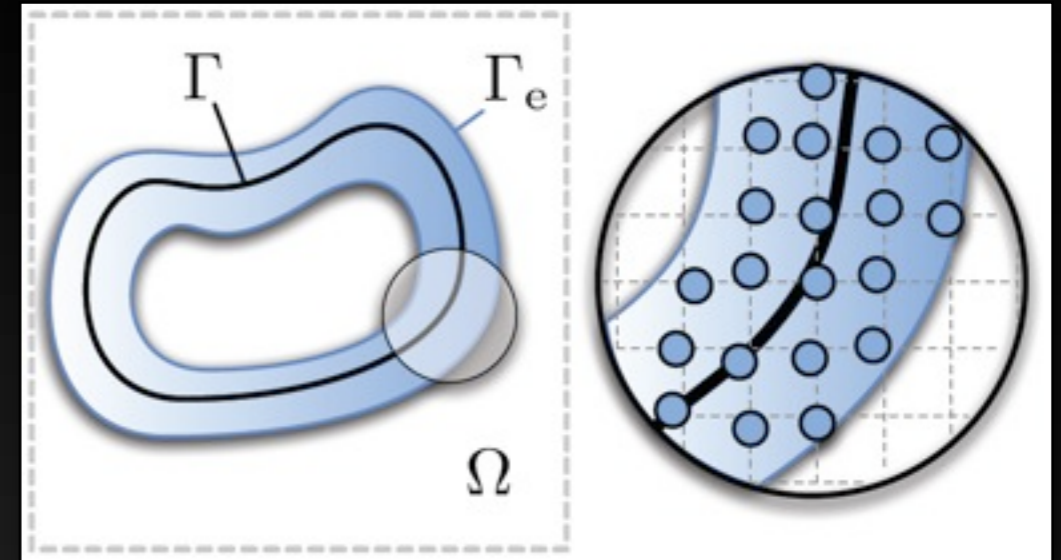
$$\Gamma(t) = \{\mathbf{x}_{\Gamma}(t)\},$$
$$\frac{d\mathbf{x}_{\Gamma}}{dt} = \mathbf{u}(\mathbf{x}_{\Gamma}, \mathbf{c}_s).$$

References:

Bergdorf, M., Sbalzarini, I. F., and Koumoutsakos, P. (2009). A Lagrangian particle method for reaction-diffusion systems on deforming surfaces, Journal of Mathematical Biology (submitted)

Extended domain

- Species given in narrow band around surface
- Use level set for surface
- Replace diffusion operator
- Extend concentration
 - simplifies surface growth



$$\Gamma = \{ \mathbf{x} \mid \varphi(\mathbf{x}) = 0 \},$$
$$\mathbf{n} = \nabla \varphi / \|\nabla \varphi\|$$

$$D_s \nabla \cdot ((\mathbb{I} - \mathbf{n} \otimes \mathbf{n}) \nabla c)$$

$$\frac{\partial c}{\partial n} = \nabla c \cdot \mathbf{n} = 0$$

Plant growth with Brusselator

$$\begin{aligned} X > X_{th} : \quad & \partial X / \partial t = D_X \nabla^2 X + aA - bBX + cX^2Y - dX, \\ & \partial Y / \partial t = D_Y \nabla^2 Y + bBX - cX^2Y, \\ X \leq X_{th} : \quad & \partial X / \partial t = D_X \nabla^2 X - dX, \\ & \partial Y / \partial t = D_Y \nabla^2 Y, \end{aligned}$$

A given as prepattern based on spherical harmonics Y_l^m ,

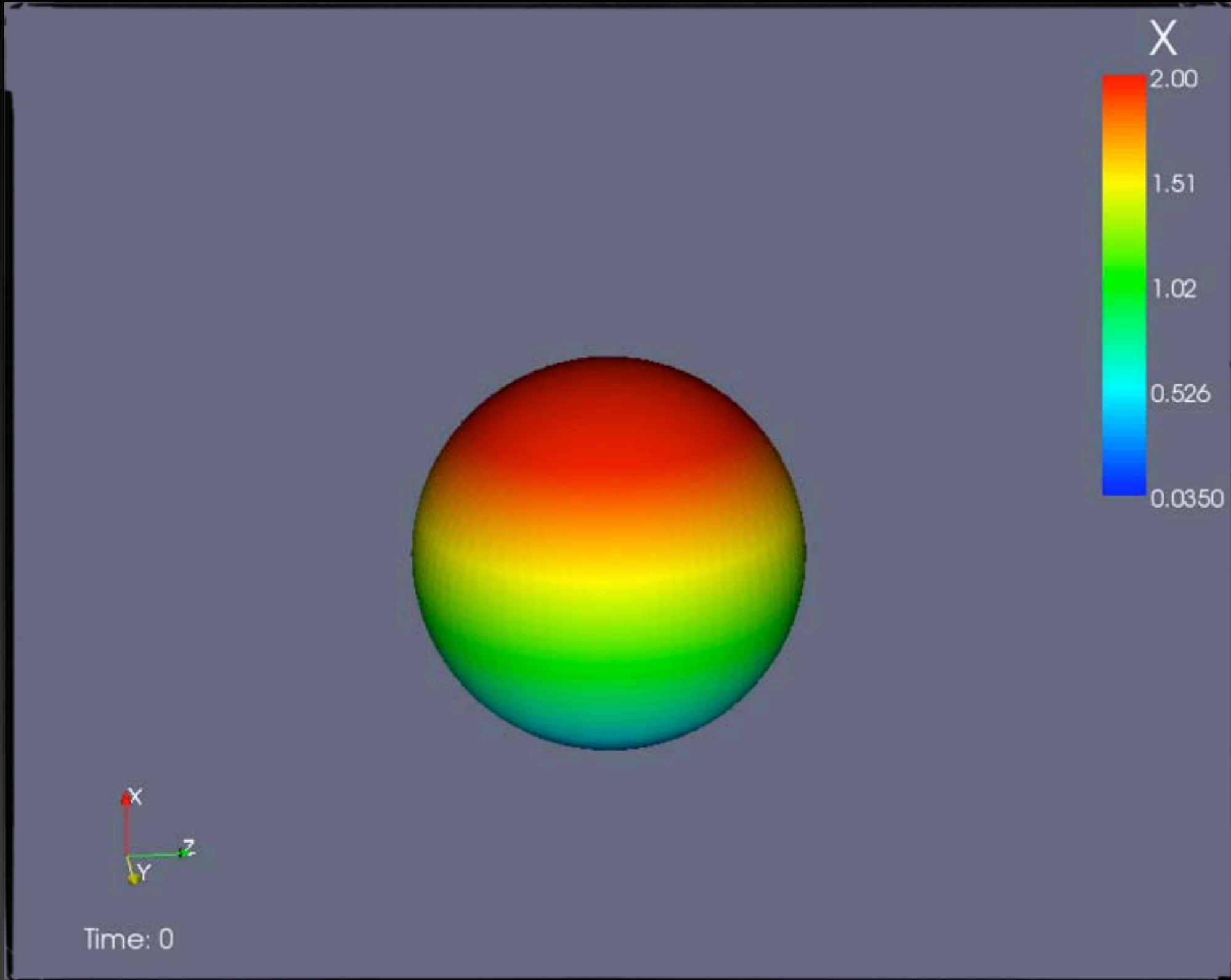
Initial condition based on A : $X_0 = \frac{aA}{d}$, $Y_0 = \frac{bB}{cX_0}$,

Surface growth starting at $t = t_{move}$ by $\mathbf{u} = vX\mathbf{n}$,

$D_X, D_Y, a, bB, c, d, X_{th}, t_{move}, v$ given as parameters.

Holloway, D. M. and Harrison, L. G. (2008). Pattern selection in plants: Coupling chemical dynamics to surface growth in three dimensions, *Annals Of Botany*, 101(3), 361--374

Results (stronger A)



Settings:

$$A = Y_1^0 \text{ in } [1, 16],$$

$$D_X = 0.008, D_Y = 0.16,$$

$$a = 0.01, bB = 1.5,$$

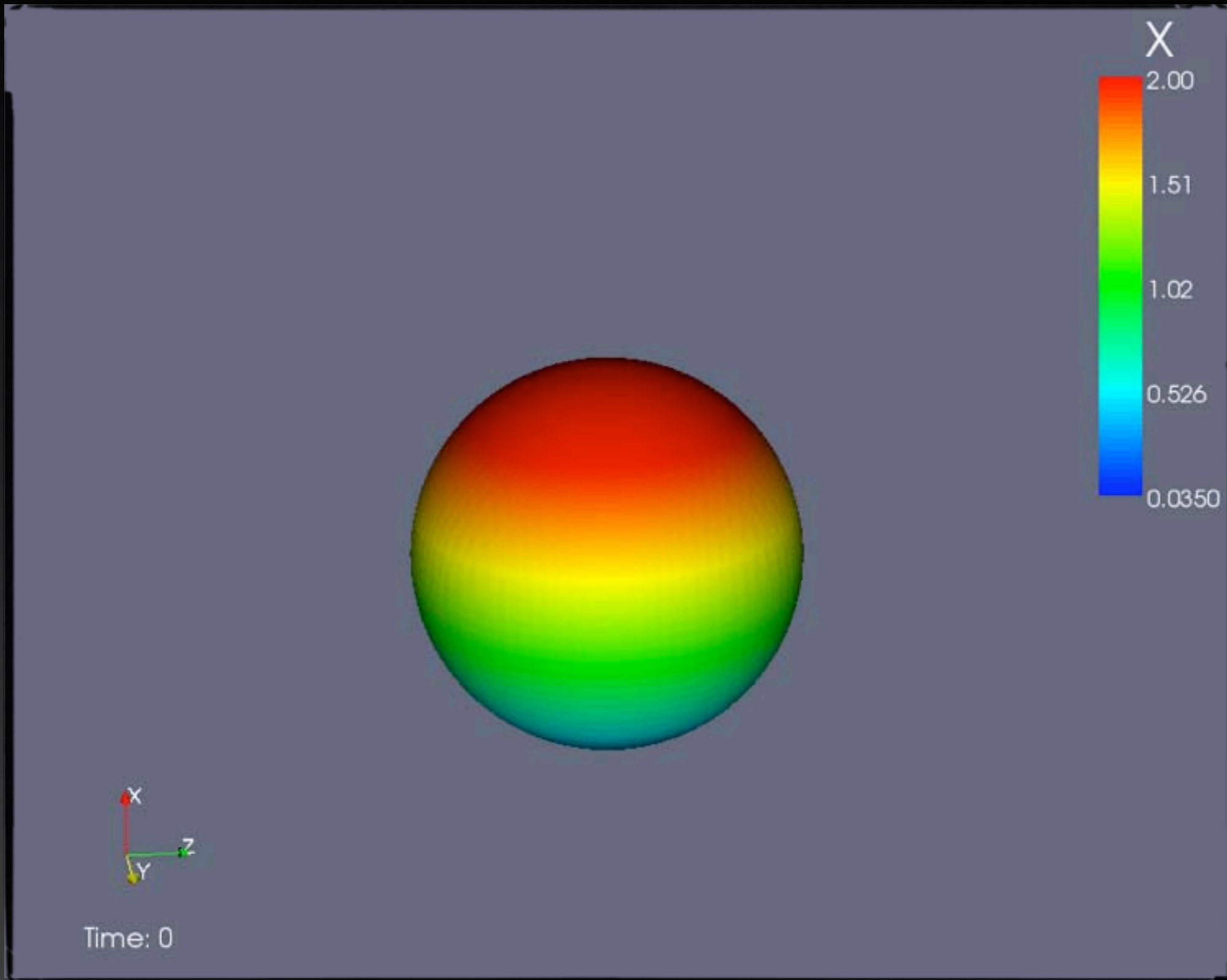
$$c = 1.8, d = 0.07,$$

$$X_{th} = 0.035, v = 0.01,$$

$$t_{move} = 20,$$

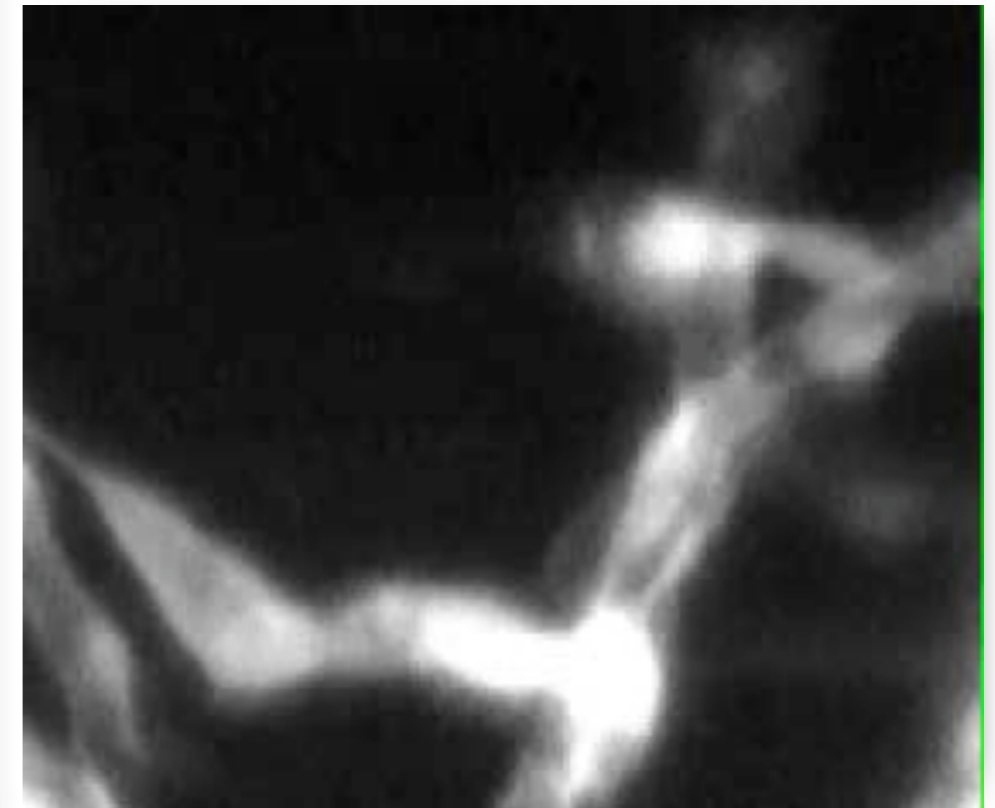
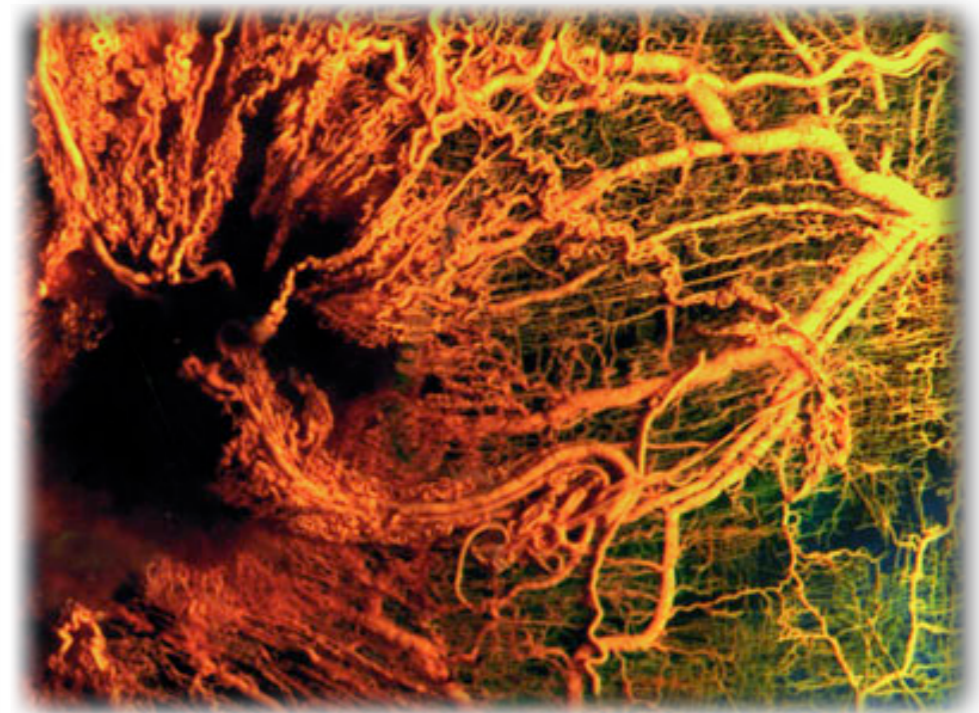
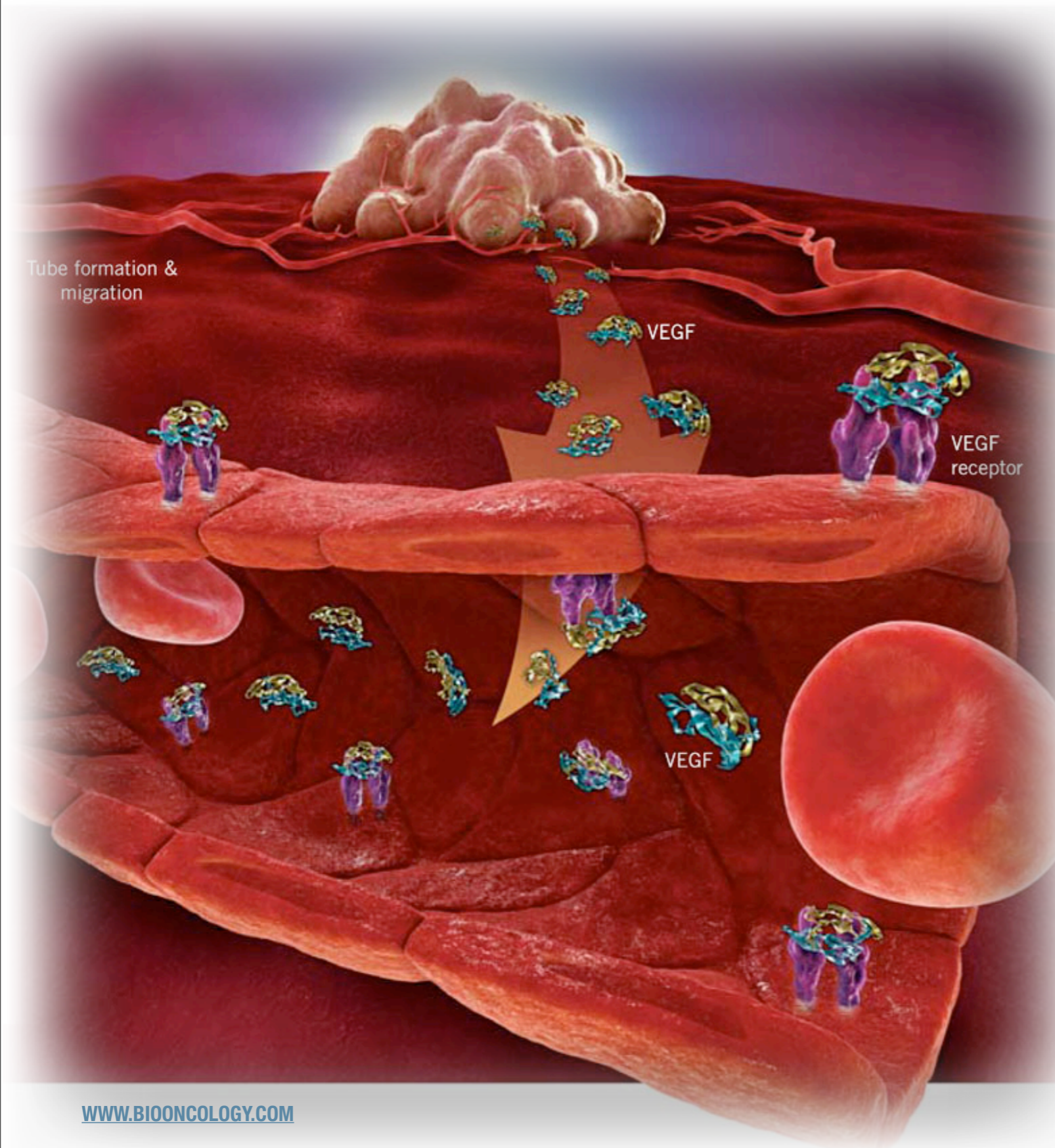
Species here are growing with surface.

Results (mass conservation)



Settings:

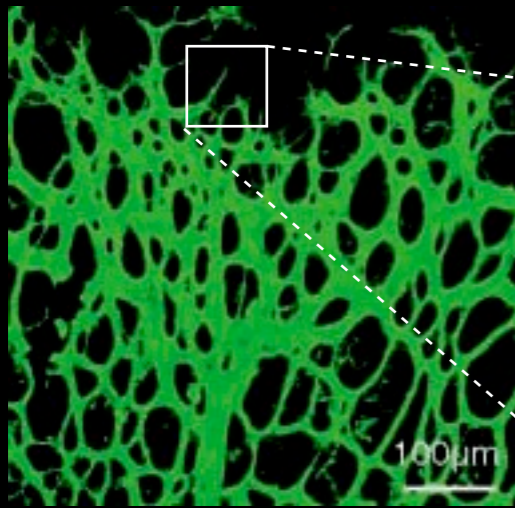
$$A = Y_1^0 \text{ in } [1, 16],$$
$$D_X = 0.008, D_Y = 0.16,$$
$$a = 0.01, bB = 1.5,$$
$$c = 1.8, d = 0.07,$$
$$X_{th} = 0.035, v = 0.01,$$
$$t_{move} = 20.$$



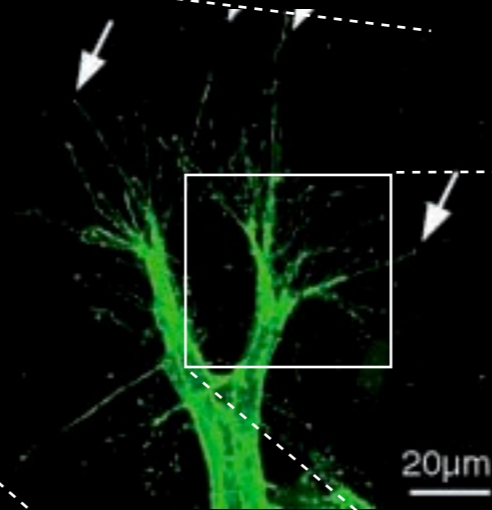
CRANIAL VESSEL ANGIOGENESIS IN ZEBRAFISH
[HTTP://ZFISH.NICHD.NIH.GOV/ZFATLAS/FLI-GFP/FLI_MOVIES.HTML](http://zfish.nichd.nih.gov/zfatlas/fli-gfp/fli_movies.html)

Example of Deterministic Models : **Angiogenesis**

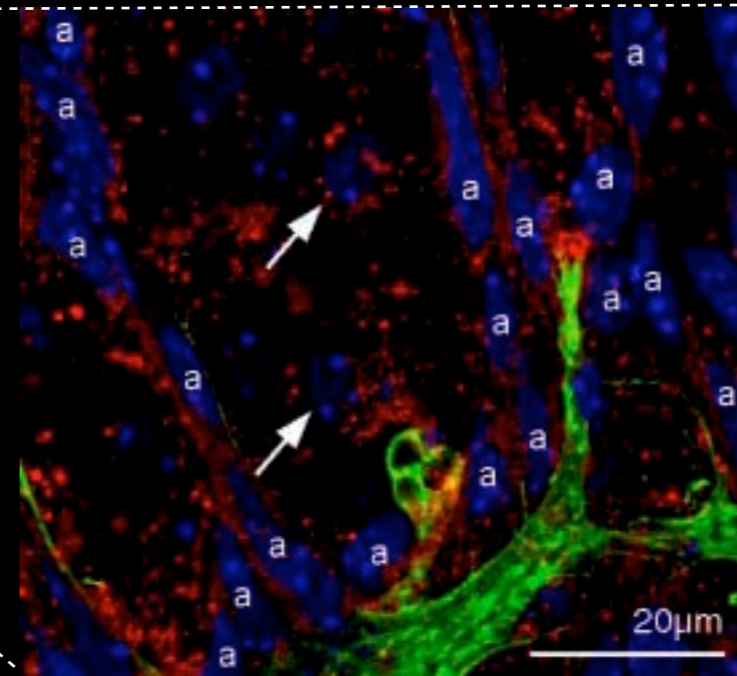
Tumor-Induced Angiogenesis



Tissue
Vessel Network



Cellular
Filopodia



Molecular
Growth factors

A Model of Sprouting Angiogenesis

Mechanism:

endothelial cells migrate towards source of growth factors

- form cords
- proliferate
- branch / fuse

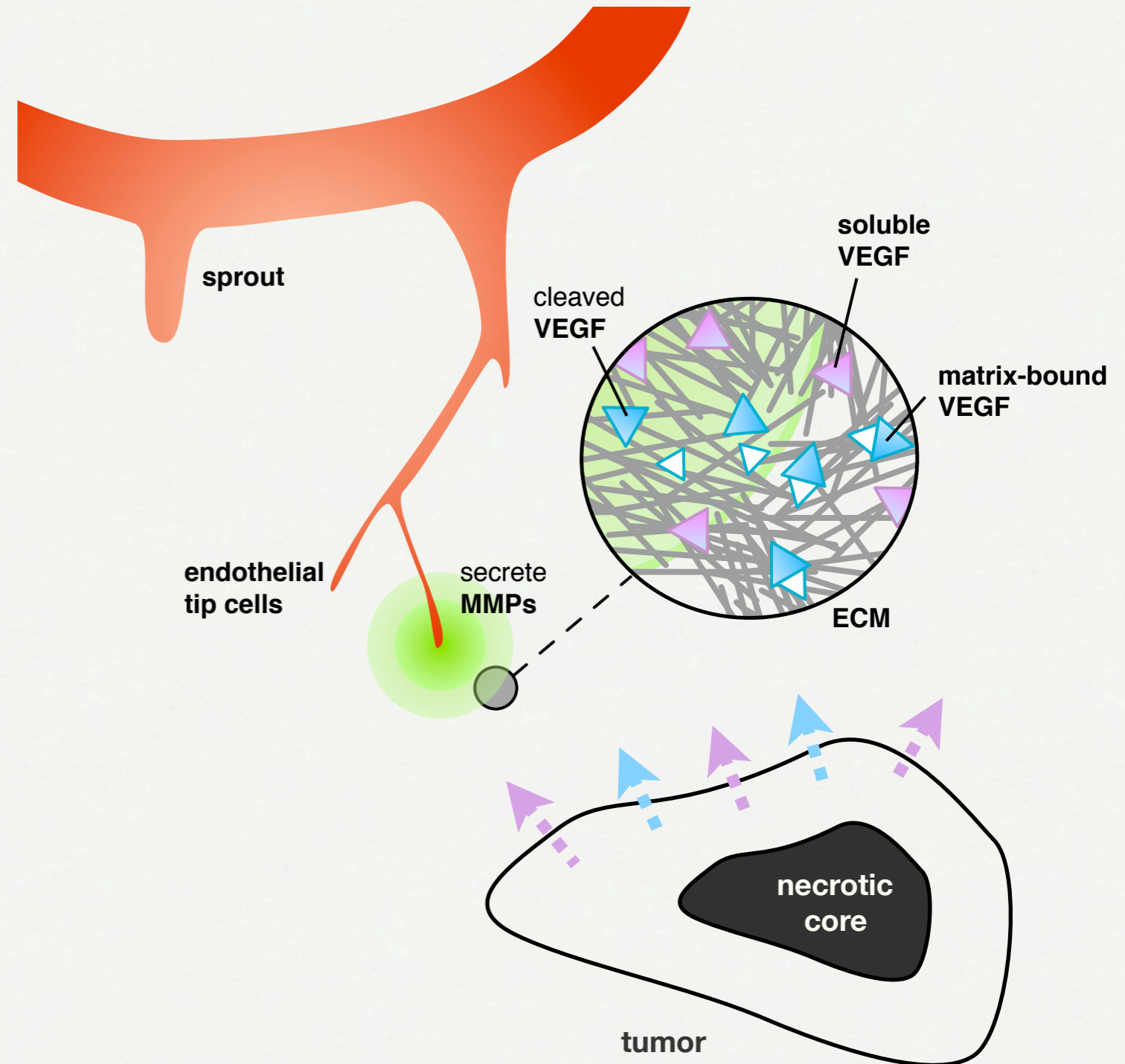
Growth factor: VEGF

exists in two forms:

- soluble
- bound to the matrix (bVEGF)

Release of bVEGF

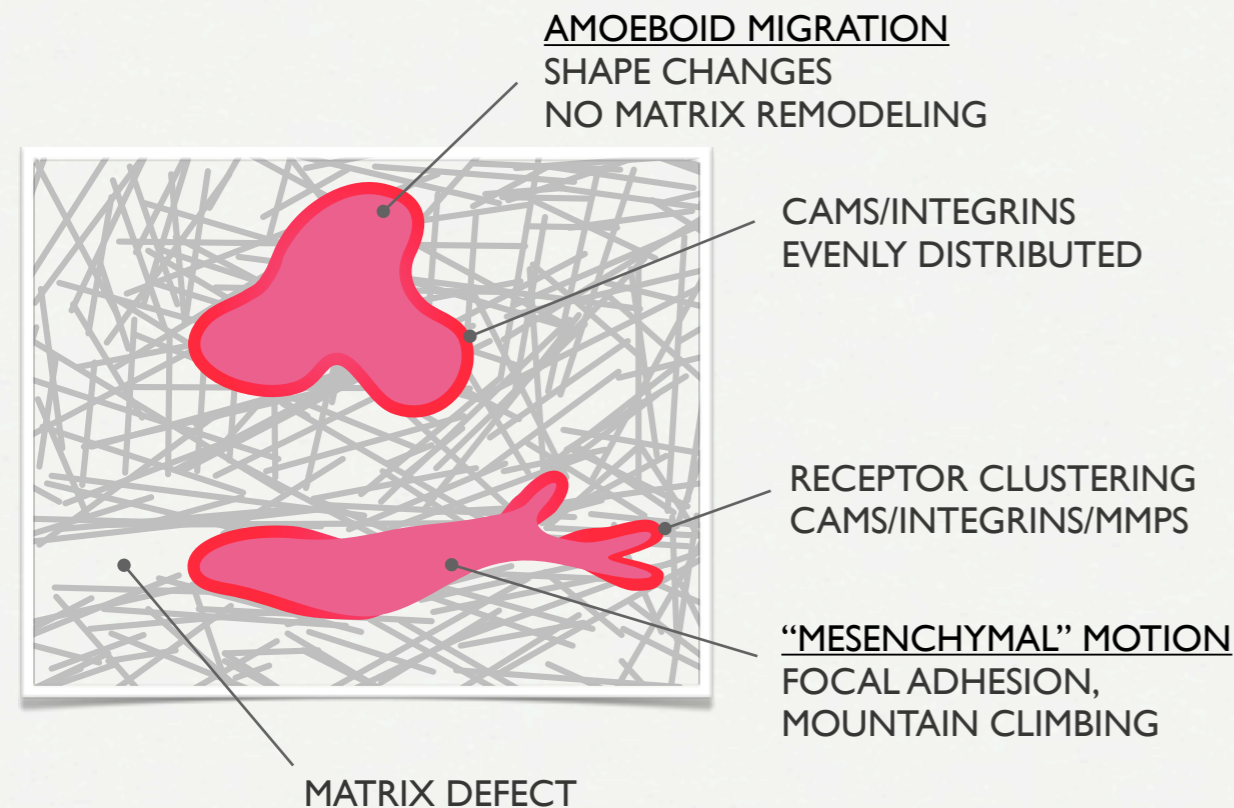
endothelial cells secrete proteinases
proteinases cleave bVEGF → soluble



Particle-mesh models for mesenchymal motion / PM4

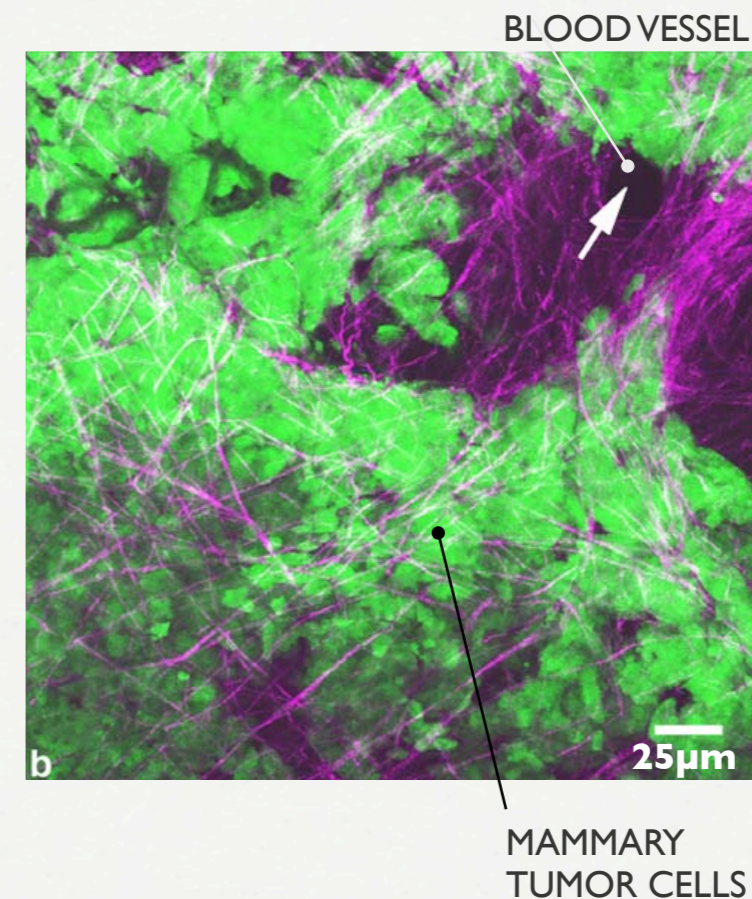
The Cell

- confined by semipermeable membrane
- inside: cytosol (fluid) & organelles
- cell adhesion molecules on the membrane
- extends filopodia for sensing



Extracellular Matrix

- fibrous proteins
- gels of polysaccharides
- sticky scaffolding
- structural support



[1] M. SIDANI, J. WYCKOFF, C. XUE, J. E. SEGALL, AND J. CONDEELIS. PROBING THE MICROENVIRONMENT OF MAMMARY TUMORS USING MULTIPHOTON MICROSCOPY. *JOURNAL OF MAMMARY GLAND BIOLOGY AND NEOPLASIA*, V11(2):151-163, 2006.

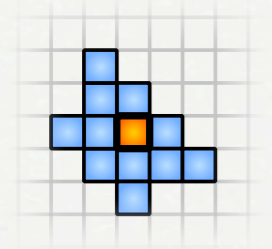
Representing Cells:

About scale:



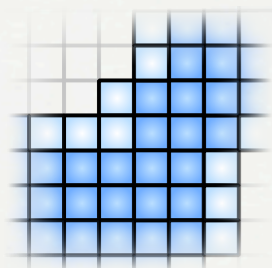
Cellular Potts

- shape optimization
- interaction energies



Cellular automaton

- intuitive
- behavioral rules
- one “cell” = one cell



Continuum

- cell density (= no individuals)
- PDEs

Continuum modeling of cells

Primary implications:

Cell density: $\rho(\mathbf{x}, t)$

$$\frac{\partial \rho}{\partial t} = - \underbrace{\nabla \cdot (\mathbf{u} \rho)}_{\text{MIGRATION}} + \underbrace{k \rho}_{\text{PROLIFERATION}}$$

Continuum cell-cell adhesion:

Existing continuum models:

either expensive (large radius of interaction), [1]
or expensive (leading to stiff PDEs) [2]

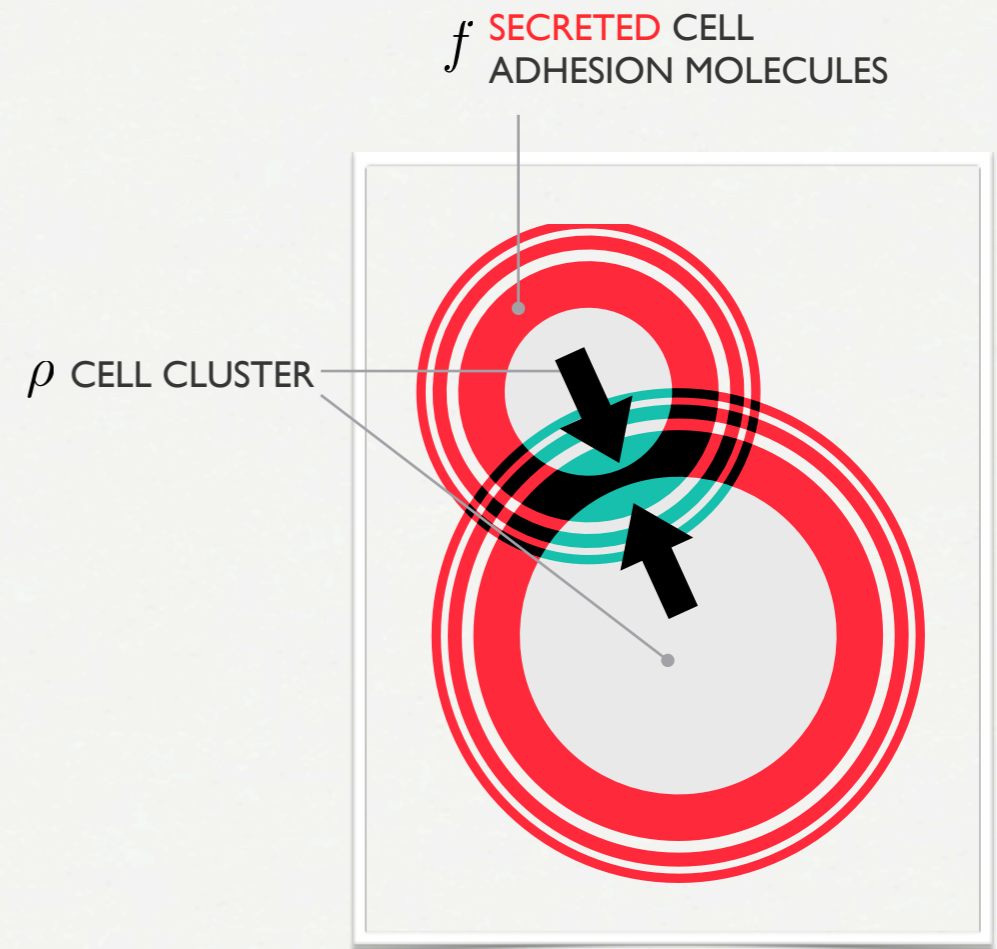
Cell-cell adhesion as cell “signaling”:

cells secrete adhesion molecules
cells follow gradient of these CAMs (autocrine signal)
the CAMs:

- diffuse (slow)
- decay (fast)

$$\mathbf{a}_{c2c,\rho} = \kappa \nabla f \quad \text{CELL-CELL ADHESION CONTRIBUTION TO MIGRATION}$$

$$\frac{\partial f}{\partial t} = \underbrace{\alpha \rho}_{\text{SECRETION}} - \underbrace{\mu f}_{\text{DECAY}} + \underbrace{D \Delta f}_{\text{DIFFUSION}}$$

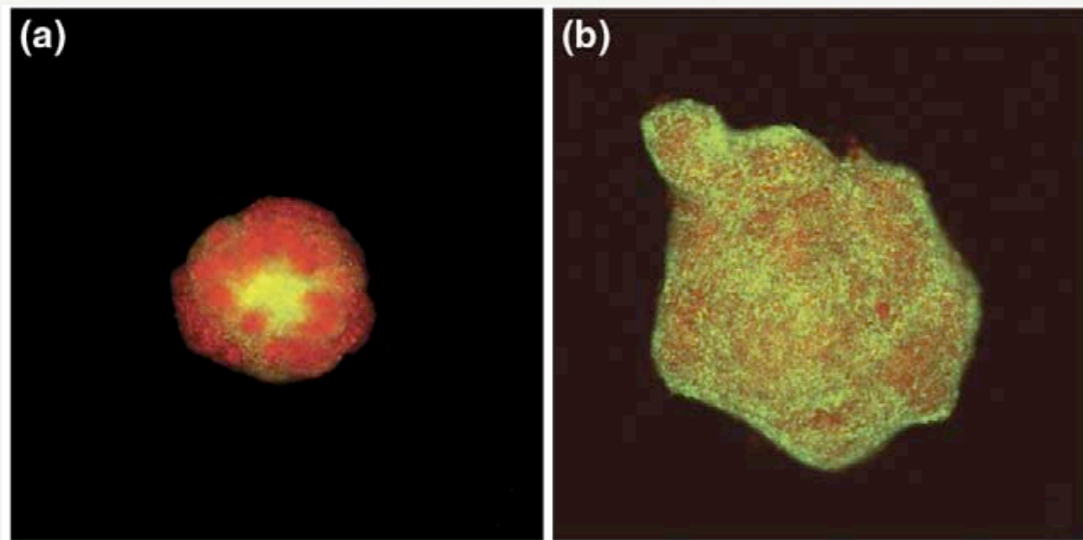


[1] N. J. ARMSTRONG, K. J. PAINTER, AND J. A. SHERRATT. A CONTINUUM APPROACH TO MODELLING CELL-CELL ADHESION. *J. THEOR. BIOL.*, 2006.

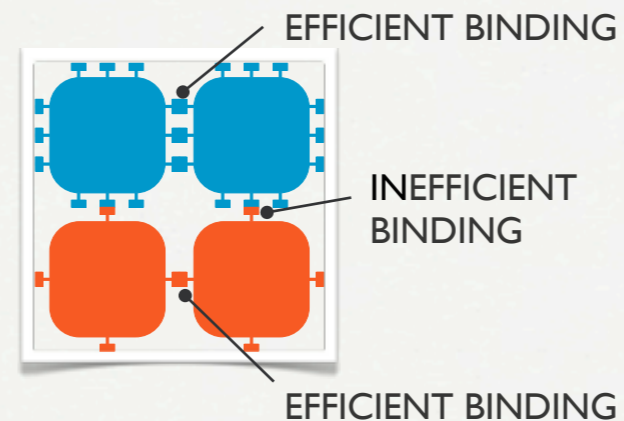
[2] J. KIM. A CONTINUOUS SURFACE TENSION FORCE FORMULATION FOR DIFFUSE-INTERFACE MODELS. *J. COMPUT. PHYS.*, 204(2):784–804, 2005.

The “differential adhesion hypothesis”

Cell sorting by differential adhesion



CELL SORTING a) VERSUS INTERMIXING b) IN PROSTATE CANCER [1]



$$a_{ij} = \kappa_{ij} \nabla f_j$$

e.g. sorting:

κ_{11} LARGE

$\kappa_{12} = \kappa_{21}$ SMALL

κ_{22} LARGE

$$\begin{aligned} \kappa_{11} &= 0.25 \\ \kappa_{22} &= 0.025 \\ \kappa_{12} = \kappa_{21} &= 0.05 \\ &+ \text{pressure due to close packing} \end{aligned}$$

$$\begin{aligned} \kappa_{11} &= 0.25 \\ \kappa_{22} &= 0.25 \\ \kappa_{12} &= 0.0 \\ \kappa_{21} &= 0.0 \end{aligned}$$

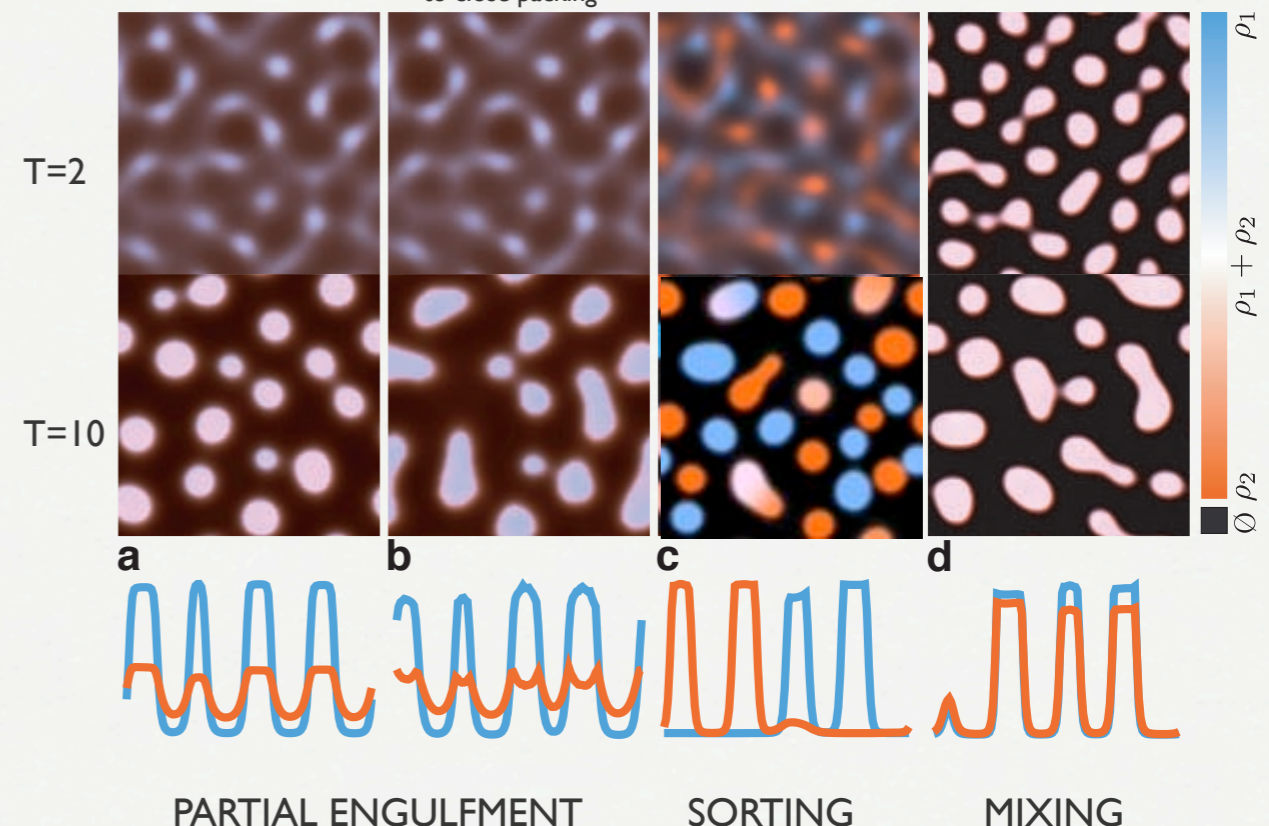
$$\begin{aligned} \kappa_{11} &= 0.25 \\ \kappa_{22} &= 0.09 \\ \kappa_{12} &= 0.2 \\ \kappa_{21} &= 0.2 \end{aligned}$$

$$\frac{\partial \rho_i}{\partial t} = -\nabla \cdot \left(\sum_j a_{ij} \rho_j \right) + d_i \Delta \rho_i$$

$i=1,2$ CELL DENSITIES, DISCRETIZED WITH PARTICLES

$$\frac{\partial f_i}{\partial t} = -\mu_i f_i + \alpha_i \rho_i + D_i \Delta f_i$$

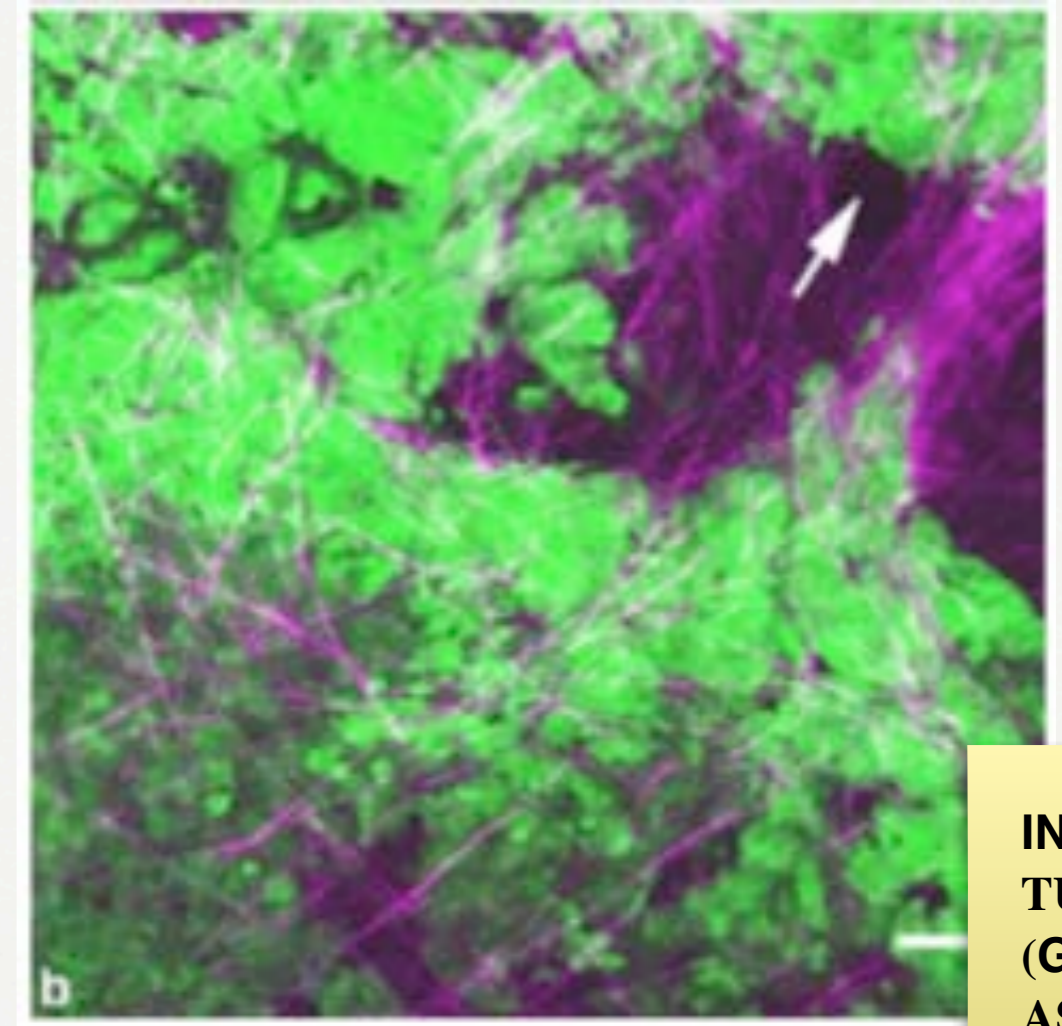
ARTIFICIAL CAM CONCENTRATIONS



[1] M. S. STEINBERG. DIFFERENTIAL ADHESION IN MORPHOGENESIS: A MODERN VIEW. *CURR. OPIN. GENET. DEV.*, 17(4):281–286, 2007.

Extracellular Matrix : Structure

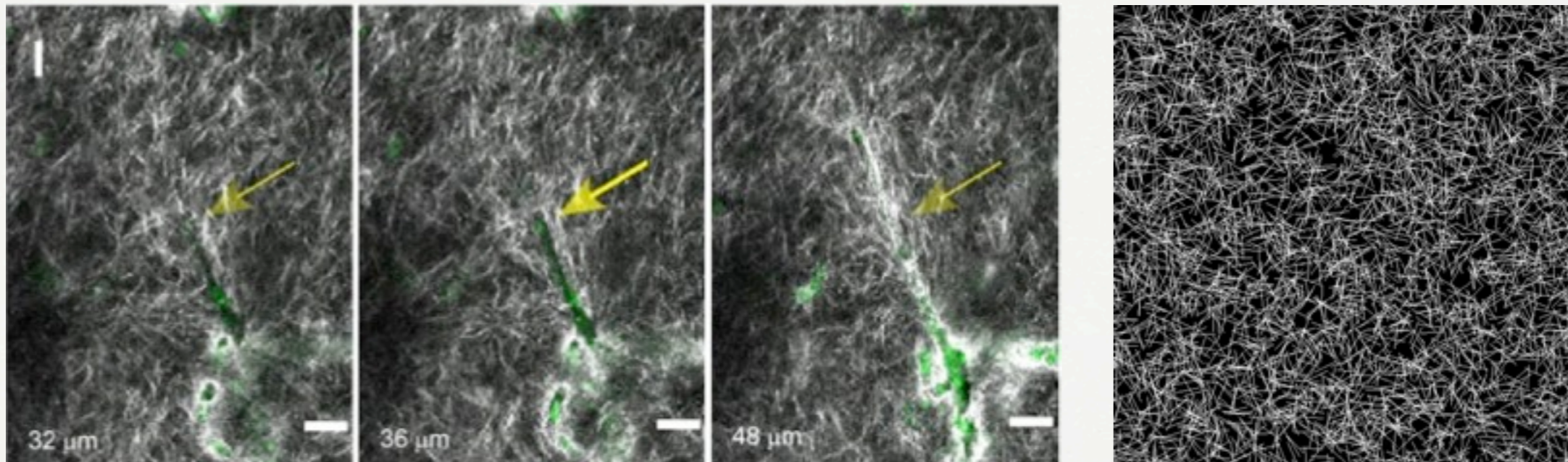
- Material occupying the space between cells
- Fibers of structural glycoproteins
(collagen, laminin and fibrillin are distributed throughout the ECM, occupying ~30% of the ECM)
- **Collagens** (the main component of the ECM cross-link with neighbouring collagens to form bundles)



IN M
TUM
(GR
ASSO
WIT
FIBR

Extracellular Matrix (ECM)

- Fibrous structures in ECM provide a guiding structure for migrating endothelial cells
- ECM fibers are subject of remodeling by migrating EC's
- The ECM expresses binding sites for various growth factors and integrins



Modeling the Matrix:

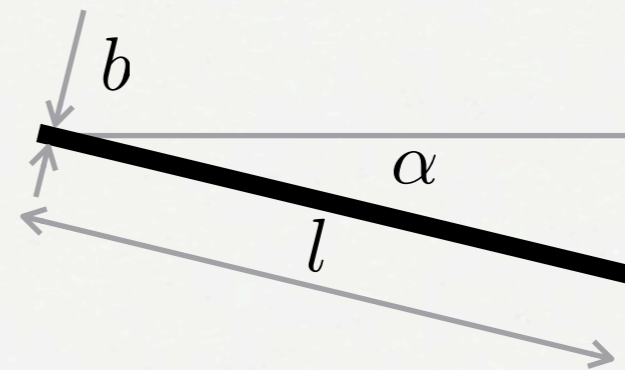
Model matrix explicitly:

- structure: collection of fiber bundles
- function: cell-matrix adhesion sites

Fibers:

- straight
- random direction
- distribution of lengths

$$l = l_0 2^{mz}$$
$$\alpha \in \mathcal{U}([0, \pi])$$
$$z \in \mathcal{N}(0, 1)$$



Indicator field ϵ

- unity where fibers present
- smoothed (implicit filopodia)



Endothelial Cell-ECM Interaction

- ECM fibers provide a guiding structure ($\underline{\mathbf{T}}$) for migrating ECs
- The ECM density E_ρ influences migration speed
- ECM expresses binding sites for matrix-bound VEGF and fibronectin

ECM density: $\alpha(E_\rho) = (0 + E_\rho)(1 - E_\rho)$

ECM direction: $\{\underline{\mathbf{T}}\}_{ij} = (1 - E_X) \{1\}_{ij} + E_X K_i K_j$

Migration Speed: $\mathbf{a} = \overbrace{\alpha(E_\rho)}^{\text{ECM}} \underline{\mathbf{T}} \left(\overbrace{w_V \nabla \Psi}^{\text{Chemotaxis}} + \overbrace{w_F \nabla \Phi_b}^{\text{Haptotaxis}} \right)$

Chemotaxis & cell-matrix adhesion

Opportunistic: get to growth factor (GF) source

Existing models: $\mathbf{a}_\phi = \nabla\phi$

PM4:

$\mathbf{a}_{\text{ecm},\phi} =$

$$\left[\left(1 - \left| \frac{\nabla e}{|\nabla e|} \cdot \frac{\nabla\phi}{|\nabla\phi|} \right| \right) \nabla e + \nabla\phi \right] (e + e_o) (\rho_{\text{cpd}} - e)$$

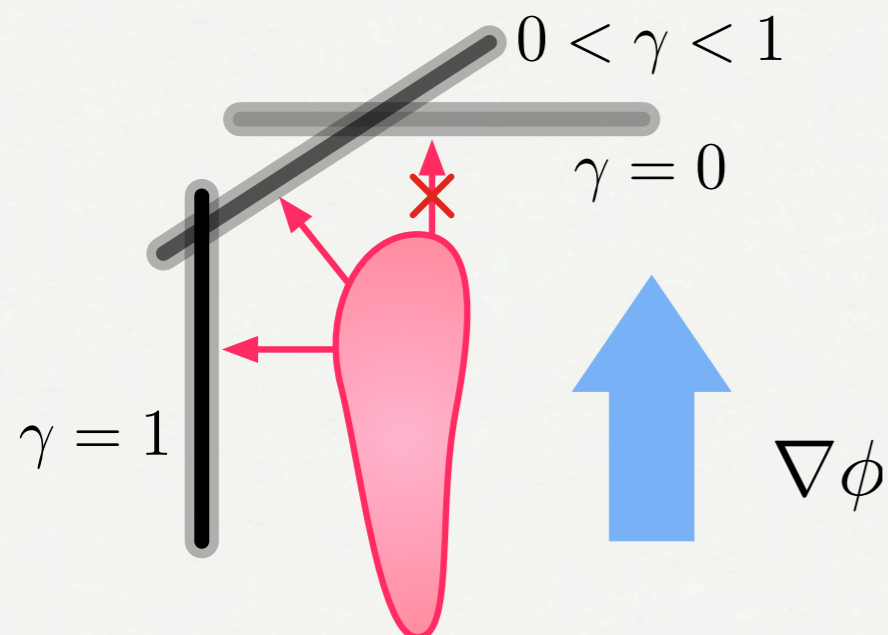
γ CLING TO FIBER
AN ADVANTAGE?

WHERE IS THE
FIBER?

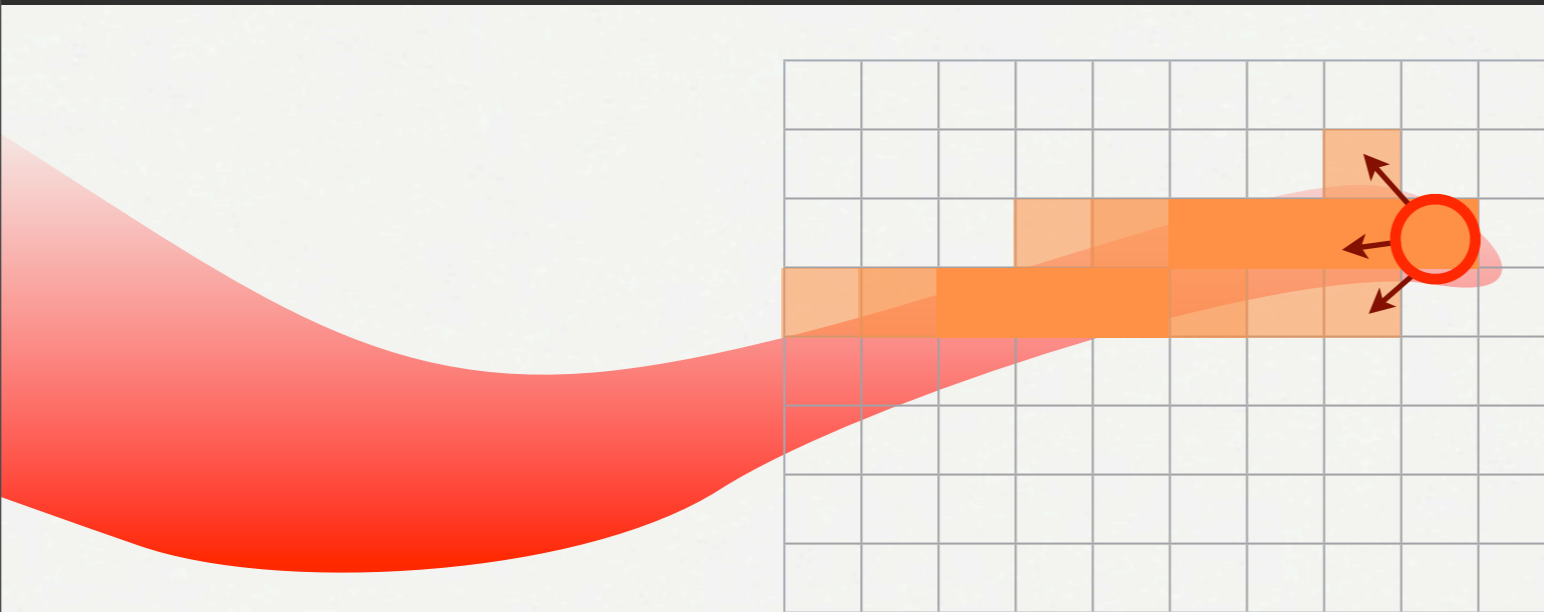
WHERE IS THE
GF SOURCE?

FIBERS FACILITATE
MIGRATION

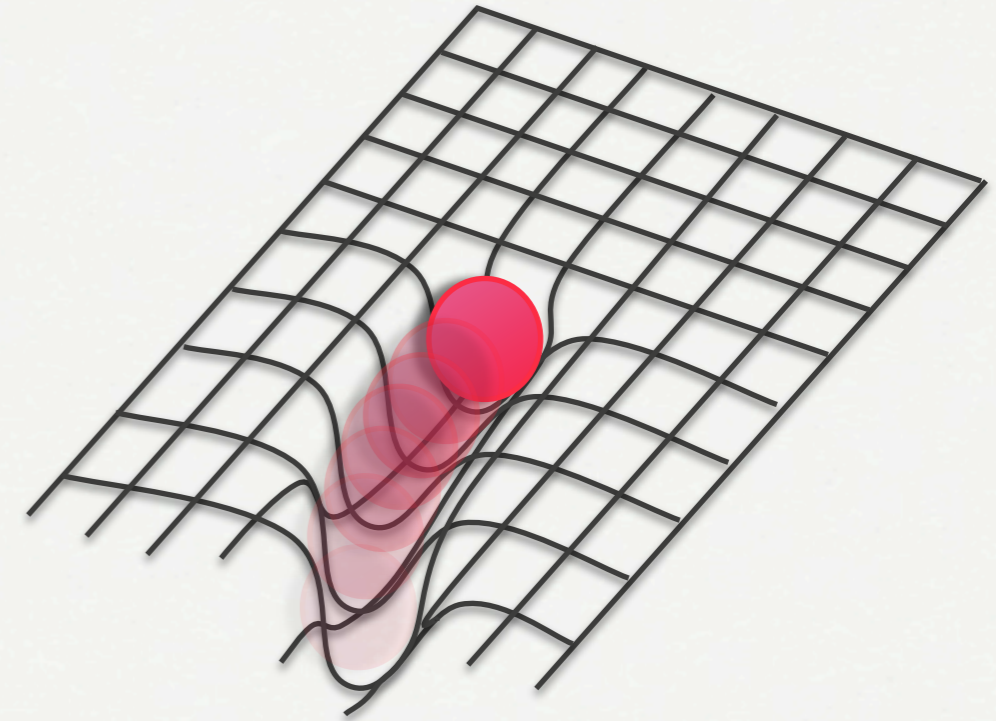
TOO MANY FIBERS
BLOCK MIG. PATH



Endothelial Cell representation



Tip Cell “deposes” endothelial cells



Hybrid representation of ECs:

Tip cell particles Q_p :

- Discrete particle representation
- Particle location: \mathbf{x}_p
- Migration acceleration: \mathbf{u}_p
- Drag coefficient: λ

$$\frac{\mathbf{x}_p}{\partial t} = \mathbf{u}_p, \quad \frac{\mathbf{u}_p}{\partial t} = \mathbf{a}_p - \lambda \mathbf{u}_p$$

Stalk cell density ρ :

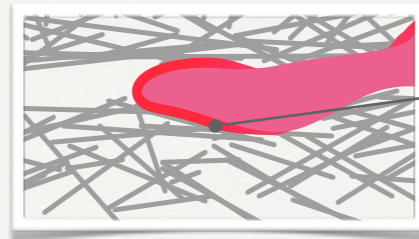
- Continuum vessel representation
- Tip and stalk communicate through Particle-Mesh, Mesh-Particle interpolations

$$\rho_i^{n+1} = \max \left(\rho_i^n, \sum_p B(\mathbf{i}h - \mathbf{x}_p) Q_p \right)$$

$$Q_p = \sum_i h^3 q_i M'_4(\mathbf{x}_p - \mathbf{i}h)$$

Tip Cell Migration

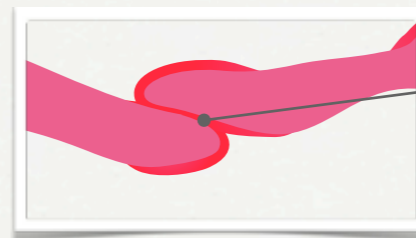
The elements of migration



cells are guided by extracellular matrix
transmembrane CAMs: integrins,...)
facilitates migration



cells sense chemical gradients
gradients of “chemoattractant” serve as
migratory cues



cells stick to cells
gradient of “haptotactic”
molecules serve as migration cues

Migration Speed

$$\mathbf{a} = \alpha (E_\rho) \underline{\mathbf{T}} (w_V \nabla \Psi + w_F \nabla \Phi_b)$$

Growth Factors: Assumptions

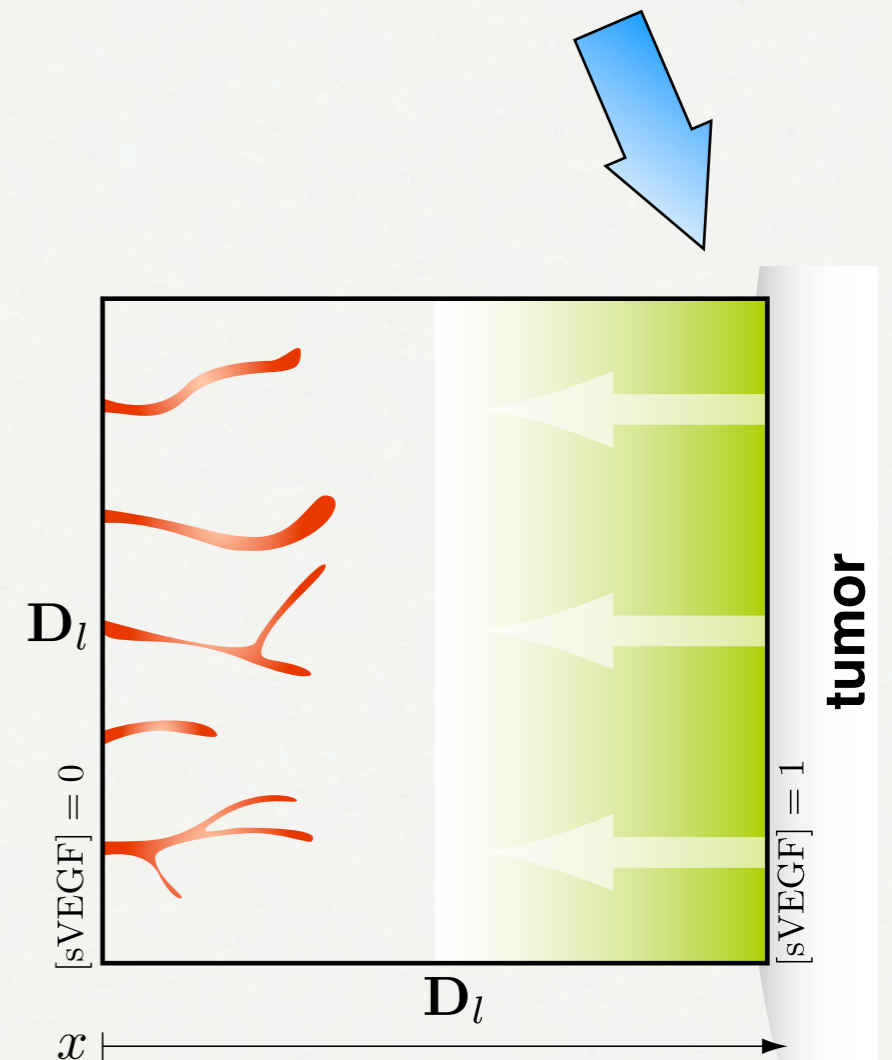
- We model only **one** representative growth factor (VEGF)
- VEGF exists in a **soluble** and a **matrix bound** isoform
- Soluble VEGF is **released** from a tumor source
- Unbound VEGF **diffuses** through the ECM
- VEGF is subject to **uptake** by endothelial cells
- **decays** naturally

Soluble VEGF (sVEGF) - Assumptions

- Model : One VEGF isoform in soluble and bound state
- **sVEGF** establishes global chemotactic gradient
 - Tumor source modeled by boundary conditions
 - sVEGF diffuses through ECM
 - Uptake of sVEGF by endothelial cells ρ
 - Subject of natural decay

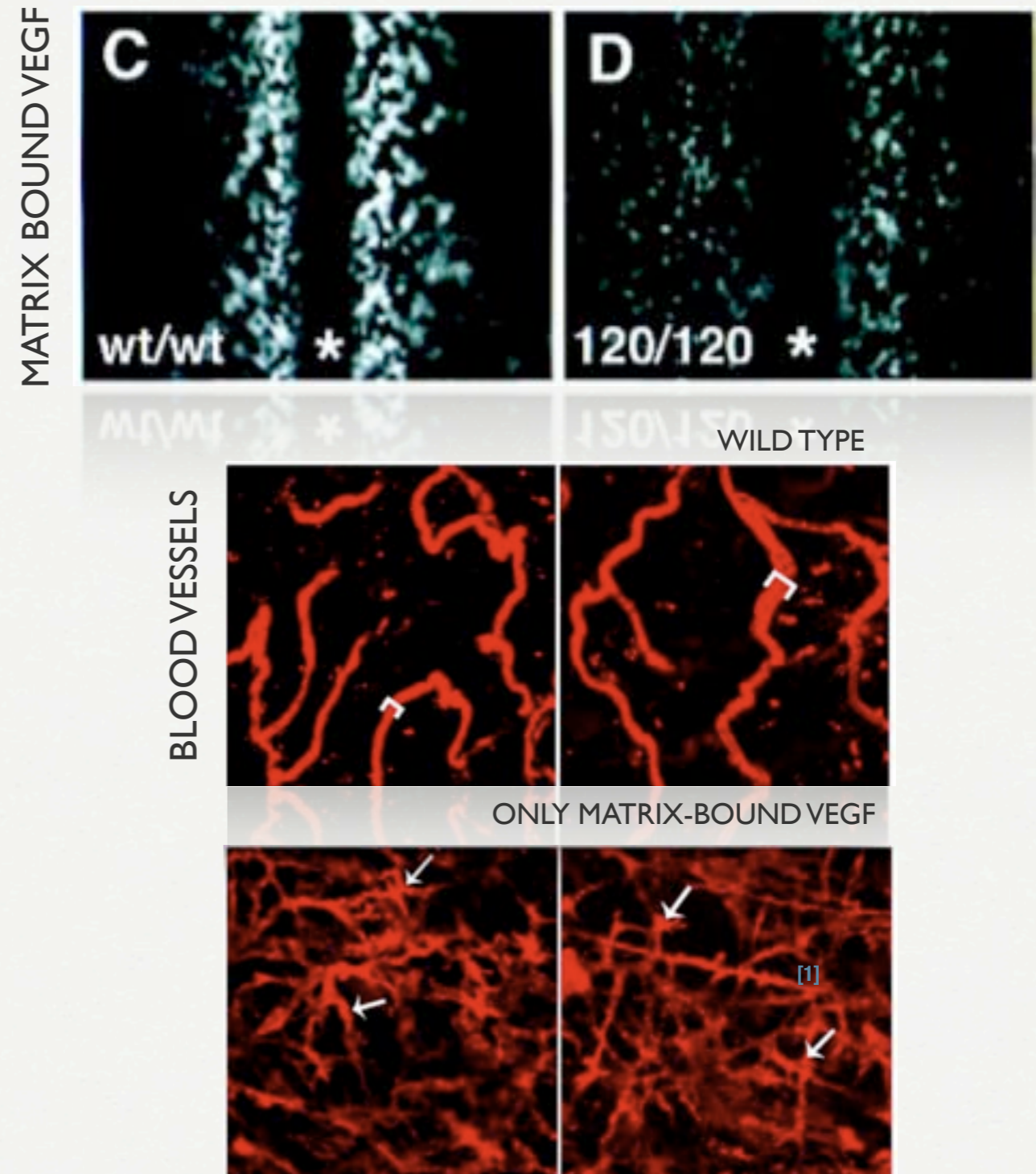
$$\frac{\partial [\text{sVEGF}]}{\partial t} = k_V \nabla^2 [\text{sVEGF}] - U([\text{sVEGF}], \rho) - \delta_V [\text{sVEGF}]$$

$$U([\text{sVEGF}], \rho) = \min([\text{sVEGF}], v_V \rho)$$



Matrix-bound VEGF (bVEGF)

- Some VEGF isoforms express heparin-binding sites **binding to domains in the ECM**
- **Local gradients** of matrix bound VEGF influence sprout morphology
- Matrix bound VEGF is cleaved by MMPs **released at endothelial sprout tips**

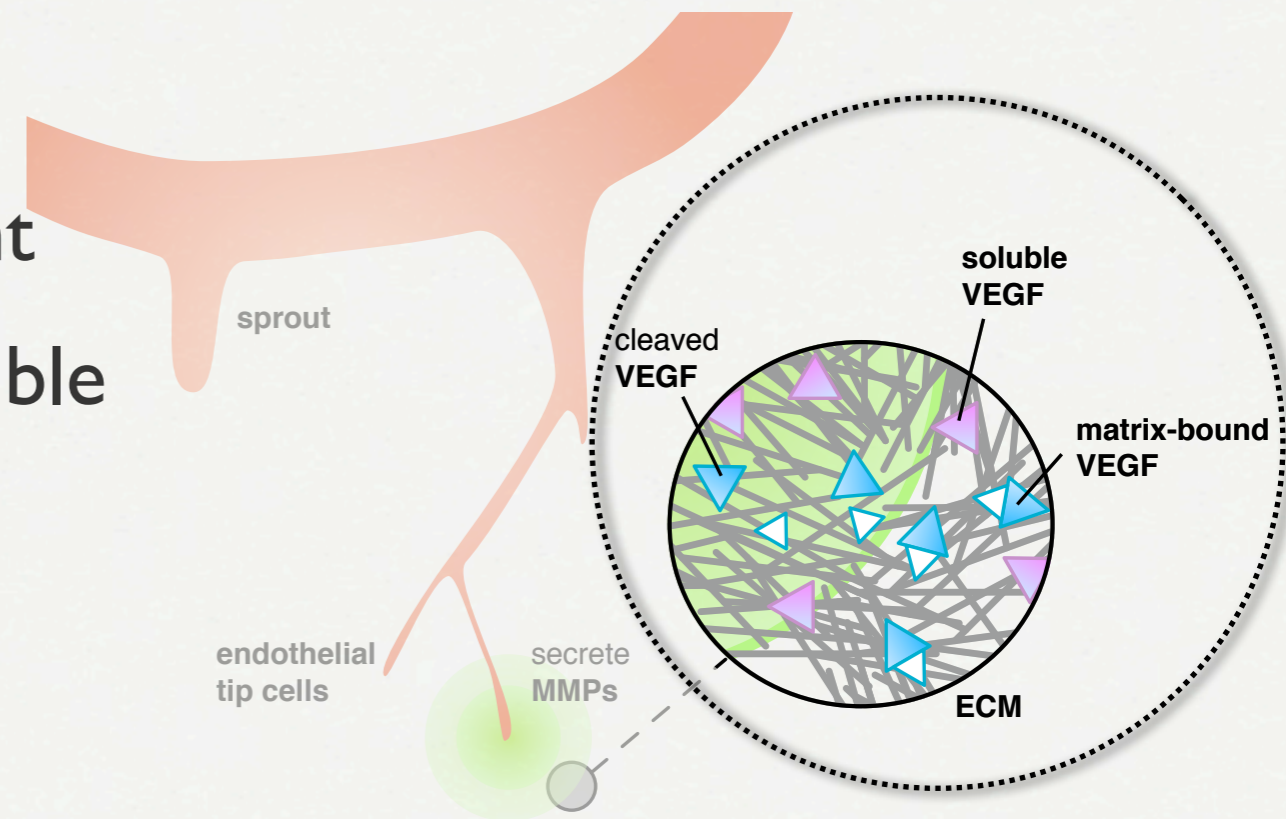


[1] C. RUHRBERG, H. GERHARDT, M. GOLDING, R. WATSON, S. IOANNIDOU, H. FUJISAWA, C. BETSHOLTZ AND D. T. SHIMA. SPATIALLY RESTRICTED PATTERNING CUES PROVIDED BY HEPARIN-BINDING VEGF-A CONTROL BLOOD VESSEL BRANCHING MORPHOGENESIS. *GENES DEV.*, 16(20):2684-2698, 2002.

[2] S. LEE, S. M. JILAI, G. V. NIKOLOVA, D. CARPIZO, AND M. L. IRUELA-ARISPE. PROCESSING OF VEGF-A BY MATRIX METALLOPROTEINASES REGULATES BIOAVAILABILITY AND VASCULAR PATTERNING IN TUMORS. *J. CELL BIOL.*, V42(3):195-238, 2001

Matrix-bound VEGF - Assumptions

- Initially distributed in pockets
- establishes local chemotactic gradient
- cleaved VEGF (**cVEGF**) becomes soluble
 - bVEGF is cleaved by MMPs
 - Uptake of cVEGF by ECs ρ
 - cVEGF diffuses through ECM
 - cVEGF is subject to natural decay



$$\frac{\partial[\text{bVEGF}]}{\partial t} = -C([\text{bVEGF}], [\text{MMP}]) - U([\text{bVEGF}], \rho)$$

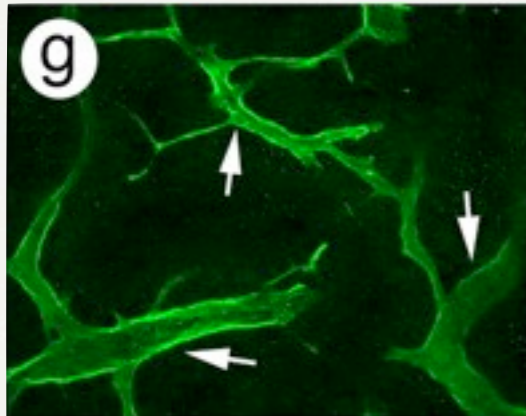
$$C([\text{bVEGF}], [\text{MMP}]) = \min([\text{bVEGF}], v_{bV}[\text{MMP}][\text{bVEGF}])$$

$$\frac{\partial[\text{cVEGF}]}{\partial t} = k_V \nabla^2[\text{cVEGF}] + C([\text{bVEGF}], [\text{MMP}]) - U([\text{cVEGF}], \rho) - \delta_V[\text{cVEGF}]$$

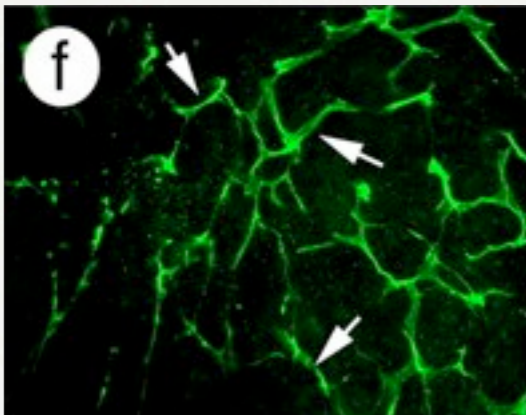
Angiogenesis: Post-dicting Experiments

Matrix-bound VEGF leads to **increased branching**.
vessel branching \leftrightarrow capillary function

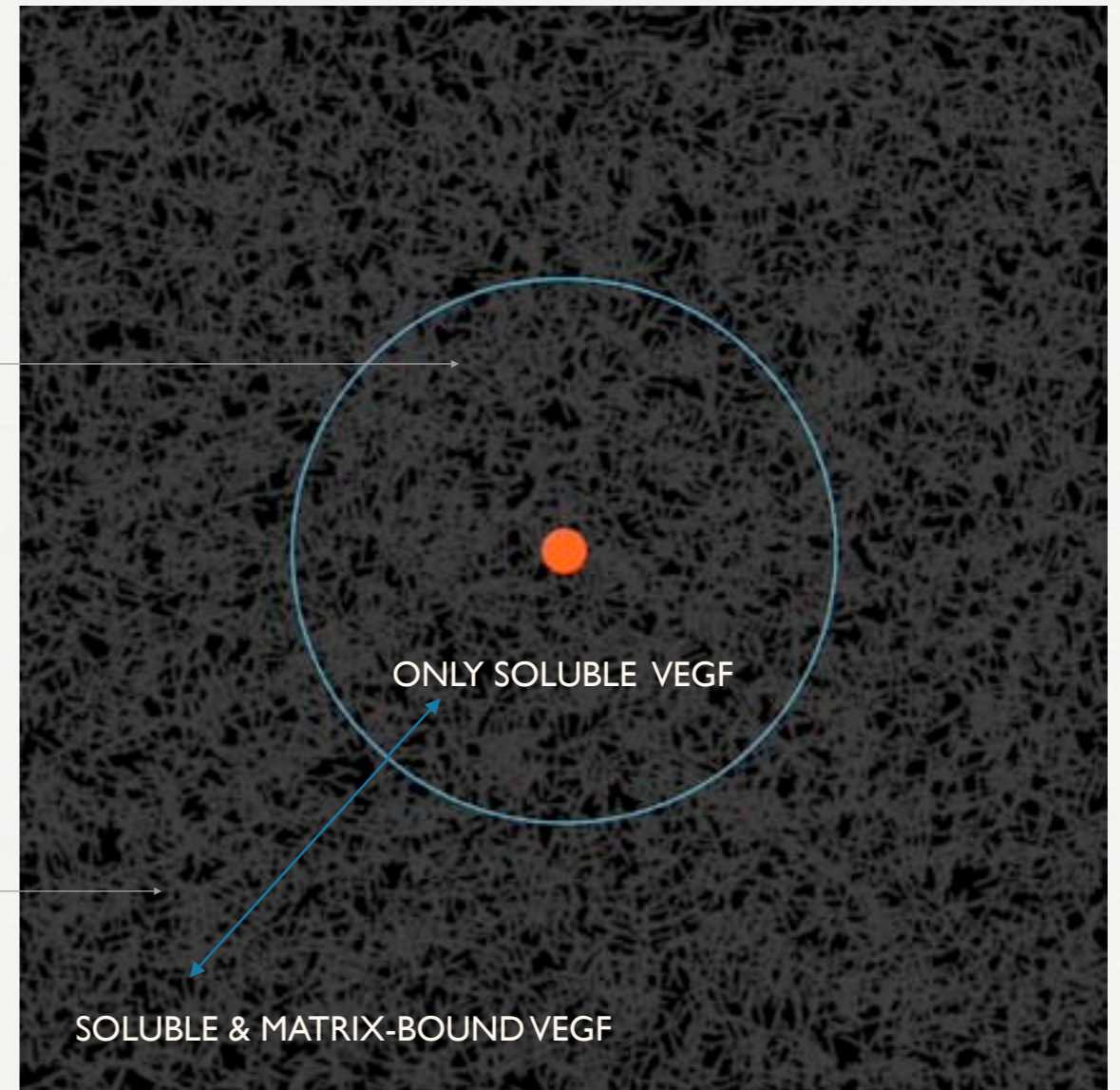
BLOOD VESSEL FORMATION IN A MOUSE MODEL



ONLY SOLUBLE VEGF
> THICKER VESSELS



SOLUBLE + MATRIX-BOUND VEGF
> INCREASED BRANCHING



RADIAL SOLUBLE VEGF GRADIENT AND
LOCALIZED MATRIX-BOUND VEGF

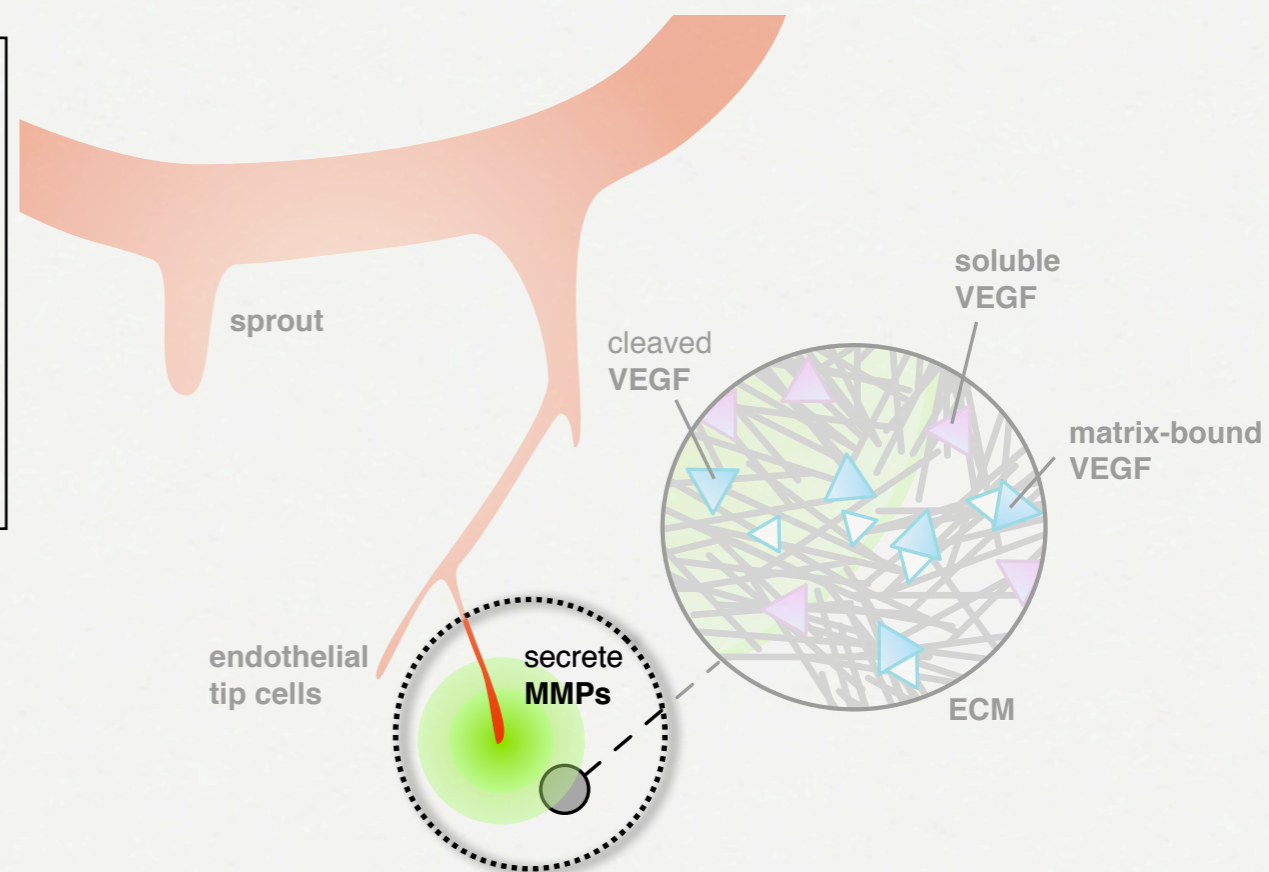
new: branching is an **output** of the simulation

[1] S. LEE, S. M. JILANI, G. V. NIKOLOVA, D. CARPIZO, AND M. L. IRUELA-ARISPE. PROCESSING OF VEGF-A BY MATRIX METALLOPROTEINASES REGULATES BIOAVAILABILITY AND VASCULAR PATTERNING IN TUMORS. *J. CELL BIOL.*, 169(4):681–691, 2005.

MATRIX METALLOPROTEINASES

- decreases local chemotactic gradients

- RELEASED BY MIGRATING TIP-CELLS
- RELEASE BOUND BY THRESHOLD LEVEL
- DIFFUSE THROUGH ECM
- SUBJECT TO NATURAL DECAY



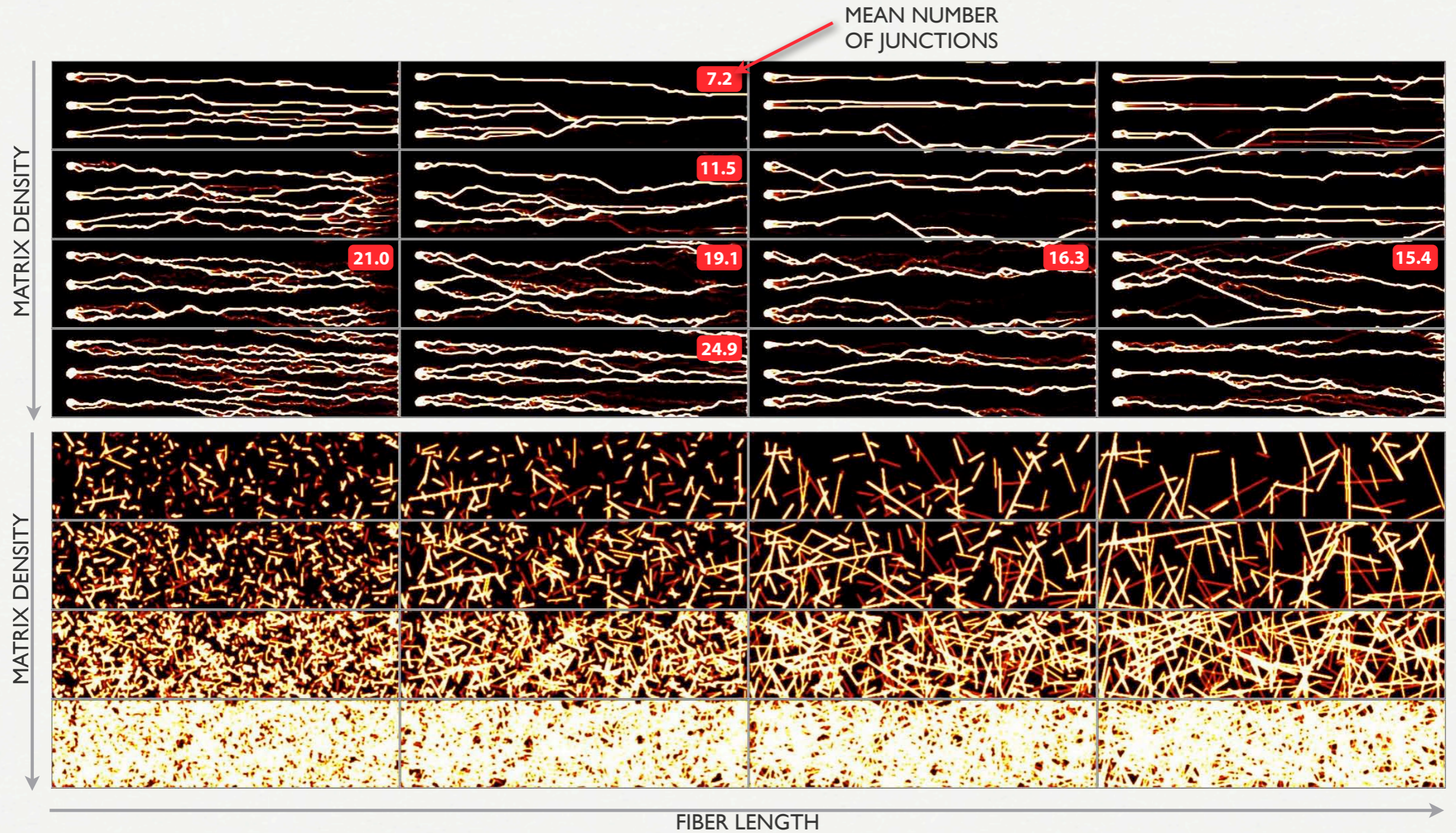
$$\frac{\partial [\text{MMP}]}{\partial t} = k_M \nabla^2 [\text{MMP}] + \gamma_M G(M_{th}, [\text{MMP}]) [\text{EC}] - \delta_M [\text{MMP}]$$

$$G(M_{th}, [\text{MMP}]) = \frac{M_{th} - [\text{MMP}]}{M_{th}}$$



Milde F., Bergdorf M., Koumoutsakos P., A hybrid model of sprouting angiogenesis, **Biophysical J.** 2008

Effect of Matrix structure on branching - Mesenchymal cells



statistics over n = 50 different matrices
junctions identified with AngioQuant



Texas

COLLABORATION

When you want to build a ship,
then do not drum the men together
in order to procure wood,
to give instructions or to distribute work;
but teach them longing for the wide endless sea
Antoine de Saint-Exupery

SEPTEMBER 13, 1942 — A.M.

What Next ?

Multiscaling

Open Source Software

Mathematicians in Labs

Computer Science



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