Sound waves in granular materials the role of disorder, friction, adhesion, ...

Stefan Luding et al. (see below) Multi Scale Mechanics, CTW, UTwente, POBox 217, 7500AE Enschede, NL --- s.luding@utwente.nl



Force-chains experiments - simulations





Force-chains experiments - simulations



Codalike Multiple Scattering of ElasticWaves in Dense Granular Media X. Jia, PRL, 2004



Self-demodulation acoustic signatures for nonlinear propagation in glass beads

V. Tournat et al, C.R.Mecanique, 2002



Discrete particle model



Equations of motion



Forces and torques:

 $\vec{f}_i = \sum_c \vec{f}_i^c + \sum_w \vec{f}_i^w + m_i g$

$$\vec{t_i} = \sum_c \vec{r_i^c} \times \vec{f_i^c}$$

 $\cdot \vec{n}$



Overlap

Normal

$$\delta = \frac{1}{2} \left(d_i + d_j \right) - \left(\vec{r}_i - \vec{r}_j \right)$$
$$\hat{n} = \vec{n}_{ij} = \frac{\left(\vec{r}_i - \vec{r}_j \right)}{\left| \vec{r}_i - \vec{r}_j \right|}$$



Sound

Compressive (P) and Shear (S) waves



Time signals



Frequency dependence

- Compressive wave
- Input frequency
- Large amplitude

Number of contacts in the whole system versus time



Compressive (P)-wave

Influence of "micro" properties



How relevant is the damping coefficient in our model?

Model system



P-wave animation



Towards complexity

Modes

- P-waves
- S-waves
- R-waves ullet
- . . .

Micro-Parameters

- Damping •
- Friction (Rotations)
 (Dis-)ordered
- Adhesion
- Contact law

. . .

Structure

. . .

- Mono- poly-disperse

Wave speed from the stiffness tensor

$$C_{\alpha\beta\gamma\phi} = \frac{1}{V} \sum_{p \in V} \frac{a^2}{2} \left(k \sum_{c=1}^C n_\alpha^c n_\beta^c n_\gamma^c n_\phi^c + k^t \sum_{c=1}^C n_\alpha^c t_\beta^c n_\gamma^c t_\phi^c \right)$$

$$V_{pz} = \sqrt{\frac{C_{zzzz}}{\rho}}$$

Velocities



Friction

Waves and stiffnesses

- Components of the stiffness tensor which corresponds to the direction of motion of the particles for both P- and S-wave.

- In this case : $C_{\rm 3333}$ for the P-wave and $C_{\rm 1313}$ for the S-wave.

- V_p and V_s denote the "Peak velocity".





Waves and stiffnesses

Ratios of C entries		Ratios of velocities	
1111/ 1313	2.5	11/13	2.475
3333/ 1313	2	33/13	2.005
1111/ 1212	5	11/12	4.95



Weak polydispersity



- The system is practically unchanged at the structure level

- Wide distribution of weak and strong contacts and <u>most important opening of contacts</u>

P-wave animation



Velocities



Friction+rotation

Weak disorder

Signal Analysis



Stress-time signal

Power-spectrum

Frequency-space Diagrams





Distance in layers





Frequency analysis



Larger system



Shear wave



P-wave with friction



Hertz Contact Law





How does sound propagation depend on

- structure?

Lattice+tiny disorder => enormous effect

Question

How does sound propagation depend on

- structure?

Lattice+tiny disorder => enormous effect 3D effect? or 1D?

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Sound Propagation in Particulate Systems with Disorder and Rotations ...

Lisa de Mol,S. Emmerich, Brian Lawney, Vanessa Magnanimo, Stefan Luding Multi-Scale Mechanics, UTwente, Netherlands





OVERVIEW

L.de Mol, B.Lawney, V. Magnanimo, S. Luding

Introduction: Frequency filtering and high-f bands

One-dimensional chains

Model system and equations
Introduction of mass–disorder (most simple)
Model for frequency (low-pass) filtering

Two- and three-dimensional regular packings with rotations

•Dispersion relation

- Smooth (frictionless)
- With friction/rotations



ONE DIMENSIONAL CHAINS

L.de Mol, B.Lawney, V. Magnanimo, S. Luding



- Convenient model
 - Analytically accessible
 - Isolation of mass-disorder
- Significant attention in literature
 - Nonlinear oscillators
 - Soliton–like waves



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ONE DIMENSIONAL CHAINS

Force Displacement Model

$$\tilde{F}_{(i,j)} = \tilde{\kappa}_{(i,j)} \tilde{\delta}^{1+\beta}$$

$$\tilde{m}^{(i)} \frac{d^2 \tilde{x}^{(i)}}{d\tilde{t}^2} = \tilde{F}_{(i,i-1)} + \tilde{F}_{(i,i+1)}$$



Scaling

• Mass
$$\tilde{m}_o$$

• Length $\tilde{\ell}$
• Time $\tilde{t}_c = \frac{1}{\tilde{\ell}^{\beta/2}} \sqrt{\frac{\tilde{m}_o}{\tilde{\kappa}_o}}$

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General equation of motion



$$b^{(i)} \frac{d^2 u^{(i)}}{d\tau^2} = \kappa_{(i-1,i)} \left[\Delta_{(i-1,i)} - u^{(i)} + u^{(i-1)} \right]^{1+\beta} -\kappa_{(i+1,i)} \left[\Delta_{(i+1,i)} + u^{(i)} - u^{(i+1)} \right]^{1+\beta}$$

$$b \equiv \tilde{m}^{(i)} / \tilde{m}_o$$
$$\tau \equiv \tilde{t} / \tilde{t}_c$$
$$\kappa_{(i,j)} \equiv \tilde{\kappa}_{(i,j)} / \tilde{\kappa}_o$$

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• General (nonlinear) equation of motion:

$$b^{(i)} \frac{d^2 u^{(i)}}{d\tau^2} = \kappa_{(i-1,i)} \left[\Delta_{(i-1,i)} - u^{(i)} + u^{(i-1)} \right]^{1+\beta} -\kappa_{(i+1,i)} \left[\Delta_{(i+1,i)} + u^{(i)} - u^{(i+1)} \right]^{1+\beta}$$

• Linearized model:

$$\mathbf{M} rac{\mathrm{d}^2 \mathbf{u}}{\mathrm{d}\tau^2} = \mathbf{K} \mathbf{u}$$



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Analytical Solution: Sine-agitation

$$u^{(p)}(\tau) = \sum_{j=1}^{N} \frac{S_{pj} S_{1j}}{\left(\omega_j^2 - \omega_o^2\right)} \left(\sin \omega_o \tau - \frac{\omega_o}{\omega_j} \sin \omega_j \tau\right)$$

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• Harmonically driven:



- Mass-disorder: Normal (Gaussian) distribution
 - Mean mass \rightarrow b = 1
 - Standard deviation $\rightarrow \sigma = \xi$
- Pre-stress \rightarrow equilibrium overlap \rightarrow NOT sonic vacuum



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How do signals propagate in such systems?

- Disorder ξ
- Input frequency ω_0
- Mass distribution
- Contact order/disorder
- Linear vs. nonlinear



BASE CASE – PERFECT CHAIN

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• Uniform stiffness κ(i,j) = kn

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CONCLUSIONS 1

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- \uparrow disorder ξ , \downarrow transmission bandwidth.
 - Threshold value of ξ
- Lower input ω_o , improved transmission
 - Low frequencies less sensitive to mass arrangements
- Mass-distribution: only moments matter ...

QUALITATIVELY THE SAME AS IN 3D => PROCEED ANALYTICAL 1D



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• Evolution (Master) Equation in k-space or w-space

$$\frac{d}{dt}\Psi = \mathbf{Q}\Psi \qquad \qquad \frac{d}{dx}$$

$$\frac{d}{dx}\Psi = \mathbf{Q}\Psi$$



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ONE DIMENSIONAL CHAINS

• Linearized model:

$$\mathbf{M}\frac{\mathrm{d}^2\mathbf{u}}{\mathrm{d}\tau^2} = \mathbf{K}\mathbf{u}$$

• Evolution (Master) Equations in f-space or k-space

$$\frac{d}{dt}\Psi = \mathbf{Q}\Psi$$

$$\frac{\mathrm{d}}{\mathrm{d}t}q^{\downarrow}(f_i) = -b_i q(f_i) + \sum_{1 \le j < N-i} b_{i+j}^i q(f_{i+j})$$
$$b_i = \sum_{j \ge 1} b_{i+j}^i$$

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THREE DIMENSIONAL CHAINS

• Linearized model: $\mathbf{M} \frac{\mathrm{d}^2 \mathbf{u}}{\mathrm{d}\tau^2} = \mathbf{K} \mathbf{u}$

• Evolution (Master) Equations in f-space or k-space



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ONE DIMENSIONAL CHAINS

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$$b_i = \sum_{j \ge 1} b_{i+j}^i$$
onlinear

Nonlinear ...

$$\frac{d}{dt}q^{\uparrow}(f_{i}) = -\sum_{j} a_{i,j} q(f_{i})q(f_{j}) + \sum_{j < i} a_{i-j,j} q(f_{i-j})q(f_{j})$$

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Self-demodulation ? higher f/k-generation





OVERVIEW

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- Smooth (frictionless)
- With friction/rotations

Experiments (in water) ...

HOMOGENEOUS & STRUCTURED SAMPLES MSc thesis S. Emmerich

- Solid sample and porous sample (PCL) with $\Phi = 0.7$
- Discrete particle radii of 0.01 mm
- Stratified model used to build the porous sample
- Wave velocity needs to be calculated:





Fig. 13: Modeling differences between solid and porous samples

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DISORDERED SAMPLES MSc thesis S. Emmerich



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DISORDERED SAMPLES MSc thesis S. Emmerich



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REGULAR SYSTEMS

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Cubic lattice

Hexagonal lattice







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MD APPROACH

• Equations of motion

$$\mathbf{M}^{p} \cdot \ddot{\mathbf{U}}^{p} = \sum_{q} \mathbf{F}^{pq}$$

 $\mathbf{M}^{p} \cdot \ddot{\mathbf{U}}^{p} = \sum_{c} \mathbf{S}^{c} \Delta^{c}$

where

- U^p is the generalized coordinate vector (including rotations)
- \mathbf{S}^{c} is the contact stiffness matrix
- Δ^c contact overlap (linear spring model)



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EIGENVALUE PROBLEM

• Harmonic wave solution

 $\mathbf{U} = \hat{\mathbf{U}} e^{i(\omega t - \mathbf{k}\mathbf{x})}$

• Inserted into the equation of motion

$$\left(\bar{\mathbf{K}} - \omega^2 \mathbf{M}\right) \hat{\mathbf{U}} = 0$$

• Solve Eigenvalue problem for a wave excitation in vertical direction



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DISPERSION

SOUND PROPAGATION IN PARTICULATE SYSTEMS WITH DISORDER AND ROTATIONS

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Dispersion relations with tangential elasticity





Eigenmodes



Eigenmodes





SUMMARY AND OUTLOOK

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- 2D+3D dispersion relations
 - Frictionless lattices
 - Lattices with rotation (tang. elasticity)

WORK IN PROGRESS

- Fully random Systems and
- Comparison with Experiments