

The Kavli Institute for Theoretical Physics University of California, Santa Barbara

Control of Complex Quantum Systems

February 19, 2013

Advances in Dynamical Quantum Error Suppression

Lorenza Viola Dept. Physics & Astronomy Dartmouth College







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'Quantum Firmware Collaboration'



Michael J. Biercuk U. Sydney



Amir Yacoby Harvard

[Hendrik Bluhm U. Aachen] Dynamical Quantum Error Suppression = Non-dissipative QEC: Open-loop Hamiltonian engineering based on unitary control operations.

<u>Simplest setting</u>: Multipulse decoherence control for quantum memory \Rightarrow Dynamical Decoupling LV & Lloyd, PRA <u>Key principle</u>: Time-scale separation \Rightarrow Coherent averaging of interactions Paradigmatic example: Spin echo Effective time-reversal Hahn 1950. t = 0b) $t = \tau^$ c) t = t

Dynamical Quantum Error Suppression = Non-dissipative QEC: Open-loop Hamiltonian engineering based on unitary control operations.

Simplest setting: Multipulse decoherence control for quantum memory \Rightarrow Dynamical Decoupling LV & Lloyd, PRA <u>Key principle</u>: Time-scale separation \Rightarrow Coherent averaging of interactions Paradigmatic example: Spin echo Effective time-reversal Hahn 1950. t = 0Key features: Non-Markovian open quantum system dynamics (1) Error component may include coupling to *quantum* bath **b**) Error suppression is enforced *perturbatively* $t = \tau^-$ (2) $\frac{\mathbf{L}_{control}}{\mathbf{T}_{c}} \sim \omega_{c} \mathbf{T}_{control} \qquad small \text{ parameter}$ (3) Error suppression/control synthesis are achieved *without* c) requiring quantitative knowledge of error sources $t = \tau$ [basic difference wrto optimal control theory approaches]

Control-theoretic setting



• Target system exposed to noise due to a *quantum or classical* environment /bath

 $H = \begin{bmatrix} H_{S,g} + H_{S,err} \end{bmatrix} \otimes I_B + I_B \otimes H_B + H_{SB} \sum_a S_a \otimes B_a$

I System operators $\{S_a\}$ form Hermitian operator basis, with $S_0 = I_S$ and $S_{a \neq 0}$ traceless.

Bath operators $\{B_a\}$ are bounded but otherwise arbitrary [possibly *unknown*]. Classical bath limit [stochastic field] is formally recovered for $B_a = I_s$ and $B_0 = 0$.

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• Environment B is *uncontrollable*. Controller acts on *system* only,

$$H_{tot}(t) \equiv H + H_{ctrt}(t), \qquad H_{ctrl,0}(t) = \sum_{m} (H_{m} \otimes I_{B}) h_{m}(t) \quad \leftarrow \quad \text{Control inputs}$$
$$U_{0}(t) = Texp\{-i \int_{0}^{t} ds \left[H_{ctrl,0}(s) + H_{S,g}\right]\} \quad \leftarrow \quad \text{'Toggling frame'}$$
propagator

□ Universal control on *S* may or may not require a non-zero pure-system [*drift*] Hamiltonian. □ Control capabilities are typically restricted, and themselves *noisy* [systematic + random].

DQES: Overview and challenges

- DQES theory has diversified into a [still growing...] number of related directions Broadly categorized based on control objective:
 - Arbitrary state preservation \Rightarrow DQES theory for quantum memory
 - ✓ Pulsed dynamical decoupling 'Bang-bang' limit/instantaneous pulses
 - ✓ Pulsed dynamical decoupling Bounded control/'fat' pulses
 - Continuous time-dependent modulation



- Quantum gate synthesis \Rightarrow DQES theory for quantum computation
 - ✓ Hybrid DD-QC schemes BB resources w or w/o encoding
- ✓ Dynamically corrected gates Bounded control only
- ✓ Optimal control/convex optimization approaches
- DQES has been validated in a variety of proof-of-principle experiments in different systems Emerging method of choice for resource-efficient physical-layer decoherence control...

Recent DD/DCG experiments [partial list...]

:

YEAR	PROTOCOL	QUBIT SYSTEM	NOISE
2009	CPMG, UDD, LODD	Be ⁺ trapped ion Eng	ineered phase noise
	CPMG, UDD	ESR in crystals	Natural dephasing
	XY4	Polarization	qubit Engineered depolarization
2010	CPMG, UDD	<i>Atomic ensemble</i>	<i>Collisional dephasing</i>
	CPMG, UDD, CDD	Double QD	Spin-bath dephasing
	CPMG, UDD, PDD	NV-center	Spin-bath dephasing/pulse errors
	CPMG, XY4	NV-center	Spin-bath dephasing
	CPMG, XY4, CDD	ESR in Si:P	Spin-bath dephasing/pulse err
2011	Hahn, CPMG	<i>Double QD</i>	Spin-bath dephasing
	Hahn, CPMG	NV-centers	Spin-bath dephasing
	CPMG, UDD	Ca ⁺ trappedions	Natural dephasing
	CPMG, XY4, CDD	Solid-state NMR	Spin-bath dephasing
	CPMG, UDD, PDD	Flux qubit	Natural phase noise
2012	CPMG	<i>Rare-earth crystal</i>	Spin-bath dephasing
	Hahn, XY4	ESR in Si:P	Spin-bath/defect dephasin
	DCGs	Be trapped ion	Laser-frequency jitter

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- DQES has been validated in a variety of proof-of-principle experiments in different systems -Emerging method of choice for resource-efficient physical-layer decoherence control...
- Going *beyond* proof-of principle [inevitably] entails more 'complex' control scenarios \Rightarrow

Key challenge: To systematically address and incorporate practical [system and control] constraints.

Sample Problem 1: High-fidelity Long-time Low-latency Quantum Memory

Khodjasteh, Sastrawan, Hayes, Green, Biercuk & LV, *Nature Commun.*, submitted.

Setting and control objective

• Simplest DD scenario: Single purely-dephasing qubit controlled by perfect π pulses

- DD sequence of duration T_p specified in terms of pulse pattern $p = \{t_j\}, j = 1, ..., n$
- I Qubit coherence decays as $e^{-\chi_p}$, with DD error at $t = T_p$ determined by spectral overlap

$$\chi_p = \int_0^\infty \frac{S(\omega)}{2\pi\omega^2} F_p(\omega) d\,\omega$$

$$\begin{array}{lll} & \text{Power spectrum} & \times & \text{Filter Function (FF)} \\ S\left(\omega\right) \propto \omega^{s} f\left(\omega, \omega_{c}\right) & F_{p}(\omega) \propto (\omega \tau)^{2(\alpha_{p}+1)} \\ & & \tau \equiv \min(t_{j+1}-t_{j}) & \text{Minimum 'switching time'} \end{array}$$

The larger the order of error suppression α_p , the higher the degree of error cancellation as long as $\omega_c \tau$ is perturbatively small.

Uhrig, PRL **98** 2007; Cywinski&al, PRB **77** (2008; Khodjasteh, Erdelyi & LV, PRA **83** (2011).

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• <u>Goal</u>: Achieve high fidelity over desired storage time $T_s \Rightarrow$ Straightforward *in principle*... I Simply use high-order DD sequence with $T_s = T_p$, e.g. Uhrig $DD \equiv t_1 = O(T_p/n^2)$

Quantum memory requirements

- In *practical* quantum-memory applications, high fidelity should be delivered while
 - allowing arbitrarily long storage time T_s ; (1)
 - (2)
 - minimizing latency for information retrieval; operating under technological [timing and sequencing] control limitations.
- Interconnected issues to address:
 - □ Perturbative DD (CDD, UDD...) is *not viable* if min switching time is constrained for fixed $\tau > 0$, a max storage time exists, beyond which increasing α_p no longer helps...

 \Box Numerical DD (BADD...) is *not viable* – search complexity grows exponentially with T_{s} ...

 \Box Mid-sequence interruptions are *not permitted* – min accesslatency is set by T_p ...



• <u>Strategy</u>: Periodically repeat a high-order DD sequence

$$\chi_{[p]^{n}} = \int_{0}^{\infty} \frac{S(\omega)}{2\pi\omega^{2}} \frac{\sin^{2}(m\omega T_{p}/2)}{\sin^{2}(\omega T_{p}/2)} F_{p}(\omega) d\omega$$
Long-time coherence determined by α_{p} , s ,
and high-frequency contributions at
'resonating frequencies' $\omega_{res} \equiv k \ 2\pi/mT_{p}$.
Assume a hard spectral cutoff, then
 $\chi_{[p]^{n}} = \int_{0}^{\omega_{c}} \frac{S(\omega)}{4\pi\omega^{2}} \frac{F_{p}(\omega)}{\sin^{2}(\omega T_{p}/2)} d\omega$

$$\int_{0}^{\omega_{c}} \frac{F_{p}(\omega)}{\sin^{2}(\omega T_{p}/2)} d\omega$$

$$\int_{0}^{\omega_{c}} \frac{S(\omega)}{10^{-10}} \frac{F_{p}(\omega)}{10^{-10}} d\omega$$

$$\int_{0}^{\omega_{c}} \frac{S(\omega)}{10^{-2}} \frac{F_{p}(\omega)}{10^{-10}} d\omega$$

• Strategy: Periodically repeat a high-order DD sequence



• A *coherence plateau* may be engineered by judicious selection of a base sequence:

$$s + 2\alpha_p > 1, \quad \omega_c T_p < 2\pi$$

I Guaranteed high fidelity throughout long storage times, with latency capped at $T_p \ll T_s$.

Quantum memory via repetition: Results

• A direct search up to $t = T_s$ is viable by restricting to *digital* DD sequences in the 'Walsh family' I Minimize *sequencing complexity*. Number of Walsh DD sequences: $(1/2)T_s/\tau$ vs. 2^{Ts/ τ}

Hayes, Khodjasteh, LV & Biercuk, PRA 84 (2011).



A periodic sequence structure emerges *naturally* for sufficiently long storage time.

Realistic effects: Pulse errors and soft cutoffs

• In reality, pulses are imperfect, noise need not have a hard cutoff nor be purely dephasing... A coherence plateau with finite yet exceptionally long duration may still be engineered.

Delta Pulse-length errors may be included using *multi-axis FF formalism*. New plateau conditions:

$$s + 2\alpha_p > 1, \quad s + 2\alpha_{pul} > 1, \quad \omega_c T_p < 2\pi$$

Coherence plateau can be restored by replacing 'primitive' with 'error-corrected' pulses. Storage times in excess of 1s ($\approx T_1$) at plateauerror rates of 10⁹ with realistic noise spectrum



Sample Problem 2: Automated Dynamically Corrected Quantum Gates

Khodjasteh, Bluhm & LV, Phys. Rev. A 86, 042329 (2012).

Setting and control objective

• <u>Goal</u>: To suppress evolution due to unwanted Hamiltonians, $H_{err} = H_{S,err} + H_B + H_{SB} + H_{ctrl,err}$ I Intended evolution \Rightarrow Ideal gate propagator over duration *T*:

$$U^{ideal}(T) = U_0(T) \otimes \boldsymbol{I}_B \equiv \boldsymbol{Q} \otimes \boldsymbol{I}_B = Texp\left\{-i \int_0^T ds \left[H_{ctrl,0}(s) + H_{s,g}\right] \otimes \boldsymbol{I}_B\right\}$$

 \square Actual evolution \Rightarrow Total gate propagator over duration *T*:

$$U^{actual}(T) = Texp\{-i\int_{0}^{T} ds \left[H_{ctrl}(s) + H_{S,g} + H_{err}\right]\} \equiv Q \exp(-iE_{Q[T]})$$
$$\exp(-iE_{Q[T]}) = Texp\{-i\int_{0}^{T} ds \left[U_{0}(s)^{\dagger}H_{err}U_{0}(s)\right]\}$$
Error action operator

Setting and control objective

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$$\exp(-iE_{Q[T]}) = Texp\{-i\int_{0}^{T} ds \left[U_{0}(s)^{\dagger}H_{err}U_{0}(s)\right]\}$$

Error action operator

• <u>Fact:</u> The norm of the error action operator 'modulo pure-bath terms' upper-bounds the distance [fidelity loss] between the intended and the actual system evolution:

$$mod_{B}(E) \equiv E - \frac{I_{S}}{d_{S}} \otimes trace_{S}(E)$$

$$\text{Lidar, Zanardi & Khodjasteh, PRA 78 2008
Khodjasteh & LV, PRL 102 2009
$$1 - f_{Uhlman}(T) \leq \left\| \rho_{S}^{ideal}(T) - \rho_{S}^{actual}(T) \right\|_{1} \leq \left\| mod_{B}(E_{Q[T]}) \right\|_{op} \equiv \text{EPG}$$$$

I Fidelity loss in DQES is reduced by *minimizing EPG*.

DCG synthesis \Leftrightarrow Seek control modulation such that effect of H_{err} is perturbatively canceled.

• System assumptions: Driftless - System Hamiltonian is zero/not needed for complete control,

$$H_{S,g} = 0, H_S \equiv H_{S,err} \Rightarrow \exp(-iE_{Q[T]}) = Texp\{-i\int_0^T ds \left[U_0(s)^{\dagger}H_{err}U_0(s)\right]\}$$
$$U_0(t) = Texp\{-i\int_0^t ds \ H_{ctrl,0}(s)\}$$

• <u>Control assumptions</u>: Access to universal set of 'primitive' control Hamiltonians – e.g. $\begin{cases} h_x(t)\sigma_x^{(i)}, h_y(t)\sigma_y^{(i)}, h_{zz}(t)\sigma_z^{(i)} \otimes \sigma_z^{(j)} \end{cases}, \quad i, j=1,...,N, \qquad \text{subject to} \end{cases}$

(C1) Finite-power and bandwidth constraints - *Bounded* amplitude, fixed *minimum* gate duration
 (C2) Perfect control - Bath coupling is the *only* error source

(C3) Stretchable control profiles - Same primitive gate achievable with different 'speeds'



Stretching gives controllable relationship between EPGs of different gat

Analytical DCGs: Constructions

• If target gate Q = I (NOOP), a solution is given by Eulerian DD. To effect non-trivial Q, identify two combinations of primitive gates that have *same* [first-order] EPG

$$Q_* = Q \exp(-i E_Q), \quad I_Q = \exp(-i E_Q)$$

- Modified Eulerian construction: Implement control path starting at *I* on *'augmented' Cayley graph* ⇒
 - (i) To non-identity vertex, attach edge labeled by I_O
 - (ii) To identity vertex, attach edge labeled by Q_*

$$E_{DCG} = E_{EDD} + \sum_{i=1}^{G} U_{g_i}^{\dagger} E_{Q} U_{g_i} + E_{DCG}^{[2+]}$$

Total first-order error vanishes as long as the primitive gate errors and E_O obey DD condition \Rightarrow

$$\| mod_{B}(E_{DCG}) \| = \| mod_{B}(E_{DCG}^{[2+]}) \| = O(\|H_{err}\|^{2})$$

Significantly smaller error compared to 'direct switching'.
 Higher-order cancellation achievable by concatenation.

LV & Knill, PRL 90 2003.

[First-order] 'balance pair'



Euler path: X I Y I X I Y Y X Y X Q

Khodjasteh & LV, PRL 102 2009; PRA 80 2009

Khodjasteh, Lidar & LV, PRL 104 2010.

11/16

Hayes, Khodjasteh, LV & Biercul Haves et al

Recently implemented Mølmer-Sørensen composite gate sequences can be interpreted as DCGs under a simple error model...

$$U_{Q}(t) = \exp[S_{N}(\alpha(t)a^{\dagger} - \alpha(t)^{*}a)]Q, \quad Q = \exp[-i\Phi(t)S_{N}^{2}] \qquad \text{Spin-dependent gate}$$
$$\alpha(t) = \frac{\Omega}{2}\int_{0}^{t} \exp[-i(\delta + \Delta)s]ds \qquad \Delta = \text{Detuning error} \ll \delta$$

 $-iE_{O}(t) = S_{N}(\alpha(t)a^{\dagger} - \alpha(t)^{*}a)$

I Key simplifications:

- (1) Target gate commutes with spin-flips (X gate); (2) Error action anti-commutes with X gate \Rightarrow

$$X Q \exp(-i E_Q) X Q \exp(-i E_Q) =$$
$$Q^2 X \exp(-i E_Q) X \exp(-i E_Q) = Q^2$$

 \square First-order implementation of gate $Q^2 \Rightarrow$ Iterate to achieve higher-order suppression...



- Problem: Control requirements are still too stringent for many lab settings
 - I Control fields are themselves imperfect/noisy...
 - □ Stretchable control profiles need not be available...
 - □ Complete control often relies on internal system Hamiltonian...

Analytic DCG constructions become ineffective (

- Problem: Control requirements are still too stringent for many lab settings
 - □ Control fields are themselves imperfect/noisy...
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Analytic DCG constructions become ineffective (

Goal: To synthesize 'aDCGs' that cancel *both* [non-Markovian] decoherence *and* control errors, without relying on stretching and allowing for/exploiting internal drift.
 <u>Strategy:</u> Relax portability and exploit control knowledge to achieve [non-competing] objectives of gate synthesis and error cancellation ⇒ multi-objective minimization problem:

$$F({x_i}) = dist\left(Q, Texp\left\{-i\int_0^T ds\left[H_{ctrl,0}(s) + H_{s,g}\right]\right\}\right)$$
 Primitive gate synthesis

[First-order] error cancellation/ 'sensitivity minimization'

□ Solving for $F = 0 = G_j$, for all *j*, yields gate implementation that is insensitive to the error parameters $\delta_j \Rightarrow$ Robust control solution as long as errors are perturbatively small.

Complete controllability of targetsystemessentialto justify existence of aDCG solution

 $B_{i}G_{i}(\{x_{i}\}) = \left\| \partial mod_{B}\left(E_{O[T]}^{(\vec{\delta})}\right)/\partial \delta_{i} \right\|_{\vec{\delta}=0}$

Case study: Single-triplet spin qubit

• Model Hamiltonian in the logical singlet-triplet basis $|S\rangle$, $|T_0\rangle$

 $H(t) = \begin{bmatrix} B + \delta B(t) \end{bmatrix} \frac{\sigma_x}{2} + J(t) \frac{\sigma_z}{2},$ Known static magnetic field gradient [drift] Hyperfine-induced error Hamiltonian [additive noise] $J(t) = J_0(t) \begin{bmatrix} 1 + \delta J(t) \end{bmatrix}$ Exchange splitting control, subject to [multiplicative] voltage noise

I Quasi-static Gaussian approximation is an adequate starting point for both noise sources:

$$\sqrt{\langle \delta B^2 \rangle} \equiv \sigma_{\delta B}, \quad \sigma_{\delta B/2\pi} \le 0.15 \text{ MHz}, \qquad \sqrt{\langle \delta J^2 \rangle} \equiv \sigma_{\delta J}, \quad \sigma_{\delta J} \le 0.02$$

Foletti et al, Nature Phys. 2009; Bluhm et al, PRL 2010.

:

Zeeman drift term is crucial for universality. Available exchange control is constrained in magnitude and sign [stretching *not* an option!]:

$$B/2\pi \in [0.03, 0.2]$$
 GHz, $0 < J_0/2\pi \le J_{max}/2\pi = 0.3$ GHz,

Each aDCG consists of a sequence of n pulses characterized by a *fixed* [digitized] profile with *fixed* duration, τ = 3 ns, compatible with current horizontal temporal resolutions.
□ Control variables = Pulse amplitudes, {x_i} ≡ {h_i}. Error sources 'marked' b(𝔅 𝔅 𝔅, 𝔅 𝑌).
□ Weighted objective function: O({h_i}) ≡ F + λ₁G^(𝔅 𝔅) + λ₂G^(𝔅𝑌)

Automated DCGs: Results

• aDCG synthesis: Search problem solved by off-the-shelf Matlab routines (FMINCON)



I Same aDCG sequence applies to *fully quantum* spin-bath model.

Uncorrected • aDCG performance: Evaluate average fidelity $\langle 1-f \rangle = 1 - \frac{1}{2} \left\langle \left| Tr(Q^{\dagger}Q_{DCG}^{(\delta B, \delta J)}) \right| \right\rangle_{\delta B, \delta J}$ 10-4 \$ 10-7 I aDCGs are simultaneously robust against Corrected [non-Markovian] gradient field fluctuations = 10⁻¹⁰ and voltage noise to leading order provided 10-2 10-13 10-3 10-4 10-1 10-2 10-3 $\sigma_{\delta B/B} + \sigma_{\delta I} \leq 0.1$ 10-5 10-5 10-4 $\sigma_{\delta B/B}$

Conclusion and outlook

• DQES has the potential to reduce memory and gate errors below the level required by accuracy threshold for non-Markovian quantum error correction.

□ Systematic/quantitative comparison between DCGs and *composite pulses*?...

Kabytayev, Green, LV, Biercuk and Brown, in preparation.

□ DQES with *continuous* driving fields?...

Fanchini & al, arXiv:1005.1666; Chaudhry & Gong, arXiv:1110.4695; Jones, Ladd & Fong, arXiv:1205.2402.

• Plenty of room exists for tailoring and/or improving DQES constructions and for optimizing performance under specific system and/or control assumptions.

- ✓ Single-qubit setting:
 - © Complexity/convergence/landscape of aDCG solution... Impose *time-optimality* on top?
- ✓ Many-qubit setting:

Better exploitation of *locality and sparsity* of physical error models...

□ Impact and role of *correlation* effects... DQES for *noise spectroscopy*?

• Dedicated experimental realizations/benchmarking of DQES schemes can continue to validate theoretical insights and identify key trade-offs/practical constraints to address.