



From Turbulence Transition to Shell Buckling



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Emergent Complexity in Physical Systems

EPFL Lausanne, Switzerland

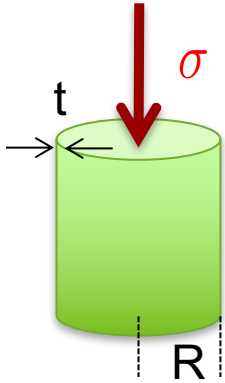


Supported by SNSF grant 200021-165530

The (seemingly simple) question

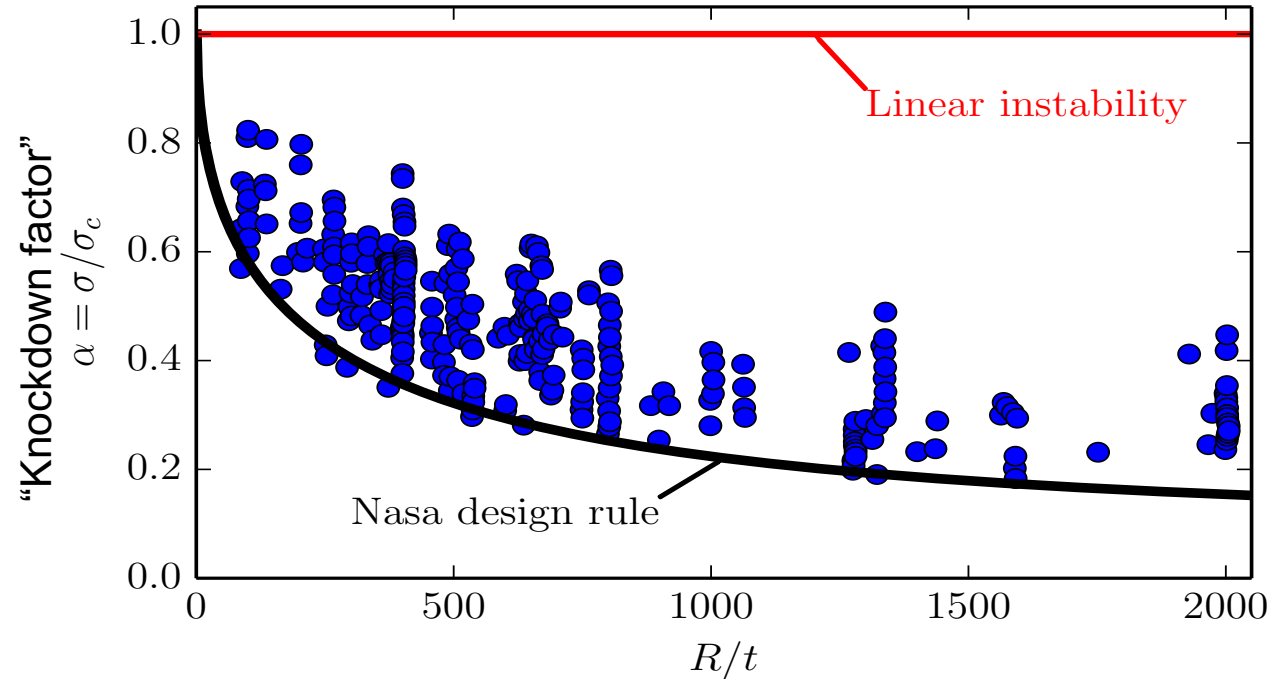
How much load can a cylinder shell carry?

Axially loaded cylinder shell



$$\sigma_C = \frac{E}{3(1 - \nu^2)} \frac{t}{R}$$

Buckling threshold (NASA)



Observation:

Failure of linear theory!

Nominally identical shells buckle at different load ('stochastic')

Thinner shells tend to buckle for lower load

Captured by empirical design rules ('knockdown factors')

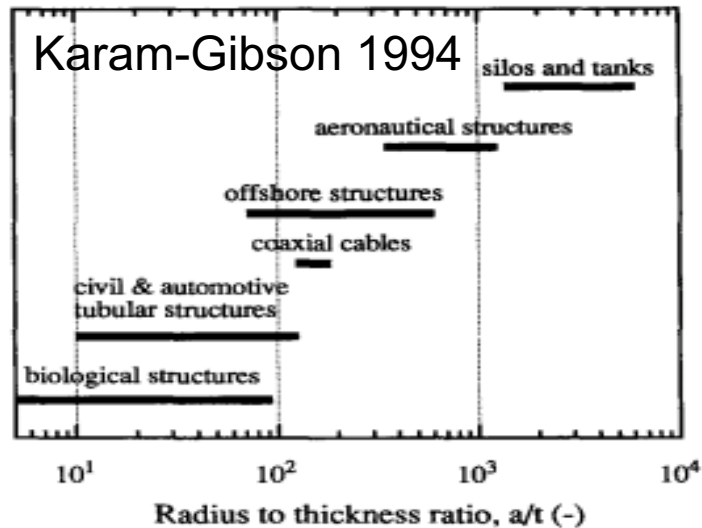
Explanation:

Extreme sensitivity to imperfections

(von Karman & Tsien 1939, Koiter 1945, ...)

Thin shell structures

Structural rigidity at minimal weight



Properties of curved shells

Exceptional load carrying capacity

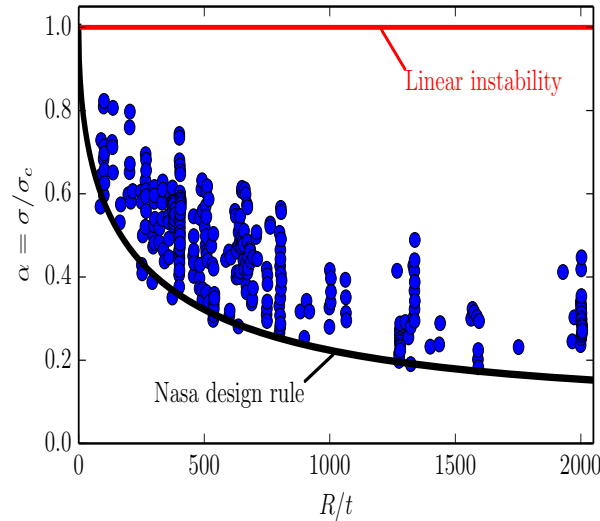
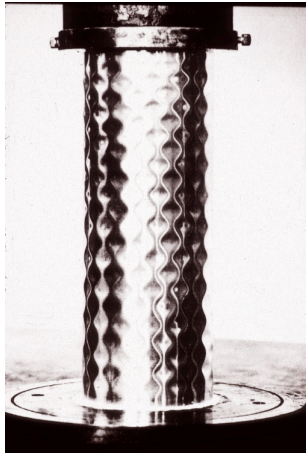
Challenging to predict buckling conditions

Reason: Imperfection sensitivity

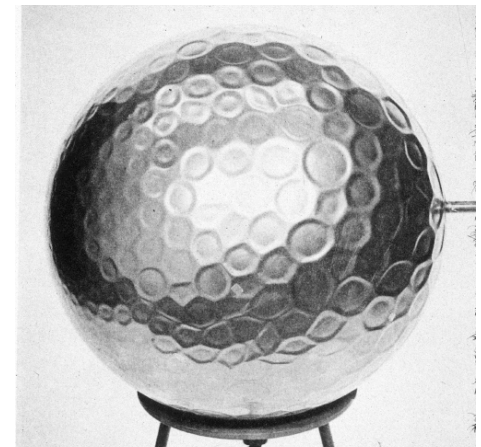
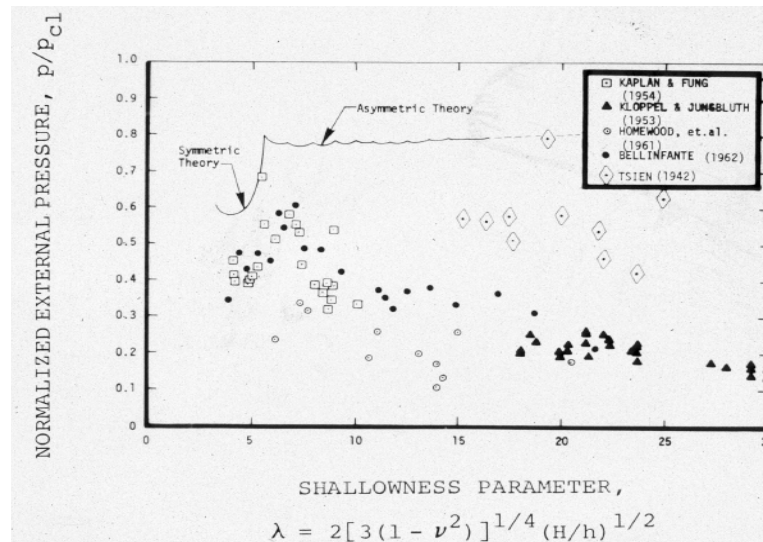
Thin shell structures

The two canonical examples

Axially loaded cylinder



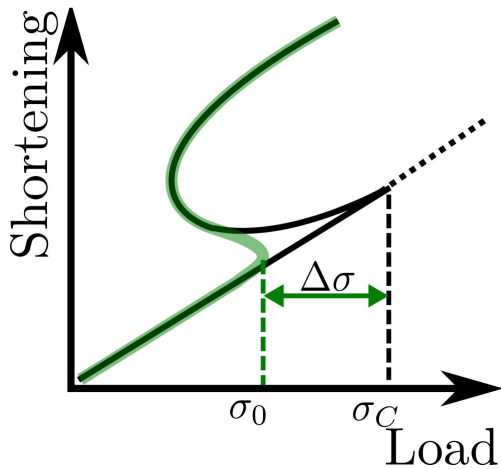
Sphere under uniform pressure



How to predict buckling loads?

The classical approach and its limitations

Classical approach: Imperfections modify the critical load

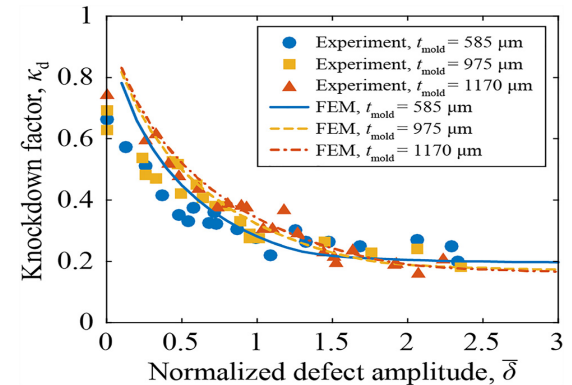
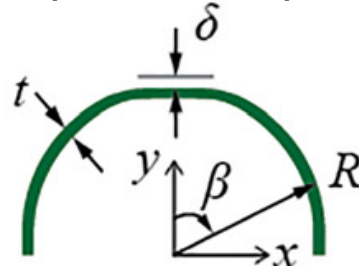


Scenario: Linear instability of the *imperfect* system

Given imperfections -> predict buckling load

Example: Lee et al. 2016, Hutchinson 2016

Spherical cap



Problem: Imperfections typically unknown a priori



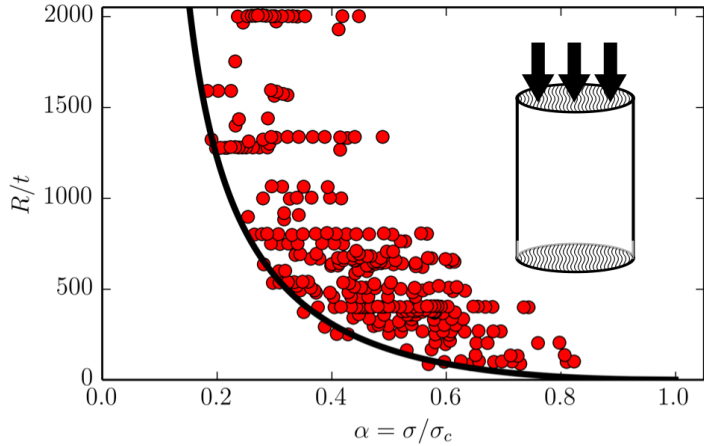
Credit: E. Lozano

Idea: Fully nonlinear dynamical systems approach?

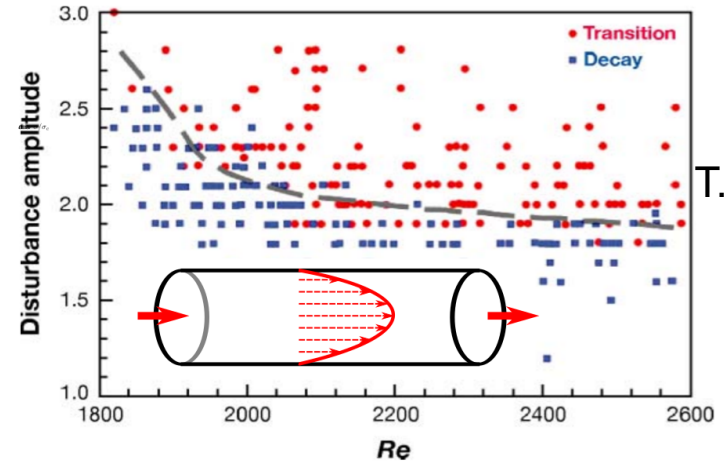
From turbulence transition to shell buckling

A new approach inspired by turbulence studies

Cylinder buckling



Pipe flow transition triggered by jet injection



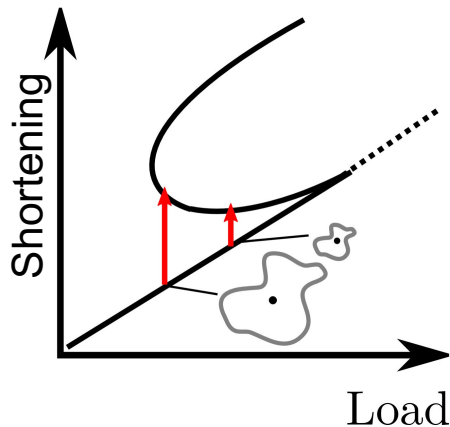
T. Mullin

Linearly stable!

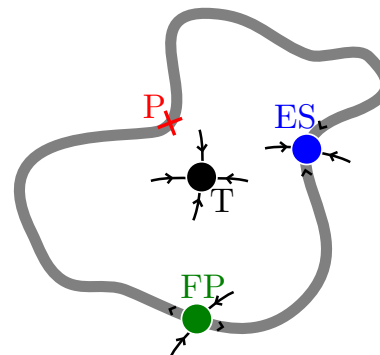
Similarity suggests paradigm shift:

Linear instability of the *imperfect* system

➔ *Nonlinear* finite amplitude instability of the *perfect* system



Characterize basin of attraction as a function of load



- : trivial (unbuckled) state
- : unstable equilibria
- : edge state

Geometric nonlinearity

Why is the problem intrinsically nonlinear?

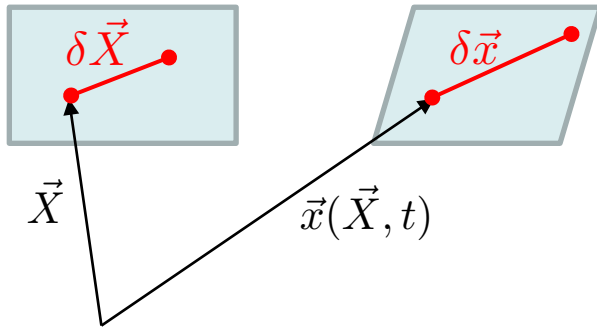
Elastic response:

deformation

nonlinear

strain

stress



Displacement field $\vec{u}(\vec{X}, t) = \vec{x} - \vec{X}$

└ Lagrangian coordinate

Strain: changed distance between material points

$$\delta \vec{x}^2 - \delta \vec{X}^2 = 2\epsilon_{ij}\delta X_i\delta X_j$$

With Green-Lagrange strain tensor

$$\epsilon_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial X_j} + \frac{\partial u_j}{\partial X_i} + \frac{\partial u_k}{\partial X_i} \frac{\partial u_k}{\partial X_j} \right)$$

Linear stress-strain relation

Nonlinear function of displacement field!!

Cauchy stress

$$\sigma_{ij} = \frac{E}{1+\nu} \left(\epsilon_{ij} + \frac{\nu}{1-2\nu} \epsilon_{kk} \delta_{ij} \right)$$

Isotropic Hookean material

Map back to reference configuration

Force balance:

~~$$\rho \partial_{tt} \vec{u} + \gamma \partial_t \vec{u} = \rho \vec{g} + \nabla \cdot \tau$$~~

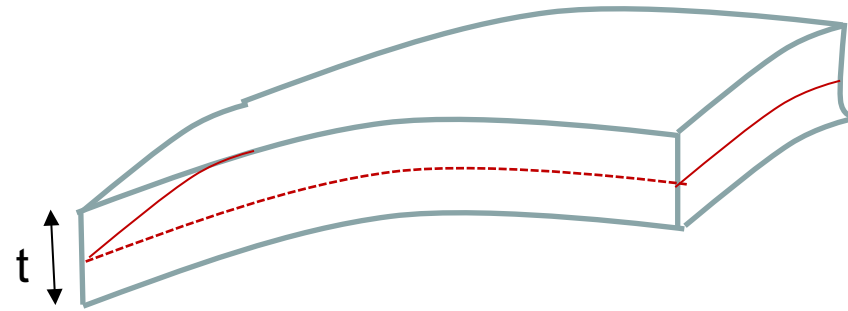
overdamped

└ Piola-Kirchhoff stress tensor

Nonlinear dynamical system: $\partial_t \vec{u} = \mathcal{N}(\vec{u})$

Equations for a thin elastic shell

The Donnell-Mushtari-Vlassov theory



Deformation of the mid-surface

$$(x_1, x_2, h(x_1, x_2)) \rightarrow (x_1 + u_1, x_2 + u_2, h(x_1, x_2) + w)$$

Transverse displacement \perp

Asymptotic reduction from 3D: $\epsilon = \frac{t}{L} \ll 1$

$$w = \mathcal{O}(\epsilon), u_\alpha = \mathcal{O}(\epsilon^2)$$

In-plane strain: $\epsilon_{\alpha\beta} = E_{\alpha\beta} + zK_{\alpha\beta}$

$$E_{\alpha\beta} = \frac{1}{2} (u_{\alpha,\beta} + u_{\beta,\alpha}) + \frac{1}{2} (h_{,\alpha}w_{,\beta} + h_{,\beta}w_{,\alpha}) + \frac{1}{2} w_{,\alpha}w_{,\beta},$$

$$K_{\alpha\beta} = -w_{,\alpha\beta}$$

- Use linear stress-strain relation
- Integrate stress over thickness: $N_{\alpha\beta} = \int_{-t/2}^{t/2} \tau_{\alpha\beta} dz$
- Introduce Airy stress potential $\phi_{,xx} = N_{yy}$, $\phi_{,yy} = N_{xx}$ and $\phi_{,xy} = -N_{xy}$
- Deviation from prebuckled base state $(w, \phi) = (w, \phi)_{tot} - (w^0, \phi^0)$

\perp depends on axial load

Equations for a thin elastic shell

The Donnell-Mushtari-Vlassov theory

$w(x, y)$: normal displacement

X : axial coordinate

Y : azimuthal

$$w_{,\tau} = f(w) \equiv -\frac{1}{\delta} \left(D \Delta^2 w + \frac{1}{R} \phi_{,xx} - [w, \phi] + \lambda w_{,xx} \right)$$

Cylinder radius Axial load

$$\frac{1}{Et} \Delta^2 \phi = \frac{1}{R} w_{,xx} - \frac{1}{2} [w, w]$$

Airy potential

DMV equations

$$[A, B] = A_{,xx} B_{,yy} + A_{,yy} B_{,xx} - 2A_{,xy} B_{,xy}$$

$$D = \frac{Et^3}{12(1-\nu^2)} \quad \text{Bending stiffness}$$

Critical load

$$\lambda_c = \frac{E}{3(1-\nu^2)} \frac{t^2}{R} = t\sigma_c$$

Clamped boundaries $w = w_{,x} = 0 \quad \phi_{,x} = (\Delta\phi)_{,x} = 0$

Characteristics: Nonlinear & Nonlocal

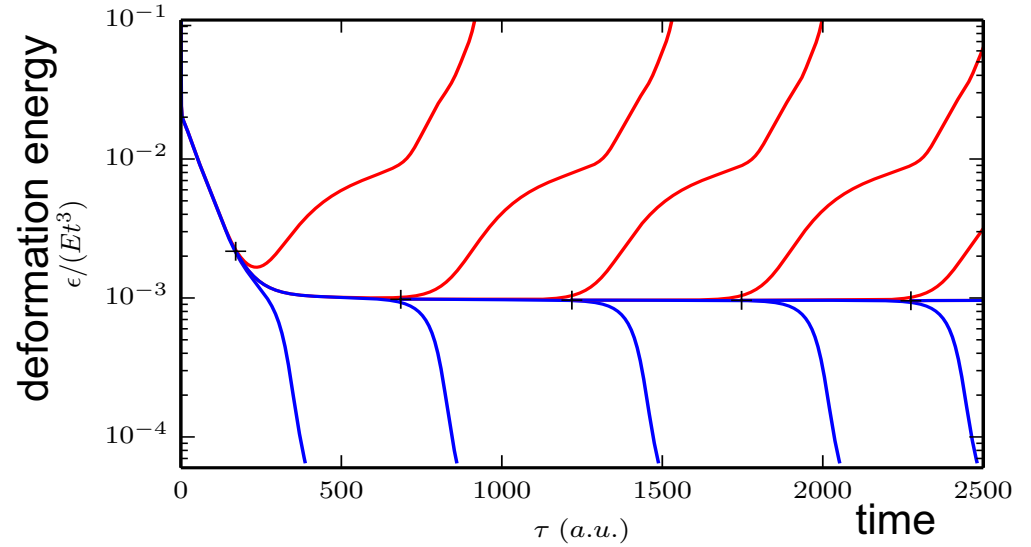
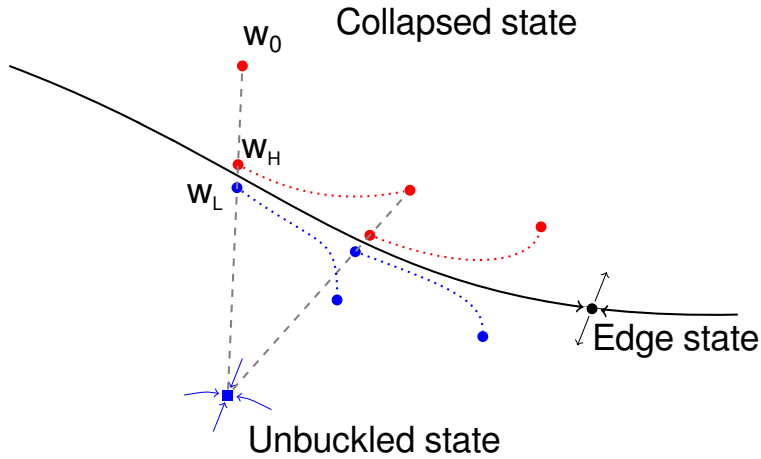
Numerical solution: Compact finite differences

Aim: Construct nonlinear equilibria on the basin boundary of the unbuckled state

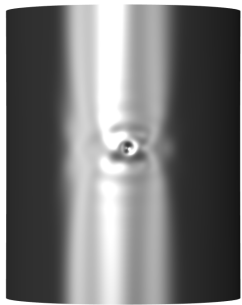
Dynamical systems methods for shells

Unstable equilibria on the basin boundary

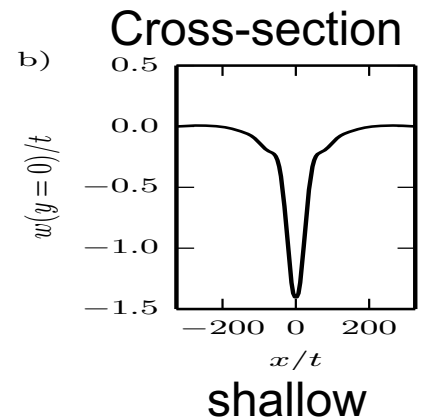
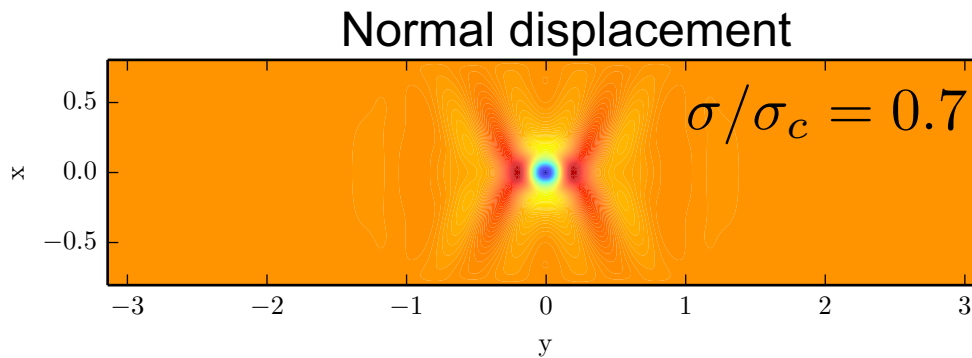
Edge tracking



yields edge state equilibrium



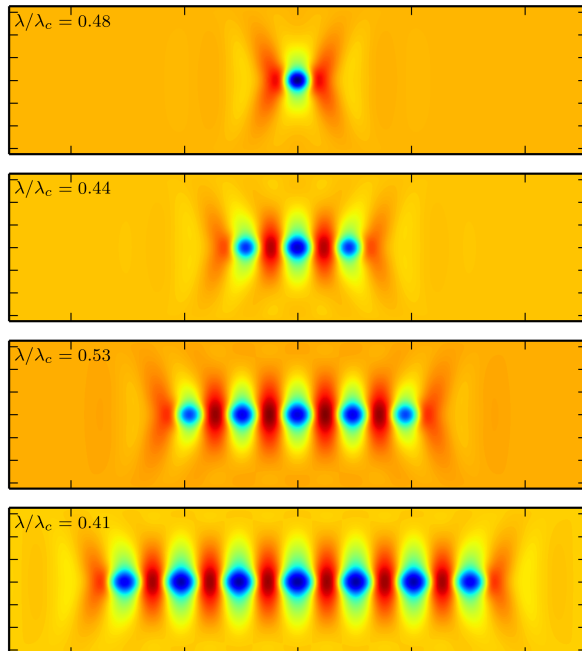
Localized single dimple



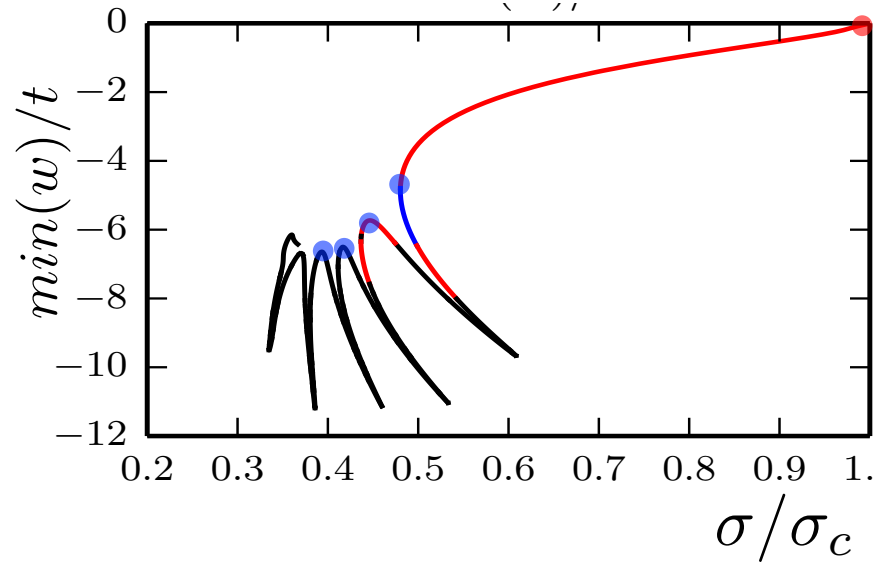
Dynamical systems methods for shells

Unstable equilibria on the basin boundary

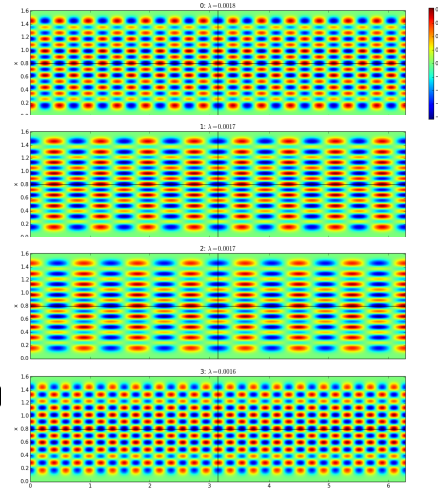
Snaking (azimuthally)



Continuation in axial load

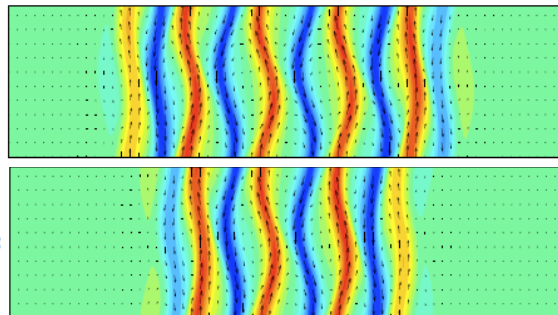


critical eigenmodes



Not localized

Compare: Plane Couette flow



Result: localized dimple patterns
low-dimensional unstable manifold
located on the stability boundary

Finite amplitude perturbations of a shell

Experiments with Shmuel Rubinstein, Harvard

Concept: Apply controlled perturbation to ‘perfect’ shell

Pipe flow transition (Mullin, Hof)

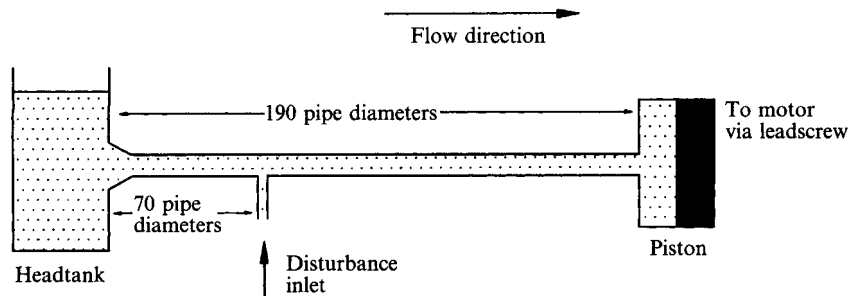
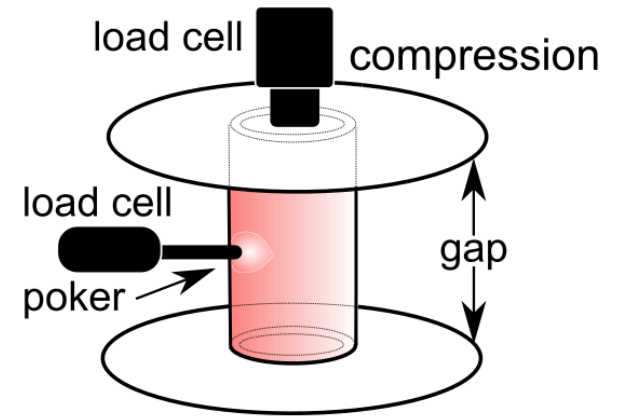


FIGURE 1. Schematic diagram of flow rig.

Dabyshire & Mullin 1994

Same for a shell

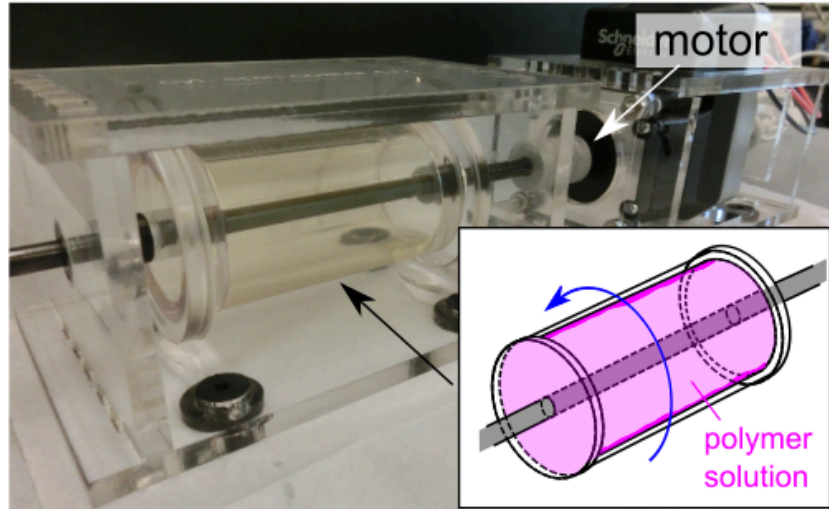


Needed:

1. Near ‘perfect’ shells
2. Biaxial testing machine – ‘shell poker’

Perturbing (almost) perfect shells

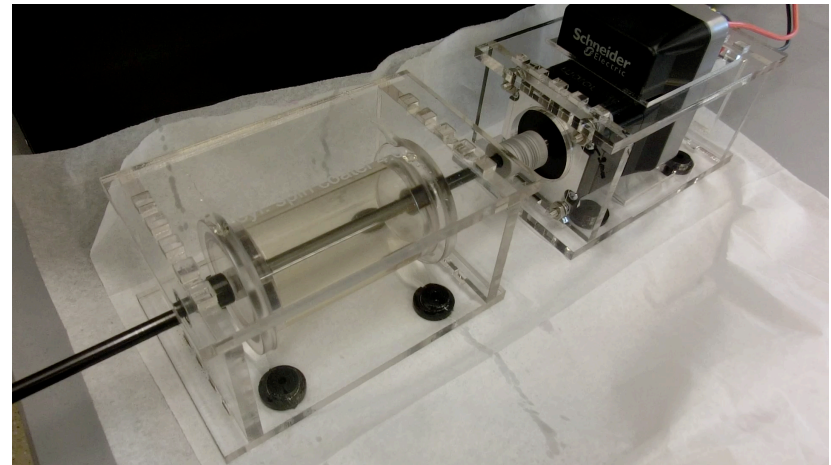
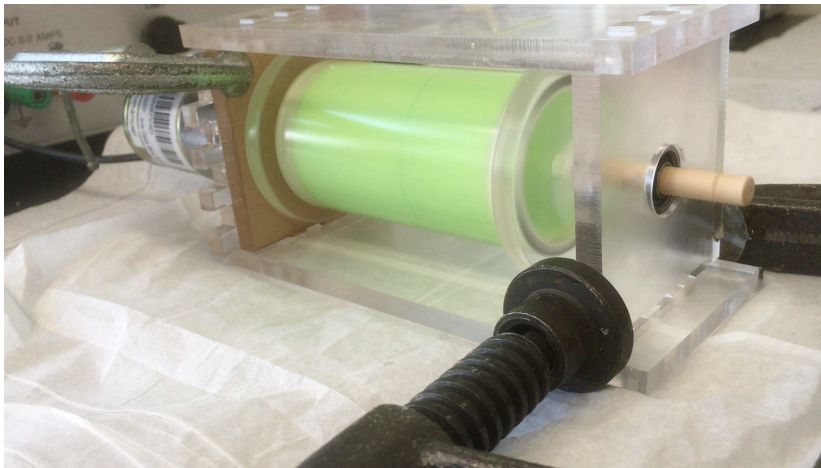
Polymer shells



Spin coater (first iteration)



Spin coater (second iteration)



Advantage:
Challenge:

No plastic deformation after buckling
Making very thin shells

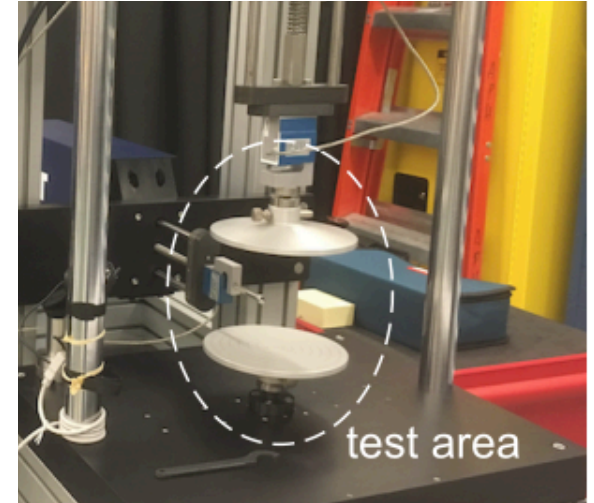
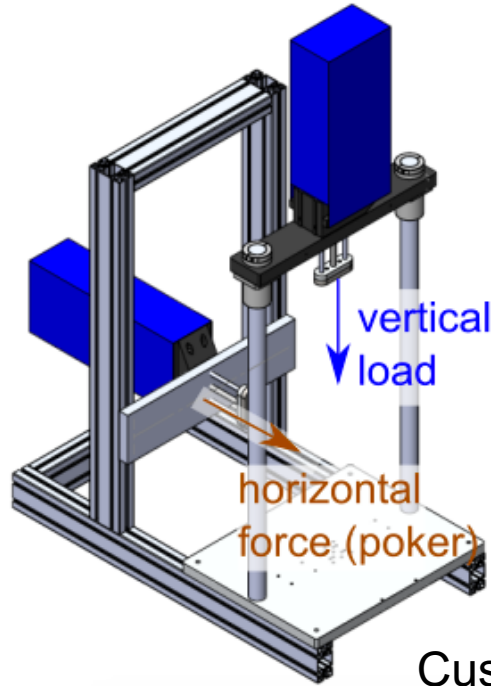
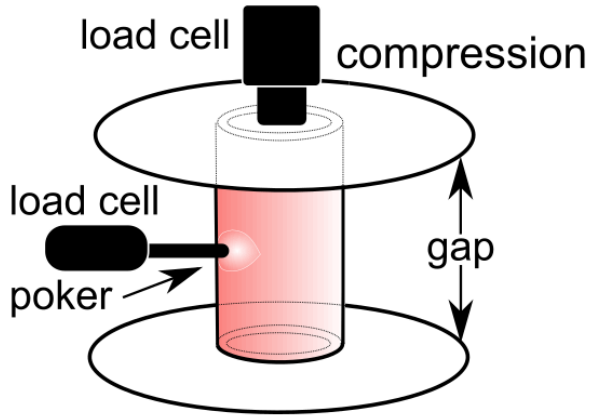
Perturbing (almost) perfect shells

Aluminum cans



Perturbing (almost) perfect shells

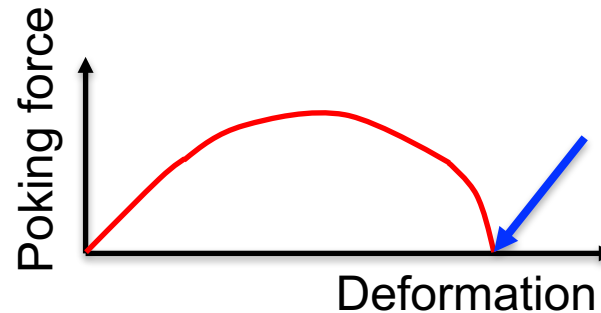
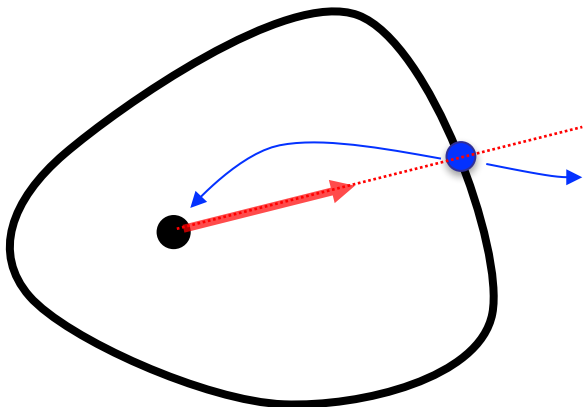
Significance of unstable (edge) states



Custom made with ADMET company

Basin boundary at fixed load

Control poker displacement and measure force

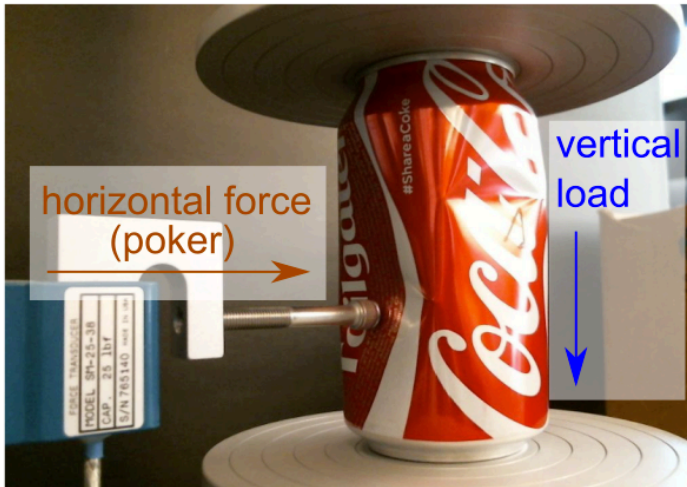


Expectation:

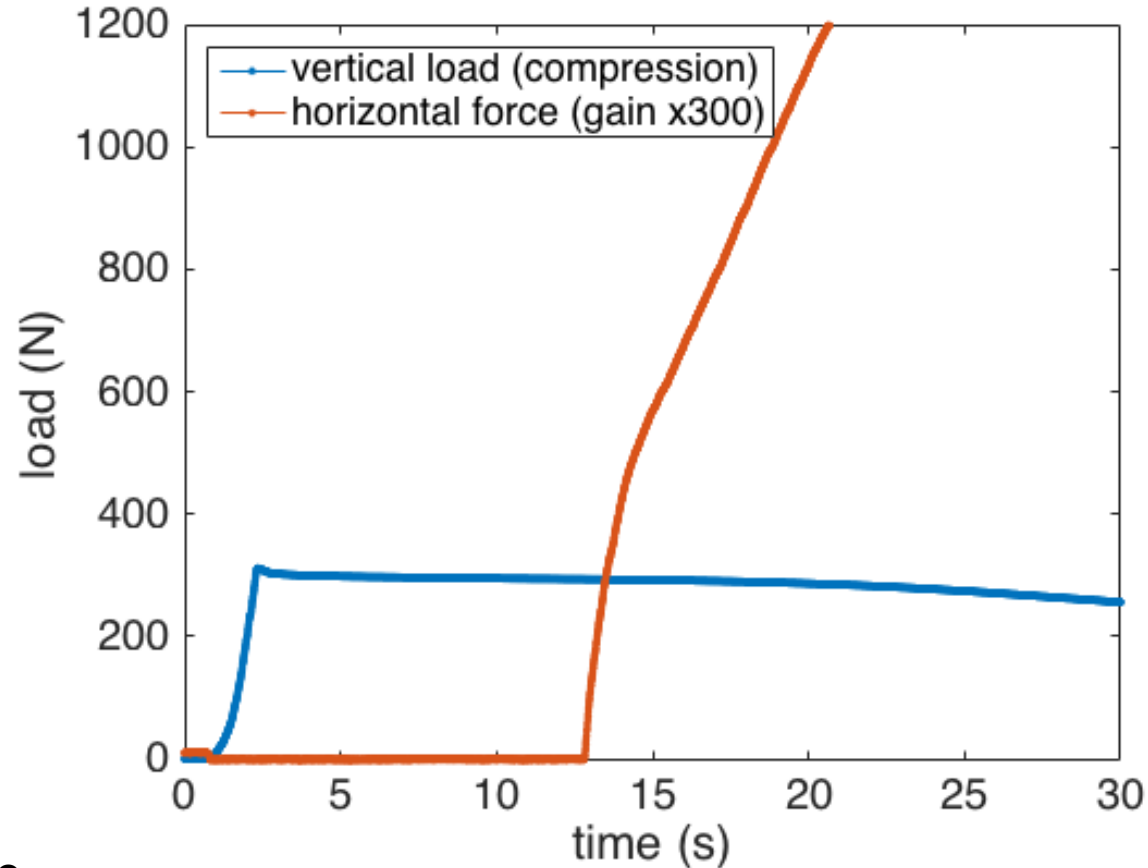
- reach edge state
- induce buckling

Poking experiment

First data (preliminary!!)



Load: 300 N

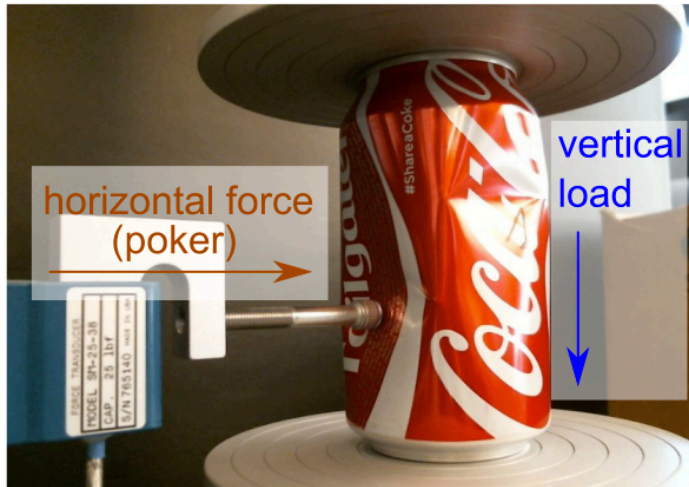


- 1: increase axial load to target value
2. Advance lateral poker

Constant speed 10mm/min

Poking experiment

First data (preliminary!!)



- 1: increase axial load to target value
2. Advance lateral pocker

Constant speed 10mm/min

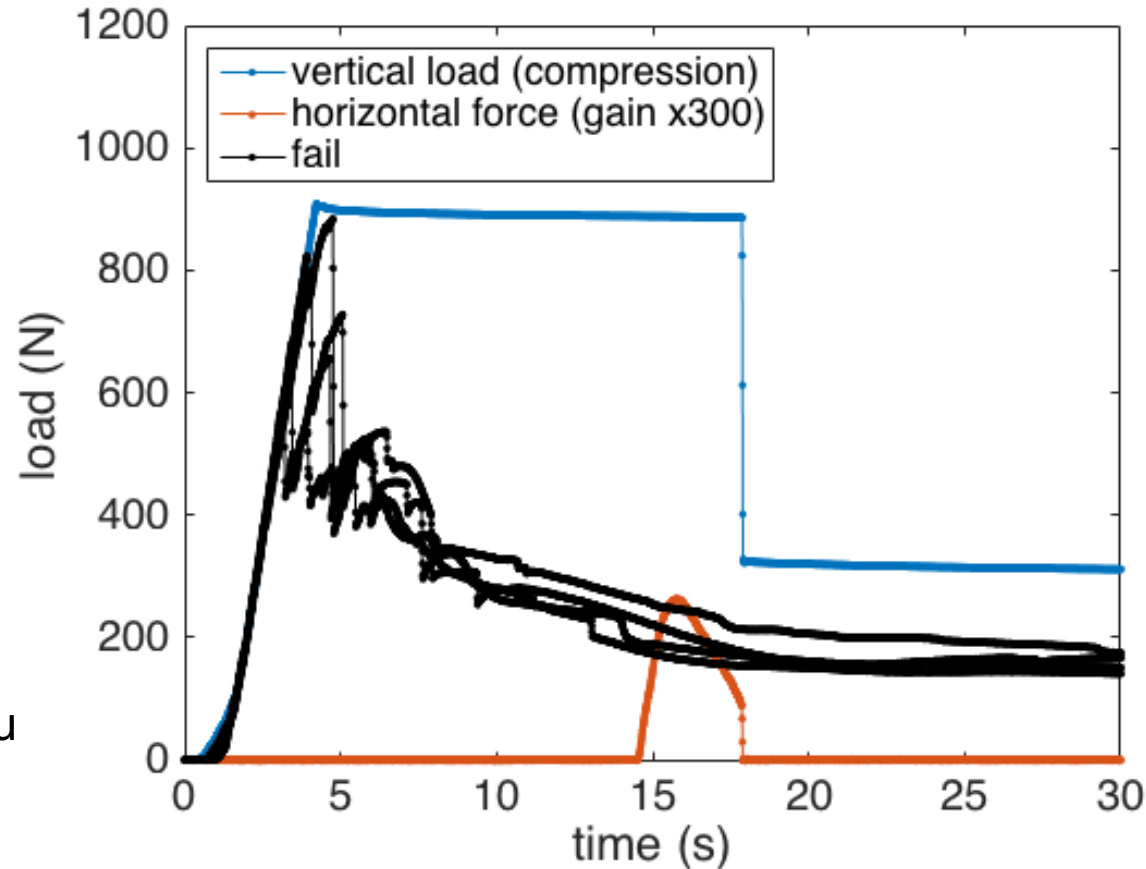
Observation:

buckling when edge state is reached

Interpretation:

Confirms nonlinear finite amplitude instability triggers buckling

Load: 900 N



5 sec corresponds to 0.8 mm

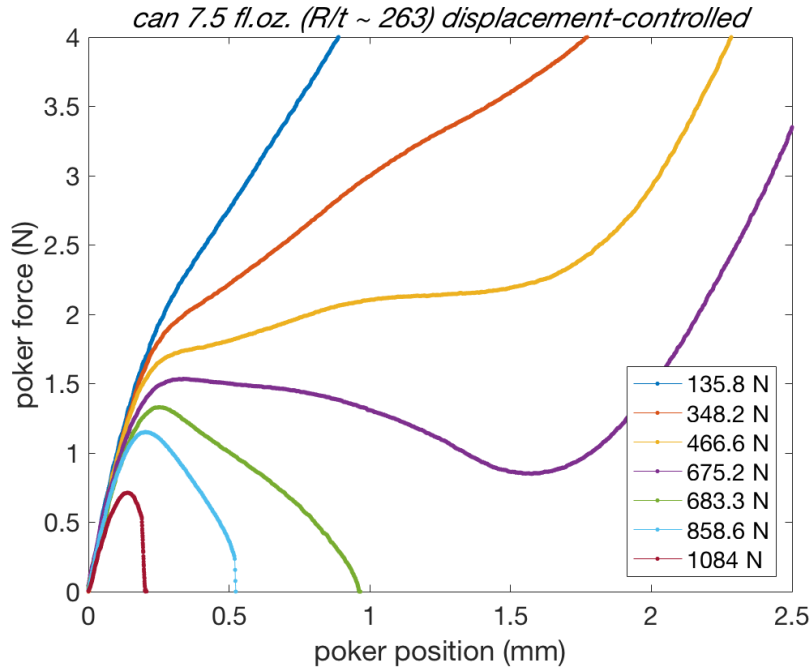
Poking experiment



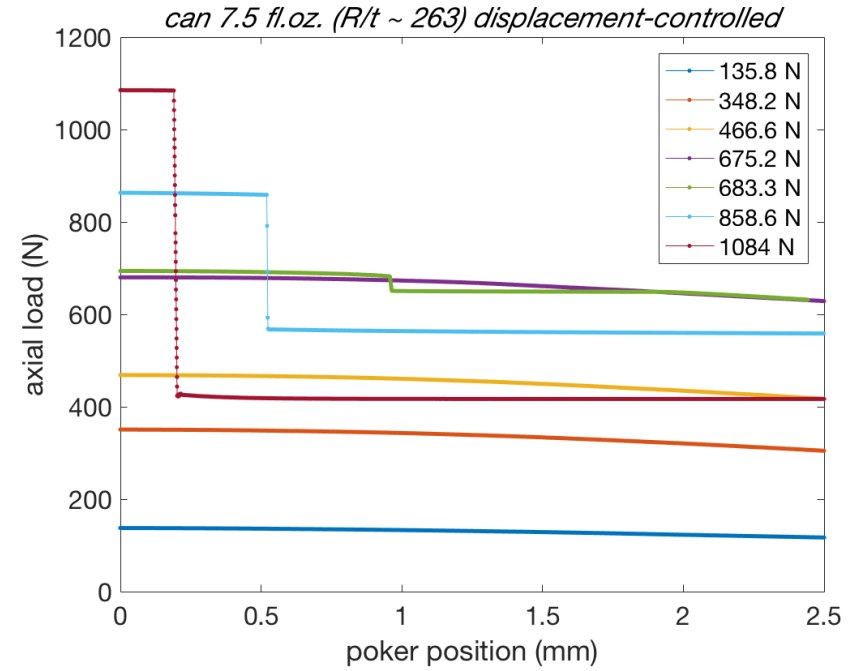
Poking experiment

Quantifying critical perturbations

Poker force



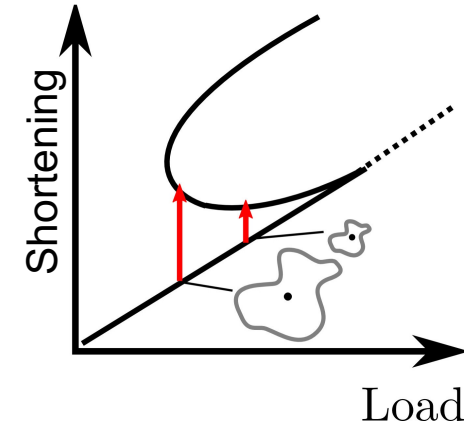
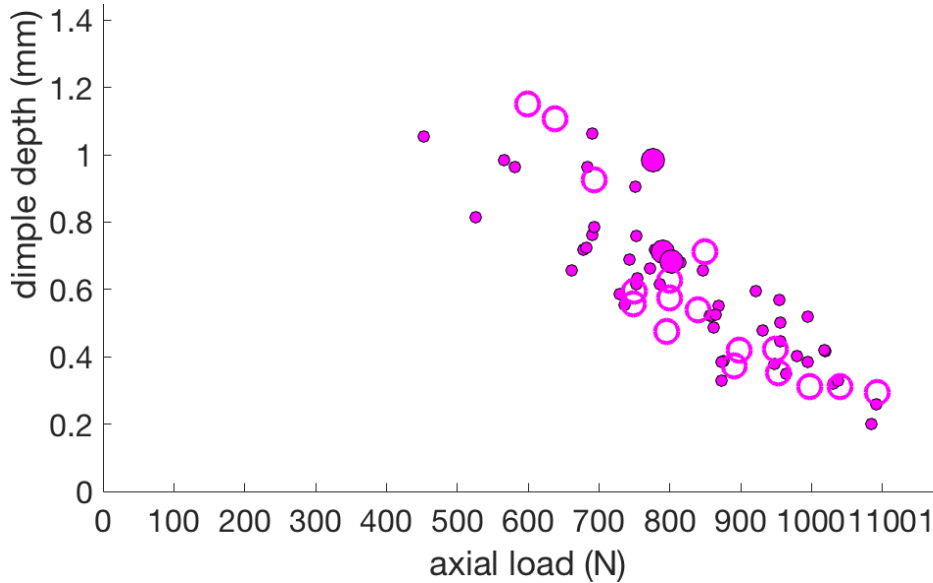
Axial force



Poking experiment

Quantifying critical perturbations

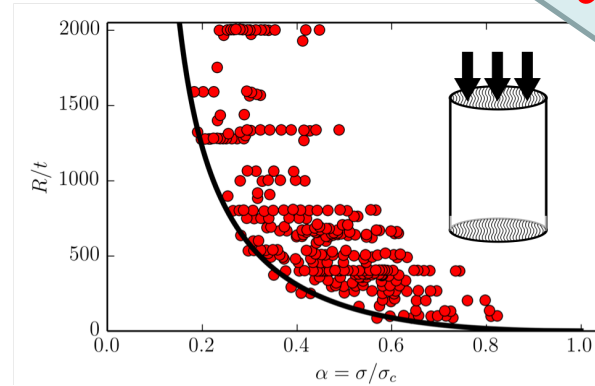
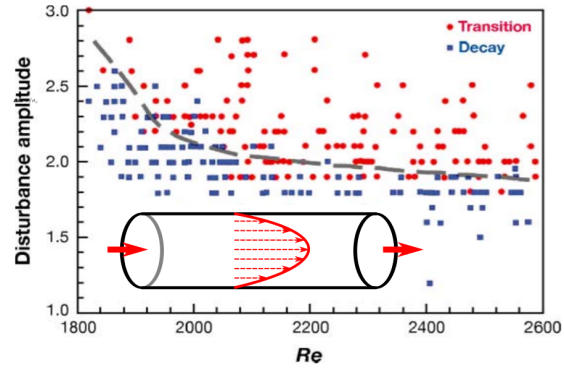
Example: dimple depth when buckling is induced



- Interpretation:**
- basin of attraction shrinks with load
 - basin vanishes at critical load

Summary and Outlook: Shell buckling

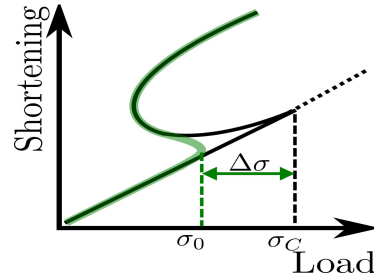
Similarity of turbulence transition and shell buckling



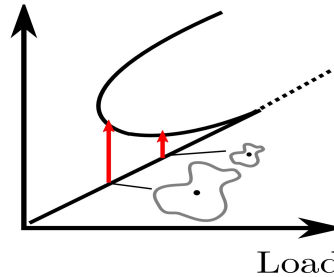
This is new, preliminary and highly speculative ... but very exciting!!!!

Suggests paradigm shift

Linear instability of the *imperfect* shell

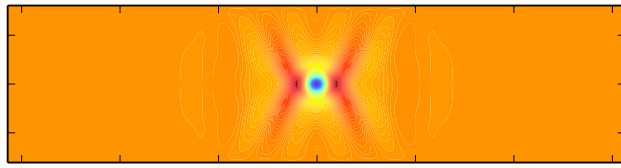


Nonlinear instability of the *perfect* shell



Approach appears supported by preliminary results

Theory: exact invariant states



Experiment: Critical perturbations



Plan / Dream: Predictive theory for buckling thresholds of thin shell structures