

Filtering Classical Noise by Quantum Control

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ARC CENTRE OF EXCELLENCE FOR
ENGINEERED QUANTUM SYSTEMS



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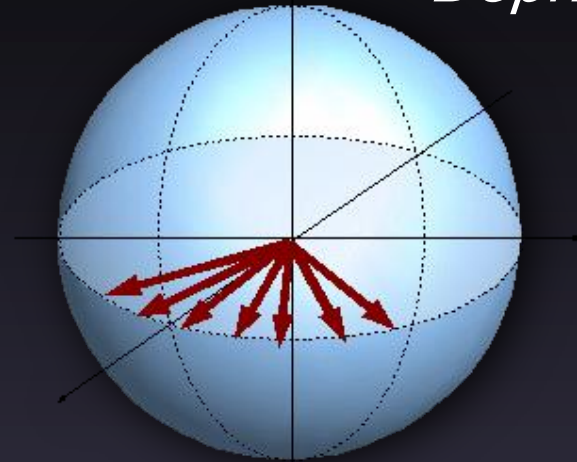
Formerly



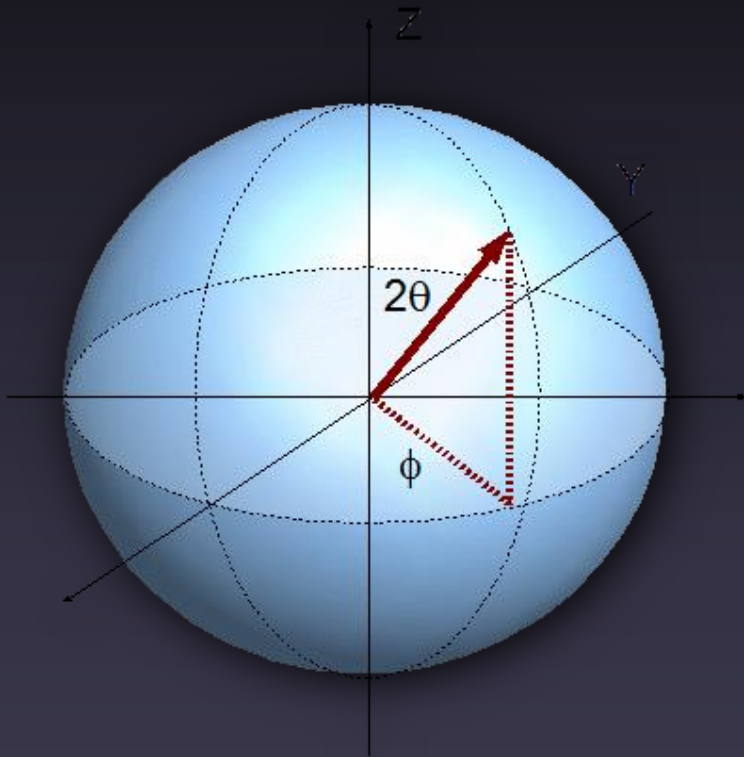
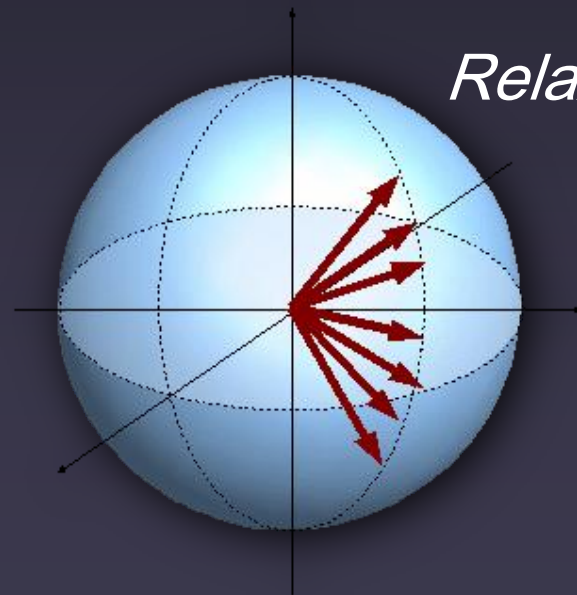
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Errors: A challenge for experimentalists

Dephasing



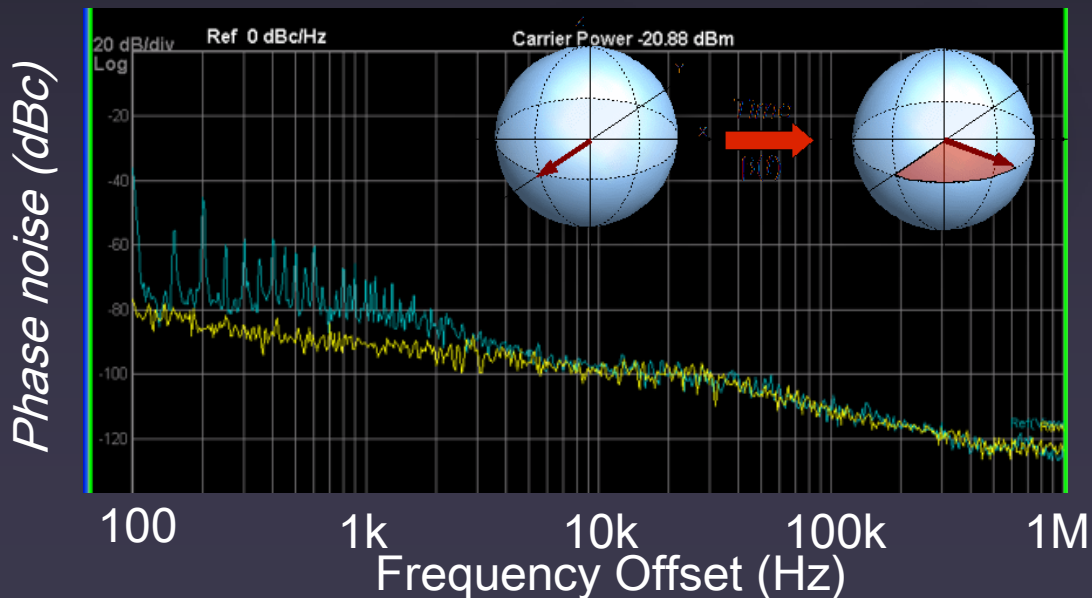
Relaxation



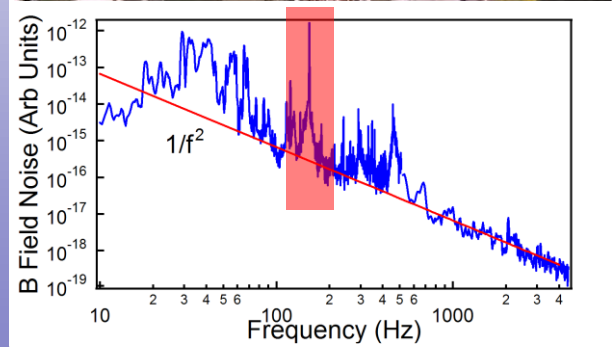
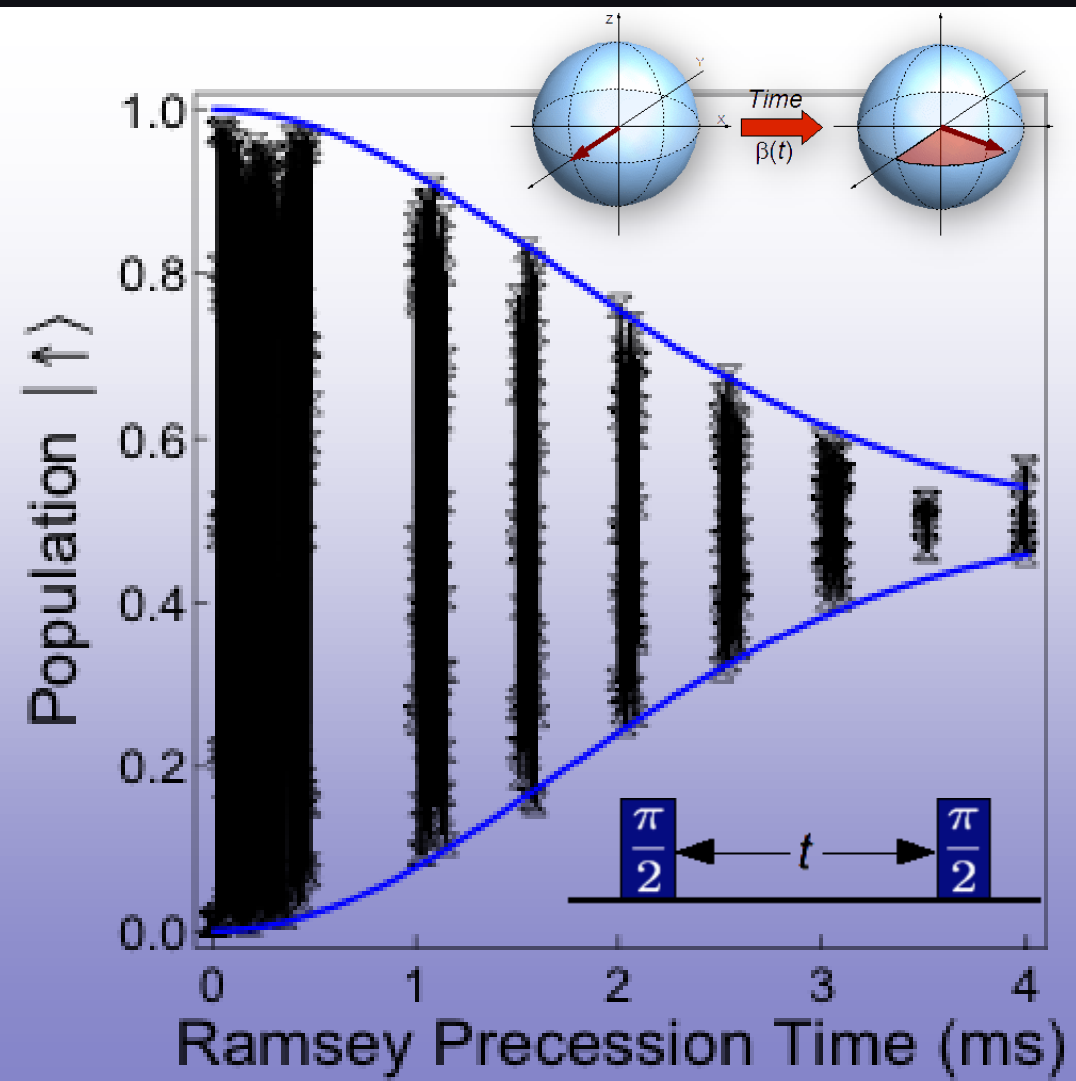
What error model should we pursue?

- Independent stochastic errors
- Full quantum mechanical bath
- **Classical colored noise**
 - Ambient fields
 - Local Oscillator instabilities

12.6 GHz carrier



Dephasing due to classical fields



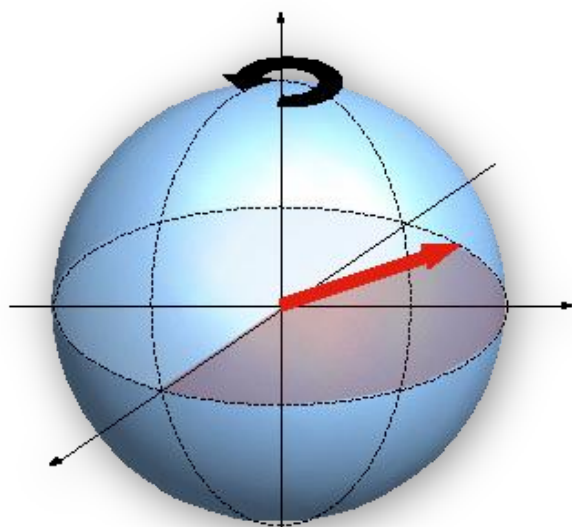
${}^9\text{Be}^+$ @4.5T
 $\Omega_0 \sim 124$ GHz

How do we deal with resulting errors?

- Closed-loop feedback control
⇒ Quantum Error Correction
- Open-loop control
⇒ Dynamic Error Suppression
(Unitary Quantum control)



What tools do we have?



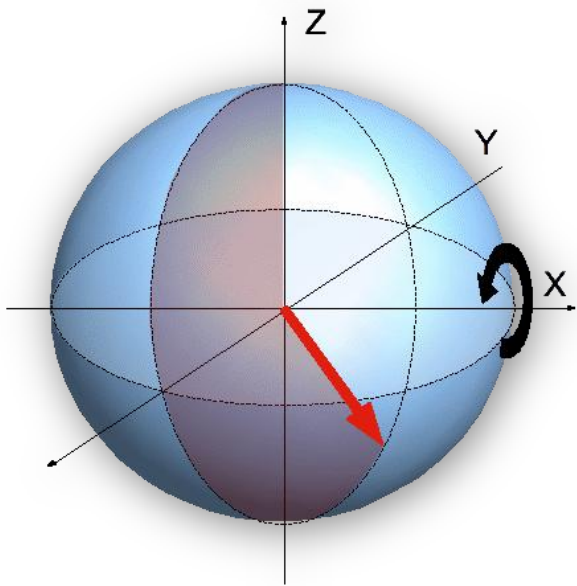
Dissipative State Prep.

“Single Qubit Gates”

$I, X, Y, Z, H, S, T,$

Telecom-style Modulation

$I(t), Q(t)$

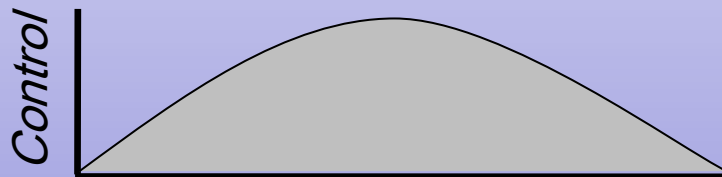
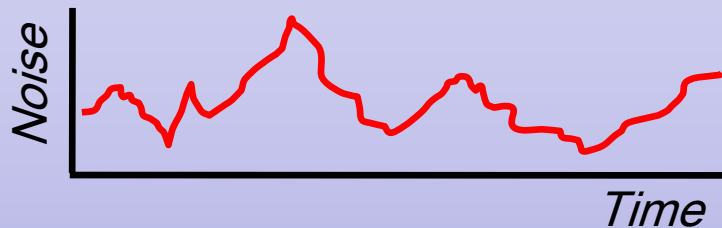


Questions: What is the influence of these techniques on control fidelity in a noisy environment? How well can we do?

Quantum Control as Noise Filtering

Requirement: Evaluate the performance of quantum control operations in the presence of *time-dependent* noise

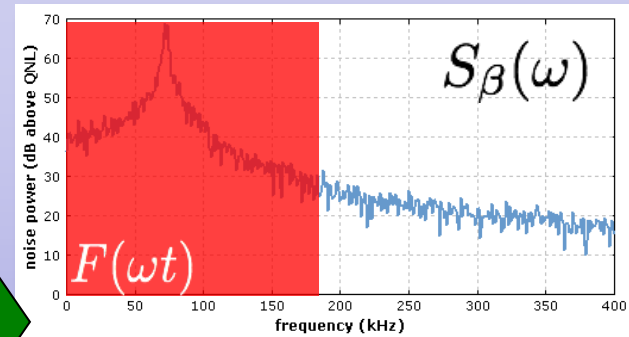
Time Domain



$$|\psi(0)\rangle \rightarrow |\psi(t)\rangle$$

Time-domain *convolution*

Fourier Domain



Coherence: $W = e^{-\chi(t)}$

$$\chi(t) = \frac{1}{\pi} \int_0^\infty S(\omega) \frac{F(\omega t)}{\omega^2} d\omega$$

Fourier-domain *product*

Kurizki *et al.*, *PRL* 87, 270405 (2001). Martinis *et al.*, *PRB* 64 094510

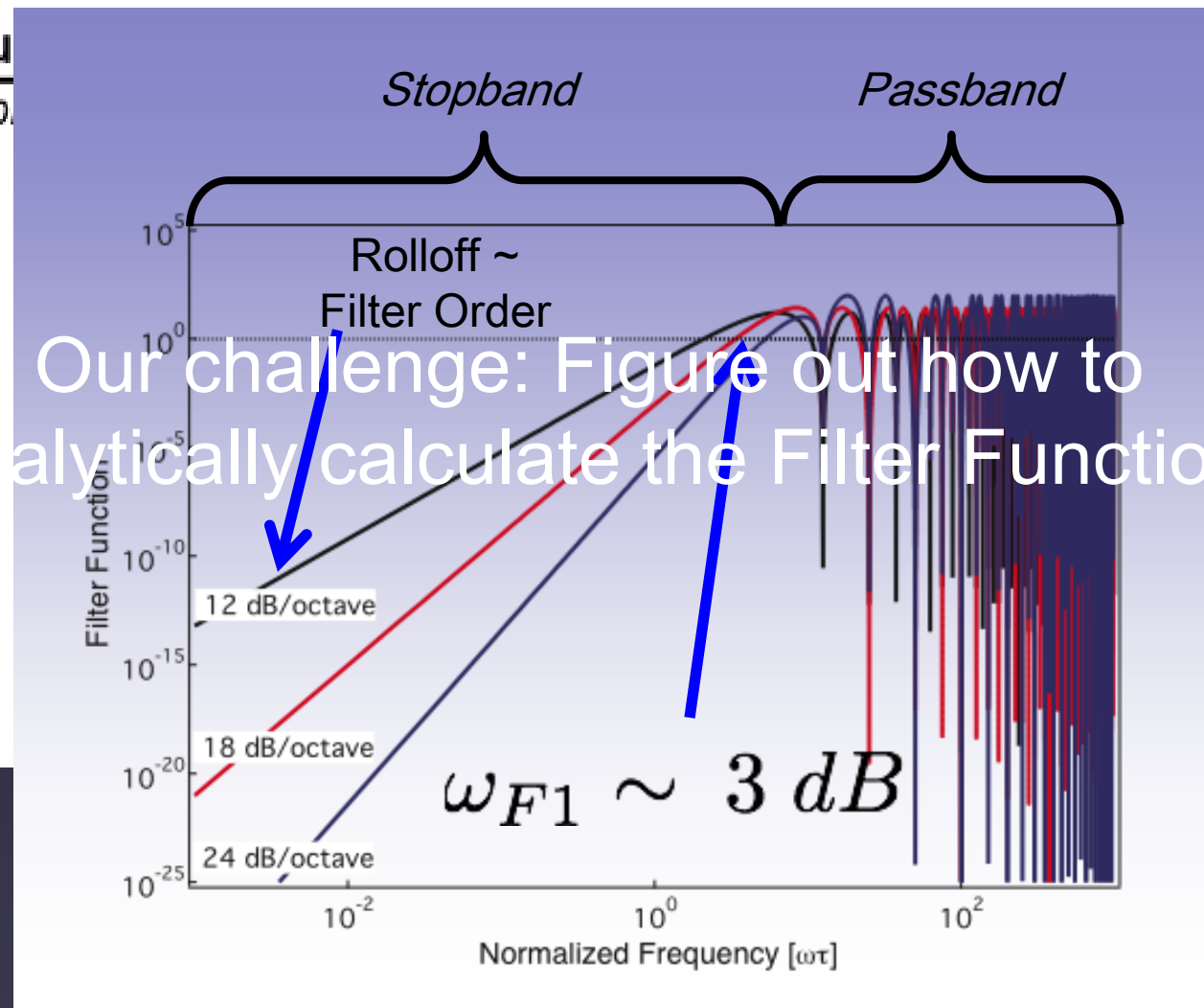
Uhrig *et al.*, *PRL* 98, 100504 (2007); Cywinski *et al.*, *PRB* 77, 174509 (2008).

MJB *et al.*, *J. Phys. B* 44, 154002 (2011). Green, Uys, MJB, *PRL* 109 020501 (2012)

The Filter Function

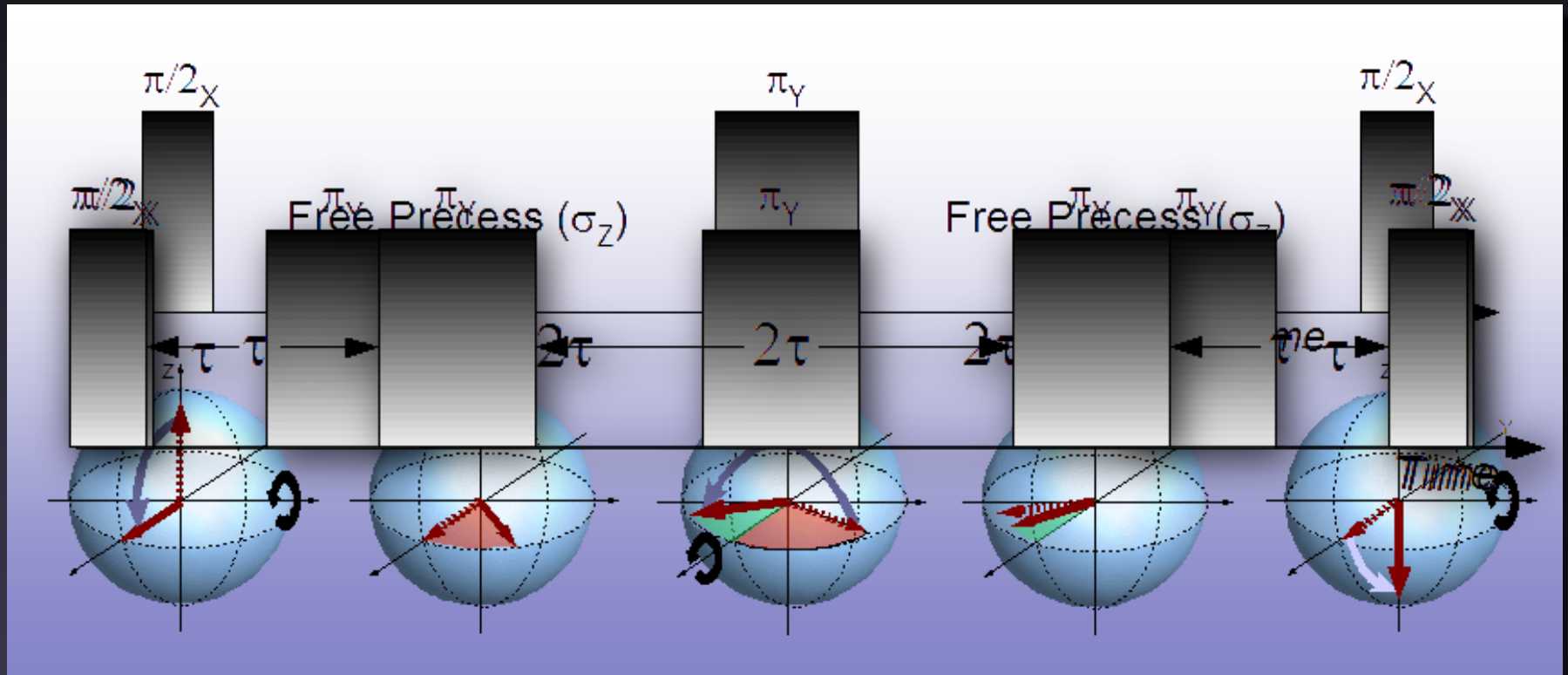
Plu
Typ.

000+



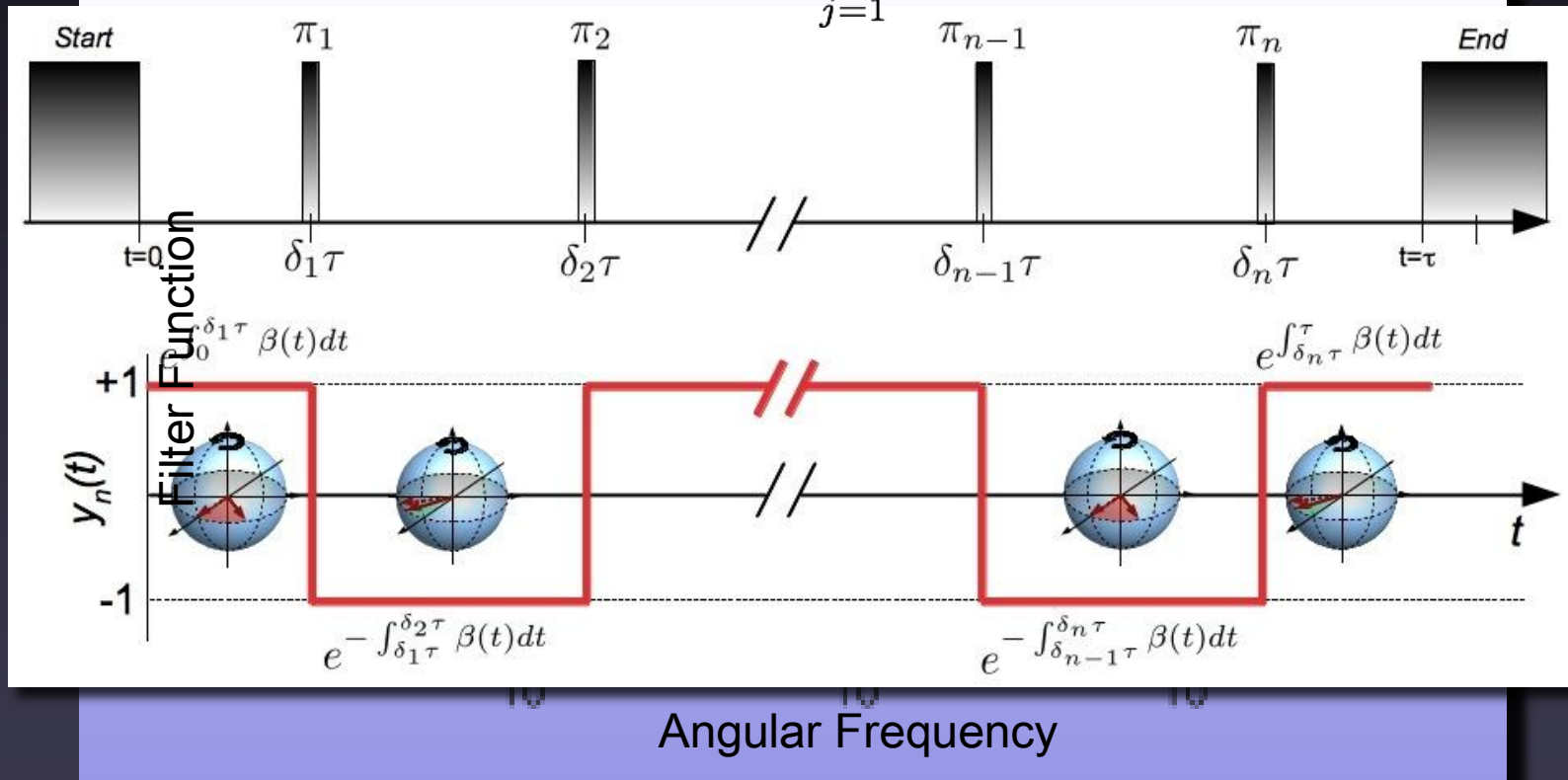
Steep = Good

Simplest Example: Dynamical Decoupling



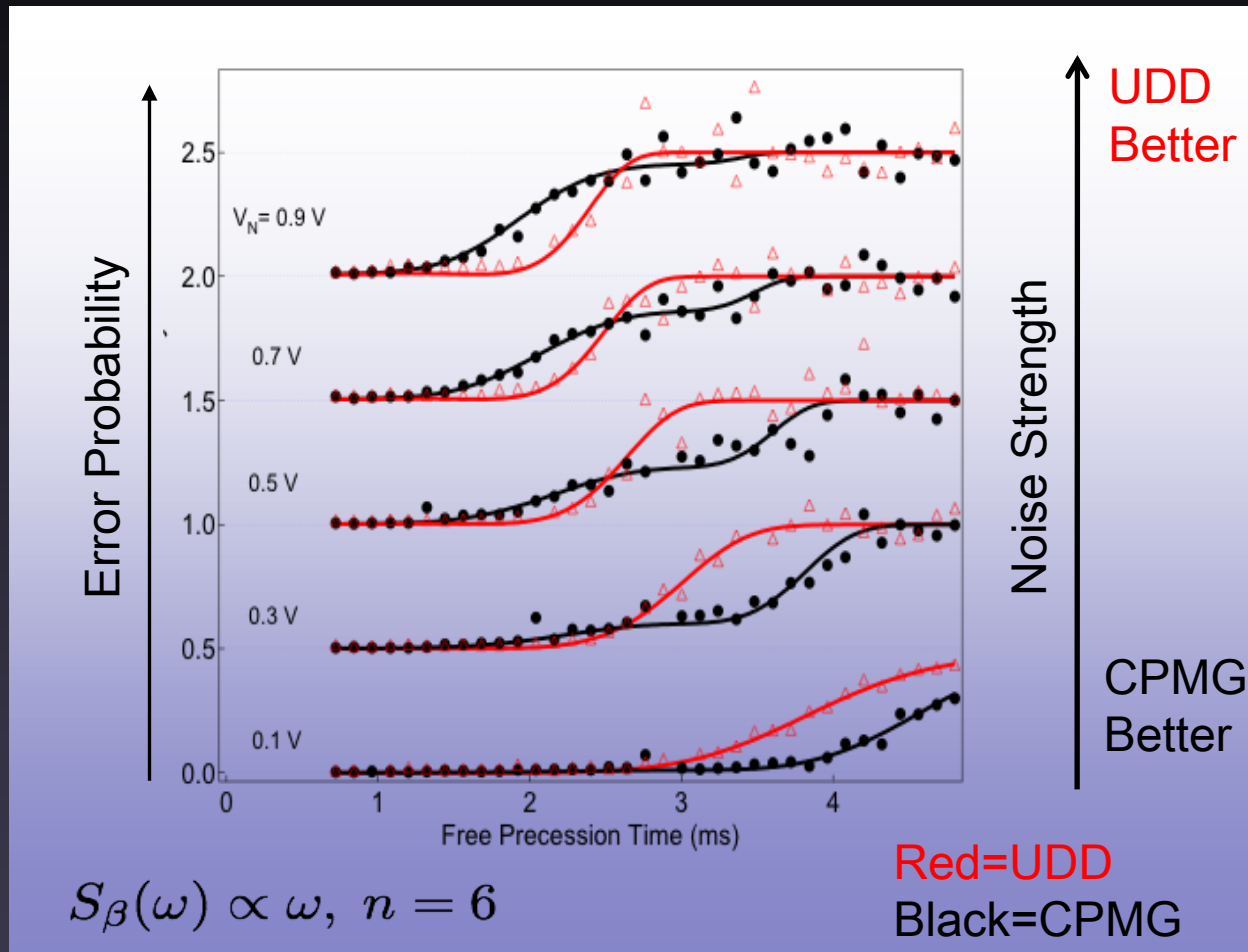
Dynamical Decoupling as Noise Filtering

$$F_n(z) = |1 + (-1)^{n+1} e^{iz} + 2 \sum_{j=1}^n (-1)^j e^{iz\delta_j} [\cos(\phi_\pi z/2)]|^2$$



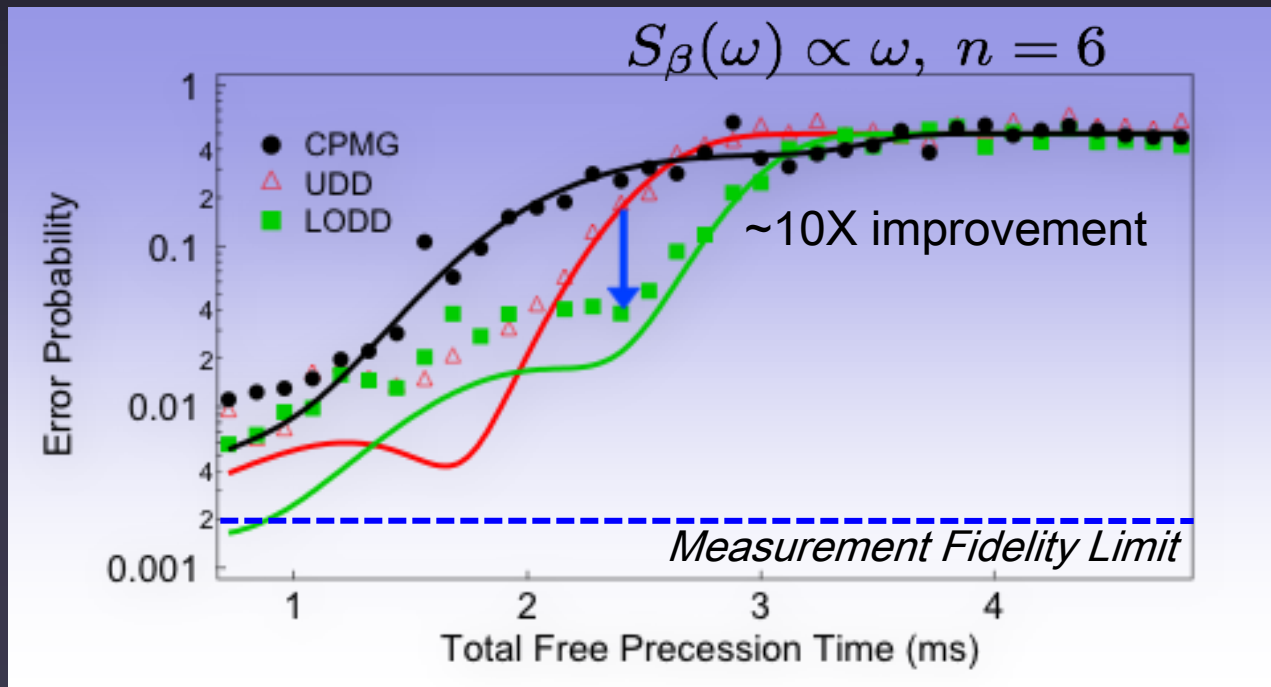
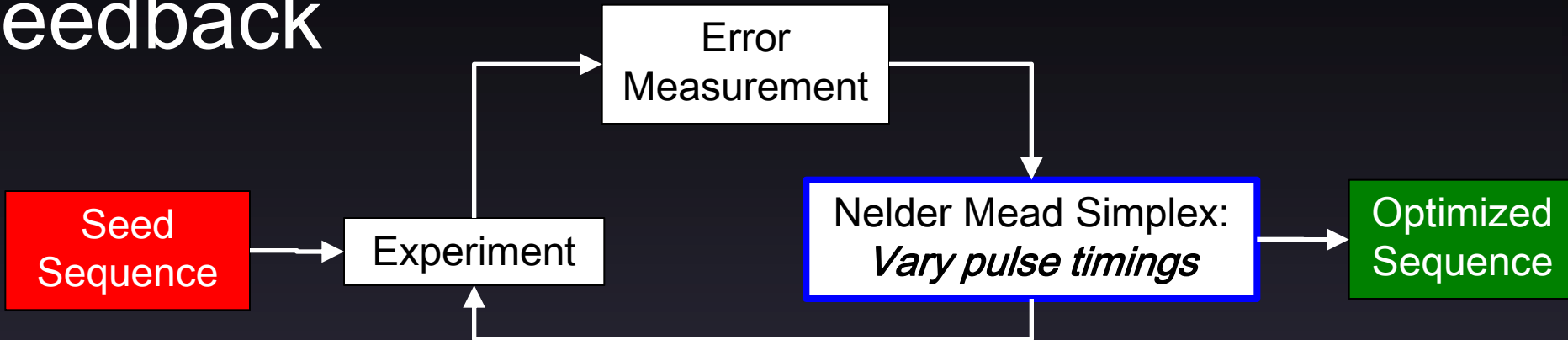
Adjust pulse timing to modify filter

FF approach is *experimentally verified*



Experiments performed with trapped ions and *Engineered Noise*

Filter optimization by autonomous feedback



Noise filtering beyond Memory

$I, X, Y, Z, H, S, T, CNOT/CPHASE$

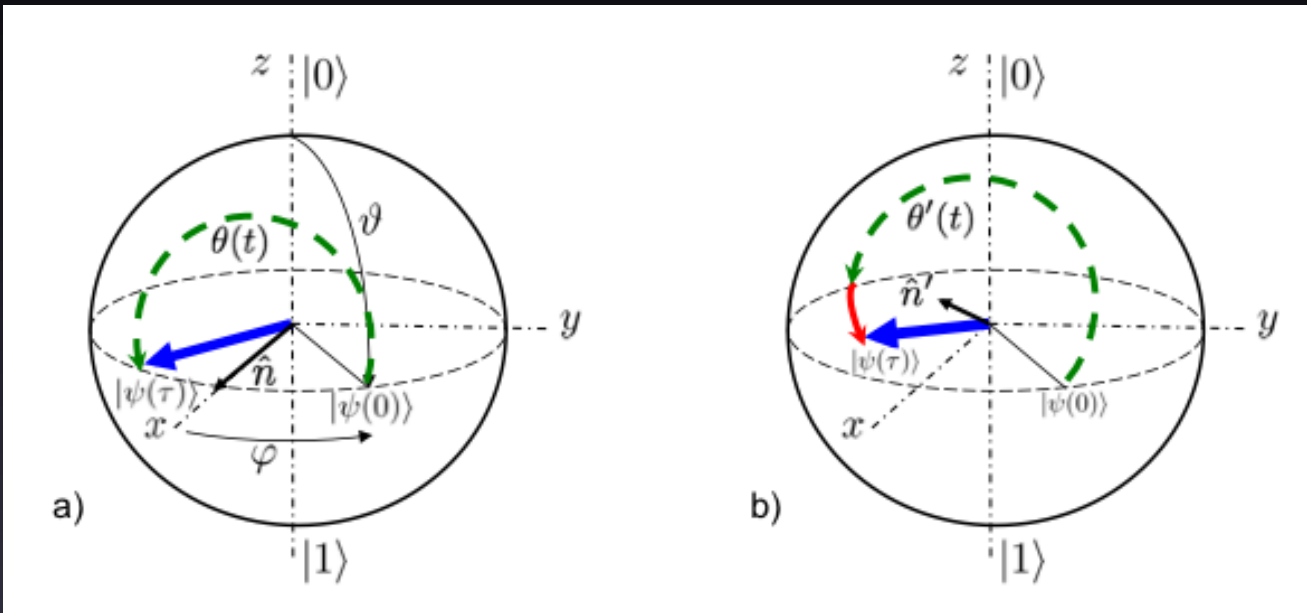
Challenge: Noncommuting control/ noise

$$H_0 \propto \beta(t)\sigma_z \quad H_c \propto \sigma_x \quad U(t) = T \exp \left(-i \int_0^\infty H(t') dt' \right)$$

$$\mathcal{F}_{av} = 1 - \sum_{n=2}^{\infty} \left\{ \frac{1}{(2\pi)^n} \sum_{i_1 \dots i_n} \int d\omega_1 \dots \int d\omega_n \mathcal{S}_{i_1 \dots i_n}(\omega_1, \dots, \omega_n) \mathcal{R}_{i_1 \dots i_n}(\omega_1, \dots, \omega_n) \right\}$$

- Treat any piecewise-constant single-qubit control protocol
- Treat the effects of universal decoherence
- Reduces error estimation from hours to milliseconds

Example: FF's for simple Pi pulses



$$\mathcal{F}_{av} = 1 - \sum_{n=2}^{\infty} \left\{ \frac{1}{(2\pi)^n} \sum_{i_1 \dots i_n} \int d\omega_1 \dots \int d\omega_n \mathcal{S}_{i_1 \dots i_n}(\omega_1, \dots, \omega_n) \mathcal{R}_{i_1 \dots i_n}(\omega_1, \dots, \omega_n) \right\}$$

Multi-axis errors from single-axis control

Fully generalized Filter Functions

$$R_{zz}^{(Prim)}(\omega) = \frac{\omega^2}{\omega^2 - \Omega^2} (e^{i\omega\tau\pi} + 1) \quad R_{zy}^{(Prim)}(\omega) = \frac{i\omega\Omega}{\omega^2 - \Omega^2} (e^{i\omega\tau\pi} + 1)$$

$$\langle \mathcal{F} \rangle \simeq 1 - \sum_i \langle a_{1,i}^2 \rangle - \left\{ \sum_i (\langle a_{2,i}^2 \rangle + 2\langle a_{1,i} a_{3,i} \rangle) - \frac{1}{3} \sum_{i,j} \langle a_{1,i}^2 a_{1,j}^2 \rangle \right\} \quad (38)$$

In the frequency domain

$$\langle \mathcal{F} \rangle = 1 - \frac{1}{4\pi} \int_0^\infty \frac{d\omega}{\omega^2} S(\omega) F_1(\omega, \tau) - \frac{1}{(4\pi)^2} \int_0^\infty \frac{d\omega}{\omega^2} S(\omega) \int_0^\infty \frac{d\omega'}{\omega'^2} S(\omega') F_2(\omega, \omega', \tau) + \dots \quad (39)$$

where

$$F_1(\omega, \tau) \equiv \sum_i |y_{1,i}(\omega, \tau)|^2 \quad (40)$$

$$F_2(\omega, \omega', \tau) \equiv \sum_i (F_{2,\rho,i}(\omega, \omega', \tau) + 2F_{2,\beta,i}(\omega, \omega', \tau)) - \frac{1}{3} \sum_{i,j} F_{2,\gamma,i,j}(\omega, \omega', \tau). \quad (41)$$

The terms making up $F_2(\omega, \omega', \tau)$, and may be written

$$F_{2,\rho,i}(\omega, \omega', \tau) \equiv \{y_{2,i}(\omega, \omega', \tau) + y_{2,i}(\omega, -\omega', \tau) + y_{2,i}(-\omega, \omega', \tau) + y_{2,i}(-\omega, -\omega', \tau)\} \quad (42)$$

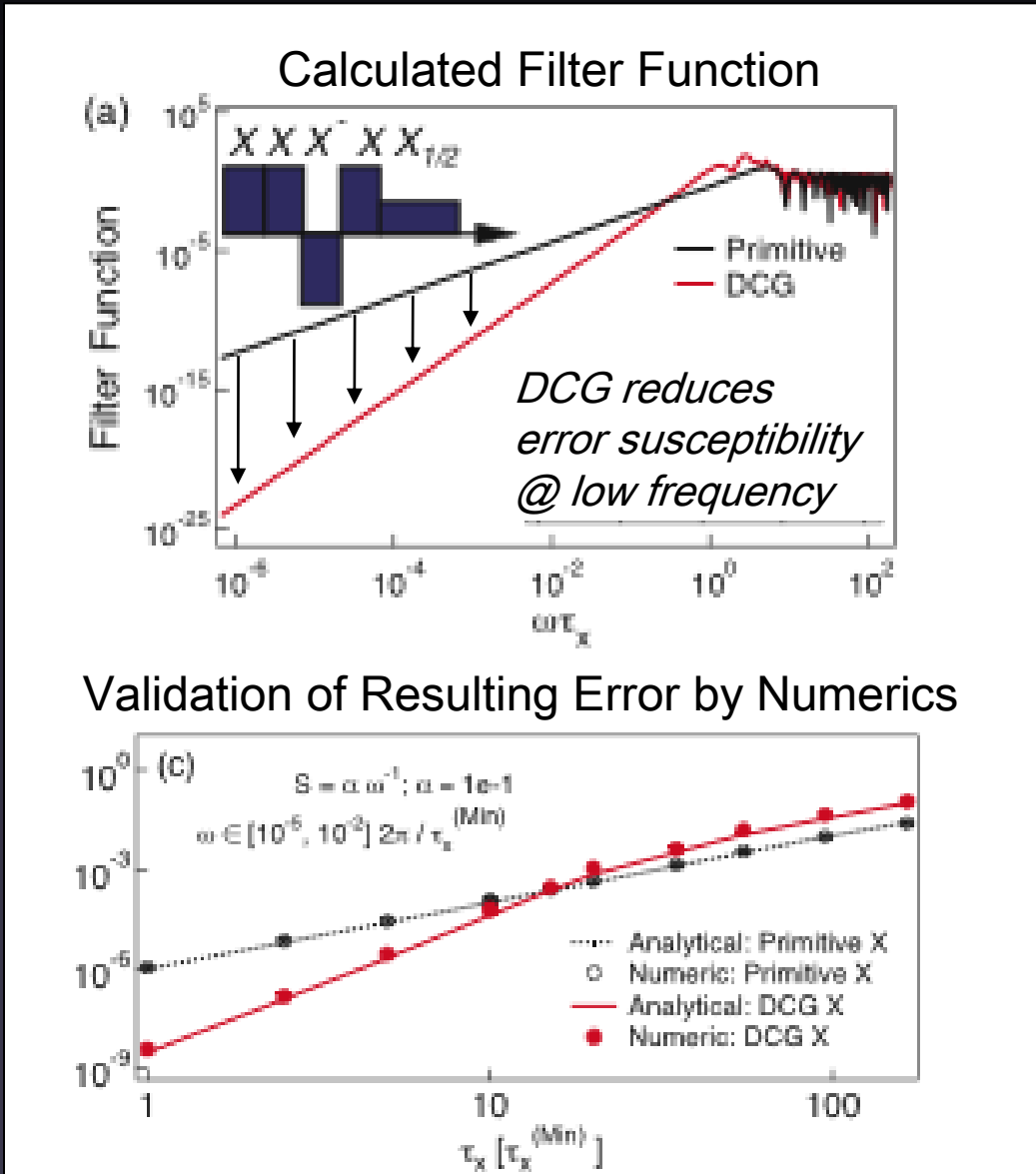
$$y_{2,i}(\omega, \omega', \tau) = \frac{\omega^2 \omega'^2}{4} \left\{ \int_0^\tau dt_4 e^{i\omega' t_4} \int_0^{t_4} dt_3 e^{-i\omega' t_3} \int_0^\tau dt_2 e^{i\omega t_2} \int_0^{t_2} dt_1 e^{-i\omega t_1} s_{2,i}(t_1, t_2) s_{2,i}(t_3, t_4) \right. \\ + \int_0^\tau dt_4 e^{i\omega' t_4} \int_0^{t_4} dt_3 e^{i\omega t_3} \int_0^\tau dt_2 e^{-i\omega' t_2} \int_0^{t_2} dt_1 e^{-i\omega t_1} s_{2,i}(t_1, t_2) s_{2,i}(t_3, t_4) \\ \left. + \int_0^\tau dt_4 e^{i\omega t_4} \int_0^{t_4} dt_3 e^{i\omega' t_3} \int_0^\tau dt_2 e^{-i\omega' t_2} \int_0^{t_2} dt_1 e^{-i\omega t_1} s_{2,i}(t_1, t_2) s_{2,i}(t_3, t_4) \right\} \quad (43)$$

$$F_{2,\beta,i}(\omega, \omega', \tau) \equiv \{y_{3,i}(\omega, \omega', \tau) + y_{3,i}(\omega, -\omega', \tau) + y_{3,i}(-\omega, \omega', \tau) + y_{3,i}(-\omega, -\omega', \tau)\} \quad (44)$$

$$y_{3,i}(\omega, \omega', \tau) = \frac{\omega^2 \omega'^2}{4} \left\{ \int_0^\tau dt_4 e^{i\omega' t_4} \int_0^\tau dt_3 e^{-i\omega' t_3} \int_0^{t_3} dt_2 e^{i\omega t_2} \int_0^{t_2} dt_1 e^{-i\omega t_1} s_{1,i}(t_4) s_{3,i}(t_1, t_2, t_3) \right. \\ + \int_0^\tau dt_4 e^{i\omega' t_4} \int_0^\tau dt_3 e^{i\omega t_3} \int_0^{t_3} dt_2 e^{-i\omega' t_2} \int_0^{t_2} dt_1 e^{-i\omega t_1} s_{1,i}(t_4) s_{3,i}(t_1, t_2, t_3) \\ \left. + \int_0^\tau dt_4 e^{i\omega t_4} \int_0^\tau dt_3 e^{i\omega' t_3} \int_0^{t_3} dt_2 e^{-i\omega' t_2} \int_0^{t_2} dt_1 e^{-i\omega t_1} s_{1,i}(t_4) s_{3,i}(t_1, t_2, t_3) \right\}$$

$$F_{2,\gamma,i,j}(\omega, \omega', \tau) \equiv |y_{1,i}(\omega, \tau)|^2 |y_{1,j}(\omega', \tau)|^2 + 2\text{Re} [y_{1,i}(\omega, \tau) y_{1,j}(\omega, \tau)^*] \text{Re} [y_{1,i}(\omega', \tau) y_{1,j}(\omega', \tau)^*]$$

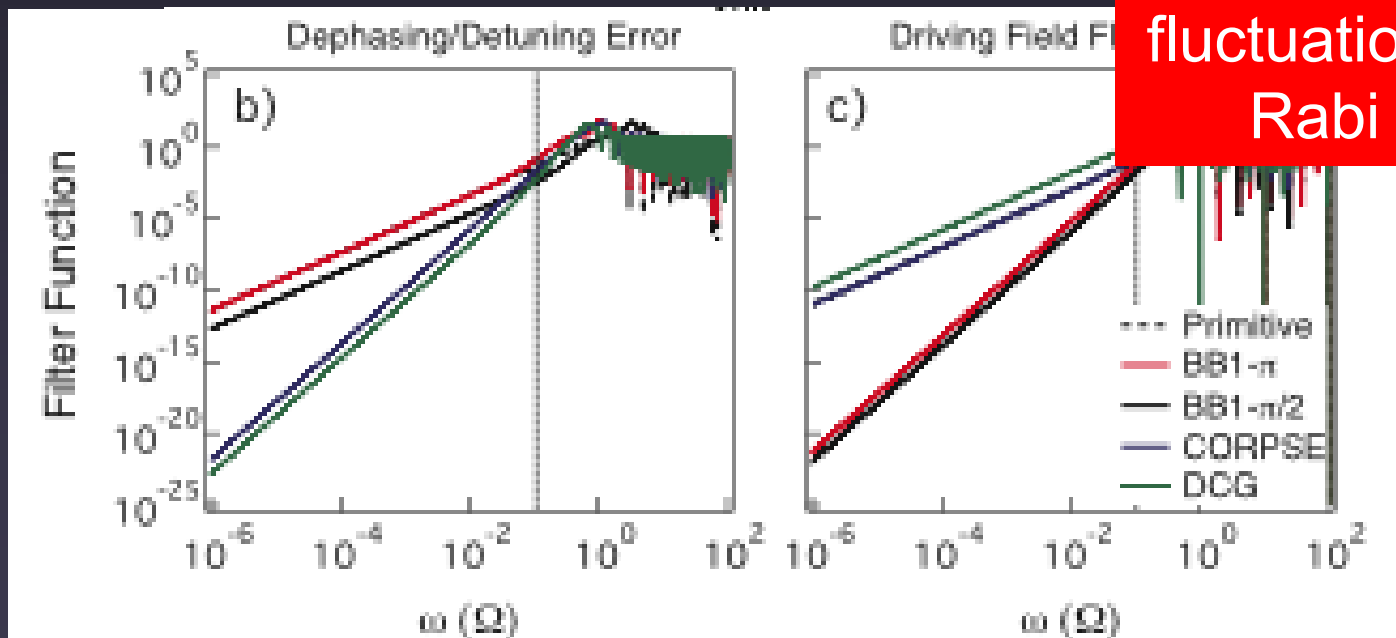
Example FF's for Corrected Gates



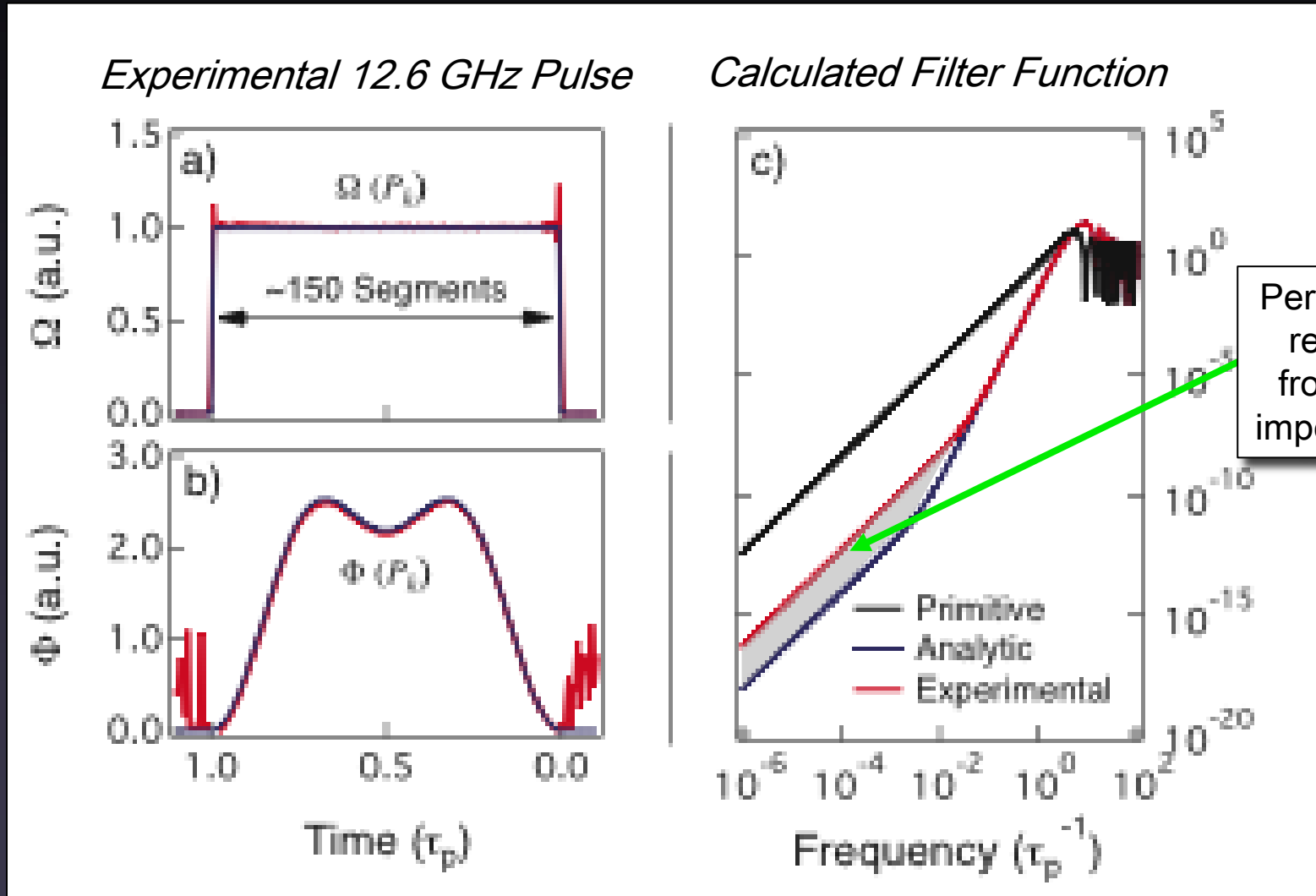
Filter Functions for Composite Pulses

- BB1: $U(\pi, \beta)U(2\pi, 3\beta)U(\pi, \beta)$
 $\beta = \cos^{-1}(-1/4)$
- CORPSE: $U(\pi/3, 0)U(5\pi/3, \pi)U(7\pi/3, 0)$
- DCG: $U(\pi, 0)U^{(1/2)}(\pi, 0)U(\pi, 0)$

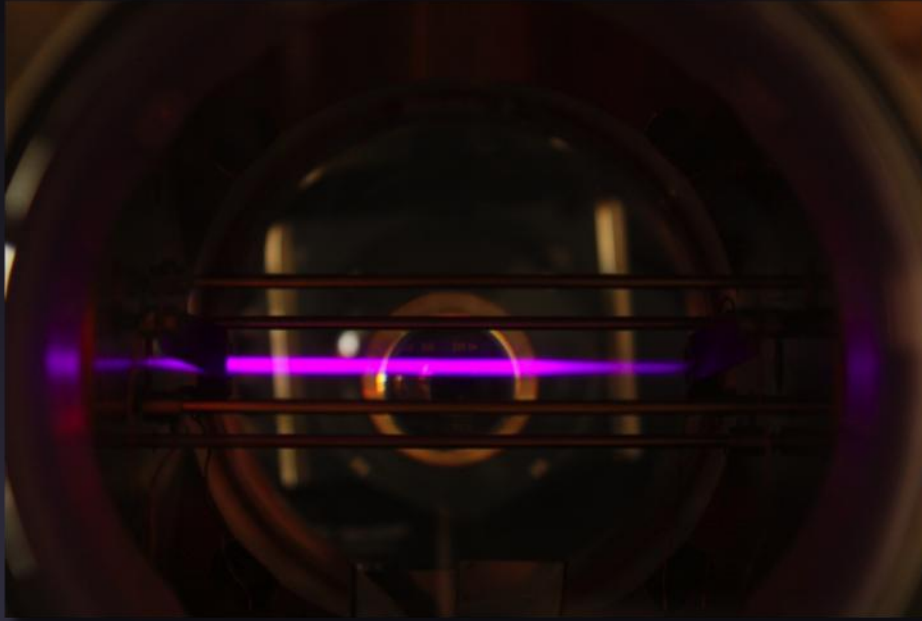
Robust to fast
fluctuations ~10%
Rabi Rate



Experimental control imperfections



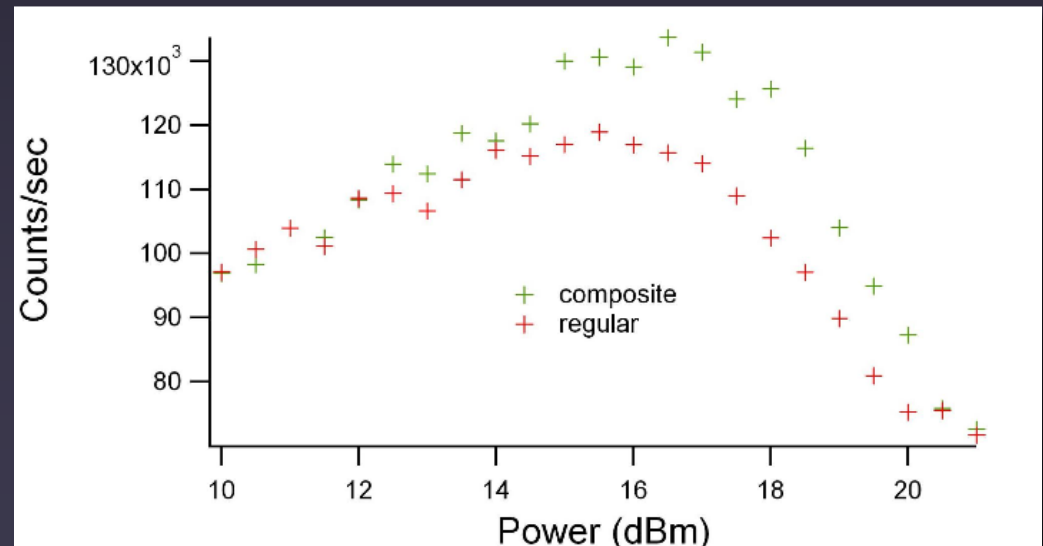
Currently studying in the lab...



- 12.6 GHz $^{171}\text{Yb}^+$ qubit
- Vector source
- Engineered noise bath

Simple composite pulse

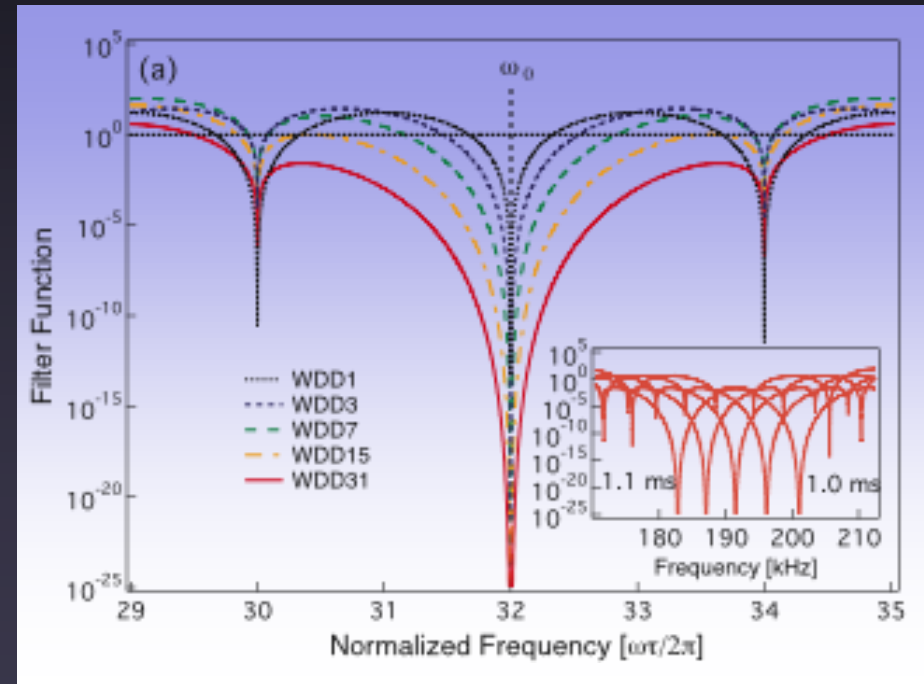
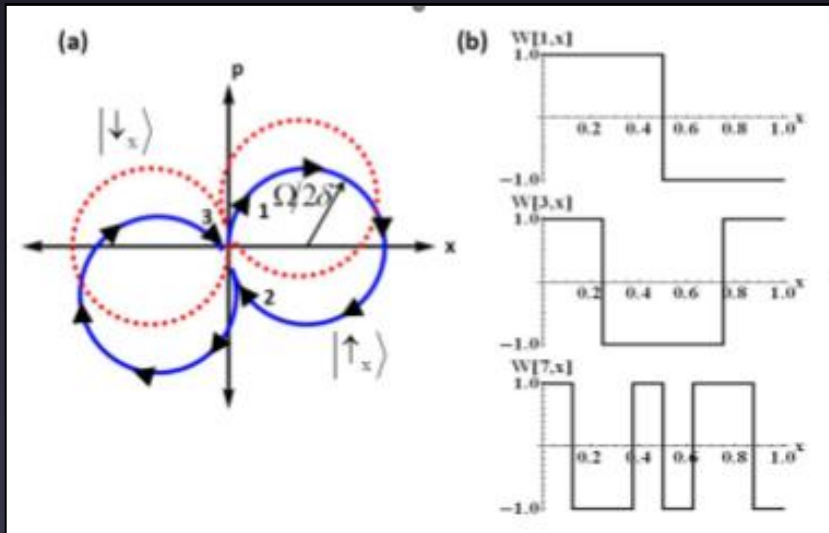
$$\frac{\pi}{2}_x - \pi_y - \frac{\pi}{2}_x$$



Moving to multiqubit gates

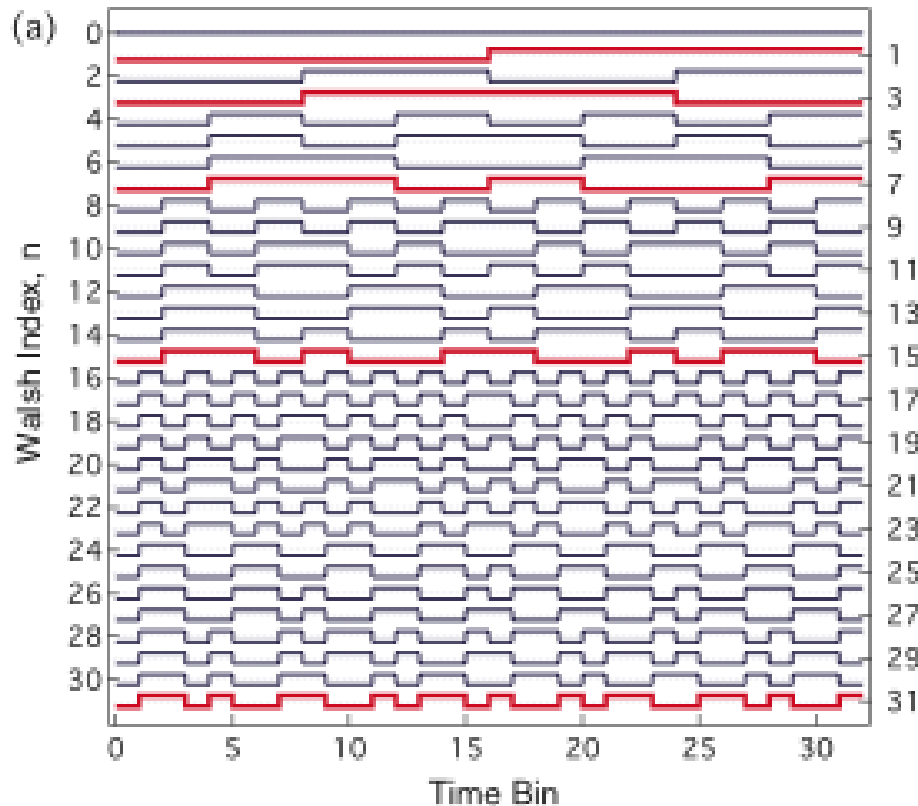
I, X, Y, Z, H, S, T, CNOT/CPHASE

MS Gates with Laser Detuning & Amplitude Errors

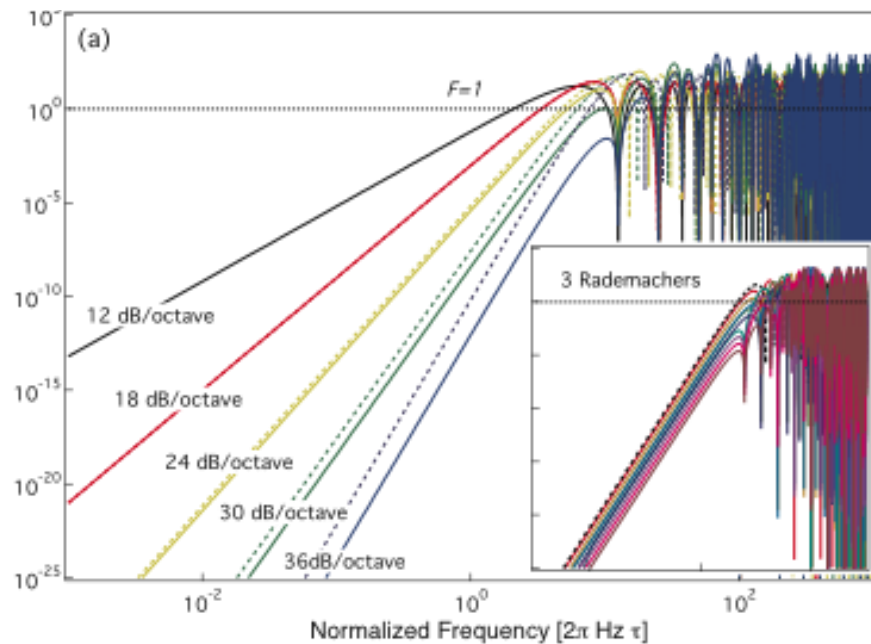


$$|\overline{\alpha(\tau)}|^2 = \frac{\Omega^2}{4} \int_{-\infty}^{\infty} \frac{F_p((\delta + \Delta)\tau)}{(\delta + \Delta)^2} P(\Delta) d\Delta$$

Our basis: Walsh functions



Error suppression determined by Hamming weight of n



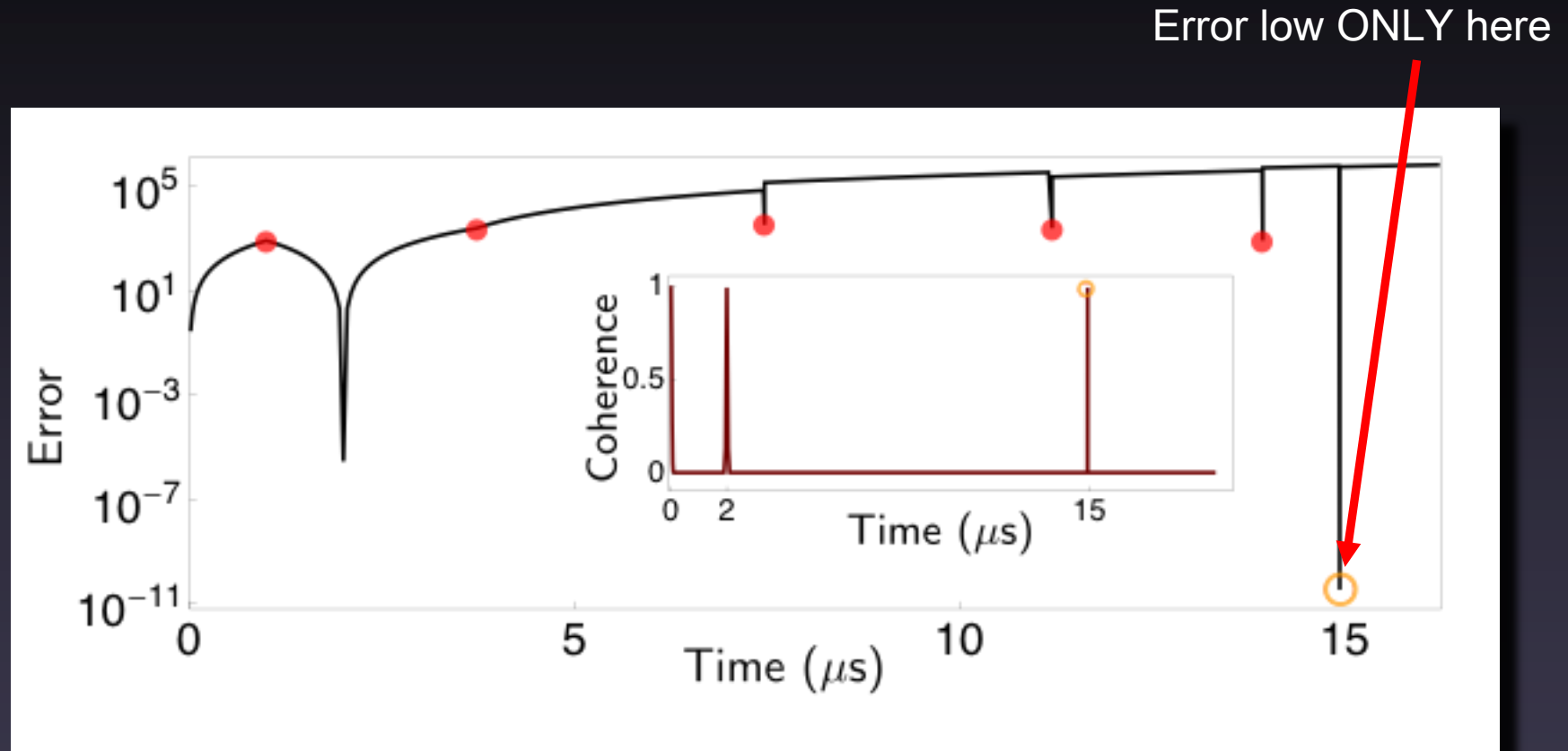
Structure gives interesting implications at the system level

Noise filtering at the system level

Designing a practical long-time quantum memory – considerations:

1. Perturbative DD (increasing N) fails for long-time storage, by requiring the unphysical constraint $\tau_{\min} \rightarrow 0$
2. Numerical optimization becomes impractical in long time (large- N) limit
3. Access to quantum state required throughout memory time, with minimum latency

Latency is a killer

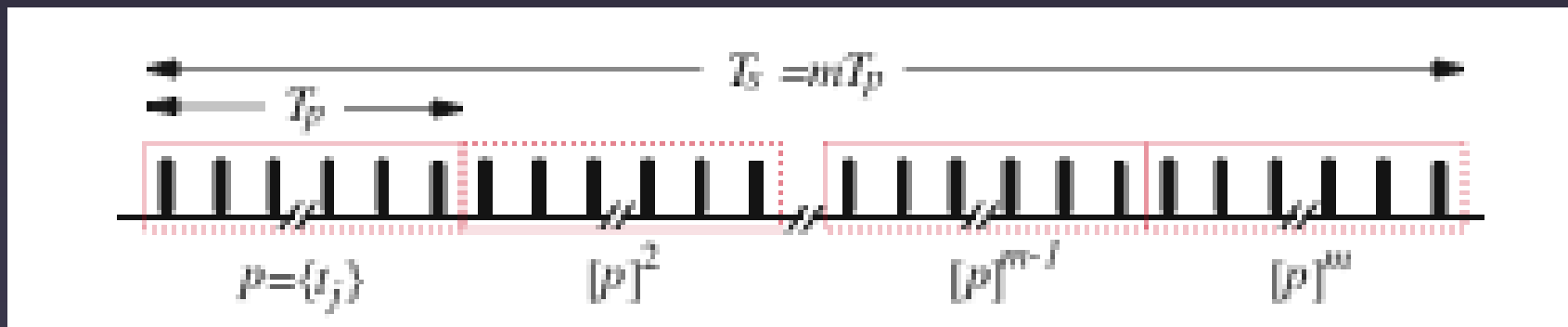


Optimizing the filter directly fails to address third consideration

Error calculated for UDD and assuming noise common for singlet-triplet qubit

Systematic approach: Repetition

- Take a short, high-order “base sequence” and repeat as needed.
- Interrupt latency is limited to integer multiples of the base sequence length, not the total storage time
- Analytically evaluate the effect of repetition in the long-storage-time limit



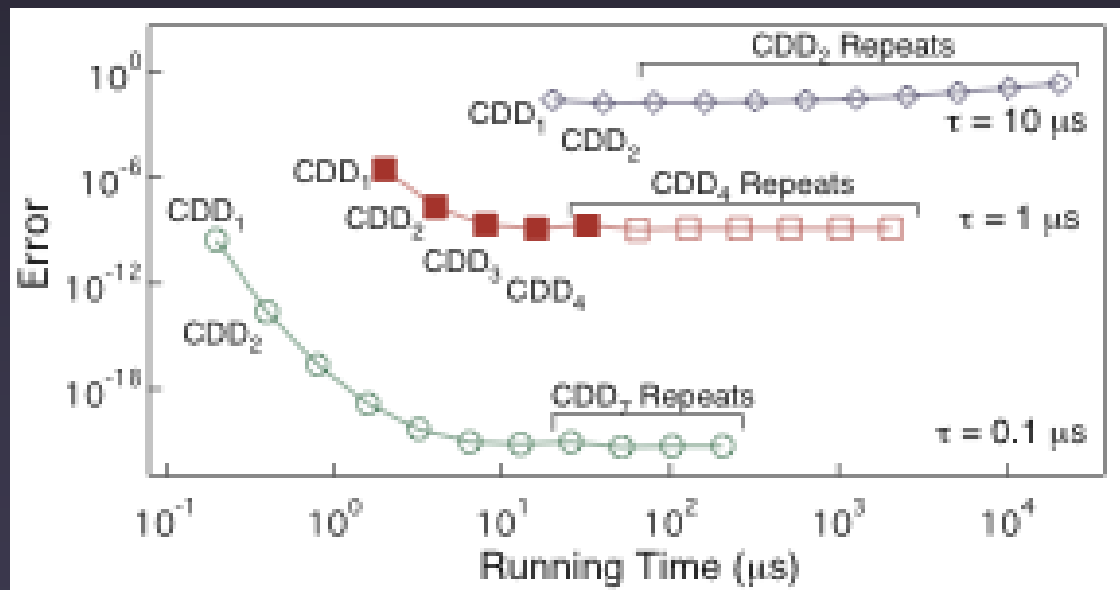
Repeated application of noise filter

$$\chi_p = \int_0^\infty \frac{S(\omega)}{2\pi\omega^2} F_p(\omega) d\omega \xrightarrow[m \text{ times}]{\text{Repeat}} \chi_{[p]^m} = \int_0^\infty \frac{S(\omega)}{2\pi\omega^2} \frac{\sin^2(m\omega T_p/2)}{\sin^2(\omega T_p/2)} F_p(\omega) d\omega$$

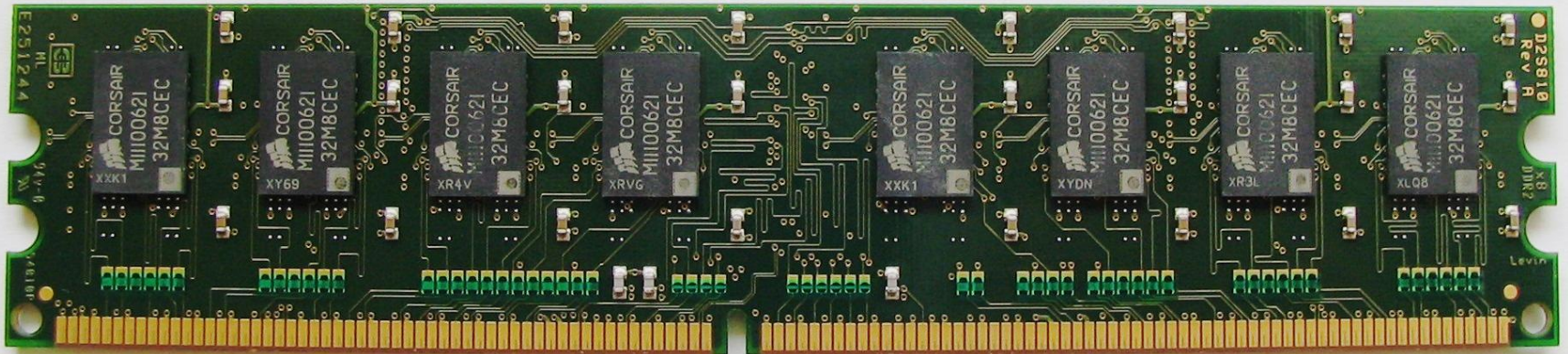
$$\lim_{m \rightarrow \infty} \chi_{[p]^m} \equiv \chi_{[p]^\infty} = \int_0^{\omega_c} \frac{S(\omega)}{4\pi\omega^2} \frac{F_p(\omega)}{\sin^2(\omega T_p/2)} d\omega$$

$$\chi_{[p]^m} \leq 2\chi_{[p]^\infty}$$

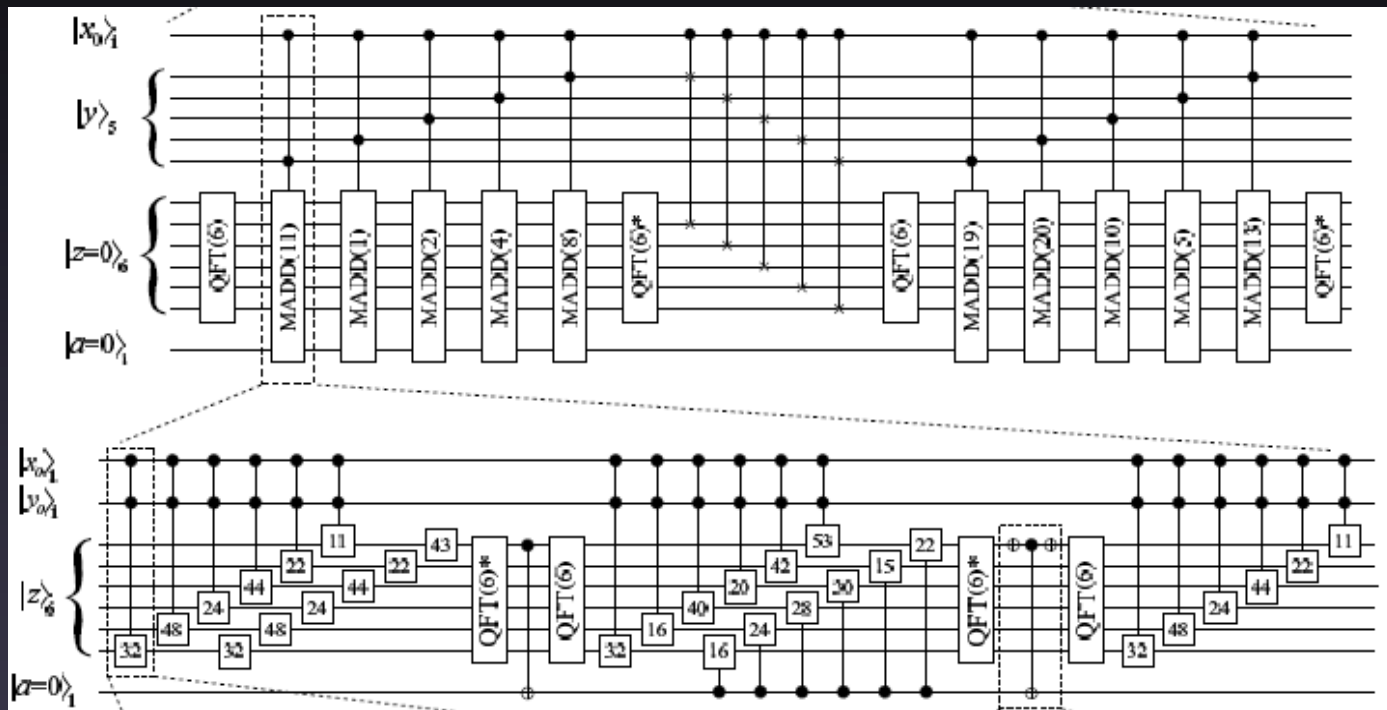
If integral converges, coherence bounded at long times



Similar effects already in use



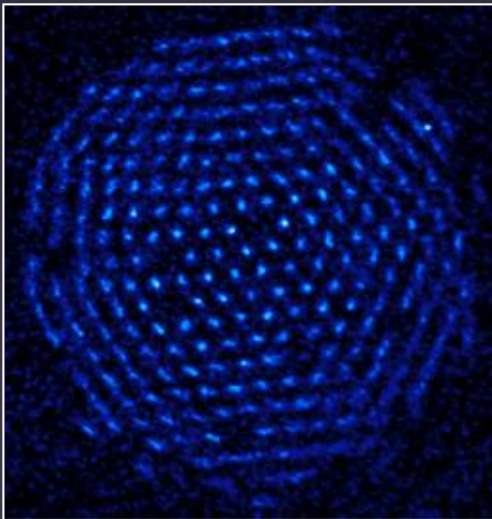
Future Possibilities: Algorithmic Design(?)



*Exploit echo-like effects in algorithmic design
Can produce filter functions for algorithms, blocks, etc.*

Summary

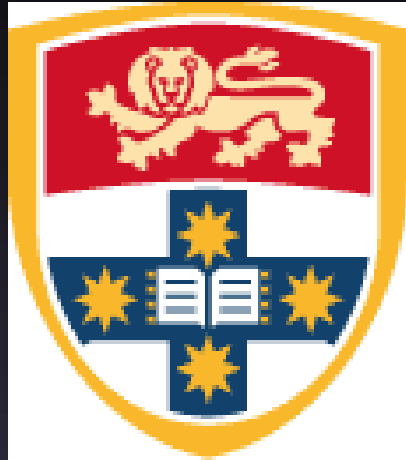
- Quantum control as noise filtering
 - New analytical approach based on noise filters
 - Filtering *during* gate operations
 - Approaches compatible with large-scale systems
- We're bringing a “30,000 foot” viewpoint to these analyses.



Other stuff:

Quantum Simulation of the
variable-range 2D Ising model
on a triangular lattice with N
 ~ 300 qubits

Acknowledgements & Collaborators



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Alex Soare



Lorenza Viola
Kaveh Khodjasteh



Hermann Uys



John Bollinger
Joe Britton
Brian Sawyer
David Wineland

PhD opportunities and postdoctoral fellowships available in my Group

Visitors Welcome!

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