

# Jamming, Shear, and Avalanches in Granular Materials

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# Context for Dense Granular Phases—some identifying features

Frozen structure: forces are carried preferentially on **force chains**, ‘long’ force chains  $\rightarrow$  anisotropy in local stress

Deformation, particularly shear, leads to large **spatio-temporal fluctuations**

Also, shear leads to **dilation and shear bands**

Granular materials jam, and shear leads to **jamming below  $\phi_J$** ,

**Friction** and preparation history matter

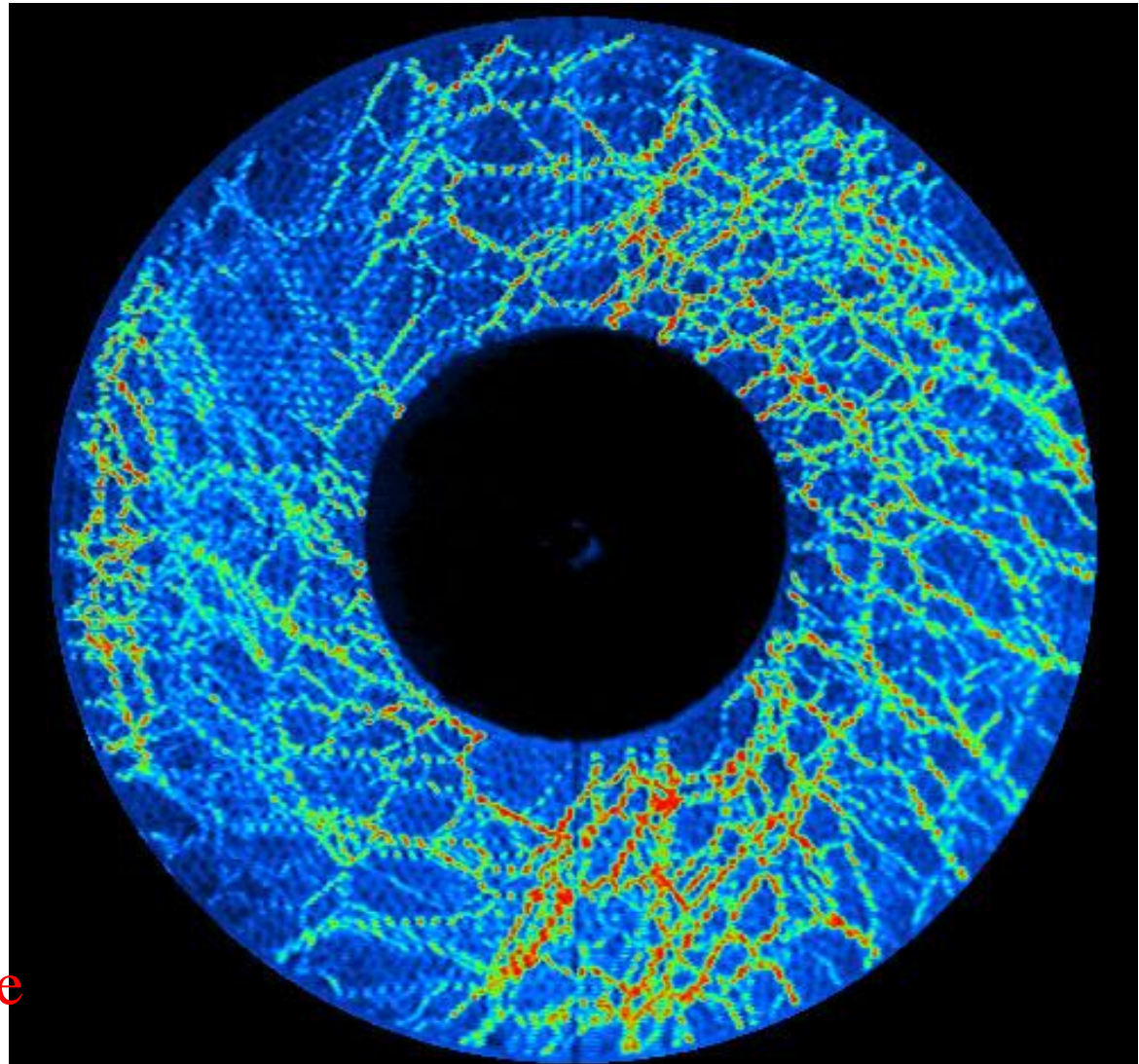


GM's exhibit novel meso-scale structures:

## Force Chains:

These depend on the preparation of the material—long chains → shear → stress and network anisotropy

2d Shear →  
Experiment



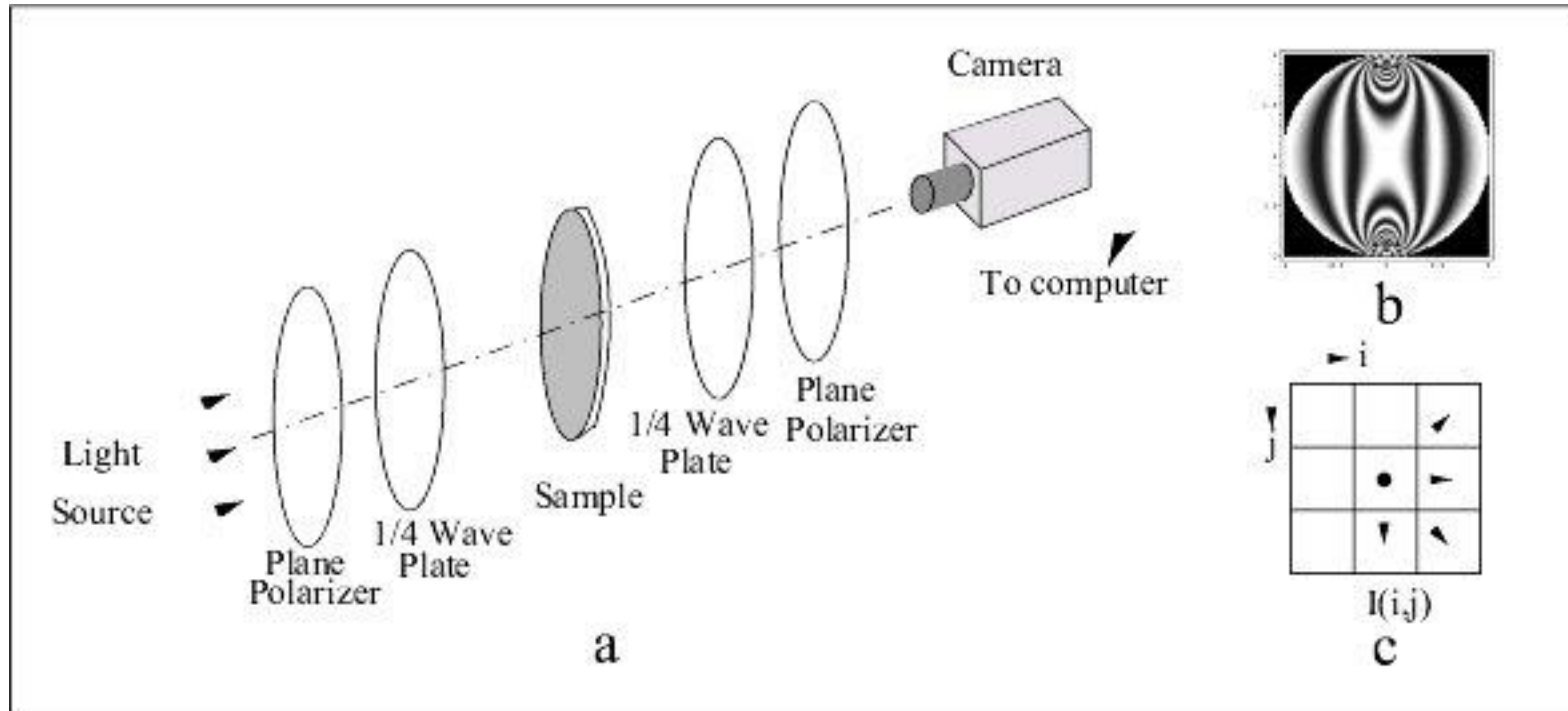
Howell et al.

PRL 82, 5241 (1999)

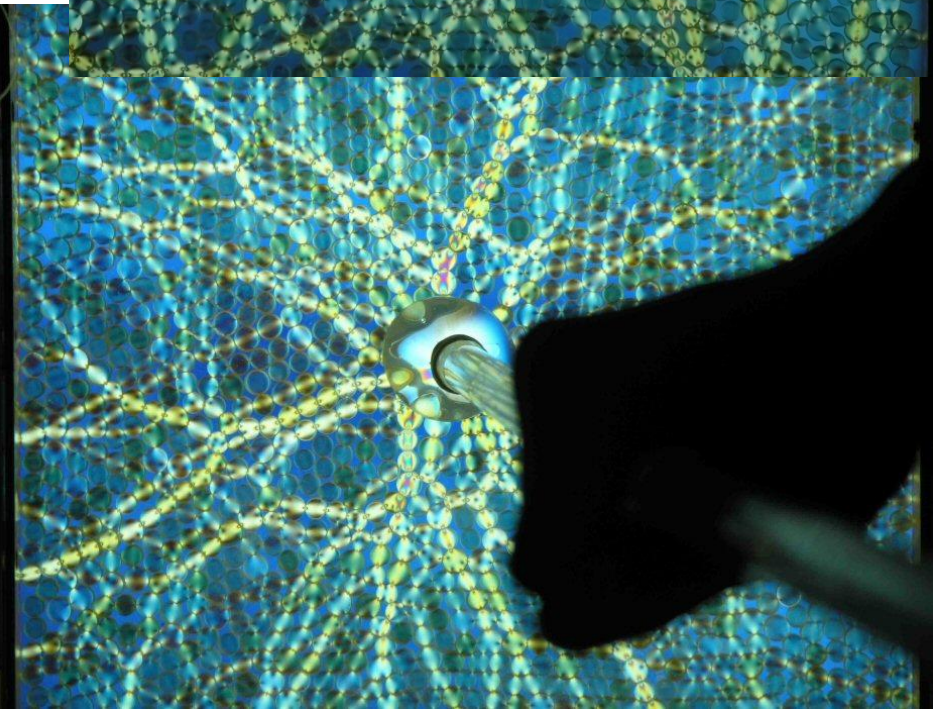
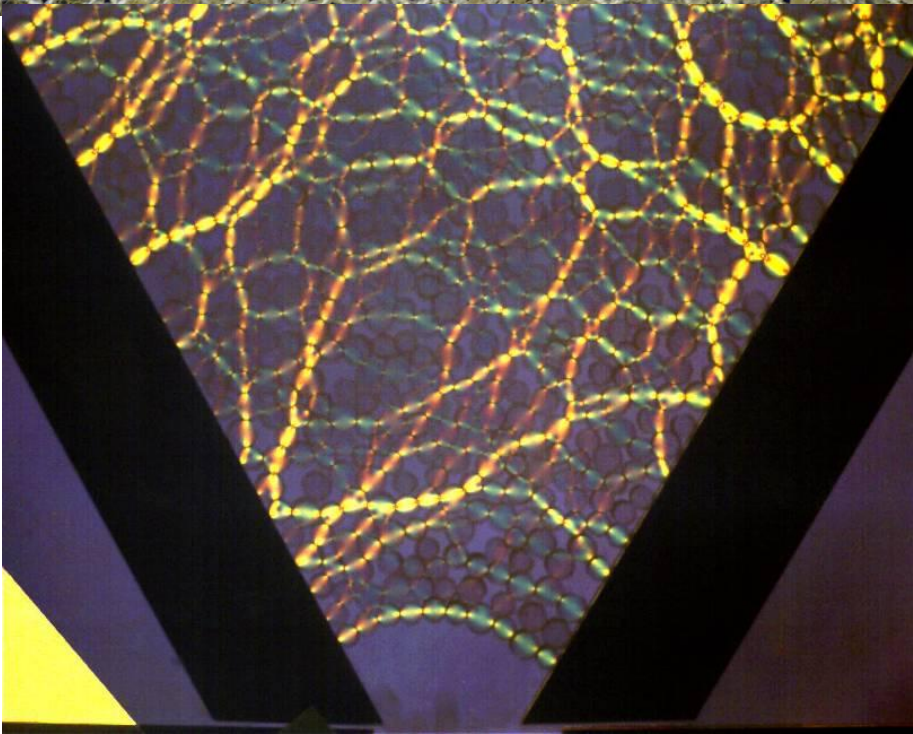
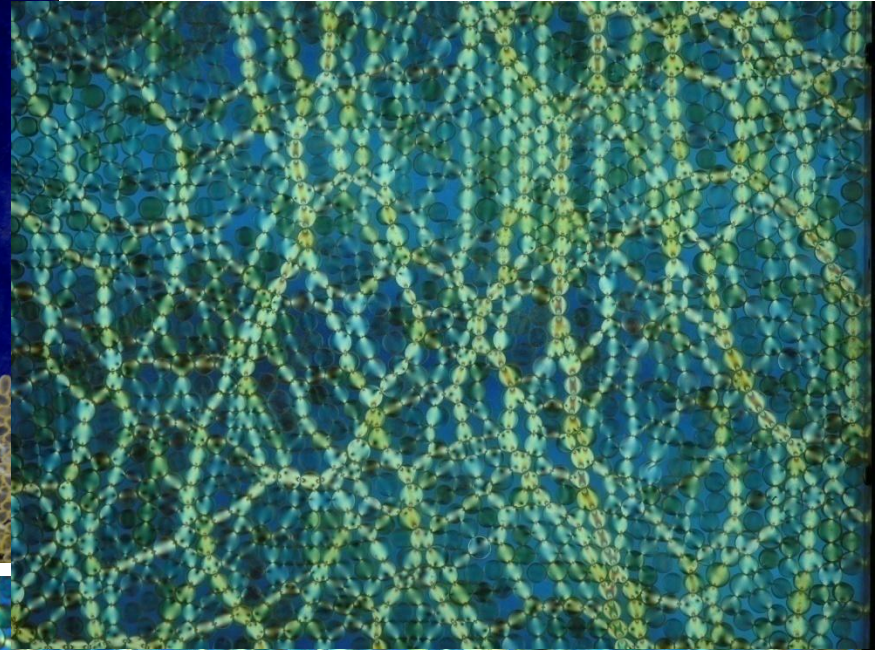
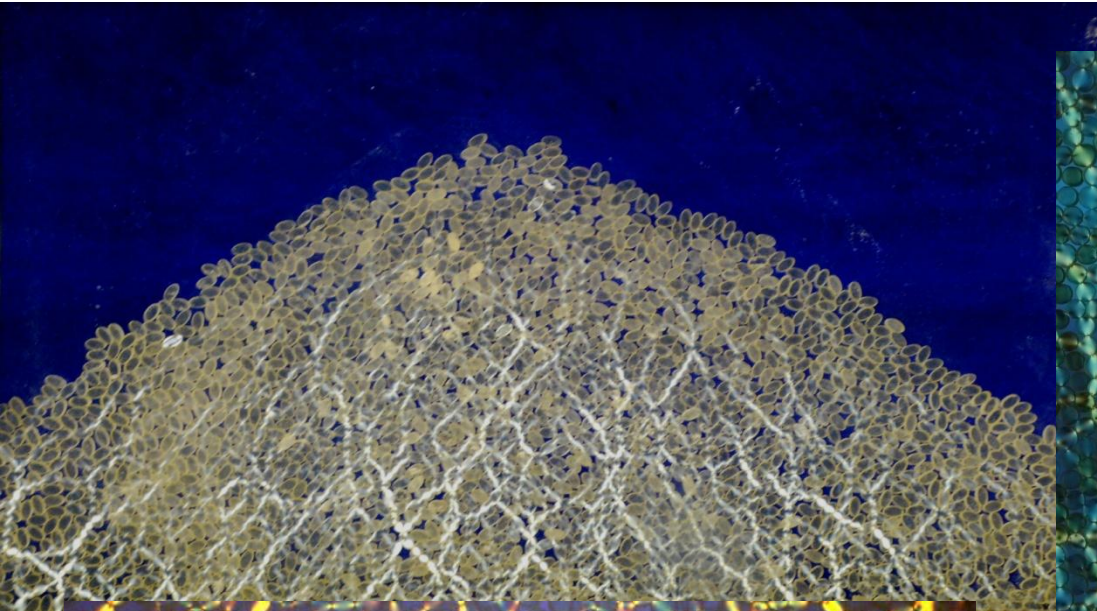
Introduces quantitative  
grain-scale force data



# Measuring contact forces by photoelasticity



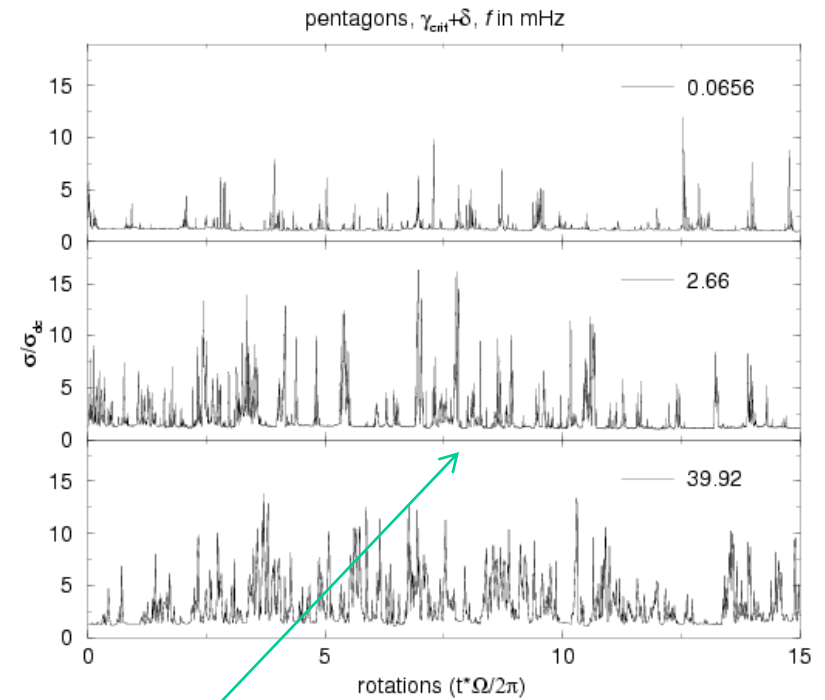
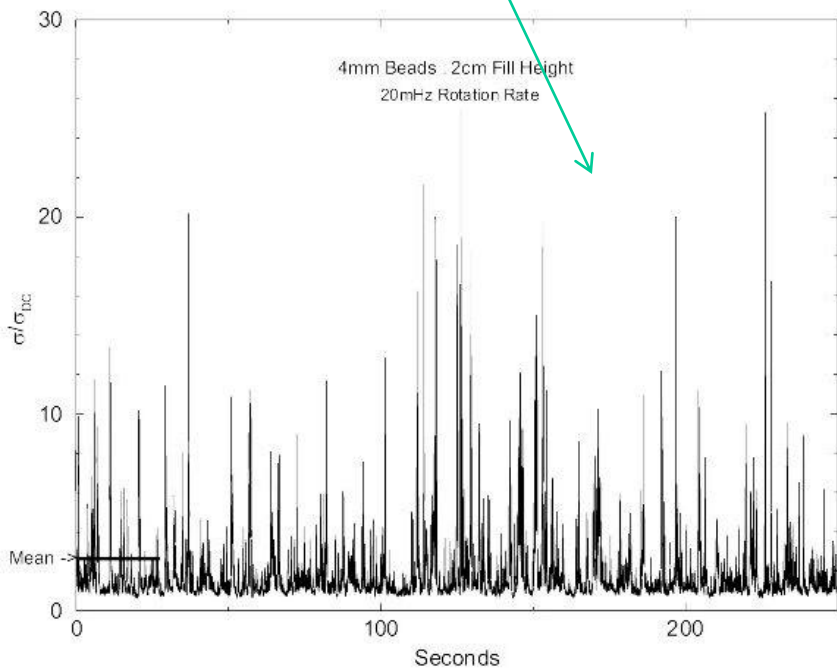
# Force networks





# Rearrangement of force chains leads to strong force fluctuations

## Time-varying Stress in 3D Shear Flow



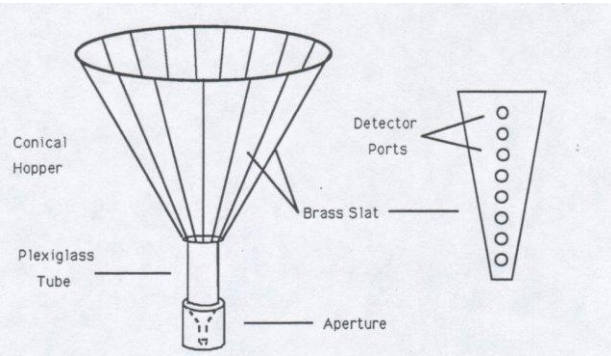
Time-varying stresses  
In 2D Couette shear  
Hartley and Howell et al.  
PRL, 1999, Hartley et al.  
Nature 2003

Miller O'Hern, RPB . PRL 77, 3110 (1996)

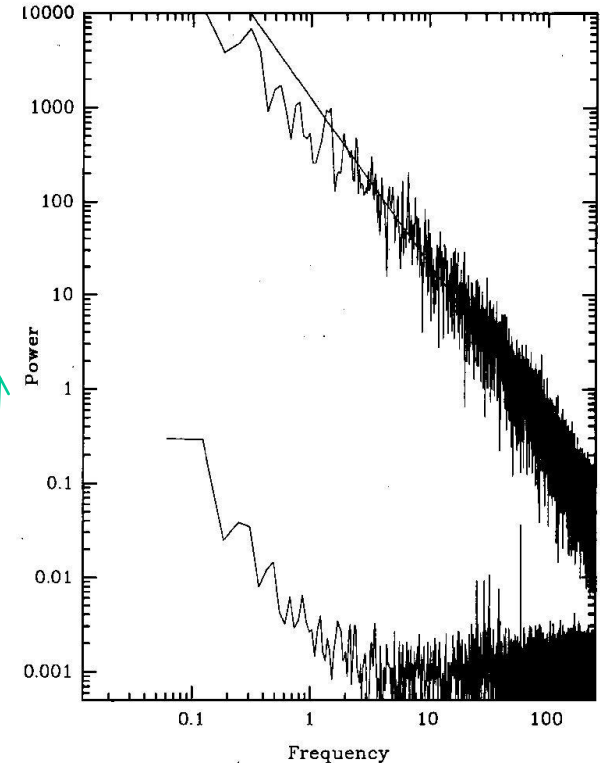
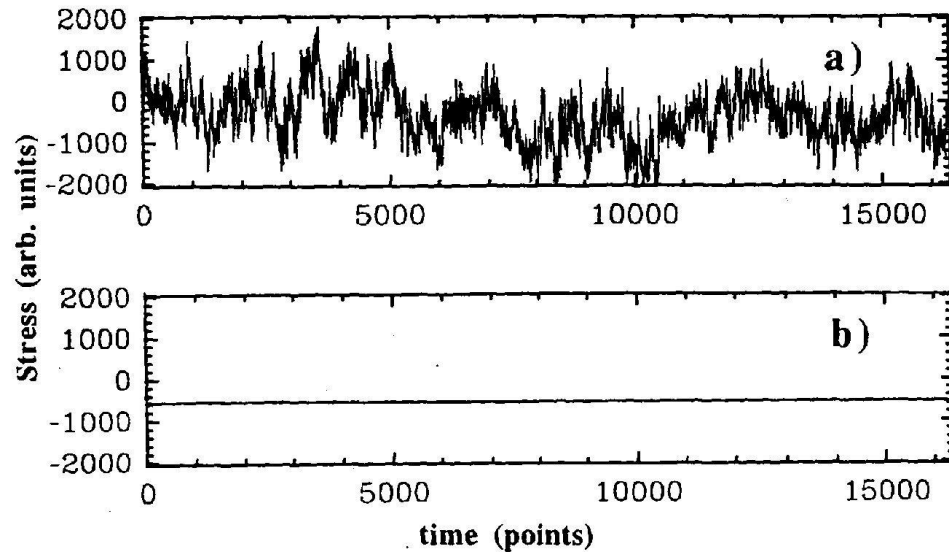


# Fluctuations Dominate Instabilities in Granular Flow:

David Schaeffer predicts instability to oscillations



Experiments measure pressure fluctuations in a hopper flow



Broad band 'noise' points  
To new and unanticipated  
Dynamics in granular materials

Baxter and BB, 1990

Reynolds of fluid mechanics fame—discovers dilatancy

## Introduction

THE  
LONDON, EDINBURGH, AND DUBLIN  
PHILOSOPHICAL MAGAZINE  
AND  
JOURNAL OF SCIENCE.

[FIFTH SERIES.]

DECEMBER 1885.

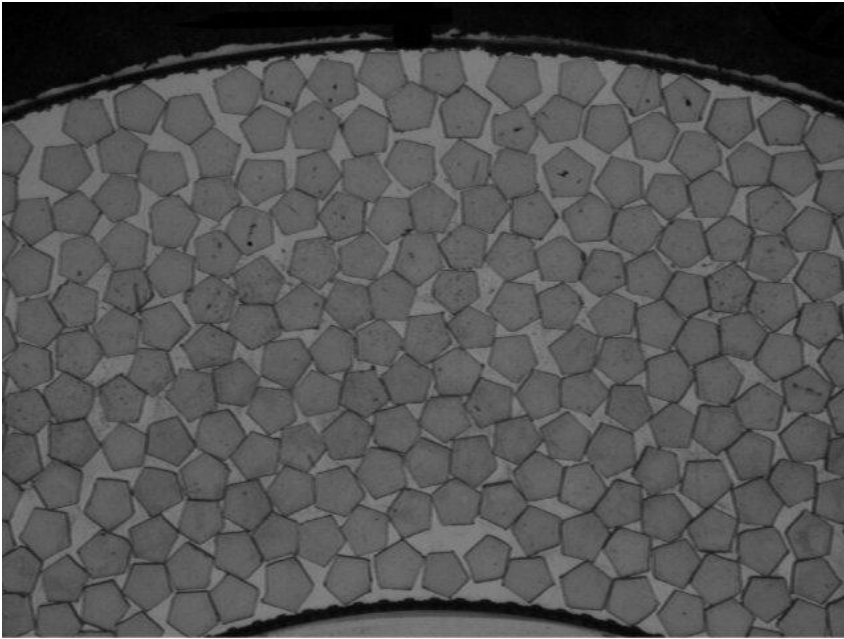
LVII. *On the Dilatancy of Media composed of Rigid Particles in Contact. With Experimental Illustrations.* By Professor OSBORNE REYNOLDS, LL.D., F.R.S.\*

[Plate X.]

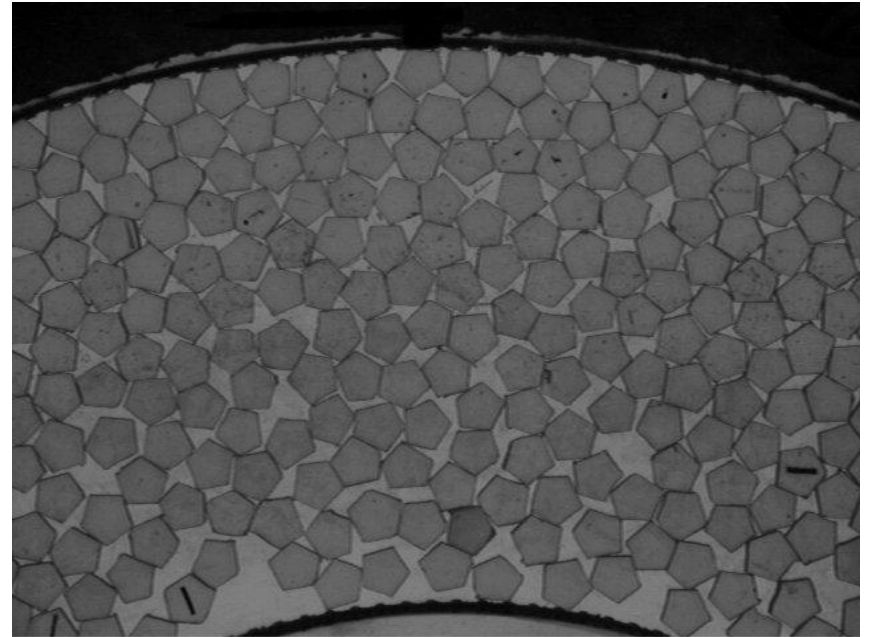
IDEAL rigid particles have been used in almost all attempts to build fundamental dynamical hypotheses of matter: these particles have generally been supposed smooth.



## Dilation under shear



*Before shearing*

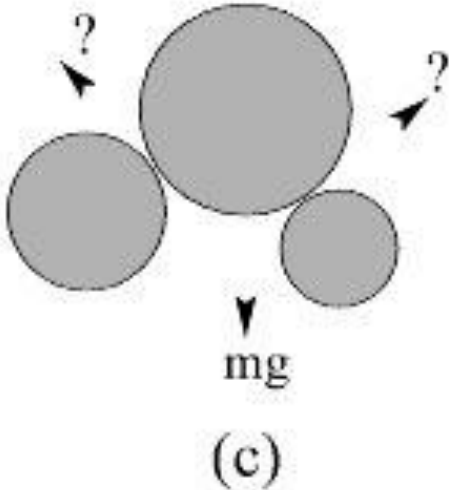
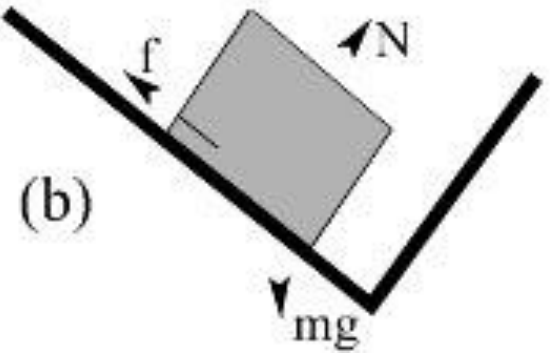
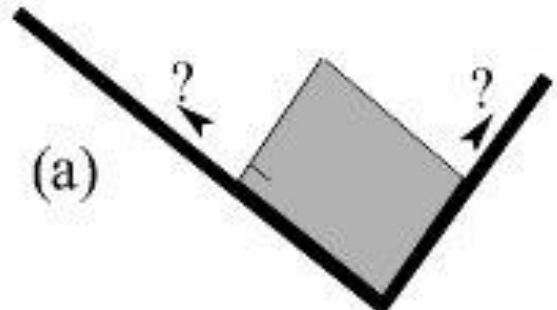


*After sustained shearing*

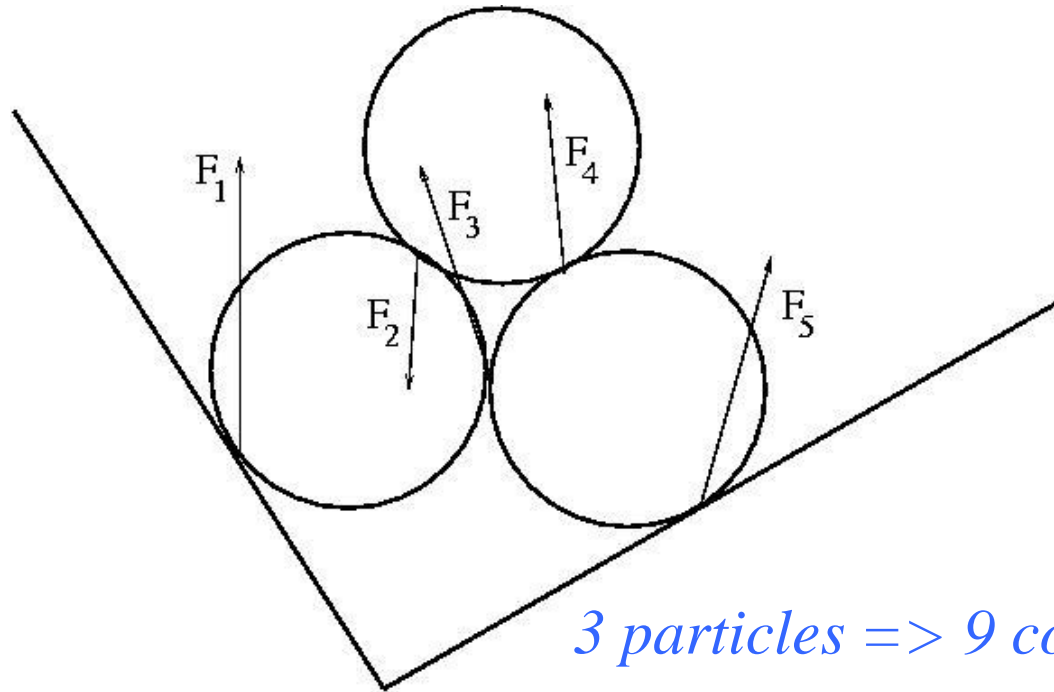
J-N Roux: no dilation for frictionless grains



Frictional indeterminacy => history dependence



## Multiple contacts => indeterminacy



*3 particles => 9 constraints*

*Note: 5 contacts => 10 unknown force components.*

*Special (isostatic) state:  
number of degrees of freedom = number of constraints*

## 4) Granular materials jam

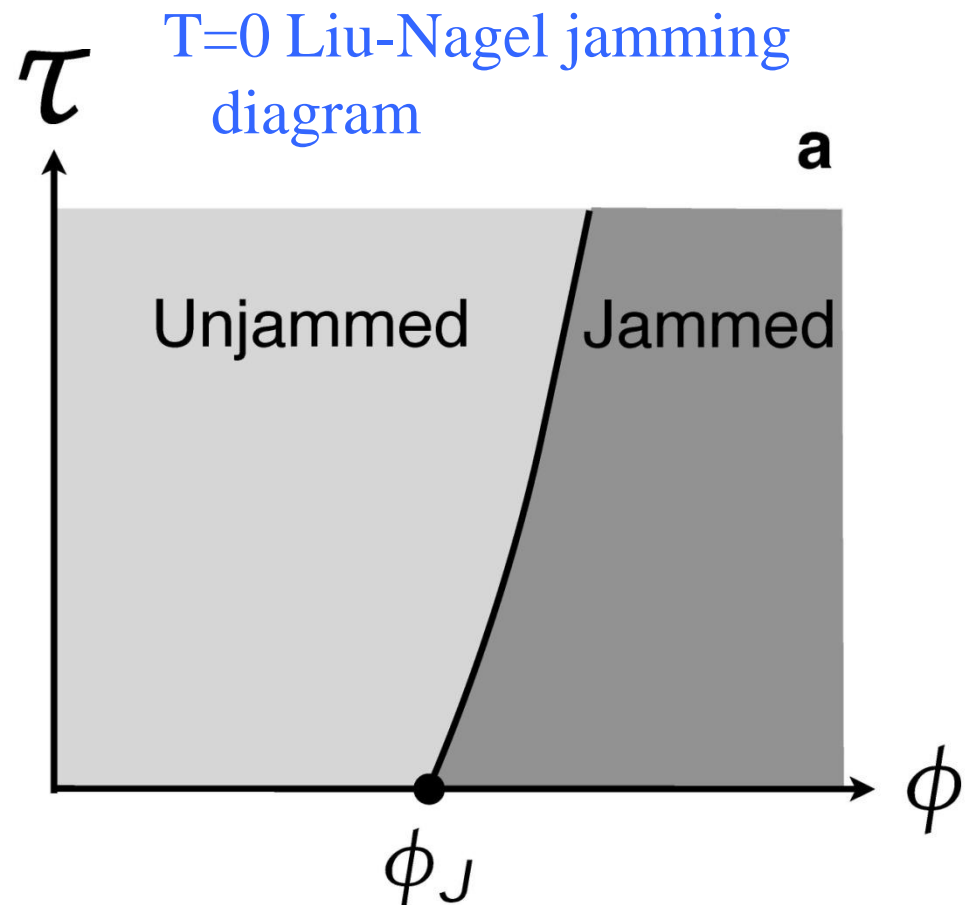
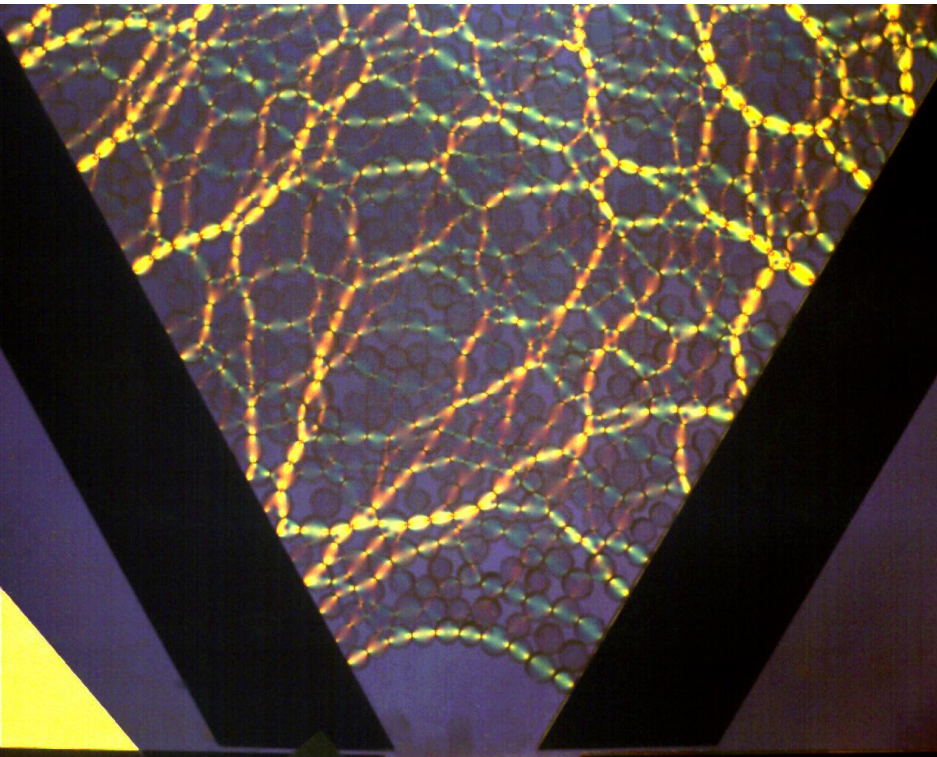
- **Jamming**—how disordered N-body systems becomes solid-like as particles are brought into contact, or fluid-like when grains are separated—thought to apply to many systems, including GM's foams, colloids, glasses...
- **Isotropic case: Density** is implicated as a key parameter, expressed as **packing (solid fraction)  $\phi$**
- **Marginal stability (isostaticity)** for spherical particles (disks in 2D) contact number,  $Z$ , attains a critical value,  $Z_{\text{iso}}$  at  $\phi_{\text{iso}}$
- $Z_{\text{iso}}$  depends on dimension, friction.



What do we mean by jamming (for granular materials)?  
Are these two pictures at all related?

Here,  $\phi$  is packing  
fraction

Jam in a hopper  
Experiment

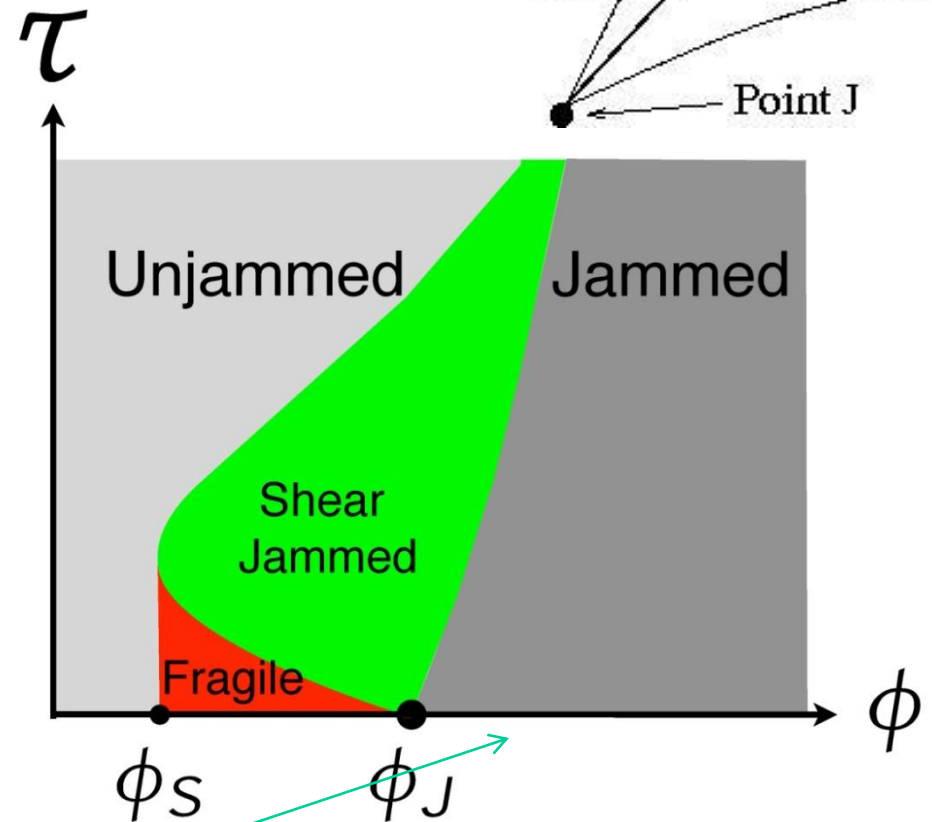
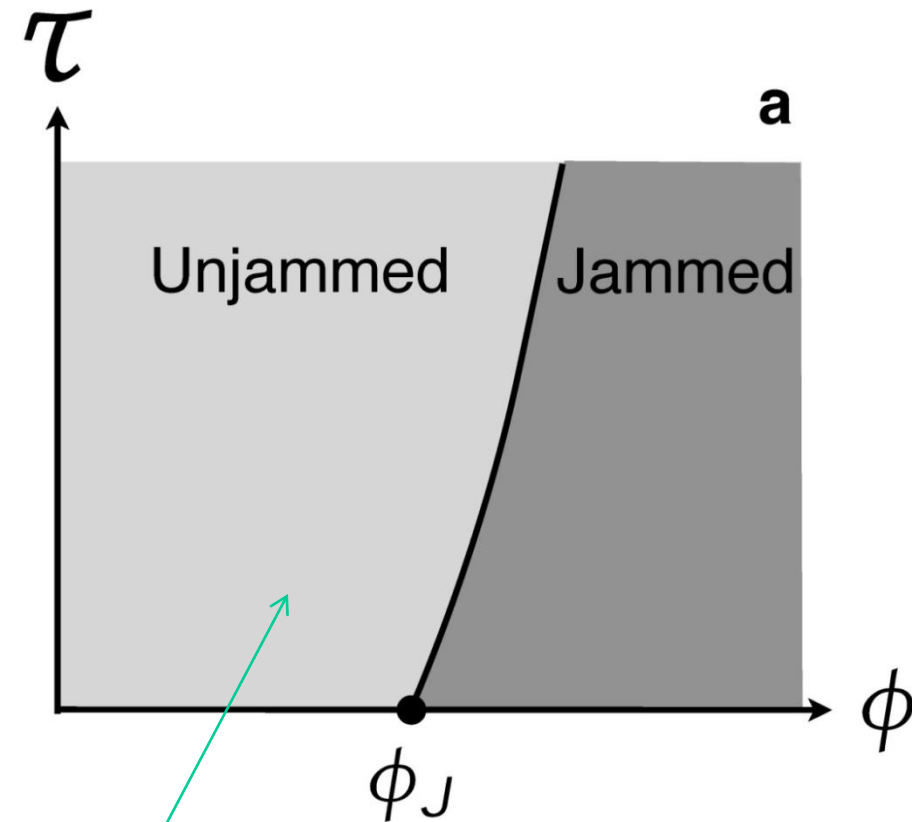
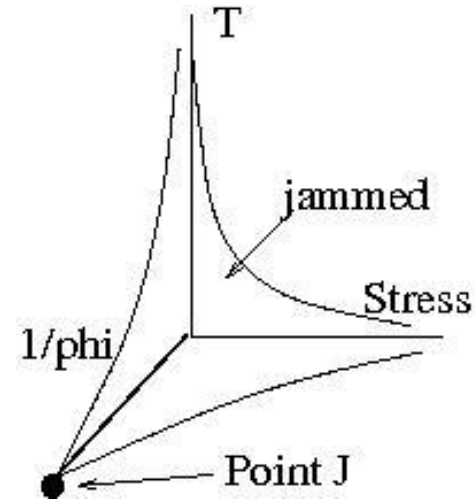


O'Hern et al. 2003

# But, experiments on frictional particles show other interesting behavior

Two kinds of state, depending on  $\phi$

- 1) ... $\phi_S < \phi < \phi_J$ —states arise under shear,  $|\tau| > 0$
- 2) ... $\phi > \phi_J$ —jammed states occur at  $\tau = 0$

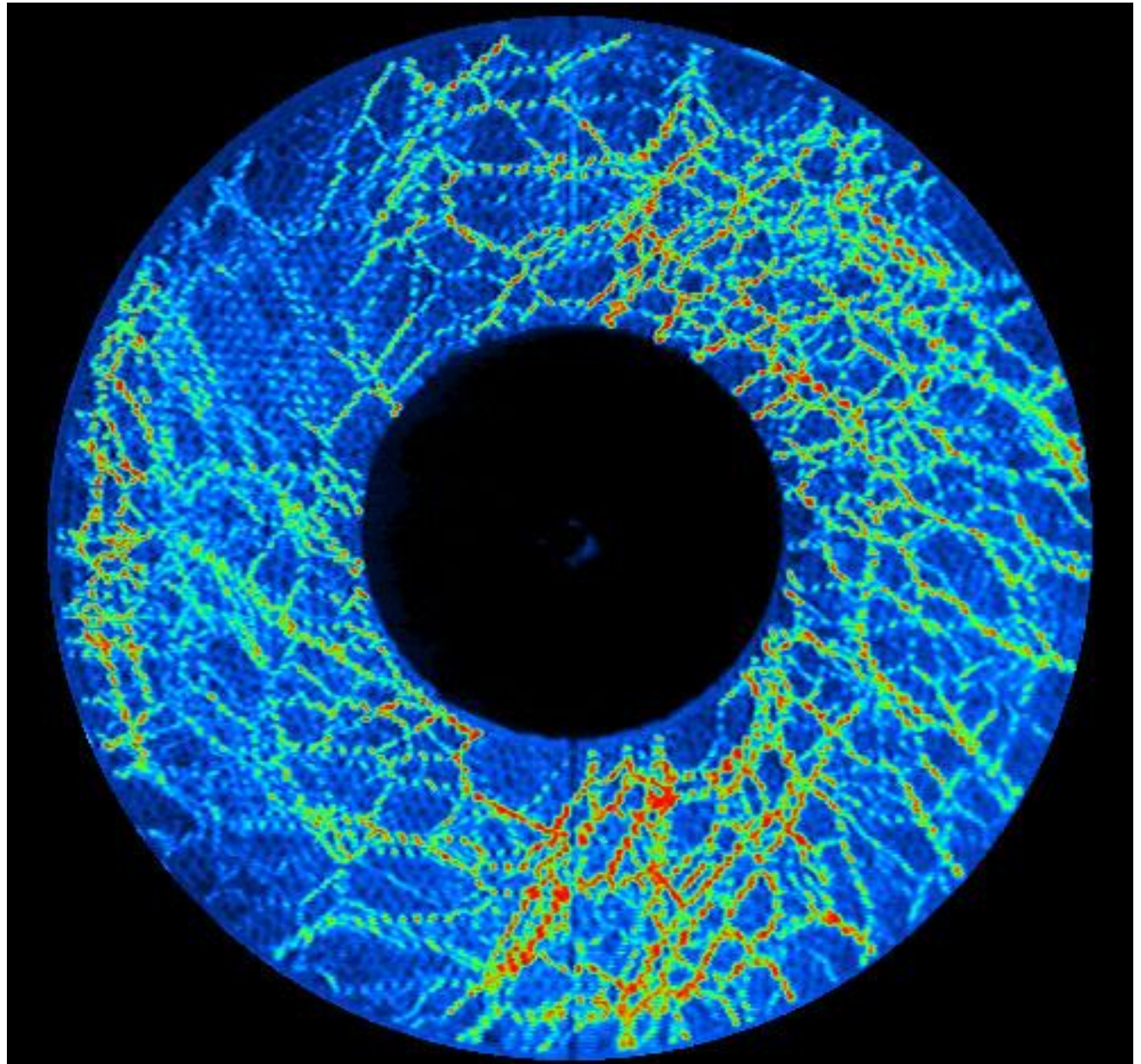


Original (Liu & Nagel, Nature 1998)

Bi et al. Nature, 480, 355 (2011)

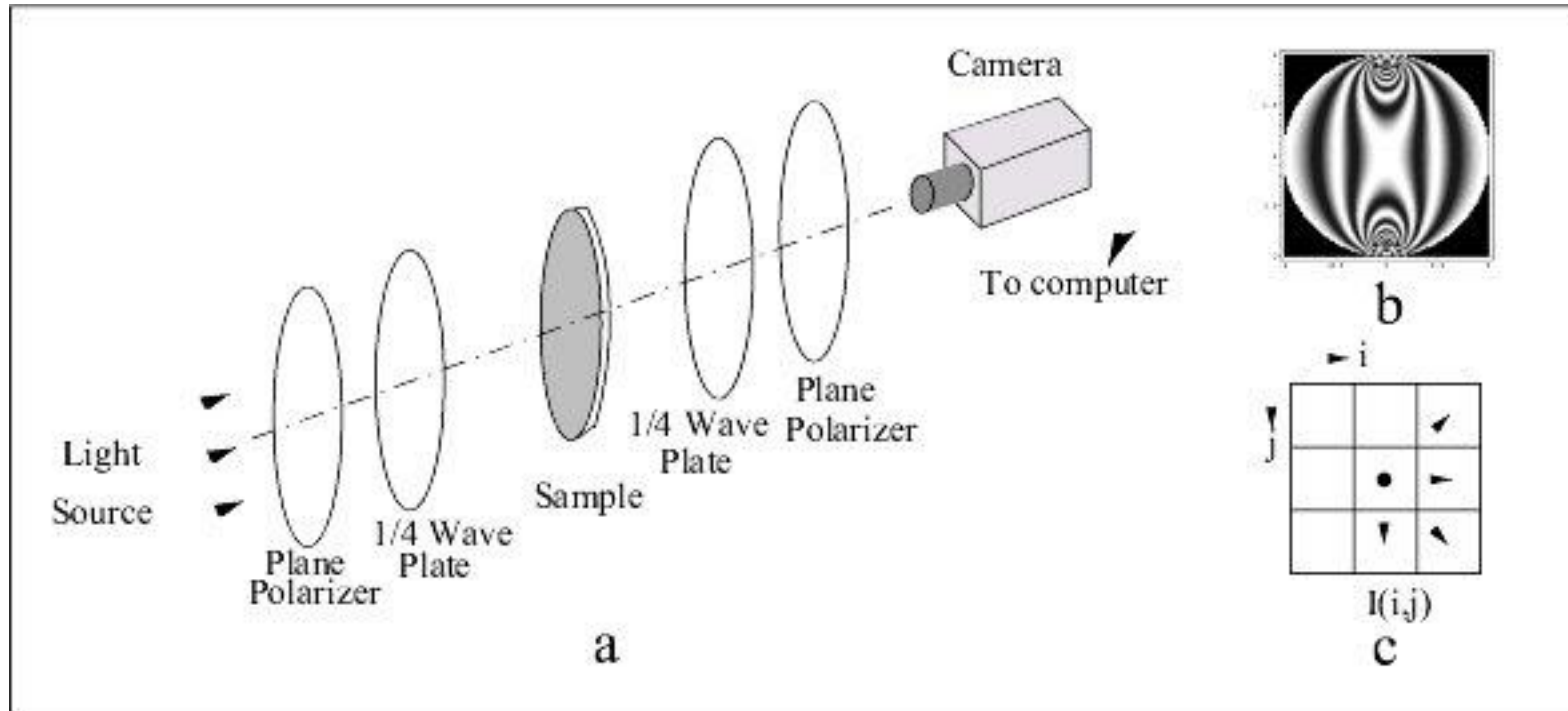
# How can photoelastic particles provide forces?

2d Shear →  
Experiment



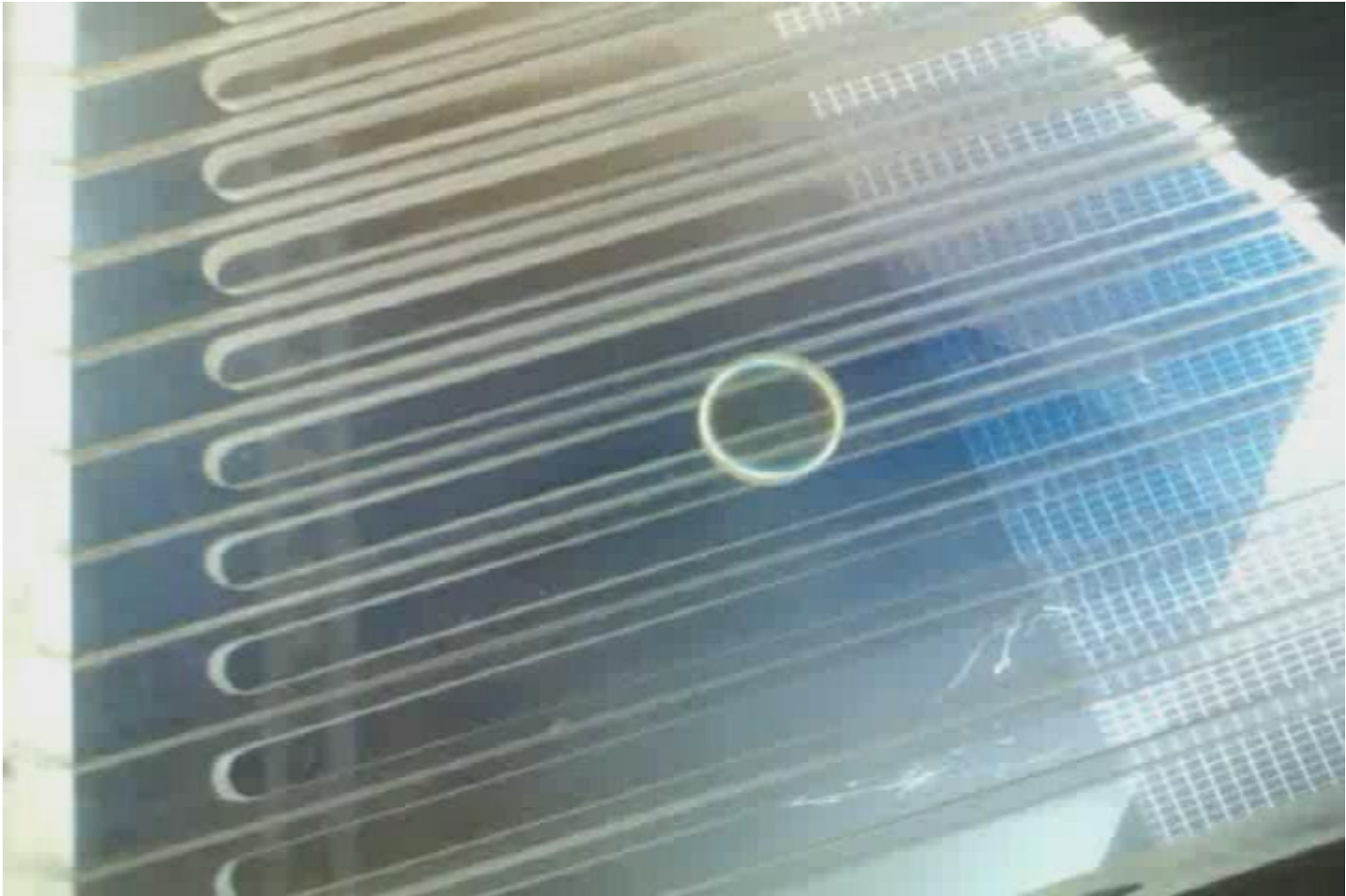
Howell et al.  
PRL 82, 5241 (1999)

# Measuring contact forces by photoelasticity





## Fun with photoelasticity\*



\*Hand, credit Joshua Dijksman



# Photoelasticity for granular materials

Some history:

Brewster discovers effect in 1800's

First used (qualitatively) by **T. Wakabayashi** 1936, 1950  
and **P. Dantu** 1957, 1968

Used by A. Drescher and J. de Jong 1972

T. Travers 1986

First used as a **quantitative local tool**: Howell et al. 1999

Used to **quantitatively measure contact forces**, then  
jamming properties etc. T. Majmudar and BB, 2005, TM, M. Sperl, S.  
Luding & BB, 2007, M. Bi, J. Zhang, B. Chakraborty & BB, 2011.

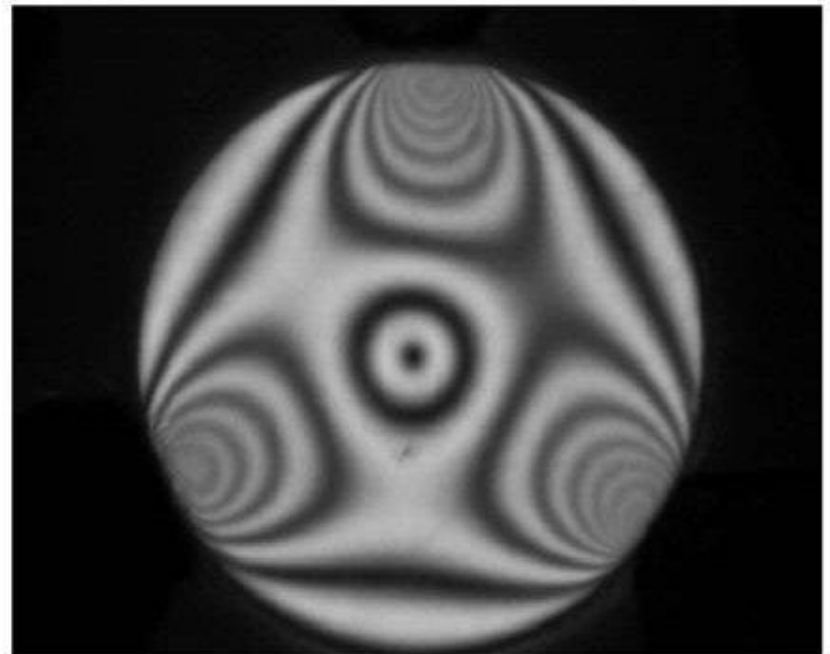
Multiple papers since then: Groups of BB , Daniels,  
Shattuck, J. Zhang

## Basic principles of technique

- $I = I_0 \sin^2[(\sigma_2 - \sigma_1)CT/\lambda]$
- Density of fringes grows with pressure on particle
- Gradient square of  $I$  is proportional to fringe density

- Details of pattern  
↔ with forces at  
contacts

**c**

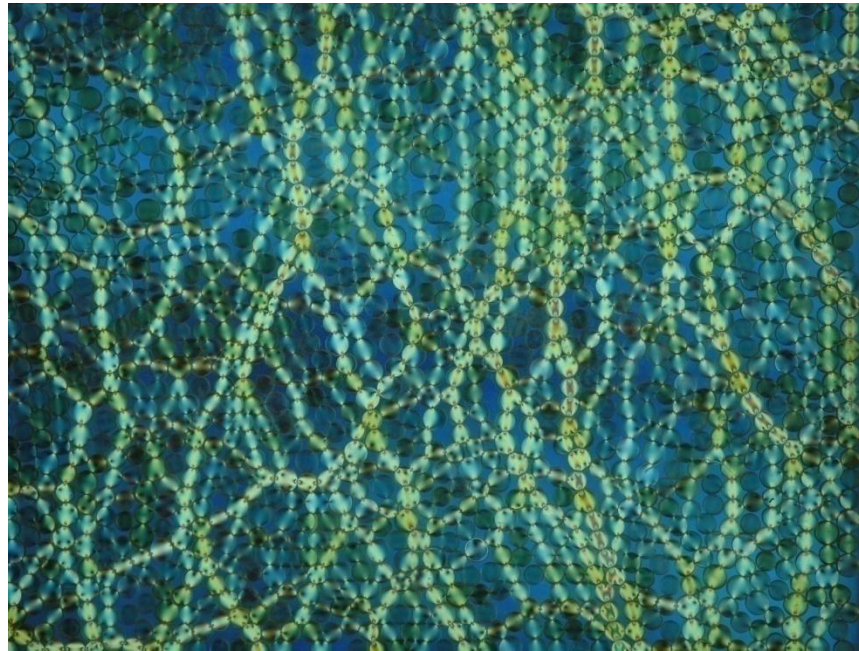


## Finding 2D contact forces

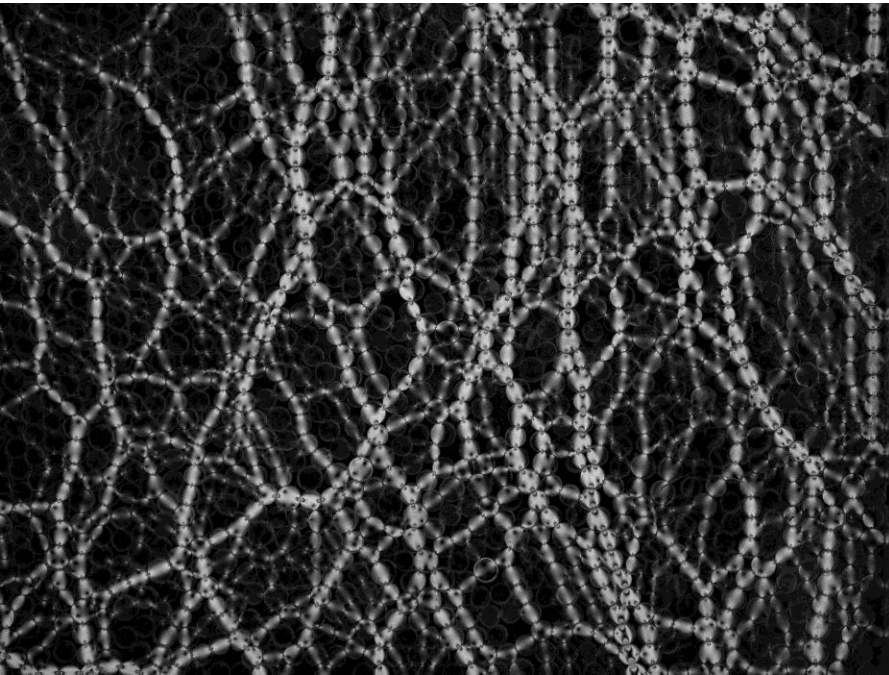
- Stresses inside particle determined by contact forces
- Transmitted intensity determined by stresses
$$I = I_0 \sin^2[(\sigma_2 - \sigma_1)CT/\lambda]$$
- Determines patterns in particles
- Nonlinear fit to photoelastic pattern: contact forces are fit parameters
- In the previous step, invoke force and torque balance

# Key new approach: obtain grain contact forces

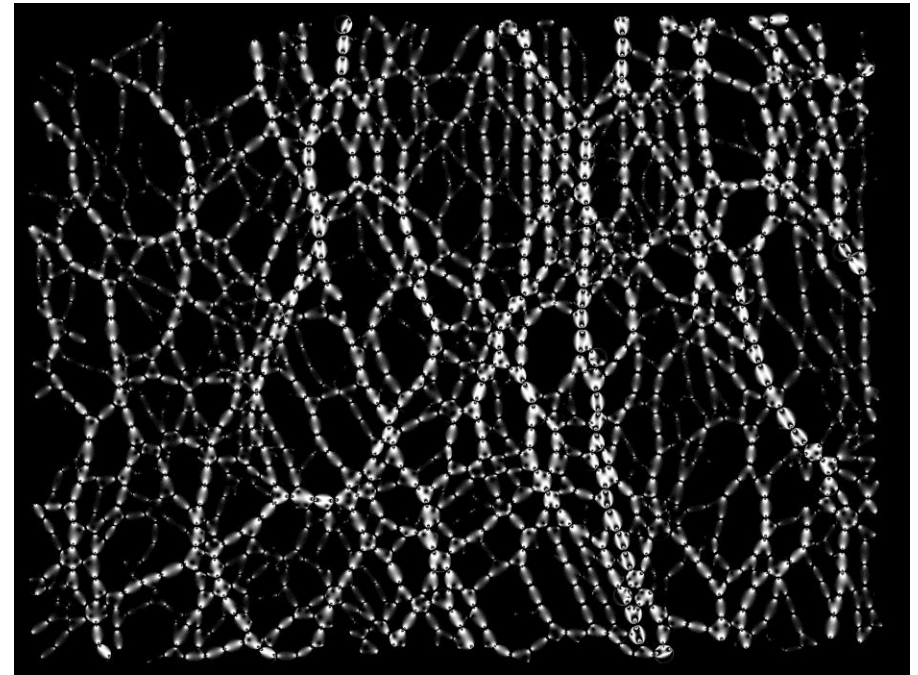
*Experiment--raw*

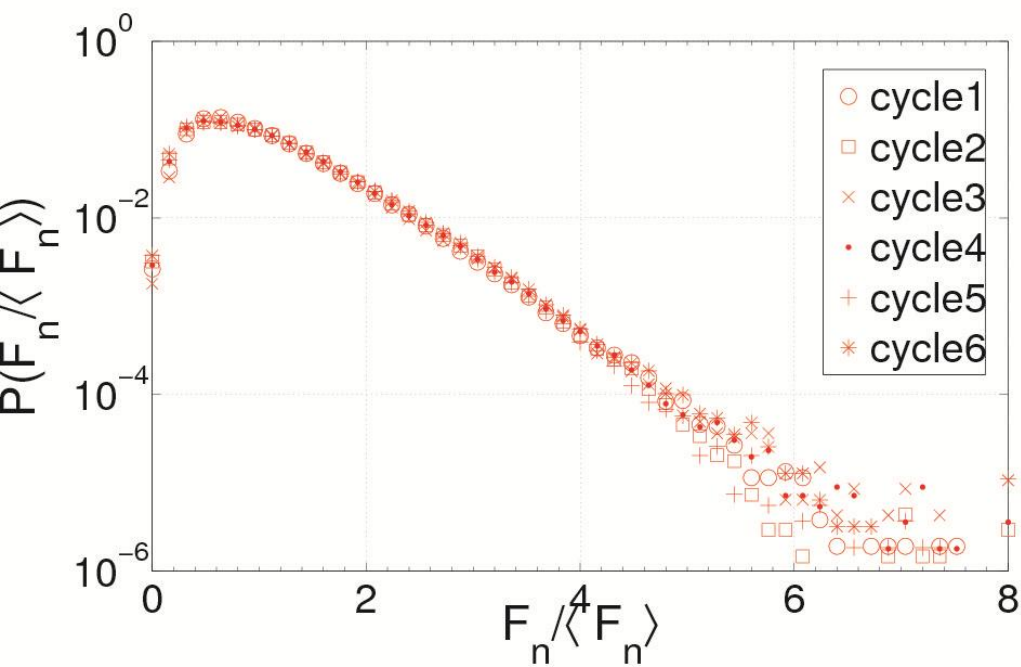


*Experiment  
Color filtered*

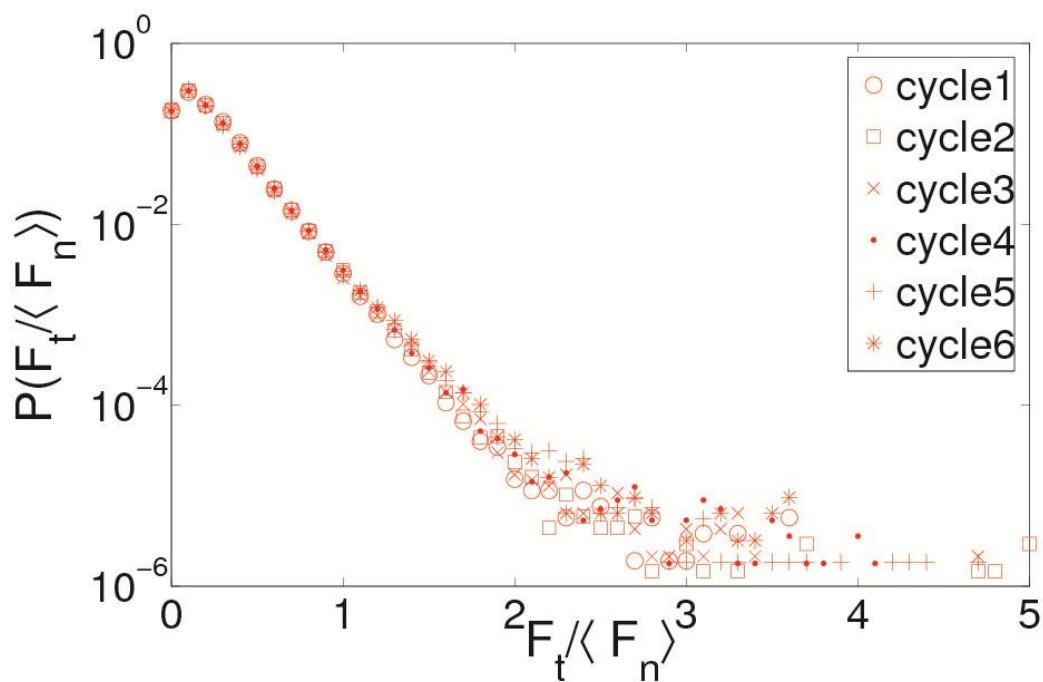


*Reconstruction  
From force  
inverse algorithm*



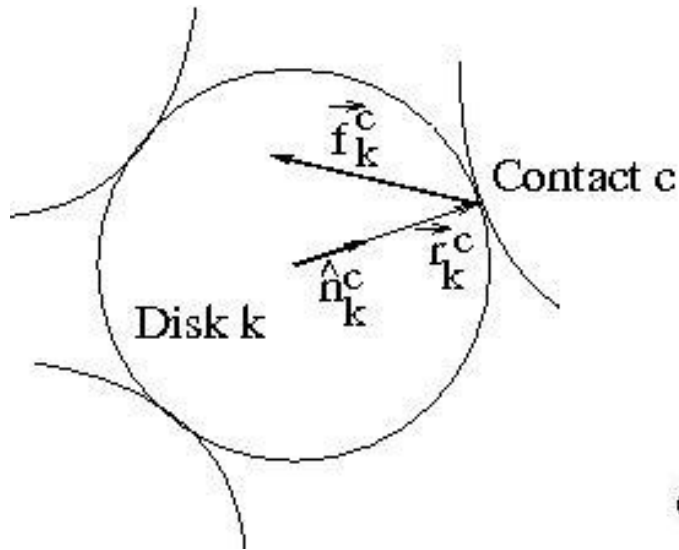


Good collapse of data for  $P(f)$  for normal and tangential contact forces





# Obtaining stresses and fabric from experimental data

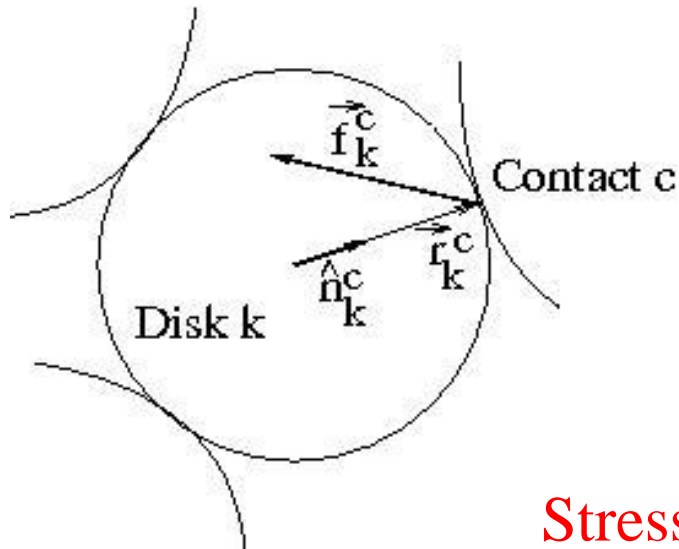


$$\hat{\sigma} = \frac{1}{V} \sum_{i \neq j} \vec{r}_{ij} \otimes \vec{f}_{ij}, \quad \text{Stress}$$

$$\hat{R} = \frac{1}{N} \sum_{i \neq j} \frac{\vec{r}_{ij}}{\|\vec{r}_{ij}\|} \otimes \frac{\vec{r}_{ij}}{\|\vec{r}_{ij}\|}, \quad \text{Fabric}$$

These quantities can be coarse-grained to produce continuum fields

# Stresses, fabric, force moment tensor—2D



Fabric tensor

$$R_{ij} = \sum_{k,c} n_{ik}^c n_{jk}^c$$

$$Z = \text{trace}[R]$$

Stress tensor, force moment tensor

$$\text{stress: } \sigma_{ij} = (1/A) \sum_{k,c} r_{ik}^c f_{jk}^c$$

Pressure, P and shear stress

$$P = \text{Tr}(\sigma)/2 = (\sigma_2 + \sigma_1)/2$$

$$\tau = (\sigma_2 - \sigma_1)/2$$

$$\text{Force moment } \Sigma_{ij} = \sum_{k,c} r_{ik}^c f_{jk}^c = A \sigma_{ij}$$

A is particle/system area

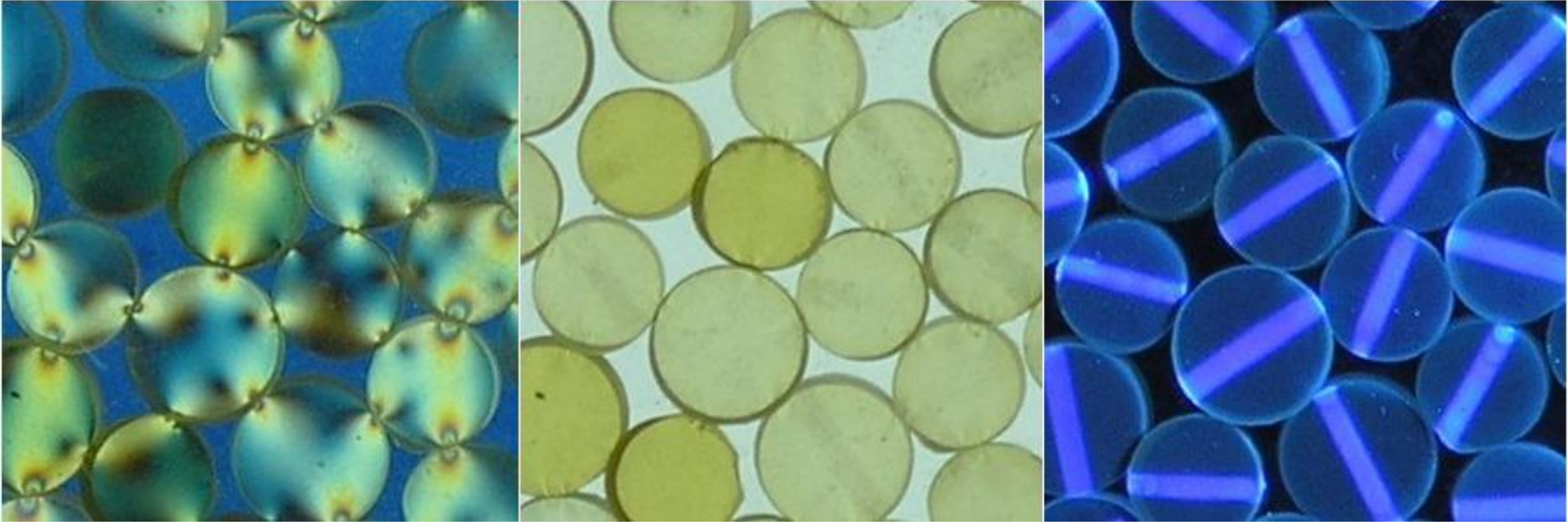
# Displacements and rotations of grains

What about rotation?



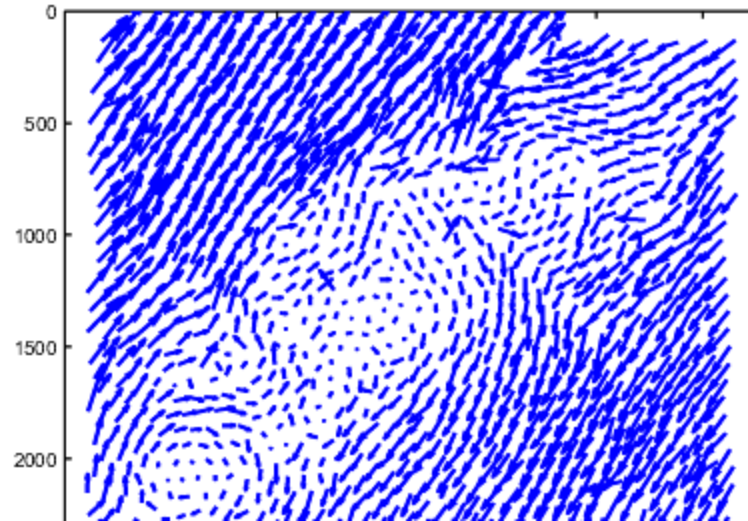
# Track Particle: Forces/Displacements/Rotations

Zhang et al. 2010, Bi et al. 2011—complete system description



Following a small strain step we track particle displacements

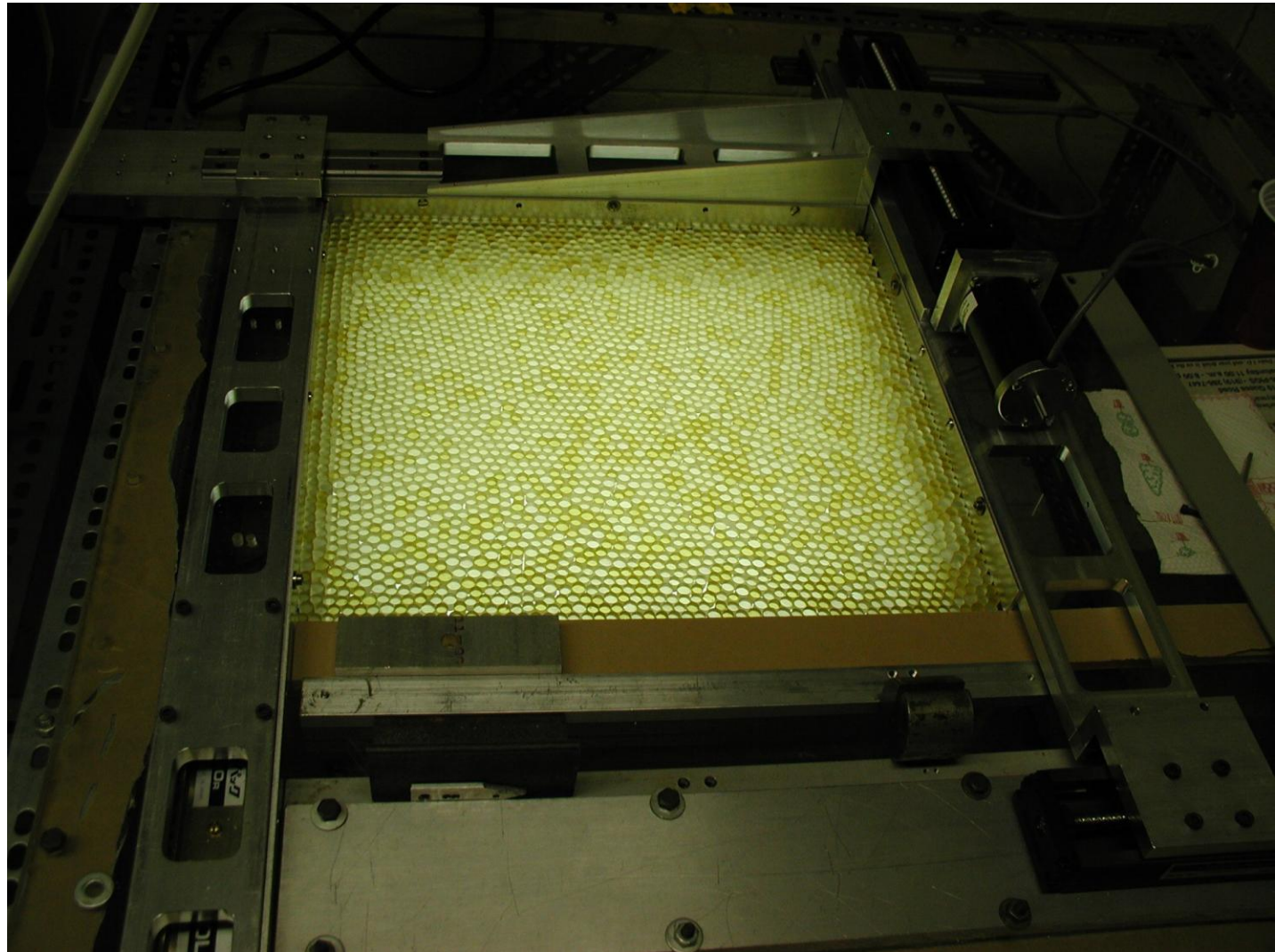
Zhang et al. 2010  
Bi et al. Nature 2011



Under UV light—  
bars allow us to  
track particle  
rotations



**Biaxial Tester—use force-inverse approach**  
Control spacing between opposing pairs of walls



*Experiments use  
biaxial tester →  
and photoelastic  
particles*

Majmudar, Sperl, Luding and BB, PRL 2007

(Trush Majmudar and RPB, Nature, June 23, 2005)

## Standard picture of jamming

- **Jamming**—how disordered N-body systems becomes solid-like as particles are brought into contact, or fluid-like when grains are separated—thought to apply to many systems, including GM's foams, colloids, glasses...
- **Density** is implicated as a key parameter, expressed as **packing (solid fraction)  $\phi$**
- **Marginal stability (isostaticity)** for spherical particles (disks in 2D) contact number,  $Z$ , attains a critical value,  $Z_{\text{iso}}$  at  $\phi_{\text{iso}}$

# The Jamming Transition

- Simple question:

What happens to key properties such as pressure, contact number as a sample is isotropically compressed/dilated through the point of mechanical stability?

$Z = \text{contacts/particle}; \Phi = \text{packing fraction}$

*Predictions (e.g. O'Hern et al. PRE 2003*

*Torquato et al., Schwarz et al.*

$$Z \sim Z_I + (\varphi - \varphi_c)^{\alpha}$$

*(discontinuity)*

*Exponent  $\alpha \approx 1/2$*

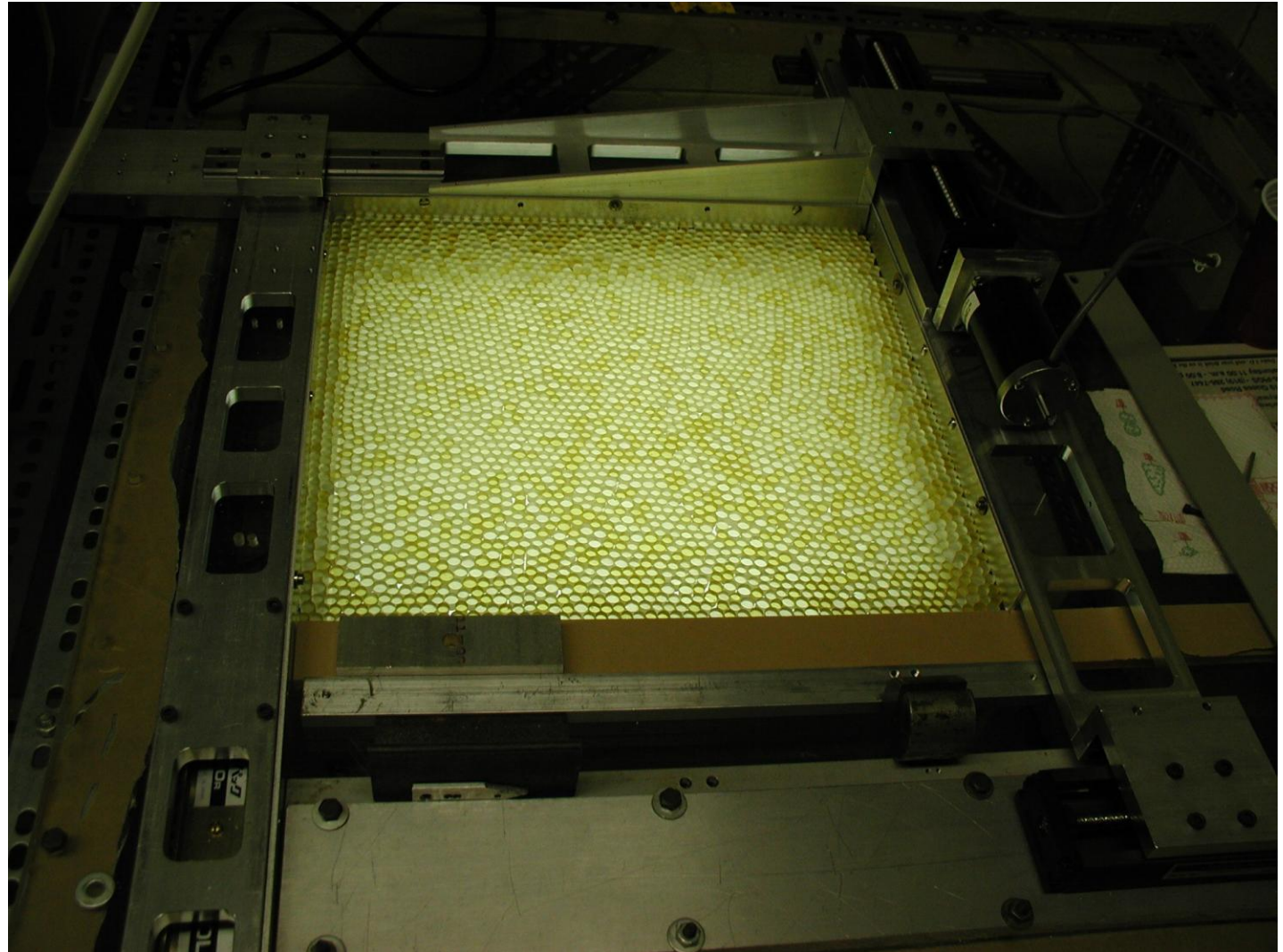
$$P \sim (\varphi - \varphi_c)^{\beta}$$

*$\beta$  depends on force law  
(= 1 for ideal disks)*

Henkes and Chakraborty: entropy-based model gives P and Z in terms of a field conjugate to entropy. Can eliminate to get P(z)

Experiments to determine vector contact forces  
 $P_1(F)$  is example of particle-scale statistical measure

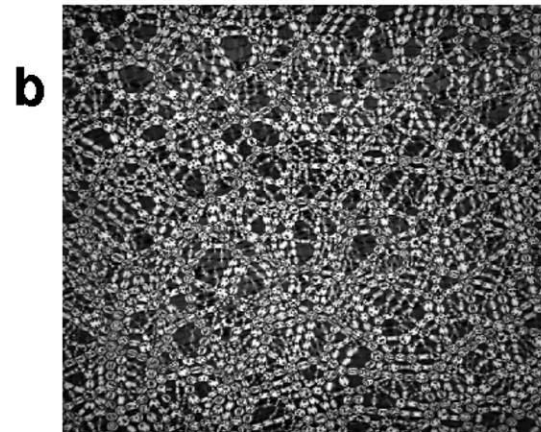
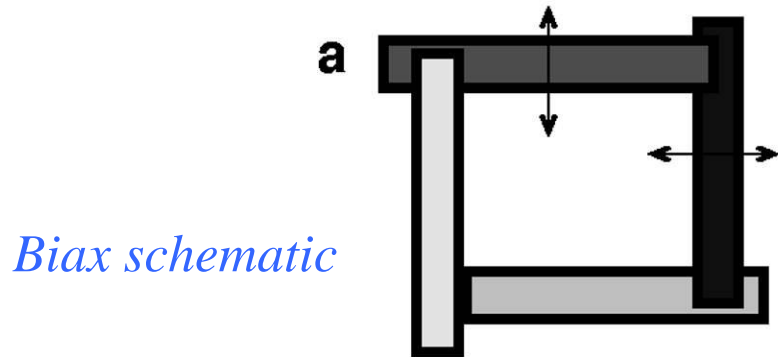
*Experiments use  
biaxial tester →  
and photoelastic  
particles*



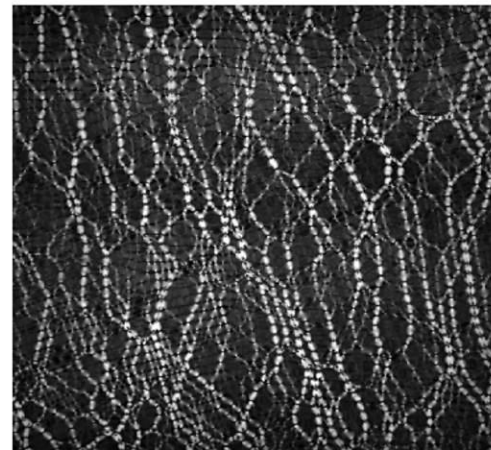
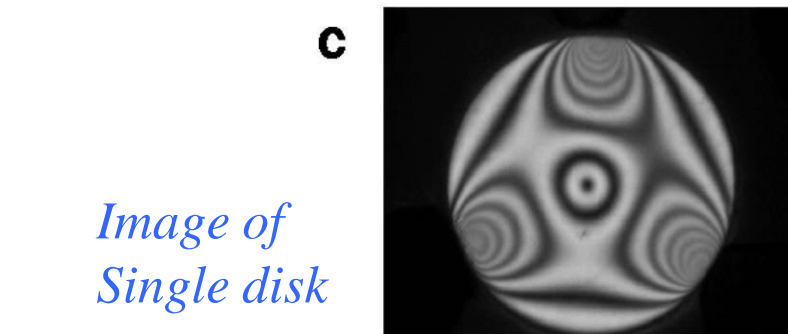
(Trush Majmudar and RPB, Nature, June 23, 2005)



# Experiment: Characterizing the Jamming Transition—Isotropic compression



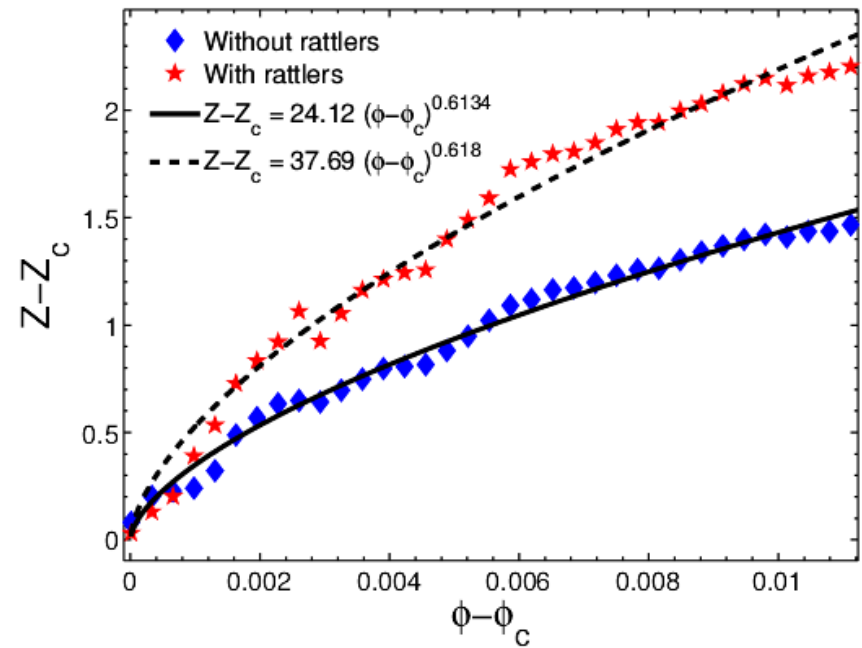
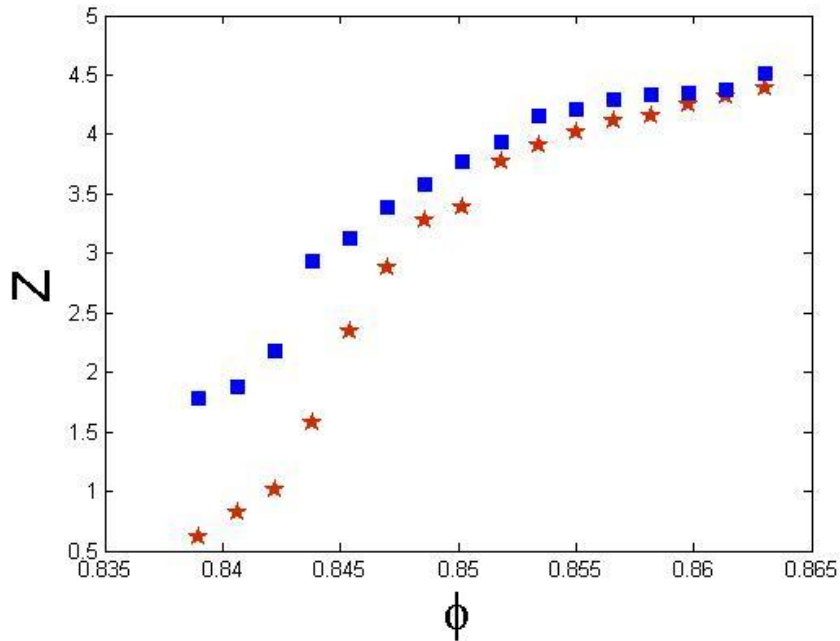
*Compression*



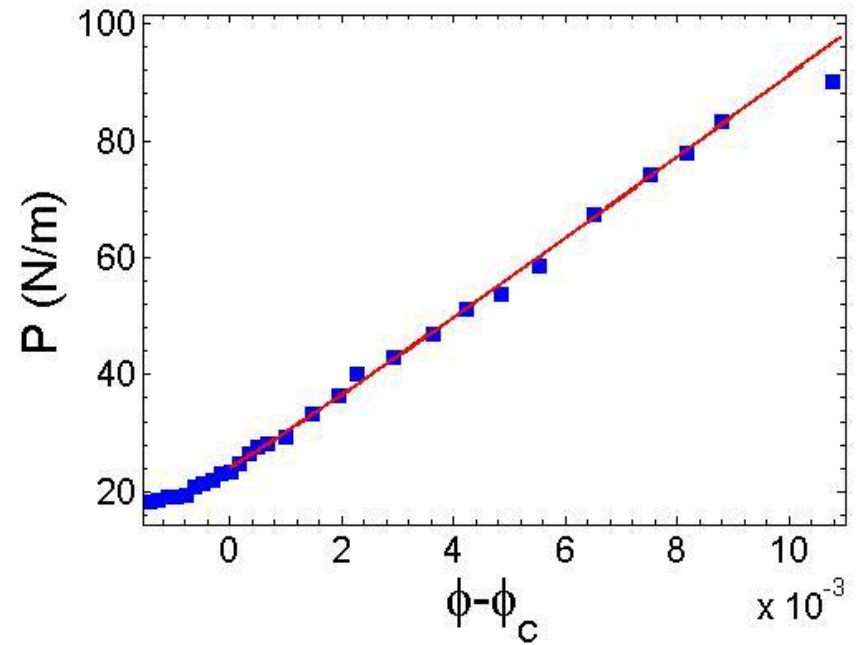
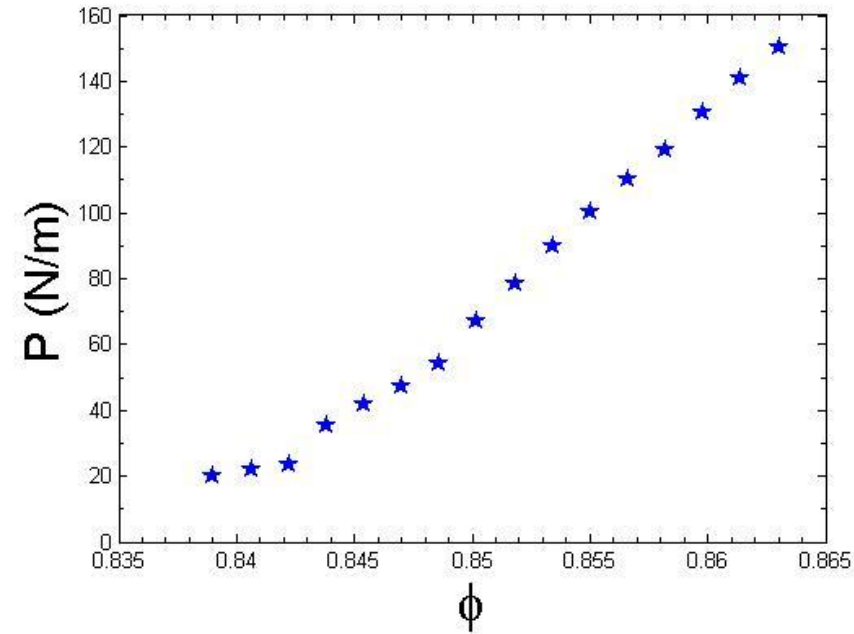
*Shear*

*~2500 particles, bi-disperse,  $d_L=0.9\text{cm}$ ,  $d_S=0.8\text{cm}$ ,  $N_S/N_L=4$*

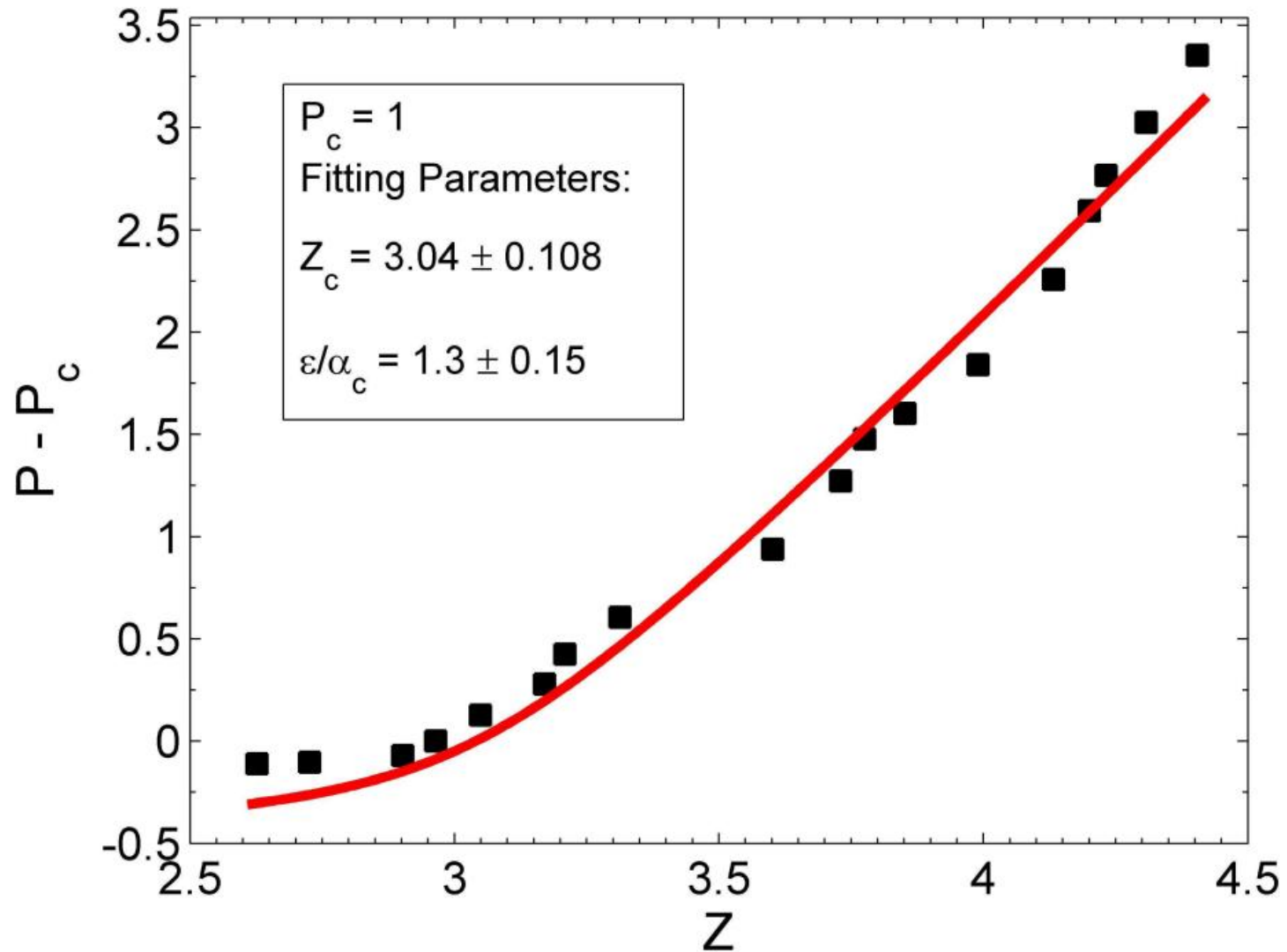
# LSQ Fits for $Z$ give an exponent of 0.5 to 0.6



# LSQ Fits for P give $\beta \approx 1.0$ to 1.1



# Comparison to Henkes and Chakraborty prediction





# Fragility

Fragile states: ability to resist strain:  
Strong in one direction but 0 in another

Chaos, Vol. 9, No. 3, 1999

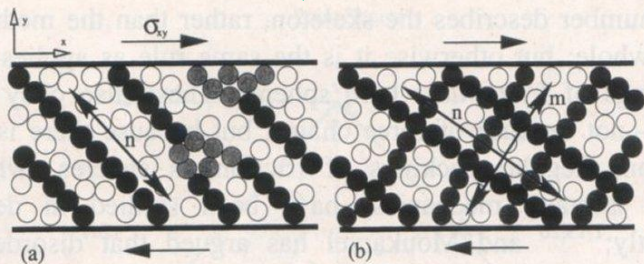
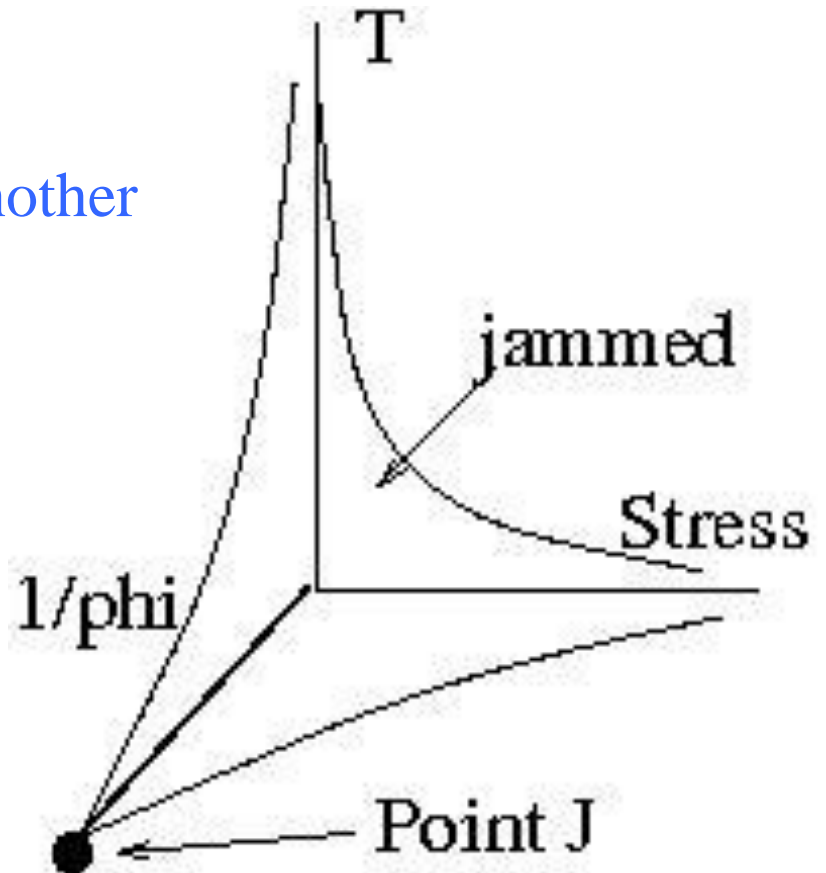


FIG. 2. (a) A jammed colloid (schematic). Black: force chains; gray: Other force-bearing particles; white: Spectators. (b) Idealized rectangular network of force chains.

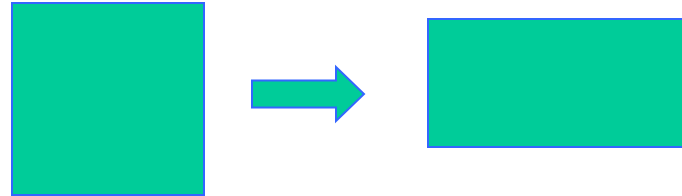
*Cates et al. PRL 1998*



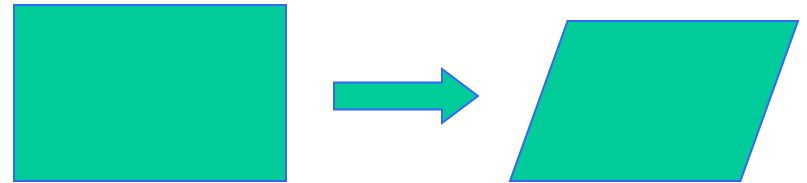
*Liu and Nagel*

## Different types methods of applying shear

- Example 1: pure shear

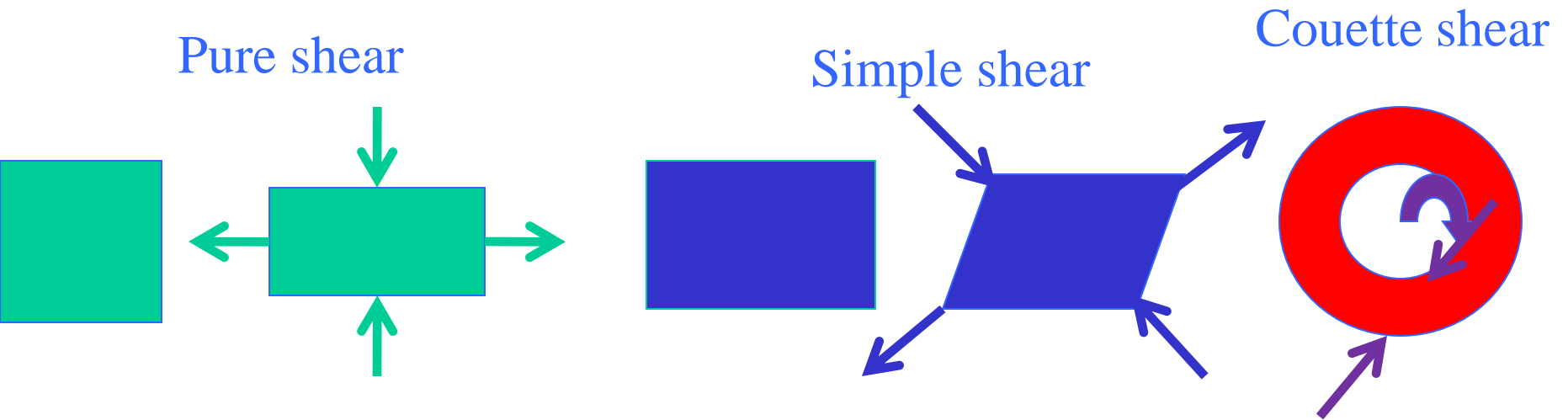


- Example 2: simple shear



- Example 3: steady shear



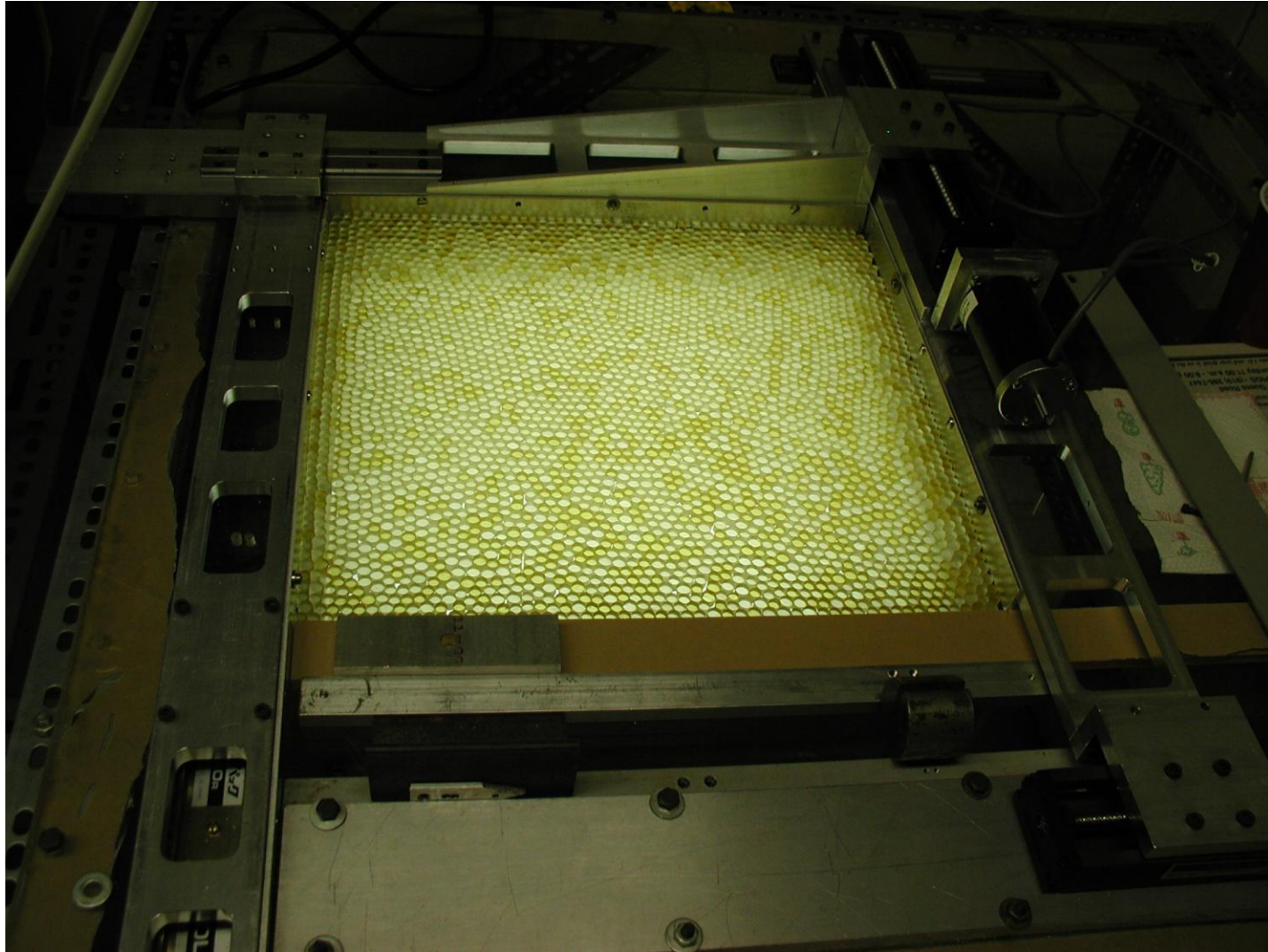


Different ways to apply shear:

Common feature of different protocols for shear

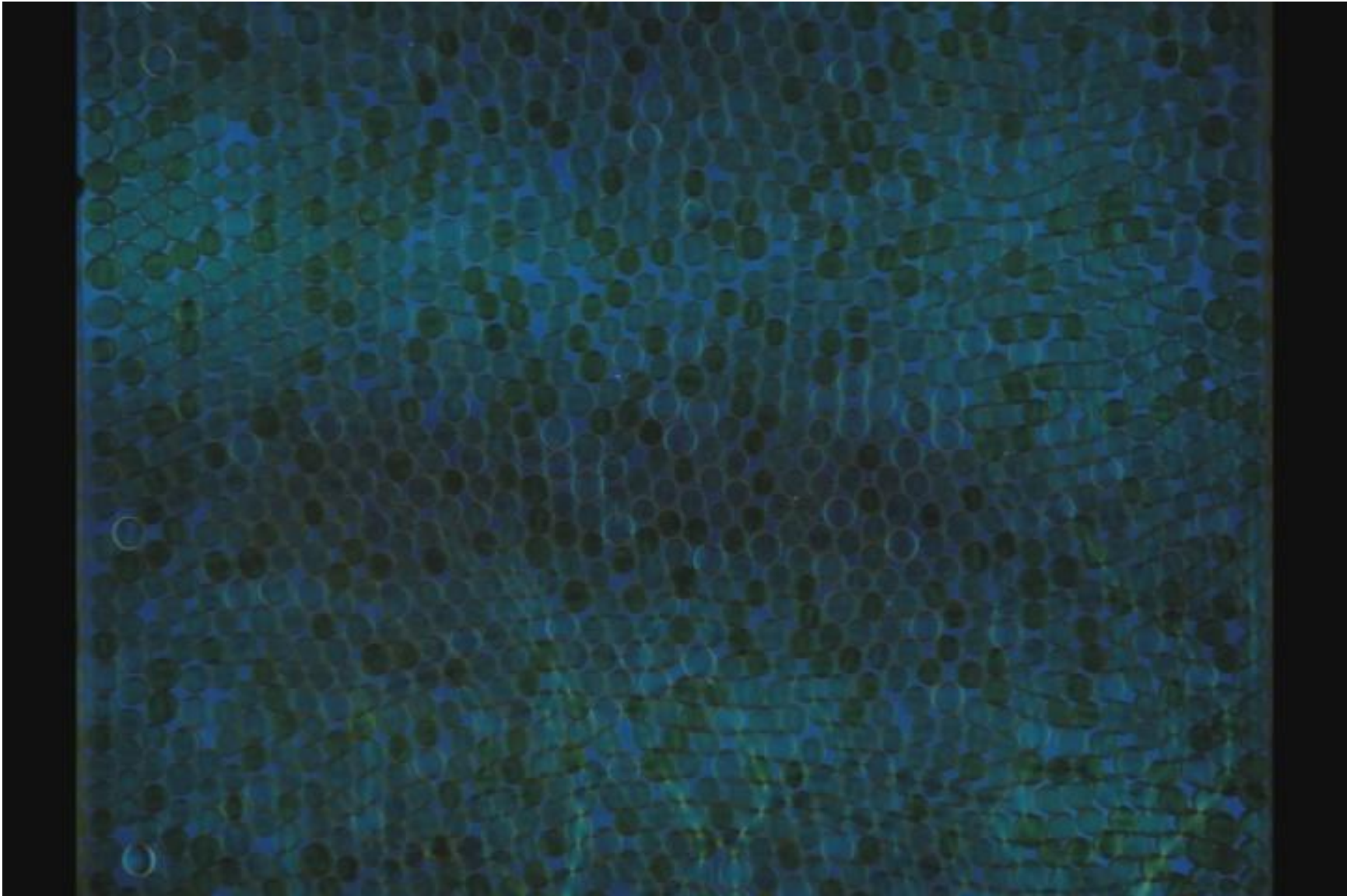
One **compressive** and one **dilational** direction  
(no change of area)

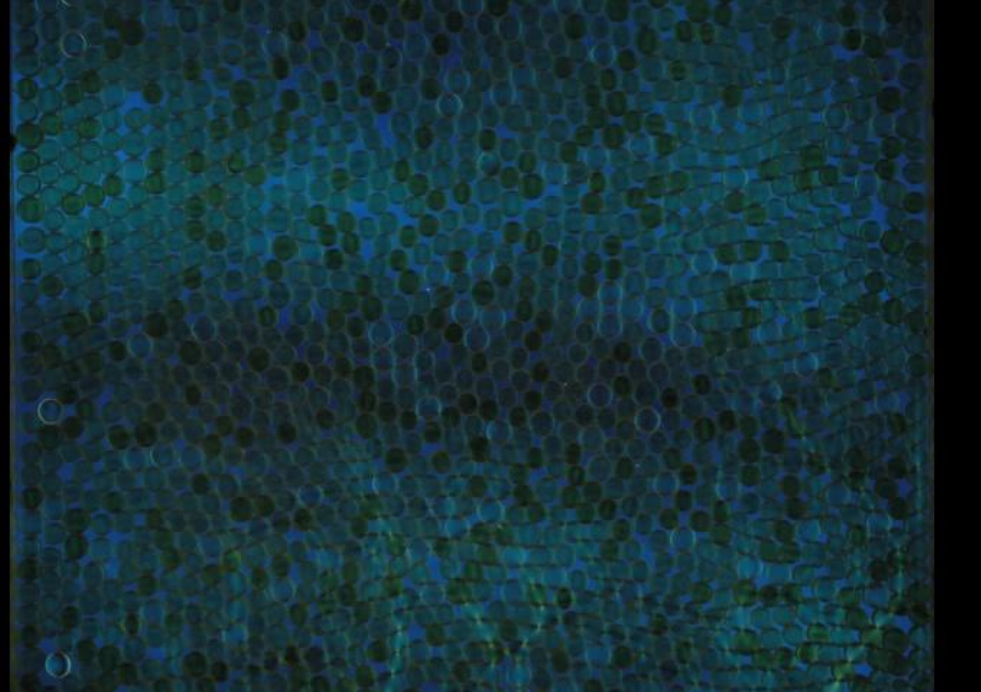
# First: Pure Shear Experiment (Bi-ax) Start from zero stress





Time-lapse video (one shear cycle) shows force network evolution—**Pure Shear**



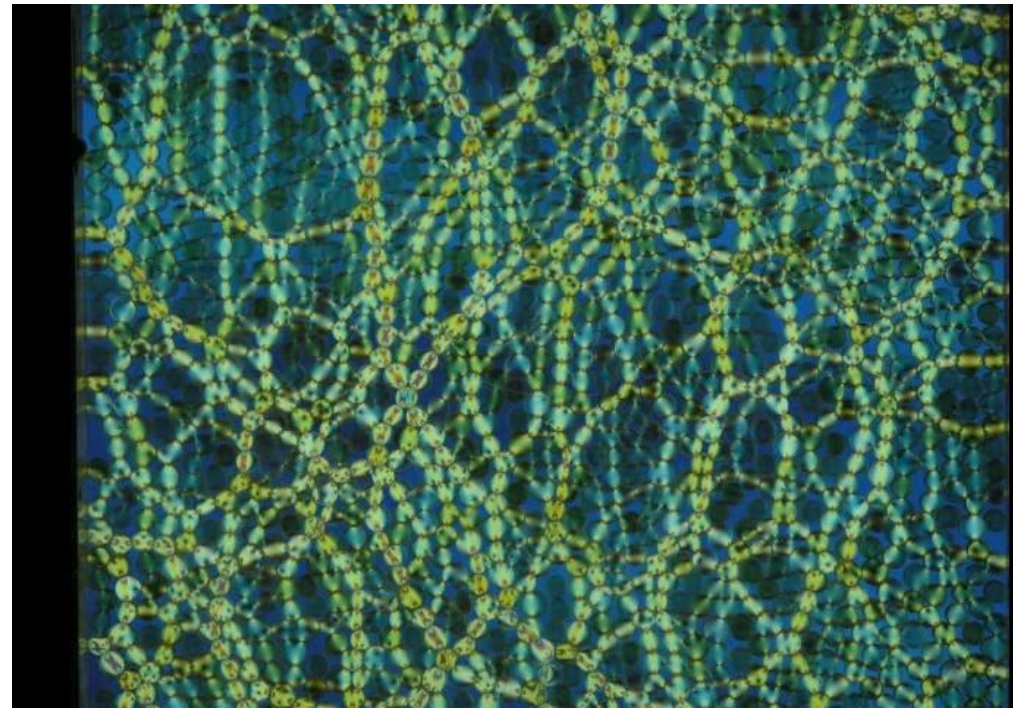


Initial and final states  
following a shear cycle—  
no change in area

← Initial state, isotropic,  
no stress

Works between  $\varphi_S < \varphi < \varphi_J$

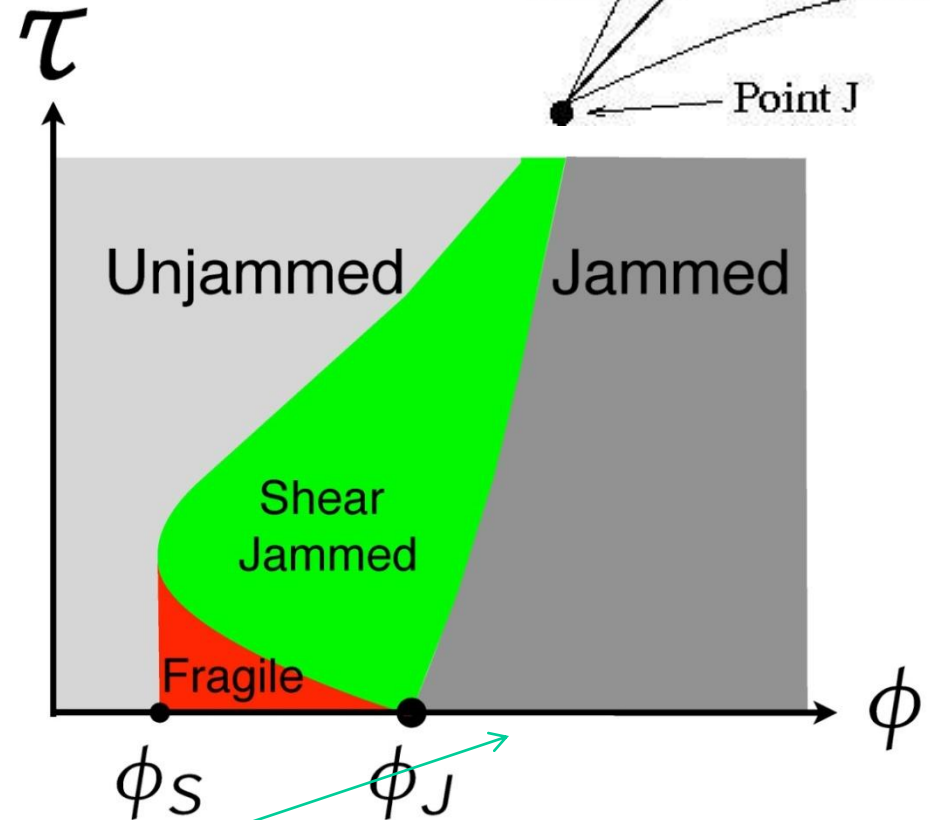
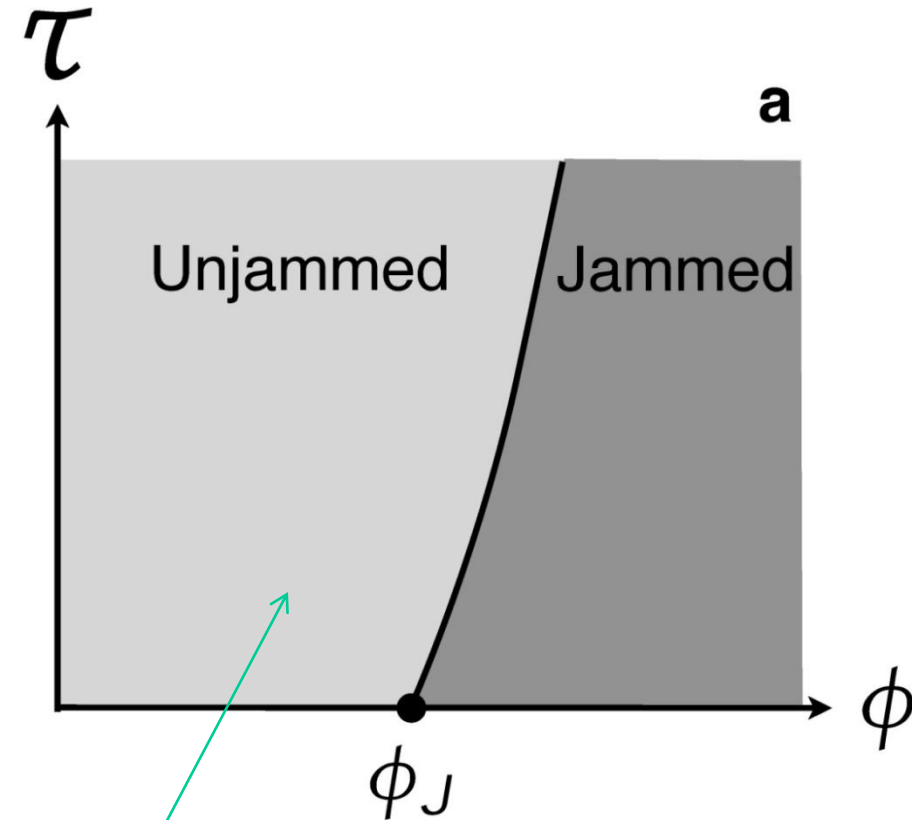
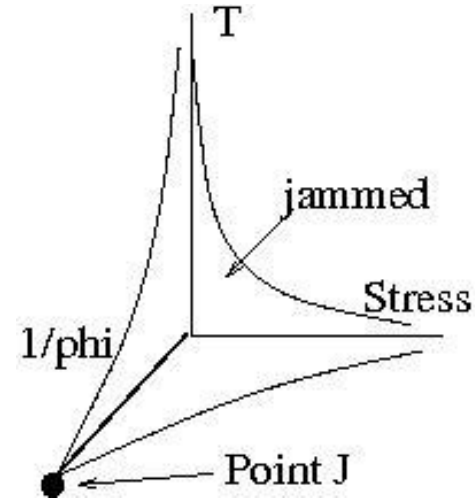
Final state →  
large stresses  
jammed



# But, experiments on frictional particles show other interesting behavior

Two kinds of state, depending on  $\phi$

- 1) ... $\phi_S < \phi < \phi_J$ —states arise under shear,  $|\tau| > 0$
- 2) ... $\phi > \phi_J$ —jammed states occur at  $\tau = 0$



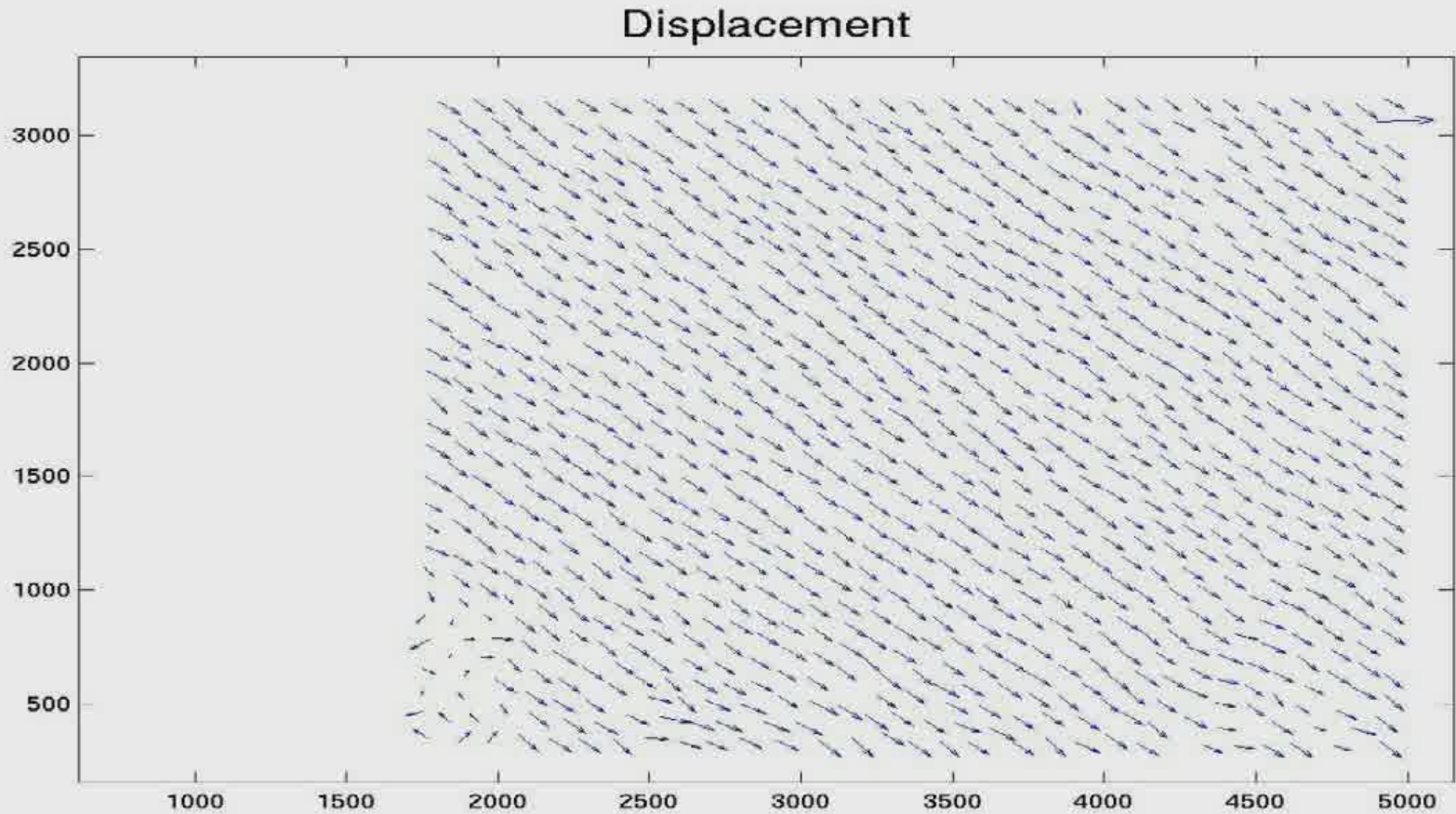
Original (Liu & Nagel, Nature 1998)

Bi et al. Nature, 480, 355 (2011)



# Particle displacements following strain steps

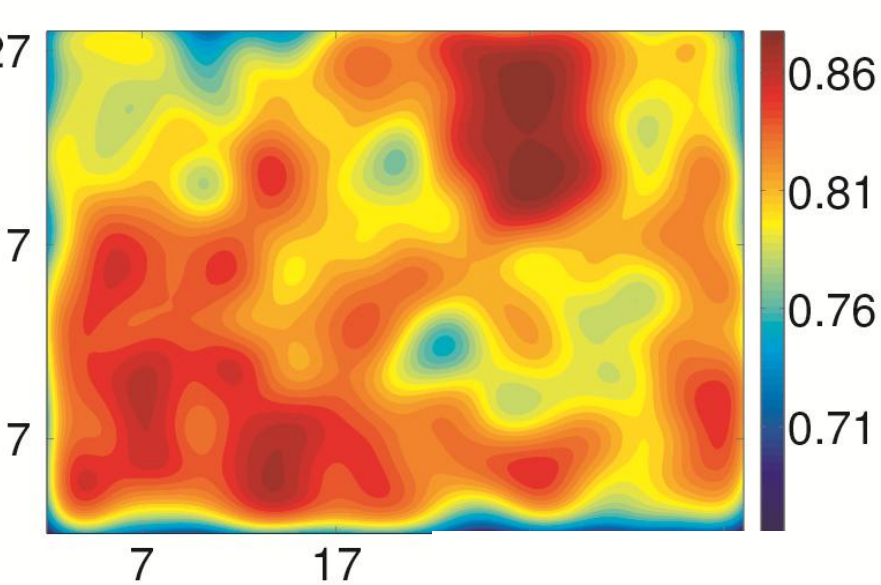
Note: shear band





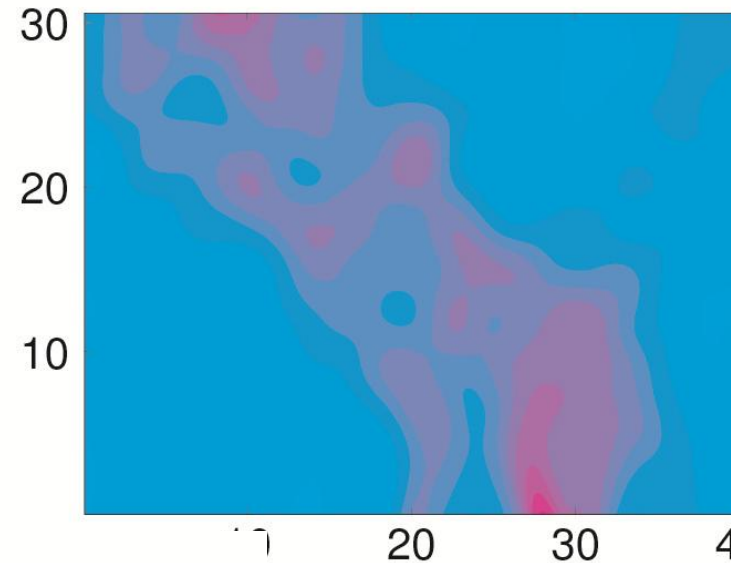
# CG measures of density and strain reflect shear band

Contour plots of coarse-grained local density and strain components,  
at a strain of  $\epsilon = 9.3\%$  }

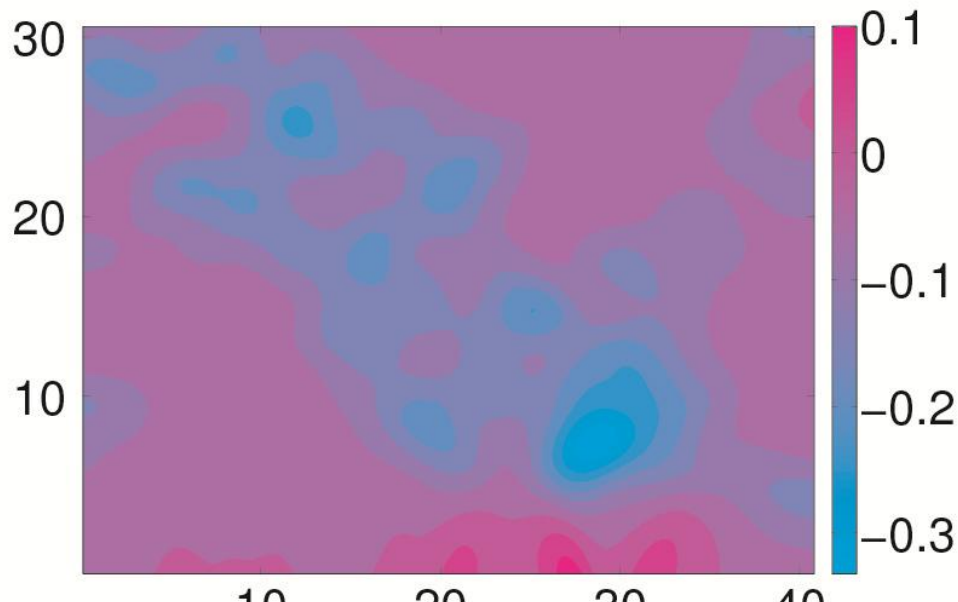


density

$\epsilon_{xx}$

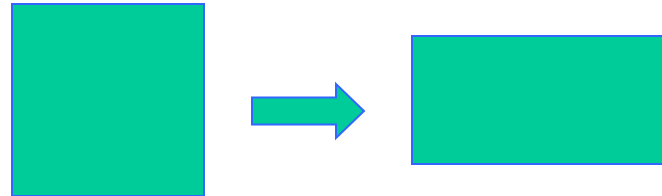


$\epsilon_{yy}$

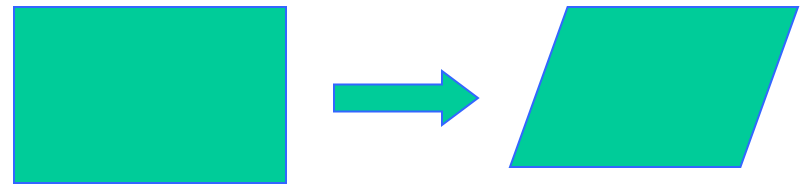


## Generation 2—an apparatus that maintains affine strain

- Example 1: pure shear



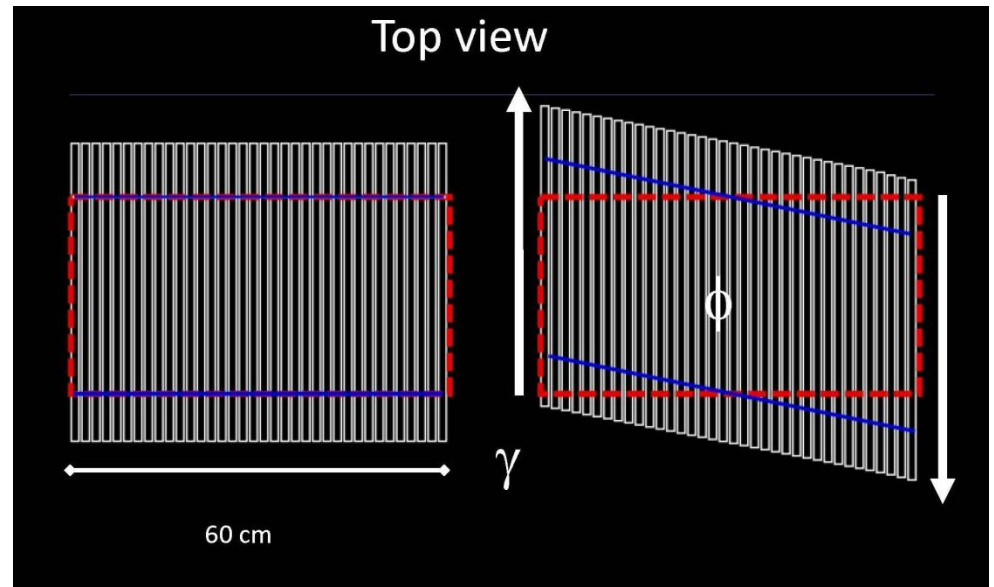
- Example 2: simple shear



- Example 3: steady shear



## 2<sup>nd</sup> apparatus: quasi-uniform simple shear

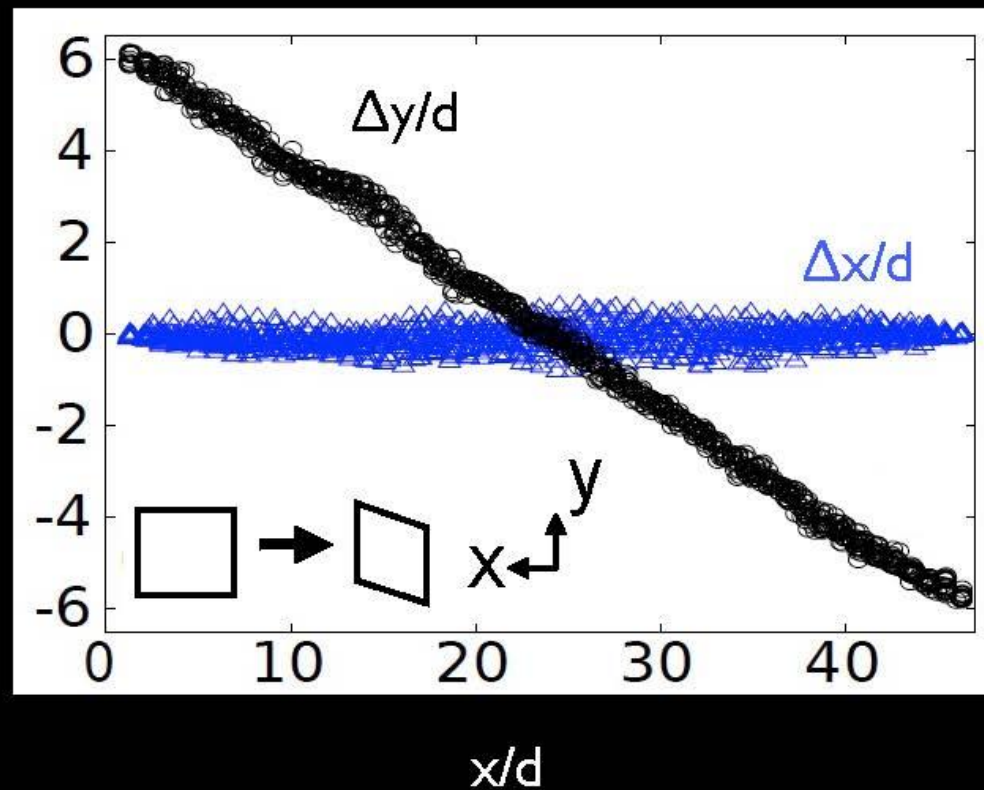


- Use bi-disperse particle:
  - $d_S=0.5''$ ,  $d_L=0.65''$ ,  $N_S/N_L \sim 3.3$
  - Total particle number:  $\sim 1000$
- Rectangle width  $\sim 25d_S$
- Slat width  $= 0.5''$ , comparable to particle size
- Shear strain  $\varepsilon = x/x_0$ , increases by 0.482% per step
- Take photos of both the normal view of the particles, and the polarized view of force chain structures.

(Joshua Dijksman and Jie Ren)

This new experimental approach supplies uniform shear

## Particle displacements after shear

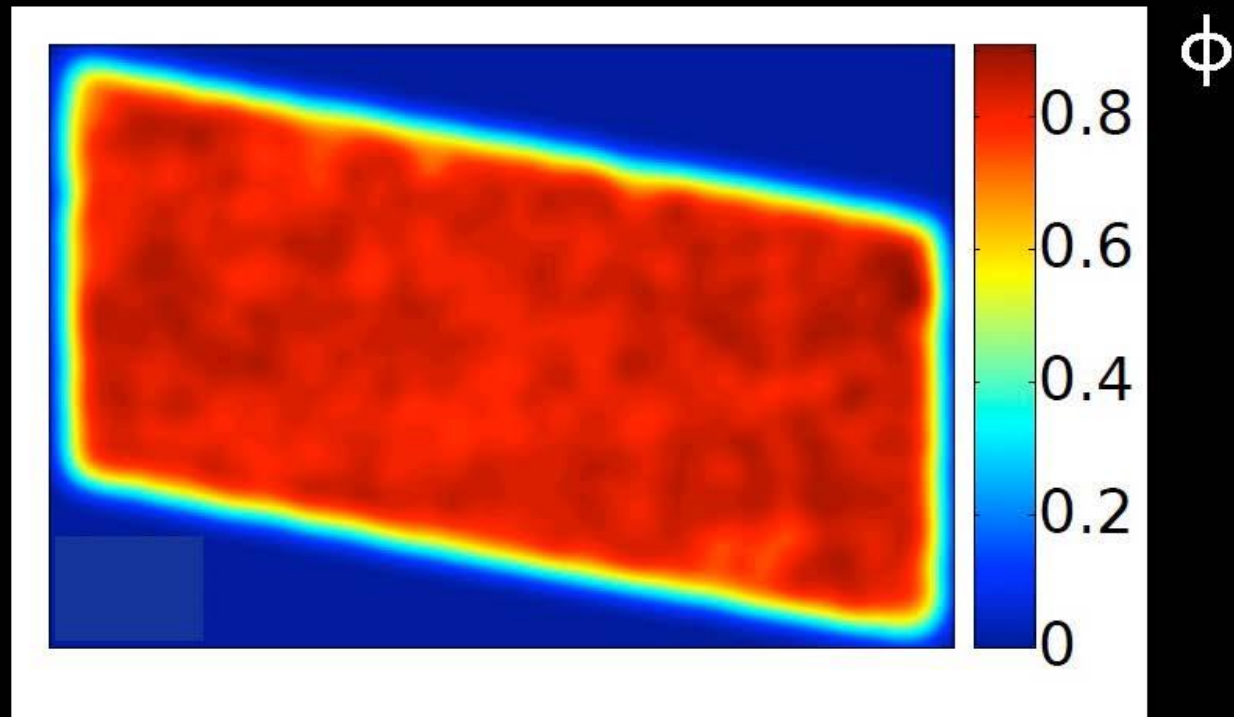


Bottom slats suppress inhomogeneities



Uniform shear  
No shear banding

Local packing fraction fluctuations are random



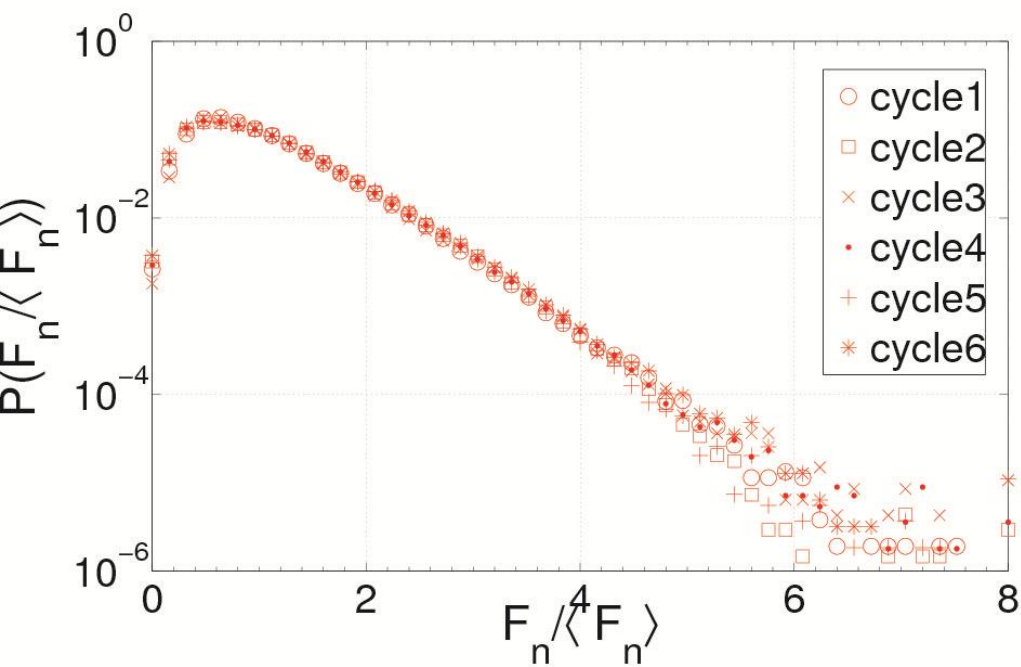
# Time-Lapse Video of Shear-Jamming



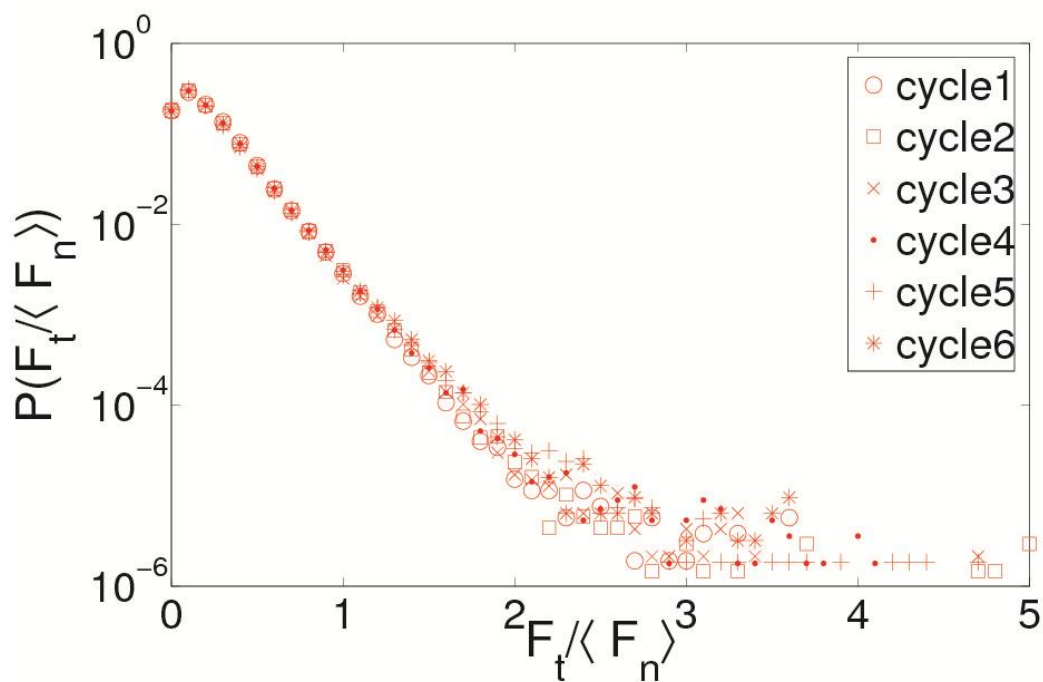
How important is friction with the base?  
Remove it by floating grains



Hu Zheng, Dijksman and RPB, Europhys. Lett. 2014

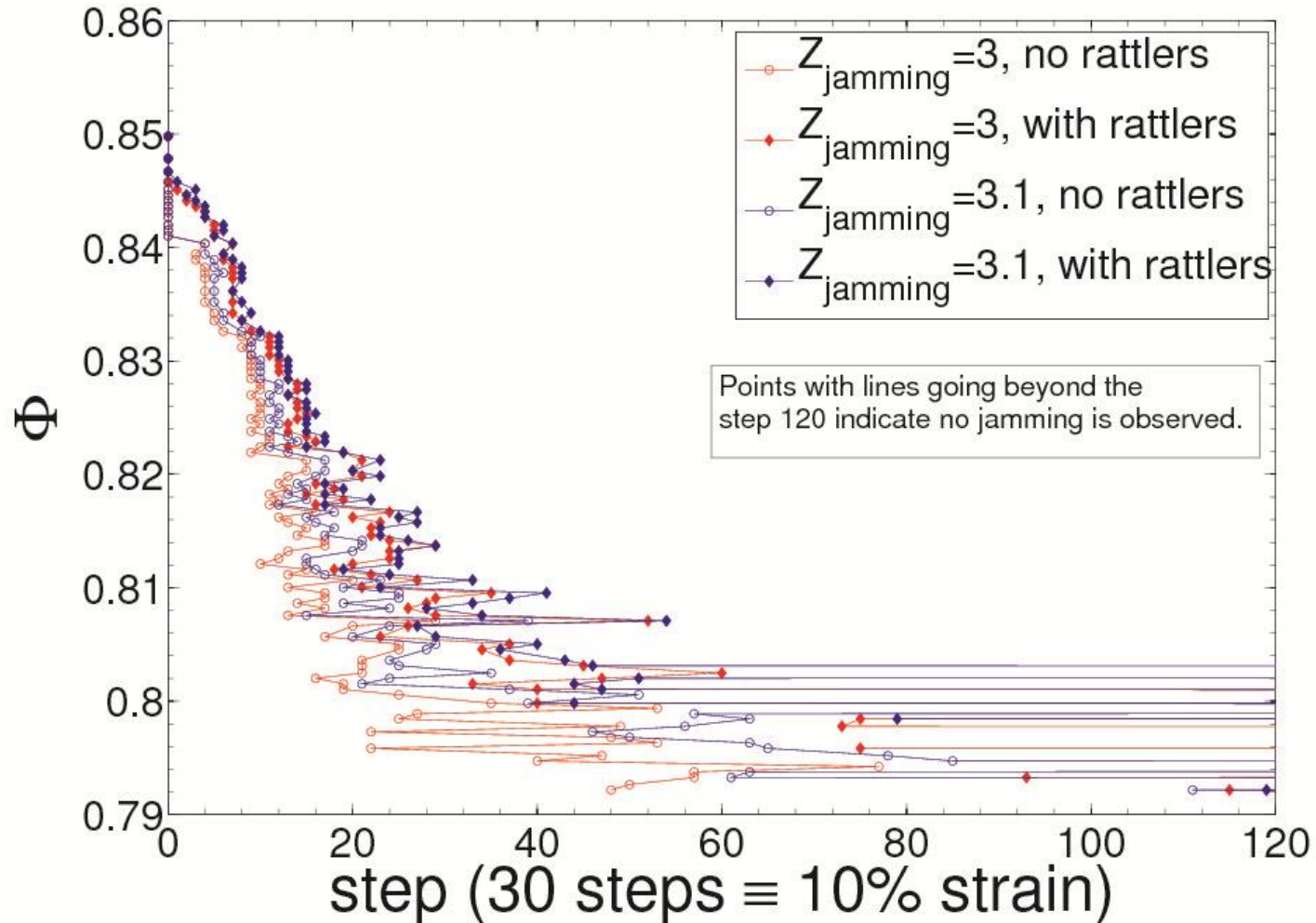


Good collapse of data for  $P(f)$  for normal and tangential contact forces

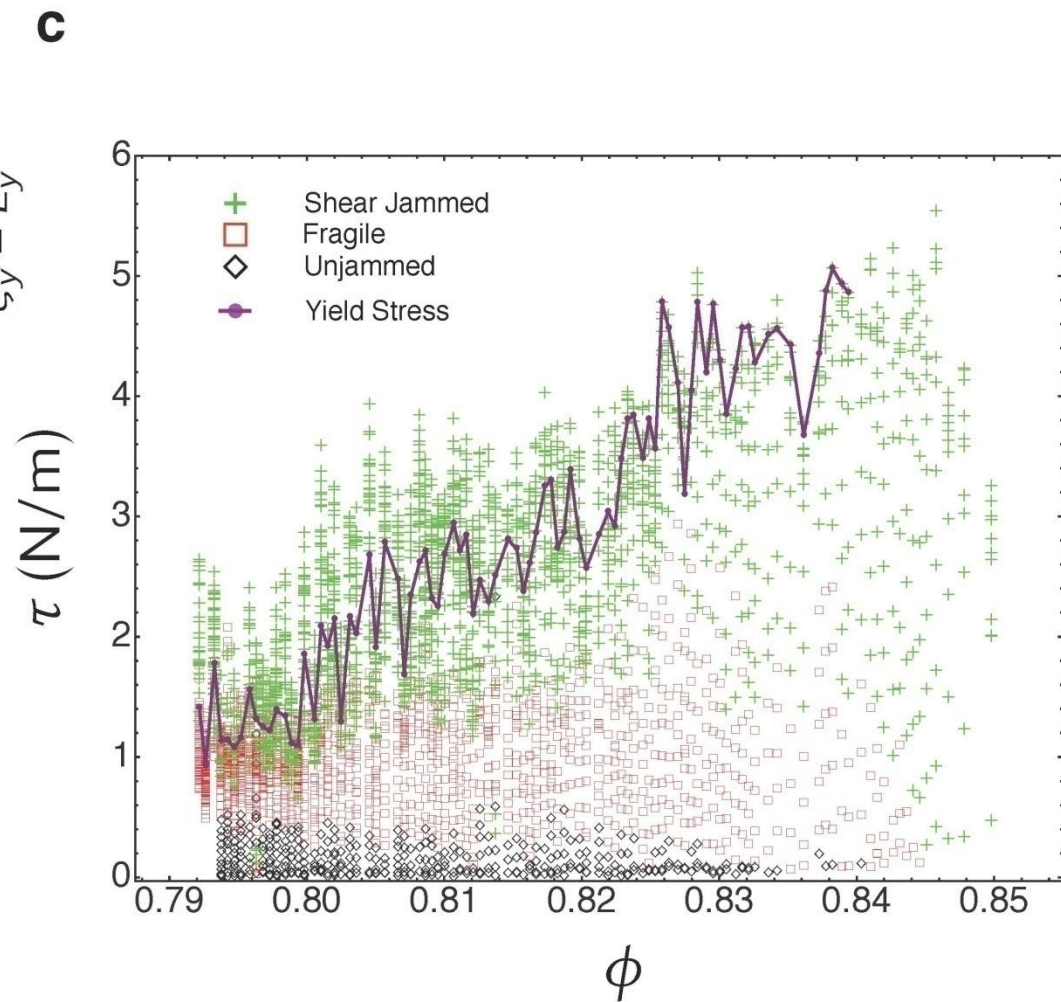
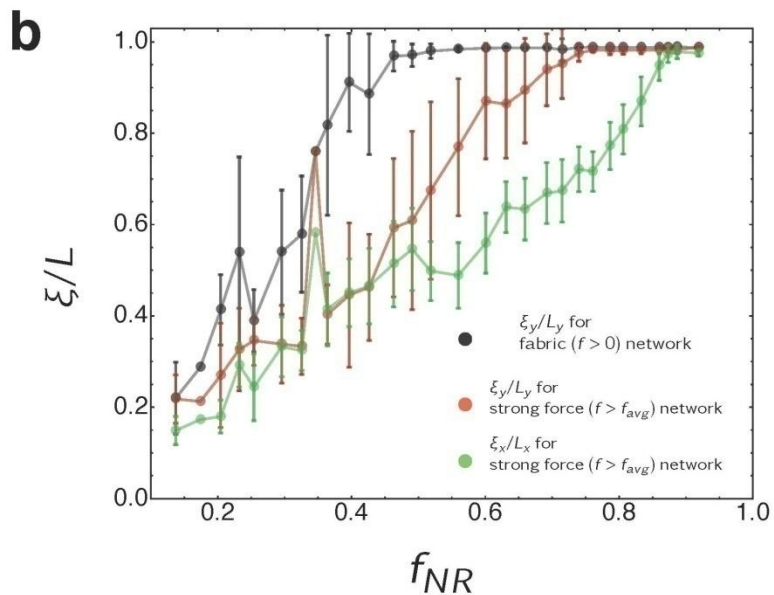
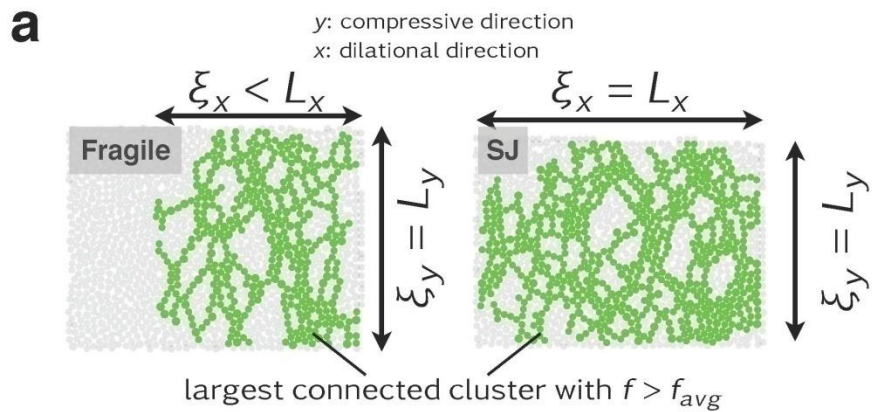




# Range of densities for which shear jamming can be achieved



# Directional Percolation, Fragile and Shear-Jammed States



See Otsuki and Hayakawa, Phys. Rev. E **83**, 051301 (2011)

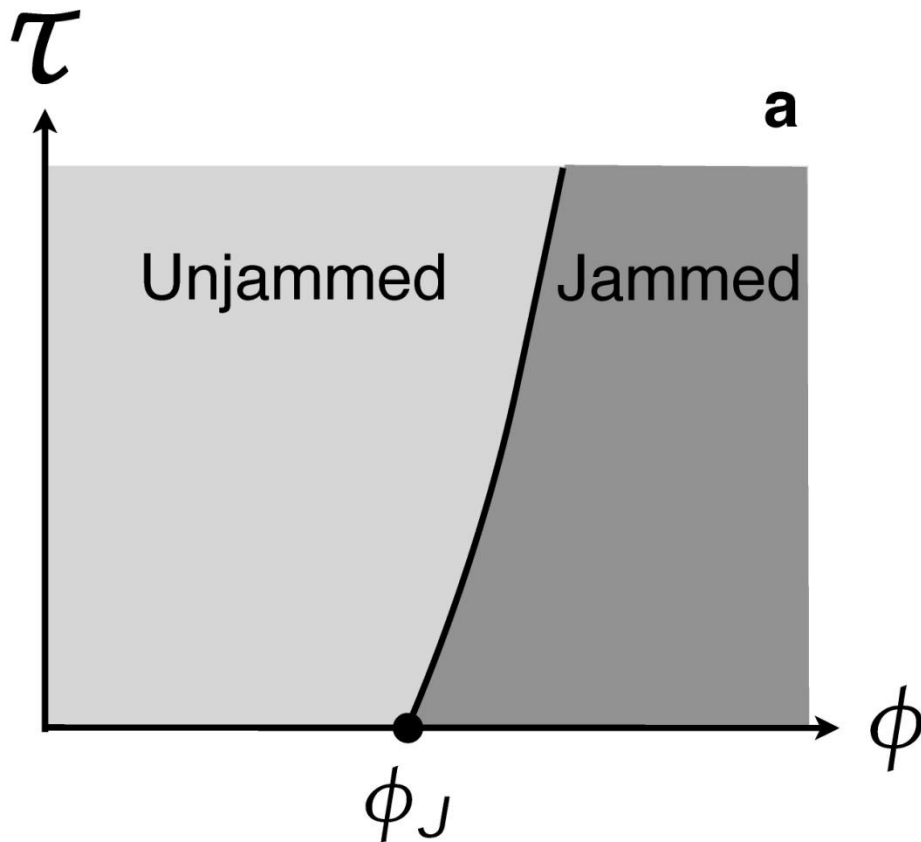
# Jamming diagram for Frictional Particles

Three kinds of state, depending on  $\phi$  and shear strain

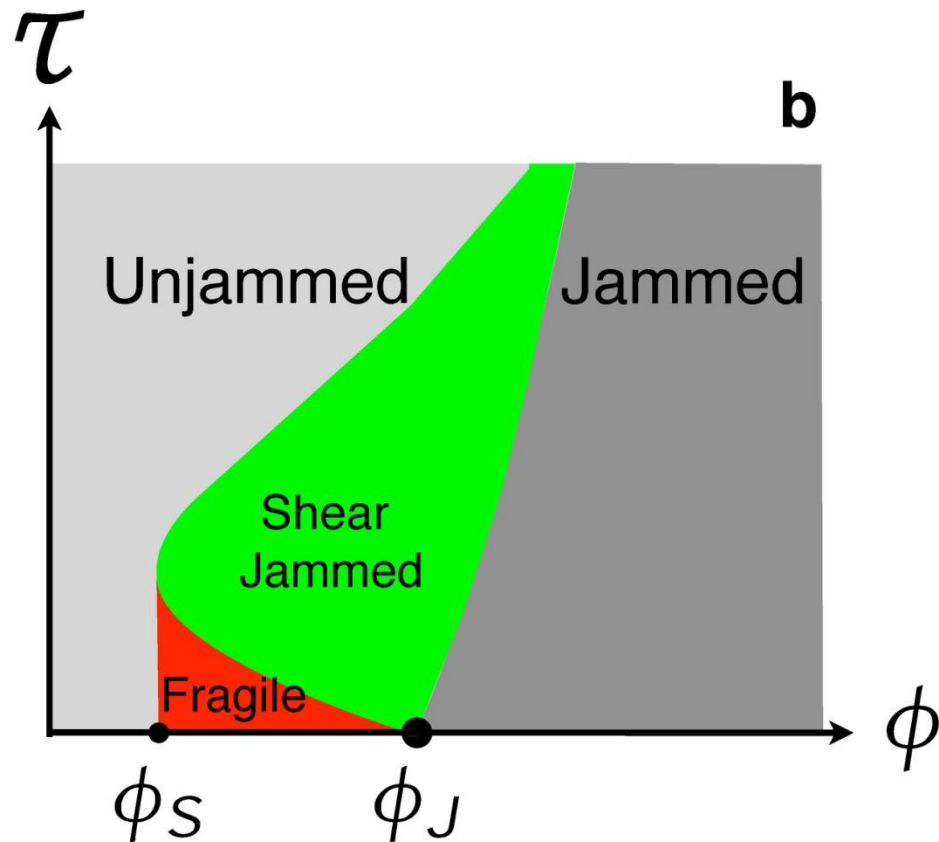
1) ... $\phi_S < \phi < \phi_J$ —for small shear, **fragile states**

2) ...with enough strain are **shear jammed states**

3) ... $\phi > \phi_J$ —jammed states occur at  $\tau = 0$

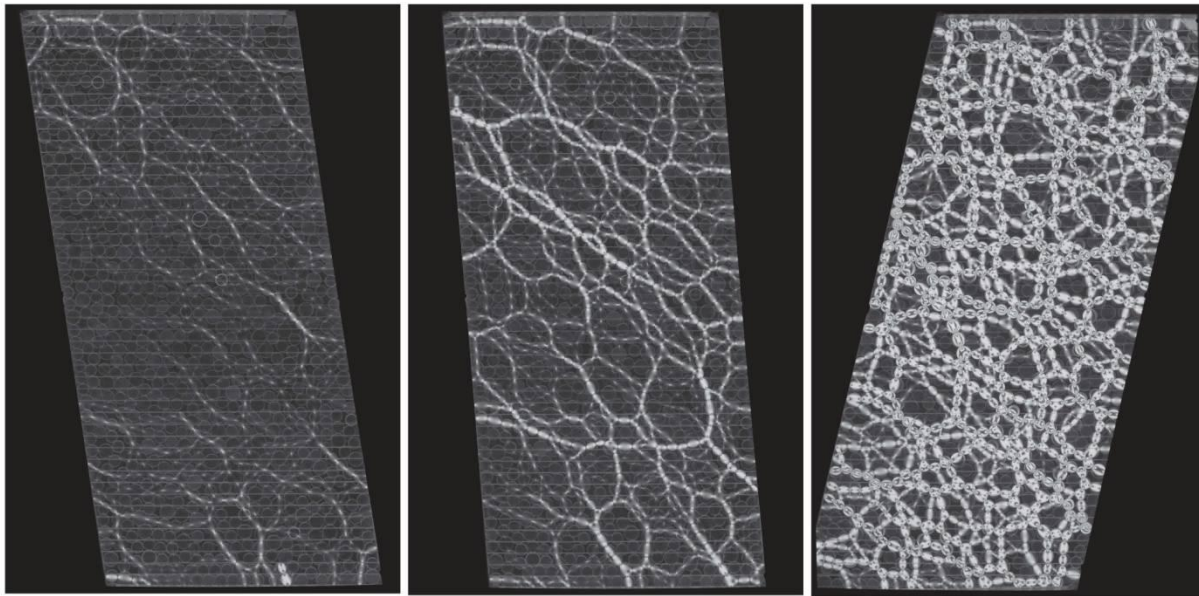


Original



New (Frictional)

# Types of States: *Fragile--Shear Jammed--Isotropic States*



Fragile

Shear jammed

Increasingly isotropic



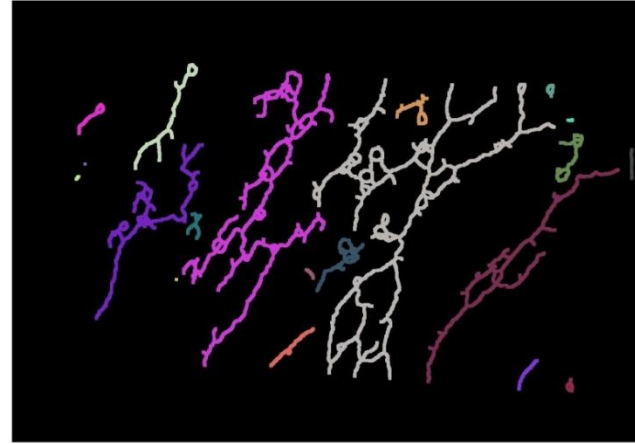
# But: networks are key to shear jamming

Increasing shear strain—first unidirectional, then all-directional  
percolation of strong force network

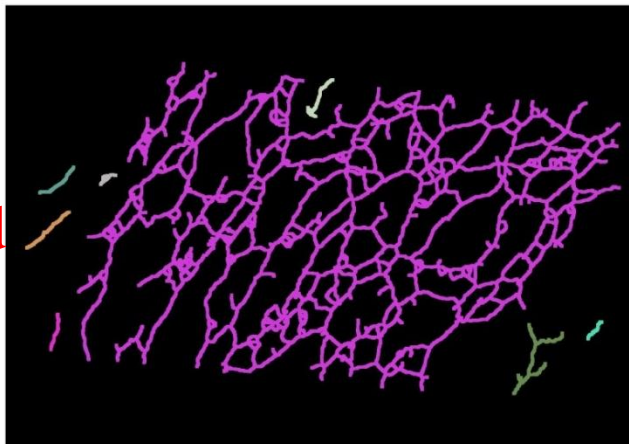
The force chains look differently at different stages of linear shear:



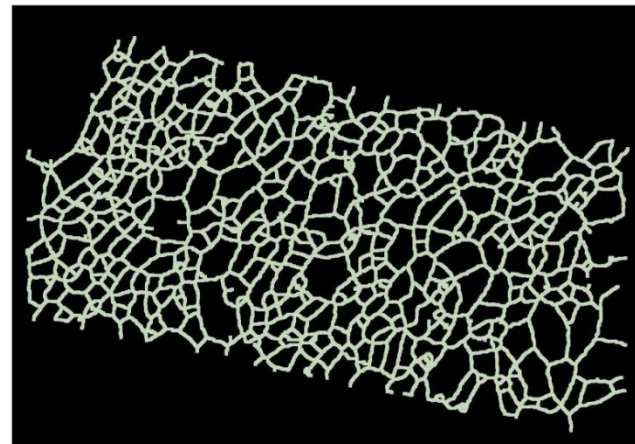
1. minimal force, unjammed



2. more force, multiple clusters; fragile



3. percolating cluster, onset of jamming



4. one large cluster, jammed

Unjammed  
not  
fragile

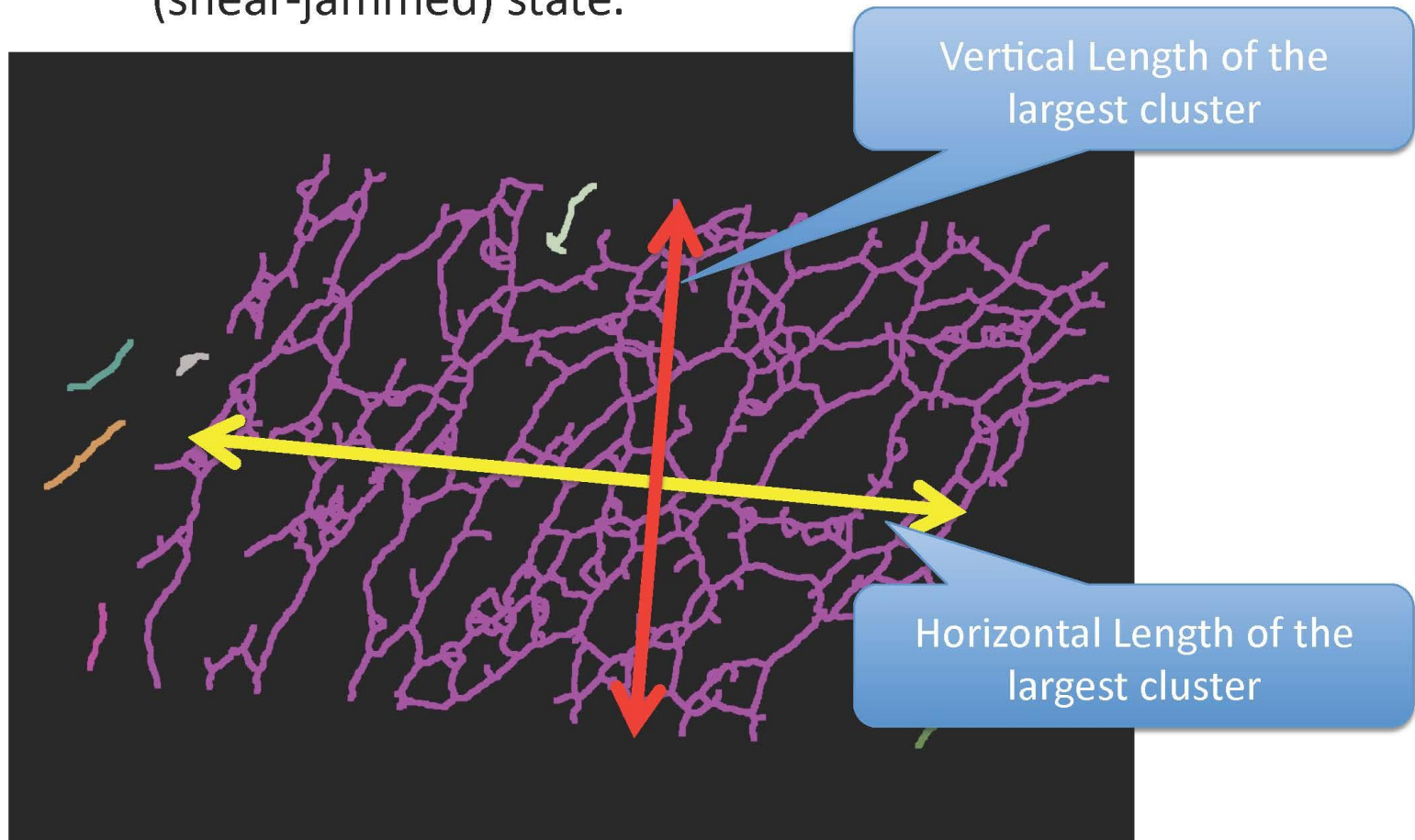
Fragile

Shear  
Jammed

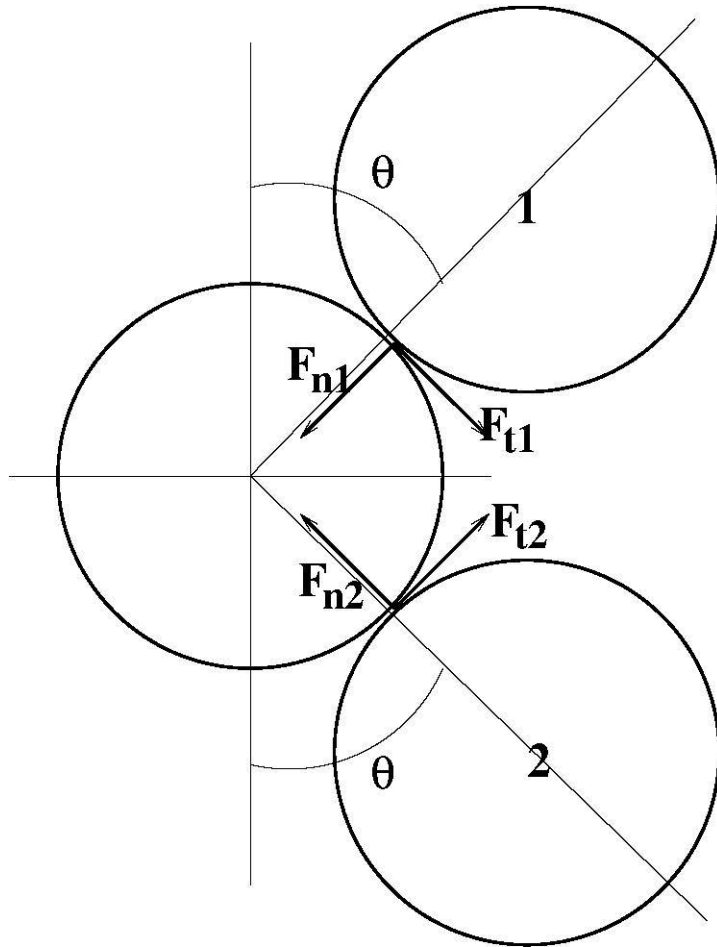
Evolves  
towards  
more  
isotropic

# Fragile and shear jammed transitions

- When the largest cluster's vertical (horizontal) length reaches the system size, the system reaches the fragile (shear-jammed) state.



# Long force chains $\rightarrow$ particles dominated by two strong contacts



Force/torque-balanced case:  
2 contacts on one particle

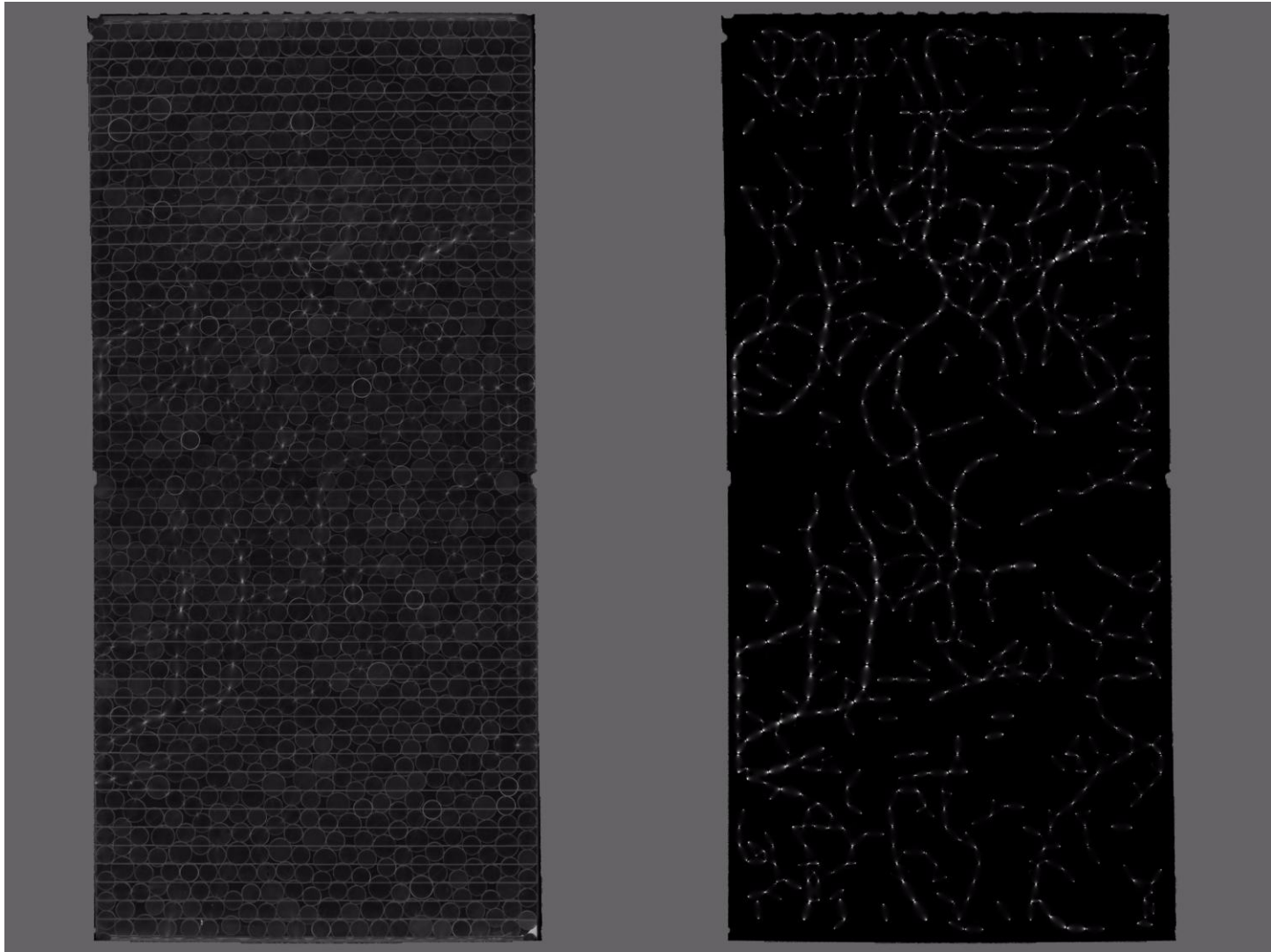
Force-moment tensor  
For this case: one non-zero and  
One zero eigenvalue—maximally  
stress anisotropic at microscale

Long force chains  $\rightarrow$  stress anisotropy

Friction enhances stress anisotropy (?)

# Friction enhances stress anisotropy (?)

Contrast shearing with high and low  $\mu$  same density, first  $\mu = 0.7$



Raw

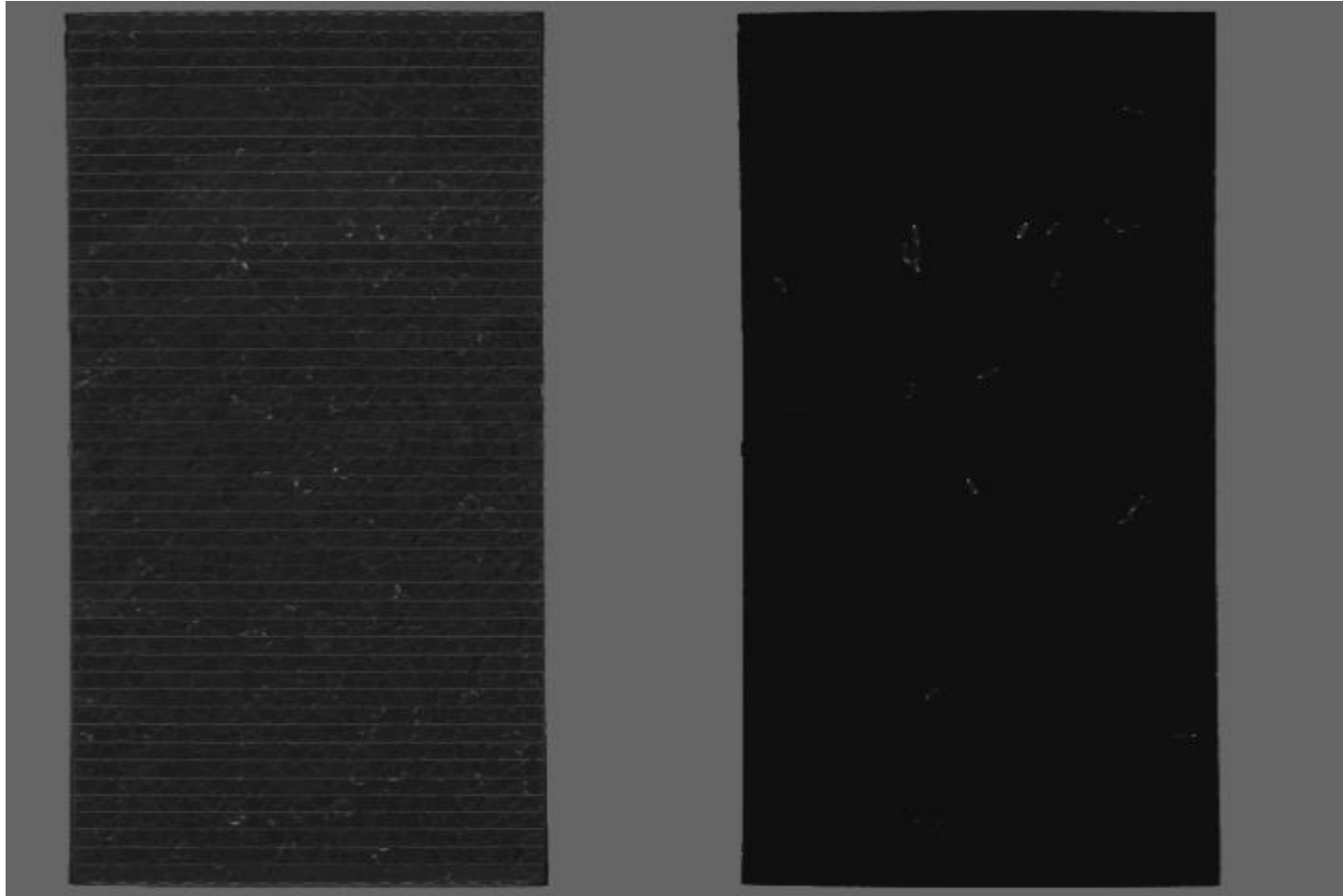
experiment

J. Ren, J. Dijksman 2013

reconstruction



Now set  $\mu = 0.15$  (wrap particles with teflon tape)

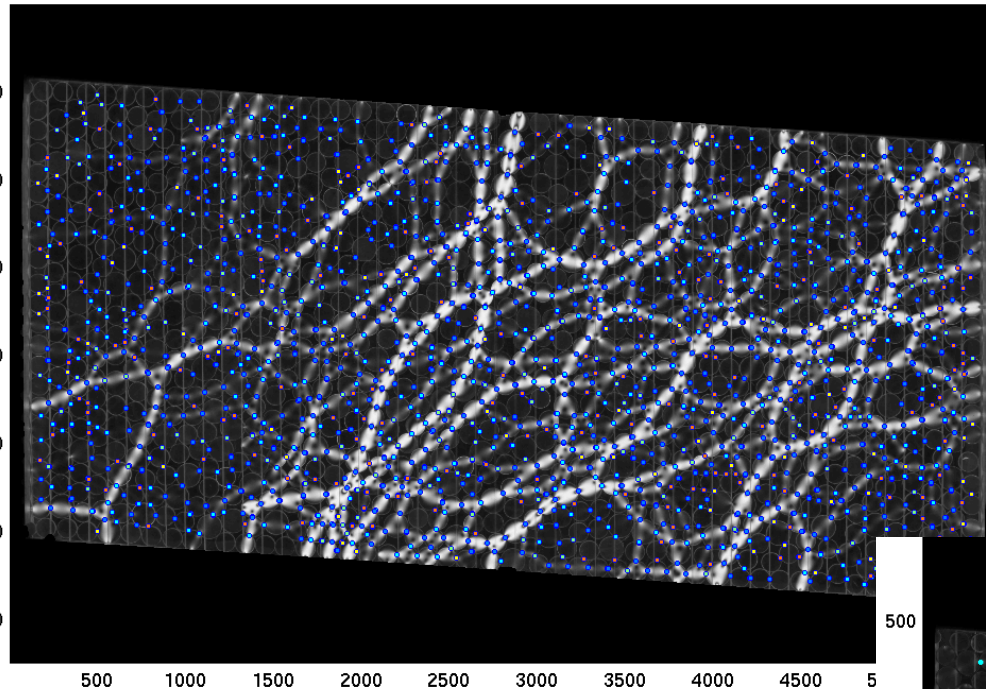


Raw  
experiment

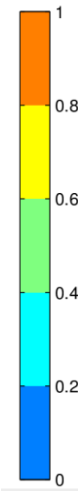
Dong Wang

reconstruction

# Mobilization of friction at contacts

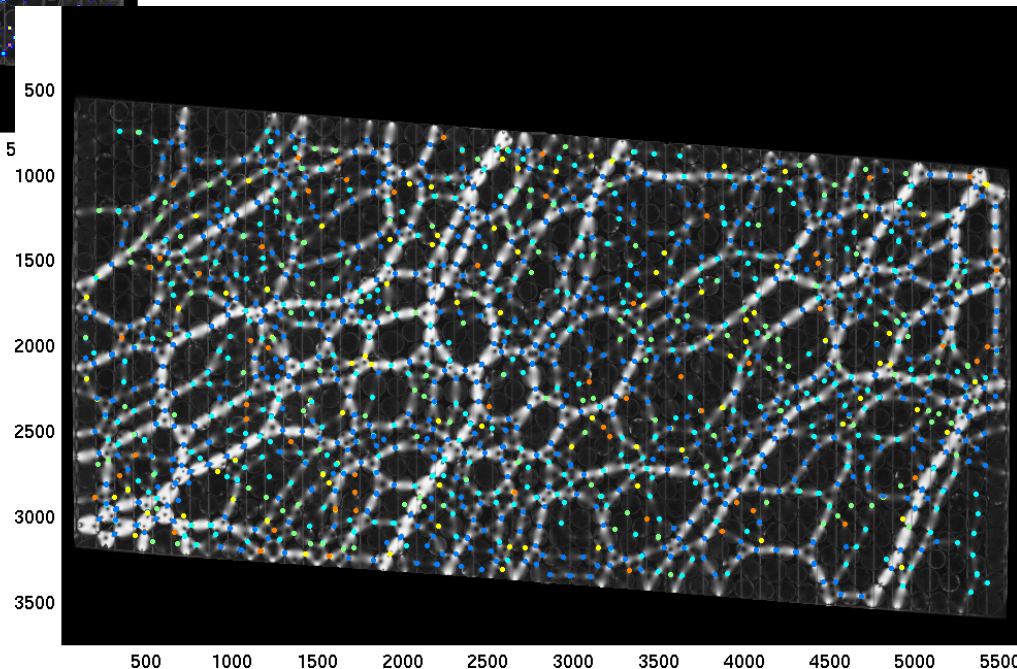


Normal particles

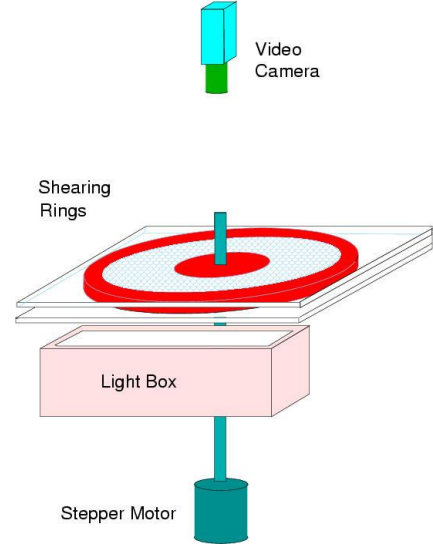
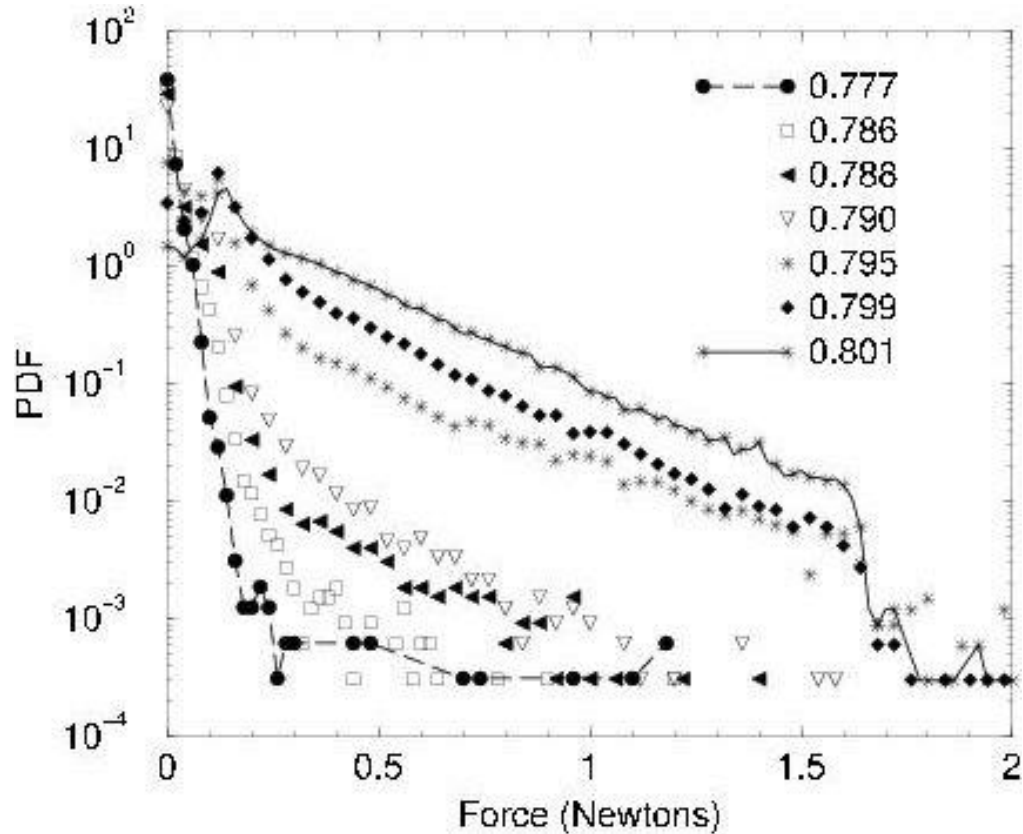


Mobilization of Friction:  $|F_t|/|F_n|$

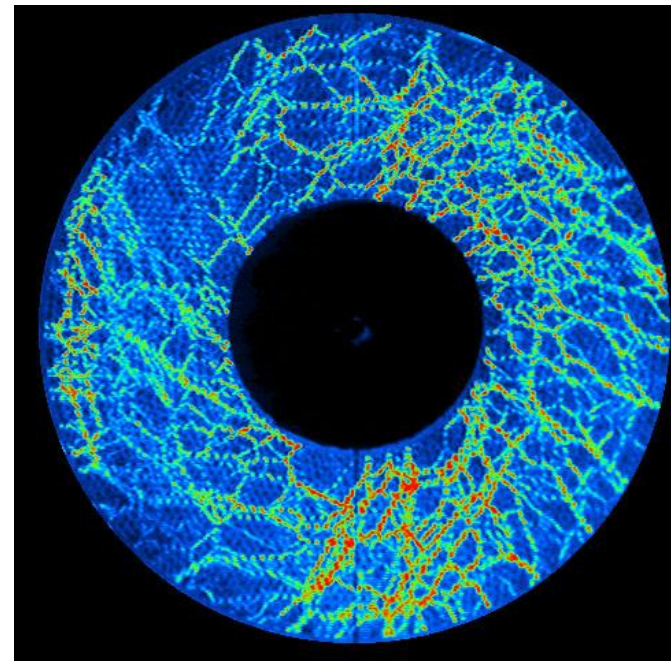
Slippery particles



# Pressure—particle-scale



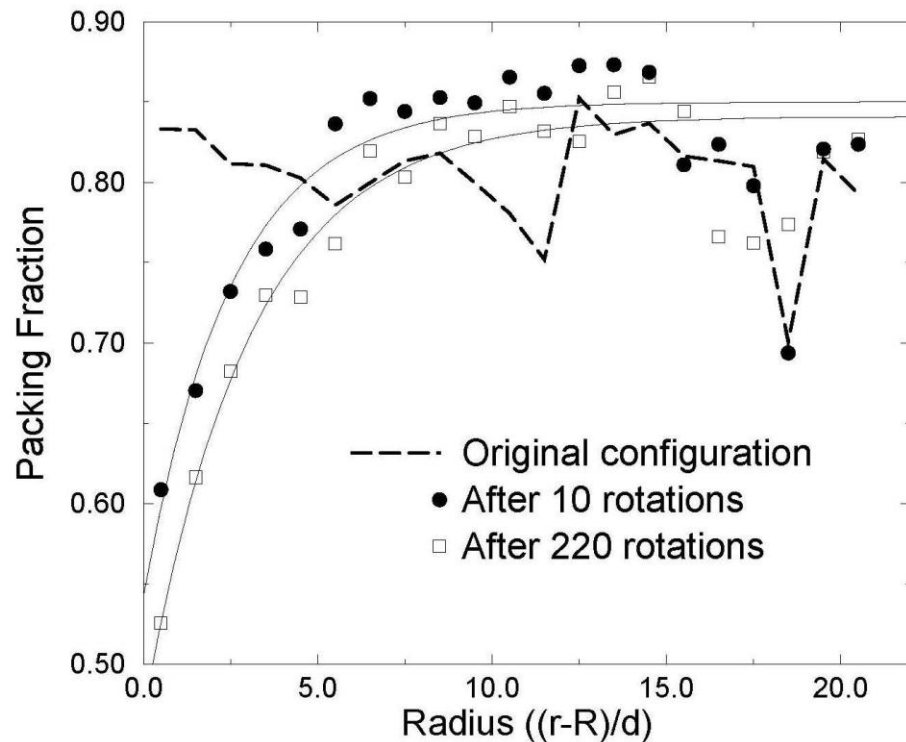
Howell et al.  
PRL 82, 5241 (1999)



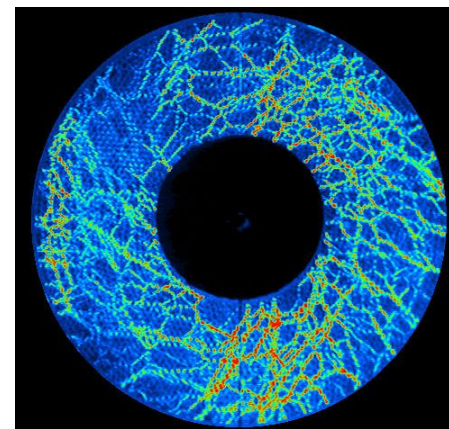
What broader role might shear jamming play

What are densities in Couette shear flow?

Deep shear band at inner rotating wheel  
densities there are ‘deep in the nose’ of the shear  
jamming diagram



Veje et al.  
PRE (1999)

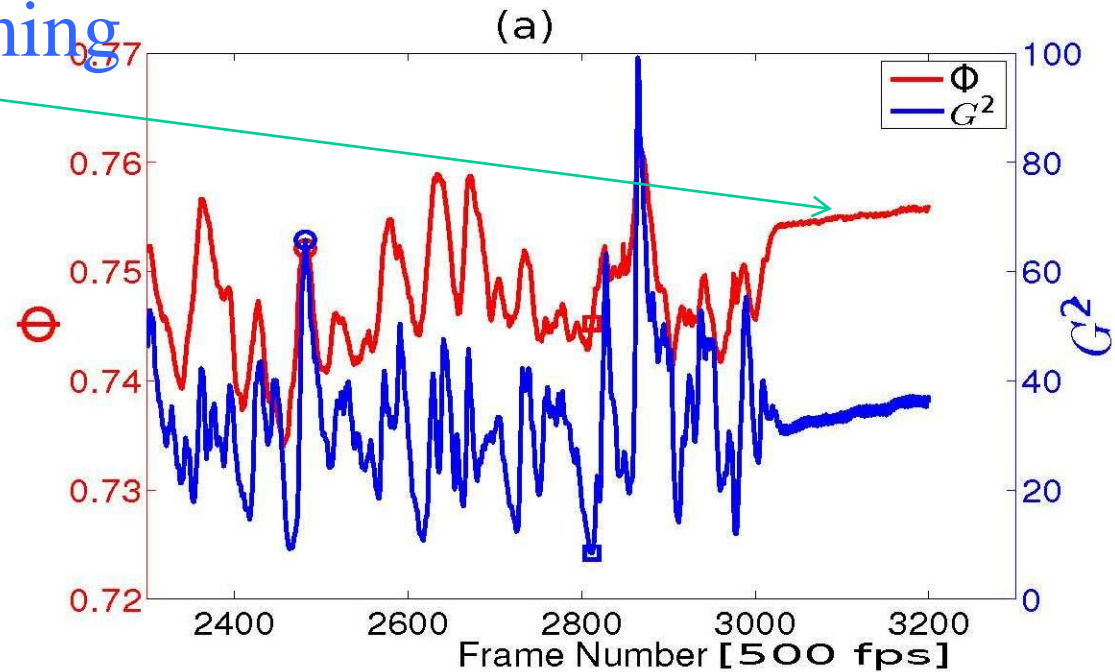
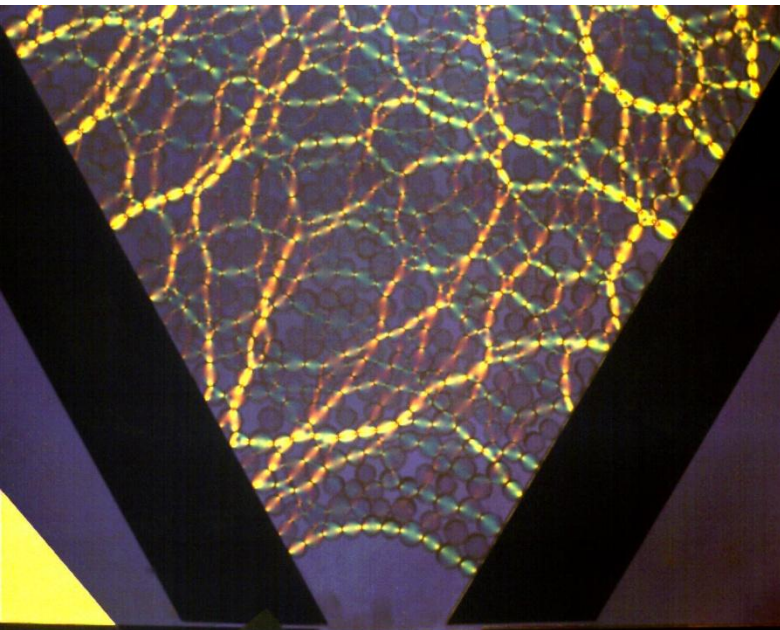




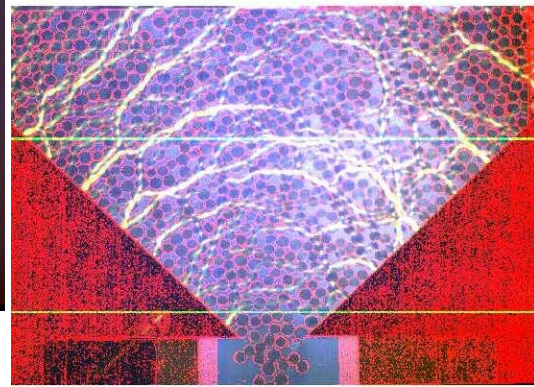
# What is the density doing during flow and after jam?

Low  $\phi$  even after jamming

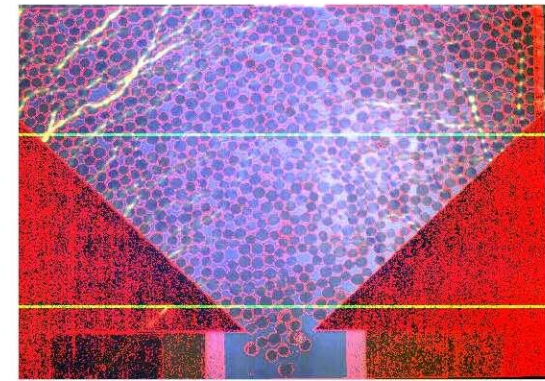
Jam in a hopper  
Experiment



(b)



(c)



What are the ‘right’ variables to describe states near shear jamming?

Possible choices:

density (packing fraction),

Shear strain,

Z,

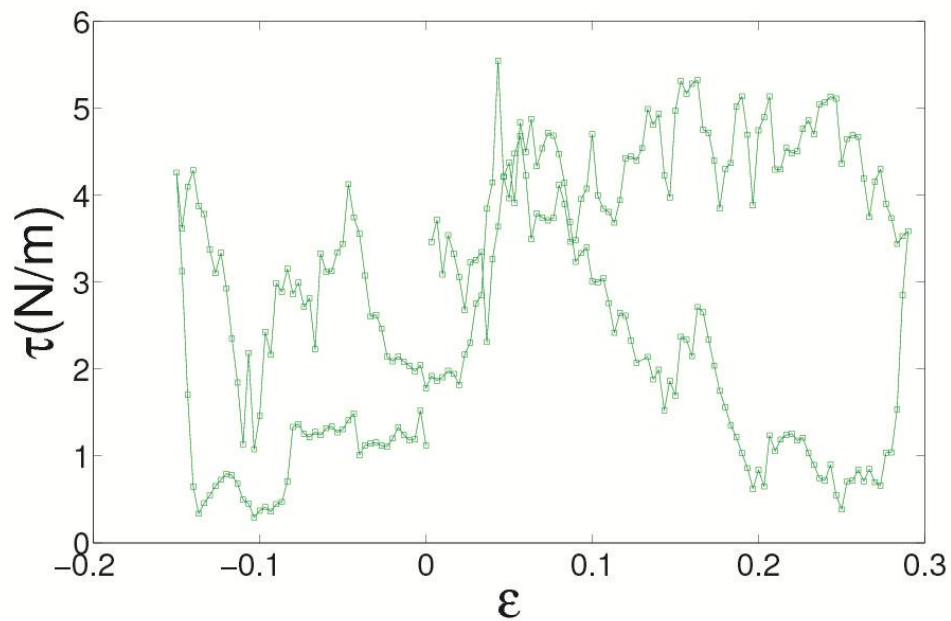
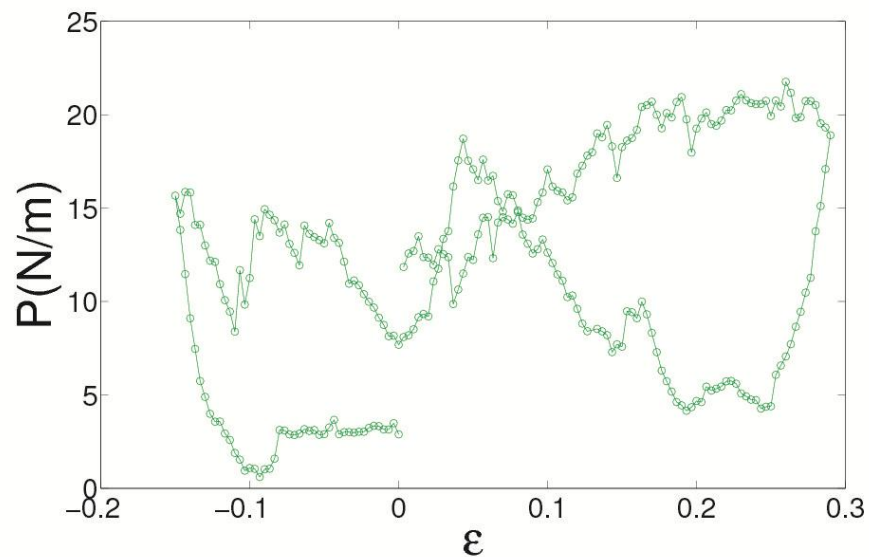
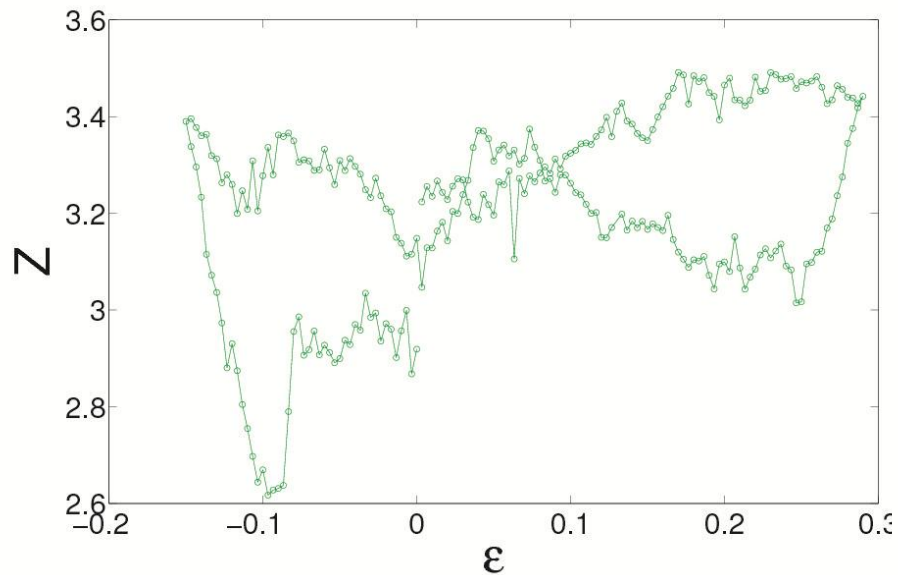
Also need a measure of anisotropy... which one?

Others?

Examine stresses and other variables to address this question—  
A ‘good’ variable is the non-Rattler fraction

# Hysteresis in stress-strain and Z-strain curves—one cycle

*Shear strain is a poor 'state variable'*

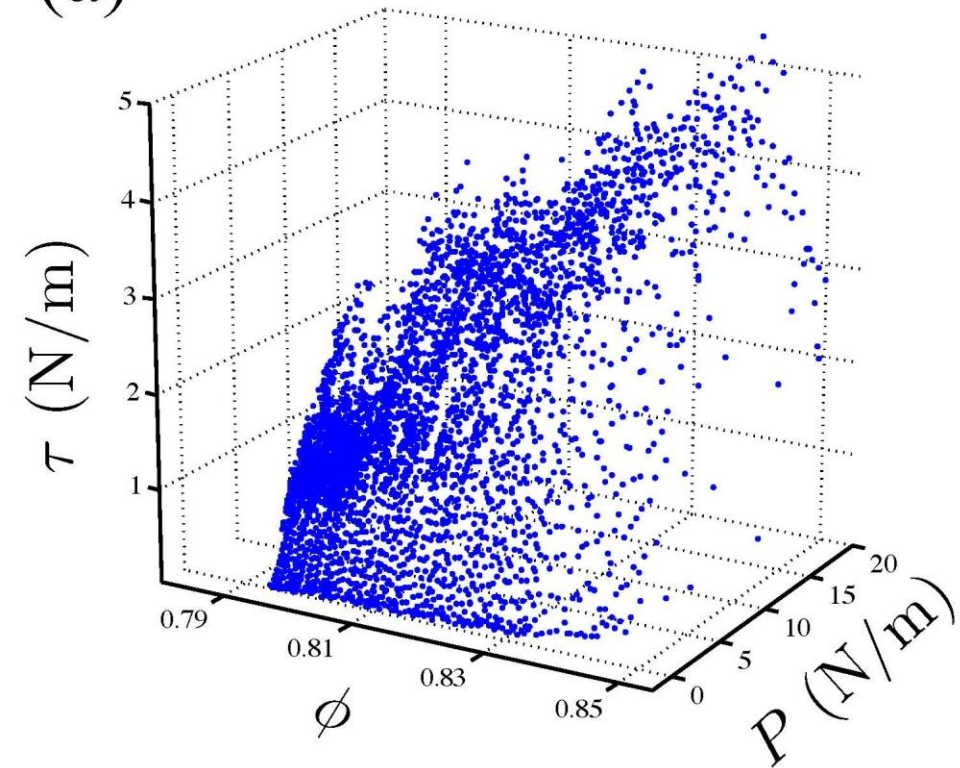


Stresses vs.

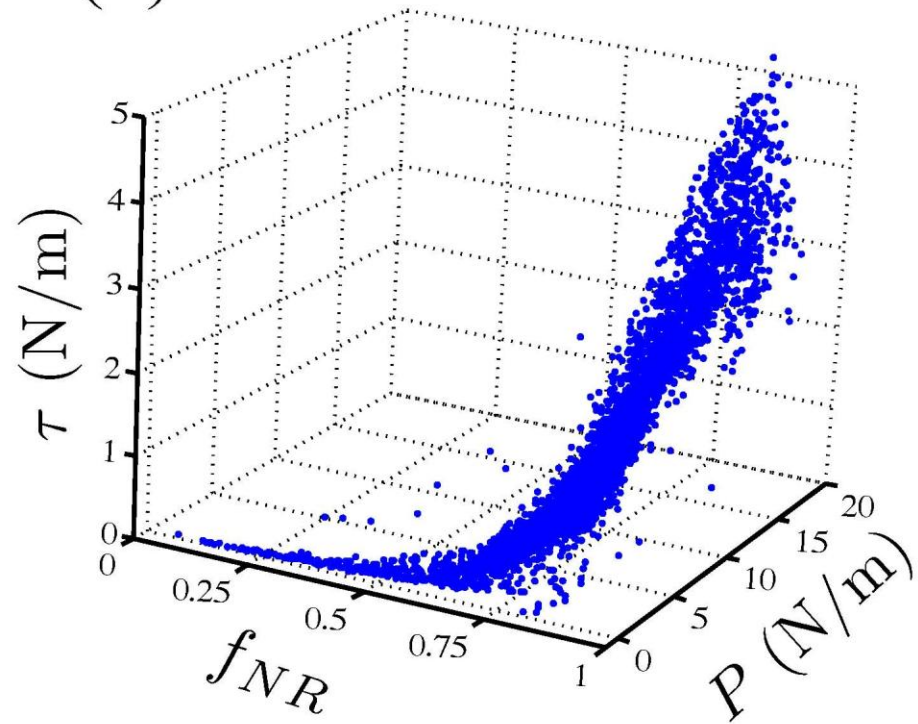
non-rattler fraction  $f_{NR}$

Close to shear jamming, good collapse of ‘classical measures’

(a)



(b)

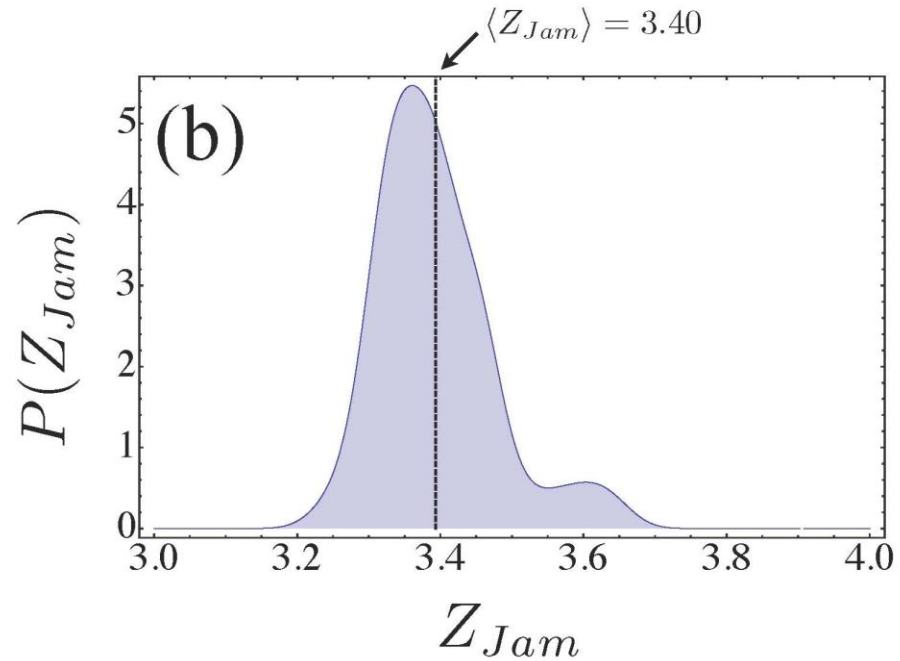
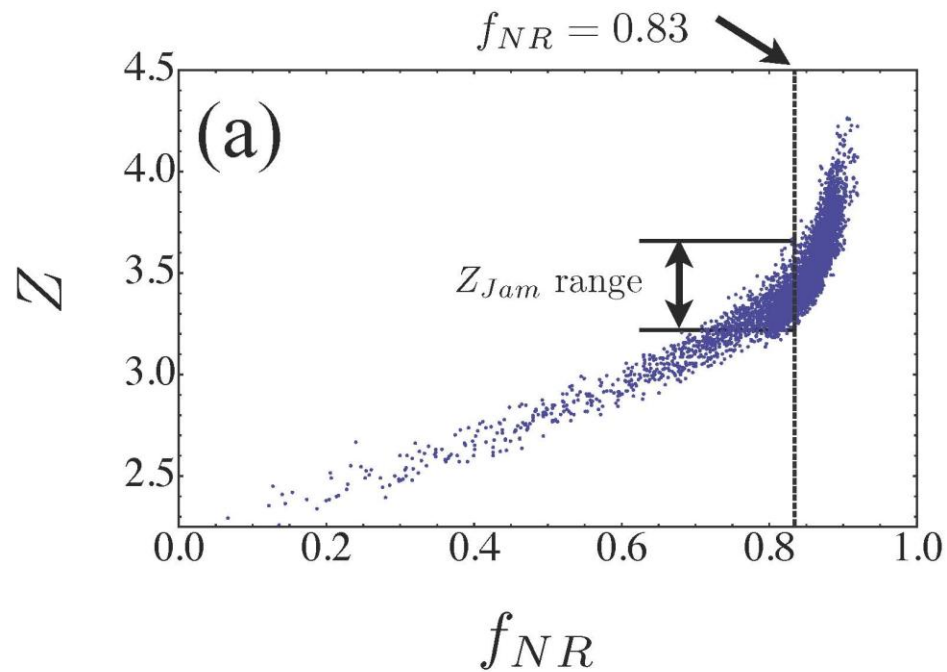


$\phi$  is important  
but not optimal

$f_{NR}$  = fraction of non-rattlers



# What about contact network properties, e.g. $Z$



$f_{NR}$  = fraction of non-rattlers

# Shear jamming has the flavor of an order-disorder transition...

- What is the nature of this transition?
- Can we identify a local order parameter?

## Analogy to a ferromagnetic system...

	Ferromagnet	Shear Jamming
Intensive Field	H (Magnetic Field)	$\gamma$ (Strain)
Extensive Field	M (Magnetization)	$\tau$ (Stress Tensor)

## Magnetic system consists of spins...

- What is spin in granular system?

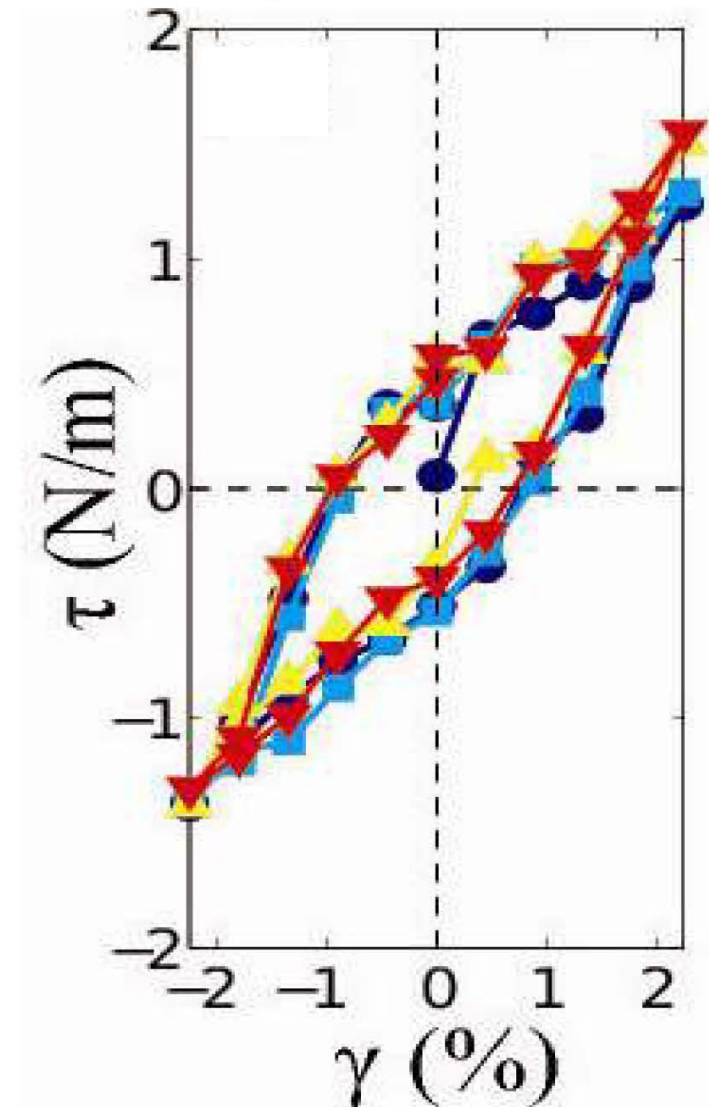
# Cyclic Shear -- Magnetization and Hysteresis Loops

“Magnetic Field”

$$\underline{\gamma} = \gamma \hat{S}_2 = (0, \gamma)$$

“Magnetization”

$$\hat{\tau} \Rightarrow \underline{s} = (a, b)$$

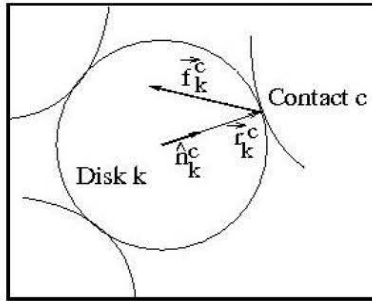


# Microscopic Order Parameter

Particle-scale Force Moment Tensor

$$\hat{\sigma} = \sum \mathbf{r} \times \mathbf{f}$$

Symmetric



Deviatoric Part

$$\hat{\tau} = \hat{\sigma} - \frac{1}{2} \text{Tr}(\hat{\sigma}) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} a & b \\ b & -a \end{pmatrix}$$

Traceless, Symmetric

$$\hat{\tau} = \begin{pmatrix} a & b \\ b & -a \end{pmatrix} = a\hat{S}_1 + b\hat{S}_2$$

Orthogonal Basis

$$\hat{S}_1 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\hat{S}_2 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\mathbf{s} = \begin{pmatrix} a \\ b \end{pmatrix}$$

$\mathbf{s}$  is a spin-like order parameter!



# Microscopic Order Parameter

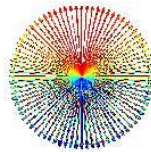
$$\hat{\tau} = \begin{pmatrix} a & b \\ b & -a \end{pmatrix} = a\hat{S}_1 + b\hat{S}_2$$
$$\hat{S}_1 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$
$$\hat{S}_2 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\hat{\tau} \Rightarrow \vec{s} = (a, b), \text{ "Spin"}$$

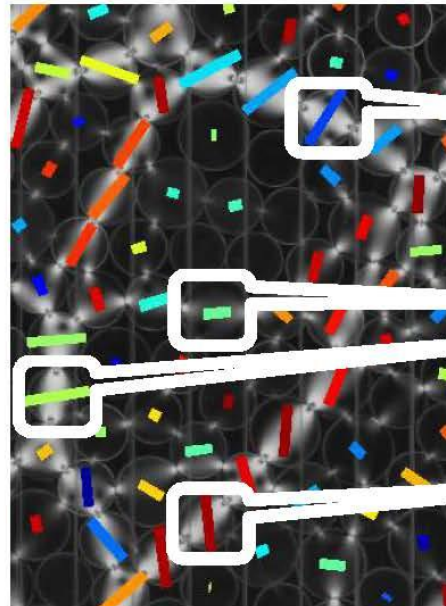
- Continuous orientation
- Length of spin is shear stress
- Extensive

## Spin Orientations

-- colored by spin orientation:



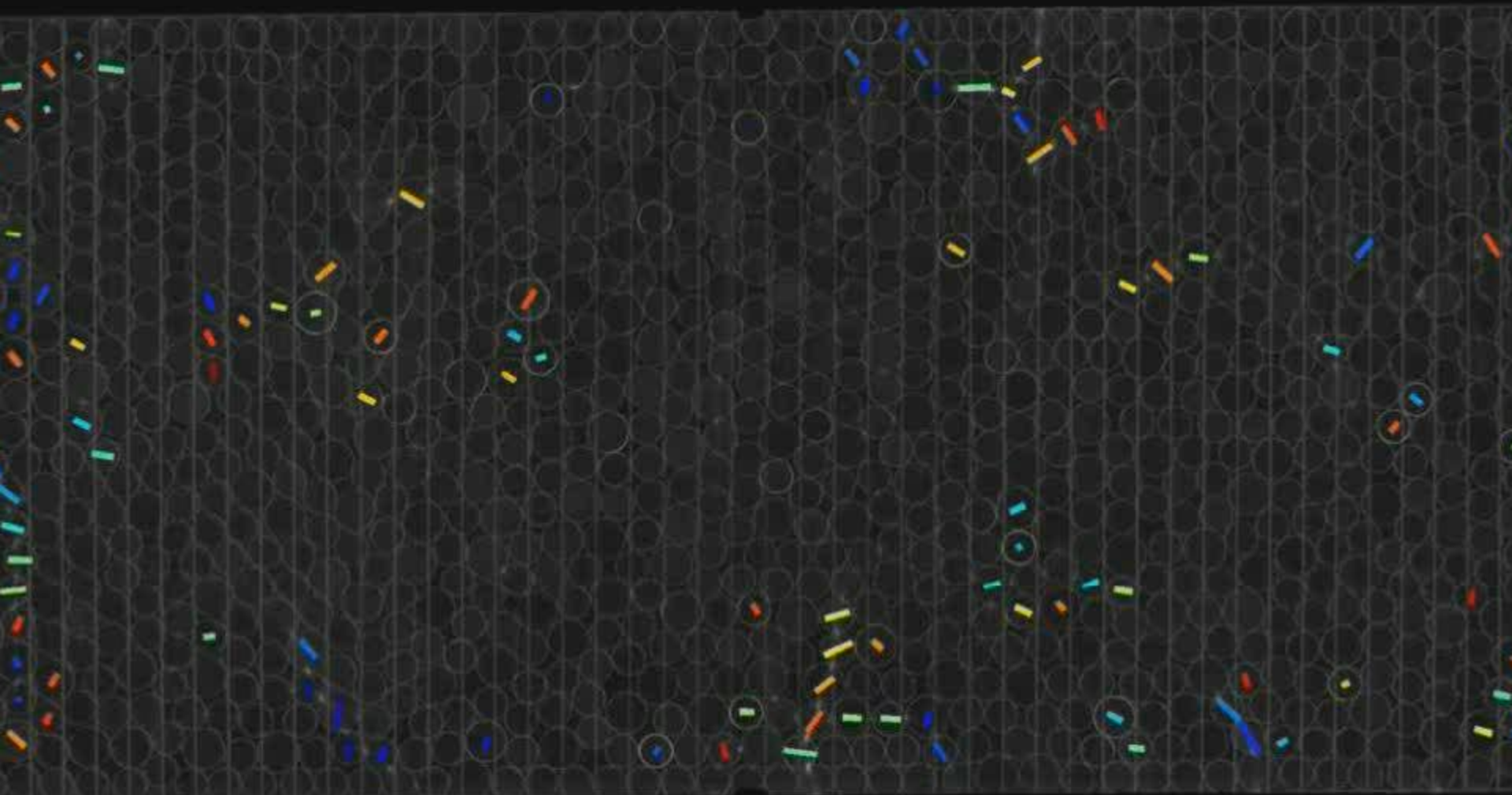
Particles with **perpendicular** stresses have **anti-parallel** spins.



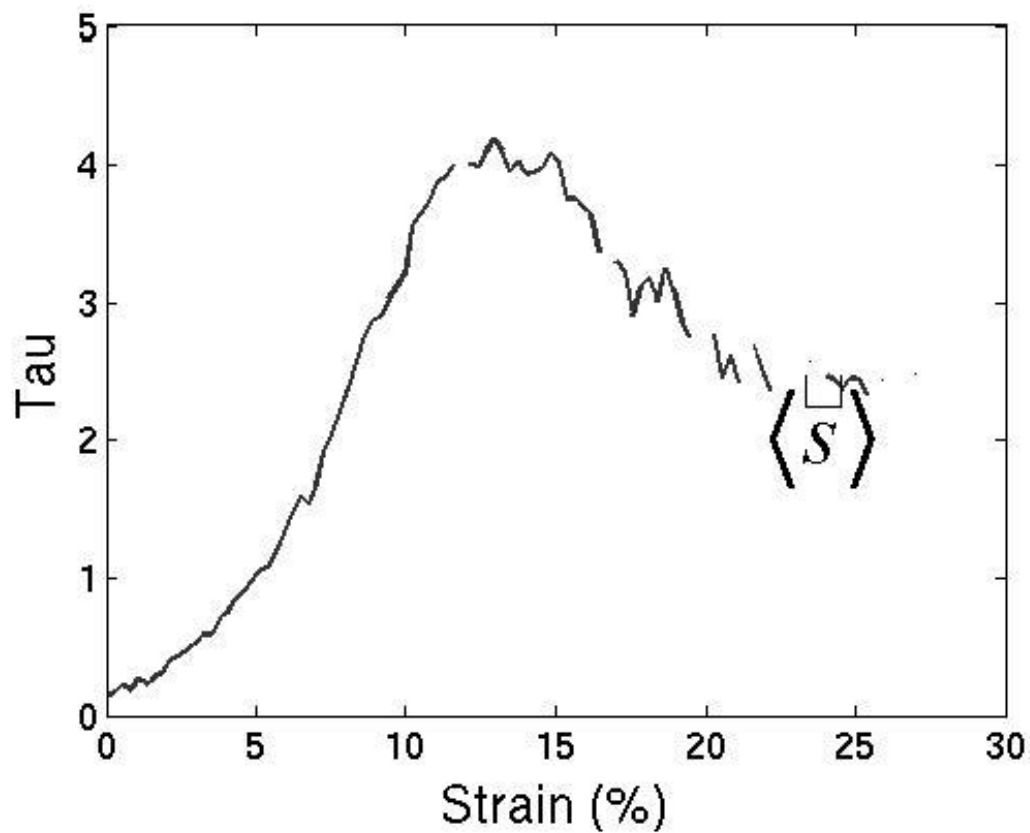
spin "Down"  
(Major compressive stress near  $-45^\circ$ )

spin "Horizontal"  
(Major compressive stress near  $0/90^\circ$ )

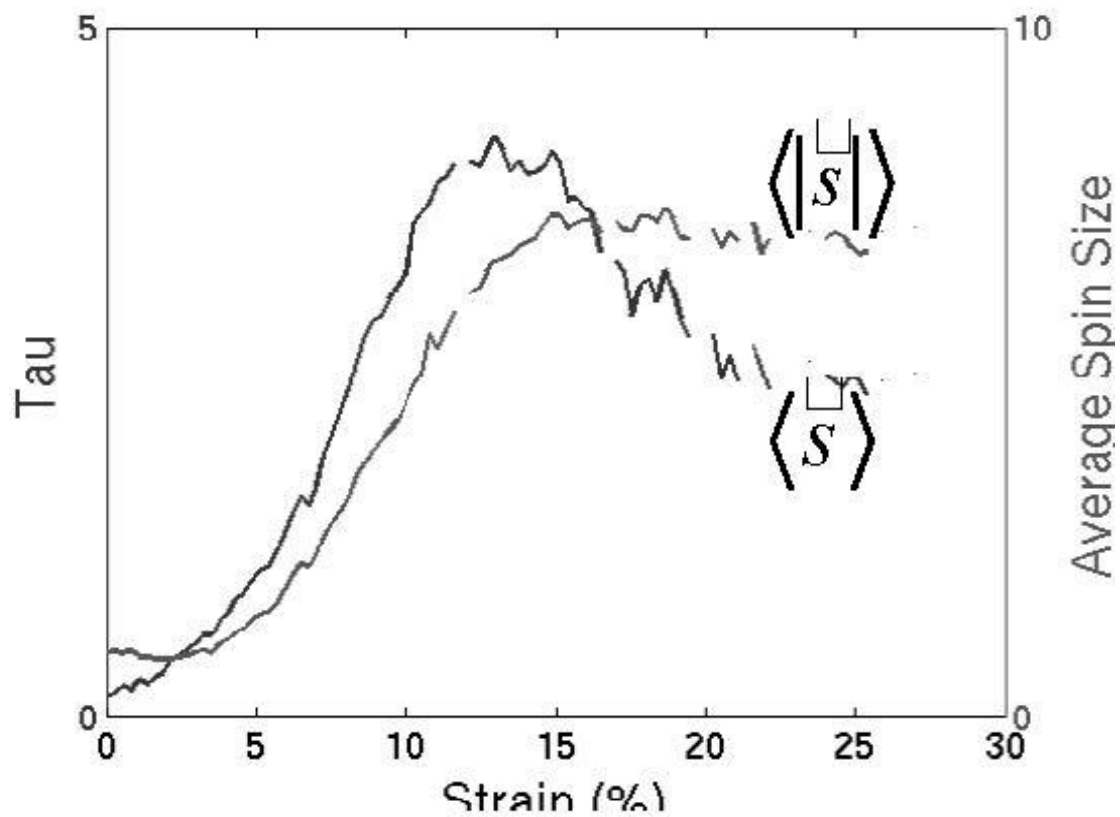
spin "Up"  
(Major compressive stress near  $45^\circ$ )



Stress Spins:  
Average value

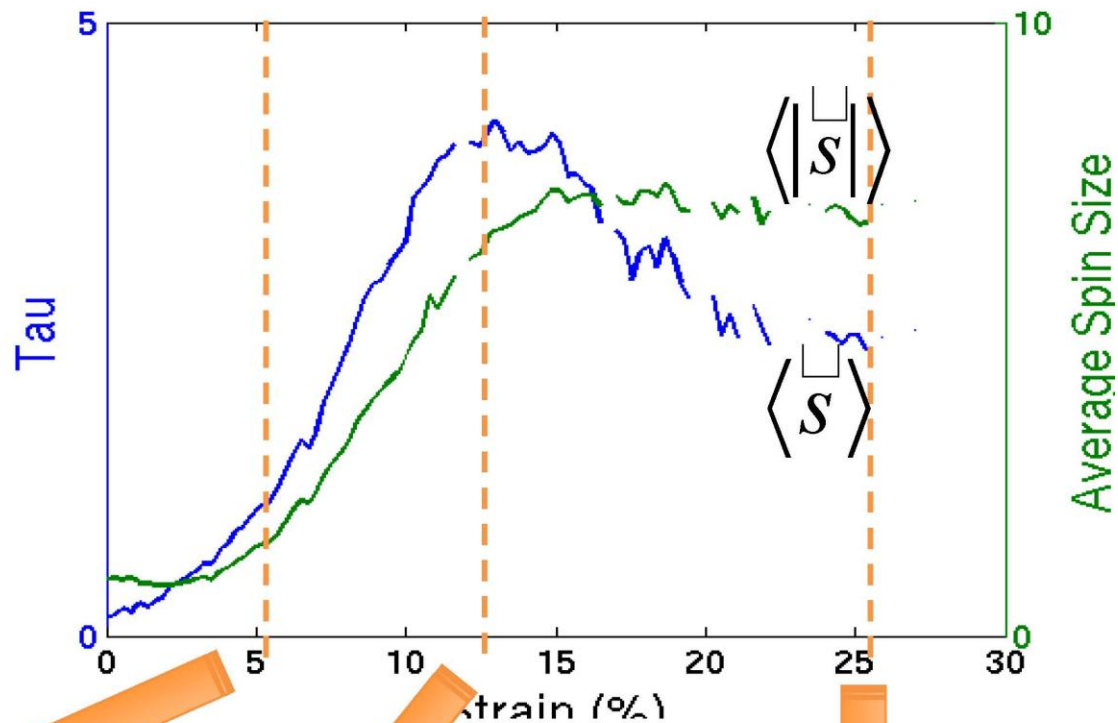


Stress Spins:  
Average value

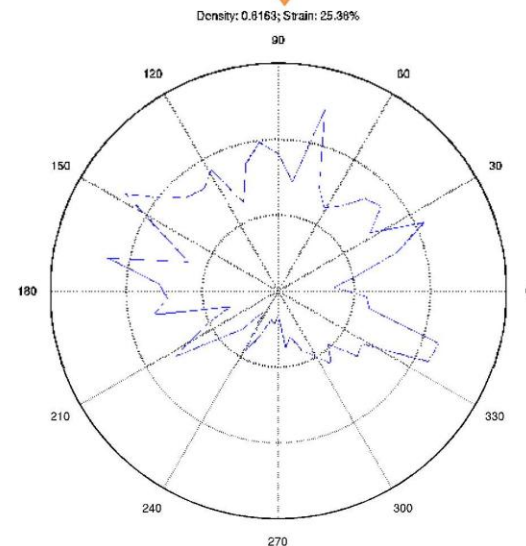
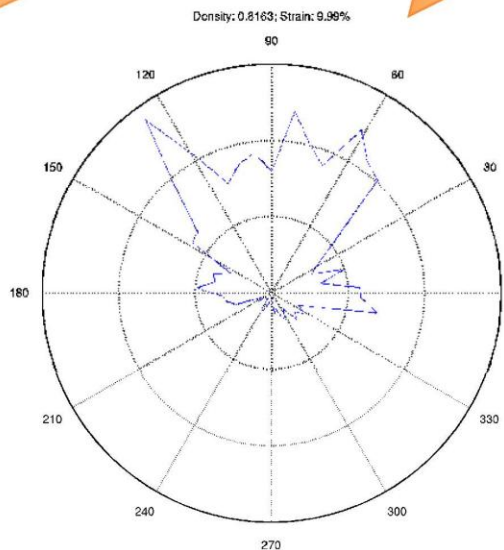
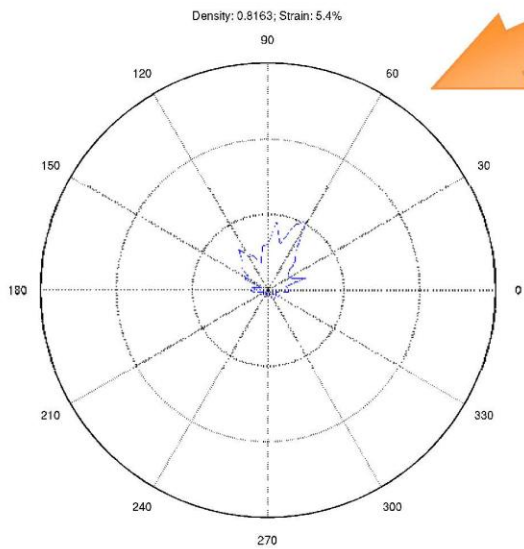




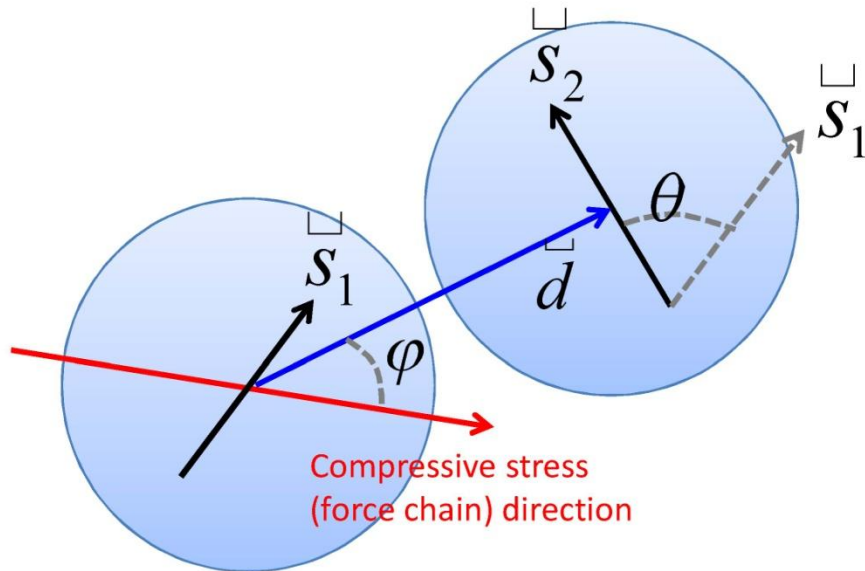
# Stress Spins: Angular distribution



Angular distribution of spins:



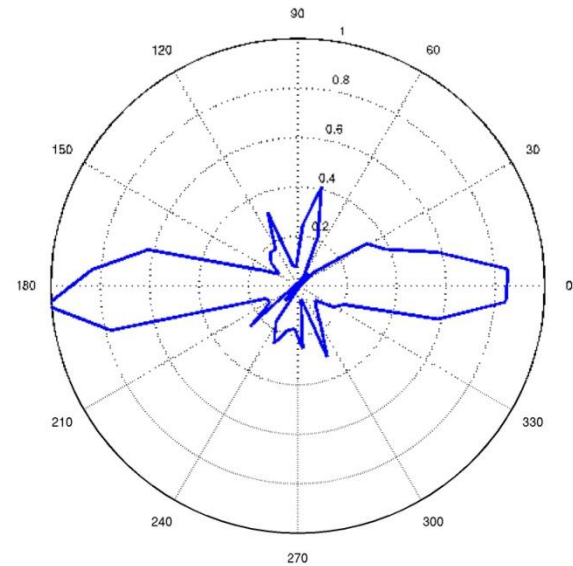
# Stress Spin Correlation: Nearest Neighbors



Scaled correlation:

$$\left( \frac{\langle S_1 \cdot S_2 \rangle}{\langle S_1 \cdot S_2 \rangle_{n.n.b.}} \right) = \cos(\theta_{n.n.b.})$$

$\cos(\theta_{n.n.b.})$  vs.  $\varphi$ :



Close-by spins tend to be parallel if they are along the force chains.

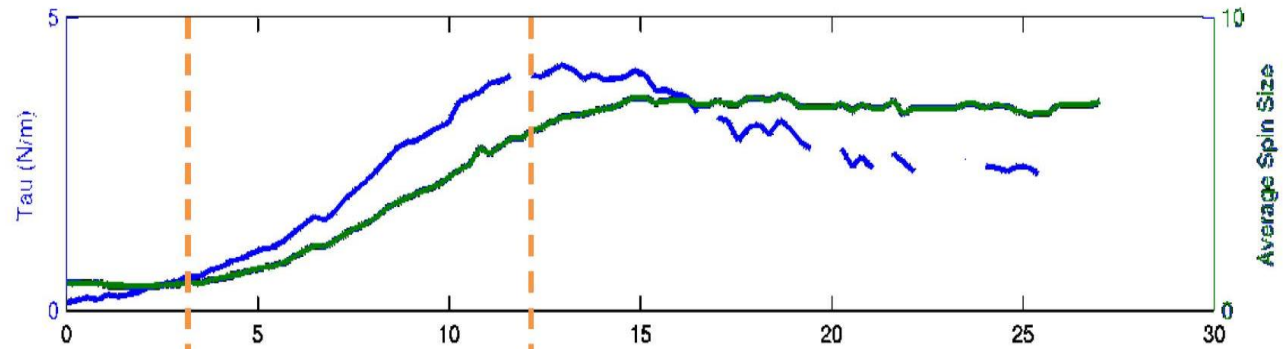
The strength of n.n.b. correlation is given by:

$$\langle \cos(\theta_{n.n.b.}) \rangle_{\varphi}$$

# Stress Spin Correlation

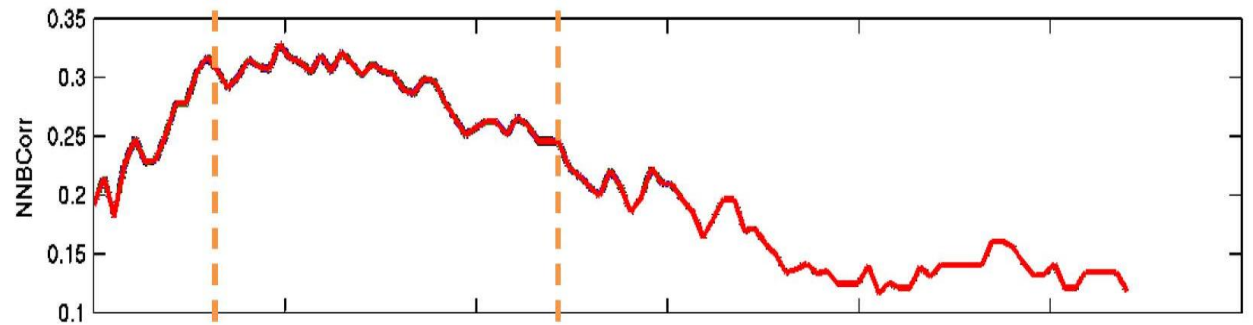
Average Stress

$$\phi = 0.8163$$



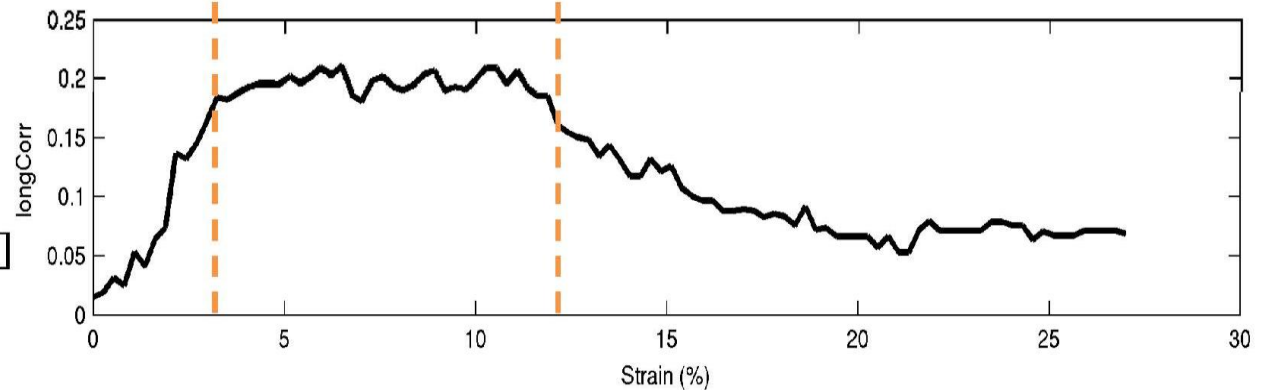
Short range correlation  
Nearest Neighbors

$$\langle \cos(\theta_{n.n.b.}) \rangle_{\phi}$$



Long range correlation

$$\langle \langle \cos(\theta) \rangle_{\phi} \rangle_{r \in [4D, 10D]}$$

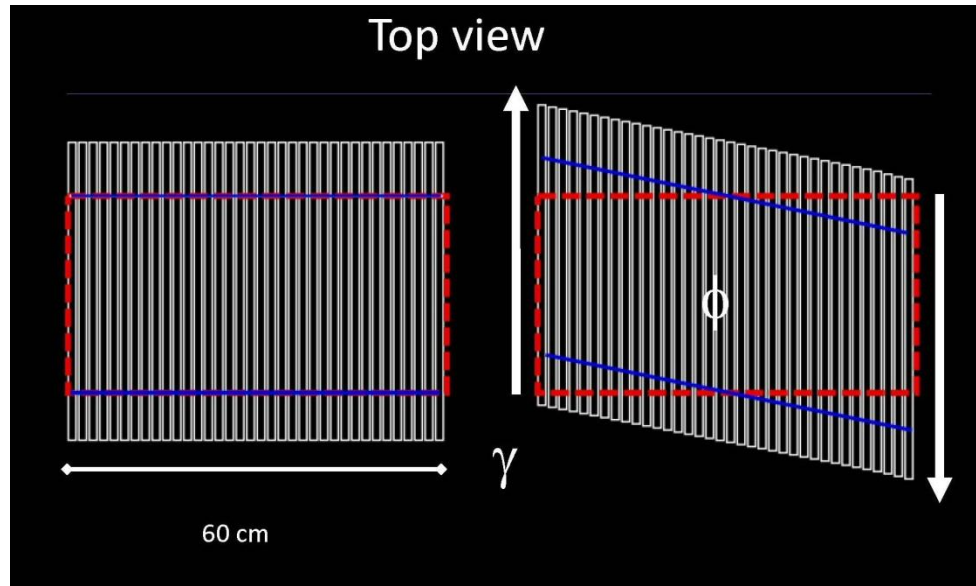


Dynamics near shear jamming and the Edwards  
stress ensemble  
and a possible ‘Angorometer’

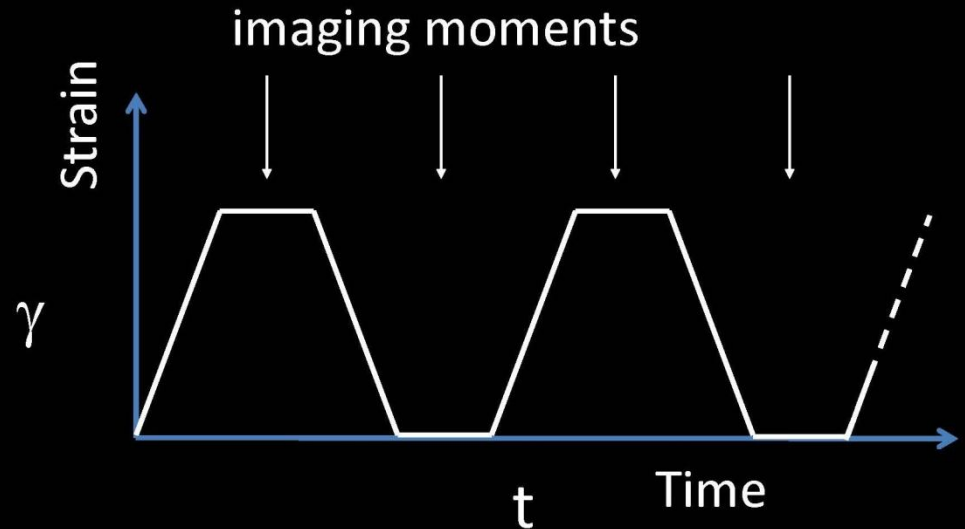
See Bi et al. for computation of Boltzmann factor



# Return to stress evolution with strain—generalized elasticity

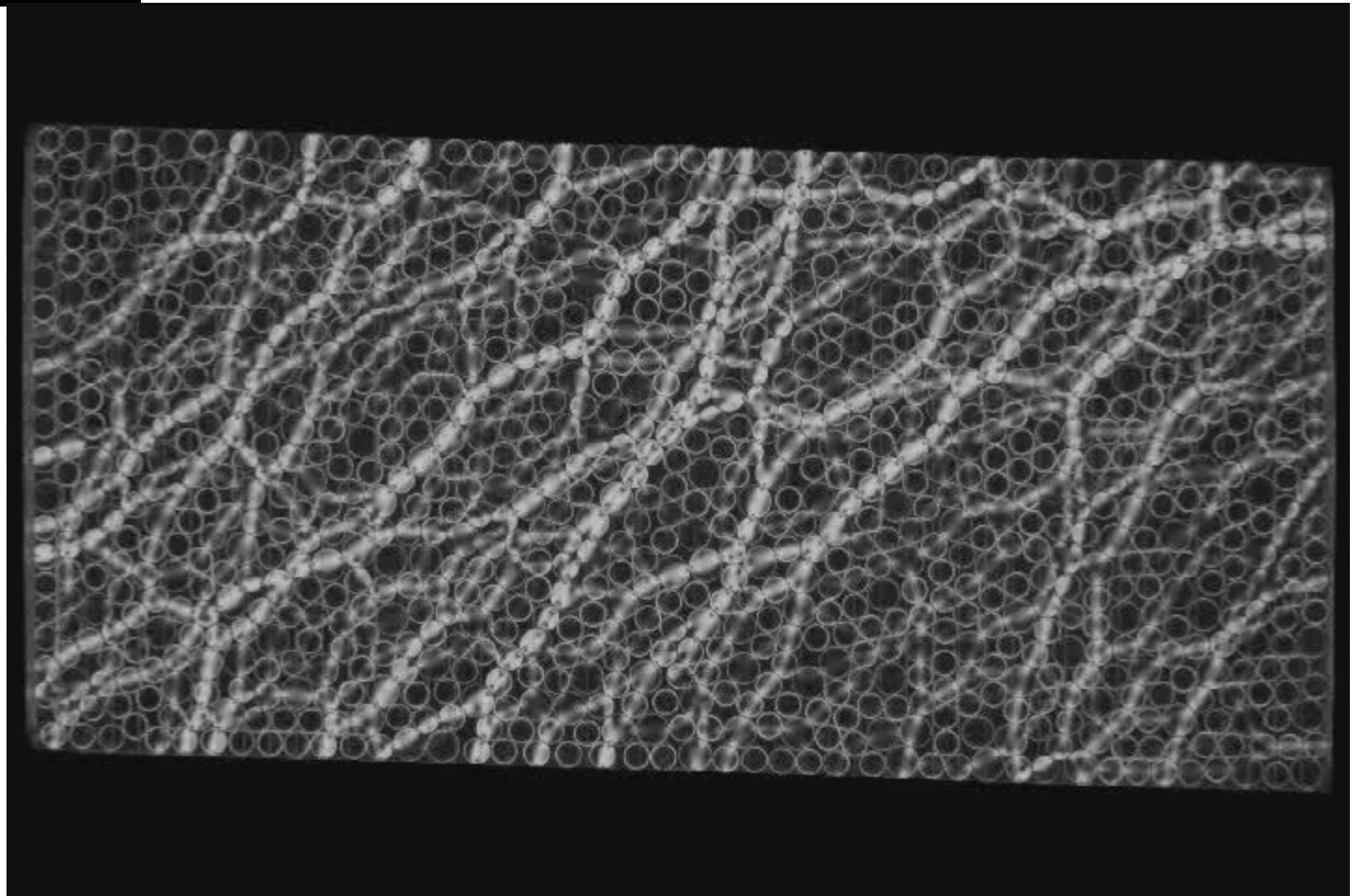
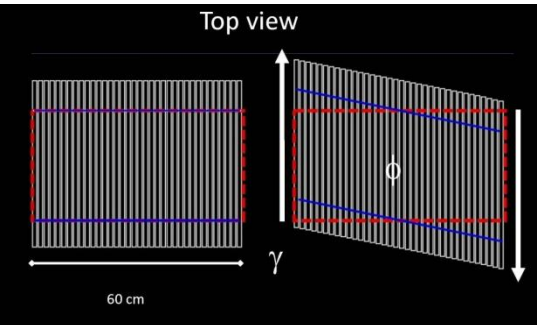


Augment unidirectional Shear with cyclic shear—  
--Samples states  
--Probes stress evolution  
And dynamics

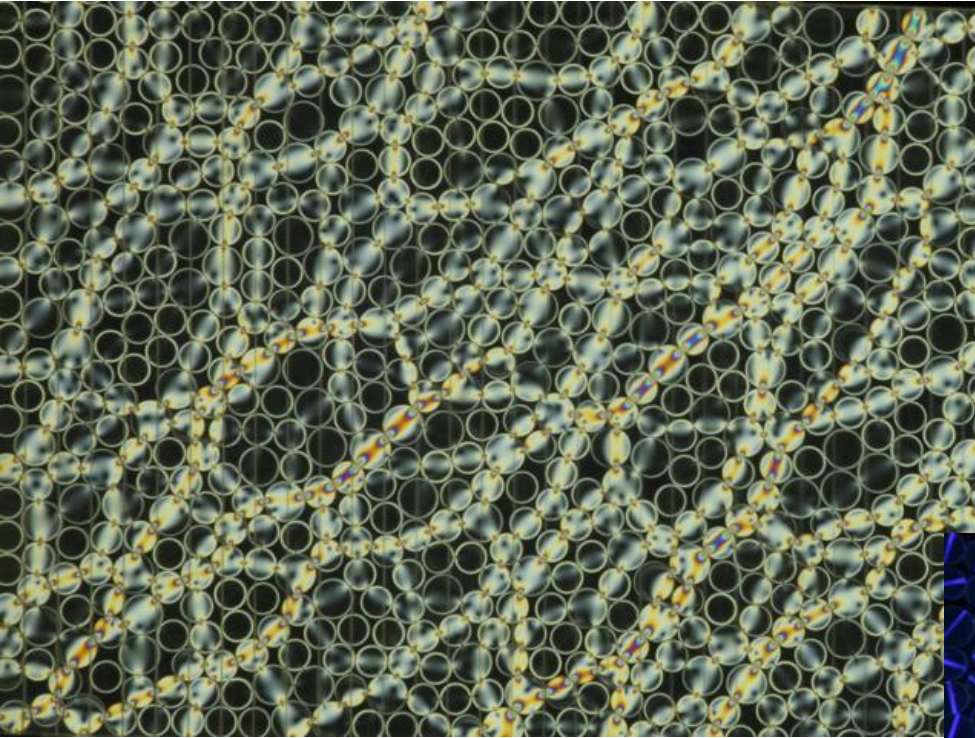


$\gamma \sim 0.5 - 10\%$      $t = 100-500$  cycles

# Dynamics near shear jamming



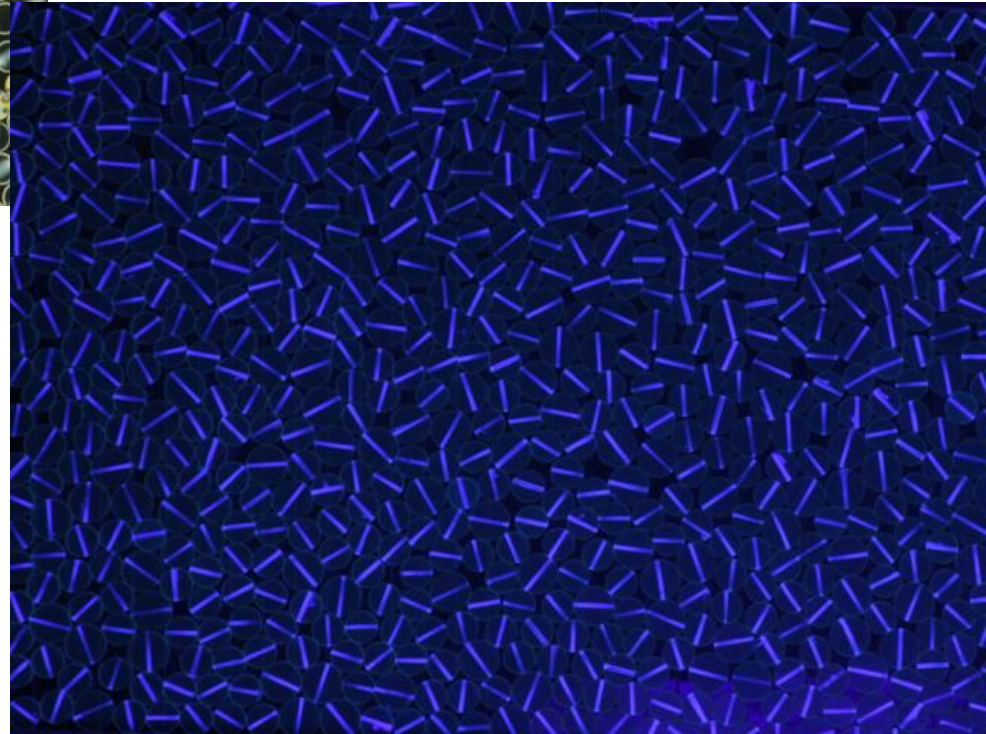
# Strobed images



← stresses fluctuate

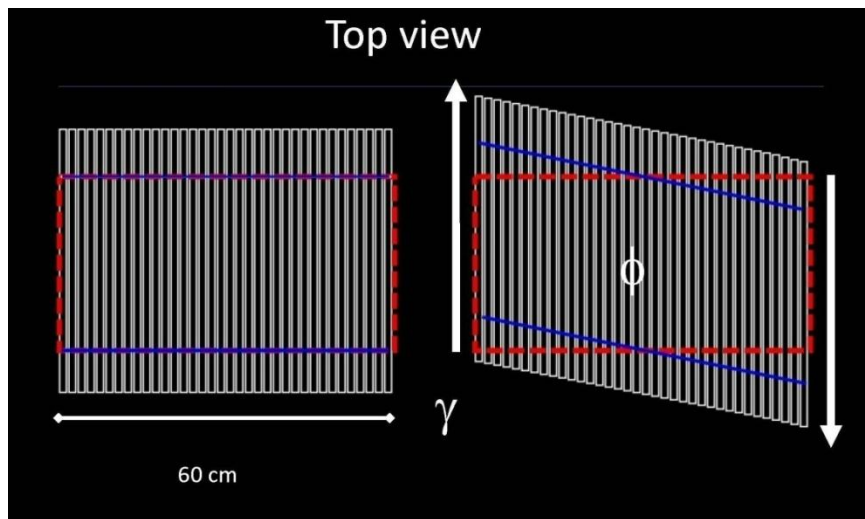
Stress, position, rotation—  
All evolve over many cycles

Positions are nearly frozen →



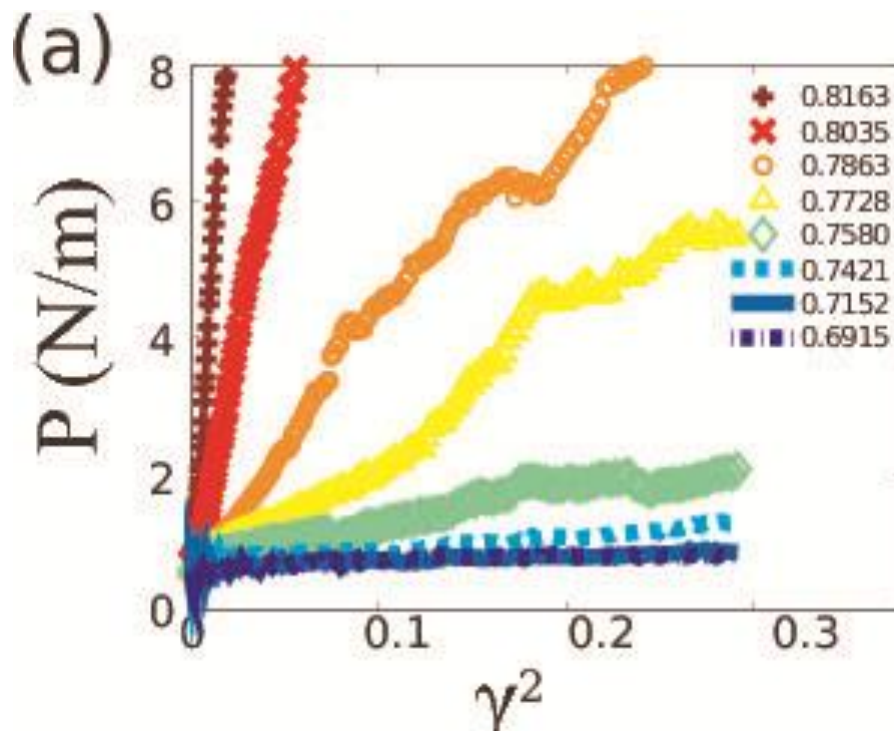


# First—stresses vs. unidirectional strain below $\phi_J$



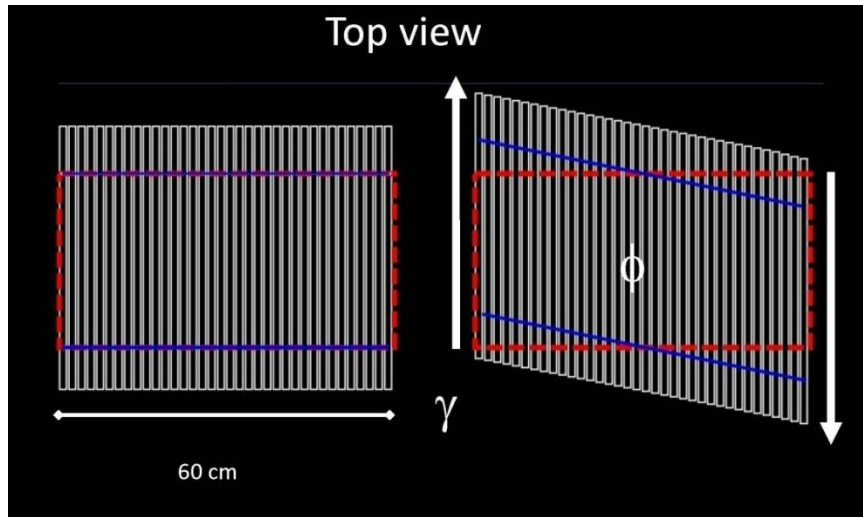
$$P \approx R\gamma^2$$

Define Reynolds coefficient,  $R$



Ren et al.  
PRL 110, 018302  
(2013)

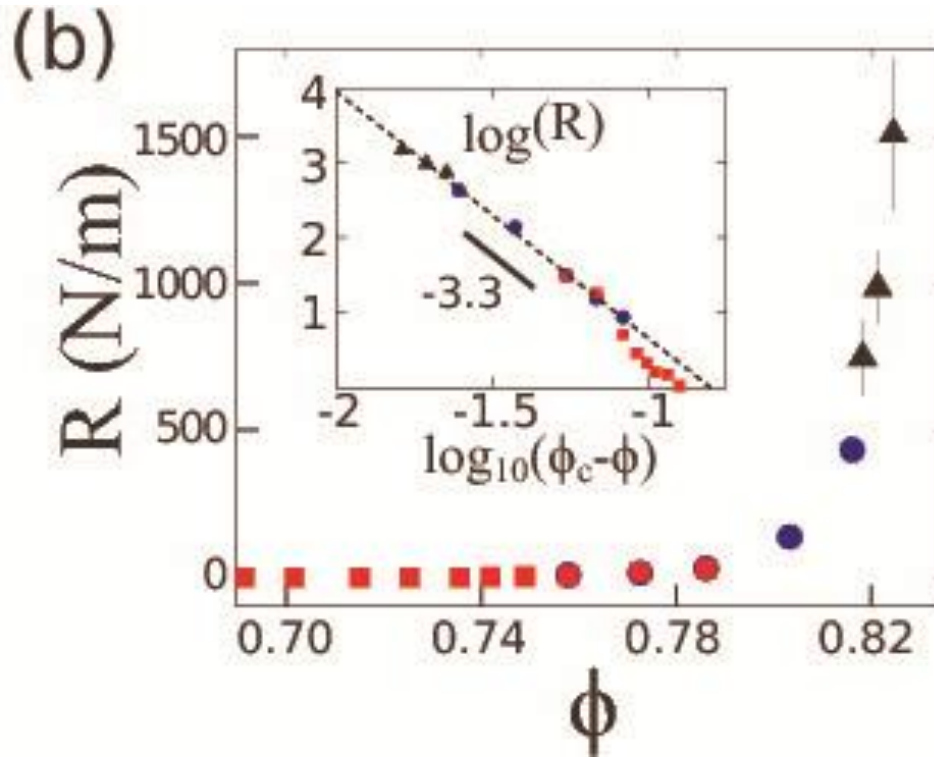
# Shear jamming dynamics below $\phi_J$



Define Reynolds coefficient,  $R$

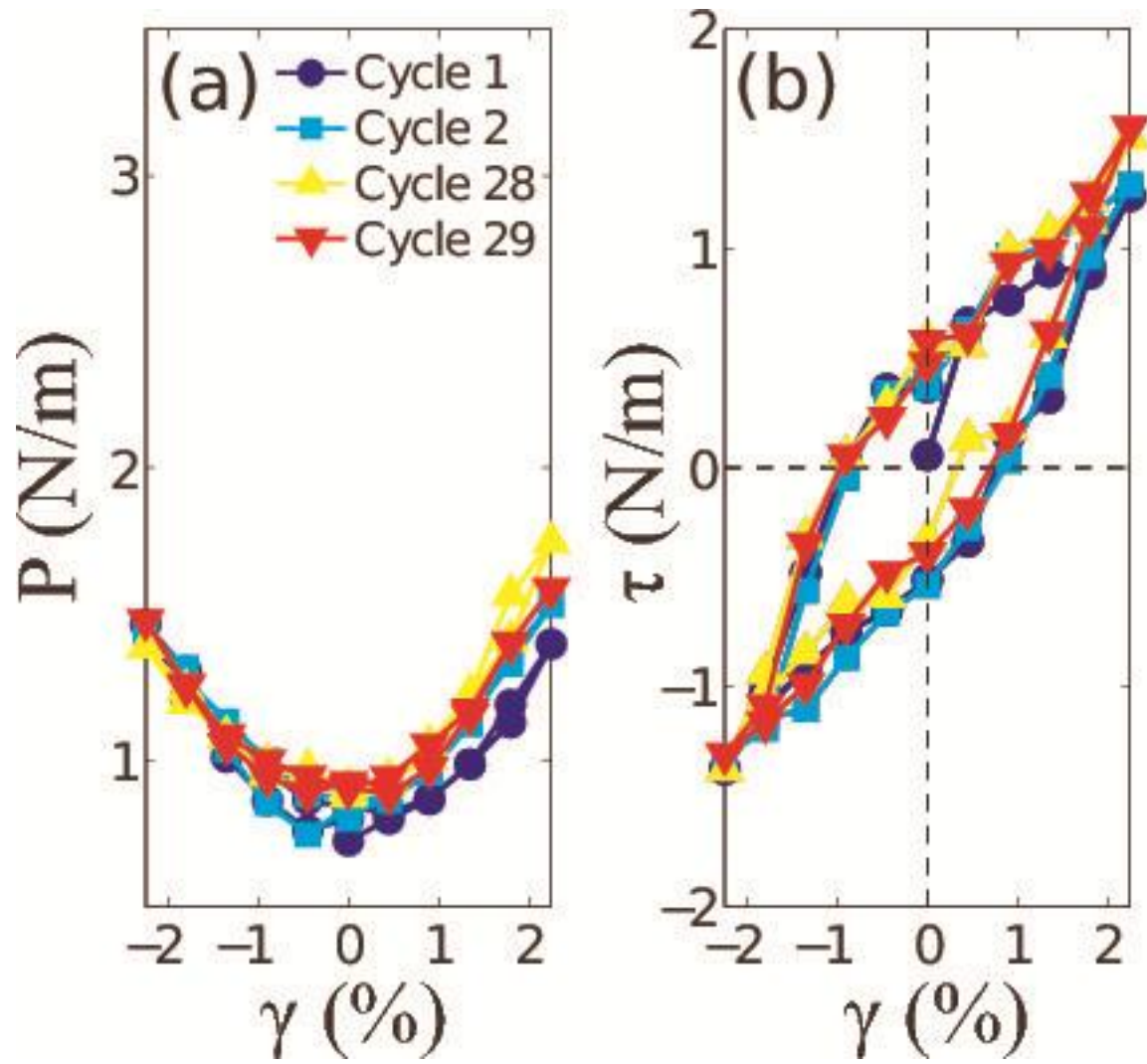
$$P \approx R\gamma^2$$

$$R \sim (\phi_J - \phi)^3$$

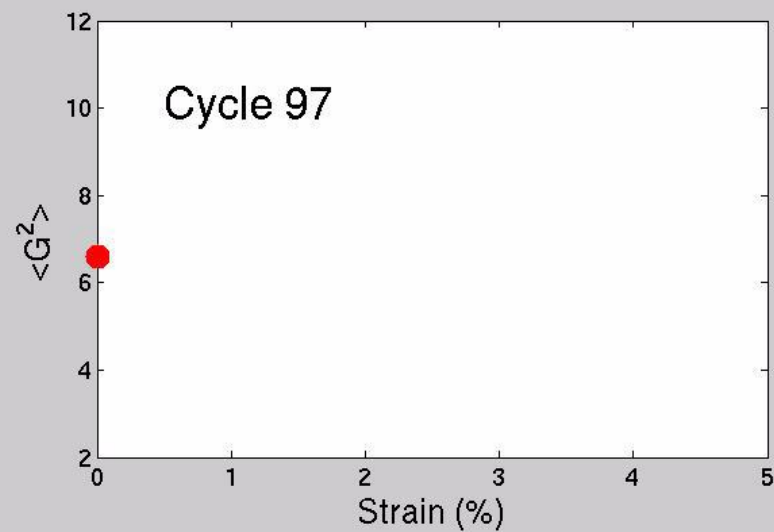
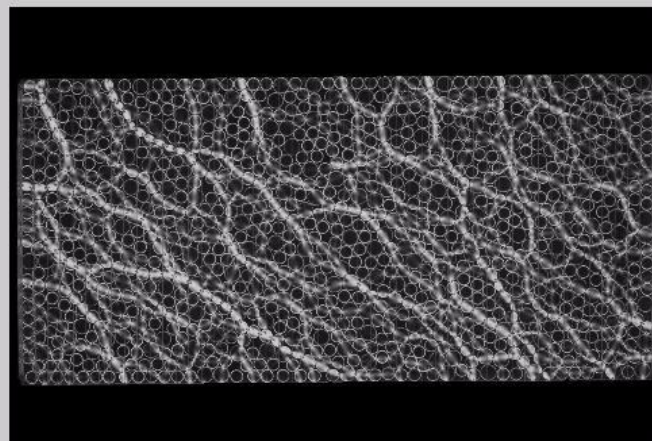
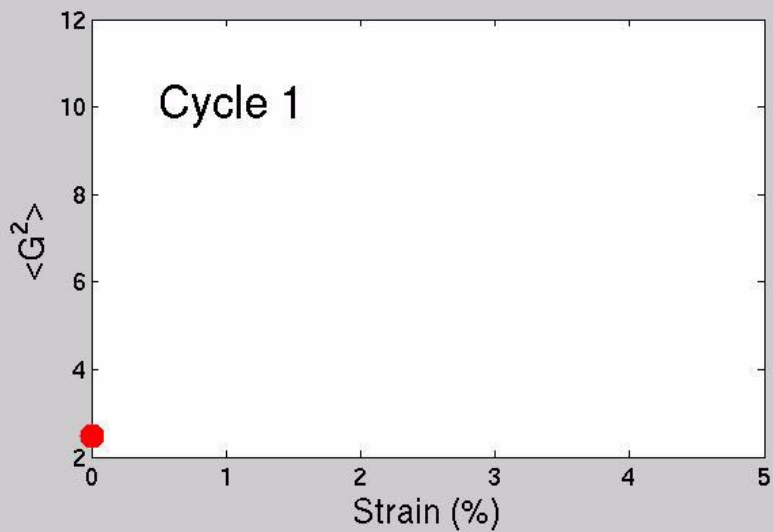
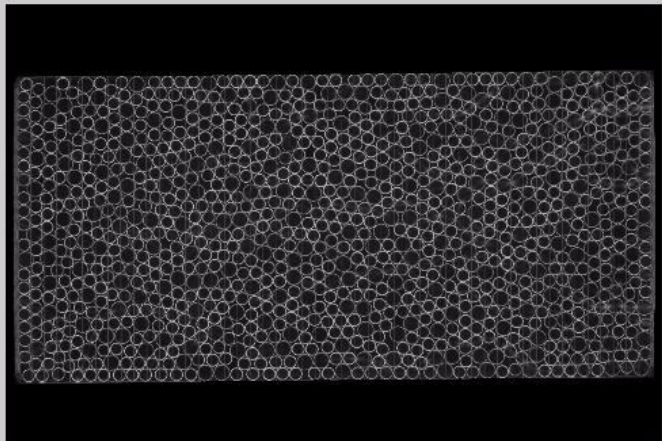




Apply symmetric cyclic shear—rapid relaxation to  
limit cycle

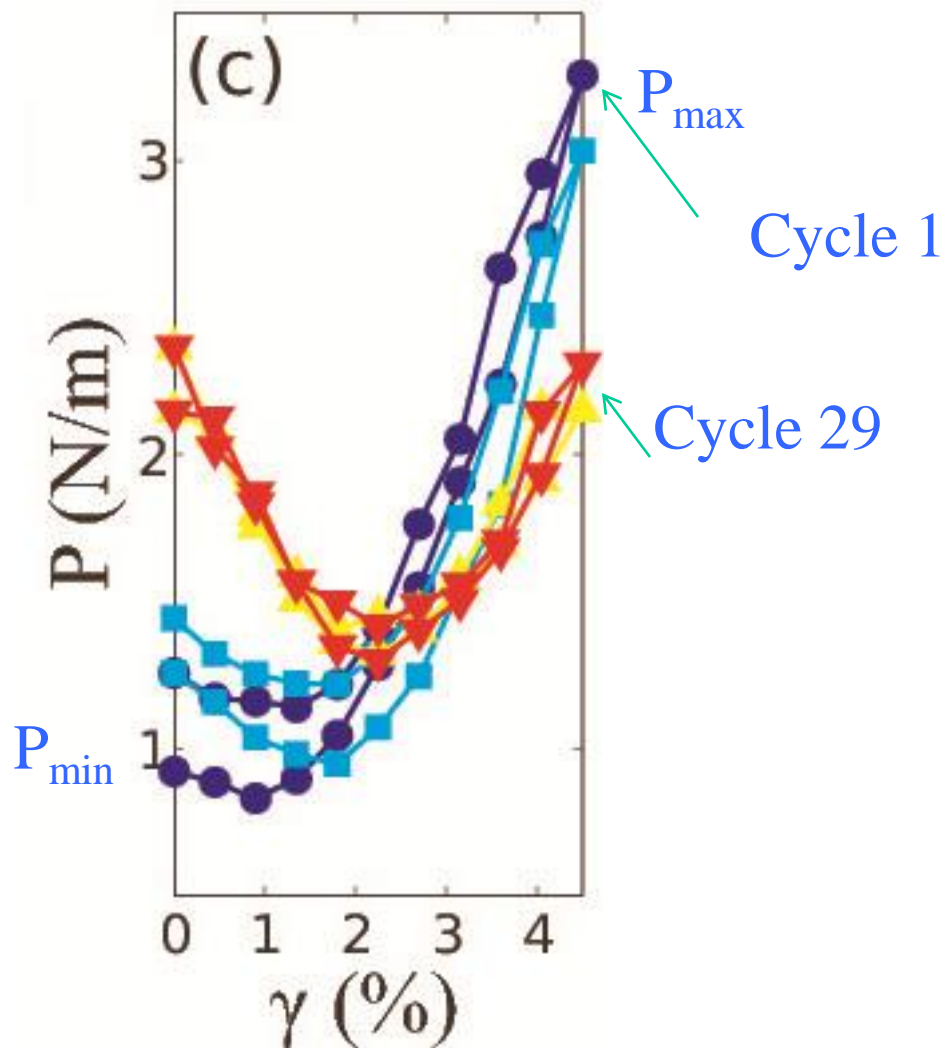


# Apply asymmetric cyclic shear: note slow relaxation



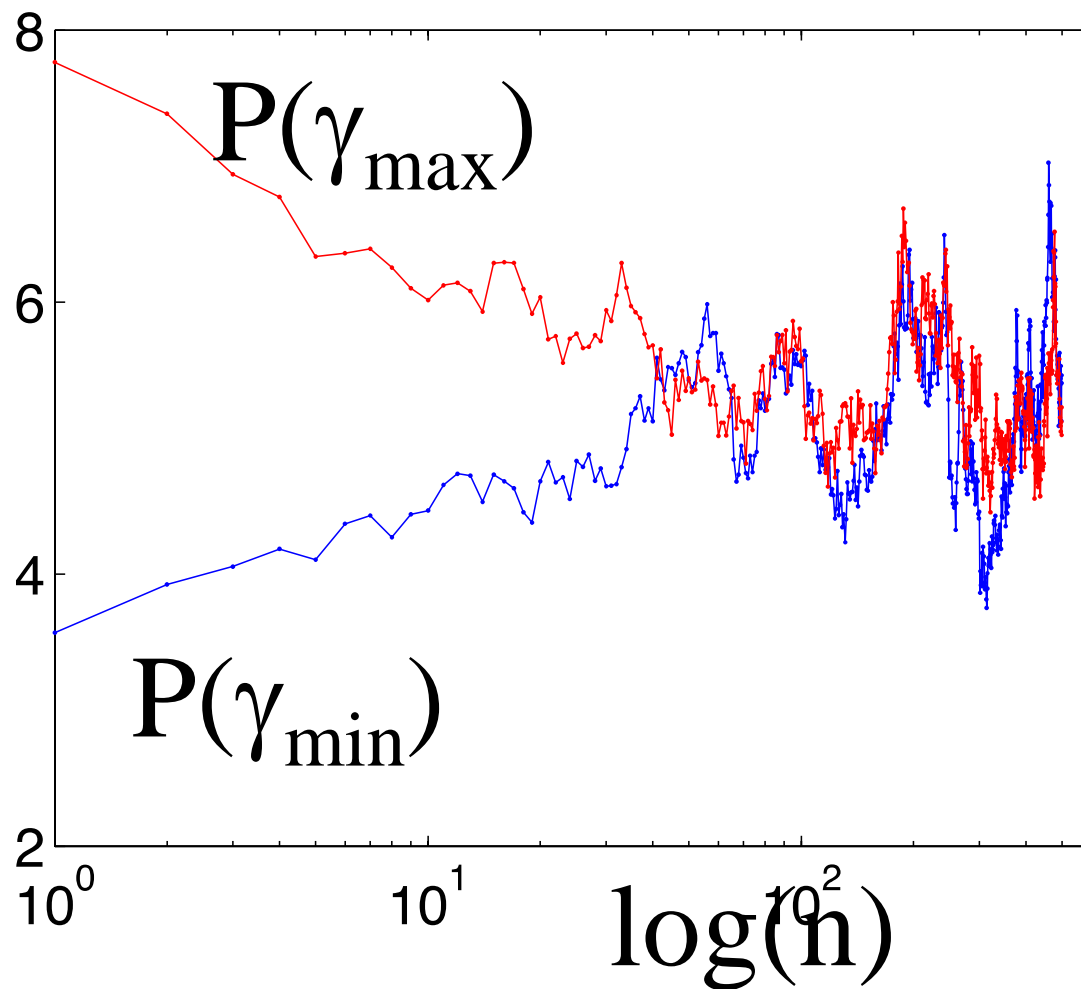
# Apply asymmetric cyclic shear: note slow relaxation

$$\Delta P = P_{\max} - P_{\min}$$



# Apply asymmetric cyclic shear: note slow relaxation

$$\Delta P = P_{\max} - P_{\min}$$

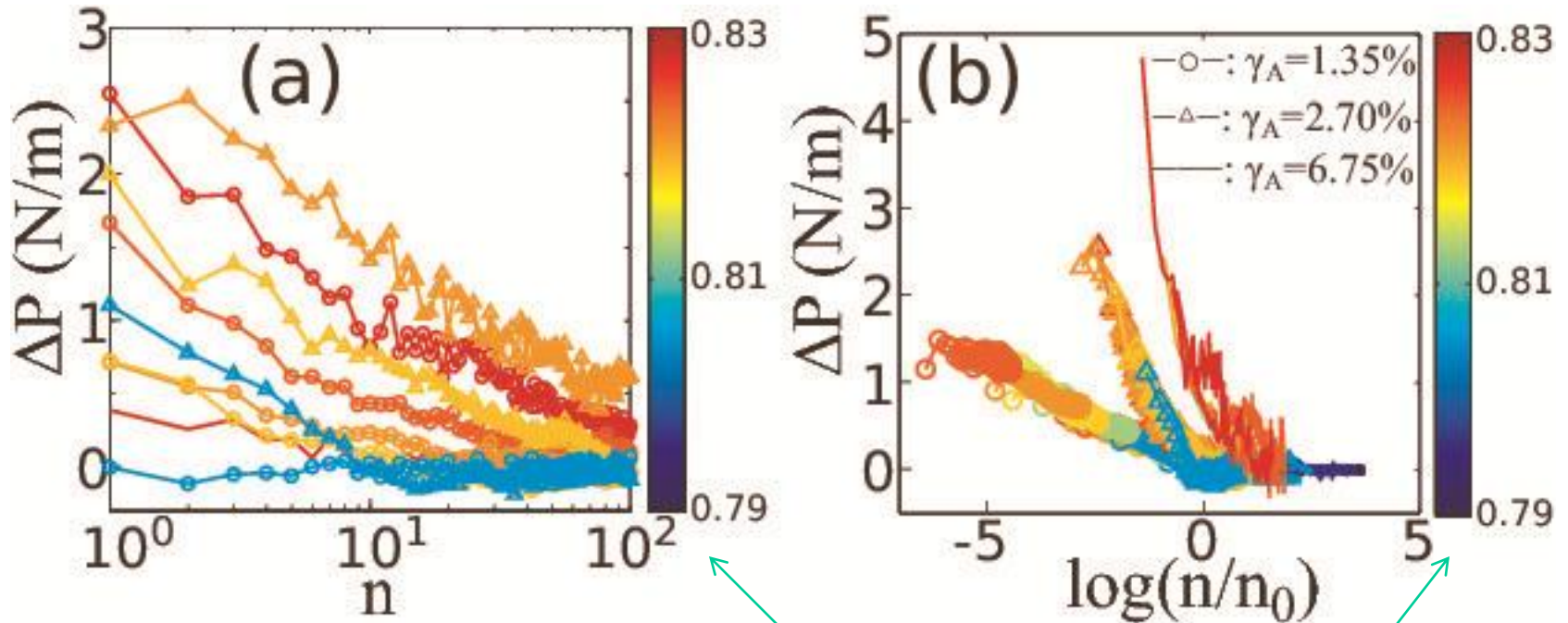




# Asymmetric shear:

1) log-relaxation:

2) simple  $\phi$  and  $\gamma$  dependence

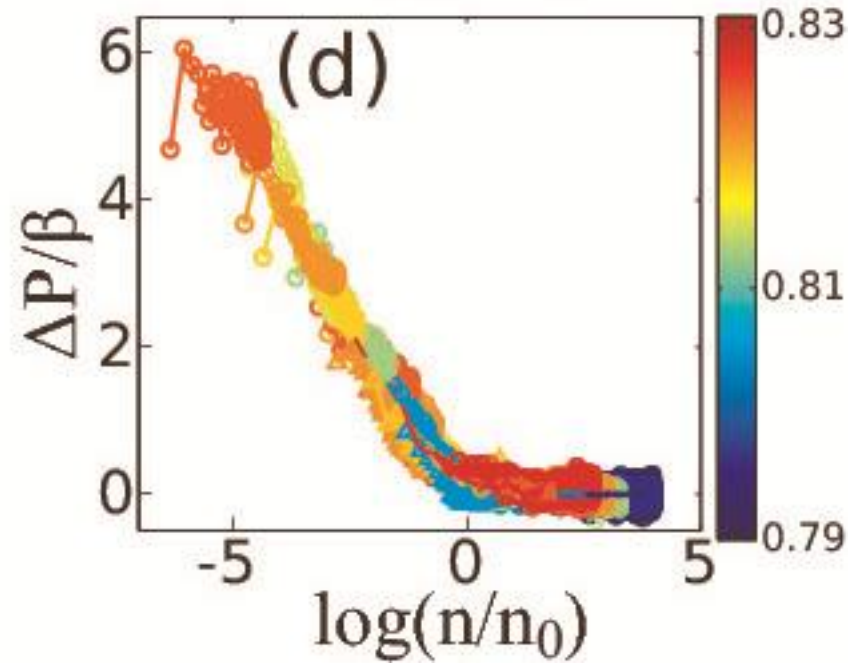
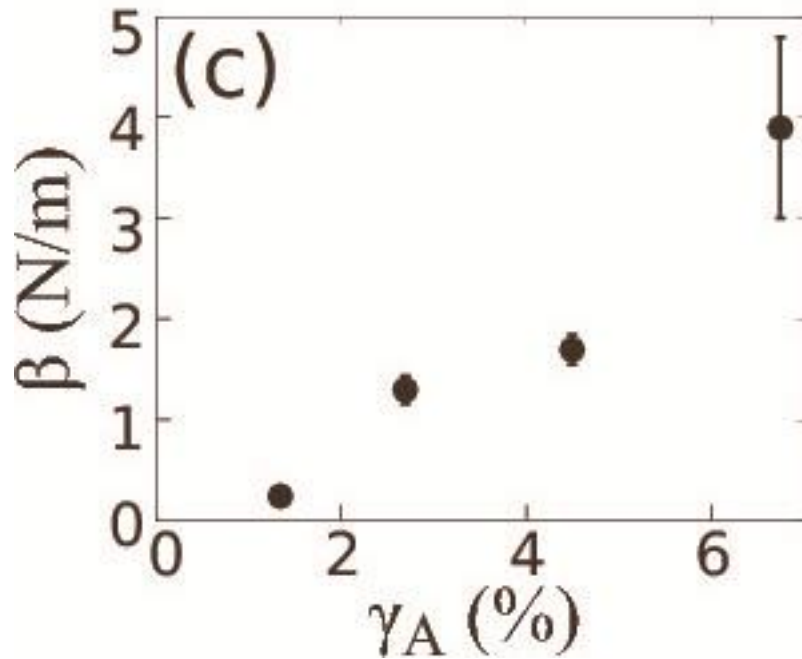


$\Delta P = -\beta \ln(n/n_0)$

Colors encode density

Universal relaxation:  
consistent with activated process in a stress ensemble

$\beta$  is temperature-like—a candidate for  
a granular ‘thermometer’ for shear

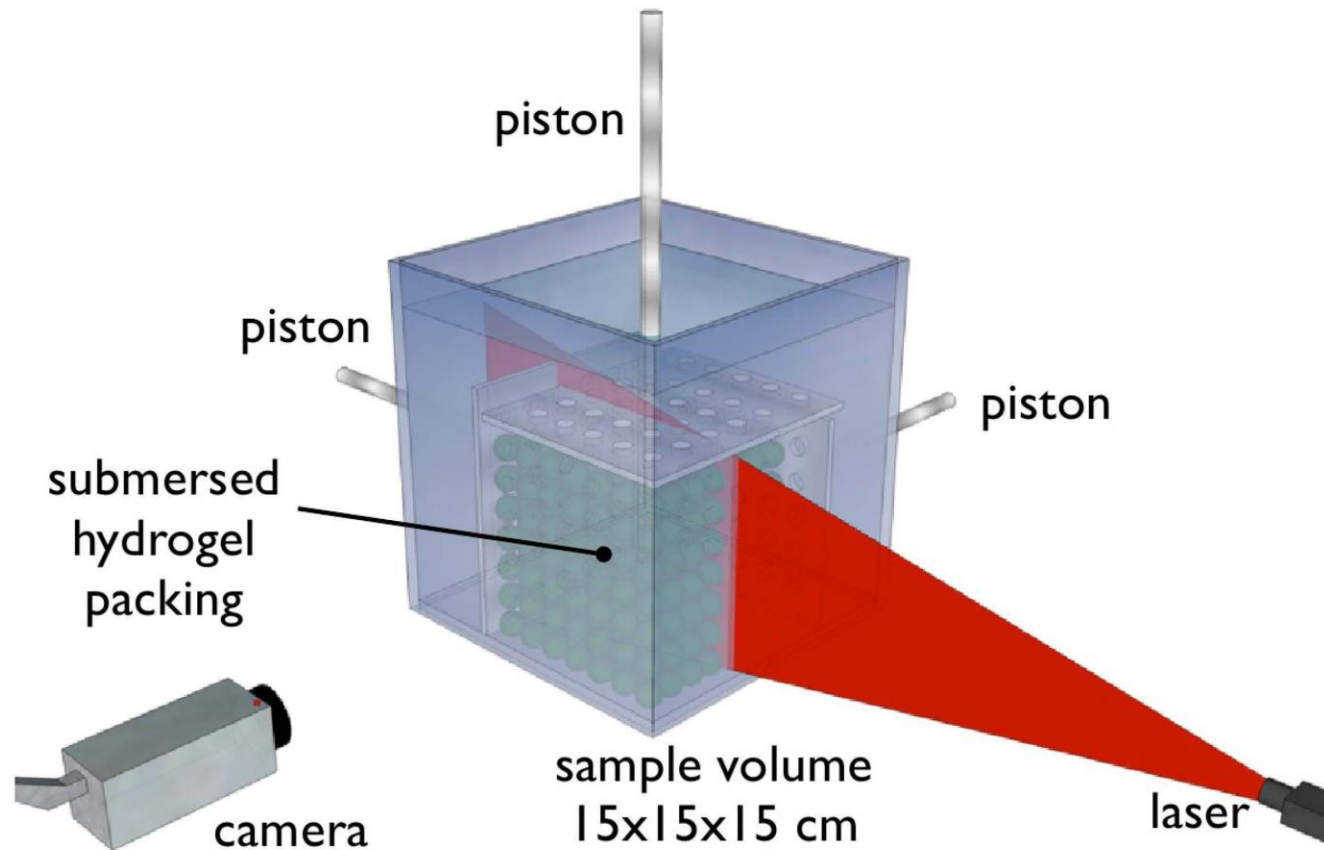


$$\Delta P = -\beta \ln(n/n_0)$$

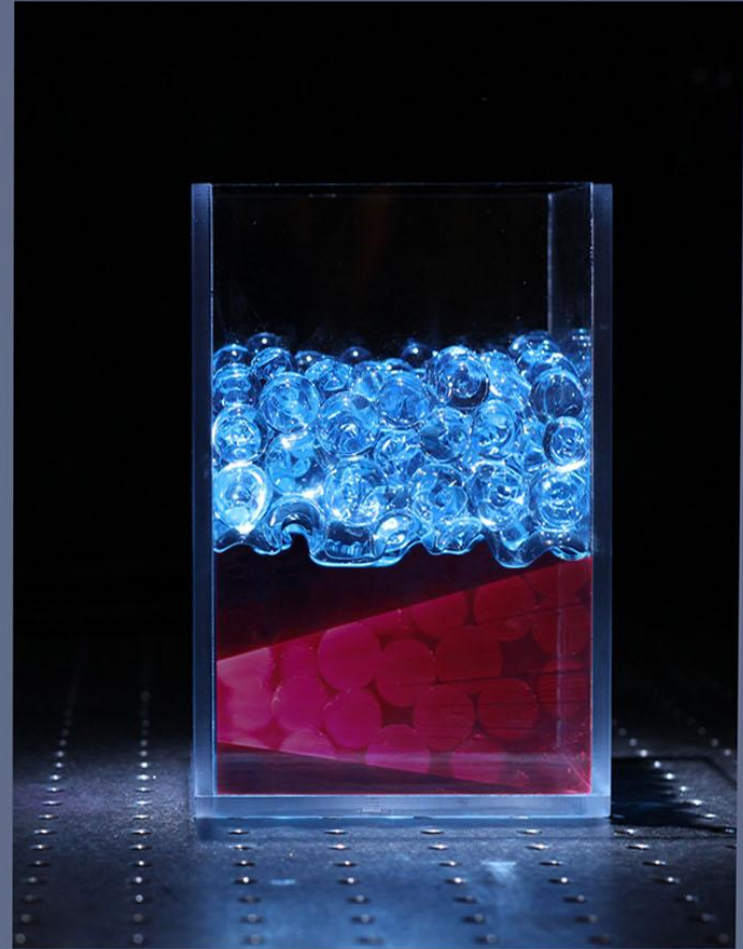
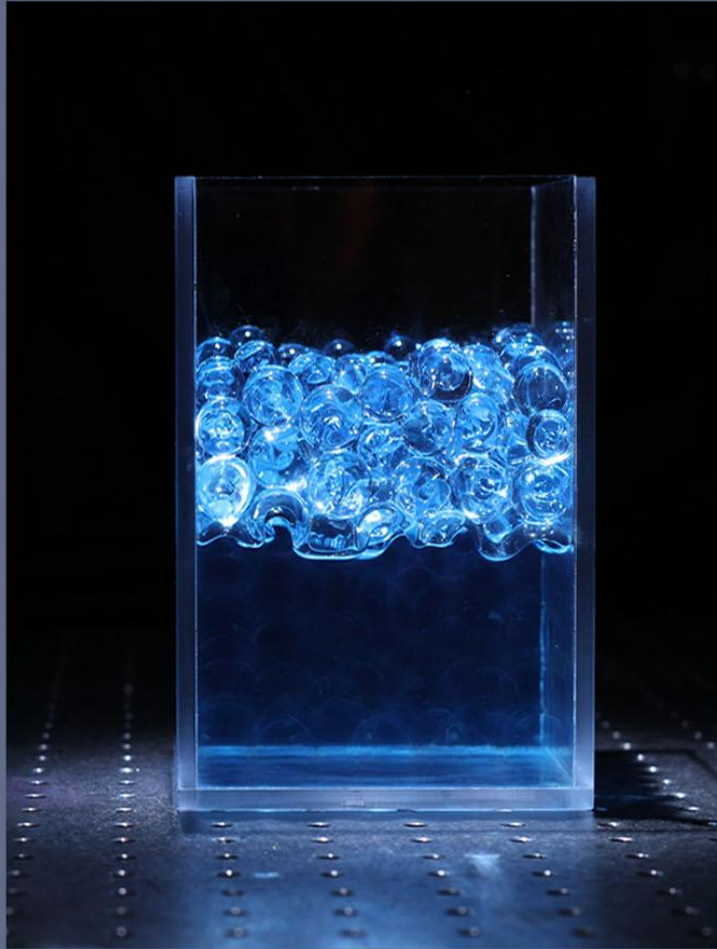
$$n/n_0 = \exp(-\Delta P/\beta)$$

# 3D

## laser scanning experiments—simple principle

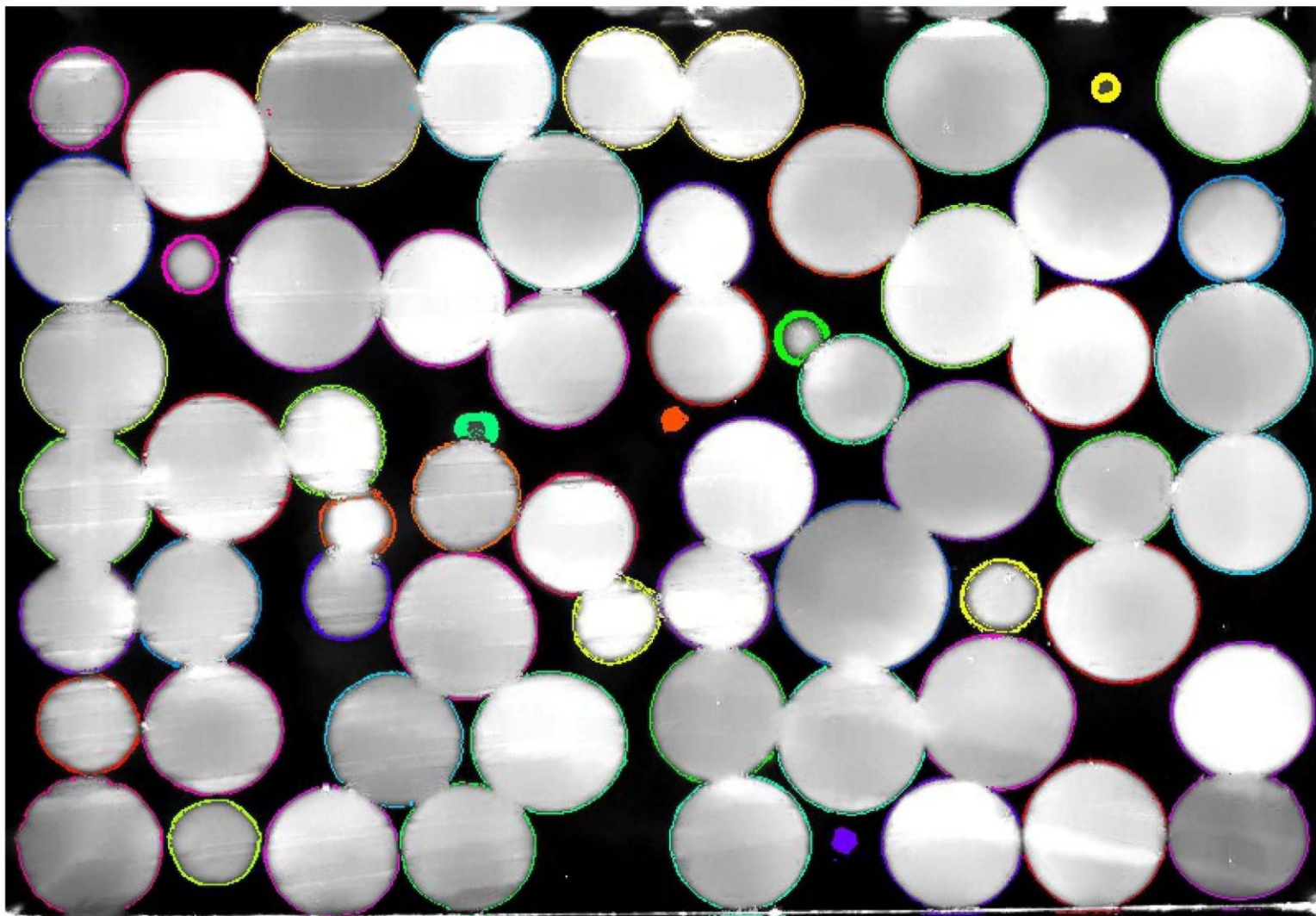


Index match surrounding fluid-particles  
add fluorescent dye to particles (hydrogels)





# A typical slice image



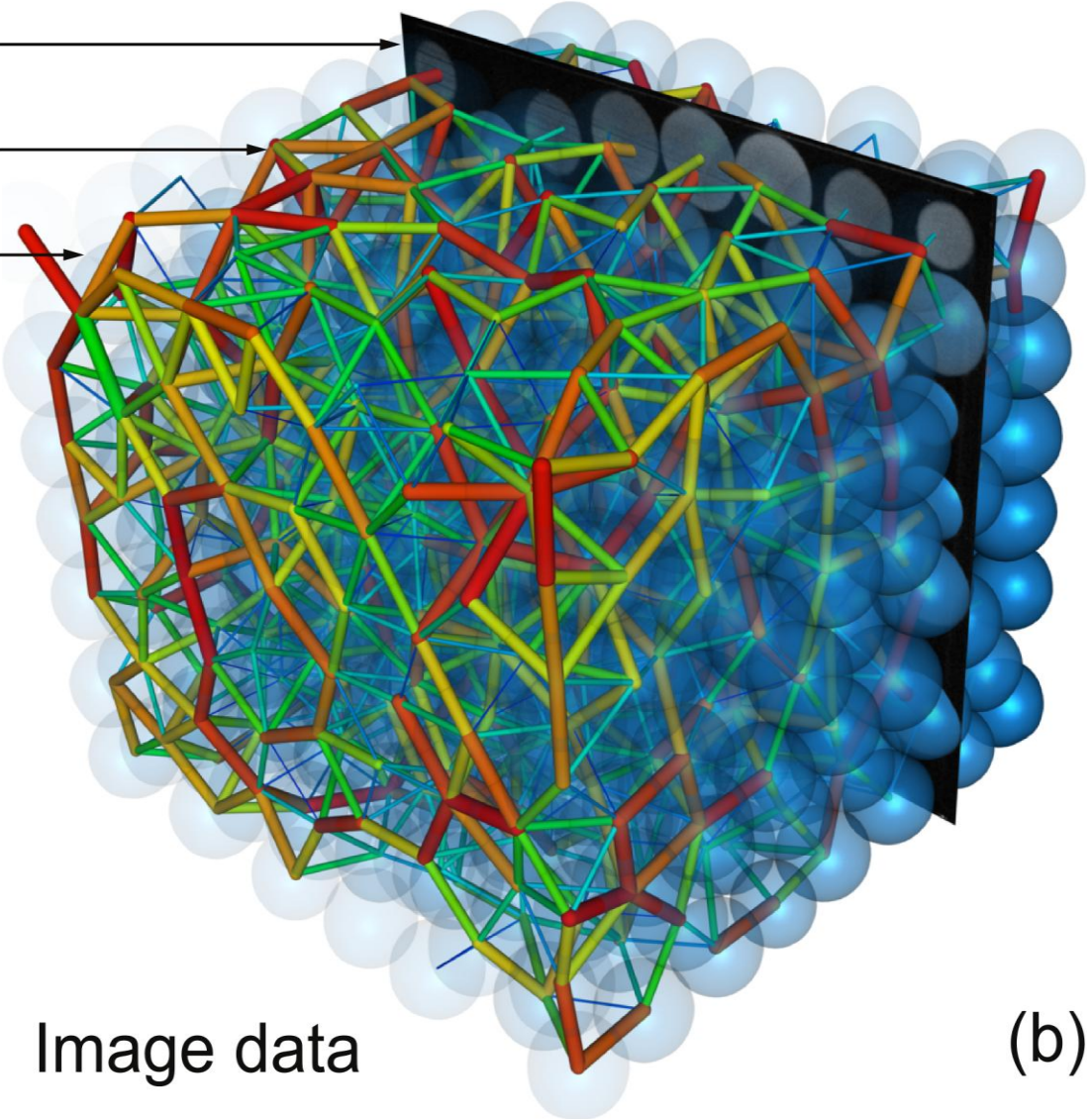


# Reconstruct particle surfaces $\rightarrow$ contact forces

Fluorescence image  $\rightarrow$

Contact forces  $\rightarrow$

Grain surface  $\rightarrow$



Setup

(a)

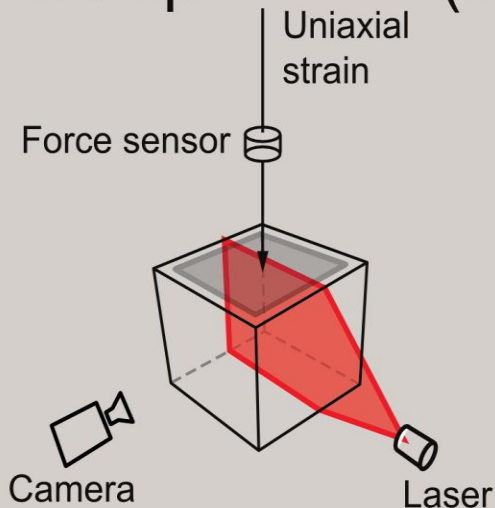
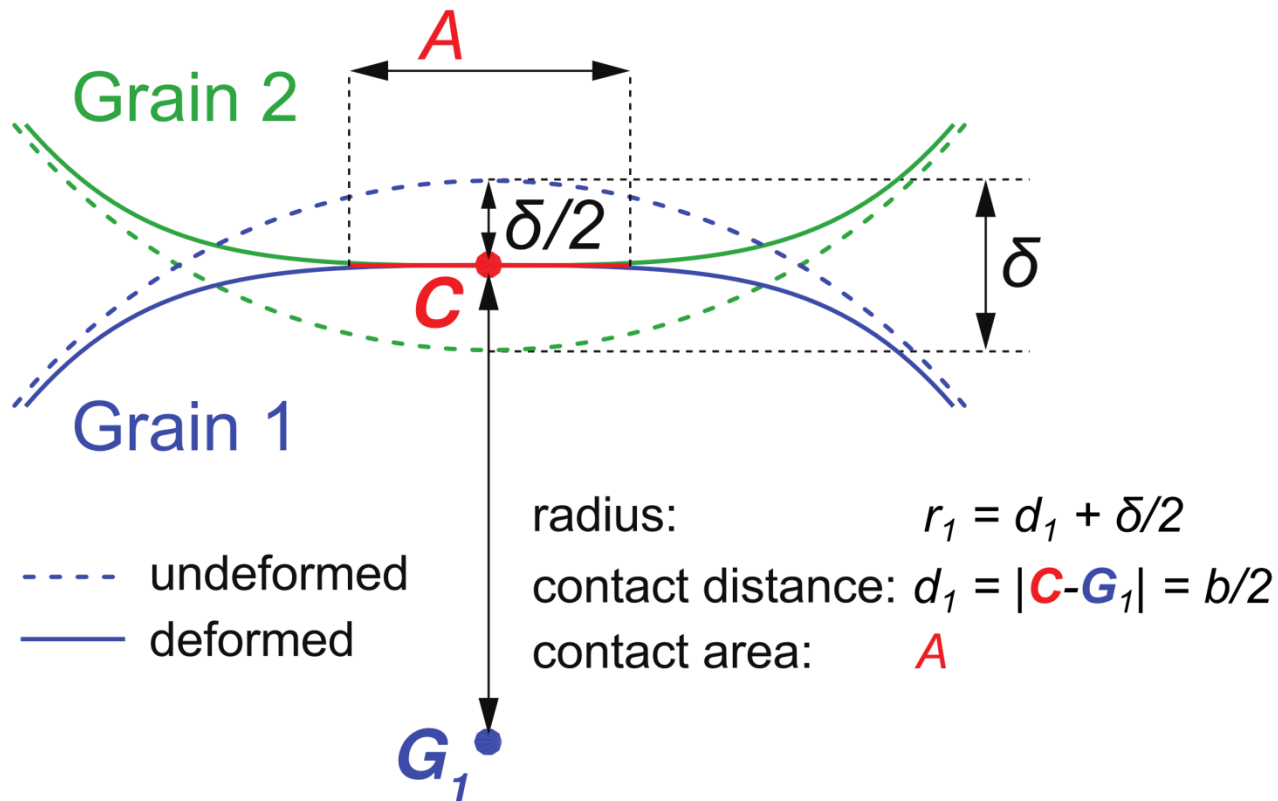


Image data

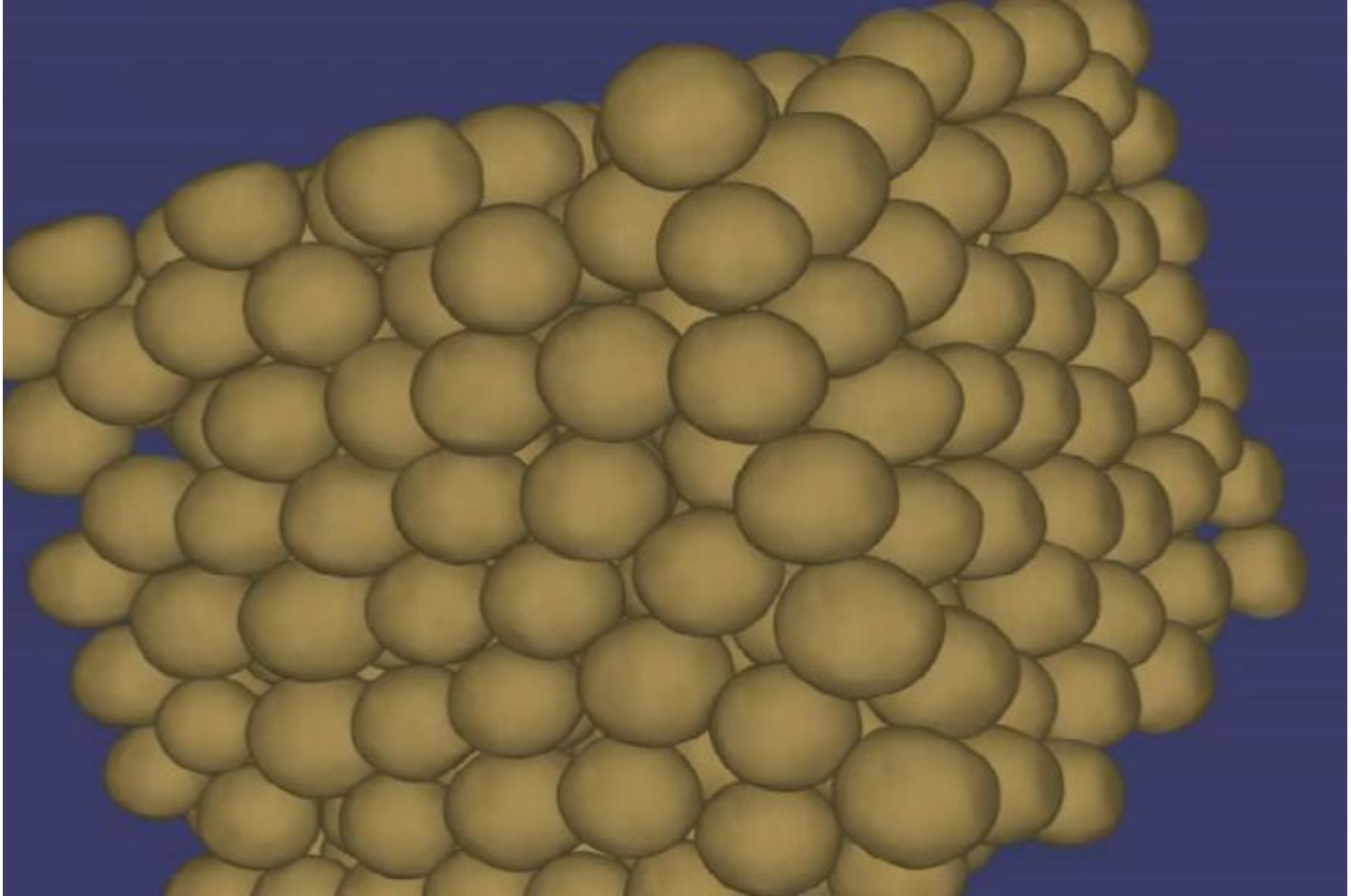
(b)

‘Flats’ at contacts  $\rightarrow$  deformation,  $\delta$

Hertz contact force law:  $\delta^{3/2}$

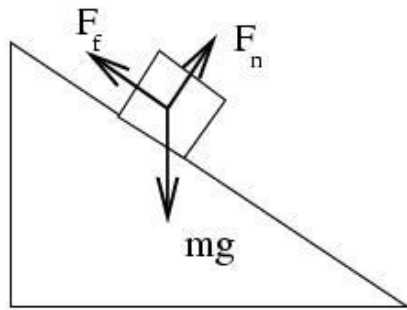


A typical slice reconstruction (video—remove particles with weaker forces)



# What do we mean by granular friction?

A Friction Analogue: Block on a Plane



At balance:

$$F_n = mg \cos \theta$$

$$F_f = mg \sin \theta$$

At failure (slipping):  $F_f = \mu F_n$

$$\tan \theta = \mu$$

## ESSAI

*Sur une application des règles de Maximis & Minimis à quelques Problèmes de Statique, relatifs à l'Architecture.*

Par M. COULOMB, Ingénieur du Roi.

### INTRODUCTION.

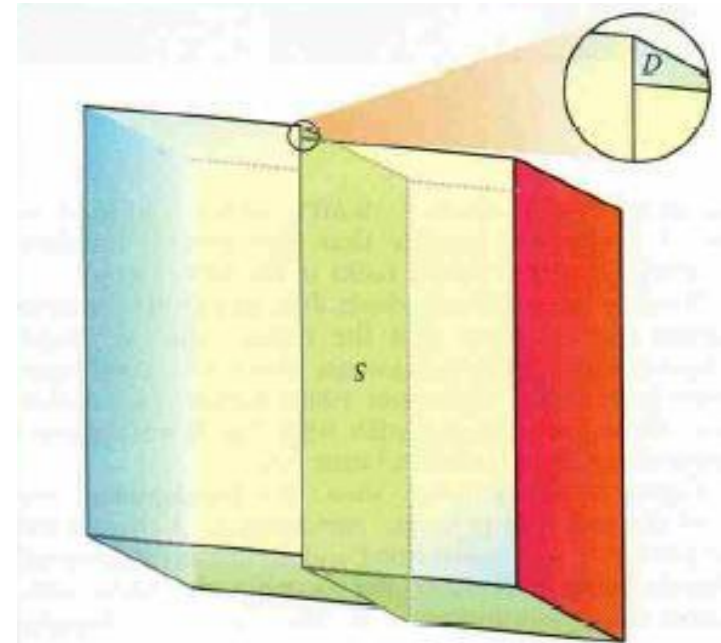
CE Mémoire est destiné à déterminer, autant que le mélange du Calcul & de la Physique peuvent le permettre, l'influence du frottement & de la cohésion, dans quelques problèmes de Statique. Voici une légère analyse des différens objets qu'il contient.

Après quelques observations préliminaires sur la cohésion, & quelques expériences sur le même objet, l'on détermine la force d'un pilier de maçonnerie; le poids qu'il peut porter, pressé suivant sa longueur; l'angle sous lequel il doit se rompre. Comme ce problème n'exige que des considérations assez simples, qui servent à faire entendre toutes les autres parties de cet Essai, tâchons de développer les principes de sa solution.

Si l'on suppose un pilier de maçonnerie coupé par un plan incliné à l'horizon, en sorte que les deux parties de ce pilier soient unies dans cette section, par une cohésion donnée, tandis que tout le reste de la masse est parfaitement solide, ou lié par une adhérence infinie; qu'ensuite on charge ce pilier d'un poids: ce poids tendra à faire couler la partie supérieure du pilier sur le plan incliné, par lequel il touche la partie inférieure. Ainsi, dans le cas d'équilibre, la portion de la pesanteur, qui agit parallèlement à la section, sera exactement égale à la cohésion. Si l'on remarque actuellement, dans le cas de l'homogénéité, que l'adhérence du pilier est réellement égale



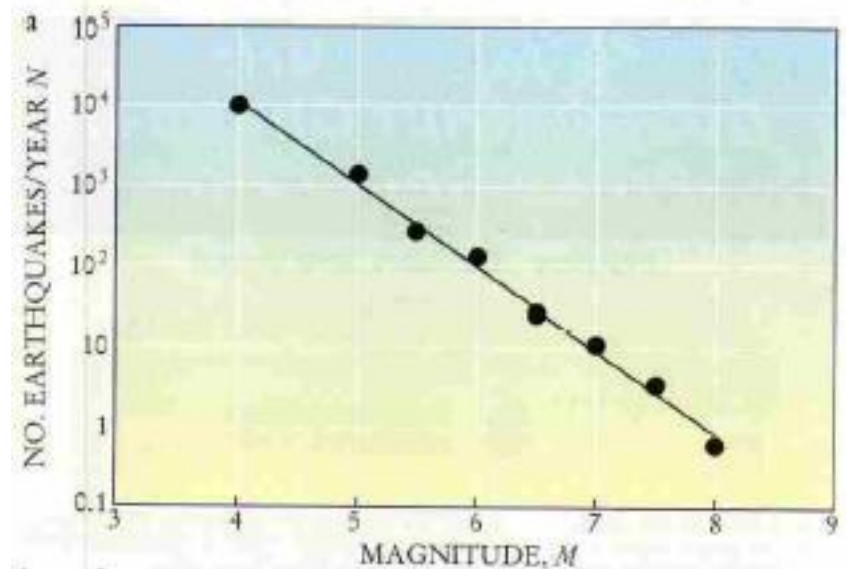
# Gutenberg-Richter relation



Earthquake events distribution:

$$\log N = a - bM$$

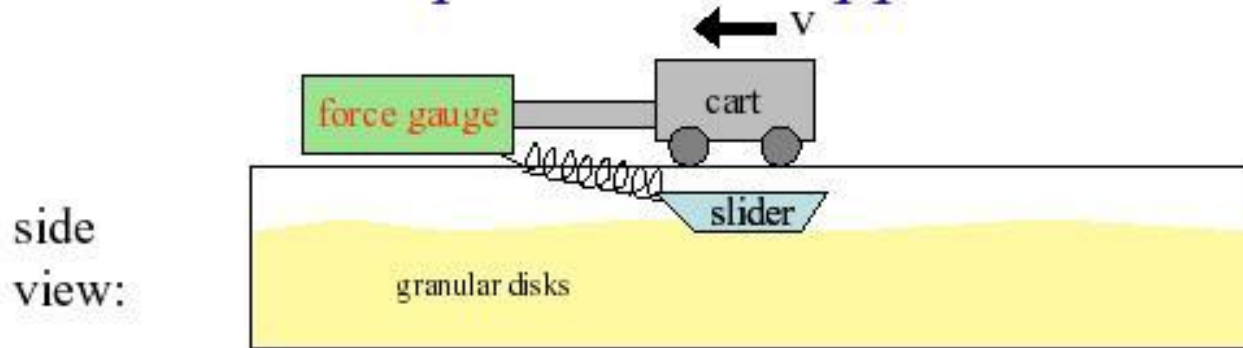
Therefore the seismic moment has a power law distribution





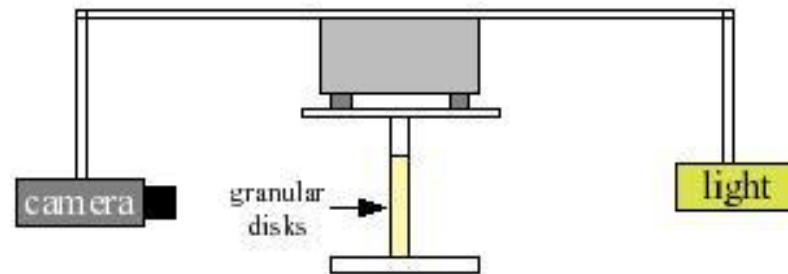
# Granular Rheology—a slider experiment (modeled after 3d expt of Nasuno et al.)

## Experimental Apparatus



- Cart and force gauge move at constant speed  $v$ .
- Slider exhibits stick-slip motion on granular bed.

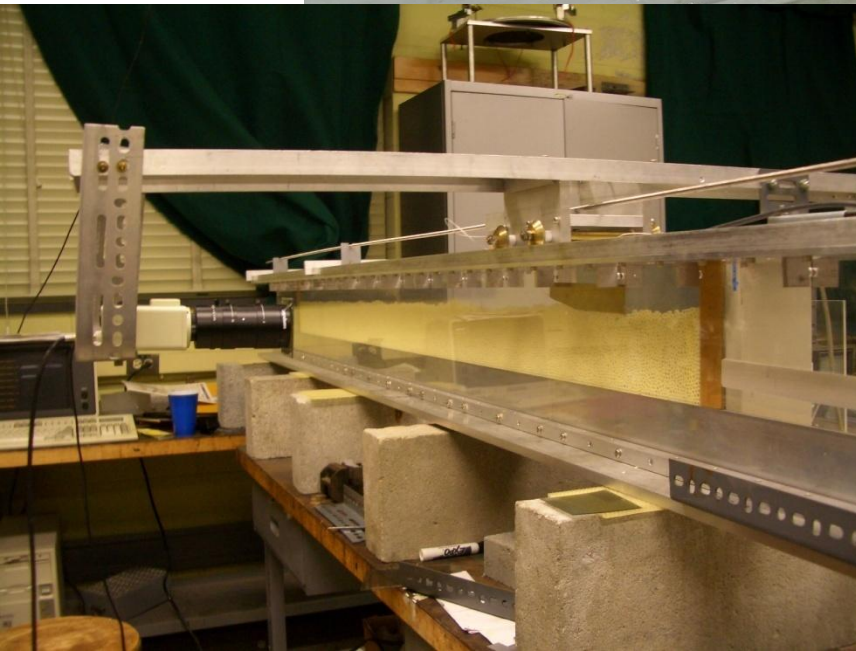
end view:



- Camera moves with the cart/slider.

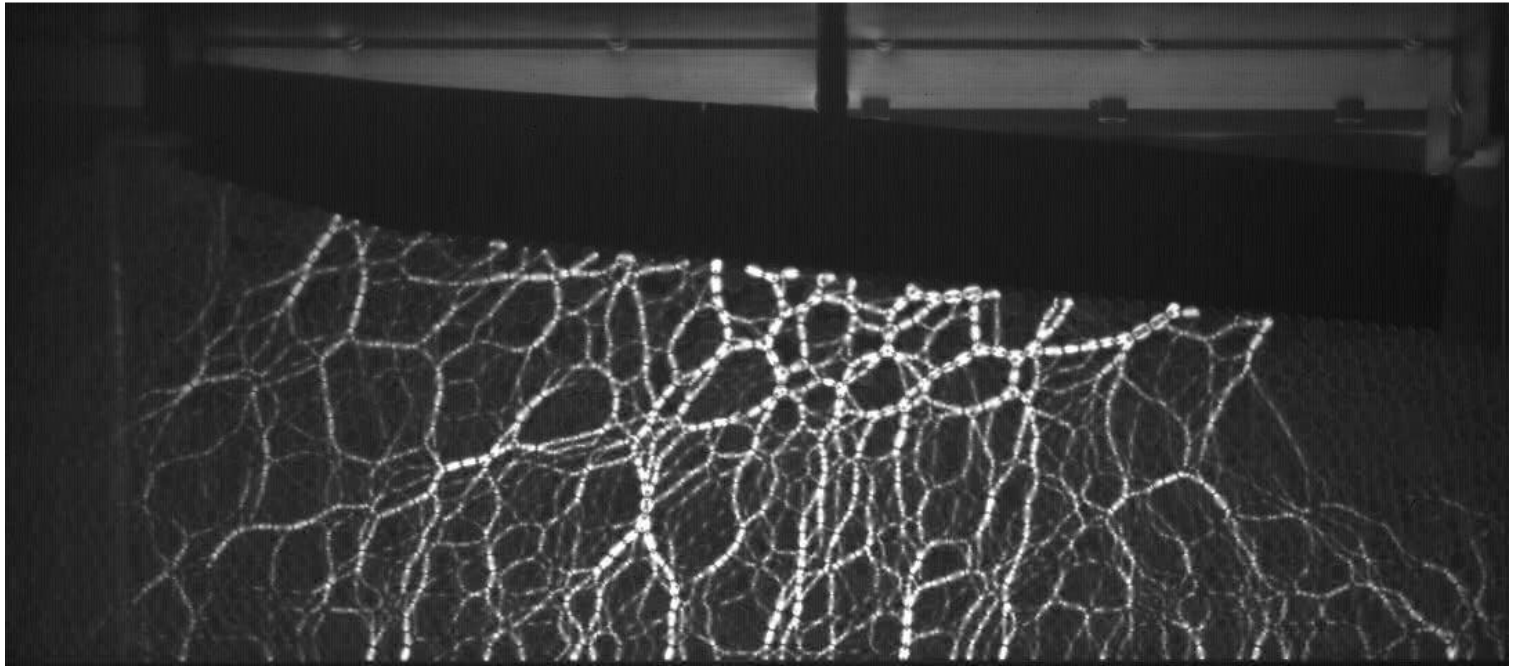
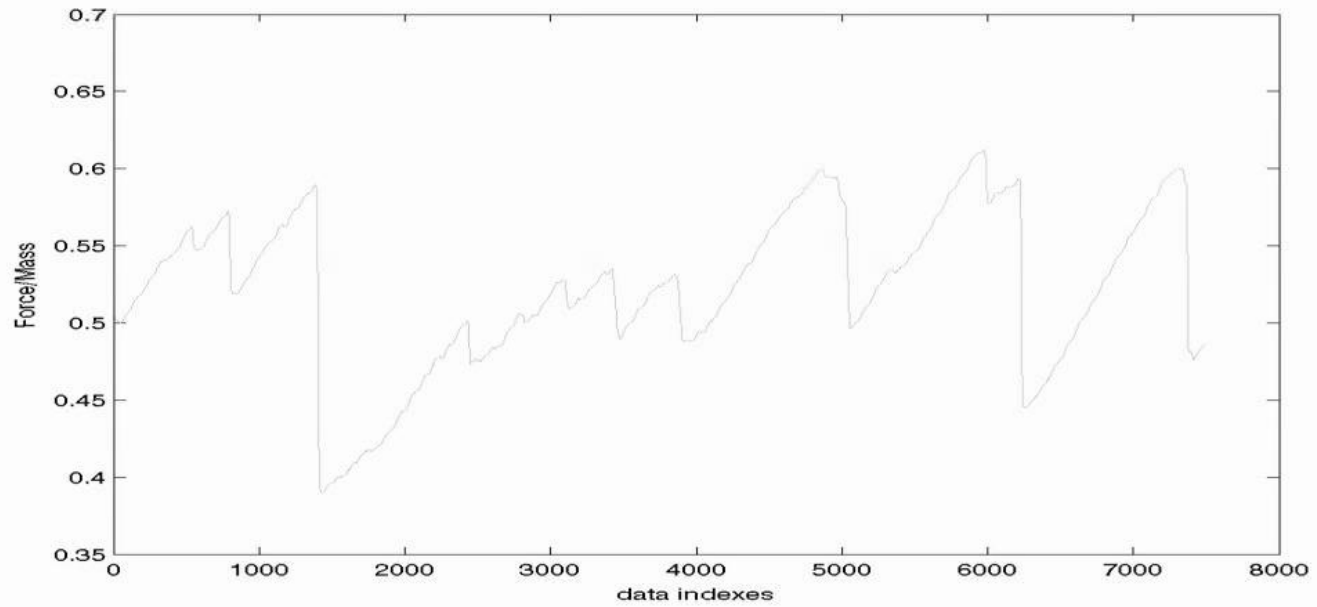
Granular bed =  $500 d \times 20 d$  deep,  $d = 0.41$  cm and  $0.51$  cm bidisperse photoelastic disks.  
Typical speeds =  $0.1-2 d/s$ . Slider length =  $30-40 d$ .  
Dragging force =  $0-100$  grams ( $0-1$  Newton s).

# Experimental apparatus



What is the relation between stick slip and granular force structure?

# Video of force evolution

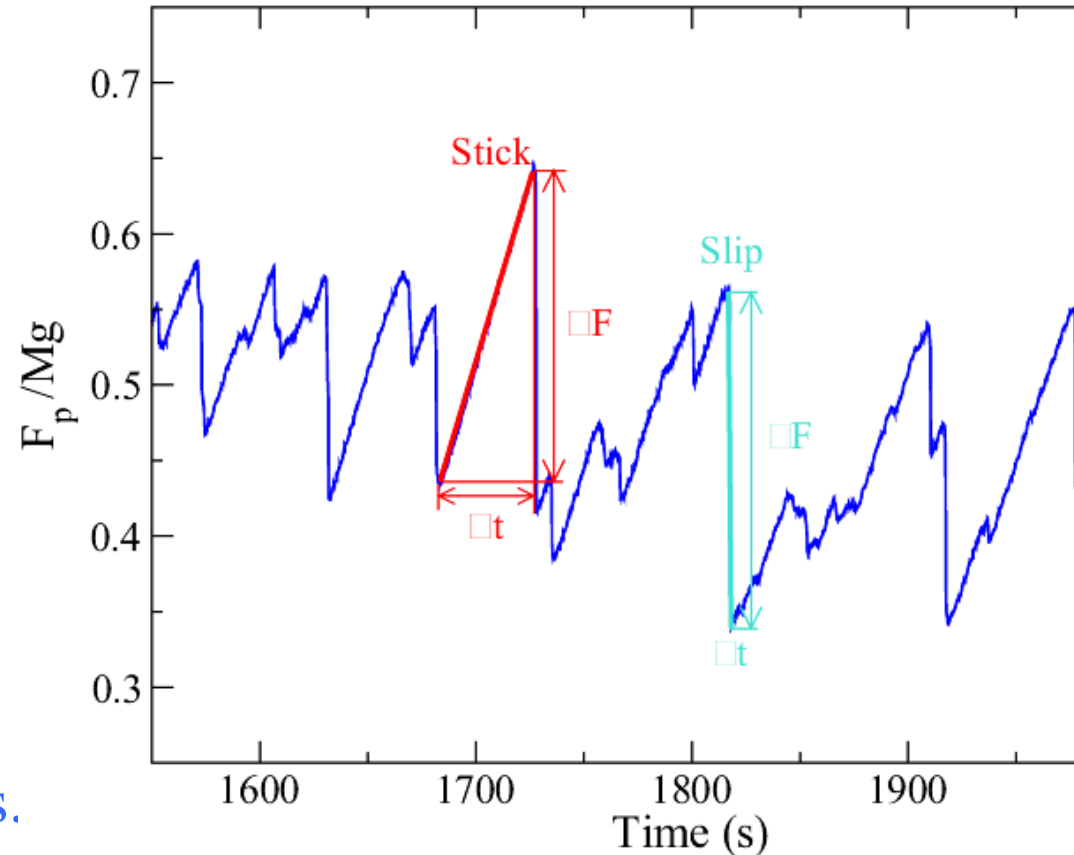




# Non-periodic Stick-slip motion

- Stick-slip motions in our 2D experiment are **non-periodic** and **irregular**
- Time duration, **initial pulling force** and **ending pulling force** all vary in a rather broad range
- Random effects associated with small number of contacts between the slider surface and the granular disks.

**Size of the slider  $\sim 30\text{-}40 d$**



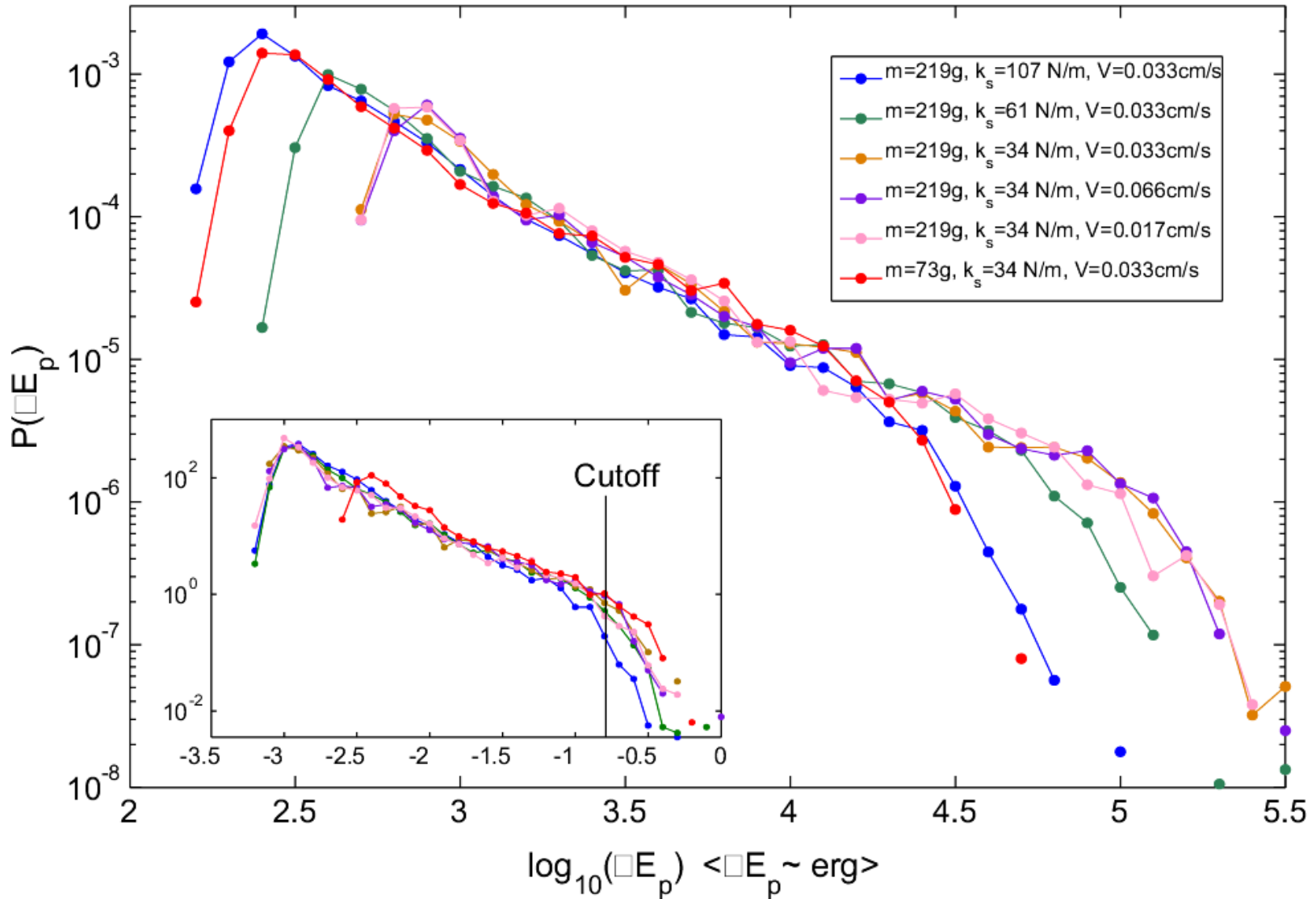
Definitions of  
stick and slip  
events

# Stick-slip Events Distributions-Gutenberg-Richter Relation

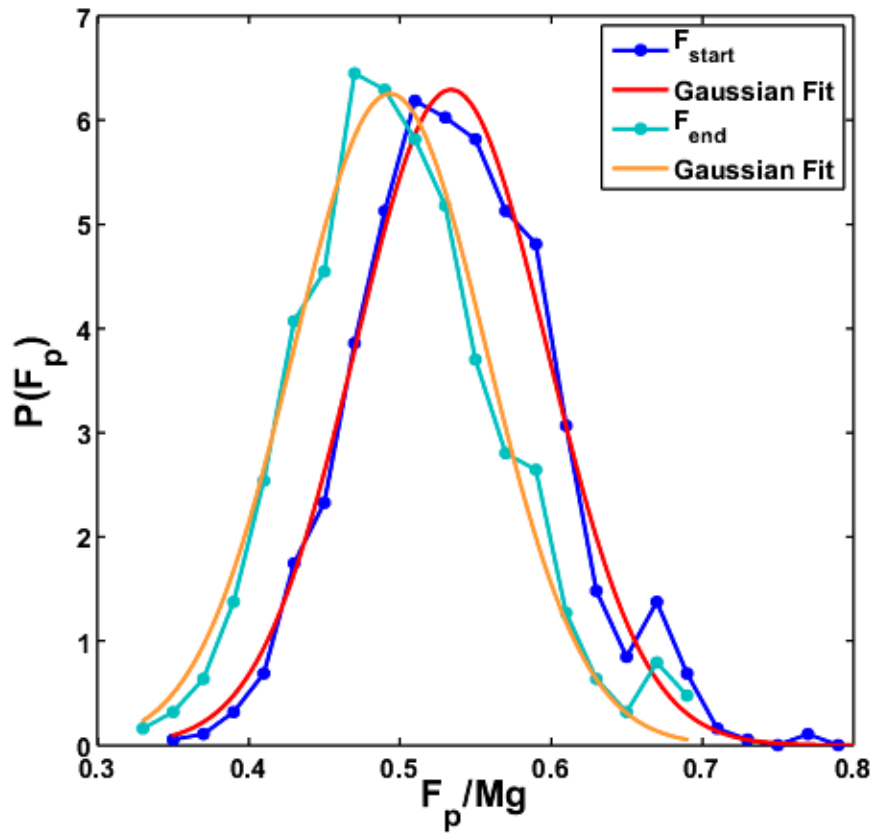
$$\log N = a + bM$$

- Note that GR relation is for a CDF—cumulative distribution function—integral of a PDF. Also, GR is for  $M$ , related to energy change by a power-law relation
- $b \sim -1$  translates to exponent of  $\sim -5/3$  for PDF of energy loss in our experiments
- **G-R Relation** for earthquake events distribution:  
where  $b$  is around  $-1$ .
- The change of  $F^2$  during stick-slip events is a measure of the energy stored or released in these events.

# PDF of energy changes—exponent is $\sim 1.2$

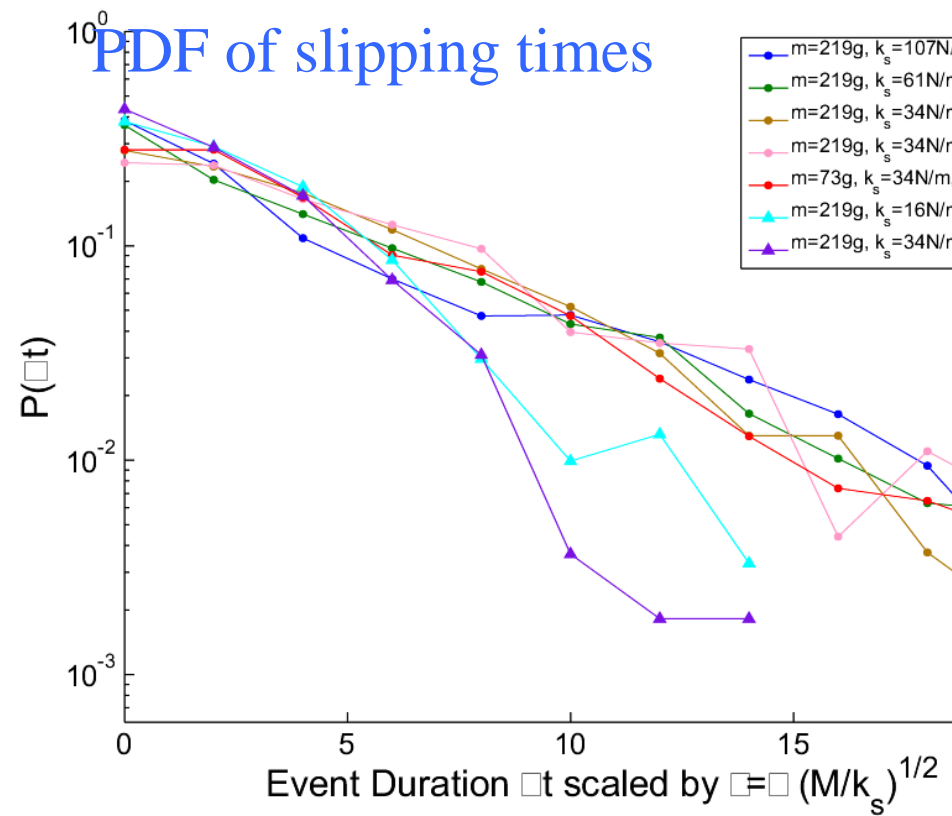


# Distributions for max pulling force, slipping times,...



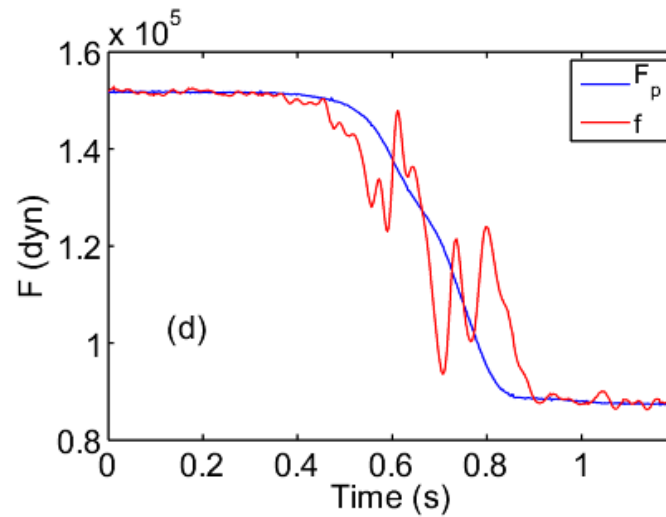
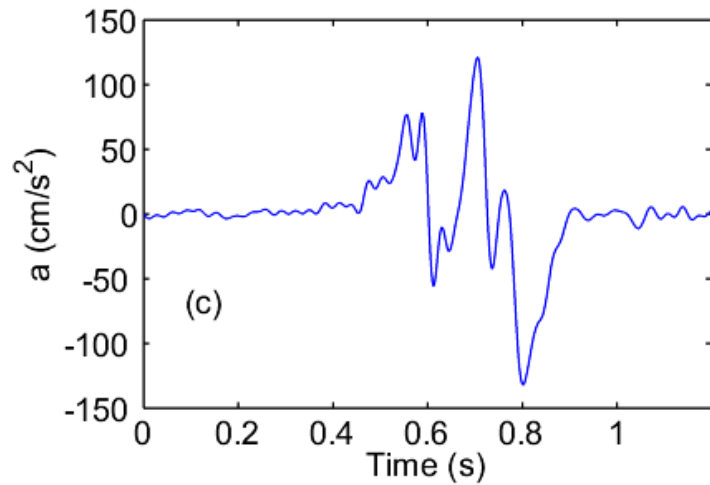
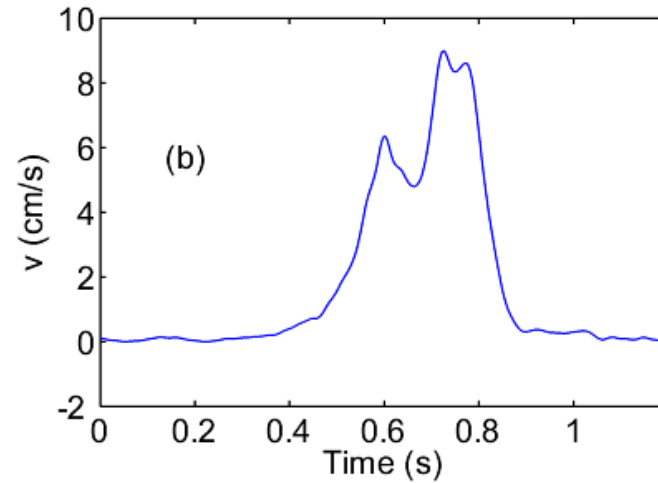
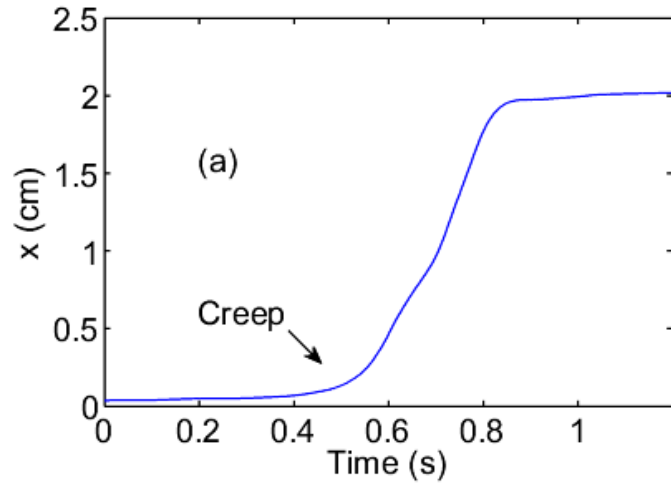
$$\mu_s = F_{max} / Mg$$

Natural scale:  $\omega = (k/M)^{1/2}$

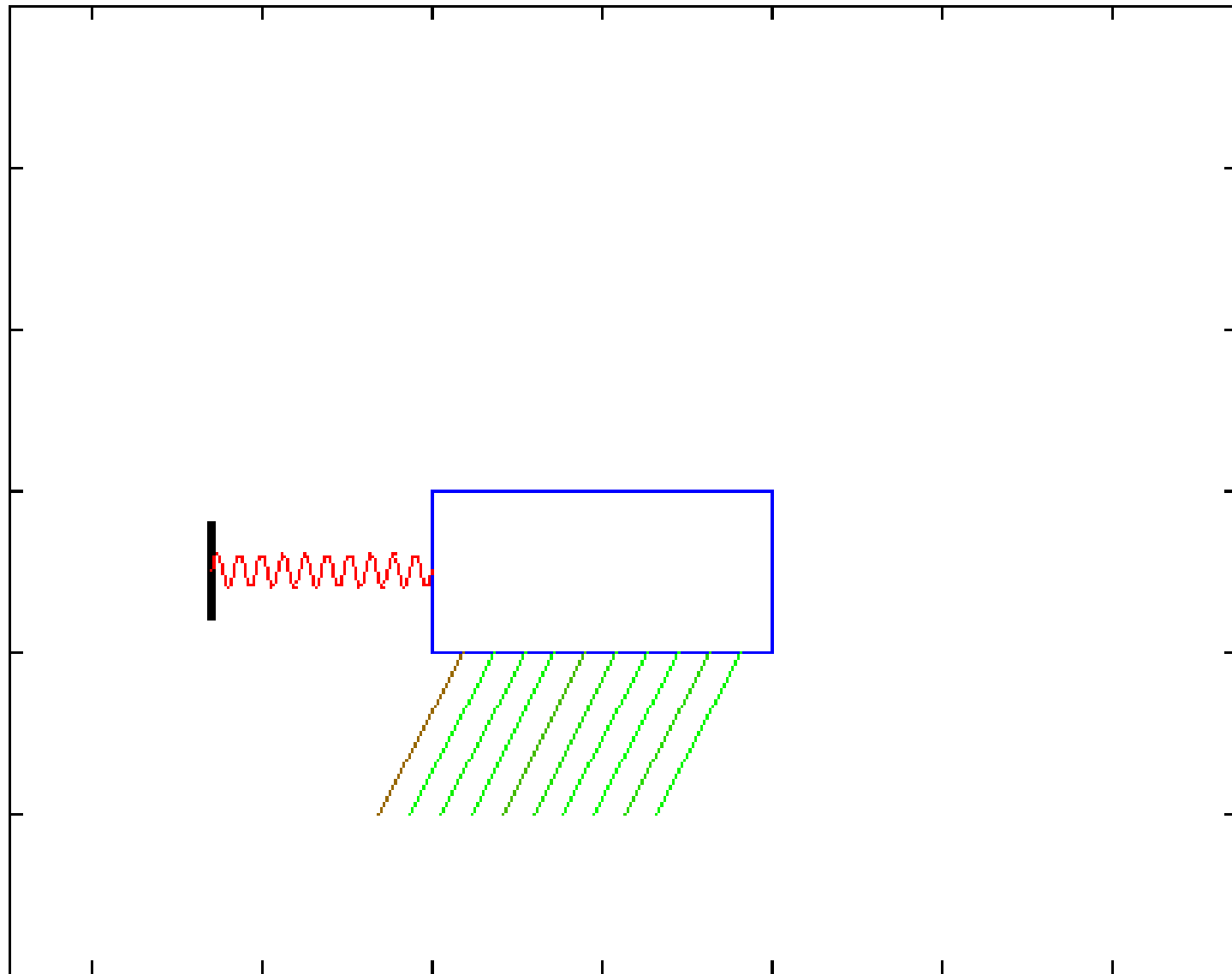




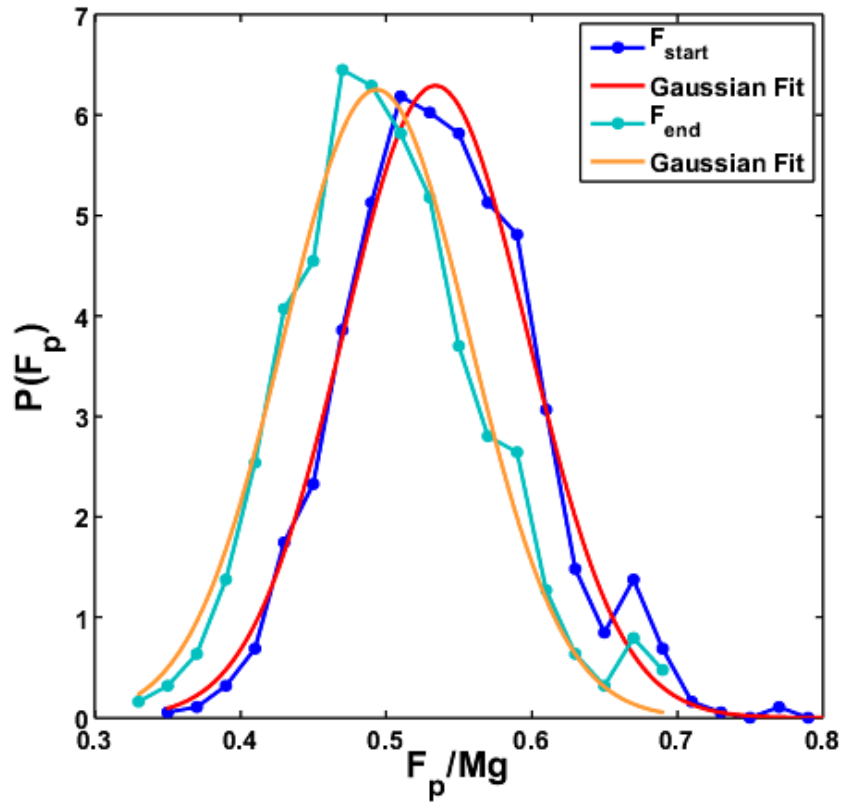
# Dynamics of actual slip events



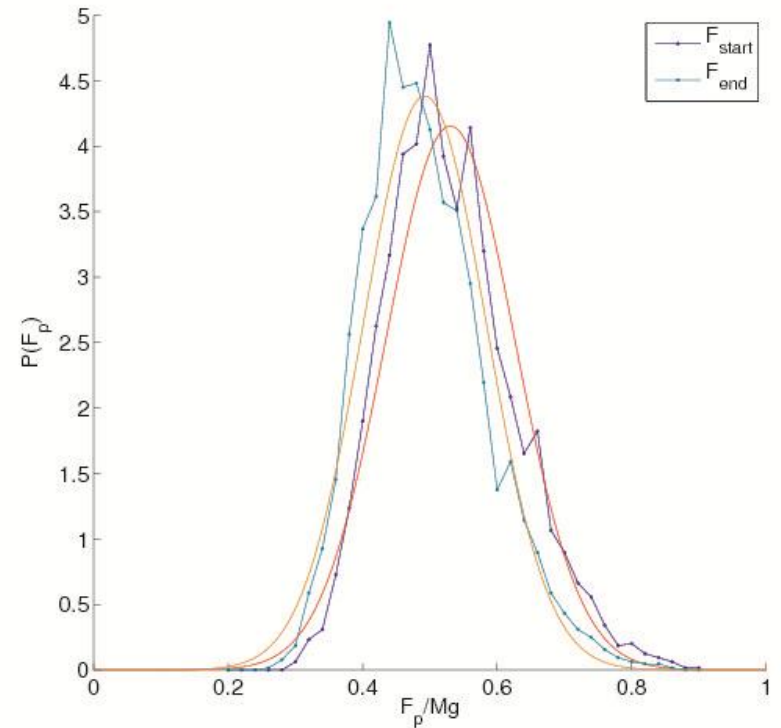
# Video of force chain failure model



# Simple comparison—model/experiment— distributions of initial and final pulling forces

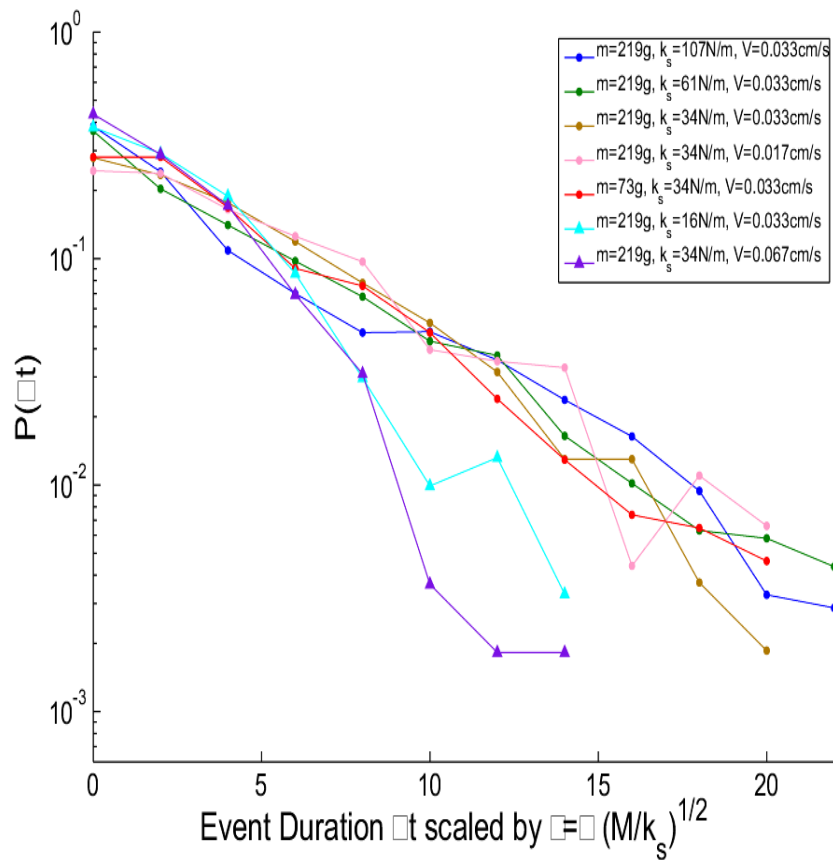


experiment

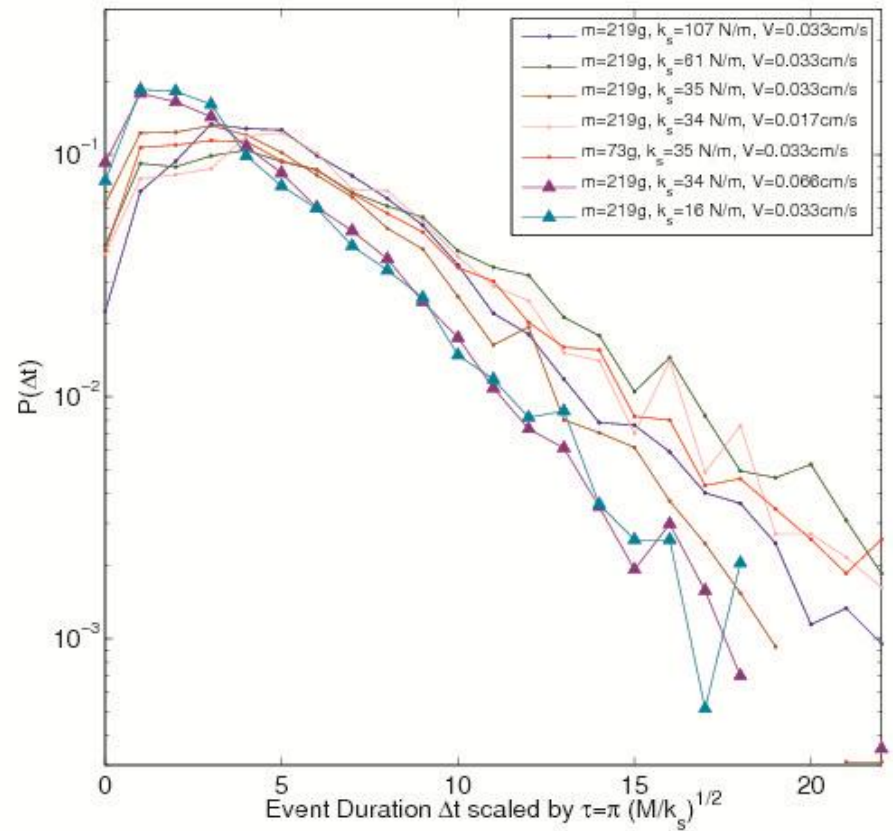


model

# Simple comparison—model/experiment— distributions of slipping times

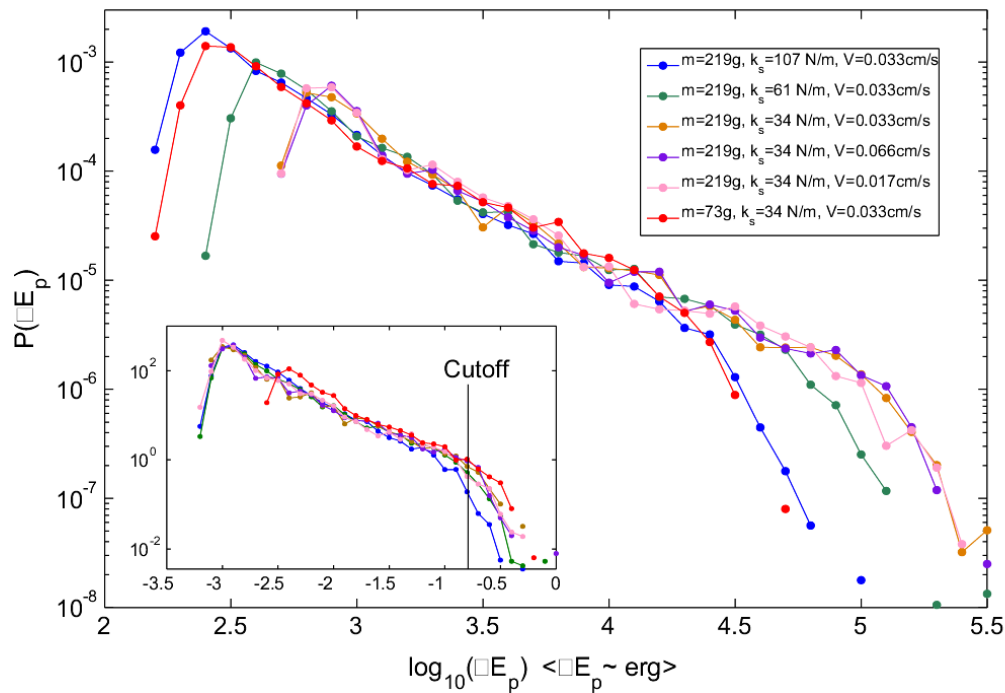


experiment

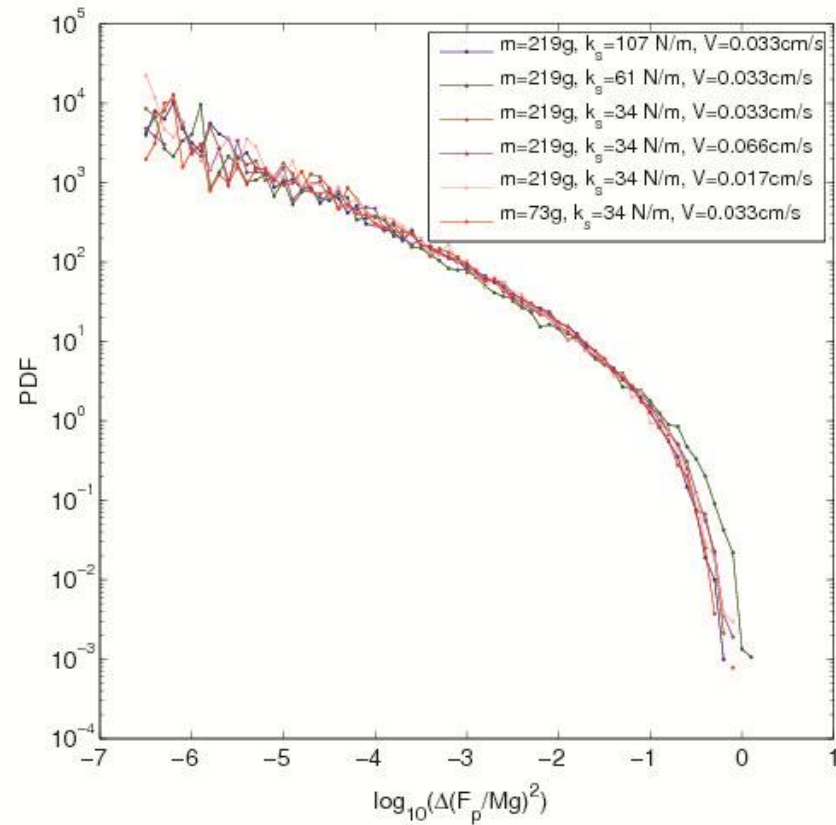


model

# Simple comparison—model/experiment— distributions of event size/energy drop



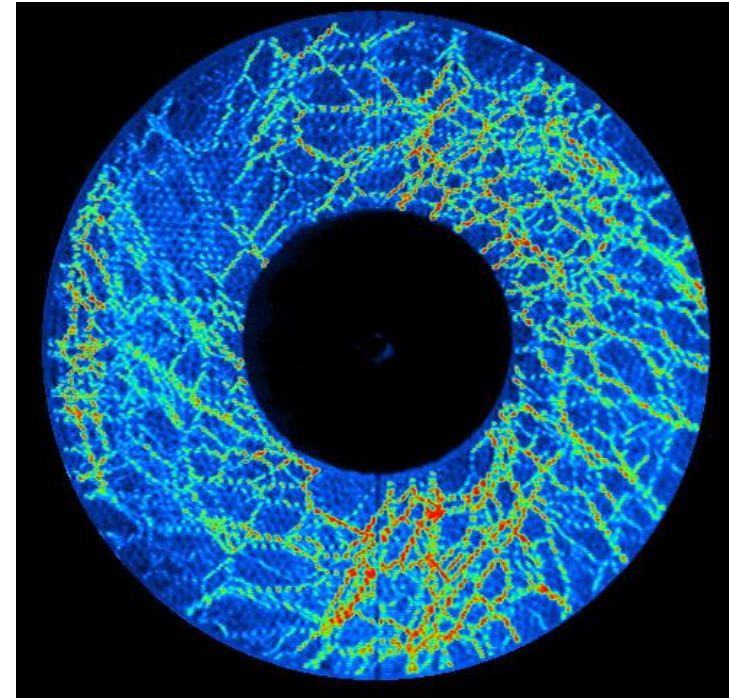
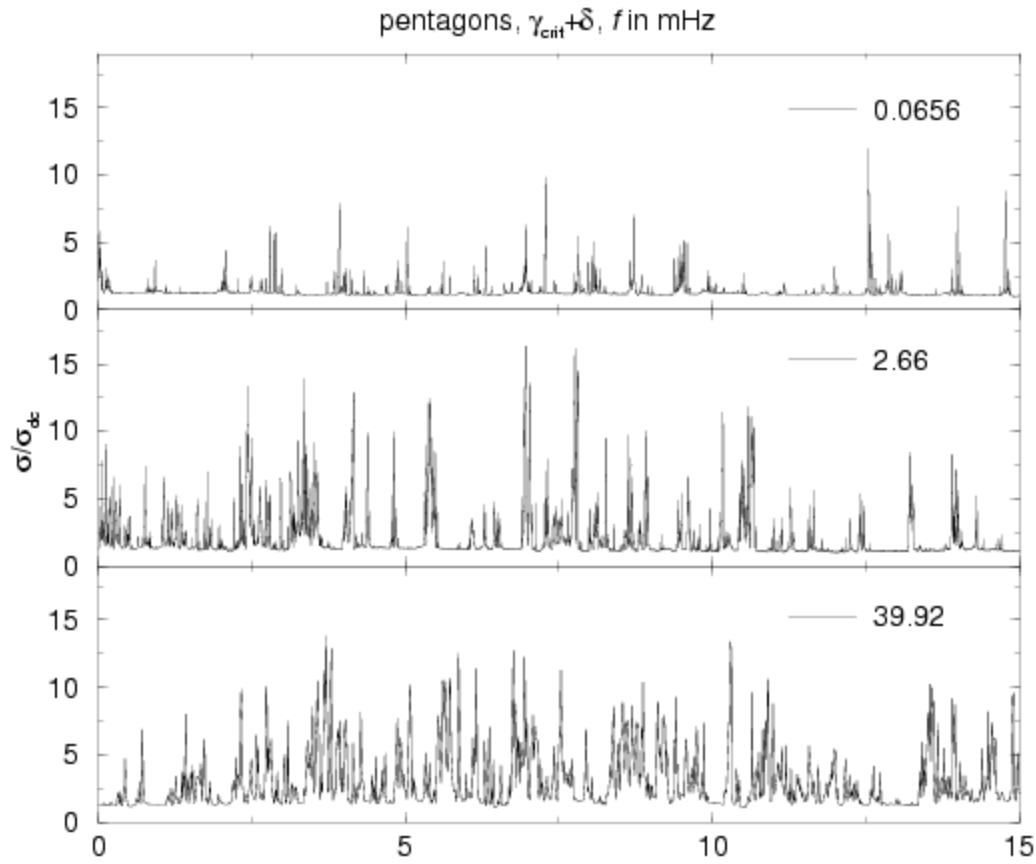
experiment



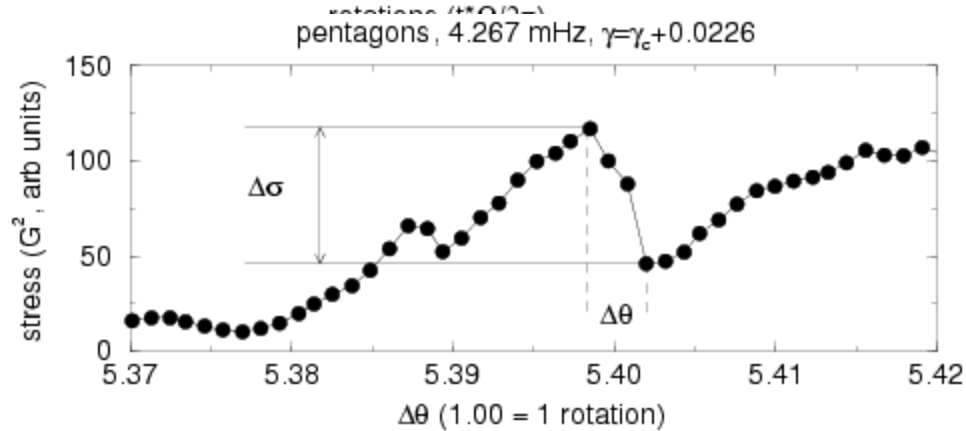
model



# Avalanches in Couette shear

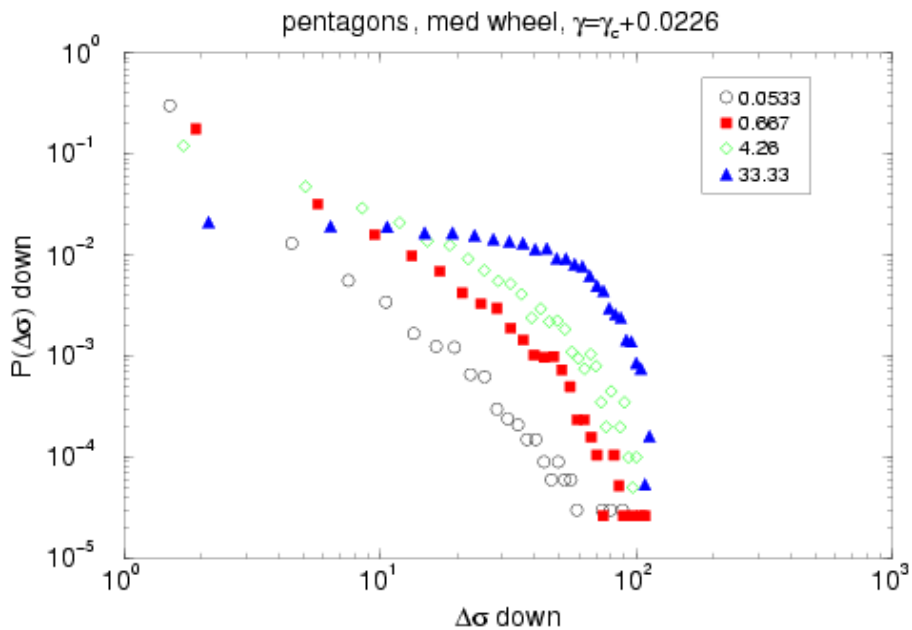


experiment

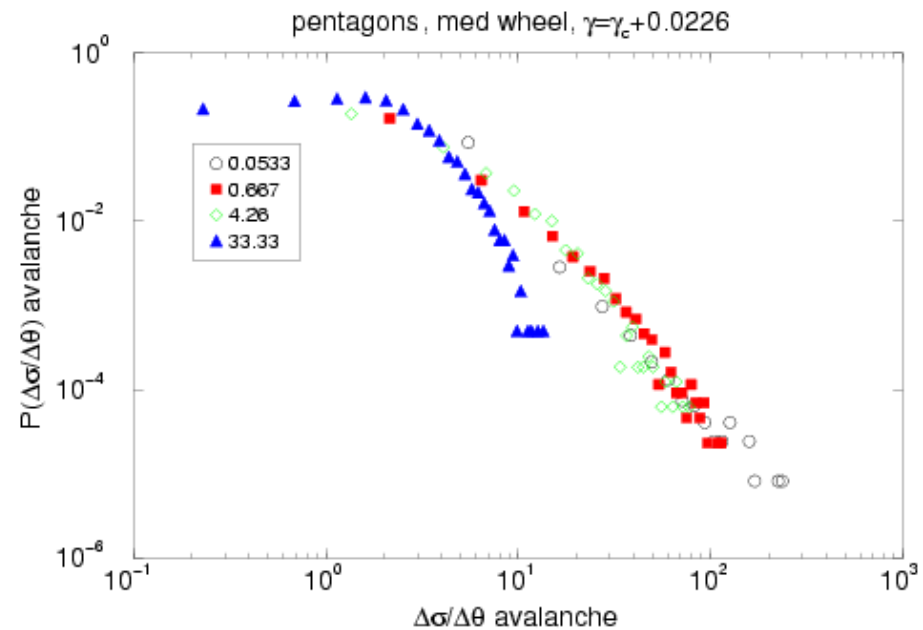


model

# Stress drops and rate of stress drops—different shear rates

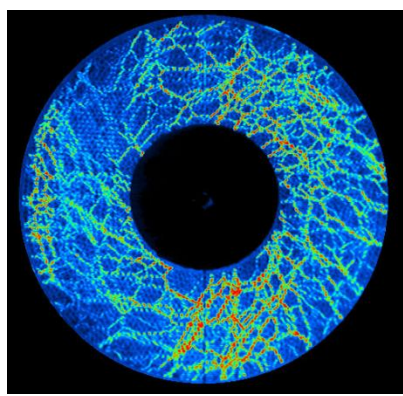
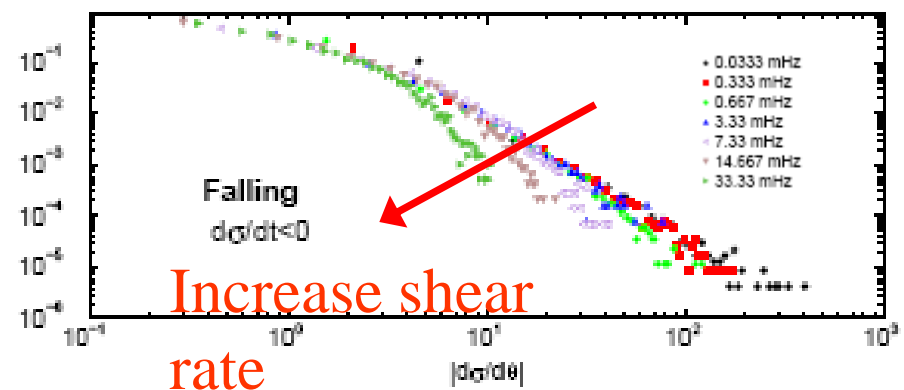
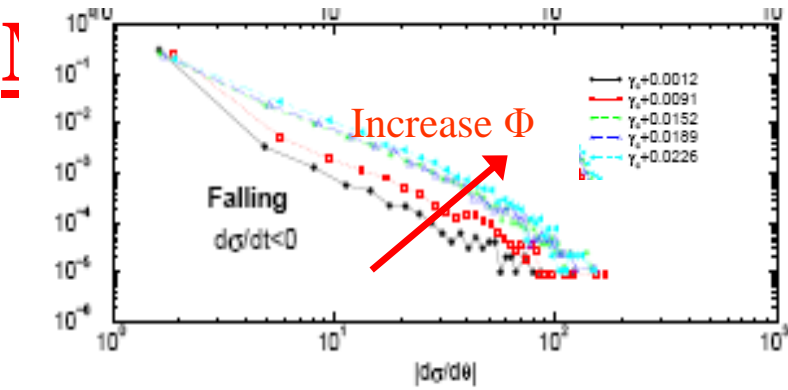


Stress drops



Rate of stress drops

# Simple Model predicts Slip Statistics in Granular



Power law exponent or other universal quantity	Mean Field Theory (MFT)	granular experiment [6,8-10,20-21,29]	granular simulation [2-4]
avalanche size distribution $D(s) \sim s^{-\kappa}$	$\kappa=1.5$	$\kappa= ???$	
avalanche duration distribution $D(T) \sim T^{-\alpha}$	$\alpha=2$	$\alpha=2$ or exponential?	
stress drop rate distribution $\sim$ $D(V) \sim V^{-\psi}$	$\psi=2$	$\psi=2$ [29]	
power spectrum $P(\omega) \sim \omega^{-\phi}$	$\phi=2$ if $\nu \approx 1$ ; $\phi=0$ if $\nu \ll 1$	$\phi=1.8-2.5, 2$	$\phi=2$ if solid $\phi=0$ if fluid
Source time function averaged over avalanches of duration T.	Symmetric (parabola)	Symmetric (parabola ? Gaussian ?)	Symmetric sine fctn ?
Stick slip statistics	Yes, if $\epsilon > 0$ and $\nu > \nu^*$	Yes, sometimes	Yes (mode switching)
Mode switching (between powerlaw and stick slip)	Yes, if $\epsilon > 0$ and $\nu > \nu^*$	Yes, sometimes	Yes in solid regime

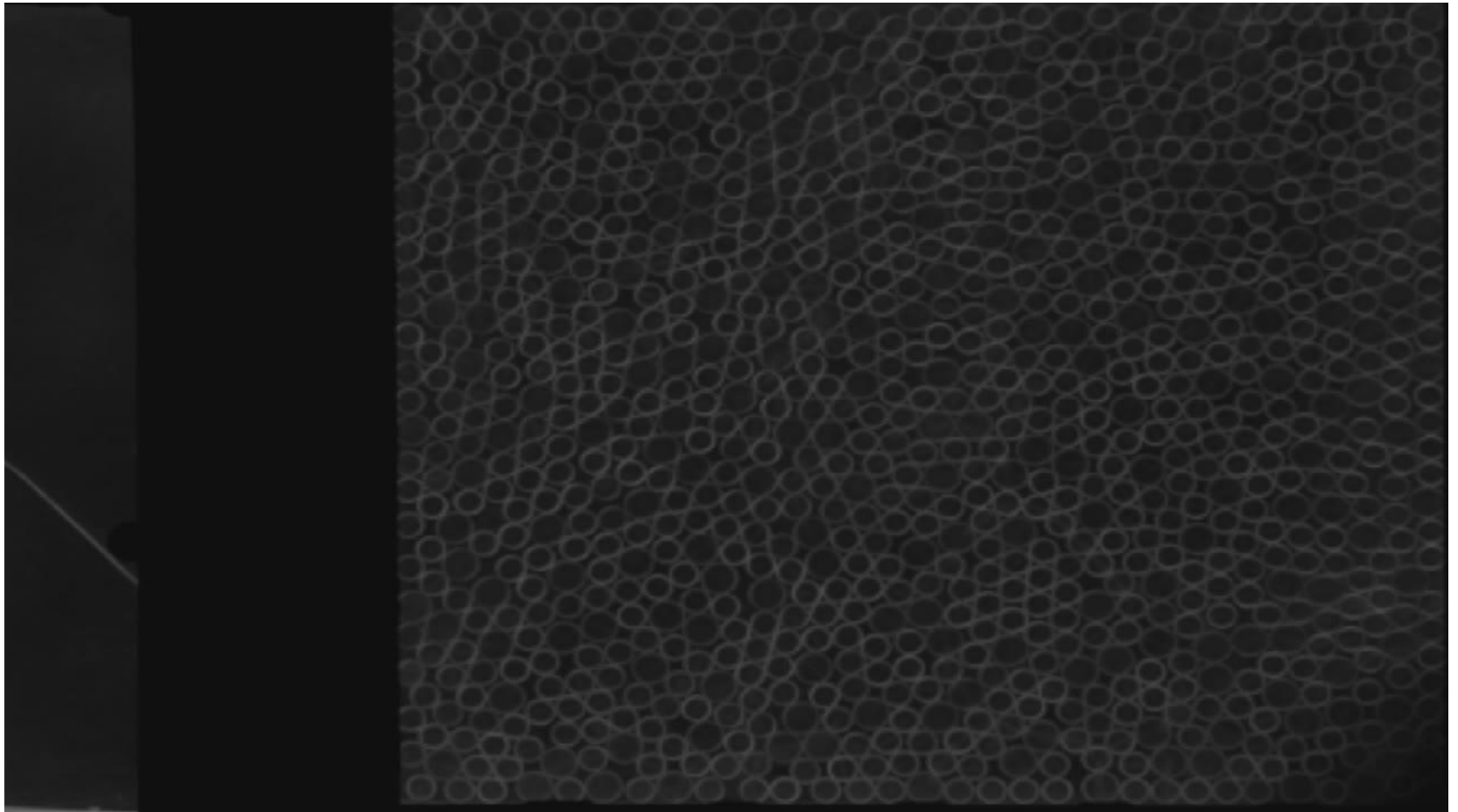
## Biaxial shear experiment (D. Wang, J. Barés)

Number of particles: 963 (214 large and 749 small)

Initial packing fraction (density): 0.7798

Maximum strain : 0.2; Steps in a cycle: 80  $\Delta\varepsilon = 5.0 \times 10^{-3}$

Total cycles: 50



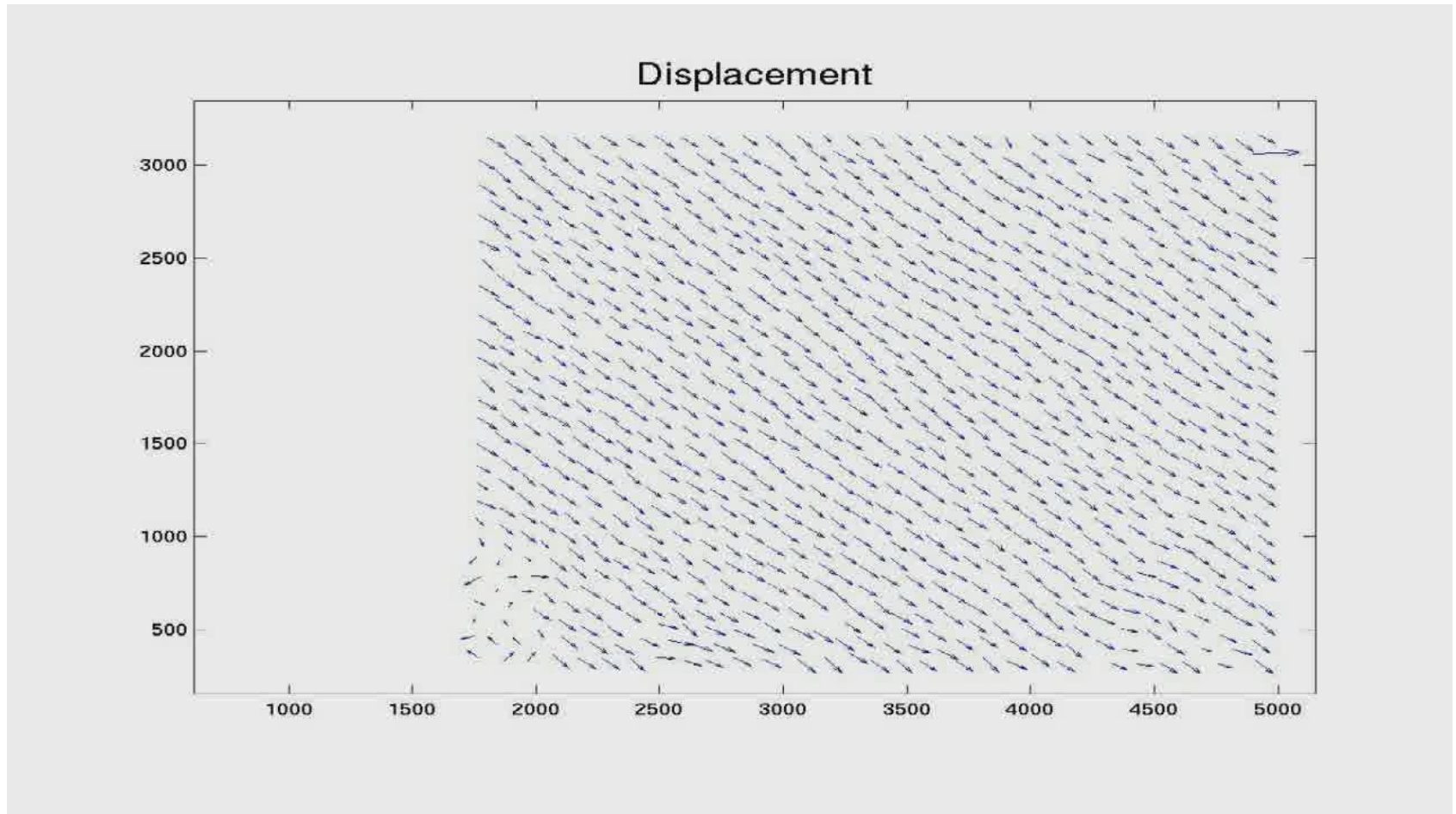
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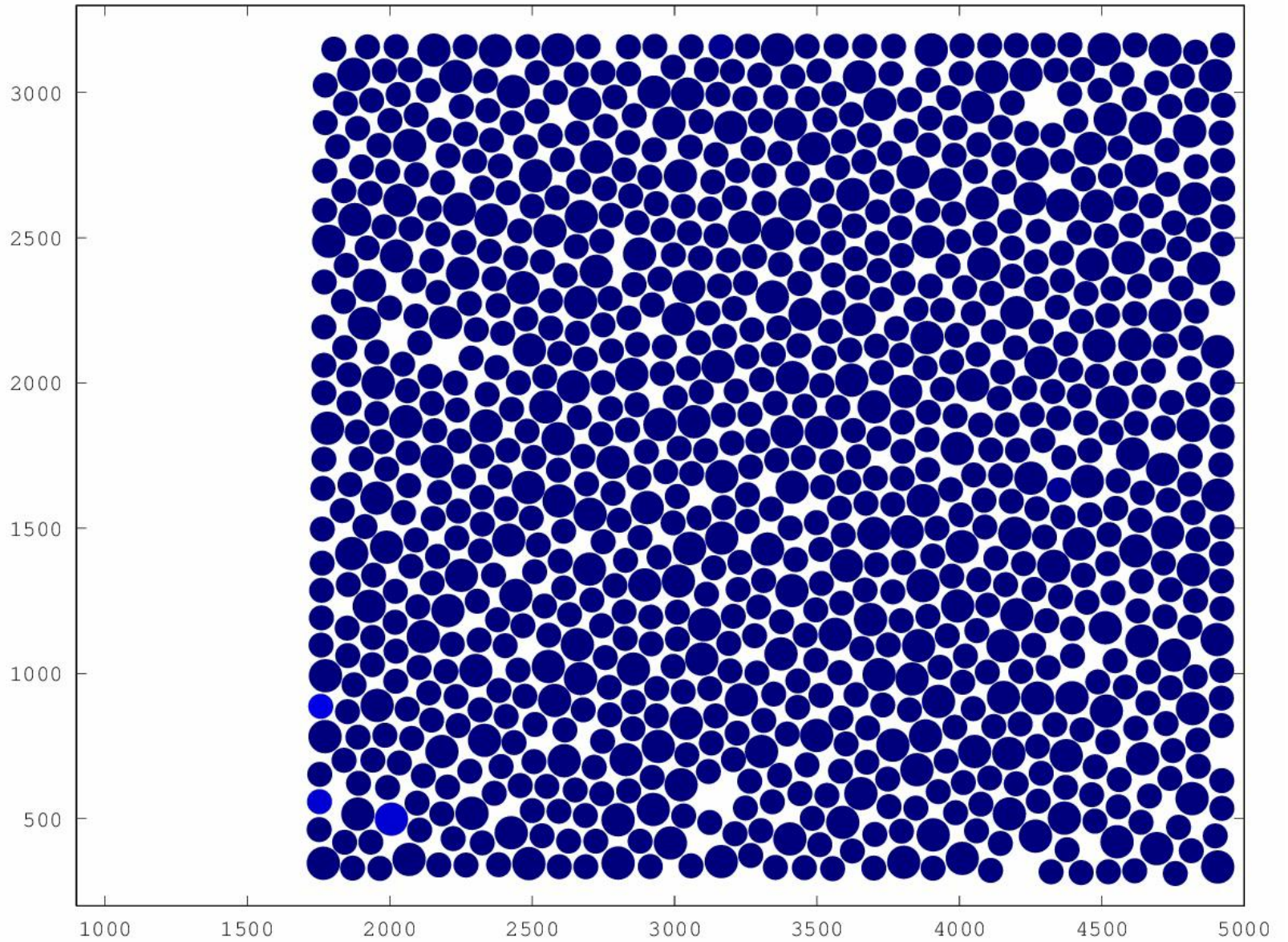
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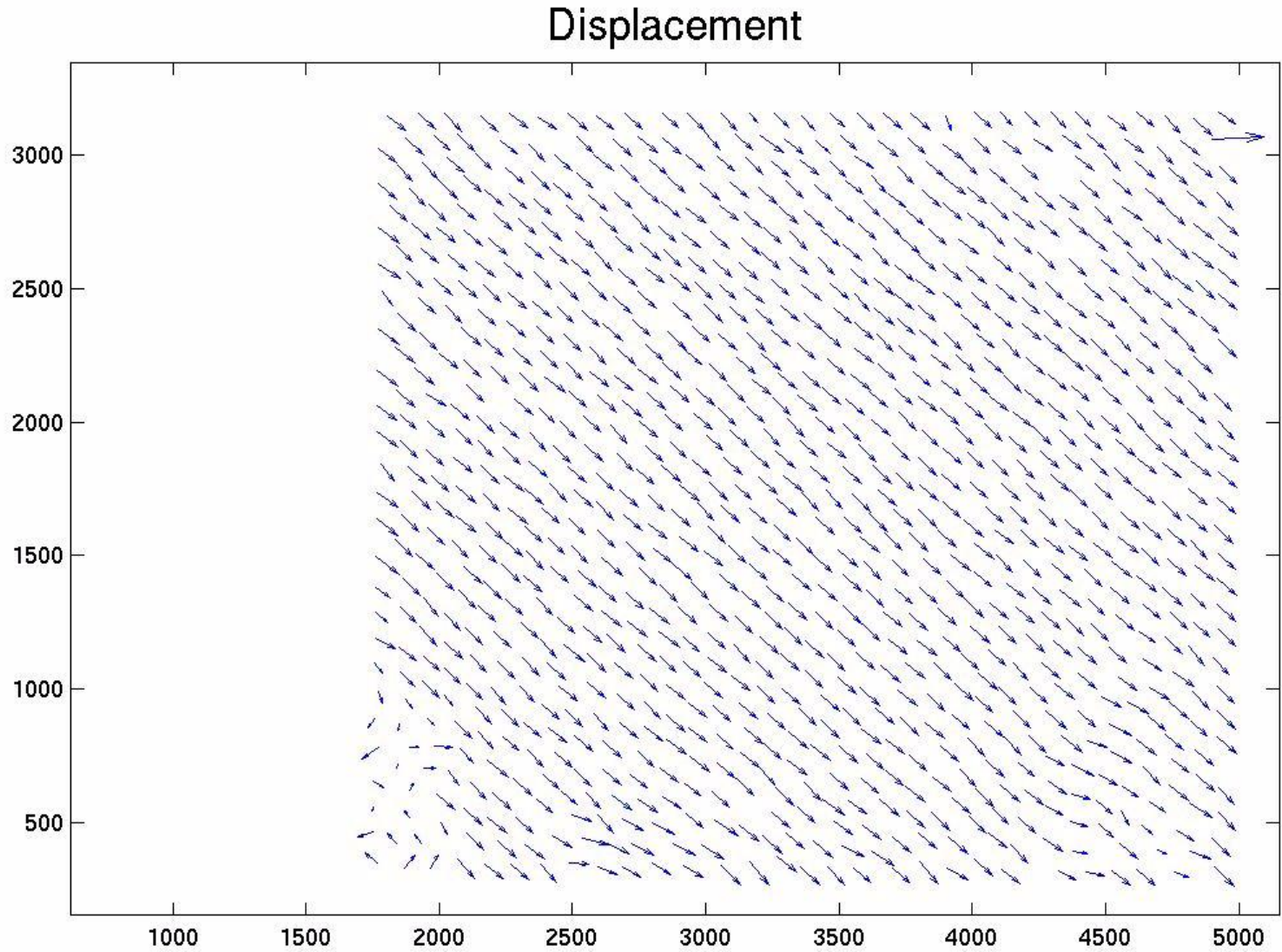




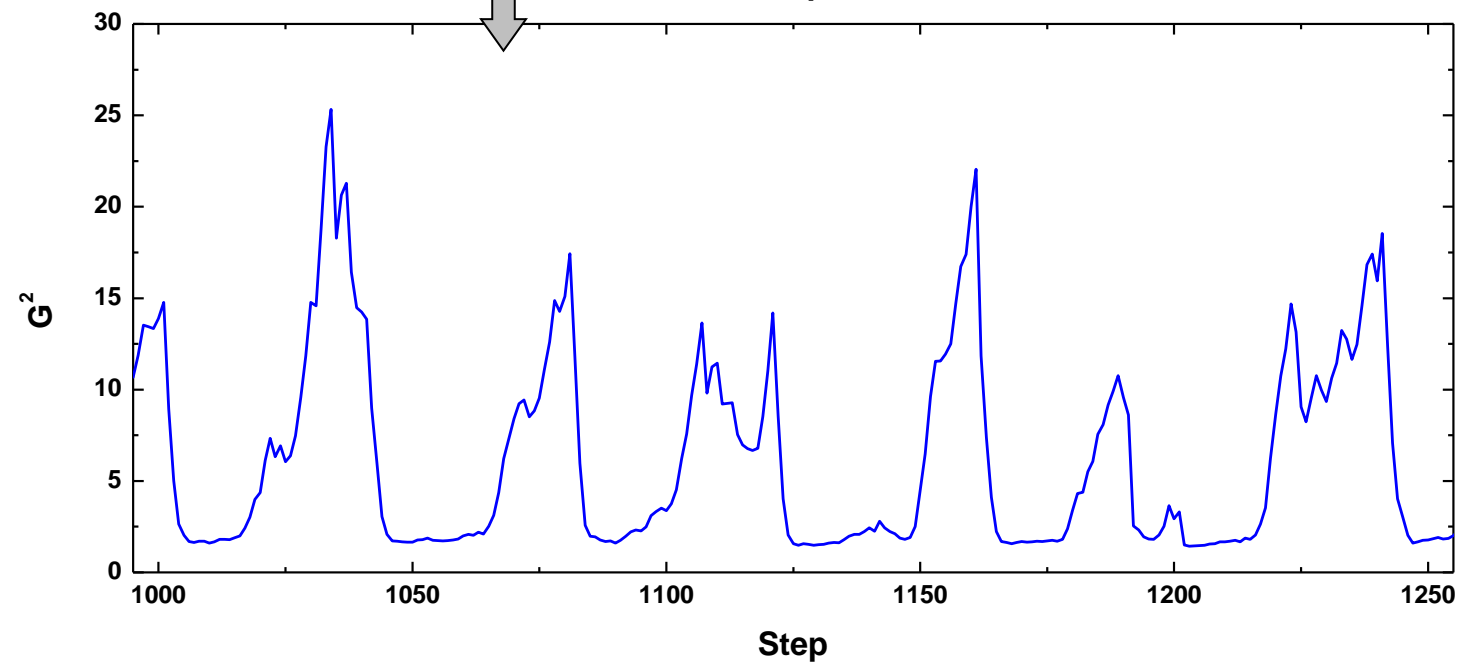
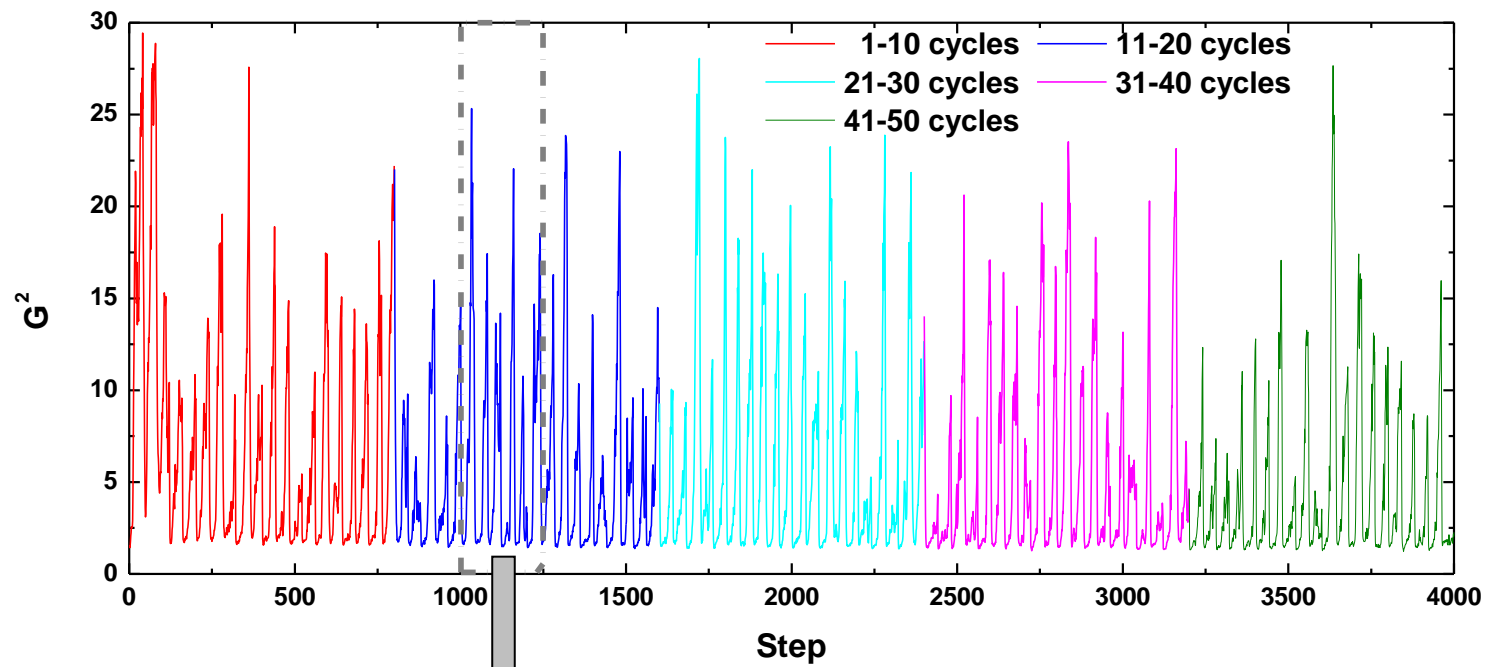
# Step-to-step particle rotations

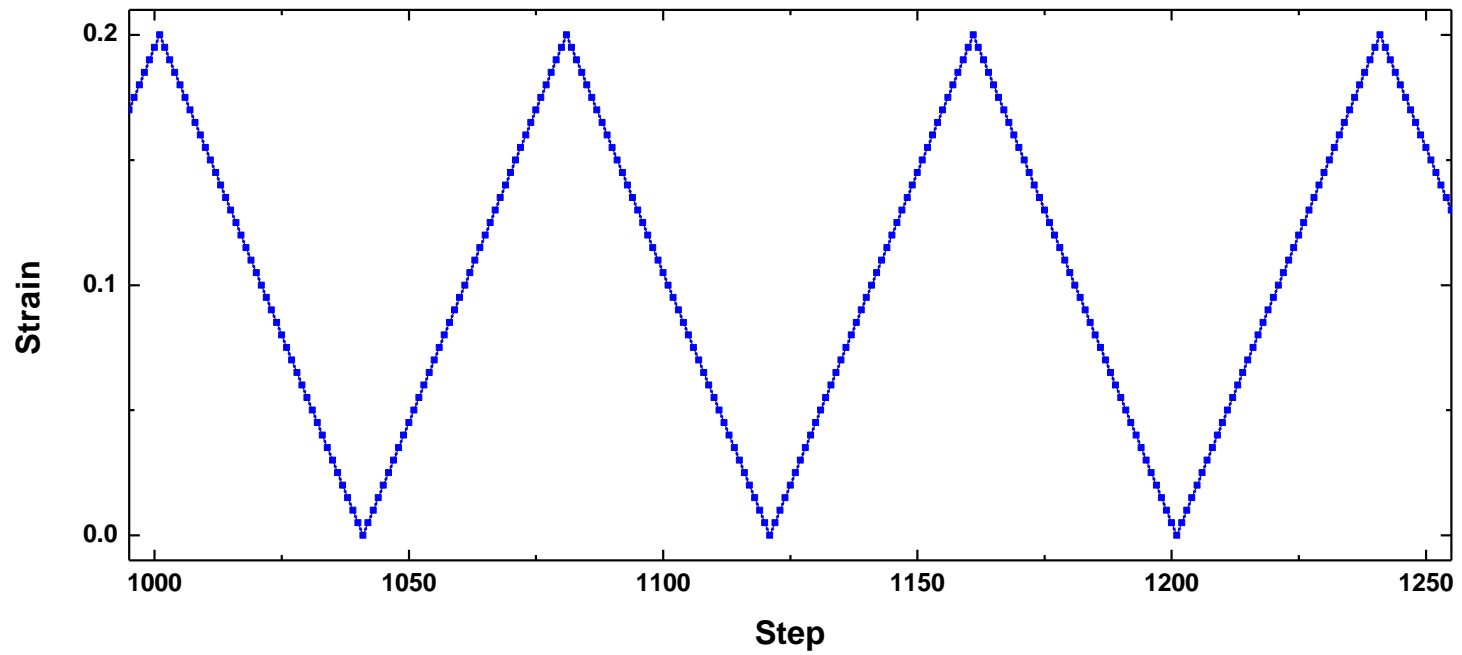
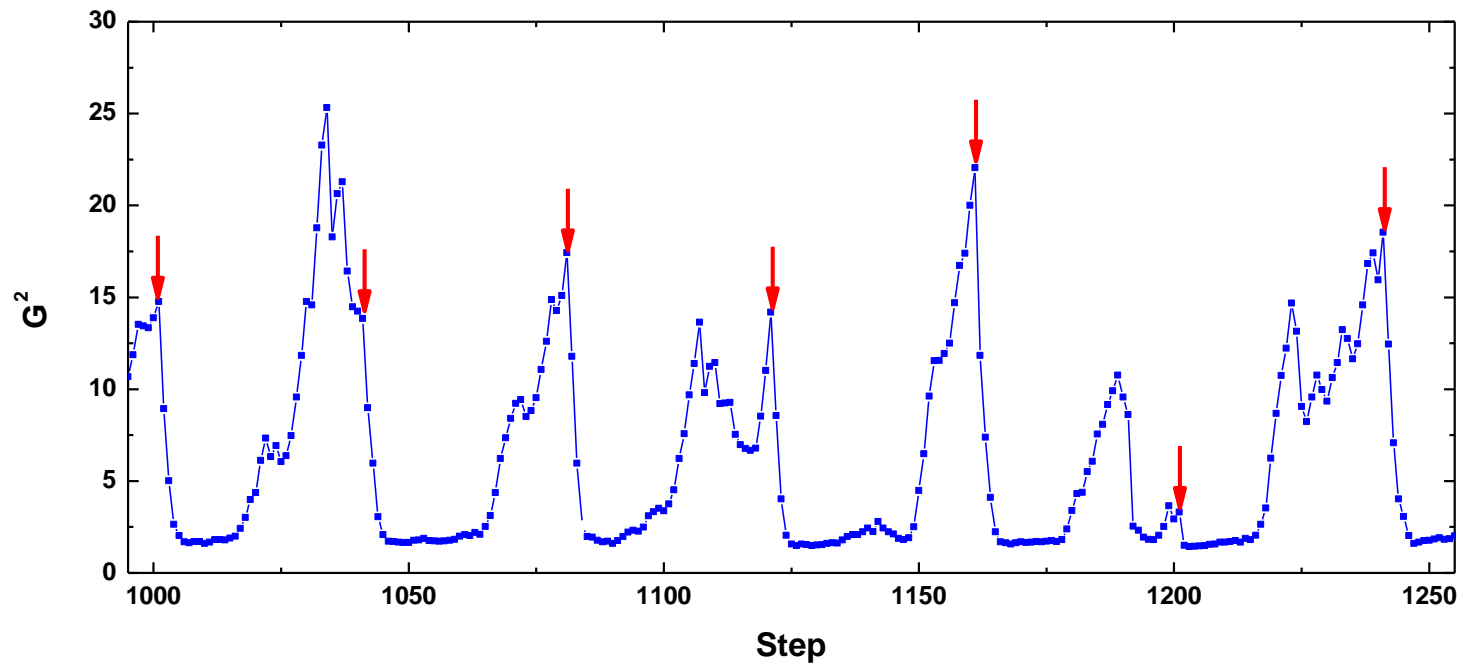


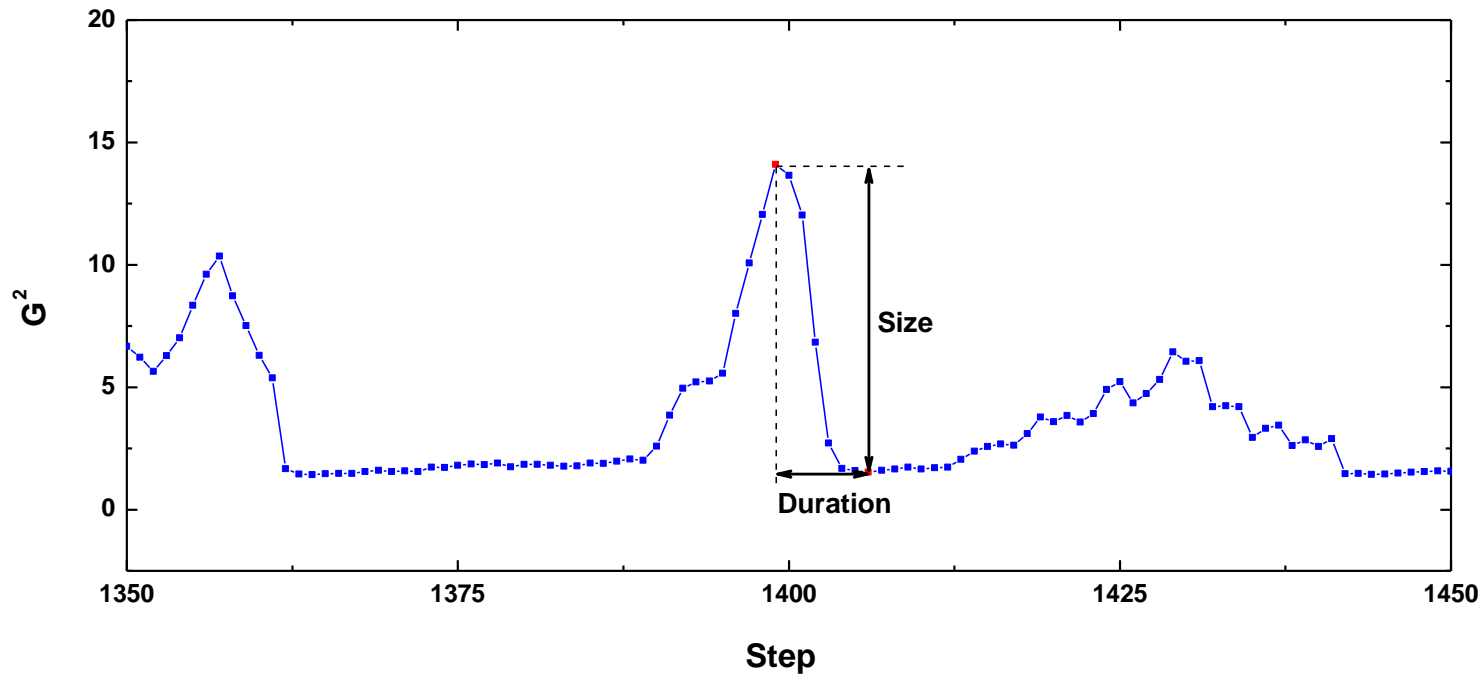
# Step-to-step particle displacements











## **An avalanche event**

is defined to be a monotonic decrease in the  $G^2$  vs Step (or Strain);

## **The size of an avalanche**

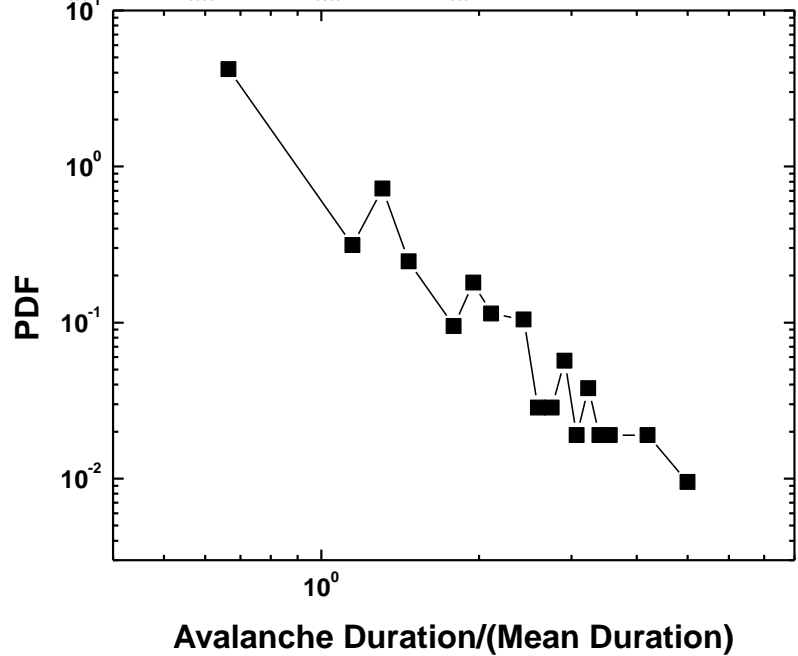
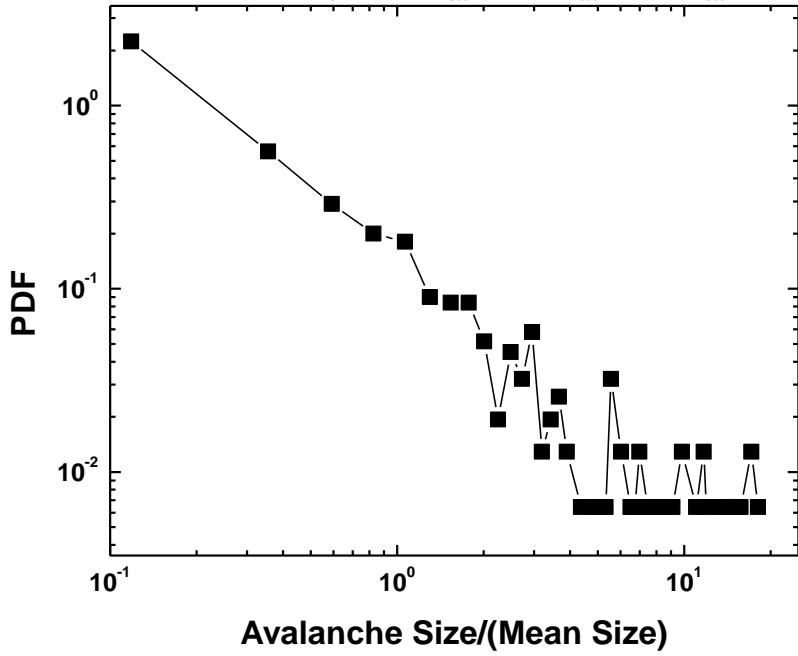
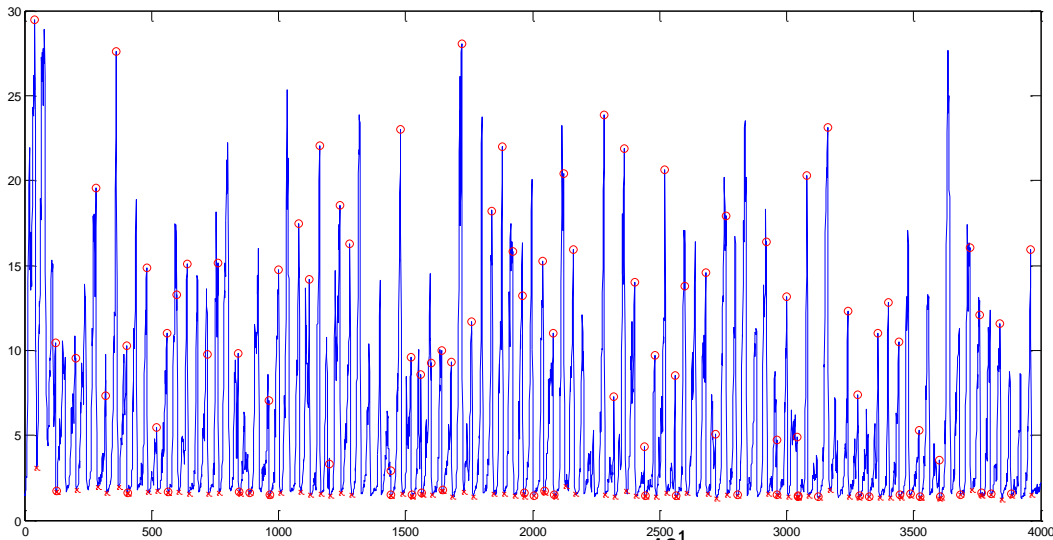
is the magnitude of the drop of the  $G^2$ ;

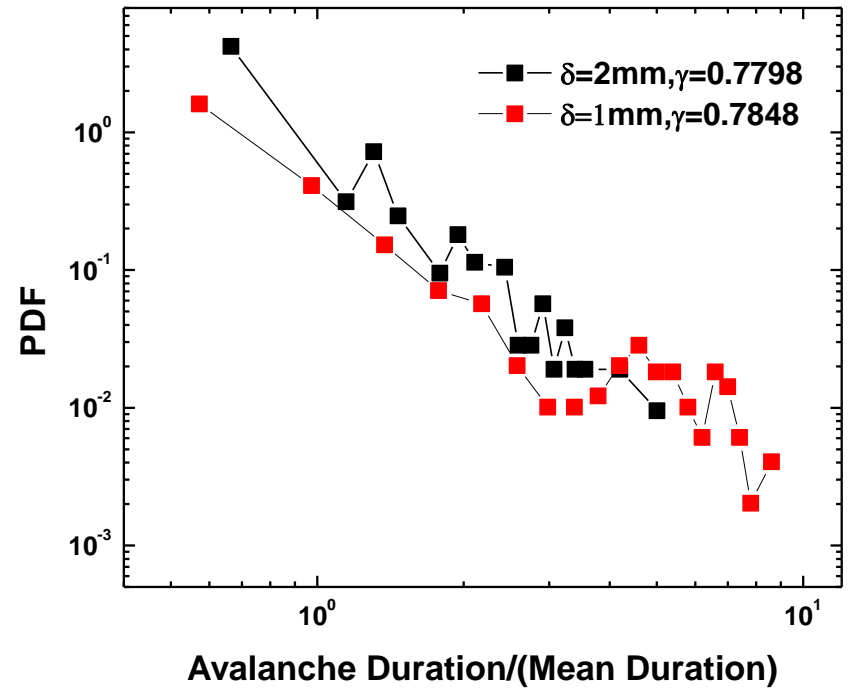
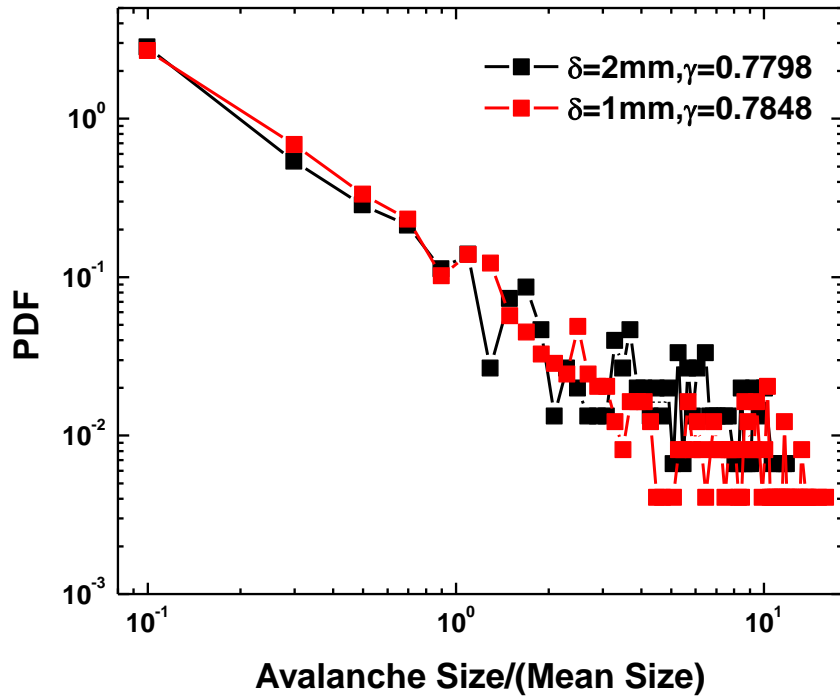
## **The duration of an avalanche**

is the strain it takes for an avalanche event to take place.



**Rescaled distribution of avalanche size without considering those avalanches due to the reverse motions of loading boundaries. Left: Size; right: Duration**





The rescaled distribution of avalanche size and duration on log-log scale.

## Shear, jamming, force ensemble, particle motion

- Particles with friction have different jamming properties from frictionless case
- Fragile and fully jammed states/networks
- Shear jamming reconciles Couette/hopper flow jamming
- Fixed volume states show Boltzmann-like activation
- Strain amplitude is providing activation and is temperature-like
- Shear granular systems provide useful approach for testing avalanche models

