

# **Probabilistic inference in networks of spiking neurons**

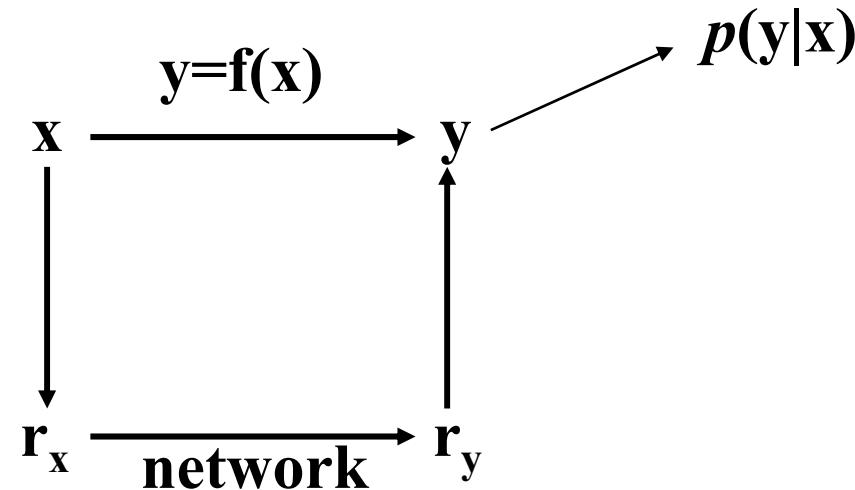
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**Gatsby Computational Neuroscience Unit, UCL**

**Kavli Institute for Theoretical Physics  
October 7, 2010**

learn to

Goal: understand how networks of neurons compute.



$x = \text{image}$

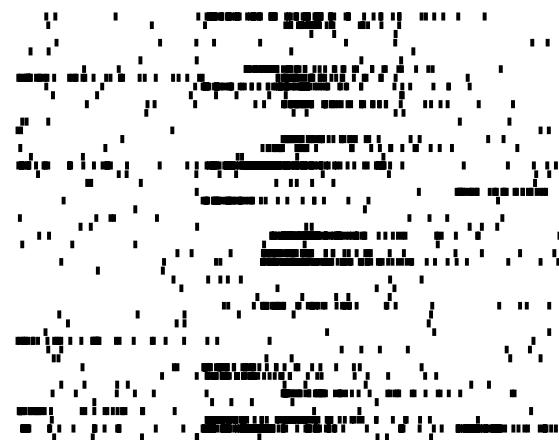


$y = \text{sunset}$

true probability:  $p(y|r_x)$

goal: choose the network so  
these are as close as possible,  
and  $r_y$  codes only for sunsets.

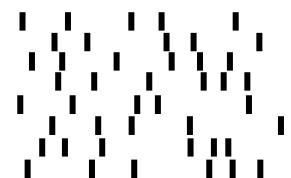
$r_x$

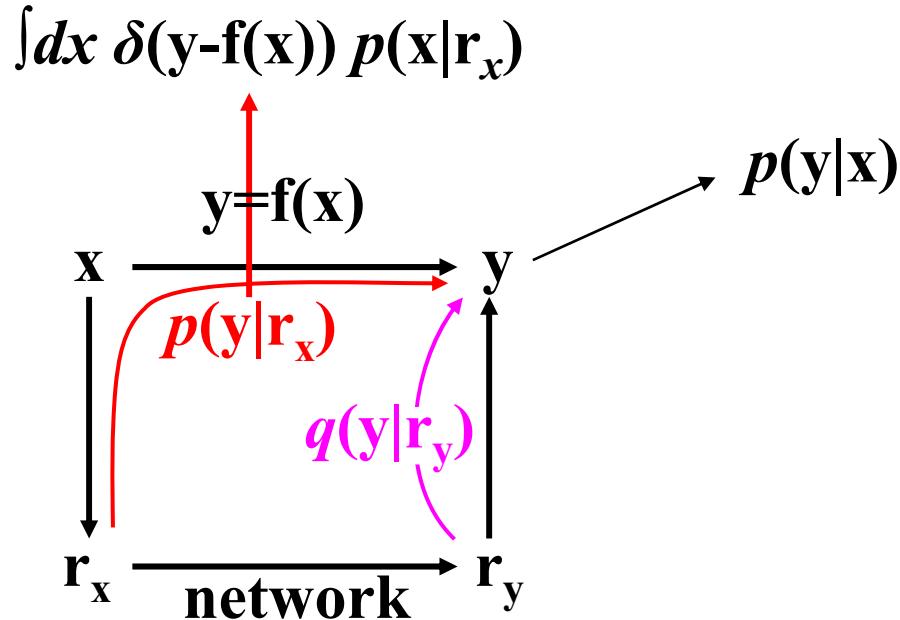


network

$q(y|r_y)$

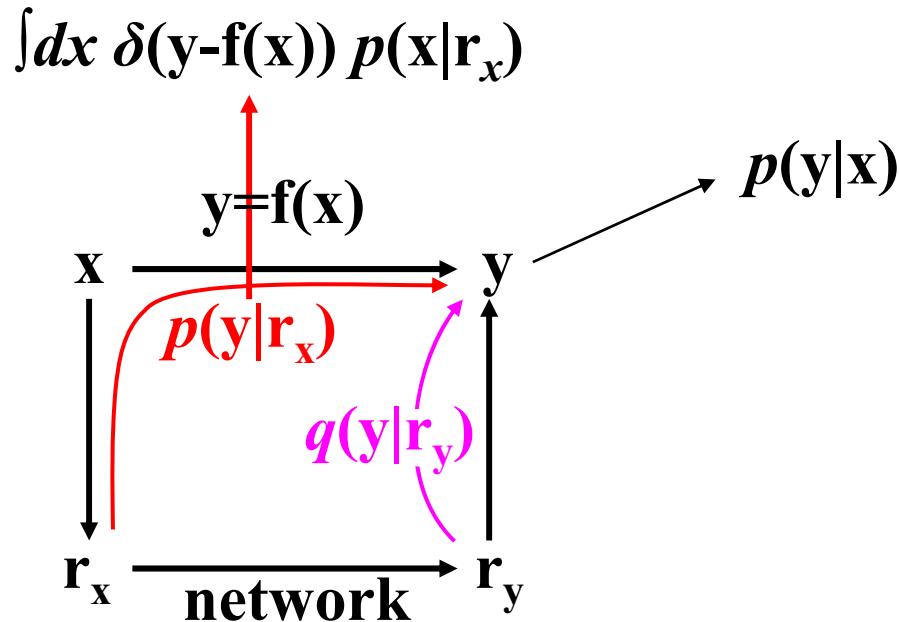
$r_y$





**Goal:** choose network so that  $p(y|r_x)$  is close to  $q(y|r_y)$   
**and**  $r_y$  is a “pure code” for  $y$ .

Quantitatively: minimize  $D_{KL}(p(y|r_x) || q(y|r_y))$



minimize  $D_{KL}(p(y|r_x) \| q(y|r_y))$  with respect to:

1. Parameters of the encoding model (e.g.,  $p(r_x|x)$ ,  $q(r_y|y)$ ).
2. Parameters of the biologically plausible network.

Three examples:

- multisensory integration
- $z=f(x, y)$
- a hard problem

minimize  $D_{KL}(p(y|r_x) || q(y|r_y))$  with respect to:

1. Parameters of the encoding model (e.g.,  $p(r_x|x)$ ,  $q(r_y|y)$ ).
2. Parameters of the biologically plausible network.

## Take home message

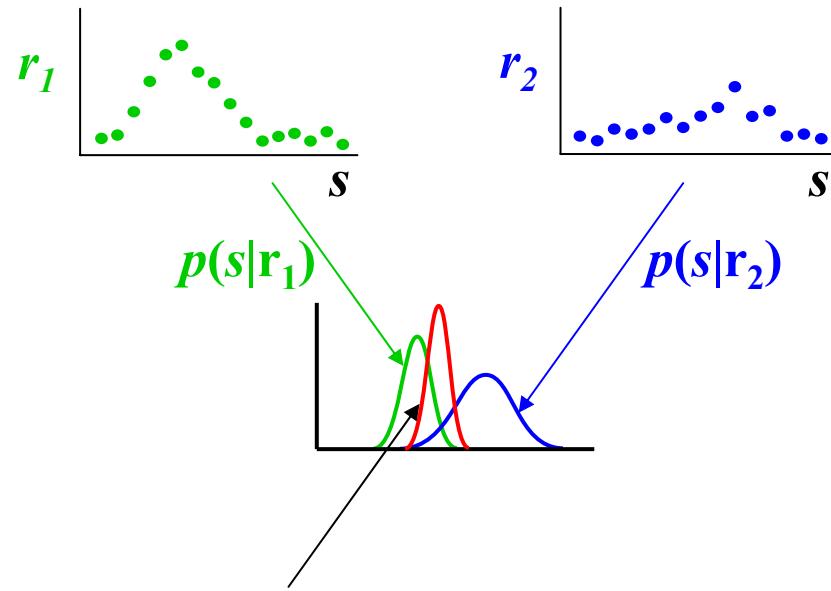
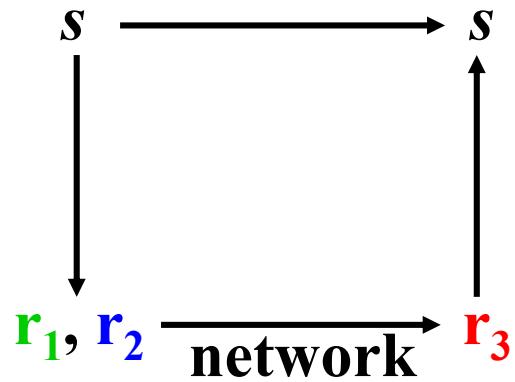
**In some ways this talk is largely technical – I'm going to tell you how biologically plausible networks could perform some (relatively) simple computations.**

**There are no deep insights into how the brain works.**

**Two things to pay attention to:**

- 1. our methodology,**
- 2. the problems we don't solve.**

# 1. multisensory integration



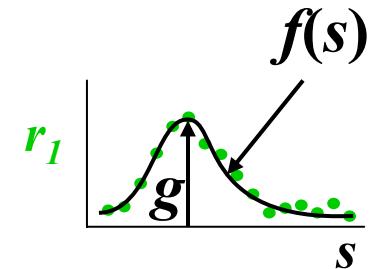
$$p(s|r_1, r_2) \propto p(s|r_1)p(s|r_2)$$

$$\text{minimize } D_{\text{KL}}(p(s|r_1, r_2) || q(s|r_3))$$

# encoding model: exponential family with linear sufficient statistics

independent Poisson:

$$\begin{aligned} p(\mathbf{r}|s, g) &= \prod_i \frac{1}{r_i!} [gf_i(s)]^{r_i} \exp[-gf_i(s)] \\ &= \varphi(\mathbf{r}, g) \exp[h(s) \cdot \mathbf{r}] \end{aligned}$$



$$h_i(s) = \log f_i(s)$$

$$\varphi(\mathbf{r}, g) = \exp \left[ -\sum_i \log r_i! + r_i \log g - gf_i(s) \right]$$

$$\exp[r_i \log g + r_i \log f_i(s)]$$

encoding model: exponential family with linear sufficient statistics

$$p(\mathbf{r}|\mathbf{s}, \mathbf{g}) = \phi(\mathbf{r}, \mathbf{g}) \exp[\mathbf{h}(\mathbf{s}) \cdot \mathbf{r}]$$

$$p(\mathbf{s}|\mathbf{r}) \propto \exp[\mathbf{h}(\mathbf{s}) \cdot \mathbf{r}]$$

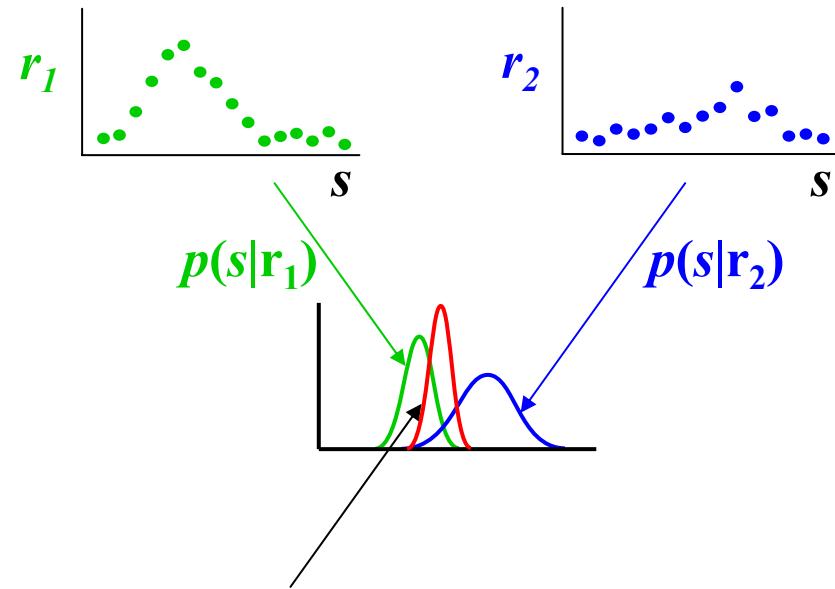
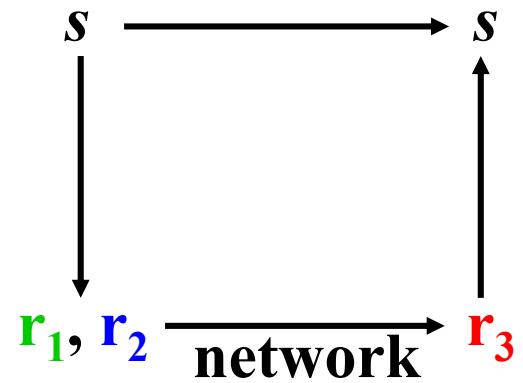
the gain parameter doesn't appear in the posterior!!!!

encoding model: linear PPC

$$p(\mathbf{r}|\mathbf{s}, g) = \phi(\mathbf{r}, g) \exp[\mathbf{h}(\mathbf{s}) \cdot \mathbf{r}]$$

$$p(\mathbf{s}|\mathbf{r}) \propto \exp[\mathbf{h}(\mathbf{s}) \cdot \mathbf{r}]$$

the gain parameter doesn't appear in the posterior!!!!



**minimize  $D_{KL}(p(s|r_1, r_2) || q(s|r_3))$**

**minimize**  $D_{KL}(p(s|r_1, r_2) || q(s|r_3))$

$$p(s|r_1, r_2) \propto p(s|r_1)p(s|r_2)$$

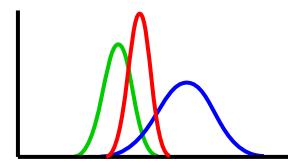
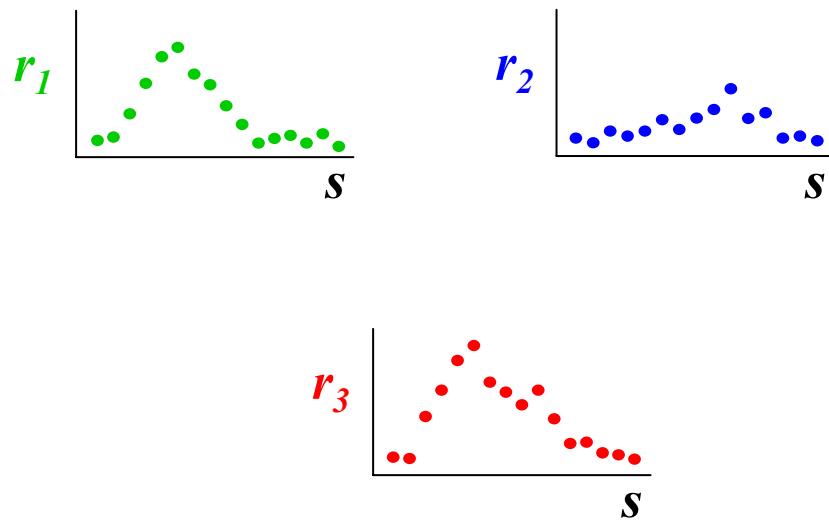
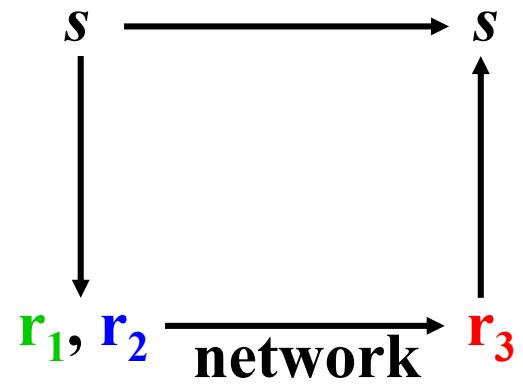
$$p(s|r_1) \propto \exp[h(s) \cdot r_1]$$

$$p(s|r_2) \propto \exp[h(s) \cdot r_2]$$

$$q(s|r_3) \propto \exp[h(s) \cdot r_3]$$

$$p(s|r_1, r_2) \propto p(s|r_1)p(s|r_2) \propto \exp[h(s) \cdot (r_1 + r_2)]$$

**network:**  $r_3 = r_1 + r_2$



# The encoding model matters!

## Gaussian encoding model:

$$p(r_1|s) \propto \exp[-(f(s)-r_1)^2/2\sigma_1^2]$$
$$p(r_2|s) \propto \exp[-(f(s)-r_2)^2/2\sigma_2^2]$$

these will vary  
from trial to trial

$$p(s|r_1, r_2) \propto p(s|r_1)p(s|r_2) \propto \exp[-(f(s)-ar_1-br_2)^2/2\sigma^2]$$

$$1/\sigma^2 = 1/\sigma_1^2 + 1/\sigma_2^2$$

$$a = \sigma^2/\sigma_1^2$$

$$b = \sigma^2/\sigma_2^2$$

network:  $r_3 = ar_1 + br_2$

depend on  $\sigma_1$  and  $\sigma_2$ , which depend,  
probabilistically, on  $r_1$  and  $r_2$ .

# The encoding model matters!

linear PPC encoding:

$$p(\mathbf{r}_1|s) \propto \varphi(\mathbf{r}_1, \mathbf{g}_1) \exp[h(s) \cdot \mathbf{r}_1]$$
$$p(\mathbf{r}_2|s) \propto \varphi(\mathbf{r}_2, \mathbf{g}_2) \exp[h(s) \cdot \mathbf{r}_2]$$

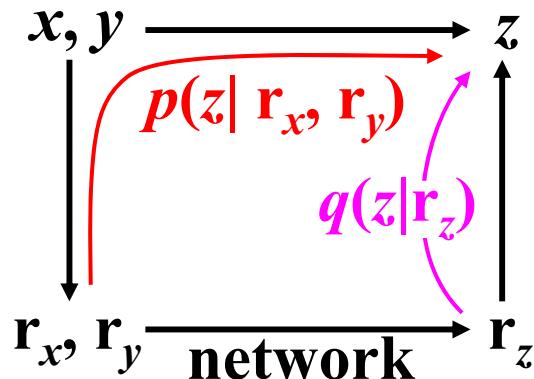
these will vary  
from trial to trial

network:  $\mathbf{r}_3 = \mathbf{r}_1 + \mathbf{r}_2$

**This was a simple example, but it has the main ingredients:**

- 1. The encoding model matters.**
- 2. Once you specify the encoding model, the network follows.**

## 2. computing functions $z=f(x, y)$



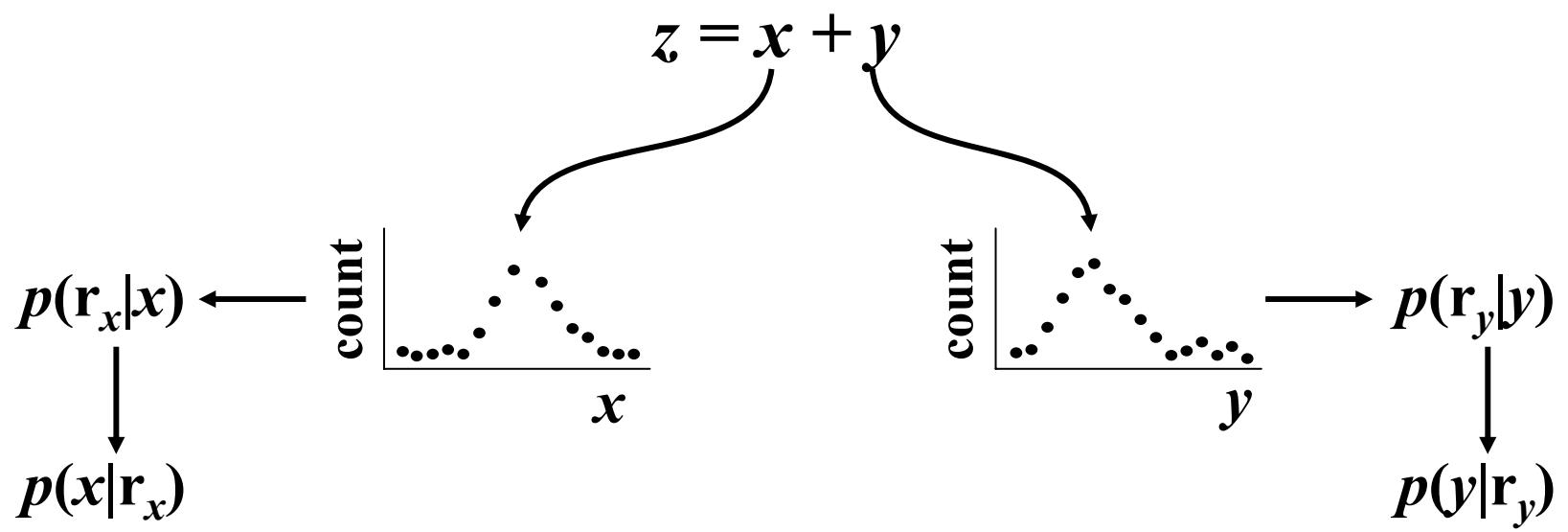
minimize  $D_{KL}(p(z|r_x, r_y) || q(z|r_z))$  with respect to:

1. Parameters of the encoding model.
2. Parameters of the network.

typically, we can't find the optimal network

**Find the optimal network for linear transformations and Gaussian posterior distributions;**

**use that network architecture for nonlinear transformation and non-Gaussian posteriors.**



$$p(z|\mathbf{r}_x, \mathbf{r}_y) = \int dx dy \delta(z - (x+y)) p(x|\mathbf{r}_x) p(y|\mathbf{r}_y)$$

**hard integral!**

$$z = x + y$$

## The Gaussian case

$$p(z|r_x, r_y) = \int dx dy \delta(z-(x+y)) p(x|r_x) p(y|r_y)$$

The diagram illustrates the convolution of two Gaussian distributions. At the top, a red  $\delta$  function is centered at  $z$ . Arrows point from this  $\delta$  function to the individual Gaussian distributions below:  $N(\mu_x, \sigma_x^2)$  and  $N(\mu_y, \sigma_y^2)$ . Another arrow points from the sum of these two Gaussians down to the resulting Gaussian at the bottom, labeled  $N(\mu_x + \mu_y, \sigma_x^2 + \sigma_y^2)$ .

Easier problem:

1. parameterize the mean and variance in a linear PPC;
2. find a network such that

$$\begin{aligned}\mu_z &= \mu_x + \mu_y \\ \sigma_z^2 &= \sigma_x^2 + \sigma_y^2\end{aligned}$$

An (important) aside: representation matters Suppose

$$p(\mathbf{r}_x|x) \sim \exp[-(x - \mathbf{a} \cdot \mathbf{r}_x)^2 / 2\mathbf{b} \cdot \mathbf{r}_x] \sim p(x|\mathbf{r}_x)$$

$$p(\mathbf{r}_y|y) \sim \exp[-(y - \mathbf{a} \cdot \mathbf{r}_y)^2 / 2\mathbf{b} \cdot \mathbf{r}_y] \sim p(y|\mathbf{r}_y)$$

$$p(\mathbf{r}_z|z) \sim \exp[-(z - \mathbf{a} \cdot \mathbf{r}_z)^2 / 2\mathbf{b} \cdot \mathbf{r}_z] \sim p(z|\mathbf{r}_z)$$

$$\mu_x = \mathbf{a} \cdot \mathbf{r}_x$$

$$\sigma_x^2 = \mathbf{b} \cdot \mathbf{r}_x$$

$$\mu_y = \mathbf{a} \cdot \mathbf{r}_y$$

$$\sigma_y^2 = \mathbf{b} \cdot \mathbf{r}_y$$

$$\mu_z = \mathbf{a} \cdot \mathbf{r}_z$$

$$\sigma_z^2 = \mathbf{b} \cdot \mathbf{r}_z$$

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$$p(\mathbf{r}_z|z) \sim \exp[-(z - \mathbf{a} \cdot \mathbf{r}_z)^2 / 2\mathbf{b} \cdot \mathbf{r}_z] \sim p(z|\mathbf{r}_z)$$

$$\mu_x = \mathbf{a} \cdot \mathbf{r}_x$$

$$\sigma_x^2 = \mathbf{b} \cdot \mathbf{r}_x$$

$$\mu_y = \mathbf{a} \cdot \mathbf{r}_y$$

$$\sigma_y^2 = \mathbf{b} \cdot \mathbf{r}_y$$

$$\mu_z = \mathbf{a} \cdot \mathbf{r}_z = \mu_x + \mu_y$$

$$\sigma_z^2 = \mathbf{b} \cdot \mathbf{r}_z = \sigma_x^2 + \sigma_y^2$$



goal

An (important) aside: representation matters Suppose

$$p(\mathbf{r}_x|x) \sim \exp[-(x - \mathbf{a} \cdot \mathbf{r}_x)^2 / 2\mathbf{b} \cdot \mathbf{r}_x] \sim p(x|\mathbf{r}_x)$$

$$p(\mathbf{r}_y|y) \sim \exp[-(y - \mathbf{a} \cdot \mathbf{r}_y)^2 / 2\mathbf{b} \cdot \mathbf{r}_y] \sim p(y|\mathbf{r}_y)$$

$$p(\mathbf{r}_z|z) \sim \exp[-(z - \mathbf{a} \cdot \mathbf{r}_z)^2 / 2\mathbf{b} \cdot \mathbf{r}_z] \sim p(z|\mathbf{r}_z)$$

$$\mu_x = \mathbf{a} \cdot \mathbf{r}_x$$

$$\sigma_x^2 = \mathbf{b} \cdot \mathbf{r}_x$$

$$\mu_y = \mathbf{a} \cdot \mathbf{r}_y$$

$$\sigma_y^2 = \mathbf{b} \cdot \mathbf{r}_y$$

$$\mu_z = \mathbf{a} \cdot \mathbf{r}_z$$

$$\sigma_z^2 = \mathbf{b} \cdot \mathbf{r}_z$$

optimal network:

$$\mathbf{r}_z = \mathbf{r}_x + \mathbf{r}_y$$

**If brains had evolved to perform linear transformations ( $z=ax+by$ ), and noise was Gaussian, then encoding probably would have looked like**

$$p(\mathbf{r}_x|x) \sim \exp[-(x - \mathbf{a} \cdot \mathbf{r}_x)^2 / 2\mathbf{b} \cdot \mathbf{r}_x].$$

**The fact that the encoding model does not look like this is probably a clue to what the brain has evolved to compute.**

**So far this is just a clue – we haven't made sense of it.**

An (important) aside: representation matters! Suppose

$$p(\mathbf{r}_x|x) \sim \exp[-(x - \mathbf{a} \cdot \mathbf{r}_x)^2 / 2\mathbf{b} \cdot \mathbf{r}_x] \sim p(x|\mathbf{r}_x)$$

$$p(\mathbf{r}_y|y) \sim \exp[-(y - \mathbf{a} \cdot \mathbf{r}_y)^2 / 2\mathbf{b} \cdot \mathbf{r}_y] \sim p(y|\mathbf{r}_y)$$

$$p(\mathbf{r}_z|z) \sim \exp[-(z - \mathbf{a} \cdot \mathbf{r}_z)^2 / 2\mathbf{b} \cdot \mathbf{r}_z] \sim p(z|\mathbf{r}_z)$$

$$\mu_x = \mathbf{a} \cdot \mathbf{r}_x$$

$$\sigma_x^2 = \mathbf{b} \cdot \mathbf{r}_x$$

$$\mu_y = \mathbf{a} \cdot \mathbf{r}_y$$

$$\sigma_y^2 = \mathbf{b} \cdot \mathbf{r}_y$$

$$\mu_z = \mathbf{a} \cdot \mathbf{r}_z = \mu_x + \mu_y = \mathbf{a} \cdot \mathbf{r}_x + \mathbf{a} \cdot \mathbf{r}_y$$

$$\sigma_z^2 = \mathbf{b} \cdot \mathbf{r}_z = \sigma_x^2 + \sigma_y^2 = \mathbf{b} \cdot \mathbf{r}_x + \mathbf{b} \cdot \mathbf{r}_y$$

optimal network:

$$\mathbf{r}_z = \mathbf{r}_x + \mathbf{r}_y$$

goal

## The real thing: a linear PPC

$$p(r_x|x) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_x (x - \mathbf{b} \cdot \mathbf{r}_x / \mathbf{a} \cdot \mathbf{r}_x)^2 / 2]$$

$$p(r_y|y) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_y (y - \mathbf{b} \cdot \mathbf{r}_y / \mathbf{a} \cdot \mathbf{r}_y)^2 / 2]$$

$$p(r_z|z) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_z (z - \mathbf{b} \cdot \mathbf{r}_z / \mathbf{a} \cdot \mathbf{r}_z)^2 / 2]$$

this is a linear PPC:

$$= \exp[-\mathbf{a} \cdot \mathbf{r}_x x^2 / 2 + \mathbf{b} \cdot \mathbf{r}_x x + (\mathbf{b} \cdot \mathbf{r}_x)^2 / 2 \mathbf{a} \cdot \mathbf{r}_x]$$

$$= \varphi(\mathbf{r}_x) \exp[-(x^2 / 2) \mathbf{a} + x \mathbf{b} \cdot \mathbf{r}_x]$$

$$\mathbf{h}(x)$$

## The real thing: a linear PPC

$$p(\mathbf{r}_x|x) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_x (x - \mathbf{b} \cdot \mathbf{r}_x / \mathbf{a} \cdot \mathbf{r}_x)^2 / 2] \sim p(x|\mathbf{r}_x)$$

$$p(\mathbf{r}_y|y) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_y (y - \mathbf{b} \cdot \mathbf{r}_y / \mathbf{a} \cdot \mathbf{r}_y)^2 / 2] \sim p(y|\mathbf{r}_y)$$

$$p(\mathbf{r}_z|z) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_z (z - \mathbf{b} \cdot \mathbf{r}_z / \mathbf{a} \cdot \mathbf{r}_z)^2 / 2] \sim p(z|\mathbf{r}_z)$$

$$\mu_x = \mathbf{b} \cdot \mathbf{r}_x / \mathbf{a} \cdot \mathbf{r}_x$$

$$\sigma_x^2 = 1 / \mathbf{a} \cdot \mathbf{r}_x$$

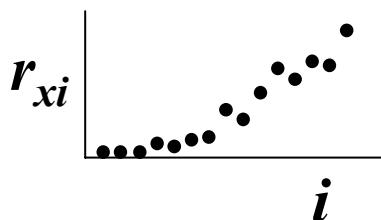
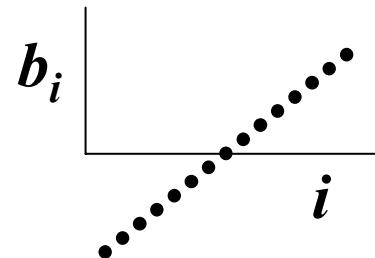
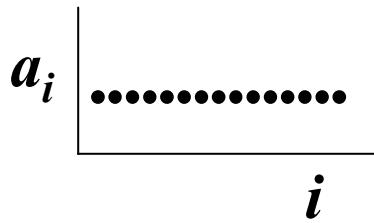
## The real thing: a linear PPC

$$p(\mathbf{r}_x|x) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_x (x - \mathbf{b} \cdot \mathbf{r}_x / \mathbf{a} \cdot \mathbf{r}_x)^2 / 2] \sim p(x|\mathbf{r}_x)$$

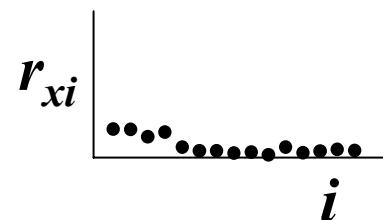
$$p(\mathbf{r}_y|y) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_y (y - \mathbf{b} \cdot \mathbf{r}_y / \mathbf{a} \cdot \mathbf{r}_y)^2 / 2] \sim p(y|\mathbf{r}_y)$$

$$p(\mathbf{r}_z|z) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_z (z - \mathbf{b} \cdot \mathbf{r}_z / \mathbf{a} \cdot \mathbf{r}_z)^2 / 2] \sim p(z|\mathbf{r}_z)$$

$$\begin{aligned}\mu_x &= \mathbf{b} \cdot \mathbf{r}_x / \mathbf{a} \cdot \mathbf{r}_x \\ \sigma_x^2 &= 1 / \mathbf{a} \cdot \mathbf{r}_x\end{aligned}$$



**positive mean,  
low variance**



**negative mean,  
high variance**

## The real thing: a linear PPC

$$p(\mathbf{r}_x|x) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_x (x - \mathbf{b} \cdot \mathbf{r}_x / \mathbf{a} \cdot \mathbf{r}_x)^2 / 2] \sim p(x|\mathbf{r}_x)$$

$$p(\mathbf{r}_y|y) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_y (y - \mathbf{b} \cdot \mathbf{r}_y / \mathbf{a} \cdot \mathbf{r}_y)^2 / 2] \sim p(y|\mathbf{r}_y)$$

$$p(\mathbf{r}_z|z) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_z (z - \mathbf{b} \cdot \mathbf{r}_z / \mathbf{a} \cdot \mathbf{r}_z)^2 / 2] \sim p(z|\mathbf{r}_z)$$

$$\mu_x = \mathbf{b} \cdot \mathbf{r}_x / \mathbf{a} \cdot \mathbf{r}_x$$

$$\sigma_x^2 = 1 / \mathbf{a} \cdot \mathbf{r}_x$$

$$\mu_y = \mathbf{b} \cdot \mathbf{r}_y / \mathbf{a} \cdot \mathbf{r}_y$$

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$$\mu_z = \mathbf{b} \cdot \mathbf{r}_z / \mathbf{a} \cdot \mathbf{r}_z$$

$$\sigma_z^2 = 1 / \mathbf{a} \cdot \mathbf{r}_z$$

## The real thing: a linear PPC

$$p(\mathbf{r}_x|x) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_x (x - \mathbf{b} \cdot \mathbf{r}_x / \mathbf{a} \cdot \mathbf{r}_x)^2 / 2] \sim p(x|\mathbf{r}_x)$$

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$$p(\mathbf{r}_z|z) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_z (z - \mathbf{b} \cdot \mathbf{r}_z / \mathbf{a} \cdot \mathbf{r}_z)^2 / 2] \sim p(z|\mathbf{r}_z)$$

$$\mu_x = \mathbf{b} \cdot \mathbf{r}_x / \mathbf{a} \cdot \mathbf{r}_x$$

$$\sigma_x^2 = 1 / \mathbf{a} \cdot \mathbf{r}_x$$

$$\mu_y = \mathbf{b} \cdot \mathbf{r}_y / \mathbf{a} \cdot \mathbf{r}_y$$

$$\sigma_y^2 = 1 / \mathbf{a} \cdot \mathbf{r}_y$$

$$\begin{aligned}\mu_z &= \mathbf{b} \cdot \mathbf{r}_z / \mathbf{a} \cdot \mathbf{r}_z = \mu_x + \mu_y \\ \sigma_z^2 &= 1 / \mathbf{a} \cdot \mathbf{r}_z = \sigma_x^2 + \sigma_y^2\end{aligned}$$

goal

## The real thing: a linear PPC

$$p(\mathbf{r}_x|x) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_x (x - \mathbf{b} \cdot \mathbf{r}_x / \mathbf{a} \cdot \mathbf{r}_x)^2 / 2] \sim p(x|\mathbf{r}_x)$$

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$$p(\mathbf{r}_z|z) \sim \exp[-\mathbf{a} \cdot \mathbf{r}_z (z - \mathbf{b} \cdot \mathbf{r}_z / \mathbf{a} \cdot \mathbf{r}_z)^2 / 2] \sim p(z|\mathbf{r}_z)$$

$$\mu_x = \mathbf{b} \cdot \mathbf{r}_x / \mathbf{a} \cdot \mathbf{r}_x$$

$$\sigma_x^2 = 1 / \mathbf{a} \cdot \mathbf{r}_x$$

$$\mu_y = \mathbf{b} \cdot \mathbf{r}_y / \mathbf{a} \cdot \mathbf{r}_y$$

$$\sigma_y^2 = 1 / \mathbf{a} \cdot \mathbf{r}_y$$

$$\begin{aligned}\mu_z &= \mathbf{b} \cdot \mathbf{r}_z / \mathbf{a} \cdot \mathbf{r}_z = \mu_x + \mu_y = \mathbf{b} \cdot \mathbf{r}_x / \mathbf{a} \cdot \mathbf{r}_x + \mathbf{b} \cdot \mathbf{r}_y / \mathbf{a} \cdot \mathbf{r}_y \\ \sigma_z^2 &= 1 / \mathbf{a} \cdot \mathbf{r}_z = \sigma_x^2 + \sigma_y^2 = 1 / \mathbf{a} \cdot \mathbf{r}_x + 1 / \mathbf{a} \cdot \mathbf{r}_y\end{aligned}$$



goal

$$\mathbf{r}_z = \frac{\mathbf{a}}{\mathbf{a} \cdot \mathbf{a}} - \frac{\mathbf{a} \cdot \mathbf{r}_x \mathbf{a} \cdot \mathbf{r}_y}{\mathbf{a} \cdot \mathbf{r}_x + \mathbf{a} \cdot \mathbf{r}_y} + \frac{\mathbf{b}}{\mathbf{b} \cdot \mathbf{b}} - \frac{\mathbf{a} \cdot \mathbf{r}_x \mathbf{b} \cdot \mathbf{r}_y + \mathbf{a} \cdot \mathbf{r}_y \mathbf{b} \cdot \mathbf{r}_x}{\mathbf{a} \cdot \mathbf{r}_x + \mathbf{a} \cdot \mathbf{r}_y} + \mathbf{c} f(\mathbf{r}_x, \mathbf{r}_y)$$

$\downarrow$

$$\mathbf{a} \cdot \mathbf{b} = 0$$

$\mathbf{a} \cdot \mathbf{r}_z = \frac{\mathbf{a} \cdot \mathbf{r}_x \mathbf{a} \cdot \mathbf{r}_y}{\mathbf{a} \cdot \mathbf{r}_x + \mathbf{a} \cdot \mathbf{r}_y}$

$\mathbf{b} \cdot \mathbf{r}_z = \frac{\mathbf{a} \cdot \mathbf{r}_x \mathbf{b} \cdot \mathbf{r}_y + \mathbf{a} \cdot \mathbf{r}_y \mathbf{b} \cdot \mathbf{r}_x}{\mathbf{a} \cdot \mathbf{r}_x + \mathbf{a} \cdot \mathbf{r}_y}$

$\mathbf{b} \cdot \mathbf{r}_z / \mathbf{a} \cdot \mathbf{r}_z =$

$1 / \mathbf{a} \cdot \mathbf{r}_z =$

$$\frac{\mathbf{b} \cdot \mathbf{r}_x / \mathbf{a} \cdot \mathbf{r}_x + \mathbf{b} \cdot \mathbf{r}_y / \mathbf{a} \cdot \mathbf{r}_y}{1 / \mathbf{a} \cdot \mathbf{r}_x + 1 / \mathbf{a} \cdot \mathbf{r}_y}$$

goal

$$\mathbf{r}_z = \frac{\mathbf{a}}{\mathbf{a} \cdot \mathbf{a}} - \frac{\mathbf{a} \cdot \mathbf{r}_x}{\mathbf{a} \cdot \mathbf{r}_x + \mathbf{a} \cdot \mathbf{r}_y} + \frac{\mathbf{b}}{\mathbf{b} \cdot \mathbf{b}} - \frac{\mathbf{b} \cdot \mathbf{r}_y}{\mathbf{a} \cdot \mathbf{r}_x + \mathbf{a} \cdot \mathbf{r}_y} + \frac{\mathbf{a} \cdot \mathbf{r}_x \mathbf{b} \cdot \mathbf{r}_y + \mathbf{a} \cdot \mathbf{r}_y \mathbf{b} \cdot \mathbf{r}_x}{\mathbf{a} \cdot \mathbf{r}_x + \mathbf{a} \cdot \mathbf{r}_y} + \mathbf{c} \mathbf{f}(\mathbf{r}_x, \mathbf{r}_y)$$

quadratic nonlinearity:  $\sum_{jk} w_{ijk} r_{xj} r_{yk}$

$$r_z = \frac{a}{a \cdot a} \frac{a \cdot r_x \ a \cdot r_y}{a \cdot r_x + a \cdot r_y} + \frac{b}{b \cdot b} \frac{a \cdot r_x \ b \cdot r_y + a \cdot r_y \ b \cdot r_x}{a \cdot r_x + a \cdot r_y} + c f(r_x, r_y)$$

quadratic nonlinearity:  $\sum_{jk} w_{ijk} r_{xj} r_{yk}$

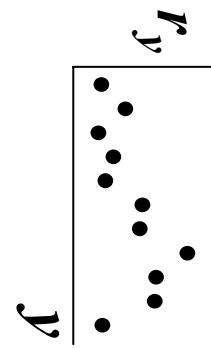
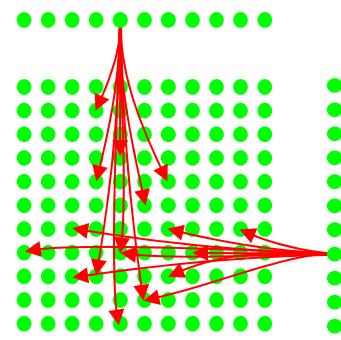
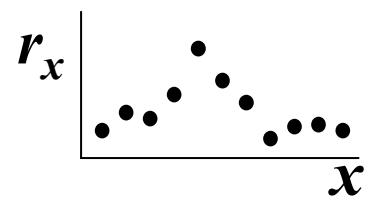
**divisive normalization**

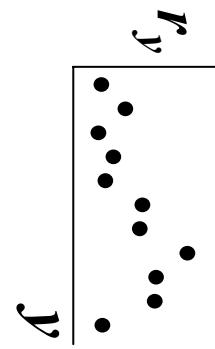
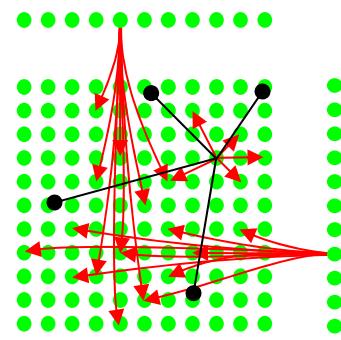
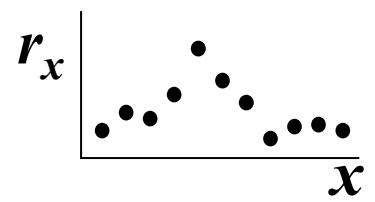
$$r_z = \frac{a}{a \cdot a} \frac{a \cdot r_x \ a \cdot r_y}{a \cdot r_x + a \cdot r_y} + \frac{b}{b \cdot b} \frac{a \cdot r_x \ b \cdot r_y + a \cdot r_y \ b \cdot r_x}{a \cdot r_x + a \cdot r_y} + c f(r_x, r_y)$$

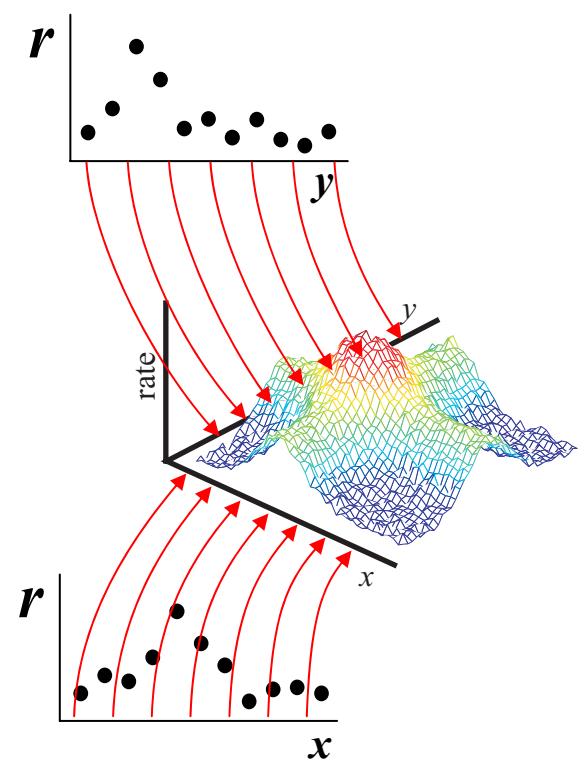
**quadratic nonlinearity:**  $\sum_{jk} w_{ijk} r_{xj} r_{yk}$

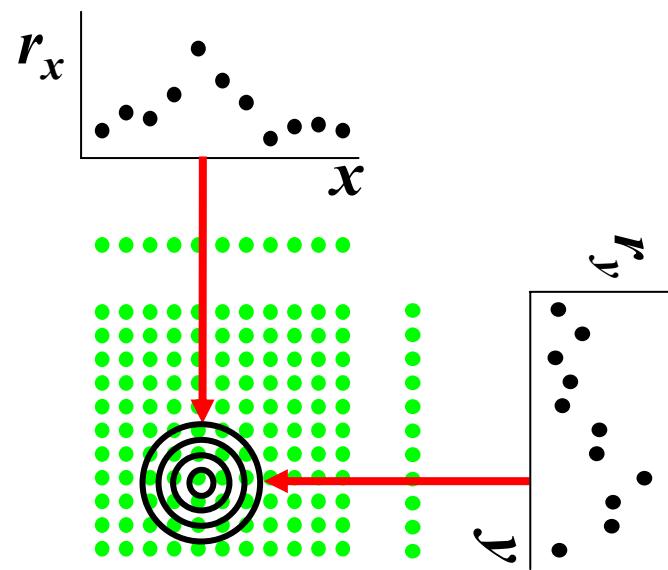
**divisive normalization**

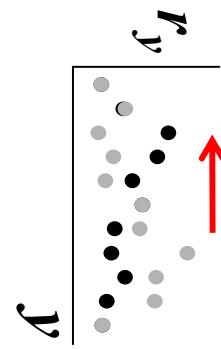
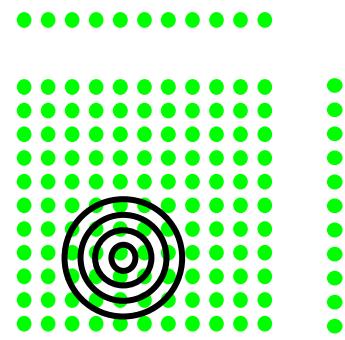
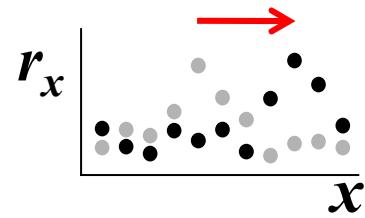
The optimal network has a quadratic nonlinearity and divisive normalization.

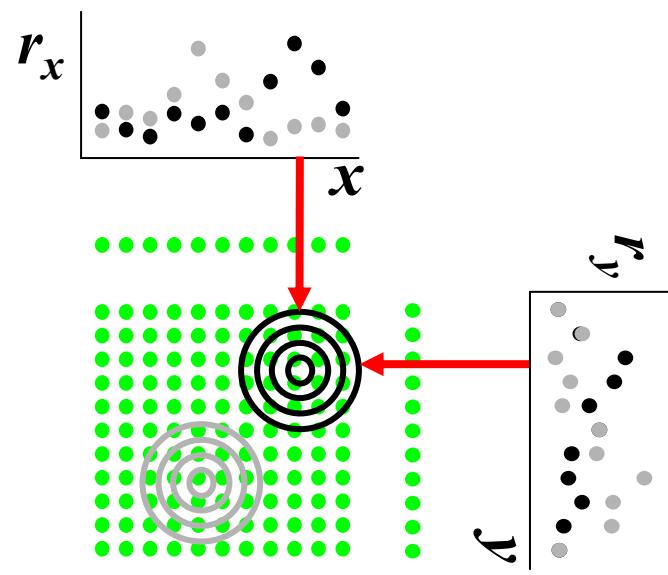


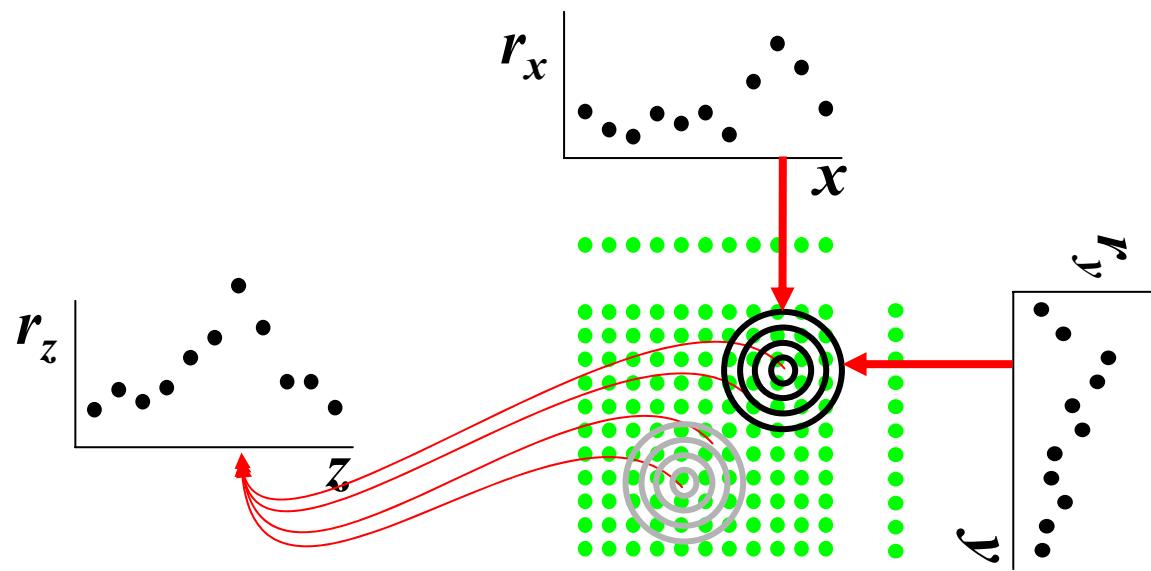


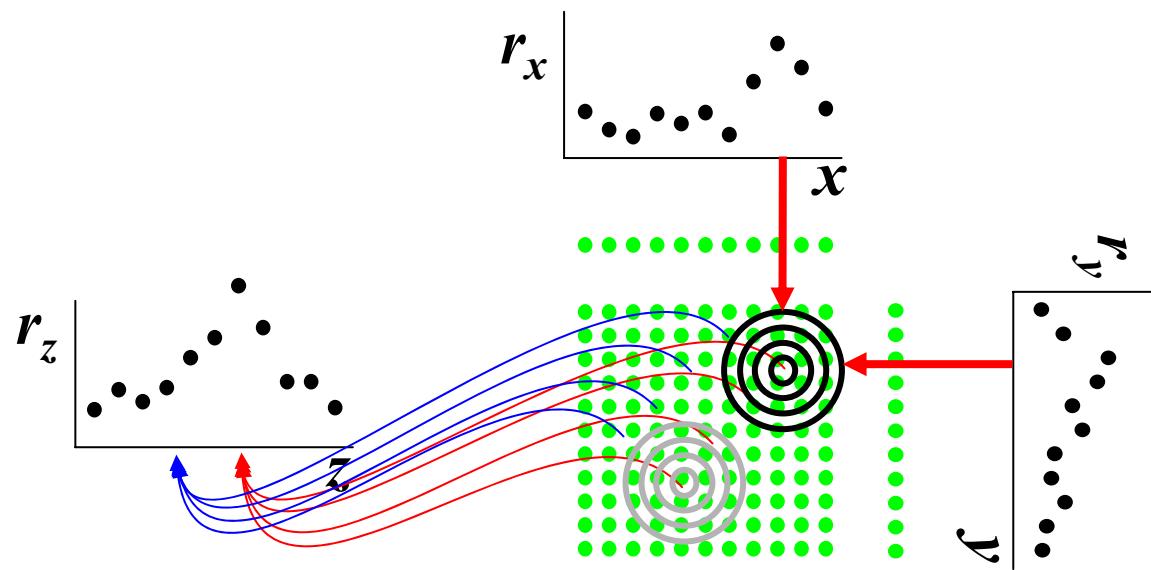








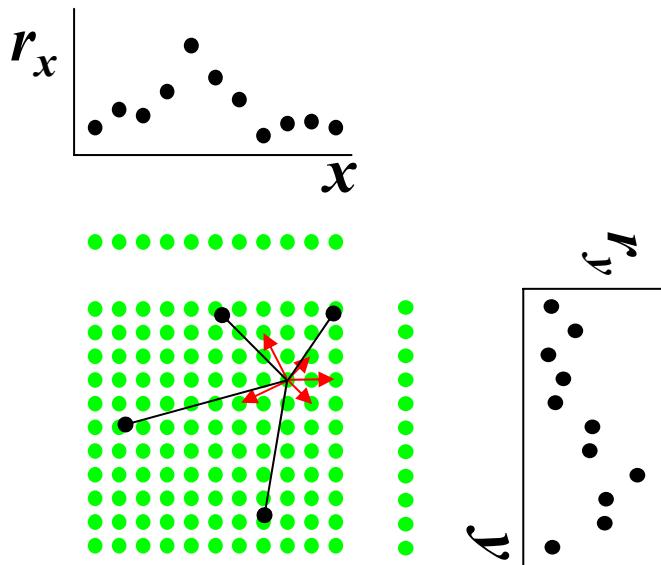




**the new analysis tells us  
exactly what the recurrent  
connections need to do:**

**they need to produce a hill  
of activity whose amplitude  
scales as**

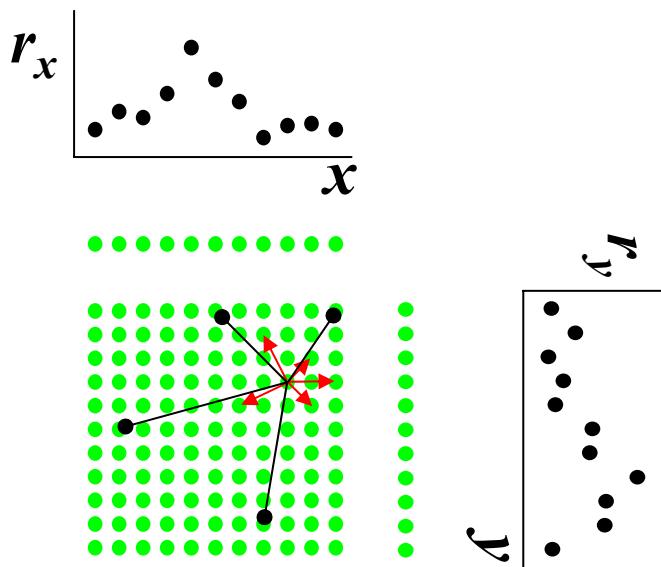
$$\frac{r_{xi} r_{yj}}{\sum_i a_i r_{xi} + a_i r_{yi}}$$

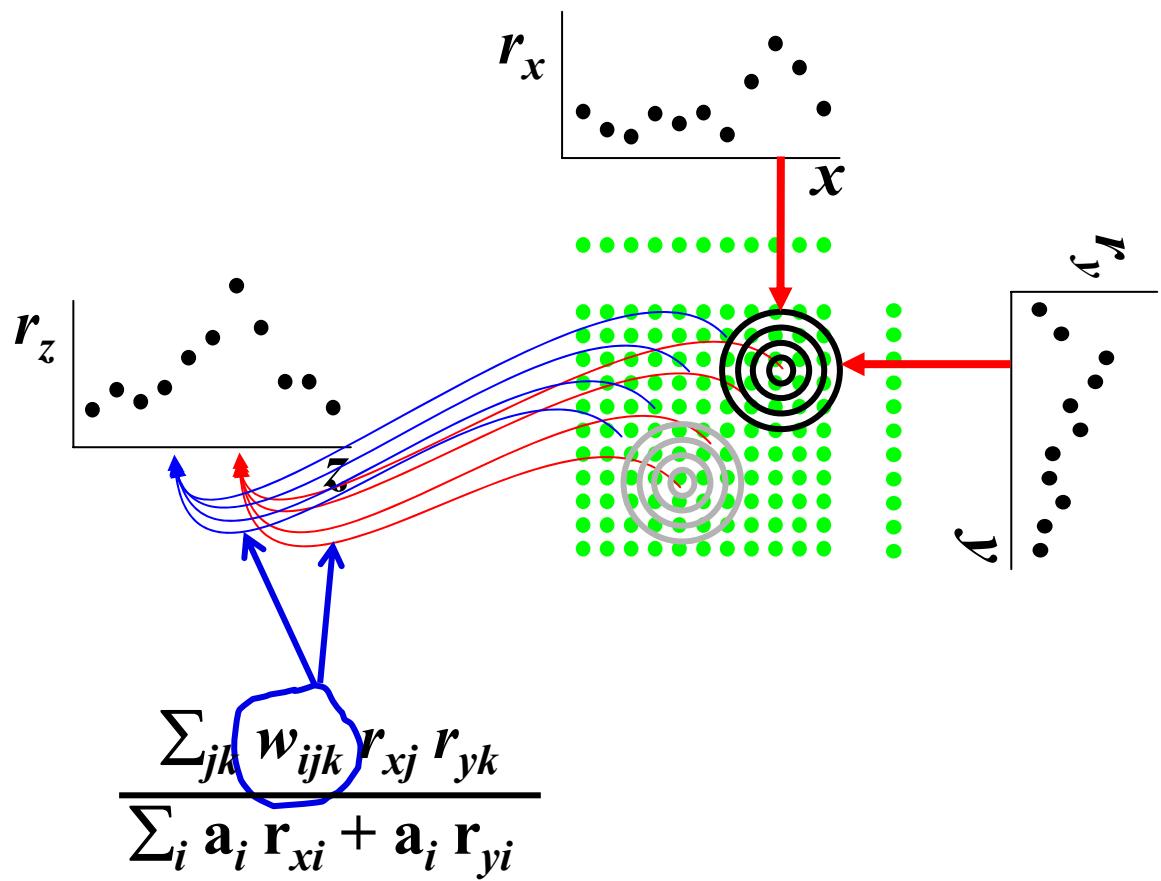


**the new analysis tells us  
exactly what the recurrent  
connections need to do:**

**they need to produce a hill  
of activity whose amplitude  
scales as**

$$\frac{\alpha r_{xi} + \beta r_{yi} + \gamma r_{xi} r_{yj}}{\sum_i a_i r_{xi} + a_i r_{yi}}$$





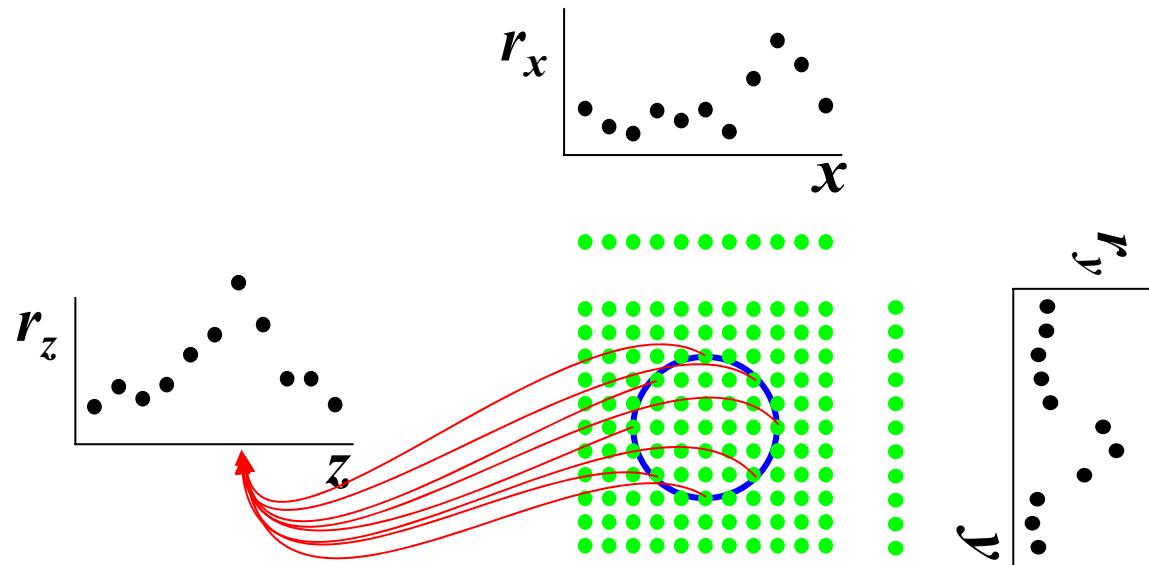
An aside: our network is deterministic,

$$r_z = \frac{a}{a \cdot a} \frac{a \cdot r_x \ a \cdot r_y}{a \cdot r_x + a \cdot r_y} + \frac{b}{b \cdot b} \frac{a \cdot r_x \ b \cdot r_y + a \cdot r_y \ b \cdot r_x}{a \cdot r_x + a \cdot r_y} + c f(r_x, r_y)$$

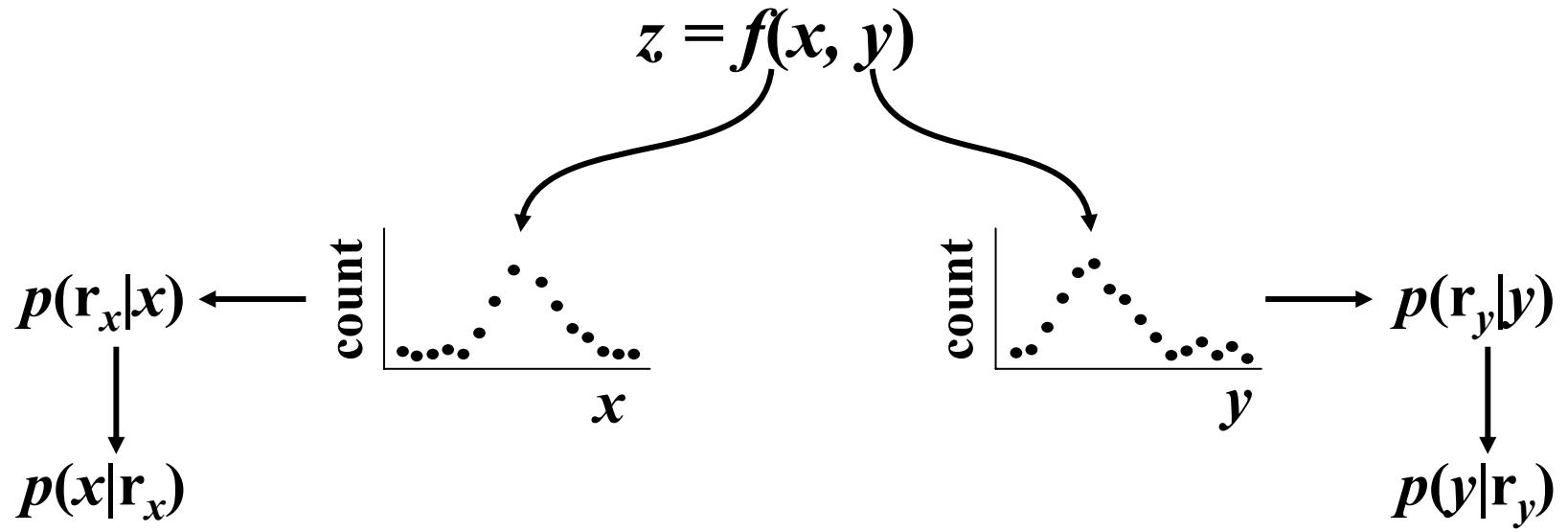
If neurons are sufficiently uncorrelated, we can replace rates with spikes, and the information loss will scale as  $1/N$ .

This information loss is negligible compared to the loss associated with approximate computations.

can handle nonlinear functions (e.g.,  $z=x^2+y^2$  )



the hard part is choosing the recurrent  
connectivity properly.



$$p(z|r_x, r_y) = \int dx dy \delta(z - f(x, y)) p(x|r_x) p(y|r_y)$$

**hard integral!**

$$p(z|\mathbf{r}_x, \mathbf{r}_y) = \int dx dy \delta(z - f(x, y)) p(x|\mathbf{r}_x) p(y|\mathbf{r}_y)$$

hard integral!

$$\mathbf{r}_z = \mathbf{F}(\mathbf{r}_x, \mathbf{r}_y) \leftarrow \text{network}$$

$$p(z|\mathbf{r}_z) = p(z|\mathbf{F}(\mathbf{r}_x, \mathbf{r}_y)) = p(z|\mathbf{r}_x, \mathbf{r}_y)$$

goal

approach: minimize

$$\mathbf{D}_{\text{KL}}(p(z|\mathbf{r}_x, \mathbf{r}_y) \parallel p(z|\mathbf{r}_z))$$

$$\mathbf{r}_z = \mathbf{F}(\mathbf{r}_x, \mathbf{r}_y)$$

network

**network:**  $\mathbf{r}_z = \mathbf{F}(\mathbf{r}_x, \mathbf{r}_y; \Theta)$

**minimize:**  $D_{KL}(p(z|\mathbf{r}_x, \mathbf{r}_y) || q(z|\mathbf{r}_z))$

**with respect to network parameters  
and parameters of encoding model**

**problem #1: there's a trivial solution,**

$$\mathbf{r}_z = (\mathbf{r}_x, \mathbf{r}_y)$$

**solution: demand that**

$$p(z|\mathbf{r}_z) \sim \exp[\mathbf{h}(z) \cdot \mathbf{r}_z]$$

**pure code!**

**minimize**

$$D_{KL}(p(z|r_x, r_y) || \exp[h(z) \cdot r_z]/Z)$$

**problem #2: what class of networks do we consider?**

$$r_{zi} = \frac{\sum_j w_{ij}^x r_{xj} + \sum_j w_{ij}^y r_{yj} + \sum_{jk} w_{ijk} r_{xj} r_{yk}}{a_i + w_i \sum_j a_j r_{xj} + a_j r_{yj}}$$

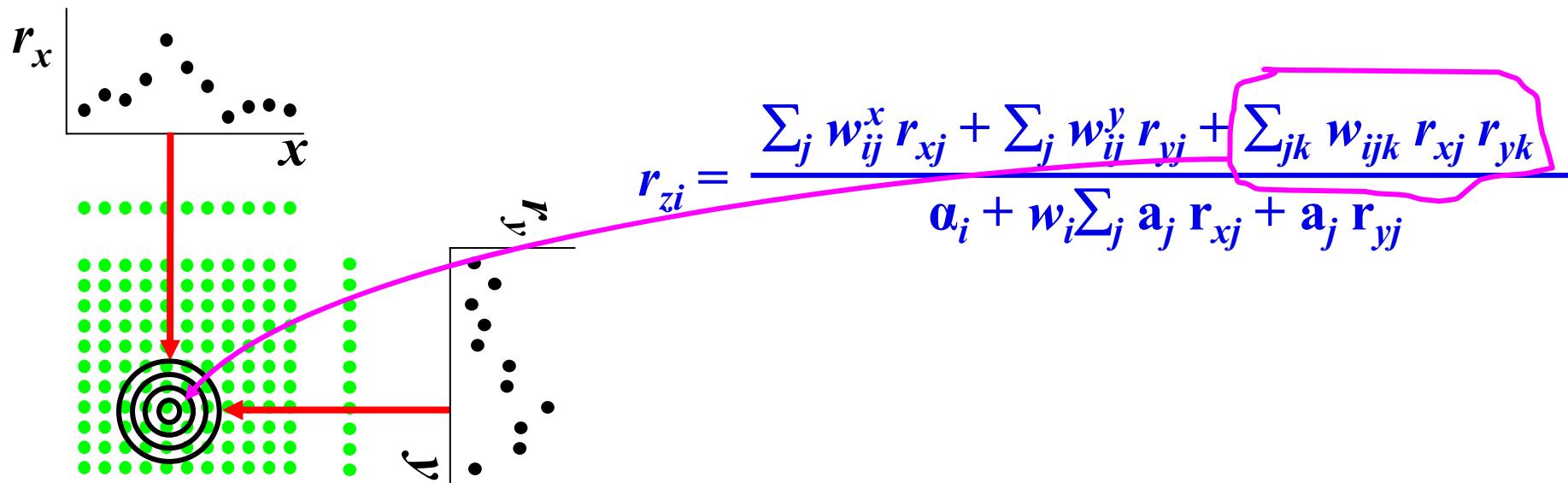
**minimize**

$$D_{KL}(p(z|r_x, r_y) || \exp[h(z) \cdot r_z] / Z)$$

**with respect to  $h(z)$  and the parameters of the network,**

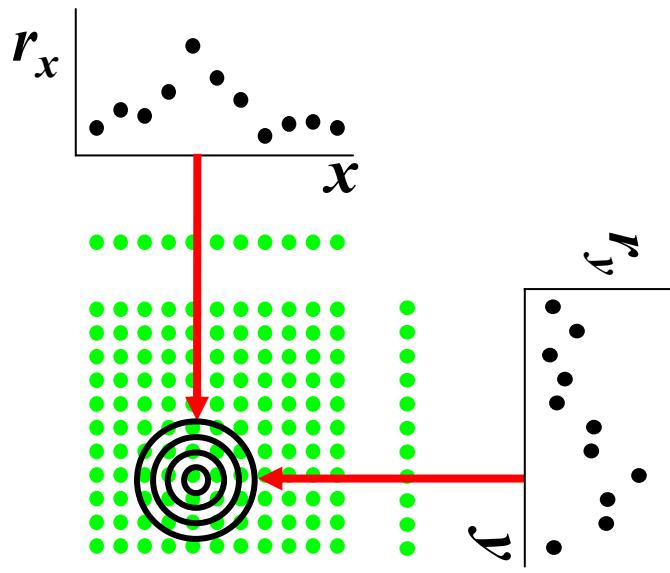
$$r_{zi} = \frac{\sum_j w_{ij}^x r_{xj} + \sum_j w_{ij}^y r_{yj} + \sum_{jk} w_{ijk} r_{xj} r_{yk}}{a_i + w_i \sum_j a_j r_{xj} + a_j r_{yj}}$$

## intuition



- quadratic nonlinearity produces a hill of activity
- divisive normalization corrects for it

## intuition

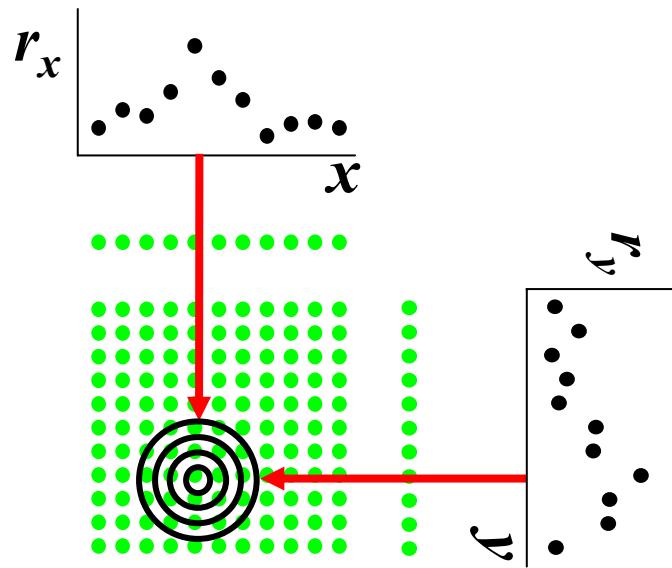


$$r_z = \frac{r_x r_y}{r_x + r_y}$$

$$\begin{aligned} 1/r_z &= 1/r_x + 1/r_y \\ \sigma_z^2 &\sim 1/r_z \end{aligned}$$

$$z=f(x, y) \Rightarrow \sigma_z^2 = \alpha \sigma_x^2 + \beta \sigma_y^2$$

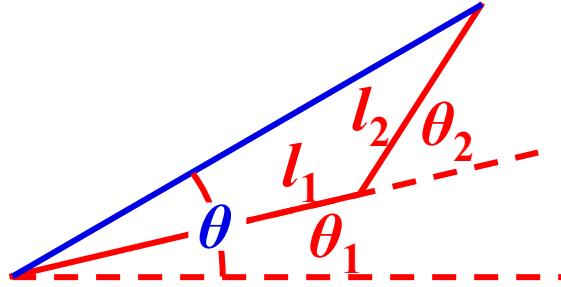
## intuition



$$r_{zi} = \frac{\sum_j w_{ij}^x r_{xj} + \sum_j w_{ij}^y r_{yj} + \sum_{jk} w_{ijk} r_{xj} r_{yk}}{a_i + w_i \sum_j a_j r_{xj} + a_j r_{yj}}$$

$$z=f(x, y) \Rightarrow \sigma_z^2 = \alpha \sigma_x^2 + \beta \sigma_y^2$$

## 2-joint arm



$$\theta = \tan^{-1} \frac{l_1 \sin(\theta_1) + l_2 \sin(\theta_1 + \theta_2)}{l_1 \cos(\theta_1) + l_2 \cos(\theta_1 + \theta_2)}$$

$$p(\mathbf{r}|\boldsymbol{\theta}) \sim \exp[ \sum_i \cos(\theta - \varphi_i) r_i ]$$

minimize

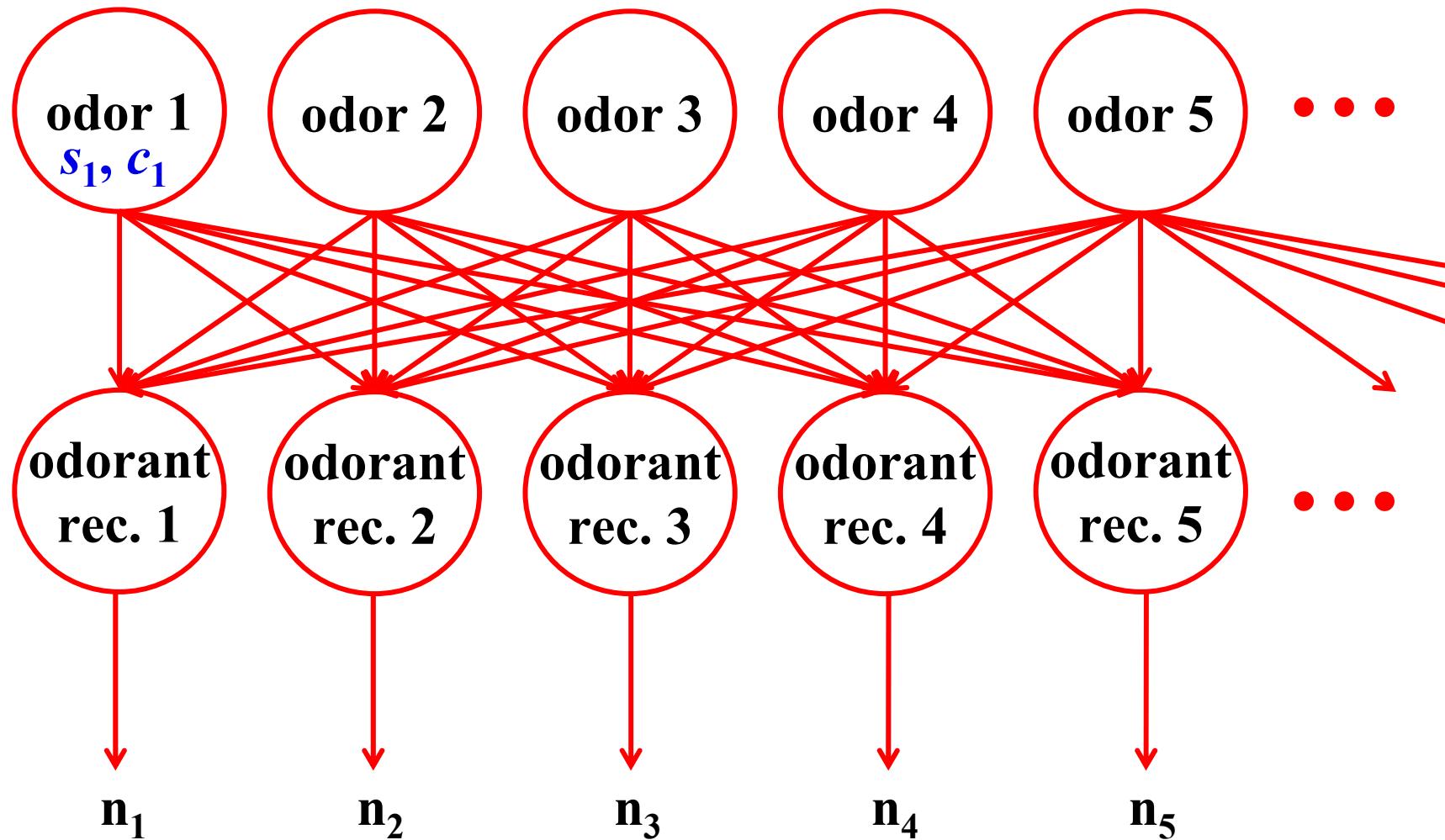
$$D_{KL}(p(\theta|r_1, r_2) || \exp[h(\theta) \cdot r] / Z)$$

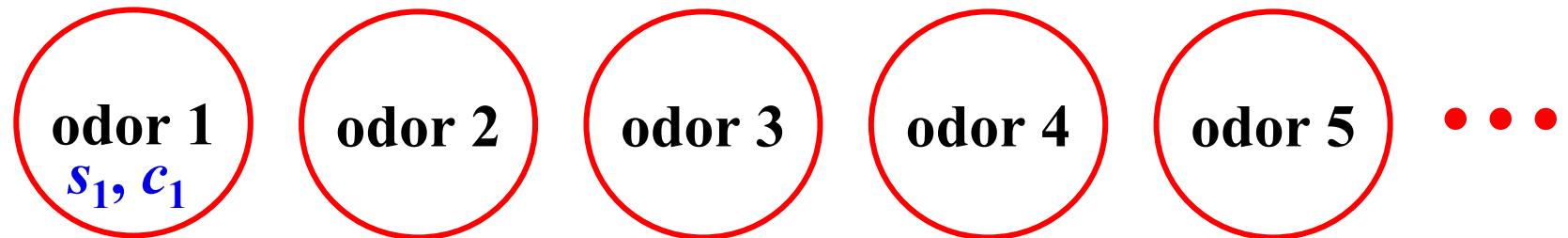
with respect to the parameters of the network

$$r_i = \frac{\sum_j w_{ij}^1 r_{1j} + \sum_j w_{ij}^2 r_{2j} + \sum_{jk} w_{ijk} r_{1j} r_{2k}}{a_i + w_i \sum_j a_j r_{1j} + a_j r_{2j}}$$

$$\frac{D_{KL}(p(\theta|r_1, r_2) || p(\theta|r))}{I(\theta; r_1, r_2)} \approx 0.05 \text{ (5% information loss)}$$

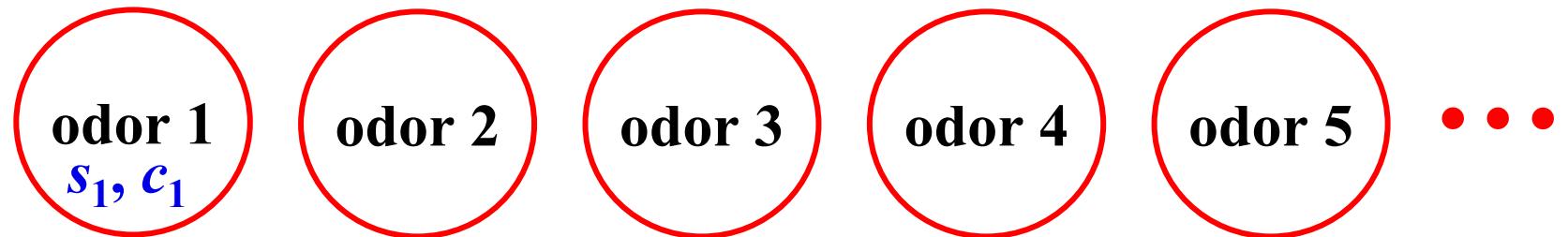
### 3: a hard problem (simplified olfaction)





$s$ :    0=absent  
      1=present

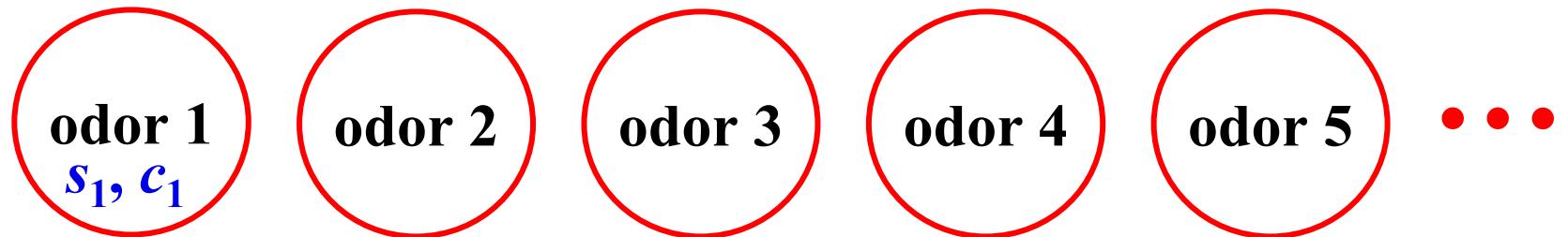
$c$ : concentration



$$o_i = \sum_j W_{ij} s_j c_j$$

$$p(\mathbf{n}_i | o_i) \sim \exp[\mathbf{h}(o_i) \cdot \mathbf{n}_i]$$

goal: compute  $p(s_i | \mathbf{n}_1, \mathbf{n}_2, \mathbf{n}_3, \dots)$

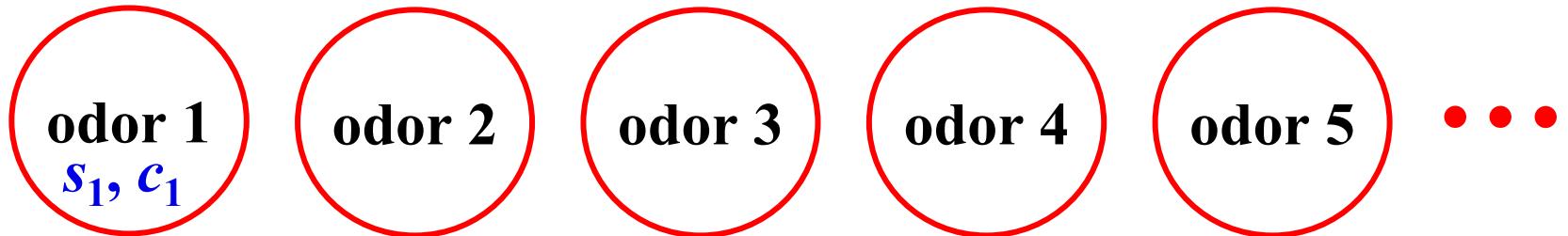


**find a network**

$$n_i^{\text{out}} = F(n_1, n_2, \dots)$$

**such that**

$$p(s_i | n_i^{\text{out}}) = p(s_i | n_1, n_2, \dots)$$



**Intractible:**

$$p(s_i | \mathbf{n}_1, \mathbf{n}_2, \dots) = \sum_{\{s_j, j \neq i\}} \int d\mathbf{c} p(s_1, c_1, s_2, c_2, \dots | \mathbf{n}_1, \mathbf{n}_2, \dots)$$

↓  
 k odors:  
 2<sup>k-1</sup> terms  
 in the sum

k-dimensional  
 integral

**minimize**

$$D_{KL}(p(s_i|n_1, n_2, \dots) || \exp[h(s_i) \cdot n_i^{\text{out}}] / Z)$$

**with respect to the parameters of the network**

$$n_i^{\text{out}} = \frac{\sum_{jk} w_{ij}^k n_{kj} + \sum_{jk} w_{ijk}^{km} n_{lj} n_{mk}}{a_i + w_i \sum_{jk} a_j^k n_{kj}}$$

$$\frac{D_{KL}(p(s_i|n_1, n_2, n_3, n_4) || p(s_i|n_i^{\text{out}}))}{I(s_i; n_1, n_2, n_3, n_4)} \approx 0.02 \text{ (2% information loss)}$$

4 odors:

$$\frac{D_{KL}(p(s_i|\mathbf{n}_1, \mathbf{n}_2, \mathbf{n}_3, \mathbf{n}_4) || p(s_i|\mathbf{n}_i^{\text{out}}))}{I(s_i; \mathbf{n}_1, \mathbf{n}_2, \mathbf{n}_3, \mathbf{n}_4)} \approx 0.02 \text{ (2% information loss)}$$

**100s of odors:**

**work in progress**

# Summary

Our approach: minimize

$$D_{KL}(p(\xi | \mathbf{r}^{in}) || \exp[\mathbf{h}(\xi) \cdot \mathbf{r}^{out}] / Z)$$
$$\xi = f(x, y, z, \dots)$$
$$(x, y, z, \dots)$$

with respect to the parameters of the network

$$r_i^{\text{out}} = \frac{\sum_j w_{ij} r_j^{\text{in}} + \sum_{jk} w_{ijk} r_j^{\text{in}} r_k^{\text{in}}}{a_i + w_i \sum_j a_j r_j^{\text{in}}}$$

# Summary

Our approach: minimize

$$D_{KL}(p(\xi | \mathbf{r}^{in}) || \exp[\mathbf{h}(\xi) \cdot \mathbf{r}^{out}] / Z)$$
$$q(\xi | x, y, z, \dots)$$
$$(x, y, z, \dots)$$

with respect to the parameters of the network

$$r_i^{\text{out}} = \frac{\sum_j w_{ij} r_j^{\text{in}} + \sum_{jk} w_{ijk} r_j^{\text{in}} r_k^{\text{in}}}{a_i + w_i \sum_j a_j r_j^{\text{in}}}$$

# Summary

Our approach: minimize

$$D_{KL}(p(\xi|r^{in}) || \exp[h(\xi) \cdot r^{out}] / Z)$$
$$\rightarrow q(\xi | x, y, z, \dots)$$
$$\rightarrow (x, y, z, \dots)$$

Just finding  $p(\xi|r^{in})$  is a hard inference problem,

$$p(\xi|r^{in}) = \int dx dy dz \dots \delta(\xi - f(x, y, z, \dots)) p(x, y, z, \dots | r^{in})$$

implementing it in a network is even harder.

$$p(\xi | \mathbf{r}^{in}) = \int dx dy dz \dots \delta(\xi - f(x, y, z, \dots)) p(x, y, z, \dots | \mathbf{r}^{in})$$

**We have to do approximate inference.**

- parameterized probability distributions.
- approximate networks, chosen by minimizing a cost function.

I talked about one parameterization and one class of networks. The big open questions:

**what is the appropriate parameterization for the brain?**  
**what is the appropriate class of networks?**  
**how is all this learned?**



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