



## Current status of exploiting theoretical modelling of gravity waves in data analysis

#### Stephen Fairhurst

Cardiff University and LIGO Scientific Collaboration



wenty ten | 350 years of nd beyond | excellence in science







#### Outline

- Detectors
- Source Waveforms
- Search Methods
- Input from Numerical Relativity









#### The LIGO Detectors



#### Livingston, LA 4km detector "L1"

Hanford, WA 4km detector "H1" 2km detector "H2"









#### **Noise Sources**







#### **LIGO Sensitivities**

 The initial LIGO detectors have completed five science runs, S1 - S5.









#### LIGO Sensitivities

- The initial LIGO detectors have completed five science runs, S1 - S5.
- S5 ended recently, having taken 1 year of coincident data at design sensitivity









Virgo





- Work has begun on enhanced LIGO
  - Approx factor of 2 improvement in sensitivity
- Advanced LIGO construction will begin this year
  - Order of magnitude more sensitive than initial detectors









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#### **Coalescing Binaries**

- Binary systems emit gravitational waves and slowly inspiral together.
- This have already been (indirectly) observed.









### The Inspiral Waveform

- Gravitational waves are emitted as the binary inspirals.
- The waveform depends upon masses, spins, binary orientation
- Waveform can be well modelled up to the last few orbits, using the post-Newtonian formalism.
- pN fails around ISCO:

$$F_{\rm ISCO} = 220Hz \times$$

m.  
C:  
$$\left(\frac{20M_{\odot}}{M_{\text{total}}}\right)$$







- Following merger, the final "ringdown" can be modelled using black hole perturbation theory
- The waveform depends upon final mass and spin
  - Currently these cannot be derived from inspiral parameters









### Astrophysical Rates

- Assume that the rate of coalescences is proportional to blue light luminosity
  - Follows star formation rate, supernova rate
  - Expected number of coalescences for a given search

$$N \approx 7.4 \times 10^{-3} \left(\frac{\mathcal{R}}{L_{10}^{-1} \text{ Myr}^{-1}}\right) \left(\frac{D_{\text{horizon}}}{100 \text{ Mpc}}\right)^3 \left(\frac{T}{\text{ yr}}\right)$$

- For binary neutron stars:  $\mathcal{R} = 10 170 \,\mathrm{Myr}^{-1} L_{10}^{-1}$
- For binary black holes:  $\mathcal{R} = 0.1 15 \,\mathrm{Myr}^{-1} L_{10}^{-1}$









### LIGO range



- Expected rates
  - 1 event per few years for Enhanced LIGO
  - Several to many events per year for Advanced LIGO







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# The Inspiral Search Pipeline

- Generate template bank
- Perform matched filter
- Require coincidence
  between detectors
- Signal consistency tests
- Interpretation of results









#### Search Details

- The inspiral waveform is described by masses, spins, distance, sky location, orientation.
- For non-spinning waveforms, the orbital plane does not precess, and the waveform can be written as:

$$h(t) = \left(\frac{1 \text{Mpc}}{D_{\text{eff}}}\right) A(t - t_o) \cos(\phi(t) - \phi_o)$$

- Where  $D_{\text{eff}}$  is the effective distance ( $\geq$  distance)
- $D_{\text{eff}}, \phi_o$  for a given detector depend upon distance, sky location, orientation relative to detector







#### Matched Filtering

• Define the 2 phases of the waveform

$$h_c(t) = A(t - t_o)\cos(\phi(t))$$

$$h_s(t) = A(t - t_o)\sin(\phi(t))$$

- And a normalization factor:  $\sigma^2 = \int_{f_{\rm low}}^{f_{\rm high}} df \, rac{|\tilde{h}_c(f)|^2}{S_h(f)}$
- $S_h(f)$  is the noise power spectral density







### Matched Filtering

- The signal to noise ratio (SNR)  $\rho$  is given by  $\rho^2(t) = \rho_c^2(t) + \rho_s^2(t)$  $\rho_{c,s}(t) = \frac{1}{\sigma} \int_{f_{\text{low}}}^{f_{\text{high}}} df \, e^{2\pi i f t} \, \frac{\tilde{s}(f) \tilde{h}_{c,s}^{\star}(f)}{S_h(f)}$
- From the measured SNR, we can calculate the observed effective distance and phase:

$$D_{\rm eff} = \sigma/\rho$$
  
$$\phi_o = \tan^{-1}(\rho_s/\rho_c)$$







#### In Pictures





- We search over the mass space by employing many template waveforms with different masses.
- Place templates so that for any waveform h in the parameter space, the match is not less than some mininum value

$$Match = Max_{t_o,\phi_o,i} \frac{\langle h|h_i \rangle}{|h||h_i|}$$

- Where the inner product is

$$< a | b > = \int_{f_{\text{low}}}^{f_{\text{high}}} df \, rac{ ilde{a}(f) ilde{b}^{\star}(f)}{S_h(f)}$$





• Placing templates is simplified by calculating a metric on the mass space

LIGO-

 $\frac{\langle h(\mathbf{x})|h(\mathbf{x} + \mathbf{d}\mathbf{x}) \rangle}{|h(\mathbf{x})||h(\mathbf{x} + \mathbf{d}\mathbf{x})|}$ 

$$\frac{d>}{dt} = 1 - g_{ab}(\mathbf{x}) dx^a dx^b$$

 Allows for efficient placing of templates









#### The Template Bank

- Typically require a minimal match of 97%
- Equivalent to allowing a loss of
  - 3% in range
  - 10% in rate



Example template bank from S5



# Coincidence between detectors

- Require that an event is seen in at least 2 detectors with similar time and masses.
  - Reduces false alarms due to environmental noise
  - Naturally account for correlations between parameters by using metric to determine coincidence windows







512

Erequency [Z56 128

64

-0.5



#### Life isn't Gaussian

• Time-frequency Q-scans showing excess power

**Inspiral Hardware Injection** 

Ô.

Time [seconds]

Normalized tile energy

10





LIGO-G080005-00-Z

0.5

15



 We know how the SNR will vary over parameter space for a true signal.



- Check if it does
  - Example: loudest surviving event in S1









 $t = t_0$ 

# The $\chi^2$ Test

 $\chi^{2} = p \sum \left(\rho_{c,i} - \rho_{c}/p\right)^{2} + \left(\rho_{s,i} - \rho_{s}/p\right)^{2}$ i=1Injected Chirp (SNR = 9.2) Spurious Event (SNR = 8.7) 5 5 100 Hz Check the power in High freq filter tomannananan 0 MAAmmoni 0 the signal is 6 -5 -5 distributed as 5 5 - 400 Hz 512 0 8 -5 -5 Erequency [Hz] TIME TIME 5 5 - 10<sup>3</sup> Hz 0 0 64 400 -5 -5 -0.5 0 0.5 Time [seconds] 5 5 10 15 Normalized tile energy – 1.2 k Hz 0 -5 -5

 $t = t_o$ 



- Signal consistency tests are sensitive to inaccuracies in the waveforms used, e.g.
  - Using non-spinning waveforms
  - Not including merger/ringdown
  - Calibration uncertainty

Example: Filtering EOB waveforms with Taylor PN templates gives increased  $\chi^2$ 









#### Search Results









#### Search Results

- We wind up with a list of candidate events
  - Want to see whether any are significant
  - Plot cumulative
    histogram of number
    of events vs SNR
  - Compare to background from time shifts







- When foreground stands out above background
- Example from S4 BNS search
  - Loudest few events are known to be due to instrumental or environmental origin, but we can dream ...





# When do things get interesting?

- When foreground stands out above background
- Improved signal consistency or better "ranking statistic" will lower the background







- When foreground stands out above background
- Improved knowledge of waveforms will increase SNR of signals





# When do things get interesting?

- When foreground stands out above background
- Improved knowledge of waveforms will increase SNR of signals
- However, more complicated template families run risk of increasing background as well!









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- We need to test the current analyses with full inspiral-merger-ringdown waveforms.
  - Have already done blind hardware injections in S5 with "made up" waveforms.
  - Would like to use the NR waveforms, I'm sure they're more accurate.







- We can perform simulations (in software) using NR waveforms, if provided in format described in "Data formats for numerical relativity waves", arXiv:0709.0093
  - Scale waveform for physical masses, distance, location, orientation
- Will run inspiral and ringdown matched filter searches, and burst "excess power" searches on same set of simulations.
- Work out which search, or combination of searches, is most sensitive.







### Final Thoughts

- We are sure to learn a lot when we do NR injections, but maybe not what we expect
  - It may turn out that we don't win by match filtering for the full waveform.
  - It may be that we don't win (in some mass ranges) by matched filtering at all.
- I've focused primarily on detection, have barely touched parameter estimation.

