

# Theoretical and computational approaches to parallel replica dynamics

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# Outline

- 1 Parallel Replica Dynamics
  - Decorrelation Step
  - Dephasing Step
  - Parallel Step
- 2 Main Results
  - QSD — Exponential First Exit Time
  - Decorrelation Step
  - Parallel Step
- 3 Computational Experiments
- 4 References

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# The Parallel Replica Algorithm

The Parallel Replica Algorithm proposed by A.F. Voter in 1998 is a method to accelerate a “coarse-grained projection” of a dynamics. We consider the overdamped Langevin dynamics:

$$dX_t = -\nabla V(X_t) dt + \sqrt{2\beta^{-1}} dW_t$$

and we assume that we are given a smooth mapping

$$\mathcal{S} : \mathbb{R}^d \rightarrow \mathbb{N}$$

which to a configuration in  $\mathbb{R}^d$  associates a state number (e.g., a numbering of the wells of the potential  $V$ ).

The goal of the parallel replica dynamics is to generate very efficiently a trajectory  $(S_t)_{t \geq 0}$  which has (almost) the same law as  $(\mathcal{S}(X_t))_{t \geq 0}$ .

# The Parallel Replica Algorithm

Initialization: Consider an initial condition  $X_0^{ref}$  for a reference walker, the associated initial state  $S_0 = \mathcal{S}(X_0^{ref})$ , and a simulation time counter  $T_{simu} = 0$ .

One iteration of the algorithm goes through three steps.

- The decorrelation step: Let the reference walker  $(X_{T_{simu}+t}^{ref})_{t \geq 0}$  evolve over a time interval  $t \in [0, \tau_{corr}]$ . Then,
  - If the process leaves the well during the time interval (*i.e.*,  $\exists t \leq \tau_{corr}$  such that  $\mathcal{S}(X_{T_{simu}+t}^{ref}) \neq \mathcal{S}(X_{T_{simu}}^{ref})$ ) advance the simulation clock by  $\tau_{corr}$  and restart the decorrelation step ;
  - otherwise, advance the simulation clock by  $\tau_{corr}$  and proceed to the dephasing step.

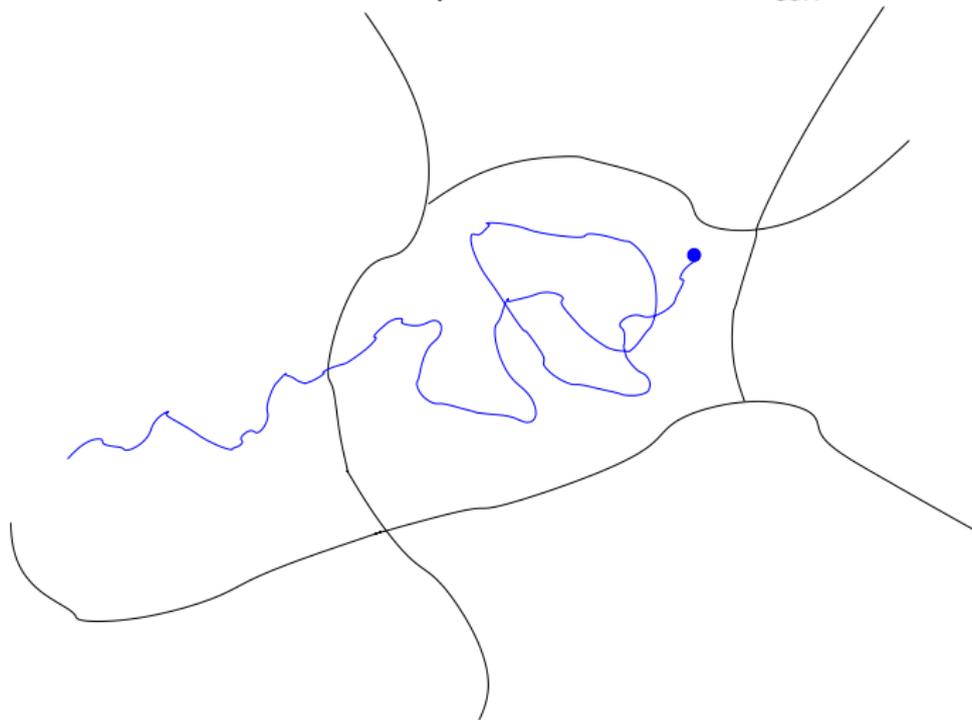
# The Parallel Replica Algorithm

The reference walker enter a new state



# The Parallel Replica Algorithm

Decorrelation step: wait for a time  $\tau_{corr}$ .



- The dephasing step: Duplicate the walker  $X_{T_{simu}}^{ref}$  into  $N$  replicas. Let these replicas evolve independently and in parallel over a time interval of length  $\tau_{dephase}$ . If a replica leaves the well during this time interval, restart the dephasing step for this replica. Throughout this step, the simulation counter is stopped.

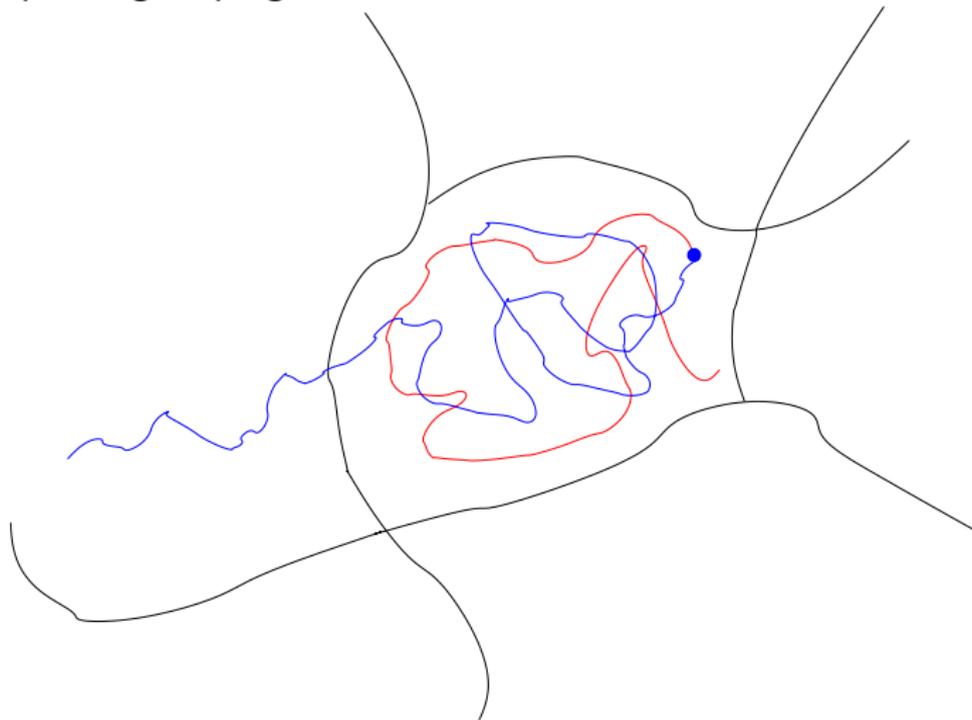
# The Parallel Replica Algorithm

Dephasing step.



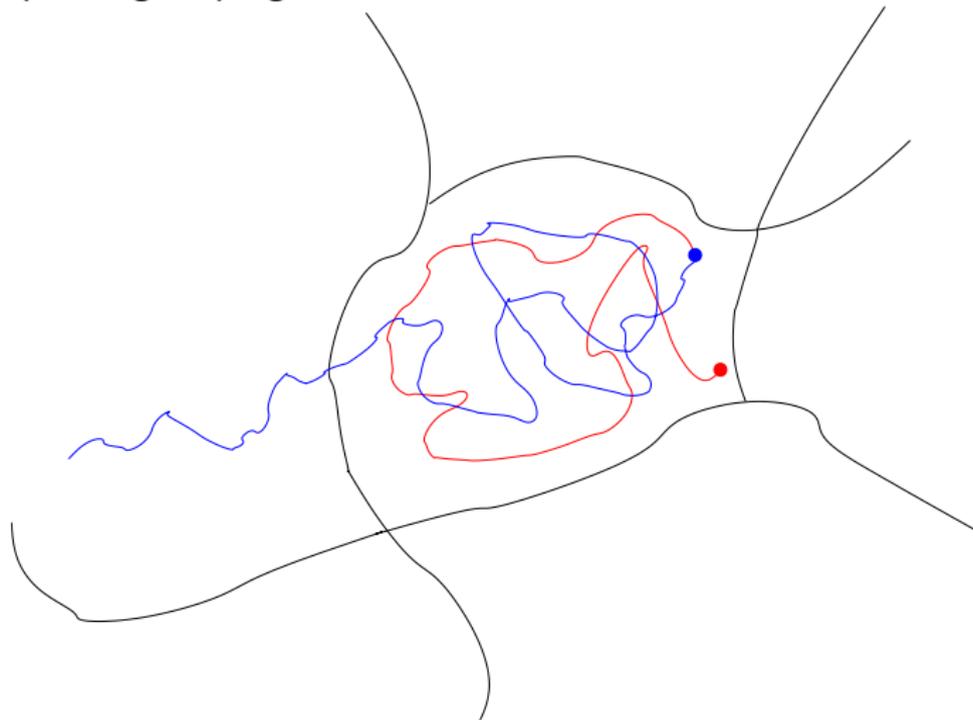
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Dephasing step: generate new initial conditions in the state.



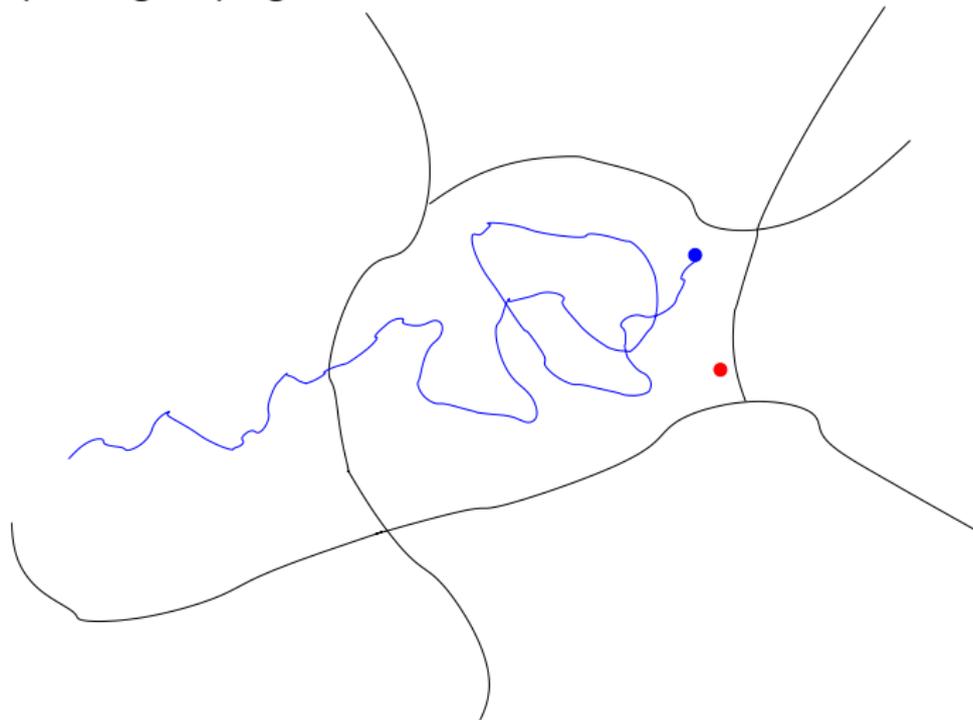
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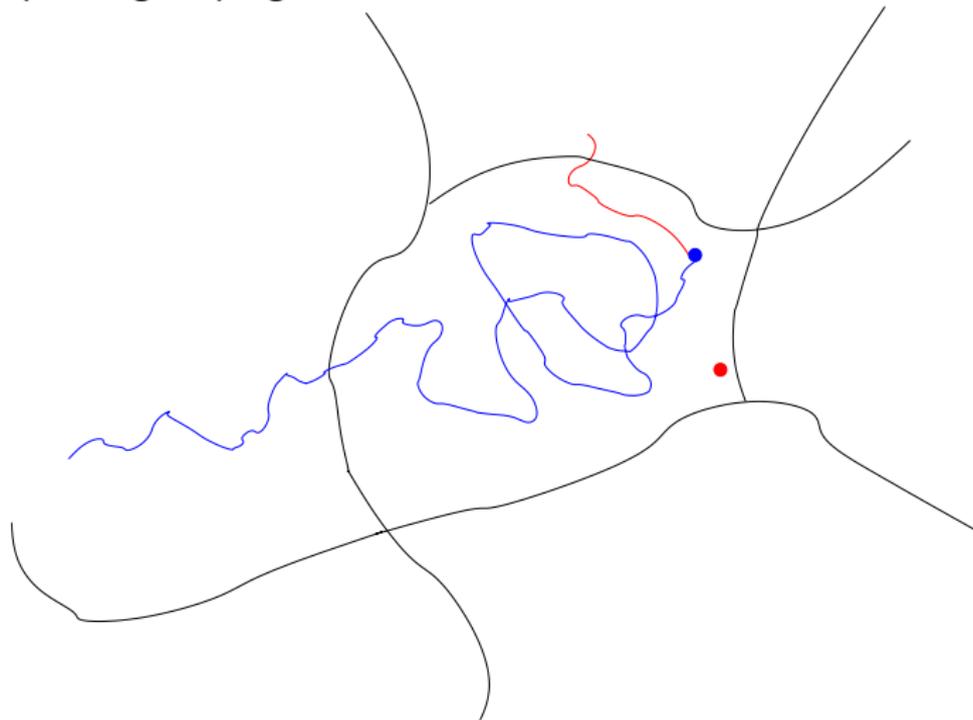
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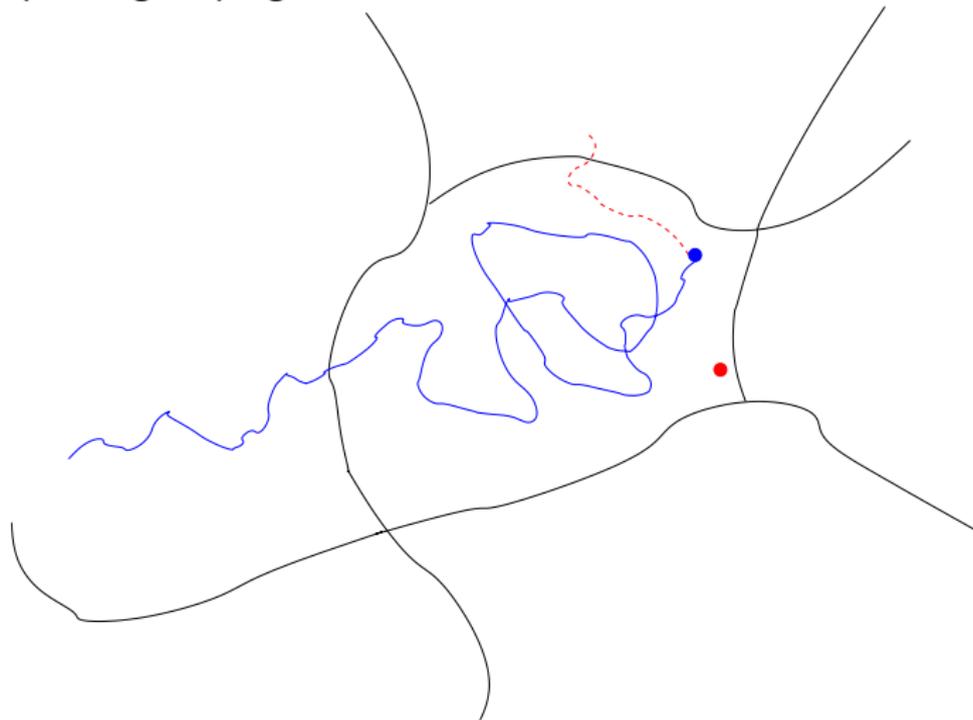
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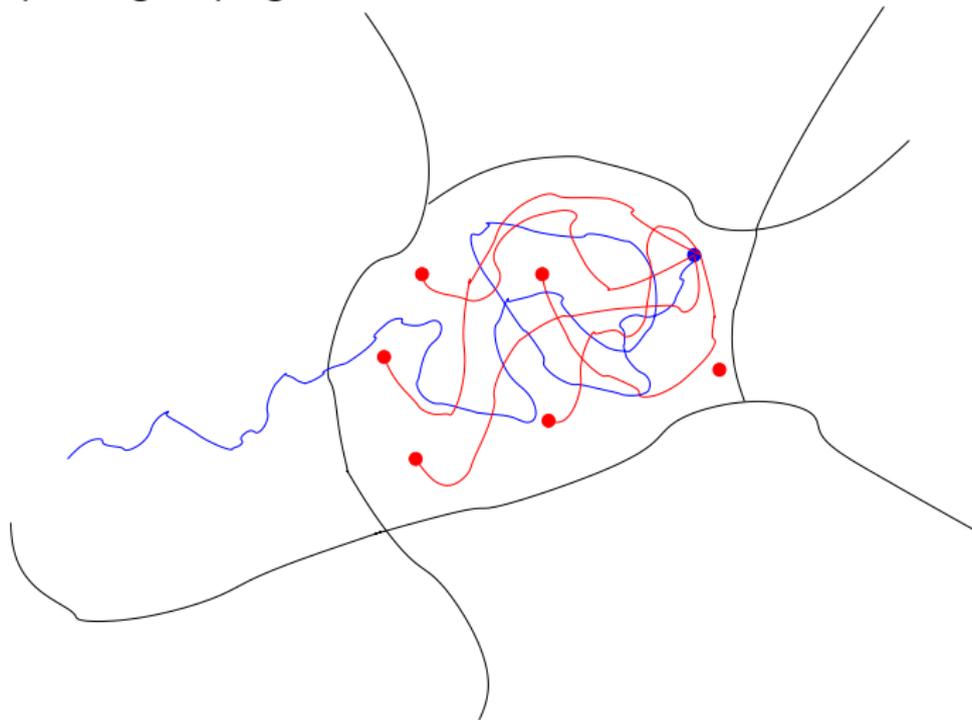
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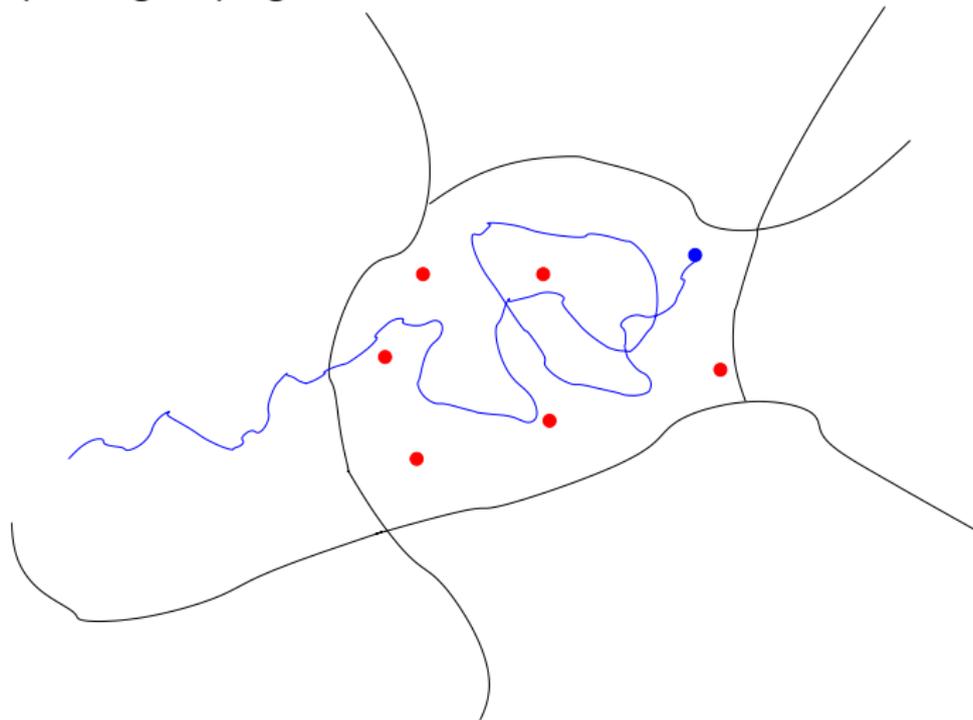
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Dephasing step: generate new initial conditions in the state.



- The parallel step: Let all the replicas evolve independently and track the first escape event:

$$T = \inf_k T_W^k = T_W^{K_0},$$

where  $K_0 = \arg \inf_k T_W^k$  and

$$T_W^k = \inf\{t \geq 0, \mathcal{S}(X_{T_{simu}+t}^k) \neq \mathcal{S}(X_{T_{simu}}^k)\}$$

is the first time the  $k$ -th replica leaves the well. Then:

$$T_{simu} = T_{simu} + NT \text{ and } X_{T_{simu}+NT}^{ref} = X_{T_{simu}+T}^{K_0}.$$

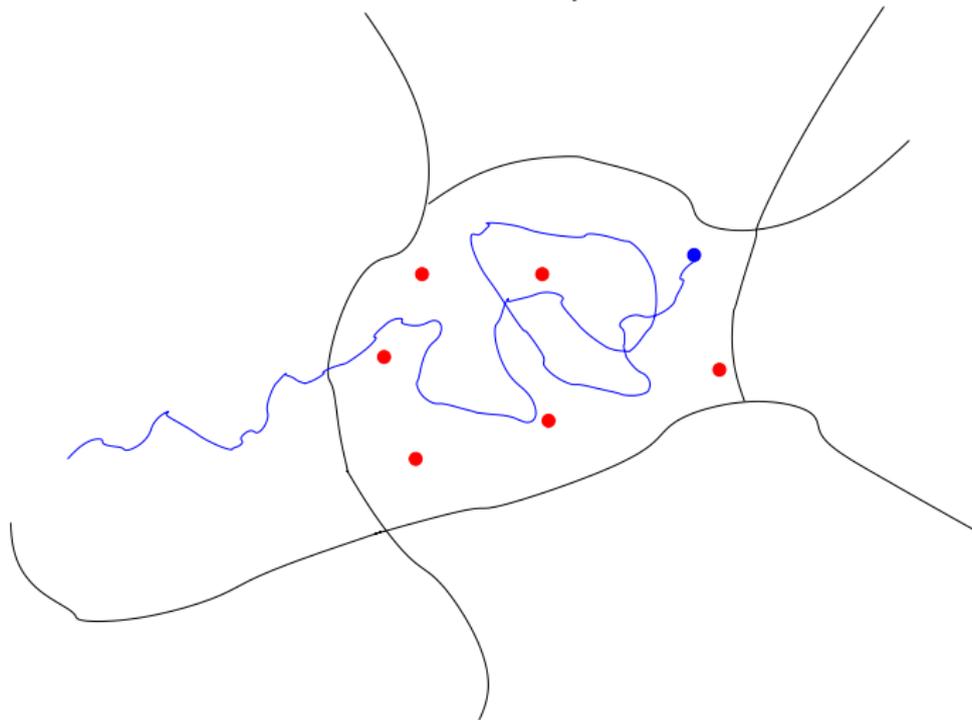
Moreover, over  $[T_{simu}, T_{simu} + NT]$ , the state dynamics  $S_t$  is constant and defined as:

$$S_t = \mathcal{S}(X_{T_{simu}}^1).$$

Then, go back to the decorrelation step...

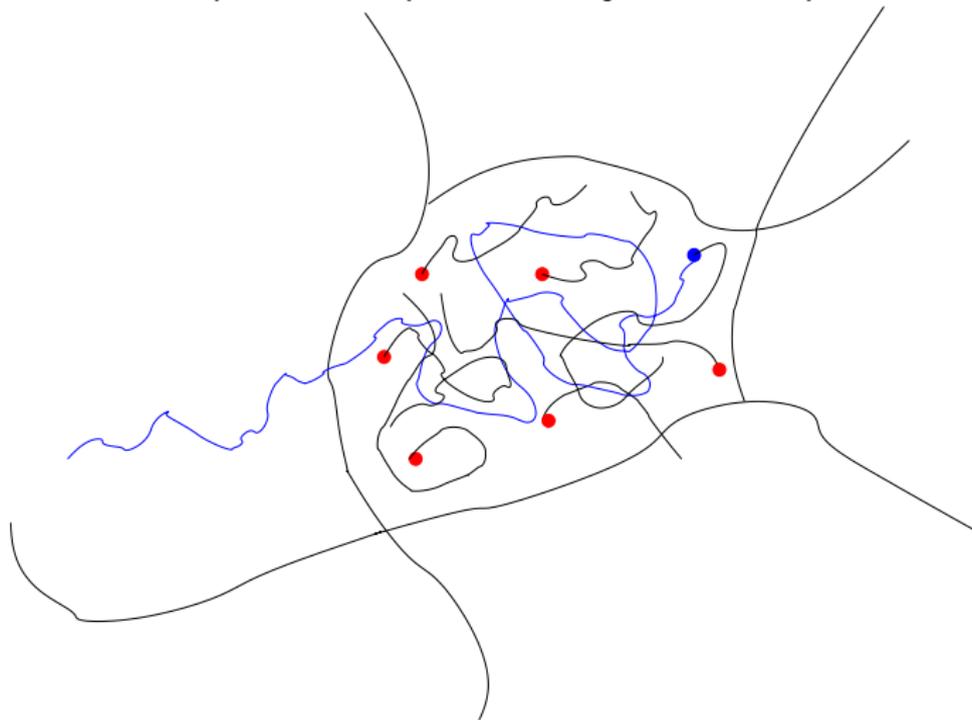
# The Parallel Replica Algorithm

Parallel step.



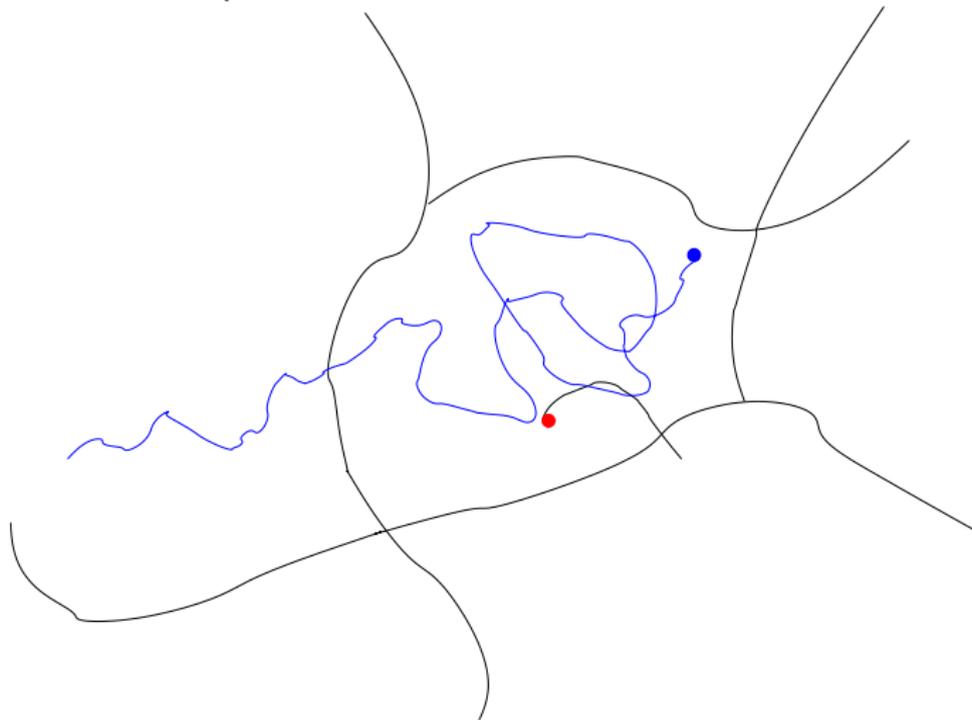
# The Parallel Replica Algorithm

Parallel step: run independent trajectories in parallel...



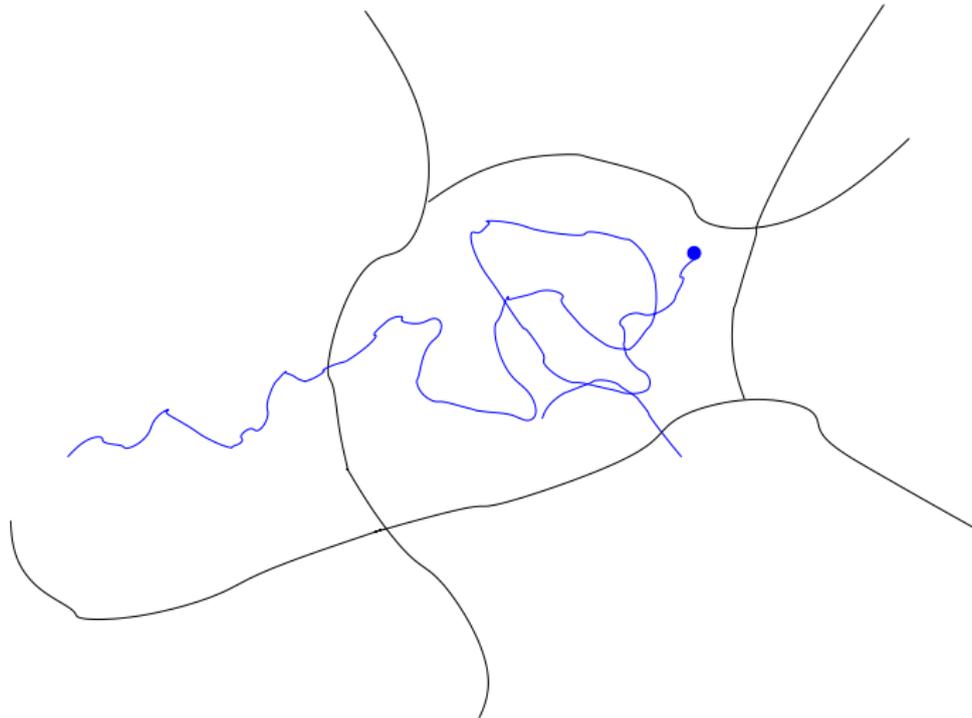
# The Parallel Replica Algorithm

Parallel step: ... and detect the first transition event.



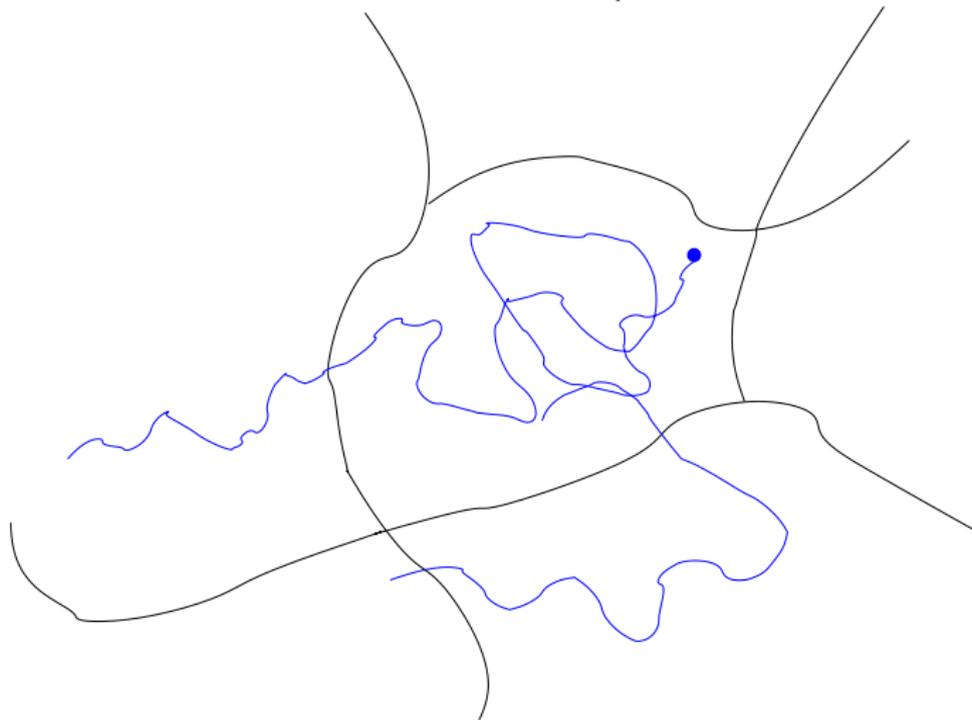
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Parallel step: update the time clock:  $T_{simu} = T_{simu} + NT$ .



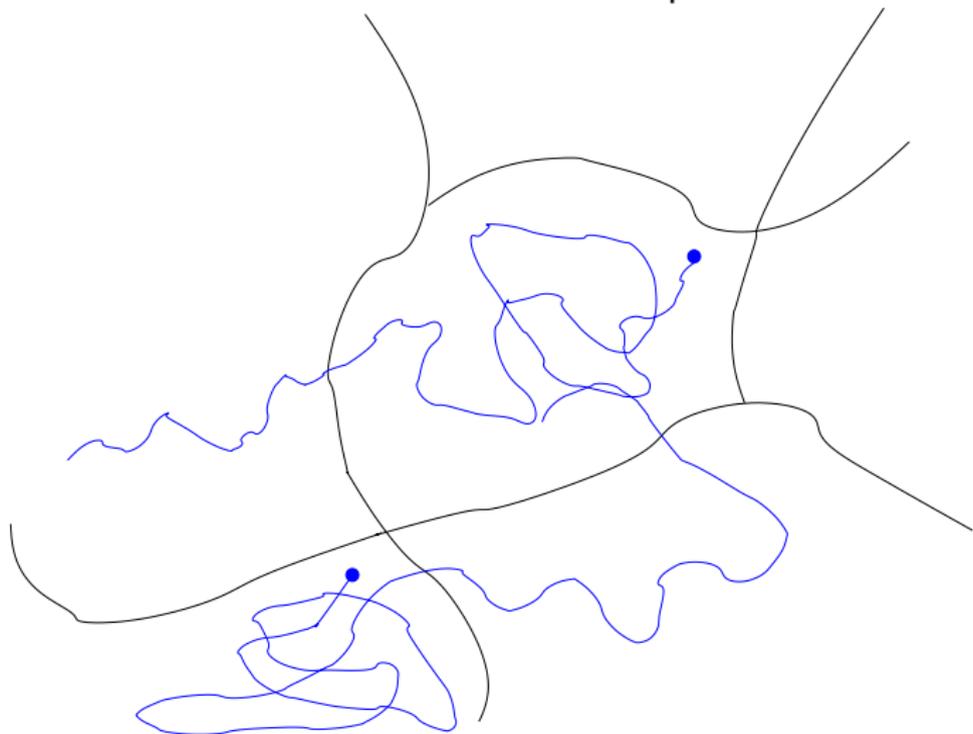
# The Parallel Replica Algorithm

A new decorrelation step starts...



# The Parallel Replica Algorithm

New decorrelation step



# Error analysis for the Parallel Replica Algorithm

The parallel step would introduce no error if

- the escape time  $T_W^1$  was exponentially distributed
- and independent of the next visited state.

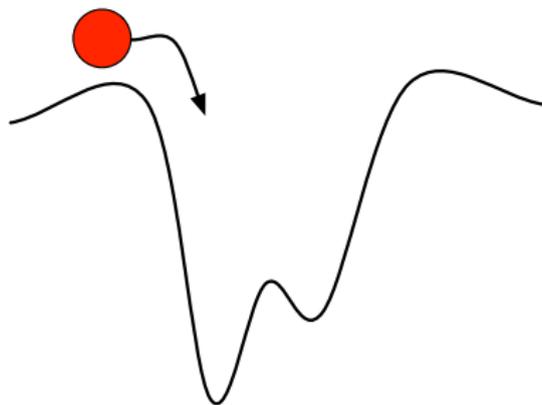
How can we analyze the error introduced by the algorithm ?

# Parallel Replica Dynamics – Steps

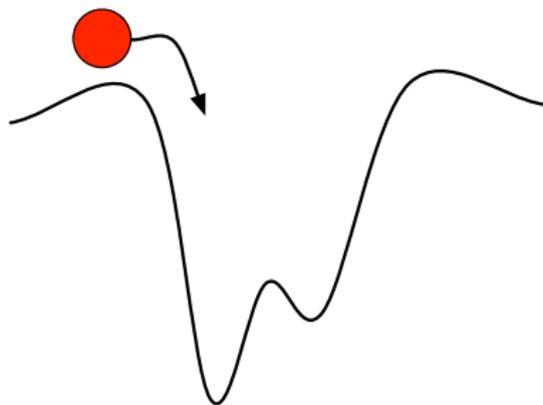
## Escaping a Single Well

- 1 Decorrelation Step – Let a reference process sample a well for some time
- 2 Dephasing Step – Simultaneously create independent replicas that further sample the well
- 3 Parallel Step – Run the replicas until one exits the well

# Decorrelating the Reference Process



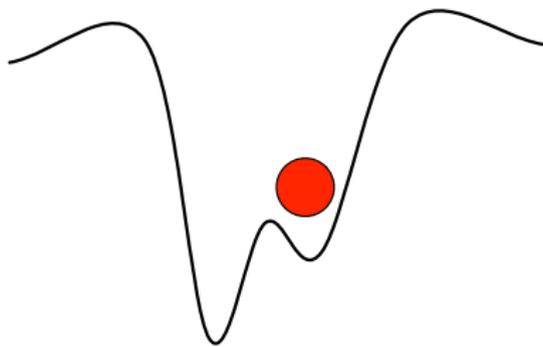
# Decorrelating the Reference Process



## Structure of the Decorrelation Step

- Run for  $t \leq t_{\text{corr}}$

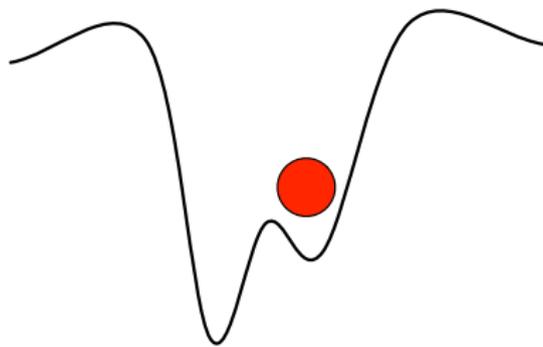
# Decorrelating the Reference Process



## Structure of the Decorrelation Step

- Run for  $t \leq t_{\text{corr}}$
- If  $X_t$  leaves the well, begin again, in the new well

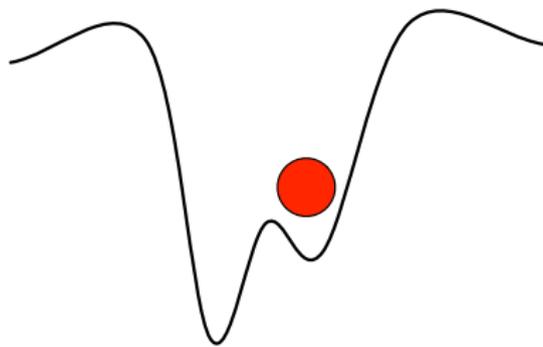
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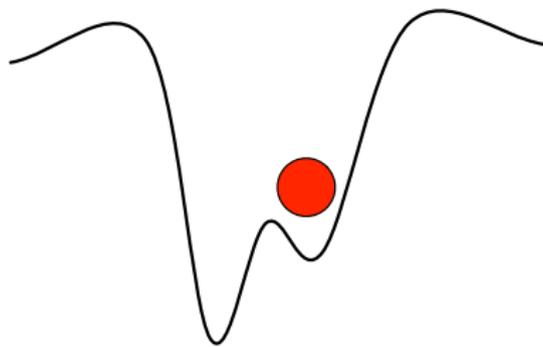
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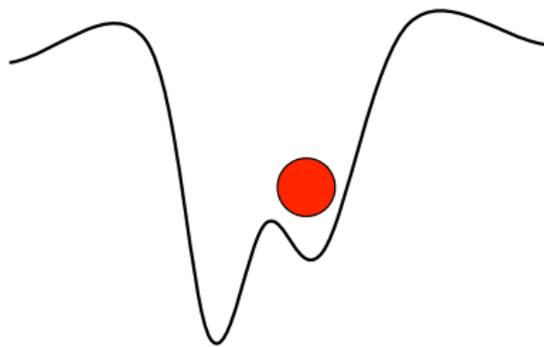
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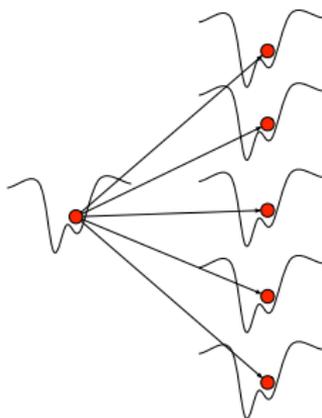
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- $t_{\text{corr}}$  is one of the user parameters
- Simulation clock is advanced by  $t_{\text{corr}}$

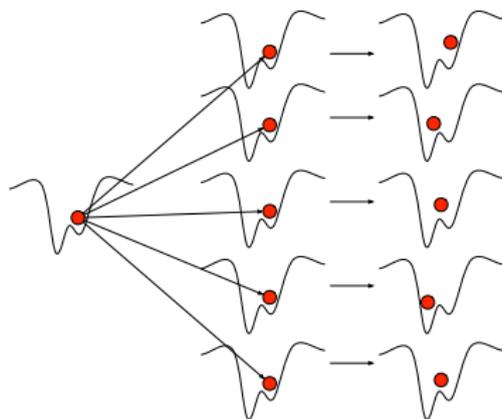
# Dephasing by Direct Simulation



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- Replicas begin running at  $t_{\text{launch}} < t_{\text{corr}}$  ( $t_{\text{launch}}$  can be zero, as in the previous Par Rep version)

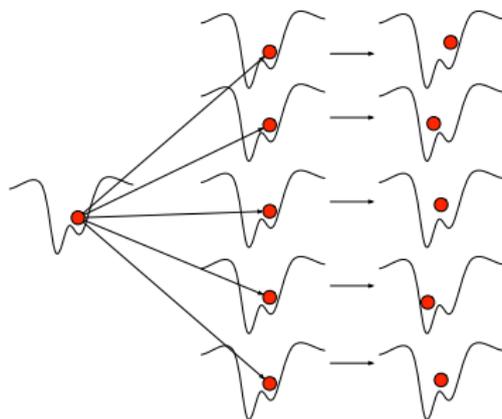
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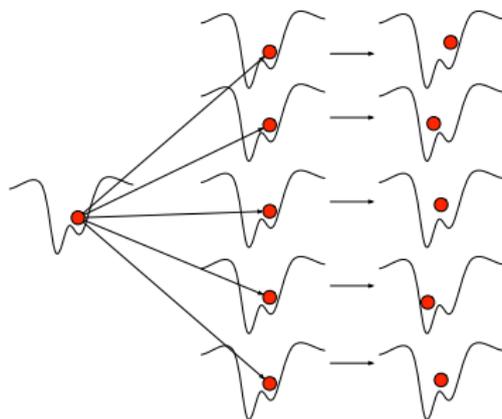
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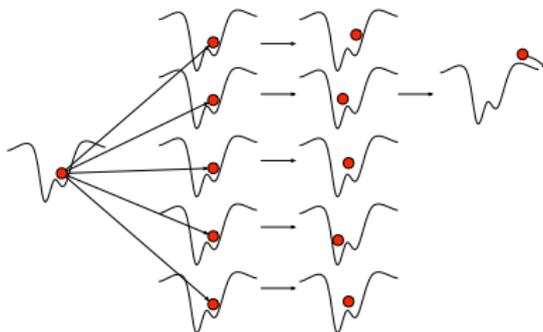
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- If  $X_t^k$  leaves the well, restart it

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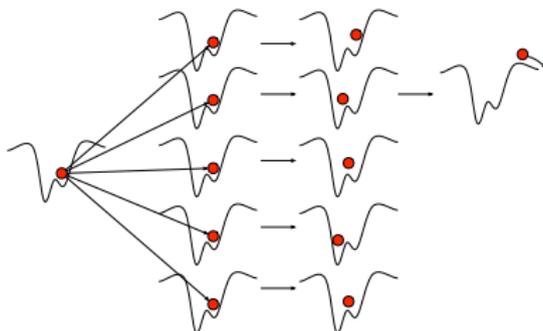
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- If  $X_t^k$  leaves the well, restart it
- $t_{\text{launch}}$  and  $t_{\text{phase}}$  are other user parameters



## Structure of the Parallel Step

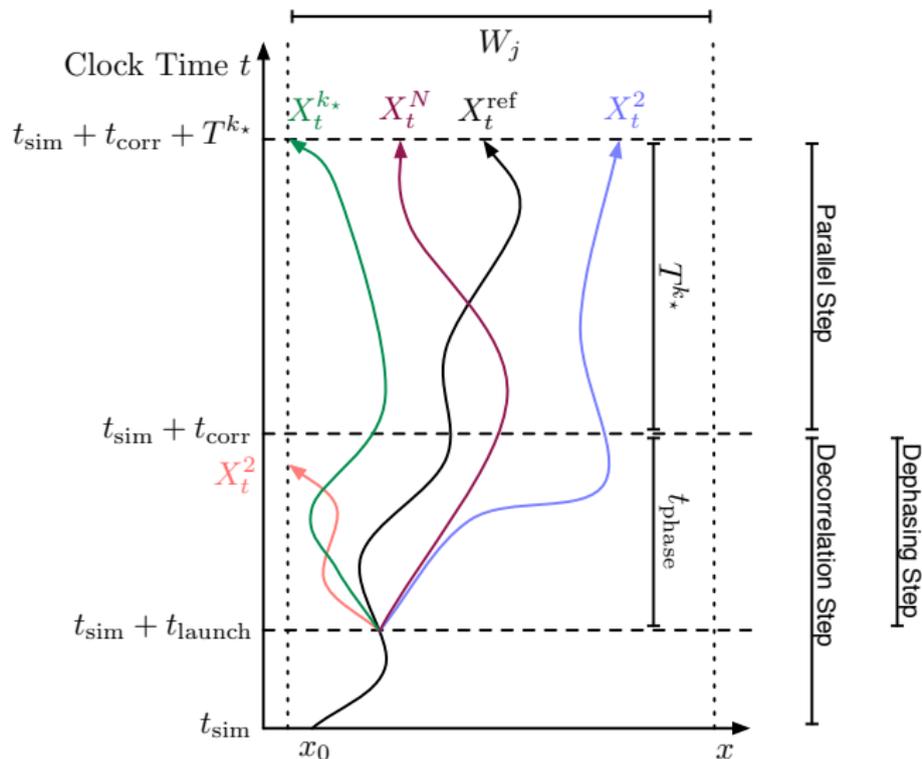
- The first process  $k_*$  to leave the well, at time  $T_{\text{exit}} := T_{k_*}$ , becomes the new reference process, and the algorithm restarts



## Structure of the Parallel Step

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- The simulation clock is advanced by  $NT_{\text{exit}}$

# Parallel Replica Dynamics – Recap



- 1 Parallel Replica Dynamics
  - Decorrelation Step
  - Dephasing Step
  - Parallel Step
- 2 Main Results
  - QSD — Exponential First Exit Time
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# Goals

- Given that we begin in well  $W \subset \mathbb{R}^n$ , determine the properties of  $T_{\text{exit}}$ , the first exit time from  $W$

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- What is the distribution for  $T_{\text{exit}}$ ?
- What are the properties of  $X_{T_{\text{exit}}}$ , the first hitting point distribution?
- Can we estimate the accuracy of ParRep?
- Can we optimize the efficiency of ParRep?

# Fokker-Planck Equation

The Fokker-Planck Equation for the overdamped Langevin equation  $dX_t = -\nabla V(X_t)dt + \sqrt{2\beta^{-1}}dB_t$  and absorbing boundary conditions:

$$\begin{aligned}\frac{\partial \rho}{\partial t} &= L^* \rho := \nabla \cdot [(\nabla V) \rho + \beta^{-1} \nabla \rho] \quad \forall x \in W, t \geq 0, \\ \rho(x, t) &= 0 \quad \forall x \in \partial W, t \geq 0, \\ \rho(x, 0) &\geq 0 \quad \forall x \in W, \quad \int_W \rho(x, 0) dx = 1,\end{aligned}$$

is given by the series expansion

$$\rho(x, t) = \sum_1^{\infty} a_j e^{-\lambda_j t} \psi_j(x),$$

for eigenvalues  $0 < \lambda_1 < \lambda_2 \leq \dots$  and eigenfunctions  $\psi_j(x)$  of

$$\begin{aligned}L^* \psi_j &= \nabla \cdot [(\nabla V) \psi_j + \beta^{-1} \nabla \psi_j] = -\lambda_j \psi_j \quad \forall x \in W, \\ \psi_j &= 0 \quad \forall x \in \partial W.\end{aligned}$$

# The Exit Density

The exit density through the boundary point  $x \in \partial W$  at time  $t \geq 0$  is

$$\beta^{-1} \frac{\partial \rho}{\partial n}(x, t),$$

the first exit time density is

$$\int_{\partial W} \beta^{-1} \frac{\partial \rho}{\partial n}(x, t) dx,$$

and the first hitting point density is

$$\int_0^\infty \beta^{-1} \frac{\partial \rho}{\partial n}(x, t) dt.$$

# The Quasistationary Distribution (QSD)

The renormalized density  $\rho(x, t)$  converges to  $\psi_1(x)$  at rate  $\lambda_2 - \lambda_1$  (where  $\psi_1(x) > 0$  is normalized by  $\int_W \psi_1(x, t) dx = 1$ ):

$$\frac{\rho(x, t)}{\int_W \rho(x, t) dx} = \psi_1(x) + O\left(e^{-(\lambda_2 - \lambda_1)t}\right) \quad \text{as } t \rightarrow \infty.$$

The Fokker-Planck solution  $\rho(x, t) = \psi_1(x)e^{-\lambda_1 t}$  has exit density

$$\beta^{-1} \frac{\partial \psi_1}{\partial n}(x) e^{-\lambda_1 t} \quad \forall x \in \partial W, \quad t \geq 0,$$

with independent exit time and hitting point.

# The Quasistationary Distribution (QSD)

The first exit time density of  $\rho(x, t) = \psi_1(x)e^{-\lambda_1 t}$  is exponential:

$$\int_{\partial W} \beta^{-1} \frac{\partial \psi_1}{\partial n}(x) e^{-\lambda_1 t} dx = \lambda_1 e^{-\lambda_1 t},$$

and independent of the hitting point density:

$$\int_0^\infty \beta^{-1} \frac{\partial \psi_1}{\partial n}(x) e^{-\lambda_1 t} dt = \frac{1}{\lambda_1 \beta} \frac{\partial \psi_1}{\partial n}(x).$$

# The Quasistationary Distribution (QSD)

## Definition

On well  $W$ , a QSD is a distribution  $\nu$  such that for all  $A \subset W$  and  $t \geq 0$ ,

$$\nu(A) = \int_W \mathbb{P}^x [X_t \in A \mid t < T_{\text{exit}}] d\nu(x). \quad (1)$$

The dephasing stage of the Par Rep Method converges to the QSD as  $t_{\text{phase}} \rightarrow \infty$ . (1) states that the QSD is invariant for the dephasing step.

## Theorem

$\psi_1(x) dx$  is a QSD where  $\psi_1(x) > 0$  is the unique ground state of the Fokker-Planck operator with eigenvalues  $0 < \lambda_1 < \lambda_2 \leq \dots$

$$\begin{aligned} L^* \psi_j &= \nabla \cdot [(\nabla V) \psi_j + \beta^{-1} \nabla \psi_j] = -\lambda_j \psi_j & \forall x \in W, \\ \psi_j &= 0 & \forall x \in \partial W. \end{aligned}$$

# Utility of the QSD

## Theorem

Let  $X_t^k$  be  $N$  i.i.d. processes in the well  $W$ , and assume:

- $T_{\text{exit}}^k$  are exponentially distributed,
- Exit time is independent of hitting point.

If

$$T_{\text{exit}} \equiv T_{\text{exit}}^{k_*}, \quad X_{T_{\text{exit}}} \equiv X_{T_{\text{exit}}}^{k_*}, \quad k_* \equiv \operatorname{argmin}_k T_{\text{exit}}^k,$$

then  $NT_{\text{exit}}$  has the same law as  $T_{\text{exit}}^k$ , and  $X_{T_{\text{exit}}}$  is independent of first hitting time.

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## QSD and ParRep

Goal of the decorrelation/dephasing step: Produce  $N$  processes distributed as close as possible to  $\nu$ .

# Decorrelation Result

## Theorem

Let  $X_0$  be distributed by  $\mu_0$  on  $W$ , then for any observable  $f$

$$|\mathbb{E}^{\mu_t} [f(T, X_T)] - \mathbb{E}^{\nu} [f(T, X_T)]| \lesssim d(\mu_0, \nu) \|f\|_{L^\infty} e^{-(\lambda_2 - \lambda_1)t}.$$

where

$$d\mu_t(x) := \frac{\rho(x, t) dx}{\int_W \rho(x, t) dx}.$$

- $d(\mu_t, \nu)$  measures the difference between  $\mu_t$  and  $\nu$ ; vanishes as  $t \rightarrow \infty$ .

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- ParRep is efficient when the decorrelation time scale is much less than the mean first exit time

# Decorrelation Example

- We have

$$|\mathbb{E}^{\mu_{t_{\text{corr}}}} [f(T, X_T)] - \mathbb{E}^{\nu} [f(T, X_T)]| \lesssim d(\mu_0, \nu) \|f\|_{L^\infty} e^{-(\lambda_2 - \lambda_1)t_{\text{corr}}}$$

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- For any  $t \geq 0$ , to obtain an error estimate for the first exit time let  $f(\tau, \xi) = \chi_{\tau > t}$ ; then

$$\left| \mathbb{P}^{\mu_{t_{\text{corr}}}} [T > t] - e^{-\lambda_1 t} \right| \lesssim d(\mu_0, \nu) e^{-(\lambda_2 - \lambda_1)t_{\text{corr}}}$$

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- We have

$$|\mathbb{E}^{\mu_{\text{corr}}} [f(T, X_T)] - \mathbb{E}^{\nu} [f(T, X_T)]| \lesssim d(\mu_0, \nu) \|f\|_{L^\infty} e^{-(\lambda_2 - \lambda_1)t_{\text{corr}}}$$

- For any  $t \geq 0$ , to obtain an error estimate for the first exit time let  $f(\tau, \xi) = \chi_{\tau > t}$ ; then

$$\left| \mathbb{P}^{\mu_{\text{corr}}} [T > t] - e^{-\lambda_1 t} \right| \lesssim d(\mu_0, \nu) e^{-(\lambda_2 - \lambda_1)t_{\text{corr}}}$$

- For any  $t \geq 0$ , to obtain an error estimate for the exit point distribution, let  $f(\tau, \xi) = \phi(\xi)$ ; then

$$\left| \mathbb{E}^{\mu_{\text{corr}}} [\phi(X_T) \mid T > t] - \int_{\partial W} \phi d\rho \right| \lesssim d(\mu_0, \nu) e^{-(\lambda_2 - \lambda_1)t_{\text{corr}}}$$

# Parallel Step Error

## Theorem

Assume at time  $t_{\text{corr}}$ , there are  $N$  processes  $X_{t_{\text{corr}}}^k$  distributed according to  $\mu_{\text{corr}}$  and such that

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Then for any  $\phi : \partial W \rightarrow \mathbb{R}$ , smooth,

$$\begin{aligned} \left| \mathbb{P}^{\mu_{\text{corr}}} [T^{k_*} > t] - e^{-N\lambda_1 t} \right| &\lesssim N\epsilon_{\text{corr}}, \\ \left| \mathbb{E}^{\mu_{\text{corr}}} \left[ \phi(X_{T^{k_*}}) \mid T^{k_*} > t \right] - \int_{\partial W} \phi d\rho \right| &\lesssim N \|\phi\|_{L^\infty} \epsilon_{\text{corr}} e^{N\lambda_1 t}. \end{aligned}$$

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- Factor of  $N$  speedup

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  - Decorrelation Step
  - Dephasing Step
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- 2 Main Results
  - QSD — Exponential First Exit Time
  - Decorrelation Step
  - Parallel Step
- 3 Computational Experiments**
- 4 References

# Toy Problem

## Set Up



$$V(x) = -k \cos(\pi x).$$

- Wells boundaries at odd integers, centered at even integers.
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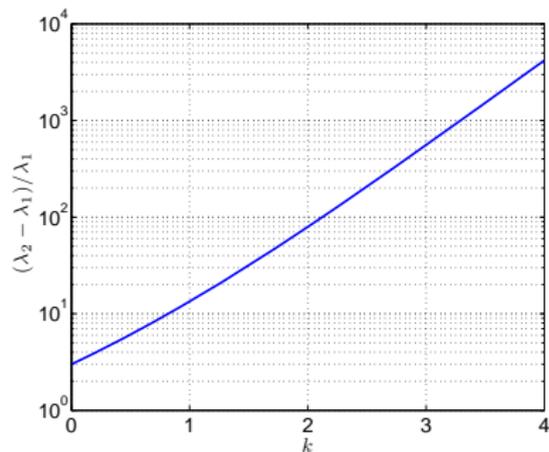
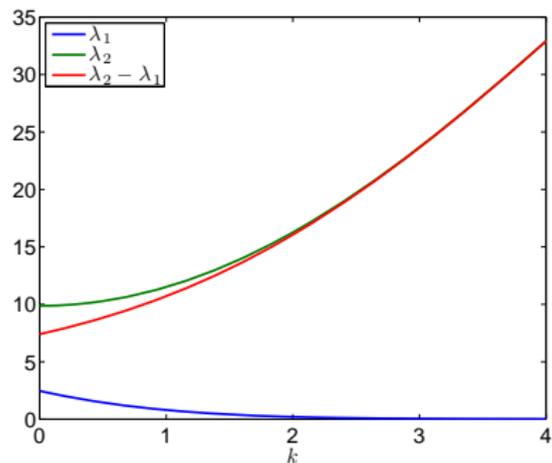
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- How well does ParRep perform?

# Time Scale Separation

$$V(x) = -k \cos(\pi x)$$



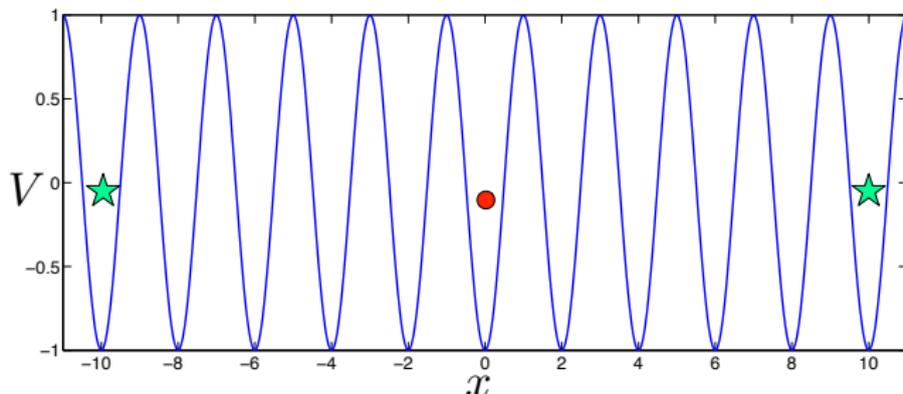
- Scale separations exist

# Rapid Convergence to the QSD

(Loading...)

- $V(x) = -2 \cos(\pi x)$ ,  $\beta = 1$ .
- $W = (-1, 1)$ .
- Initial distribution is  $\delta_0(x)$ .

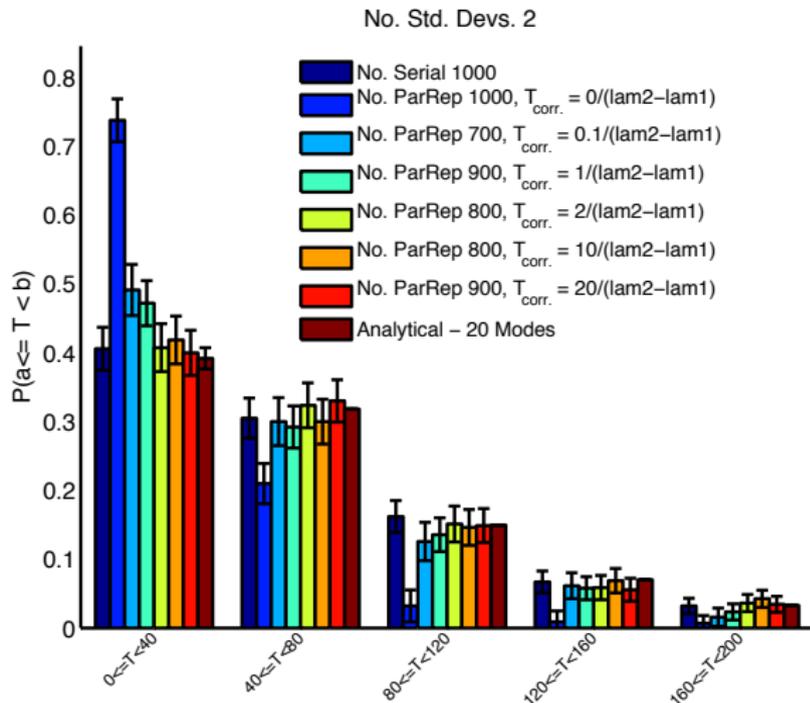
# First Exit Problem – Many Wells



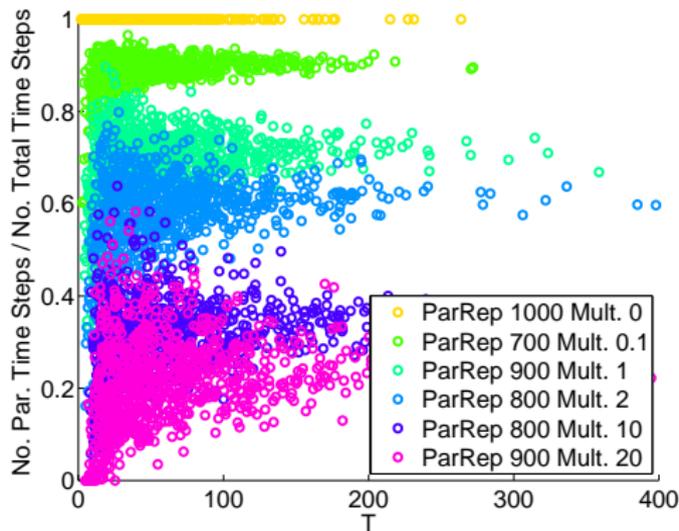
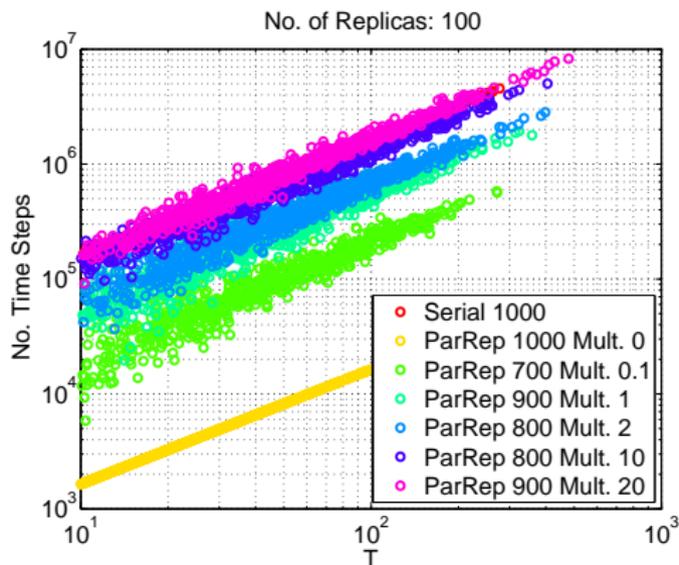
- Process ends if  $X_t$  enters either well at  $\pm 10$ .
- Run a full step of ParRep (Decorrelation, Dephasing, Parallel) every time a new well is entered.
- Dephasing is conducted “analytically” from the QSD.

# Hitting Time Distribution, $k = 1$

$V(x) = -k \cos(\pi x)$ , Target Wells  $\pm 10$



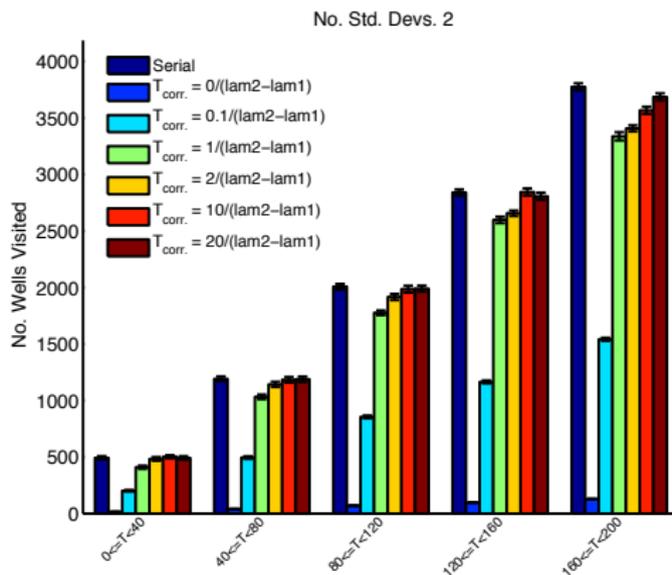
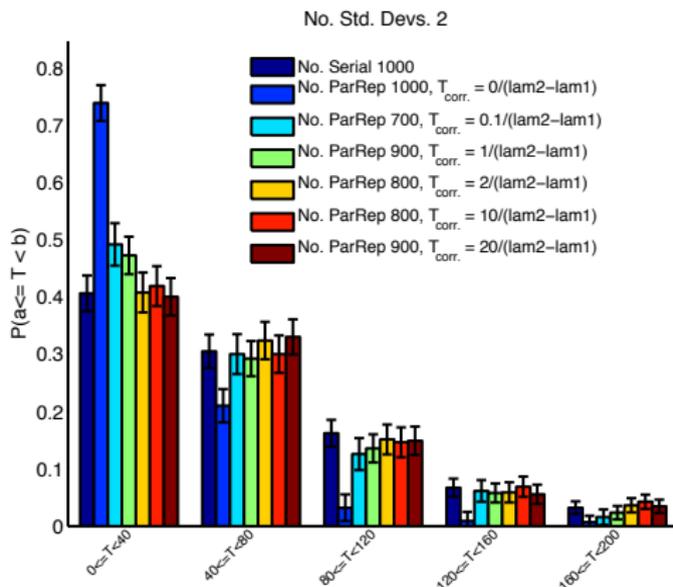
- Time scale separation  $\sim 10$
- Cases with  $t_{\text{corr}} < 2/(\lambda_2 - \lambda_1)$  give poor results

Performance,  $k = 1$ 
 $V(x) = -k \cos(\pi x)$ , Target Wells  $\pm 10$ 


- For small separation of time scales,  $\sim 10$ , minimal speedup

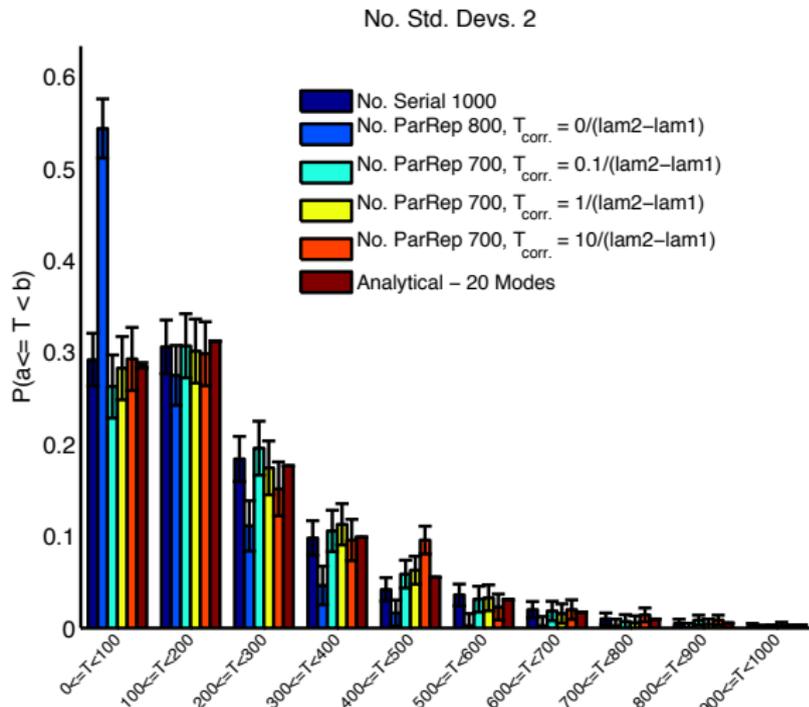
# Number of Wells Visited, $k = 1$

$V(x) = -k \cos(\pi x)$ , Target Wells  $\pm 10$



# Hitting Time Distribution, $k = 2$

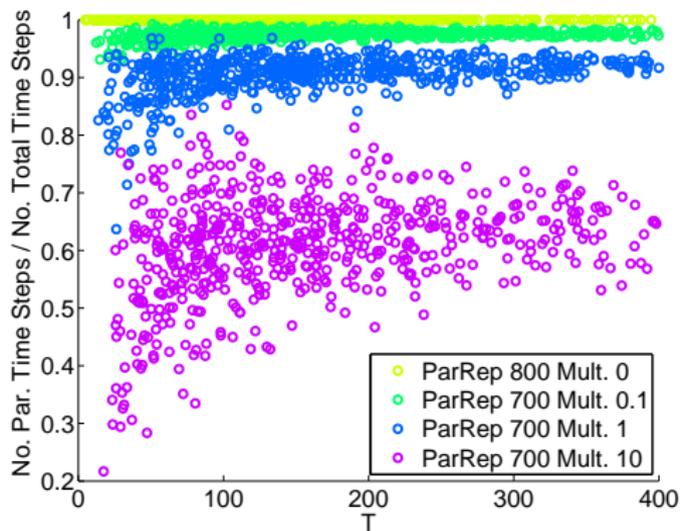
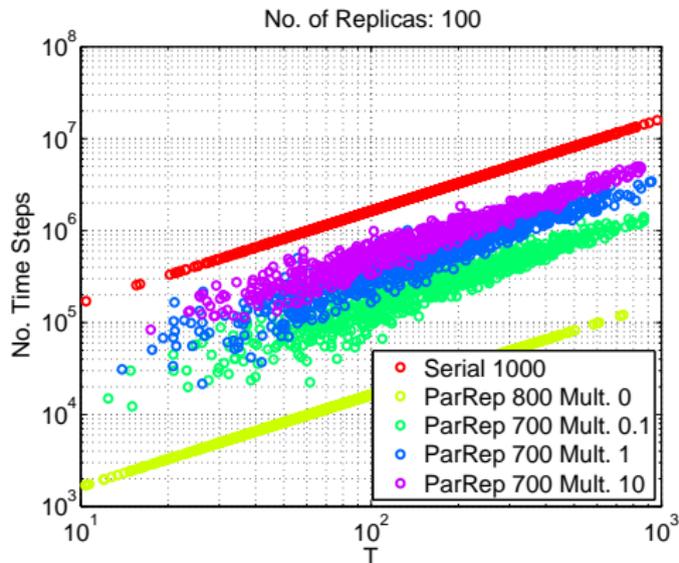
$V(x) = -k \cos(\pi x)$ , Target Wells  $\pm 10$



- Time scale separation  $\sim 80$
- Only  $T_{\text{corr.}} = 0$  gives poor results

Performance,  $k = 2$ 

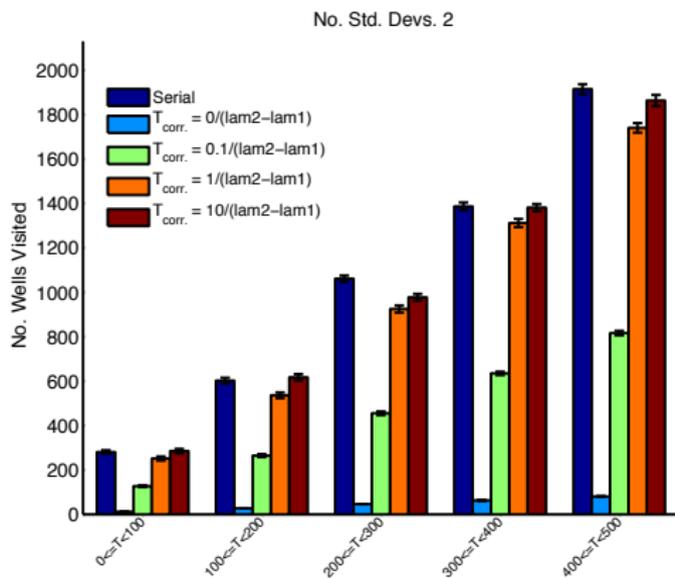
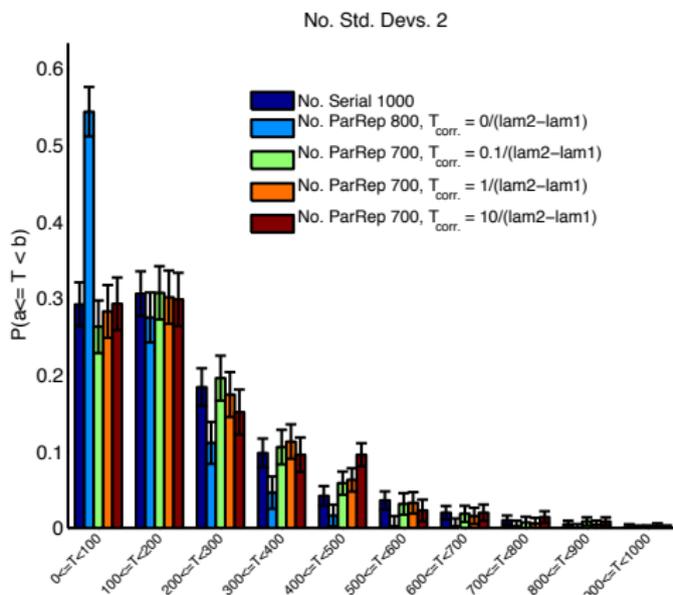
$$V(x) = -k \cos(\pi x), \text{Target Wells } \pm 10$$



- For larger separation of time scales,  $\sim 80$ , speedup approaches theoretical factor of  $N = 100$ .

# Number of Wells Visited, $k = 2$

$$V(x) = -k \cos(\pi x), \text{ Target Wells } \pm 10$$



- Despite agreement in the exit time distributions, there may be disagreements in the distribution in the number of wells visited

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