

# Asymptotically-Motivated Models of Langmuir Circulation Dynamics on Ocean Submesoscales

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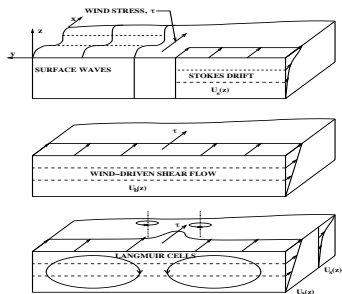
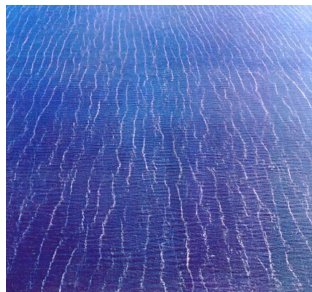
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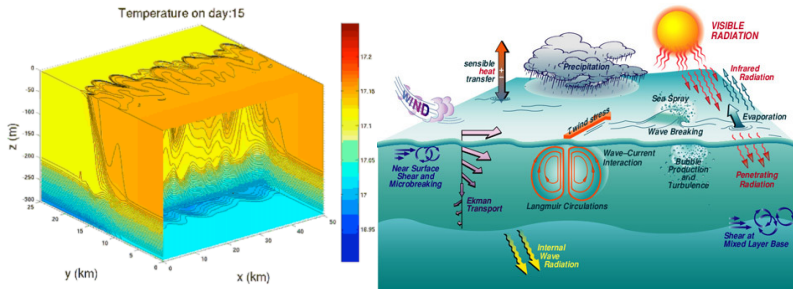
## Langmuir Circulation (LC)



### Craik–Leibovich (CL) Theory

- Dominant upper ocean motion due to irrotational surface waves:  $O(\text{m/s})$
- Wind-driven shear flow, LC, other rotational (turbulent) motions weaker:  $O(\text{cm/s})$
- Rectified effects of filtered surface waves arise from Stokes drift velocity  $\mathbf{u}_s(z)\hat{\mathbf{x}}$
- CL vortex force  $\mathbf{u}_s(z)\hat{\mathbf{x}} \times \boldsymbol{\omega}$  and Stokes–Coriolis force  $2\boldsymbol{\Omega}_e \times \mathbf{u}_s(z)\hat{\mathbf{x}}$  and additional contribution to tracer ( $\phi$ ) advection  $\mathbf{u}_s(z)\hat{\mathbf{x}} \cdot \nabla \phi$

# The Ocean Surface Boundary Layer (BL): Submeso- to BL Scales



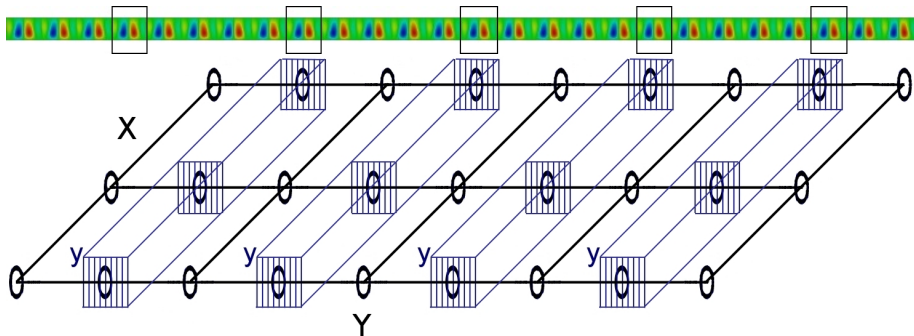
Efficient multiscale framework to study coupling b/w 3D  $O(50)$ -m non-hydrostatic BL turbulence and  $O(5)$ -km largely-hydrostatic, rotationally influenced submesoscale flows:

- DNS.. LES<sup>a</sup>... **Multiscale Models**..... Hydrostatic Primitive Equation Models
- Identify and understand new physical phenomena

<sup>a</sup>Hamlington et al., *JPO* (2014, in revision) "Langmuir-Submesoscale Interactions...":

LES on 1024-core supercomputer required  $\approx 1$  month of wall-clock time to simulate  $\approx 2$  weeks physical time in a  $20 \text{ km} \times 20 \text{ km} \times 160 \text{ m}$  domain with  $5 \text{ m} \times 5 \text{ m} \times 1.25 \text{ m}$  spatial resolution for  $La_t \equiv \sqrt{u_* / u_{S0}} = 0.29$ .

## Asymptotic Reduction



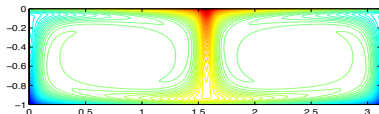
## Asymptotic Limits

- 1 **Hydrostatic (small aspect-ratio) submesoscale (subMS) dynamics:** disparate-scale coupling between LC and subMS flows  $\Rightarrow$  Long **cross-wind** scales ( $\delta \rightarrow 0$ )
- 2 **Strong CL vortex force:** “pure” Langmuir turbulence regime, in which turbulence *constrained* by vortex force  $\Rightarrow$  Long **downwind** scales ( $La_t \rightarrow 0$ )

Secondary Stability Analysis of Fully 3D CL Equations: Trends as  $La_t \rightarrow 0$ 

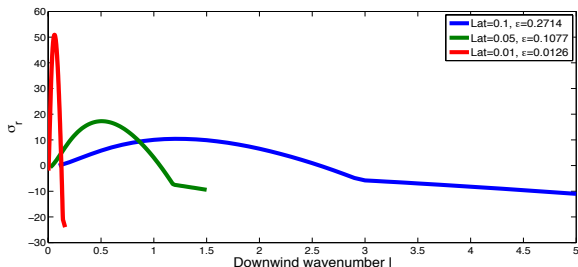
- Linearize about **fully nonlinear 2D** flow:  $U(x, y, z, T) = U_{2D}(y, z) + u(x, y, z, T)$

$$U_{2D}(y, z)$$



- Employ spatial **Floquet theory**, e.g.

$$u(x, y, z, T) = e^{i\gamma y} \left[ \sum_{n=-\infty}^{\infty} \hat{u}_n(z) e^{i(nky)} \right] e^{i\alpha x} e^{\sigma t} + \text{c.c.}$$





## Master PDEs: Rotating, Stratified CL Equations

- Downwind invariant (2D–3C)
- $f$ -plane approximation
- Boussinesq approximation

## PDEs

$$D_t u - \delta Ro^{-1} v = La (\partial_y^2 + \partial_z^2) u$$

$$D_t v + \delta Ro^{-1} (u + S U_s) = -\partial_y p + S U_s \partial_y u + La (\partial_y^2 + \partial_z^2) v$$

$$D_t w = -\partial_z p + S U_s \partial_z u + Ri b + La (\partial_y^2 + \partial_z^2) w$$

$$D_t b = Pr^{-1} La (\partial_y^2 + \partial_z^2) b$$

$$\partial_y v + \partial_z w = 0. \quad D_t \equiv \partial_t + v \partial_y + w \partial_z. \quad \text{Wind-Stress BC: } \partial_z u = 1$$

## Parameters

$$\delta \equiv h/\mathcal{L}. \quad Ro \equiv U/f\mathcal{L}. \quad Ri \equiv Bh/U^2. \quad La \equiv \nu_{sgs}/Uh. \quad S = 0 \text{ or } 1.$$

## Derivation of Multiscale PDEs

- Introduction of slow **horizontal** length and slow time scales:

$$Y = \delta y \quad \text{and} \quad T = \delta t$$

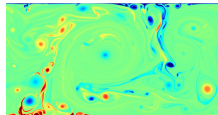
- Multi-scale differentiation:  $\partial_y \rightarrow \partial_y + \delta \partial_Y$  and  $\partial_t \rightarrow \partial_t + \delta \partial_T$
- Mean-fluctuation decomposition and asymptotic expansion:

$$f(y, z, t) \sim \bar{f}(Y, z, T) + \delta \bar{f}_1(Y, z, T) + \dots \\ + f'(y, z, t; Y, T) + \delta f'_1(y, z, t; Y, T) + \dots$$

where  $\bar{f}$  is the (leading-order) fast time, fast horizontal average of  $f$

Note:  $\bar{w} \sim \delta \bar{w}_1(Y, z, T) + \dots \equiv \delta \bar{W}(Y, z, T) + \dots$

- Distinguished limit, as  $\delta \rightarrow 0$ :



–Johnston & Doering, *PRL* (2009)

$$\overline{La} \equiv La/\delta = O(1). \quad [Ri, Ro] = O(1). \quad \overline{w'(u', v', b')} = O(\delta).$$



## Leading-Order Mean System: Submesoscale (Coarse-Scale) Dynamics

## Mean Equations

$$\bar{D}_T \bar{u} + \delta^{-1} \partial_z (\overline{w' u'}) - Ro^{-1} \bar{v} = \bar{L}a \partial_z^2 \bar{u}$$

$$\begin{aligned} \bar{D}_T \bar{v} + \partial_Y (\overline{v' v'}) + \delta^{-1} \partial_z (\overline{w' v'}) \\ + Ro^{-1} (\bar{u} + SU_s) = -\partial_Y \bar{p} + SU_s \partial_Y \bar{u} + \bar{L}a \partial_z^2 \bar{v} \end{aligned}$$

$$0 = -\partial_z \bar{p} + Ri \bar{b} + SU_s \partial_z \bar{u} - \partial_z (\overline{w' w'})$$

$$\bar{D}_T \bar{b} + \delta^{-1} \partial_z (\overline{w' b'}) = Pr^{-1} \bar{L}a \partial_z^2 \bar{b}$$

$$\partial_Y \bar{v} + \partial_z \bar{W} = 0. \quad \bar{D}_T \equiv \partial_T + \bar{v} \partial_Y + \bar{W} \partial_z. \quad \text{Wind-Stress BC: } \partial_z \bar{u} = 1$$

- The **blue terms** represent eddy fluxes, which must be calculated by solving the fluctuation system
- In the absence of these terms, the **hydrostatic primitive equations** are recovered

## Leading-Order Fluctuation System: Langmuir Circulation (Fine-Scale) Dynamics

## Fluctuation Equations

$$D'_t u' + w' \partial_z \bar{u} = La (\partial_y^2 + \partial_z^2) u'$$

$$D'_t v' + w' \partial_z \bar{v} = -\partial_y p' + SU_s \partial_y u' + La (\partial_y^2 + \partial_z^2) v'$$

$$D'_t w' - \partial_z (\overline{w'w'}) = -\partial_z p' + SU_s \partial_z u' + Ri b' + La (\partial_y^2 + \partial_z^2) w'$$

$$D'_t b' + w' \partial_z \bar{b} = Pr^{-1} La (\partial_y^2 + \partial_z^2) b'$$

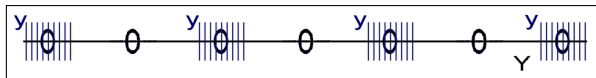
$$\partial_y v' + \partial_z w' = 0. \quad D'_t \equiv \partial_t + (\bar{v} + v') \partial_y + w' \partial_z. \quad \text{Traction BC: } \partial_z u' = 0$$

- The **blue terms** show that the fluctuations “feed” on vertical gradients of the mean fields and are advected by the mean horizontal flow
- **Coriolis forces** are sub-dominant (as expected) on fine scales, only “appearing” indirectly through profiles of mean fields

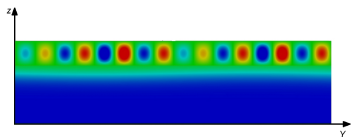
## Multiscale Numerical Algorithm

The integration of the multi-scale system is performed as follows:

- 1 Perform  $M \leq M_{max}$  fine-scale time steps  $\Delta t$  of fluctuation system on  $N$  fine ( $y$ )  $l$ -periodic grids during which time mean fields are frozen
- 2 Perform one coarse-scale time step  $\Delta T$  of mean system on coarse ( $Y$ ) grid of length  $L$  to update mean fields using fine-scale fluxes

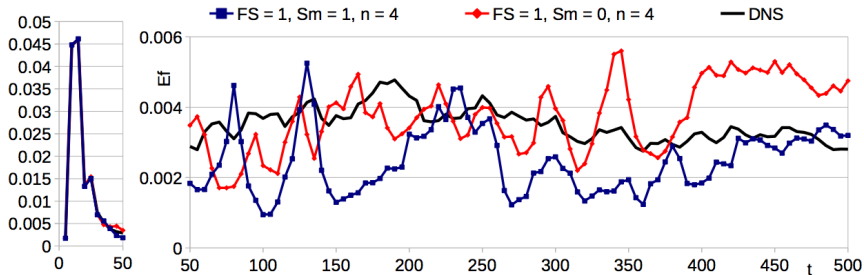
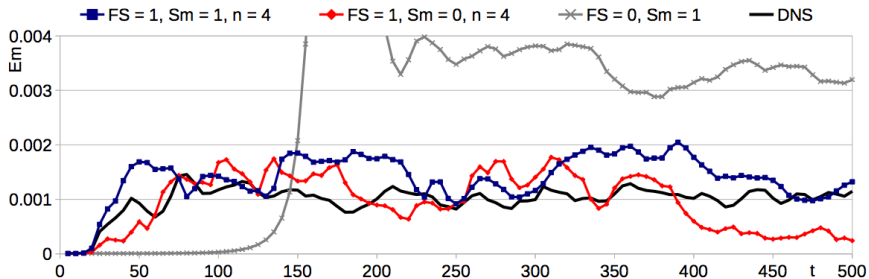


**Computational Advantage:** No communication b/w embedded fine-scale domains  $\Rightarrow$  “embarrassingly” parallelizable

LC Interaction with Submesoscale IW ( $Ro \rightarrow \infty$ ,  $Ri = 1$ )

Mode	$ \bar{v} _{MAX}$	$ \bar{W} _{MAX}$
Pure Traveling IW	0.005	0.05
Pure LC	0.17	0
LC-IW	0.5	2.3

## Time-Evolution of Mean and Fluctuation Area-Averaged Cross-Wind KE

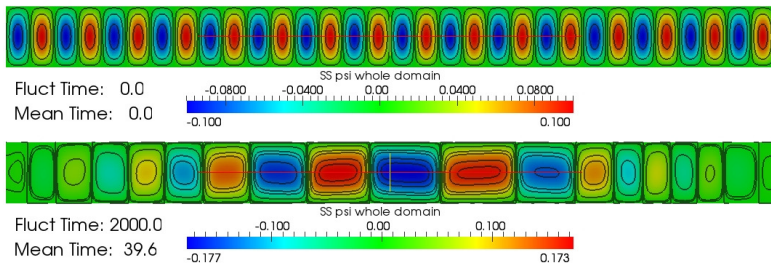


Computational Parameters for Domain Size:  $H = \pi$ ,  $l = \pi$ ,  $\mathcal{L} = 16\pi$

Model	$N_z$	$N_y$	$N_x$	# CPUs	Wall Clock for $t = 25$
DNS	128	$16 \times 128$	—	1	22 hours
MS	128	$4 \times 128$	32	4	2 hours

**Computational Acceleration:** MS simulations 11 times faster than DNS

## Challenge: The Need for a Phase-Variable Formalism?



- Desire **adaptivity** in **location** and **width** of embedded fine scale domains
- Employ **WKBJ**-like approximation by replacing fine scale  $y$  coordinate with  $\eta \equiv \frac{\Theta(Y, T)}{\delta}$

## Challenge: The Need for a Phase-Variable Formalism? (Cont'd)

• **Phase-Advection Equation:**  $\partial_T \Theta + \mathcal{V} \partial_Y \Theta = \overline{L} \delta^2 \partial_Y^2 \Theta; \quad k(Y, T) \equiv \partial_Y \Theta(Y, T)$

• Rational procedure needed for choosing  $\mathcal{V}(Y, T)$ ; e.g.,

i)  $\mathcal{V}(Y, T) \equiv \frac{1}{H_{ML}} \int_{-H_{ML}}^0 \bar{v}(Y, z, T) dz$

ii) **Solvability conditions** arising in the fluctuation equations at  $O(\delta)$ ?

• **Fluctuation equations** modified by “additional” slowly-varying coefficients:

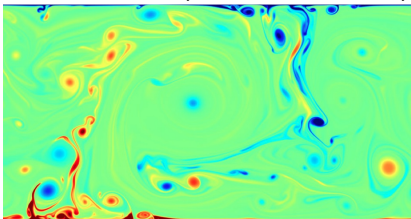
$$D_t^\eta v' + w' \partial_z \bar{v} = -\partial_Y \Theta \partial_\eta p' + S U_s \partial_Y \Theta \partial_\eta u' + La [(\partial_Y \Theta)^2 \partial_\eta^2 + \partial_z^2] v'$$

$$D_t^\eta \equiv \partial_t + (\bar{v} - \mathcal{V} + v') (\partial_Y \Theta) \partial_\eta + w' \partial_z$$

• **Mean equations** formally unchanged... but evaluation of **flux divergences** modified since embedded domains advected by  $\mathcal{V}(Y, T) \Rightarrow$  **Hybrid E-L approach**

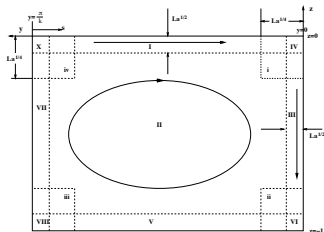
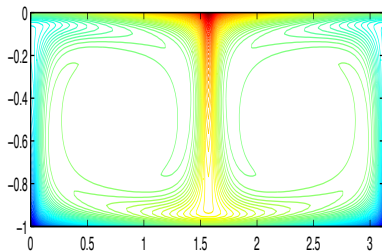


## Challenge: Mode Reduction for Embedded Domain Computations

Turbulent RBC (Johnston *PRL*, 2009)

- Even turbulent (2D) RBC organizes into thin, well-separated plumes
- Asymptotic analysis of *steady LC* as  $La \rightarrow 0$  shows that  $\psi'(y, z)$  smooth: well-represented with a few Fourier modes in  $y$  and  $z$
- **Goal:** Modified **mean-field** model, accounting for *localized*  $u'(y, z)$

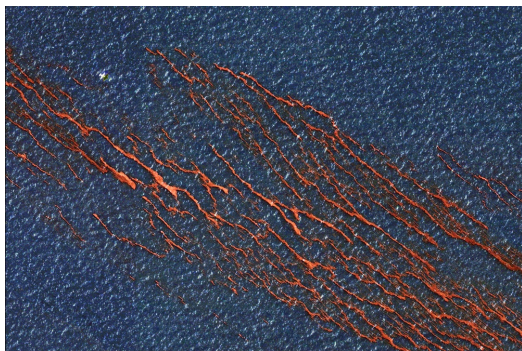
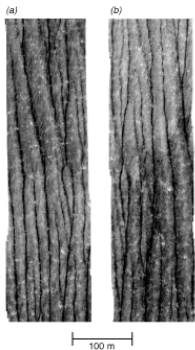
## Steady LC



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# Long Downwind Scales: Asymptotically Reduced PDEs for Strongly Anisotropic LC



## Emergence of Anisotropic Structure

## Isotropically Scaled (Non-Rotating, Constant-Density) CL Equations

$$\frac{D\mathbf{u}}{Dt} = -\nabla p + \frac{1}{La_t^2}(\mathbf{U}_s \times \boldsymbol{\omega}) + \frac{1}{R_*} \nabla^2 \mathbf{u}$$

where, in 3D,  $La_t = \sqrt{u_*/u_{s0}}$  and  $R_* \equiv u_* H / \nu_e$  replace single parameter (“laminar Langmuir number”)  $La \equiv La_t R_*^{-3/2}$  which governs 2D dynamics

## Ocean Surface BL Turbulence Regimes

**Shear flow turbulence regime:**  $La_t \gg 1$  with  $R_* \gg 1$

**Langmuir turbulence regime:**  $La_t = O(0.1)$  with  $La \ll 1$

▷ As  $La_t \rightarrow 0$ , vorticity aligns with Stokes drift

▷ Motivates consideration of formal limit  $La_t \rightarrow 0$

## Implications of Leading-Order Physics: Rapid Distortion and Secular Growth

- As  $La_t \rightarrow 0$ , there is a “rapid-distortion” (strong Stokes “shear”) transient that drives strong cellular  $(v, w)$  2D–3C velocity fluctuations. Upon rescaling time,

$$\Omega(y, z, \tau) = - [U'_s(z) \partial_y U_0(y, z)] \tau + \Omega_0(y, z)$$

- Upon rescaling pressure and seeking a leading-order (“geostrophic-like”) balance:

$$\nabla \mathcal{P} = \mathbf{U}_s \times \boldsymbol{\Omega} \quad \Rightarrow \quad \mathbf{U}_s \cdot \nabla \boldsymbol{\Omega} = \boldsymbol{\Omega} \cdot \nabla \mathbf{U}_s$$

- From this balance, the following deductions can be made:

- (i)  $\partial_x \mathcal{P} = 0$
- (ii)  $U_s \partial_x \Omega_x = \Omega_z U'_s(z)$
- (iii)  $U_s \partial_x \Omega_y = 0$
- (iv)  $U_s \partial_x \Omega_z = 0$

- $\Omega_x \neq 0$ ,  $\partial_x \Omega_x = 0$ ,  $u$ -fluctuations  $\ll (v, w)$ -fluctuations

## Rescaled CL Equations in Strong CL Vortex-Force Limit

## Anisotropically Scaled CL Equations

$$\partial_t u + \varepsilon u \partial_x u + (\mathbf{v}_\perp \cdot \nabla_\perp) u = -\varepsilon^{-1} \partial_x P + La [\partial_x^2 + \nabla_\perp^2] u$$

$$\begin{aligned} \partial_t \mathbf{v}_\perp + \varepsilon u \partial_x \mathbf{v}_\perp + (\mathbf{v}_\perp \cdot \nabla_\perp) \mathbf{v}_\perp &= -\nabla_\perp P + La [\partial_x^2 + \nabla_\perp^2] \mathbf{v}_\perp \\ &+ U_s (\nabla_\perp u - \varepsilon^{-1} \partial_x \mathbf{v}_\perp) \end{aligned}$$

$$\varepsilon \partial_x u + \nabla_\perp \cdot \mathbf{v}_\perp = 0$$

- Wind stress BC:  $\partial_z u = 1$  along  $z = 0, -1$
- x-invariance at leading-order:  $\partial_x P = \partial_x v = \partial_x w = 0$  and  $\nabla_\perp \cdot \mathbf{v}_\perp = 0$

## Multiple Scale Expansion

- ① Limit process:  $\varepsilon \propto La_t \rightarrow 0$  with  $R_* = o(La_t^{-2})$
- ② Introduce slow  $x$  scale:  $X \equiv \varepsilon x$  so that  $\partial_x \rightarrow \partial_x + \varepsilon \partial_X$
- ③ Expand fields:

$$\begin{aligned}
 u(x, y, z, t) &= u_0(x, X, y, z, t) + \varepsilon u_1(x, X, y, z, t) + \dots \\
 \mathbf{v}_\perp(x, y, z, t) &= \mathbf{v}_{0\perp}(X, y, z, t) + \varepsilon \mathbf{v}_{1\perp}(x, X, y, z, t) + \dots \\
 P(x, y, z, t) &= P_0(X, y, z, t) + \varepsilon P_1(x, X, y, z, t) + \dots
 \end{aligned}$$

- ④ Substitute into PDEs, collect terms of like order and **average** over fast  $x$
- ⑤ Obtain closed set of equations for  $\bar{u}_0 \equiv U(X, y, z, t)$ ,  $\mathbf{v}_{0\perp} \equiv \mathbf{V}_\perp(X, y, z, t)$  and  $P_0 \equiv \Pi(X, y, z, t)$

## Asymptotically Reduced PDEs

## Reduced CL (rCL) Equations

$$D_t^\perp U = -\partial_x \Pi + La \nabla_\perp^2 U$$

$$D_t^\perp \Omega + U_s(z) \partial_x \Omega = U'_s(z) (\partial_x V - \partial_y U) + La \nabla_\perp^2 \Omega$$

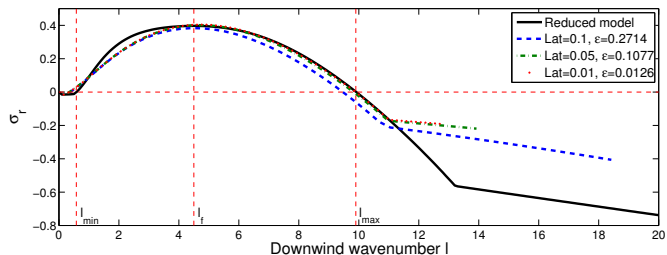
$$\nabla_\perp^2 \Pi = 2J[\partial_y \psi, \partial_z \psi] + \nabla_\perp \cdot (U_s(z) \nabla_\perp U) + U'_s(z) \partial_x (\partial_y \psi)$$

$$\nabla_\perp^2 \psi = -\Omega, \quad \mathbf{V}_\perp \equiv \nabla_\perp \times \psi \hat{i}$$

- $D_t^\perp(\cdot) \equiv \partial_t(\cdot) + (\mathbf{V}_\perp \cdot \nabla_\perp)(\cdot) \equiv \partial_t(\cdot) + J[(\cdot), \psi]$ ,  
where  $J[(\cdot), \psi] = \partial_z \psi \partial_y(\cdot) - \partial_y \psi \partial_z(\cdot)$
- Fast  $x$  averaged BCs along  $z = 0, -1$ :  $\partial_z U = 1$ ,  $\Omega = 0$ ,  $\psi = 0$
- Advection by  $U$  and stretching of  $\Omega$  are subdominant processes



## Secondary Stability Results: Comparison of rCL and CL Equations



$La_t$	$\varepsilon$	$\sigma_m$ (rescaled)	$l_f$ (rescaled)
0.10	0.2714	10.4101 (0.3835)	1.20 (4.4208)
0.05	0.1077	17.2789 (0.4010)	0.50 (4.6416)
0.01	0.0126	50.9579 (0.4045)	0.06 (4.7622)
Reduced model	$\varepsilon \rightarrow 0$	0.3968	4.5

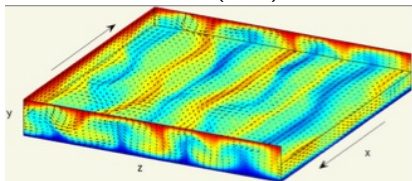
# Numerical Simulations of rCL Equations: Phenomenology

# Numerical Simulations of rCL Equations: “Turbulent” Dynamics

## rCL Equations Summary

- Derived reduced PDEs for anisotropic turbulent Langmuir circulation in strong vortex-force limit
- rCL equations provide nonlinear rectification of [RDT theory of Langmuir turbulence](#) by Teixeira & Belcher (*Ocean Modelling*, 2010)
- Reduced PDEs capture dominant linear and secondary instabilities
- Reduced PDEs offer several analytical and computational advantages:  
[Filter rapid-distortion transients and fine x-scale variability](#)  $\Rightarrow$  larger  $\Delta x$ ,  $\Delta t$
- Limiting procedure suppresses “self-sustaining process” proposed by Waleffe for wall-bounded shear-flow turbulence

## Plane Couette Flow (PCF)



(Courtesy J. Gibson)

- Applying methodology to PCF turbulence. . .

$$\mathcal{U} = U_w, \quad (\mathcal{V}, \mathcal{W}) = \frac{1}{Re} U_w$$

## SubMS and BL Scales

## Dimensional Scales

<u>Scale</u>	<u>Submesocale</u>	<u>Value</u>	<u>BL</u>	<u>Value</u>
Horizontal Length	$\mathcal{L}$	1–10 km	$l = h$	50–100 m
BL Depth	$h$	50–100 m	$h$	50–100 m
Horizontal Velocity	$U$	0.1 m/s	$U$	0.05–0.1 m/s
Vertical Velocity	$Uh/\mathcal{L}$	<0.01 m/s	$U$	0.05–0.1 m/s
Advection Time	$\mathcal{L}/U$	5–10 hr	$h/U$	0.5 hr
Wind Stress	$u_*$	0.01 m/s	$u_*$	0.01 m/s
Stokes Drift Velocity	$u_{s0}$	0.1 m/s	$u_{s0}$	0.1 m/s
Dynamic Pressure	$\rho_0 U^2$	10 Pa	$\rho_0 U^2$	10 Pa
Buoyancy Anomaly	$B = g \Delta\rho /\rho_0$	0.001 m/s <sup>2</sup>	$B$	0.001 m/s <sup>2</sup>